# **Creating an end-to-end IoT solution**

In part 3 of this workshop we will create an IoT node which will be connected to our TTN node as build in part 1, using NodeRed as installed in part 2.

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View, CA 94042, USA.

### **Prepare the ESP Wemos modules**

#### Parts needed:

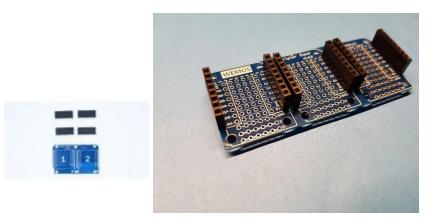
- Wemos Dual Base
- Wemos D1 mini v3 ESP8266
- Wemos OLED shield
- Servo SG90 mini servo
- 3 male-male jumper wires

### Soldering

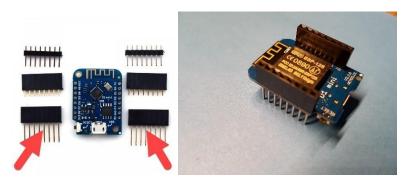
If your kit is not pre-soldered we have to solder the

headers first. Be ware of the pin numbers and orientation. Each Wemos board has a small notch on the left.

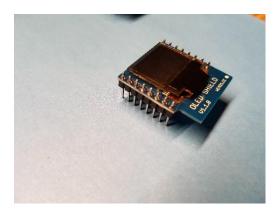
The Dual Base has four female headers to solder, put them on the front side:



The Wemos D1 mini v3 – ESP8266 comes with three possible options. For experimental purposes use the longer female connectors.



The Oled display must be always 'on top', so solder the connectors on the backside, display in front.



Now we can create our test configuration: Wemos and OLED: You can stack them (align the notches) or put them next to each other on the Dual Base:



#### **Arduino Software**

To use the ESP8266 we need the ESP toolchain. Installation instructions can be found here: <a href="http://esp8266.github.io/Arduino/versions/2.0.0/doc/installing.html">http://esp8266.github.io/Arduino/versions/2.0.0/doc/installing.html</a>

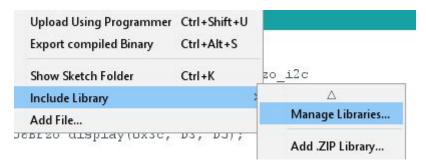
# **Installing with Boards Manager**

Starting with 1.6.4, Arduino allows installation of third-party platform packages using Boards Manager. We have packages available for Windows, Mac OS, and Linux (32 and 64 bit).

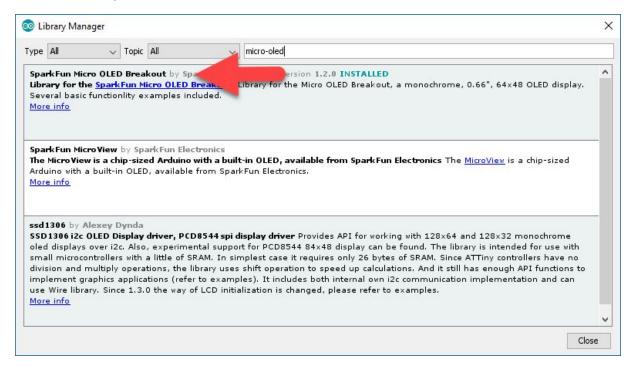
- Install the current upstream Arduino IDE at the 1.8 level or later. The current version is at the Arduino website.
- Start Arduino and open Preferences window.
- Enter http://arduino.esp8266.com/stable/package\_esp8266com\_index.json into Add itional Board Manager URLs field. You can add multiple URLs, separating them with commas.
- Open Boards Manager from Tools > Board menu and install *esp8266* platform (and don't forget to select your ESP8266 board from Tools > Board menu after installation).

After installation we have to add two libraries we want to use, OLED and MQTT:

#### Go to Sketch, Include Library, Manage Libraries:

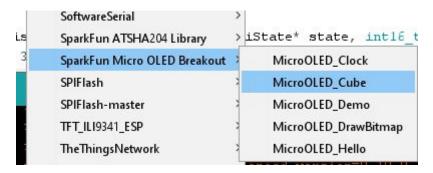


In the library manager search for 'micro oled' and find the 'SparkFun Micro OLED Breakout' and install this library:



Do the same for 'PubSubClient'.

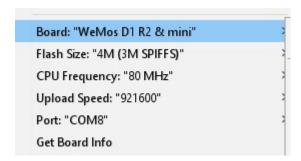
We can test our setup by using the example 'MicroOLED\_Cube. This can be found under 'Examples, SparkFun Micro OLED Breakout'.



Change the code from SPI to I2C (PIN\_RESET 255, comment out the SPI declaration and add the I2C declaration.

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Connect your Wemos with a micro USB data cable, choose the right COM port and board settings:

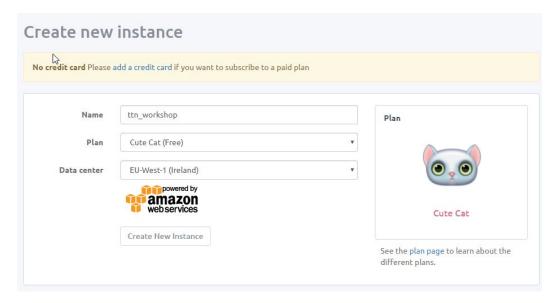


(COM port might differ!)

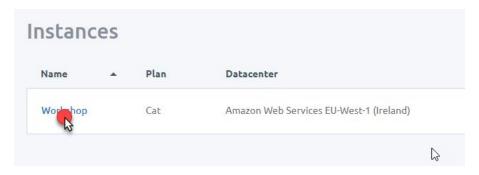
Upload your code, and see the cube rotating!

# **MQTT**

Register an account at www.cloudmqtt.com. An account is free for limited data use and devices.



In your list of instances, select your instance:



Now the settings for your MQTT instance are shown, we will use these later on:



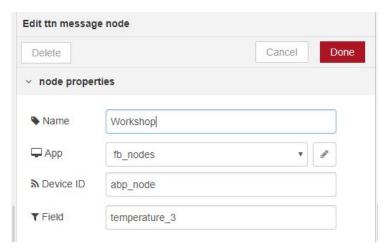
# **Prepare NodeRed**

To sent your data to MQTT we can use 'NodeRed'.

We start with a clean 'flow'.

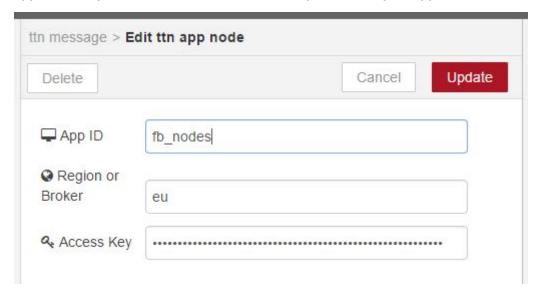
Add a TTN message node by drag and drop it on your flow screen.

By double clicking on the TTN message node you can change the values:



The name can be any name,

App refers to your TTN console. With the Pencil you can add your application here:

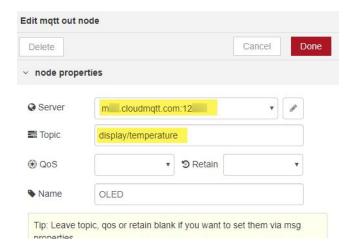


- App ID is the written name 'Application ID' from the TTN console
- Region is eu (you have to fill this in!!)
- Access Key is a copy of the access key of your application (access key of application, default key).
- Check Update and select your App in the previous screen.
- Device ID is the Device ID in TTN console

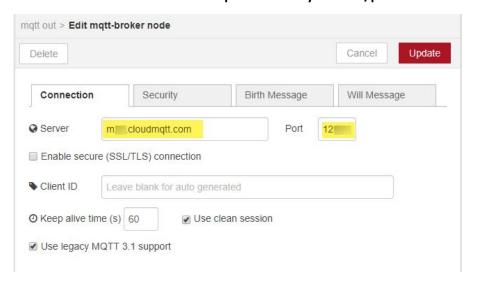
You can use temperature\_3 if you use the ttn\_bmp\_280\_abp\_cayenne.ino sketch. Beware that you use the same payload function in TTN as used in the previous nodes workshop!! If you do not have a payload function loaded, you can use an empty 'field', all the output will be shown.

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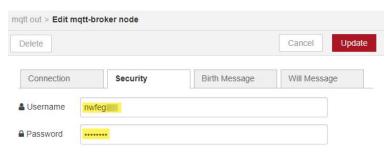
#### Now add a 'MQTT' output node to your flow and connect the both with a wire:



### Fill in the server name and use the pencil to add your user/password.

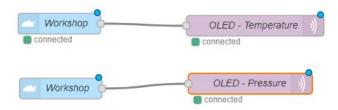


### On the tab security:

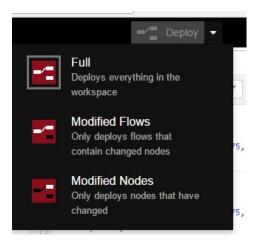


Repeat above steps for the 'Airpressure\_4' node, and use 'display/pressure' as topic.

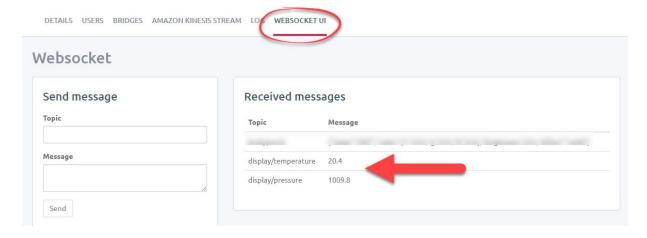
Your flow will look like this:



Now activate your flow with Deploy->Full:



We can check the working of MQTT in the CloudMQTT console. Select the Websocket UI, and you will see the values published.

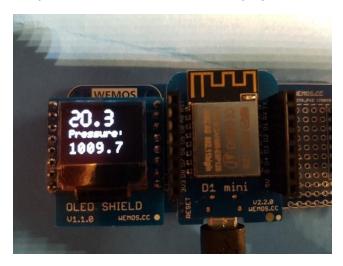


# **ESP MQTT node**

Download the ESP8266\_MQTT\_OLED sketch from https://github.com/galagaking/esp8266\_mqtt\_oled

Copy the WiFi credentials to be used and your MQTT settings in the beginning of the code:

Compile and upload your code to your ESP. It will reboot, connect to WiFi, your MQTT cloud server and listen to the topic 'display/+' and therefore any values coming in under 'display'. Temperature and pressure will be shown on the display:



The console will display the values as well:

```
Message arrived [display/pressure] -> 1009.7

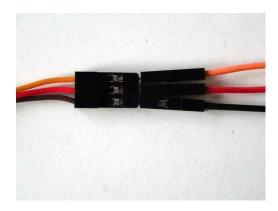
Message arrived [display/temperature] -> 20.3

Message arrived [display/temperature] -> 20.3

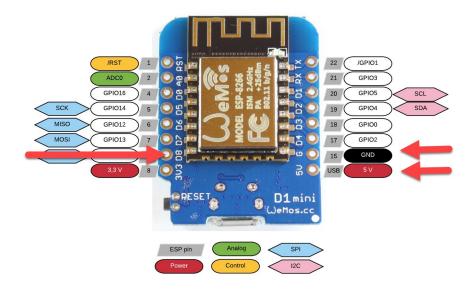
Message arrived [display/pressure] -> 1009.7
```

# **Connect the servo**

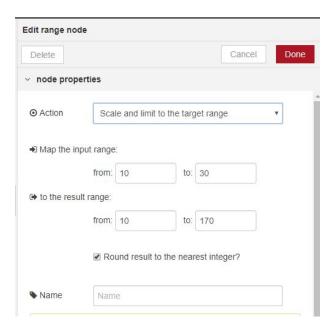
Use three jumper wires to connect your servo.



Connect the black wire (GND) to GND / G, the RED one to 5V, and the orange one to D8:

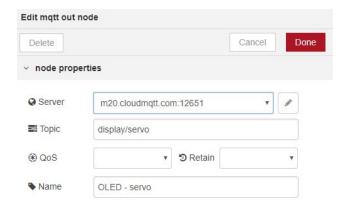


Add a 'range' node to your sketch:

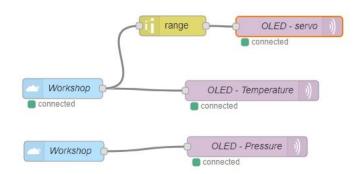


This object will scale the temperature 10 to 30 to an angle 10 to 170 of the servo. Choose other settings if you want another range.

Copy the MQTT object for temperature and replace 'temperature' with 'servo':



#### **Connect the objects:**



The angle of the servo will change when the temperature changes.

The ESP node can be used anywhere, just change the wifi credentials and it will connect to the (cloud) MQTT server and show your results. In this way you can move servos, but also switch lights

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on and off by publishing values to MQTT. The 'callback' function can do the work for you, controlled by Node-Red.

You can use the webui of CloudMQTT (or any other publishing service) to publish values.



The onboard LED will react on display/led (0 is off, 1 is on).