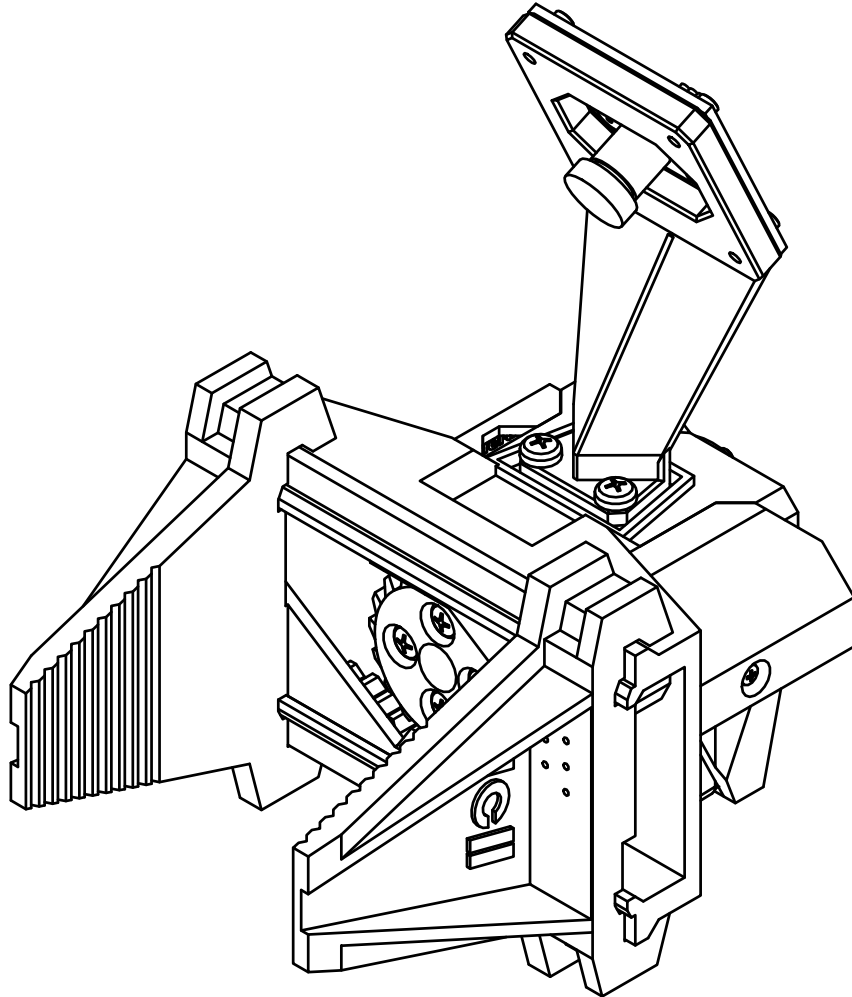


GRIPPER



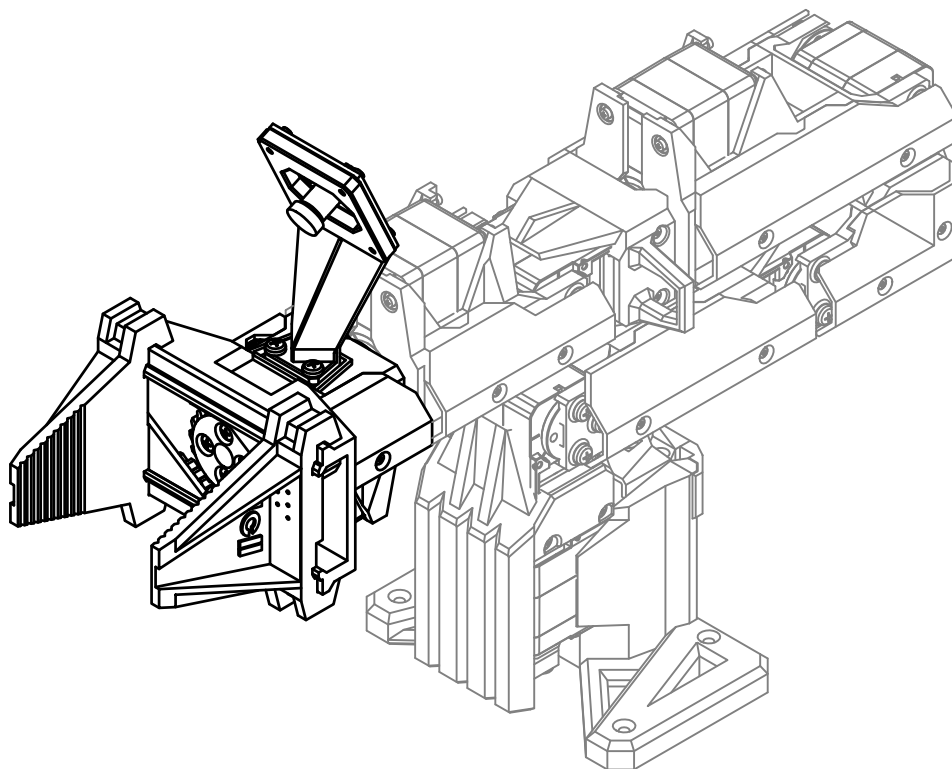
X: [HTTPS://X.COM/NORMA_CORE_DEV](https://x.com/norma_core_dev)

DISCORD: [HTTPS://DISCORD.GG/Z4YTW3QFHP](https://discord.gg/Z4YTW3QFHP)

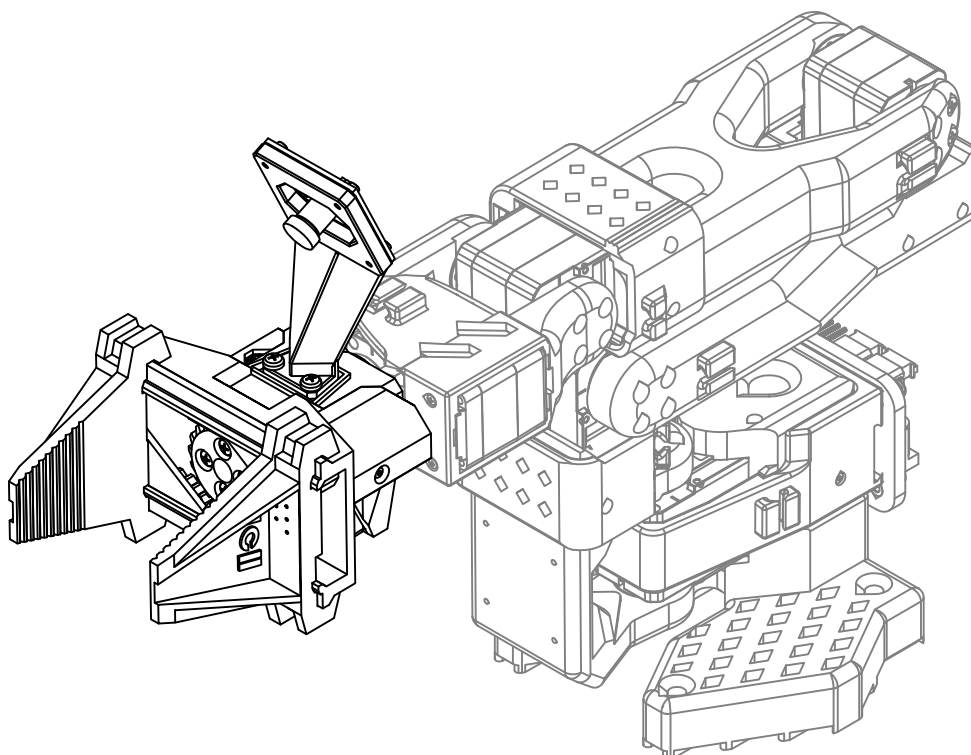
GITHUB: [HTTPS://GITHUB.COM/NORMA-CORE/NORMA-CORE](https://github.com/norma-core/norma-core)

REDDIT: [HTTPS://WWW.REDDIT.COM/R/NORMACORE/](https://www.reddit.com/r/normacore/)

GRIPPER



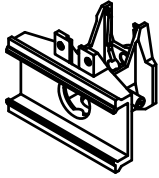

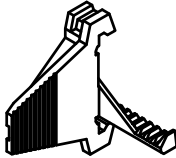
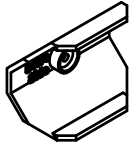
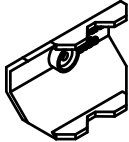
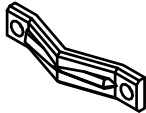

ELROBOT




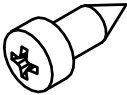
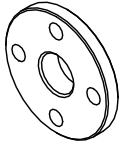

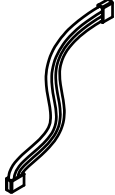
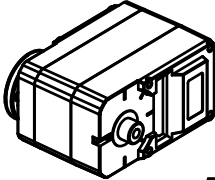
SO-I01

GRIPPER

3D PRINTING PARTS

GRIPPER BASE  A 1x	GRIPPER_GEAR  B 1x	GRIPPER JAW  C 2x	GRIPPER BASE SHIELD DRIVE SIDE  D 1x
GRIPPER BASE SHIELD CAMERA SIDE  E 1x	WIRING BRACKET  F 1x	CAMERA MOUNT  G 1x	

SERVO PARTS

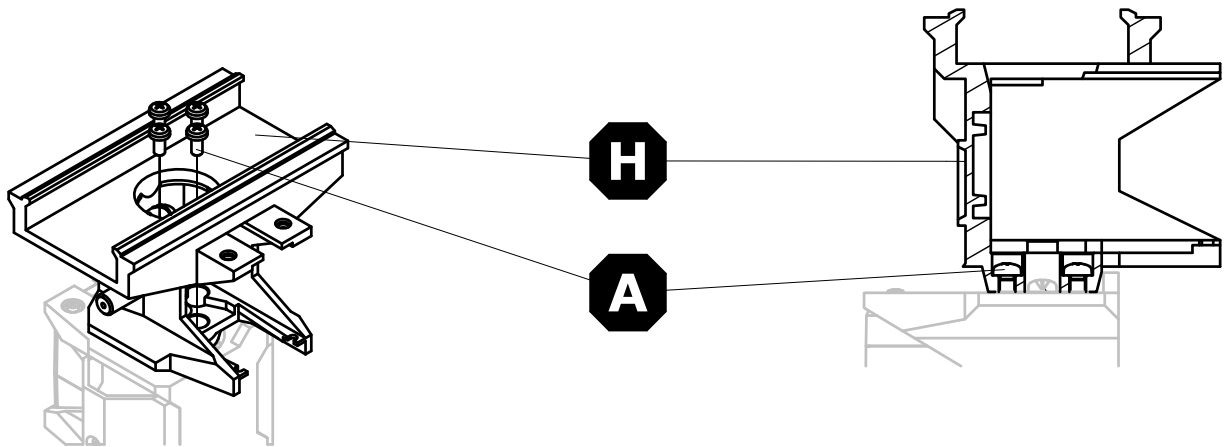
SCREW M3x8  H 11x	SELF-TAPPING SCREW M2x6  I 10x	IDLER HORN  J 1x	SERVO HORN  K 1x
MOTOR WIRE  L 1x	SERVO ST3215  M 1x		

OTHER PARTS

UVC CAMERA INNOMAKER U20CAM  N 1x	
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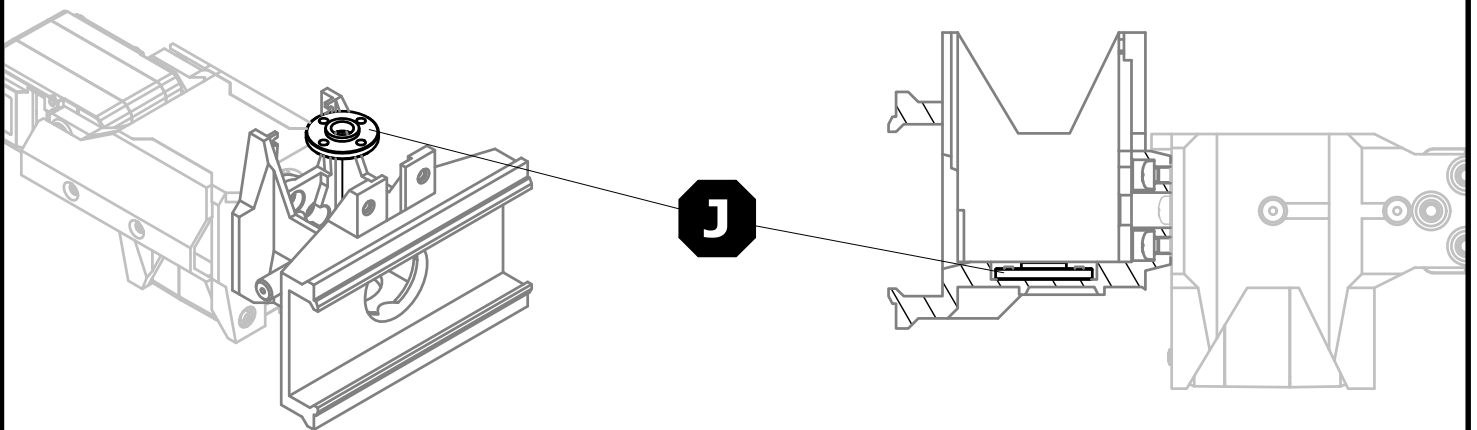
GRIPPER

STEP 1

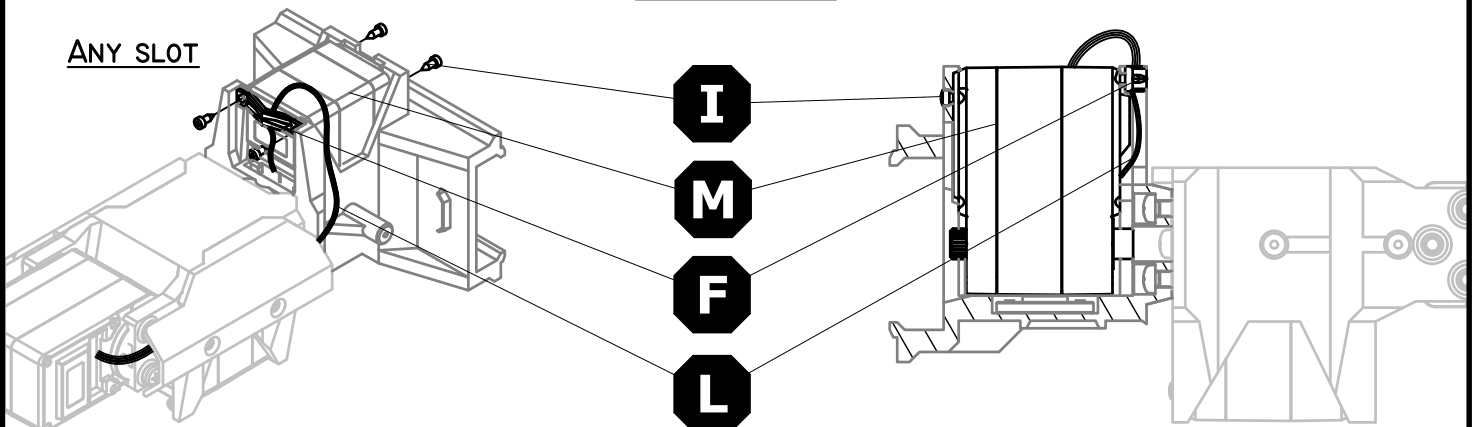


! THE GRAY COLOR SHOWS THE ALREADY ASSEMBLED ELROBOT/SO-I01 STRUCTURES !

STEP 2



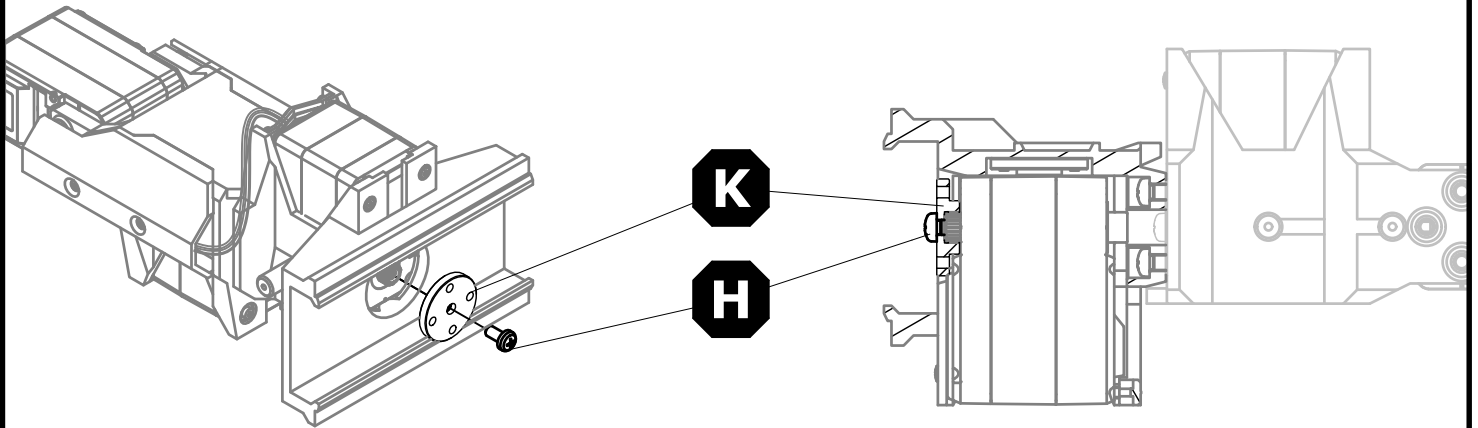
STEP 3



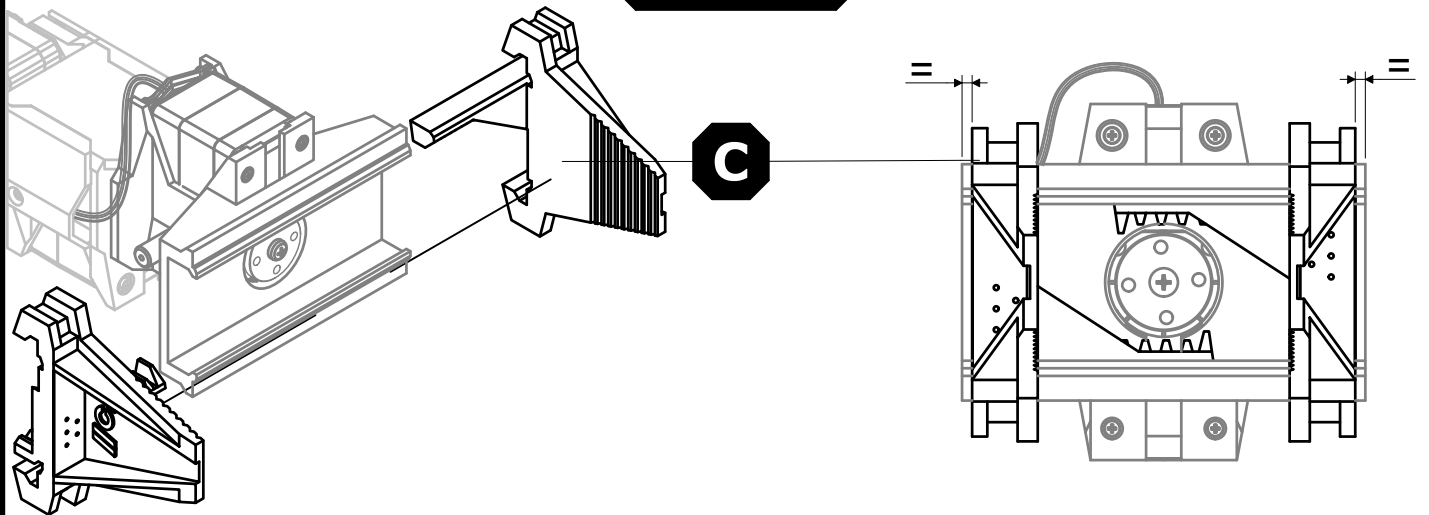
! FIRST CONNECT THE SERVO, THEN ATTACH THE WIRE WITH A BRACKET !

GRIPPER

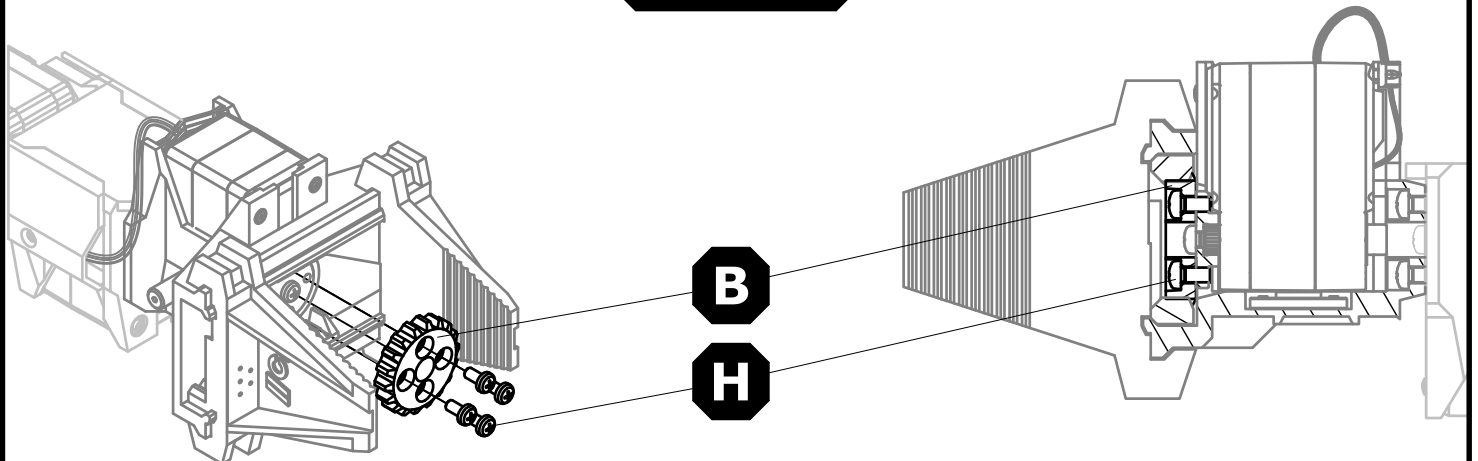
STEP 4



STEP 5



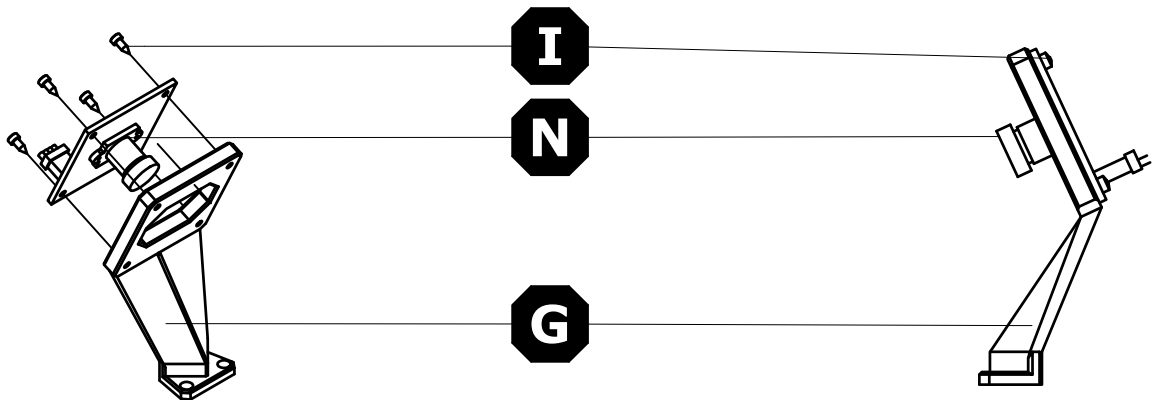
STEP 6



! BY MOVING THE JAWS WE POSITION THE GEAR RELATIVE TO THE SERVO HORN !

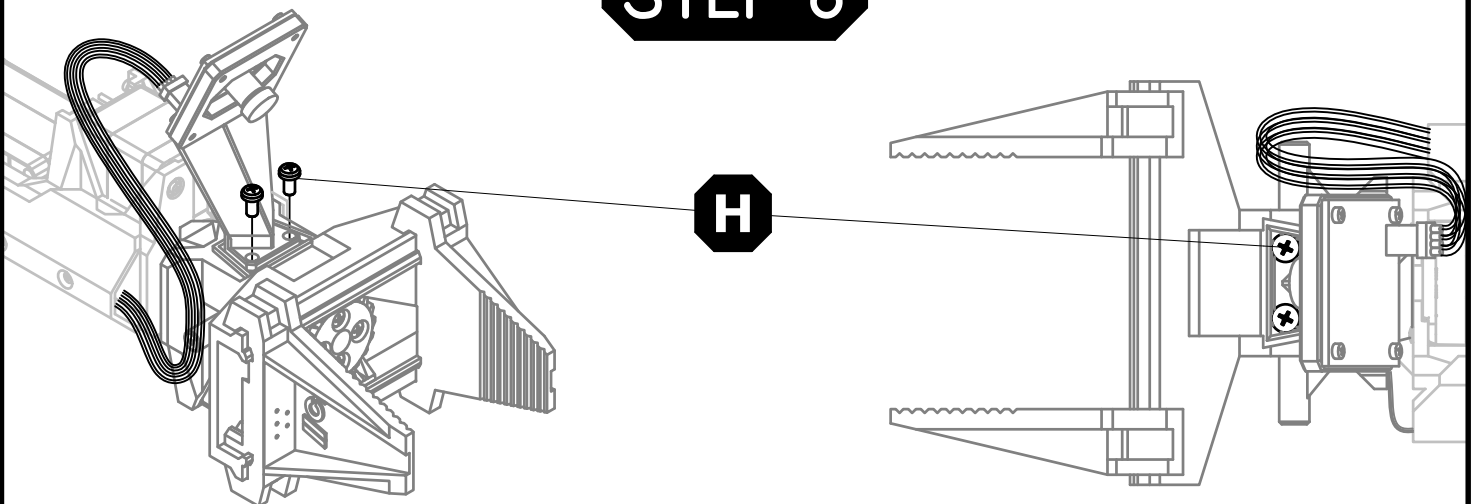
GRIPPER

STEP 7



ROTATE

STEP 8



! CONNECT THE CAMERA !

STEP 9

