

# Fundamentals of Radio Communication

## 1 Introduction

### Analog Radio

In a traditional analog radio, like a “Walkie-Talkie”, there is a physical chain of circuits which work to process an incoming or outgoing signal. For a receiver, an antenna and front end collect and amplify an incoming radio frequency (RF) signal. A local oscillator and mixer shift the desired station from its broadcast frequency down to an intermediate frequency where filters can isolate it. A demodulator then recovers the information (e.g. voice, music, etc.) and an audio amplifier drives a speaker. Every change to that radio’s behavior lives in the physical circuits that make up the radio; if you want a different filter or new modulation type, then the hardware must be redesigned.

### Software-Defined Radio

A software-defined radio (SDR) keeps only the minimum analog front end and moves everything else into code running on a computer. An analog-to-digital converter (ADC) samples, or measures, the RF signal and turns it into a stream of numbers that can be processed with computers. Tuning, filtering, demodulation, even entire modulation schemes become algorithms that operate on those samples. If you want to change how the radio operates, all you have to do is update the software/algorithms. GNU Radio is a software that allows you to easily build digital signal processing (DSP) systems by connecting together signal processing blocks into a flowgraph.

In this lab we’ll take one more step by keeping the whole radio link inside the computer. Instead of sampling a real RF signal, we generate and process it entirely in software. The “transmitter”, “channel”, and “receiver” are just connected GNU Radio blocks, so nothing is radiated and no hardware needs wiring. The only physical interfaces you’ll need are your computer’s audio devices, e.g. microphone in, headphones out.

## 2 GNU Radio Flowgraphs

**Default rates:** `audio_rate = 48000, samp_rate = 192000`   **Start deviation:** `nbfm_deviation = 5000 Hz`

### Overview of the two-graph setup (ZMQ)

You will run two separate GNU Radio flowgraphs linked by ZeroMQ (ZMQ) at complex baseband. The transmitter (TX) generates NBFM from your microphone and pushes complex IQ samples over the network; the receiver (RX) pulls those samples, optionally adds impairments, demodulates, and plays audio.

#### TX flowgraph (block order)

`Audio Source → Multiply Const (mic gain) → NBFM Transmit → ZMQ PUSH Sink`

*Settings:* Audio Rate = 48000; Quadrature Rate = 192000; Max Deviation = 2000–7000 Hz; Tau = 0  $\mu$ s (base lab). In ZMQ PUSH Sink set `Bind = On`, `Address = tcp://*:PORT` (e.g. `tcp://*:6001`), High-Water-Mark (HWM) = 25, Linger = 0. Do *not* use a Throttle block on TX when using ZMQ.

## RX flowgraph (block order)

ZMQ PULL Source → Channel Model (optional) → NBFM Receive → Multiply Const (volume) → Audio Sink

*Settings:* Quadrature Rate = 192000; Audio Rate = 48000; Tau = 0  $\mu$ s. In ZMQ PULL Source set *Bind* = *Off*, Address = `tcp://TX_IP:PORT` (e.g. `tcp://192.168.1.50:6001`), HWM = 25.

## Required variables (both graphs)

`audio_rate = 48000 samp_rate = 192000 port = 6001` (unique per pair)

TX Address: `tcp://*:${port}` RX Address: `tcp://TX_IP:${port}`

## Instructions for use

**Same-machine dry run** Start the TX graph first with Address `tcp://*:6001` and Bind = On. Start the RX graph on the same machine with Address `tcp://127.0.0.1:6001` and Bind = Off. Speak into the mic; you should hear your voice with a small delay. If you have a frequency sink on RX, you should see energy centered at 0 Hz that responds to speech.

**Two-computer run** Choose a unique port per team (e.g. 6001, 6002, ...). On TX, run with Bind = On and Address `tcp://*:PORT`. Determine the TX IP address (Windows: `ipconfig`; macOS/Linux: `ifconfig` or `ip addr`). On RX, set Address `tcp://TX_IP:PORT` with Bind = Off, then run RX. Wear headphones on RX.

## Bring-up checklist (Checkpoint A)

Audio heard on RX      RF spectrum active at 0 Hz (if plotted)      Audio waveform visible (if plotted)

If silent: verify matching sample rates (48 k/192 k), TX binds and RX connects to the correct IP:PORT, and OS firewalls allow Python on that port. Set mic gain and volume near 1.0–2.0.

## B. Deviation vs. bandwidth (Carson)

**Goal.** Measure occupied bandwidth vs. deviation  $\Delta f$  and compare to  $B \approx 2(\Delta f + 3 \text{ kHz})$ .

Set TX Max Deviation to 3, 5, and 7, one at a time. On RX, enable averaging in the frequency sink (if present). While speaking steadily, estimate the main-lobe width down to roughly –20 dB.

$\Delta f$ (kHz)	Measured BW (kHz)	Carson $2(\Delta f + 3)$ (kHz)	Notes
3	_____	12	_____
5	_____	16	_____
7	_____	20	_____

**B1 (1–2 sentences).** Does measured bandwidth grow approximately linearly with  $\Delta f$ ? If it differs from Carson, give one plausible reason (measurement threshold, speech spectrum, etc.).

**Screenshots.** Capture RF spectra for one low- $\Delta f$  and one high- $\Delta f$  case; label each with  $\Delta f$ .

## C. Mic gain and apparent over-deviation

**Goal.** Show how excessive input level widens the spectrum and degrades audio.

Sweep TX mic gain from  $\approx 0.5$  to 3.0 while keeping voice level constant. Listen for distortion and watch spectral shoulders widen even if  $\Delta f$  is unchanged.

**C1 (1–2 sentences).** Why can too much mic gain look like larger  $\Delta f$  in the spectrum? What trade-off did you hear?

## D. Noise robustness

**Goal.** Observe FM’s gradual degradation with noise.

On RX, set Channel Model Noise Voltage to 0.00, 0.01, then 0.02. For each, note intelligibility and how the spectrum fattens. Optionally, insert a Power Squelch (Complex) before NBFM Receive (threshold  $\approx -60$  dB,  $\alpha = 10^{-4}$ , Gate = True) and toggle it.

**D1 (2–3 sentences).** At what noise level did speech become hard to follow? Why does FM fail gradually rather than abruptly?

**Screenshot.** Capture an RF spectrum at your “noisy” setting; label with the Noise Voltage.

## E. Carrier-frequency offset (CFO) tolerance

**Goal.** Explore mistuning tolerance.

On RX, set Channel Model Frequency Offset to 0, +200 Hz, -200 Hz, then  $\pm 800$  Hz. Note when audio becomes warbly or collapses.

**E1 (1–2 sentences).** Why is small CFO tolerable in FM? What finally breaks as CFO increases?

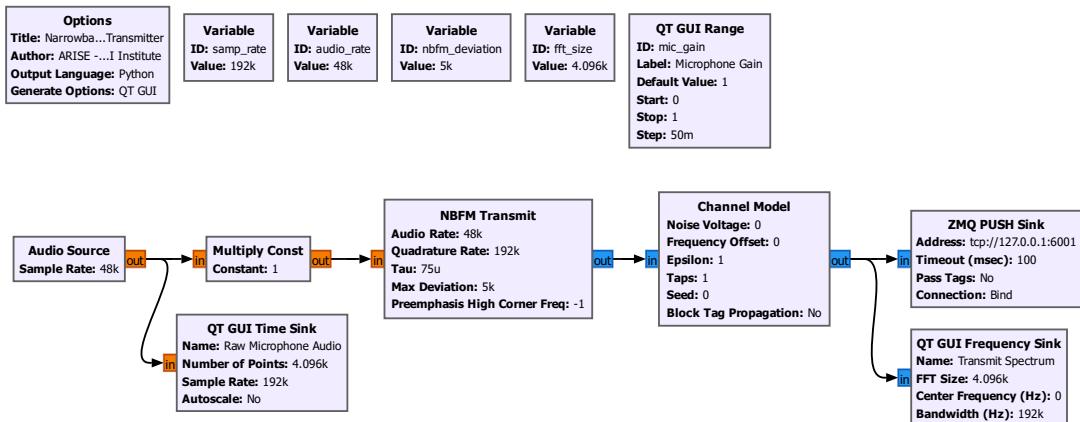


Figure 1: NBFM\_Virtual\_Transmitter.grc GNU Radio flowgraph.

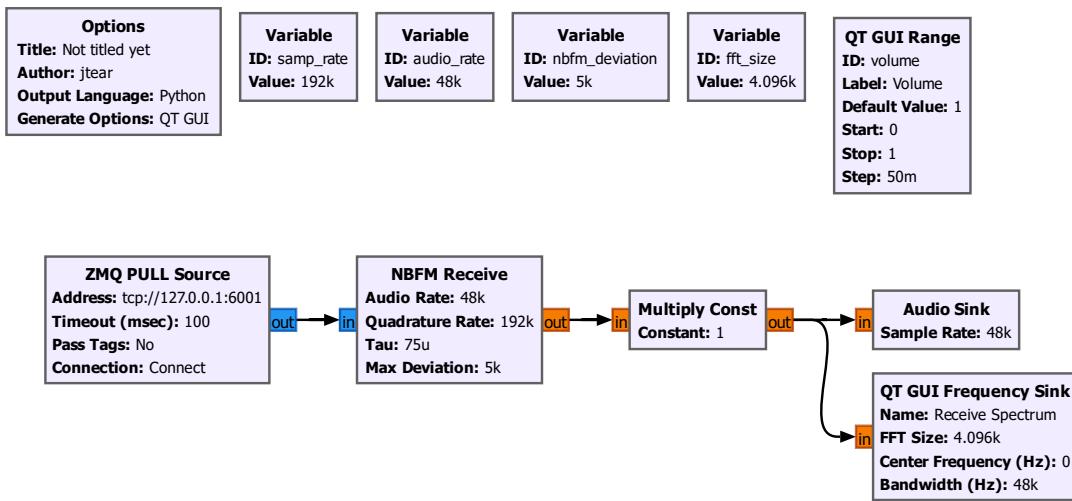


Figure 2: NBFM\_Virtual\_Receiver.grc GNU Radio flowgraph.