

Galen Savidge

Robotics Engineer

Berkeley, CA 94708
(510) 246-9256
✉ galensavidge@gmail.com
📧 galensavidge.com

Education

2014–2019 **Bachelor of Science, Robotics Engineering**, *University of California, Santa Cruz*.

GPA: 3.80

Courses: Introduction to Mechatronics, Microprocessor System Design, Feedback Control Systems, Sensing and Sensor Technologies, Models of Robotic Manipulation, Algorithms and Abstract Data Types

Awards

Highest Honors in the Major, *Jack Baskin School of Engineering*.

Dean's Honors List, *F '14; W '15; W '16; W '17; S '17; F '17; S '18*.

Tau Beta Pi, *Engineering Honor Society*.

Experience

Oct 2018– **Attitude Control System Team Lead**, *SlugSat*, Microsatellite Design Project.

June 2019 Led a team of 4 electrical and robotics engineers working to design a CubeSat attitude control system. Chose and prototyped space-grade sensors and actuators, wrote embedded C programs for sensor fusion and feedback control, and ran hardware-in-the-loop simulations. Presented team work summaries, ran meetings, and managed team deadlines.

Apr 2018– **Lab Tutor**, *Microprocessor System Design*, Embedded Systems Programming Course.

June 2018 Helped students program microcontrollers to read sensors, communicate over serial connections, and use embedded hardware. Debugged students' embedded C programs. Wrote test code used by instructors.

June 2016– **Undergraduate Researcher**, *Biomimetic Millisystems Lab*, UC Berkeley.

Sept 2016 Developed and tested feedback control systems for use with bio-inspired locomotion techniques. Improved the mobility and efficiency of existing robotic designs. Wrote C++ code used for closed-loop control of wheeled and multi-legged autonomous robots.

Projects

Dec 2018 **Autonomous Mobile Robot**.

Designed, built, and tested an autonomous robot in a team of 3. Laser cut and assembled parts modeled in SOLIDWORKS. Soldered multistage filtering circuits. Wrote hierarchical state machines in embedded C. Demonstrated that the robot could consistently complete a randomized test course.

March 2018 **Three-Sensor Attitude Estimation**.

Implemented closed-loop attitude estimation using a three-sensor IMU package. Read and processed raw data in bare-metal C code. Used MATLAB to calibrate for sensor drift and misalignment.

Dec 2017 **Oscilloscope & Logic Analyzer**.

Programmed a PIC32 to function as a USB oscilloscope and logic analyzer. Read data from ADCs and transferred it using DMA and USB. Created a visual client in Linux on a Raspberry Pi.

Skills

Languages Embedded C, Python, Java

Software Git, Matlab, SolidWorks, L^AT_EX

Electronics Microcontrollers, Sensors, DC Motors & Actuators

Prototyping Soldering & Desoldering, Rapid Prototyping, 3D Printing, Laser Cutting

Misc Leadership, Presentation, Project Planning