# Tutorial 6 - Variable Elimination

# COMP9418 – Advanced Topics in Statistical Machine Learning

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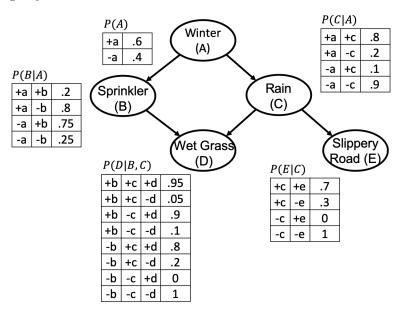
Lecture: Variable Elimination

**Topic:** Questions from lecture topics

Last revision: Sunday  $4^{\rm th}$  October, 2020 at 13:00

### Question 1

Consider the following Bayesian network.

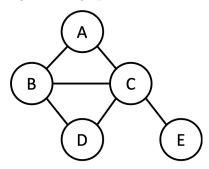


Use variable elimination to computer the marginals P(Q,e) and P(Q|e) where  $\mathbf{Q} = \{E\}$  and  $\mathbf{e} : D = false$ . Use the min-degree heuristic for determining the elimination order breaking ties by choosing variables that come first in the alphabet. Use the following algorithm for min-degree order:

```
Data: PGM: probabilistic grahical model
  Data: X: variables in the PGM
  Result: an ordering \pi of variables X
1
  begin
      G \leftarrow \text{induced graph of the factors in } PGM;
\mathbf{2}
      for i = 1 to number of variables in X do
3
          \pi(i) \leftarrow a variable in X with smallest number of neighbours in G;
4
          add an edge between every pair of non-adjacent neighbours of \pi(i) in G;
5
          delete variable \pi(i) from G and from X;
6
7
      end
  \mathbf{end}
8
  \mathbf{return} \,\, \pi
```

### Answer

The Bayesian network has the following induced graph:



As E is a query variable, we will not eliminate it. Considering the remaining variables, A and D have degree two. We chose A according to our tie-breaking policy. The removal of A from the induced graph makes the degree of B to decrease to two and the degree of C to reduce to three. Now, B and D have degree two, we chose B. The removal of B decreases the degree of D to one and C to two. We conclude choosing D and C.

The final elimination order is  $\pi = A, B, D, C$ .

To answer the query, we need first to set the evidence D = false.

$\overline{B}$	C	D	P(D B,C)
+b	+c	-d	.05
+b	-c	-d	.1
-b	+c	-d	.2
-b	-c	-d	1

We have the following factors:

$$\phi_A(A), \phi_B(B, A), \phi_C(C, A), \phi_D(D, B, C), \phi_E(E, C)$$

We start eliminating A by calculating  $\sigma_1(A, B, C) = \phi_A(A) \times \phi_B(B, A) \times \phi_C(C, A)$  and summing out A, resulting in a new factor  $\tau_1(B, C) = \sum_A \sigma_1(A, B, C)$ .

$\overline{A}$	В	C	$\sigma_1(A,B,C)$
+a	+b	+c	.096
+a	+b	-c	.024
+a	-b	+c	.384

$\overline{A}$	B	C	$\sigma_1(A,B,C)$
+a	-b	-с	.096
-a	+b	+c	.03
-a	+b	-c	.27
-a	-b	+c	.01
-a	-b	-c	.09

and,

B	C	$\tau_1(B,C)$
+b	+c	.126
+b	-c	.294
+b	+c	.394
+b	-c	.186

Now, we have the factors:

$$\phi_D(D, B, C), \phi_E(E, C), \tau_1(B, C)$$

and we proceed to eliminate B by calculating  $\sigma_2(B,C,D) = \phi_D(D,B,C) \times \tau_1(B,C)$  and summing out B,  $\tau_2(C,D) = \sum_B \sigma_2(B,C,D)$ 

В	C	D	$\sigma_2(B,C,D)$
+b	+c	-d	.0063
+b	-c	-d	.0294
-b	+c	-d	.0788
-b	-c	-d	.186

and,

$$\begin{array}{cccc}
C & D & \tau_2(C, D) \\
+c & -d & .0851 \\
-c & -d & .2154
\end{array}$$

Now, we have the factors:

$$\phi_E(E,C), \tau_2(C,D)$$

and we proceed to eliminate D by calculating  $\tau_3(C) = \sum_D \tau_2(C,D)$ 

$$\begin{array}{c|c}
C & \tau_3(C) \\
+c & .0851 \\
-c & .2154
\end{array}$$

Now, we have the factors:

$$\phi_E(E,C), \tau_3(C)$$

and we proceed to eliminate C by calculating  $\sigma_4(C,E) = \phi_E(E,C) \times \tau_3(C)$  and summing out C,  $\tau_4(E) = \sigma_4(C,E)$ 

 $\sum_{C} \sigma_4(C, E)$ 

$\overline{C}$		E
+c	+e	.05957
+c	-e	.02553
-c	+e	0
-c	-e	.2154

and we proceed to eliminate C by calculating  $\tau_4(E) = \sum_C \sigma_4(C, E)$ 

(E)
957
093

Therefore P(+e, -d) = 0.05957 and P(-e, -d) = 0.24093. We can also calculate P(-d) = 0.05957 + 0.24093 = 0.3005.

Normalizing the results, we get  $P(+e|-d) = \frac{P(+e,-d)}{P(-d)} \approx 0.198236$  and  $P(-e|-d) = \frac{P(-e,-d)}{P(-d)} \approx 0.801764$ .

## Question 2

Consider a chain network  $C_0 \to C_1 \to \ldots \to C_n$ . Suppose that variable  $C_t$ , for  $t \geq 0$ , denotes the health state of a component at time t. In particular, let each  $C_t$  take on states ok and faulty. Let  $C_0$  denote component birth where  $P(C_0 = ok) = 1$  and  $P(C_0 = faulty) = 0$ . For each t > 0, let the CPT of  $C_t$  be  $P(C_t = ok | C_{t-1} = ok) = \lambda$  and  $P(C_t = faulty | C_{t-1} = faulty) = 1$ . That is, if a component is healty at time t - 1, then it remains healthy at time t with probability  $\lambda$ . If a component is faulty at time t - 1, then it remains faulty at time t with probability 1.

- a. Using variable elimination with variable ordering  $C_0, C_1$  compute  $P(C_2)$ .
- b. Using variable elimination with variable ordering  $C_0, C_1, \ldots, C_{n-1}$  compute  $P(C_n)$ .

### Answer

a. 
$$P(C_2) = \sum_{C_0, C_1} P(C_0, C_1, C_2)$$
$$= \sum_{C_0, C_1} P(C_2 | C_1) P(C_1 | C_0) P(C_0)$$
$$= \sum_{C_1} P(C_2 | C_1) \sum_{C_0} P(C_1 | C_0) P(C_0)$$

Operating over factors, we have

$$\begin{array}{c|c}
C_0 & P(C_0) \\
\hline
\text{ok} & 1 \\
\text{faulty} & 0
\end{array}$$

and

$$\begin{array}{c|cccc} \hline C_{t-1} & C_t & P(C_t|C_{t-1}) \\ \hline \text{ok} & \text{ok} & \lambda \\ \text{ok} & \text{faulty} & 1-\lambda \\ \text{faulty} & \text{ok} & 0 \\ \hline \end{array}$$

$C_{t-1}$	$C_t$	$P(C_t C_{t-1})$
faulty	faulty	1

Therefore,

$C_0$	$C_1$	$P(C_1 C_0)$
ok	ok	λ
ok	faulty	$1 - \lambda$
faulty	ok	0
faulty	faulty	0

Now, we eliminate  $C_0$ 

$$\begin{array}{c|c}
\hline
C_1 & P(C_1) \\
\hline
\text{ok} & \lambda \\
\text{faulty} & 1 - \lambda
\end{array}$$

We do the same computation to obtain P(C2|C1).

$C_1$	$C_2$	$P(C_2 C_1)$
ok	ok	$\lambda^2$
ok	faulty	$(1-\lambda)\lambda$
faulty	ok	0
faulty	faulty	$1 - \lambda$

Now, we eliminate  $C_1$ 

$$\frac{C_2}{\text{ok}} \frac{P(C_2)}{\lambda^2}$$
faulty  $1 - \lambda^2$ 

b. Using variable elimination, we can observe that each time transition from t-1 to t and elimination of variable  $C_{t-1}$  results in a multiplication of  $P(C_{t-1} = ok)$  by  $\lambda$ . Therefore, we can use the following factor to represent  $P(C_n)$ 

$$\frac{C_n \qquad P(C_n)}{\text{ok} \qquad \lambda^n}$$
faulty  $1 - \lambda^n$ 

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# Question 3

Consider a Naive Bayes structure with edges  $X \to Y_1, \dots, X \to Y_n$ .

- a. What is the size of the largest factor of variable elimination order  $Y_1, \ldots, Y_n, X$ ?
- b. What is the size of the largest factor of variable elimination order  $X, \ldots, Y_n$ ?

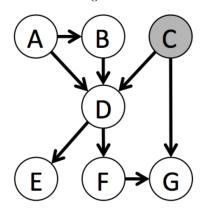
### Answer

The Naive Bayes structure has the following factors:  $\phi_{Y_1}(Y_1, X), \phi_{Y_2}(Y_2, X), \dots, \phi_{Y_n}(Y_n, X), \phi_{X}(X)$ .

- a. If we start eliminating  $Y_1$ , we will compute  $\tau_1(X) = \sum_{Y_1} \phi_{Y_1}(Y_1, X) \phi_x(X)$ , which is a factor of size O(d), where d is the size of the outcome space of each variable. The other factors that involve variables  $Y_i$  will have the same size. After eliminating variables  $Y_1, \ldots, Y_n$ , we end with factors  $\tau_1(X), \ldots, \tau_n(X)$ . The multiplication of these factors also results in a final factor of size O(d).
- b. If we start eliminating X, we will need to multiply all factors of the network since the variable X is present in all of them. This computation will result in a factor of size  $O(d^n)$ , which is exponential in the number of variables. Therefore, the first elimination order is more efficient than the second one.

### Question 4

For the Bayesian network below, all variables are binary. Assume we run variable elimination to compute the answer to the query P(A, E|+c), with the following elimination order: B, D, G, F.



- a. What is the size of the largest computed factor?
- b. Can the min-degree heuristic help to find an ordering that generates a smaller largest factor?

### Answer

Initially, we have the following factors:

$$\phi_A(A), \phi_B(B, A), \phi_C(C), \phi_D(D, A, B, C), \phi_E(E, D), \phi_F(F, D), \phi_G(G, F, C)$$

We start by noting the evidence, so we will not consider it when computing the factor sizes:

$$\phi_A(A), \phi_B(B, A), \phi_C(+c), \phi_D(D, A, B, +c), \phi_E(E, D), \phi_F(F, D), \phi_G(G, F, +c)$$

We eliminate variable B. The elimination involves the factors:  $\phi_B(B, A), \phi_D(D, A, B, +c)$ , resulting in the new factor  $\tau_1(D, A, +c)$ . This new factor has two variables and therefore four entries.

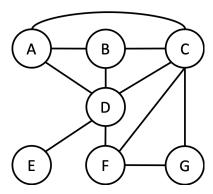
Now, we eliminate variable D. The elimination involves the factors:  $\tau_1(D, A, +c), \phi_E(E, D), \phi_F(F, D)$ , resulting in the new factor  $\tau_2(A, +c, E, F)$  with three variables and eight entries.

Eliminating G involves only one factor  $\phi_G(G, F, +c)$ , creating the factor  $\tau_3(F, +c)$ .

Finally, the elimination of F includes the factors:  $\tau_2(A, +c, E, F), \tau_3(F, +c)$  and creates the factor  $\tau_4(A, +c, E)$  with two variables and four entries.

Therefore, the largest factor has three variables and eight entries.

Let us see whether min-degree can help to find a better ordering. In this case, the induced graph is the following:



We start with G since it has degree 2. The elimination of G involves a single factor  $\phi_G(G, F, +c)$ , resulting in a new factor  $\tau_1(F, +c)$ . This factor has a single variable and two entries.

Now, F has degree 2 and is the next to be eliminated. This involves the factors  $\phi_F(F, D)$ ,  $\tau_1(F, +c)$  resulting in  $\tau_2(+c, D)$  that also has a single variable and two entries.

The elimination of F reduces the degree of D to 4. However, B has degree 3 and is the following to be eliminated. The elimination has the factors  $\phi_B(B,A)$ ,  $\phi_D(D,A,B,+c)$  and results on the factor  $\tau_3(D,A,+c)$  that as two variables and four entries.

Finally, factor D is eliminated with the multiplication of  $\tau_3(D, A, +c)$ ,  $\phi_E(E, D)$  creating a new factor  $\tau_4(A, +c, E)$  that also has two variables and four entries.

In the end, the min-degree heuristic generated a smaller maximum factor of four entries compared to eight entries of the first elimination order.