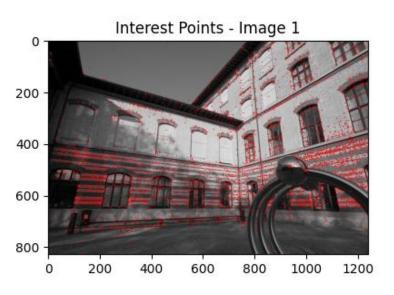
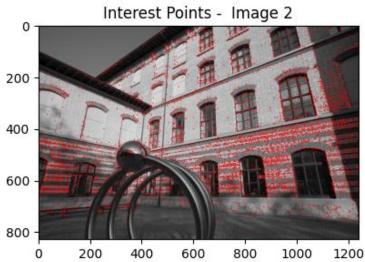
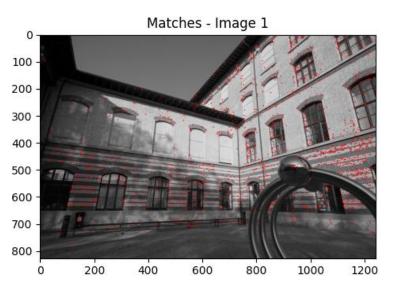
Computer Vision Ex.2 – Results

1. Finding Interest Points:





2. Finding Matching Interest Points:



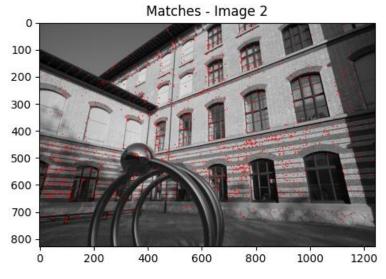


Image with Matches Subset



3. a. Essential and Fundamental Matrices:

Essential Matrix:

[[0.001867651636587 0.262120965375416 -0.073149908697821] [0.030475763405628 0.008554197693450 0.702383536342618] [-0.013423092158607 -0.656533409024104 -0.019424909243505]]

Fundamental Matrix:

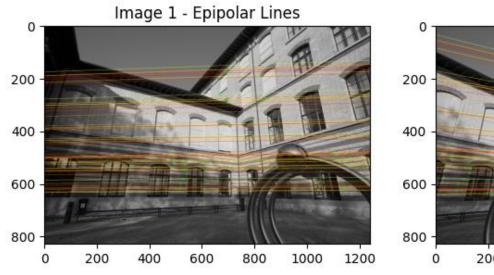
[[0.000000004001924 0.000000561964278 -0.000341172958617] [0.000000065337354 0.0000000018349331 0.000980438033623] [-0.000049070032102 -0.001319304489155 0.197636878990257]]

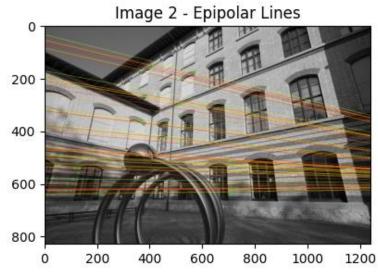
b. <u>Visualizing the Inlier Matches:</u>



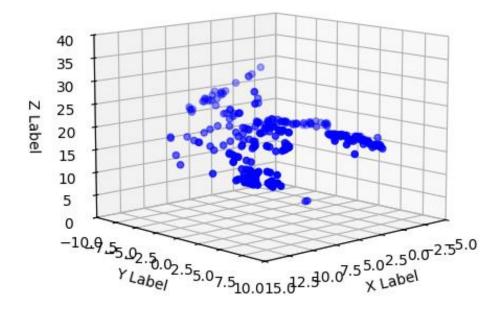


c. Epipolar Lines Image:





4. <u>3D reconstruction:</u>



5. Plane Fitting:

Colored 3D Point Cloud by Plane

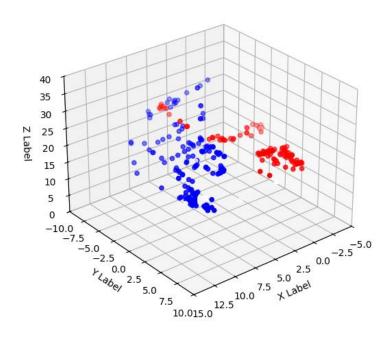
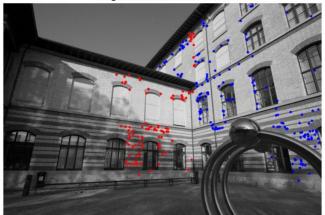
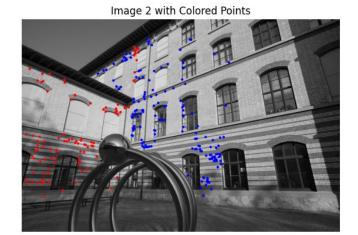


Image 1 with Colored Points





6. Normal Plotting:

Image 1 with Normals

