

Galen Savidge

Robotics & Control Engineer

Berkeley, CA 94708
☎ (510) 246-9256
✉ galensavidge@gmail.com
📧 galensavidge.com

Education

2014–2019 **Bachelor of Science, Robotics Engineering**, *University of California, Santa Cruz*, Santa Cruz, CA.

GPA: 3.80

Courses: Introduction to Mechatronics, Feedback Control Systems, Sensing and Sensor Technologies, Models of Robotic Manipulation, Microprocessor System Design, Algorithms and Abstract Data Types, Introduction to VLSI

Experience

Oct 2018– **Attitude Control System Team Lead**, *SlugSat*, Microsatellite Design Project.

June 2019 Lead a team of 4 electrical and robotics engineers designing an attitude control system for a CubeSat. Designed and built space-grade sensors and actuators, wrote embedded C programs for sensor fusion and feedback control, and ran hardware-in-the-loop simulations. Presented team work summaries, ran meetings, and managed team deadlines.

Apr 2018– **Lab Tutor**, *Microprocessor System Design*, Embedded Systems Programming Course.

June 2018 Helped students program microcontrollers to read sensors, communicate over serial connections, and use embedded hardware. Assisted students with debugging embedded C programs. Wrote test code used by instructors.

June 2016– **Robotics Intern**, *Biomimetic Millisystems Lab*, UC Berkeley.

Sept 2016 Developed and tested feedback control systems for use with bio-inspired locomotion techniques. Established the code base used for closed-loop control of wheeled and multi-legged autonomous platforms. Presented improved mobility and efficiency of existing designs.

Projects

Dec 2018 **Autonomous Mobile Robot.**

Designed, built, and tested an autonomous robot in a team of 3. Laser cut and assembled parts modeled in SOLIDWORKS. Designed multistage filtering circuits on protoboard and perfboard. Wrote hierarchical state machines. Demonstrated that the robot could consistently complete a randomized test course.

May 2018 **Optimization of Theo Jansen's "Strandbeest".**

Simulated a multi-linked leg using MATLAB and optimized its design for maximum stability and efficient locomotion.

March 2018 **Three-Sensor Attitude Estimation.**

Implemented closed-loop attitude estimation using raw data from a three-sensor IMU package. Calibrated for sensor drift and misalignment using MATLAB.

Awards

High Honors, *Jack Baskin School of Engineering*.

Dean's Honors List, F '14; W '15; W '16; W '17; S '17; F '17; S '18.

Tau Beta Pi, *Engineering Honor Society*.

Skills

Languages & Software	C, Java, MATLAB, SOLIDWORKS, Git, digital filtering, embedded programming (PSoC 5, PIC32, STM32 Nucleo, Raspberry Pi, and mbed), L ^A T _E X
Electronics	Soldering & desoldering, DC motors & actuators, active/resistive/capacitive sensors, hardware filters
Rapid Prototyping	Laser cutters, 3D printers
Communication & Leadership	Presenting, leading meetings, Gantt charts