## Assignment 2

Zou Yuan Student No. 21960216

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## 1 Jacobi Method

The problems to be solved in this section are below:

Use the Jacobi Method to solve the sparse system within three correct decimal places (forward error in the infinity norm) for n=100. The correct solution is  $[1,-1,1,-1,\ldots,1,-1]$ . Report the number of steps needed and the backward error. The system is

$$\begin{bmatrix} 2 & 1 & & & & \\ 1 & 2 & 1 & & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & 2 & 1 \\ & & & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ -1 \end{bmatrix}$$

The Matlab code is as follows:

n=100;

```
[a,b]=sparsesetup(n);
[x,cout]=jacobi(a,b)

function [a,b] = sparsesetup(n)
e = ones(n,1);
n2=n/2;
a = spdiags([e 2*e e],-1:1,n,n);
b=zeros(n,1);
```

```
b(1)=1;b(n)=-1;
     end
     function [x2, cout]=jacobi(B, c)
     D=diag(diag(B));
     U=D-triu(B);
     L=D-(triu(B));
     x1 = (rand(1, size(B,1)));
      cout = 0;
      while 1
      cout = cout + 1;
     x2=inv(D)*(U+L)*x1+inv(D)*c;
      t=ones(1, size(B,1));
      t(2:2:size(B,1))=-1;
      t=t ';
      t1=x2-x1;
      {t}2{=}x2{-}t\;;
      if (\mathbf{norm}(t1, inf) < 10e - 3) & (\mathbf{norm}(t2, inf) < 10e - 3)
     break
     \mathbf{end}
     x1=x2;
     end
     end
The output is:
```

As shown above, the number of iterations is 10896 which varies slightly with the initial value, and the backward error is 0.0137.

 $back\_error = 0.0137$ 

cout = 10896

## 2 Gauss-Seidel Method

This chapter uses the Gauss - Seidel method method and the SOR method to solve the problems in the previous chapter.

Gauss-Seidel method:

```
n = 100;
[a,b] = sparsesetup(n);
x1 = (rand(1,n));
[x, cout] = seidel(a, b)
back_error=norm(b-a*x, inf)
function [a,b] = sparsesetup(n)
e = ones(n,1);
n2=n/2;
a = spdiags([e \ 2*e \ e], -1:1,n,n);
b=zeros(n,1);
b(1)=1;b(n)=-1;
end
function [x2, cout] = seidel(A, b)
D=diag(diag(A));
L = -\mathbf{tril}(A, -1); %求A的下三角矩阵
U = -triu(A,1);%求A的上三角矩阵
G = (D-L) \setminus U;
f = (D-L) \setminus b;
x0 = (rand(1, size(A, 1)));
x = G*x0+f;
cout = 0; % 选 代 次 数
t=ones(1, size(A,1));
t(2:2:size(A,1))=-1;
t=t;
while 1
x0 = x;
```

```
x = G*x0+f;
cout = cout + 1;
if (\mathbf{norm}(x-x0, inf) < 10e - 3) & (\mathbf{norm}(x-t, inf) < 10e)
break
\quad \text{end} \quad
x2=x;
end
end
                   SOR method:
n=100;
[a,b]=sparsesetup(n);
x1 = (rand(1,n));
[x, cout] = seidel(a, b)
back_error=norm(b-a*x, inf)
function [a,b] = sparsesetup(n)
e = ones(n,1);
n2=n/2;
a = spdiags([e \ 2*e \ e], -1:1, n, n);
b=zeros(n,1);
b(1)=1;b(n)=-1;
end
function [x2, cout] = seidel(A, b)
D=diag(diag(A));
L = -\mathbf{tril}(A, -1); %求A的下三角矩阵
U = -triu(A,1); %求A的上三角矩阵
w = 1.5;
G = (D-w*L) \setminus ((1-w)*D+w*U);
f = (D-w*L) \setminus (w*b);
x0 = (rand(1, size(A, 1)));
```

```
x = G*x0+f;
cout = 0; % 迭 代 次 数
t=ones(1, size(A,1));
t(2:2:size(A,1))=-1;
t=t ';
while 1
x0 = x;
x = G*x0+f;
cout = cout + 1;
if (\mathbf{norm}(x-x0, inf) < 10e - 3) & (\mathbf{norm}(x-t, inf) < 10e)
    -3)
break
end
x2=x;
end
end
```

The Seidel method output is:

$$cout = 5031$$
 
$$back\_error = 9.6863e - 06$$

The SOR output is:

$$cout = 1659$$
 
$$back\_error = 9.7578e - 06$$

As shown above, These methods can converge faster and get Higher precision than Jacobi method.

## 3 Cojugate Method

The problems to be solved in this section are below:

Let A be the n × n matrix with n = 1000 and entries A(i,i)=i, A(i,i+1)=A(i+1,i)=1/2, A(i,i+2)=A(i+2,i)=1/2 for

all i that fit within the matrix. (a) Print the nonzero structure spy(A). (b) Let  $x_e$  be the vector of n ones. Set  $b = Ax_e$ , and apply the Conjugate Gradient Method, without preconditioner, with the Jacobi preconditioner, and with the Gauss-Seidel preconditioner. Compare errors of the three runs in a plot versus step number.

```
n = 1000;
[a,b] = matrixetup(n);
xc=ones(n,1);
[x1, cout1, be1] = conjugate(a, b);
dd = diag(diag(a));
a=dd \setminus a;
b=dd \setminus b;
[x2, cout2, be2] = jacobi(a, b, xc);
[x3, cout3, be3] = guaseidel(a,b,xc);
t = 1:100;
figure();
plot(t, be1, '-o', t, be2, '-h', t, be3, '-s')
semilogy(t, be1, '-o', t, be2, '-h', t, be3, '-s')
legend ('conjugate', 'Prejacobi', 'Pregauss Seidel
    ');
function [a,b] = matrixetup(n)
v = (1:1:n);
a = diag(v);
for i = 1:n-2
a(i, i+1)=1/2; a(i+1, i)=1/2;
a(i, i+2)=1/2; a(i+2, i)=1/2;
end
xe=ones(n,1);
b=a*xe;
end
```

```
function [x, t, be] = jacobi(a, c, xc)
D=diag(diag(a));
U=D-triu(a);
L=-tril(a,-1);
for t=1:100
x=inv(D)*(U+L)*xc+inv(D)*c;
be(t) = norm(x-xc, 'inf');
end
end
function [x, t, be] = guaseidel(a, b, xc)
D=diag(diag(a));
L = -\mathbf{tril}(a, -1);
U = -triu(a,1);
G = (D-L) \setminus U;
f = (D-L) \setminus b;
x0 = (rand(1, size(a, 1)));
x = G*x0+f;
for t = 1:100
be(t)=norm(x-xc, 'inf');
x0 = x;
x = G*x0+f;
\mathbf{end}
end
function [x,t,be]=conjugate(a,b)
n = length(b);
xc=ones(n,1);
x=zeros(n,1);
r=b-a*x;
d=r;
for t=1:100
G=(\mathbf{norm}(r)^2)/(d'*a*d);
x=x+G*d;
rr=b-a*x;
```

```
be(t)=norm(x-xc,'inf');
B=(norm(rr)^2)/(norm(r)^2);
d=rr+B*d;
r=rr;
end
end
```

Result is below:

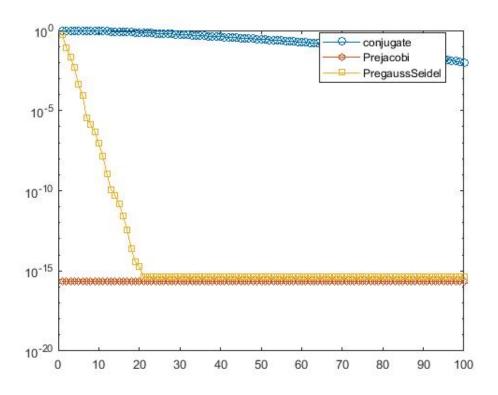


图 1: Converge Results