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Port-o-matic IoT and Drones for Smart Ports

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Winners TM Forum Open Hack Nice 2017



Joann O'Brien (TM Forum), Dr Craig Gallen (Open NMS UK), Michael Sievenpiper (3rd yr. Student), Joe Appleton (Lecturer Solent Uni), Marcin Wisniewski (2nd yr. Student), Jergus Lejko (1st yr. Student)

Southampton Port-o-matic Smart Port Platform



- Southampton Port is the second largest in the UK
 - **52,000** ships a year
 - The UK's number one cruise port, which welcomes 1.7m passengers
 - Each cruise ship up to **6,000** passenger and crew
 - Contributes **£1.23 billion** to the UK economy
- Port-o-matic
 - Is a platform bringing together shipping companies and ports
- API's provided by:



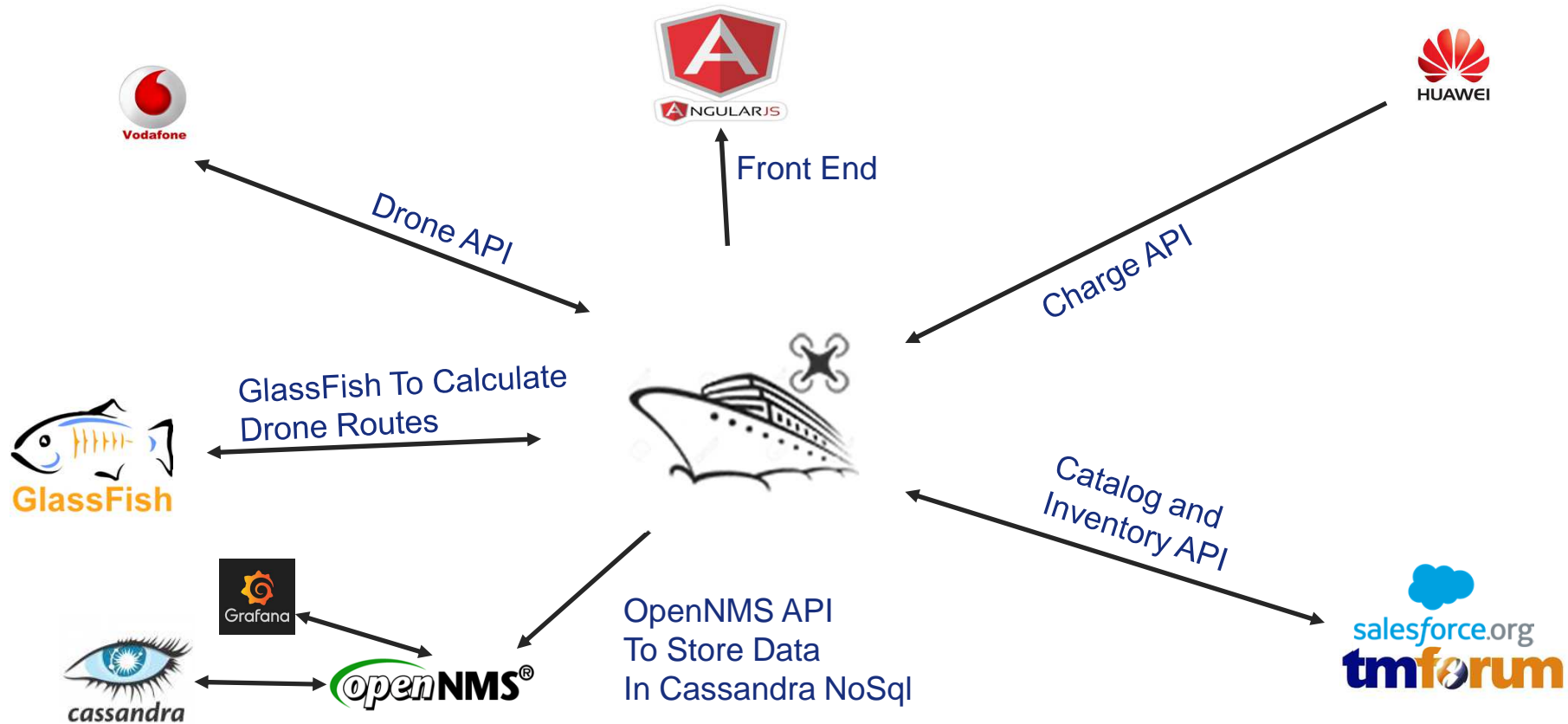
Our Platform Solution



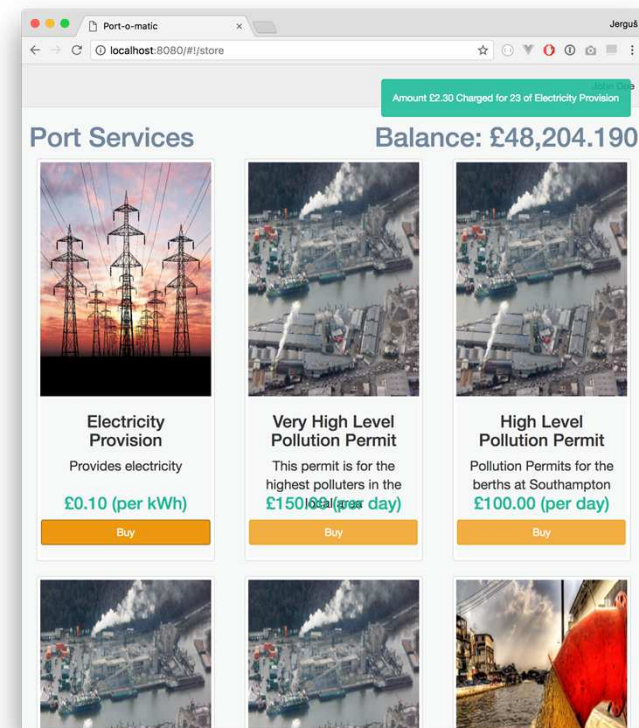
Single point for ordering and accessing port services

- Service Catalogue
 - Easily discoverable services
 - Aggregation of 3rd part offers
 - Port services (Docking charges, Water, Electricity, Waste Water and Data Communications etc.)
 - Pollution charging (for running generators in port)
- Measurements
 - Ship Side IoT devices Measuring Water, Electricity, Waste Water and Data consumption
 - Flying Drones measuring smoke emissions for pollution charging
- Presentation
 - User Web Application to view, order and access services

System Architecture

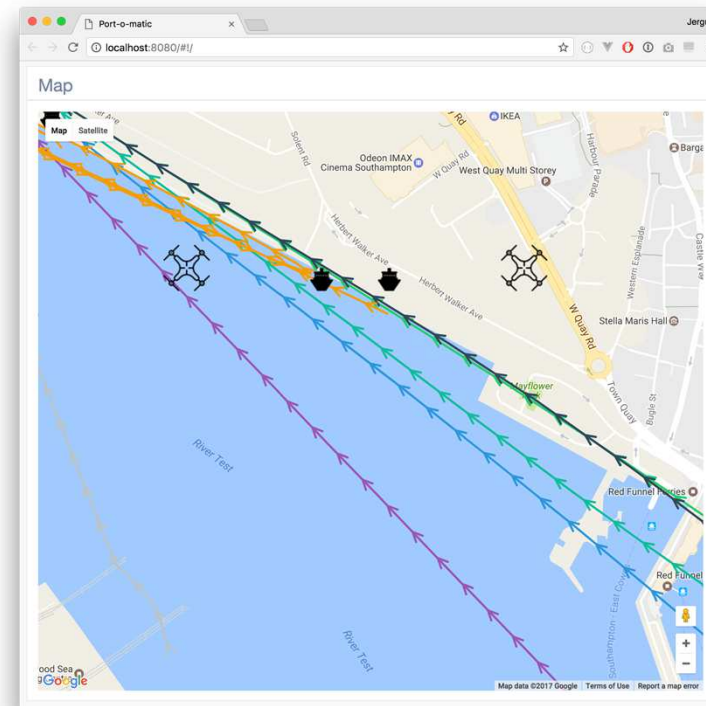


- Salesforce Catalog
 - ❑ Pulled services
 - ❑ Their data/pricing
- Huawei Charging & Balance API
 - ❑ Used to charge for services

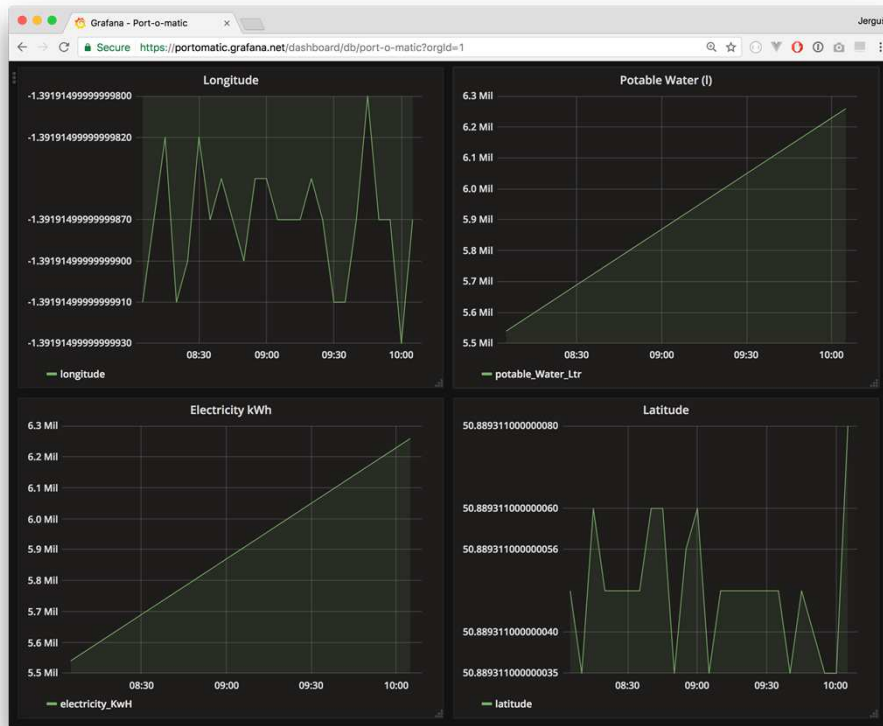


Vodafone Drone API integration

- Real-time data mapping
 - Position, direction
- API's
 - TMForum Address API
 - Vodafone Drone API
- Flight Control Algorithm
 - Automatic mission handling



Display of real time data from drones and metering devices

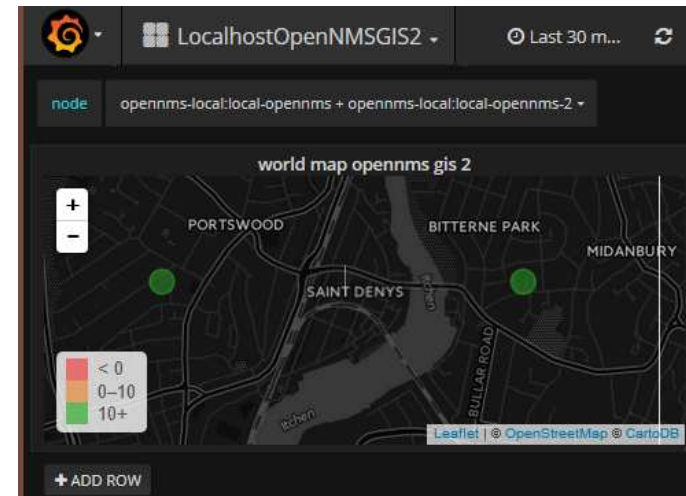
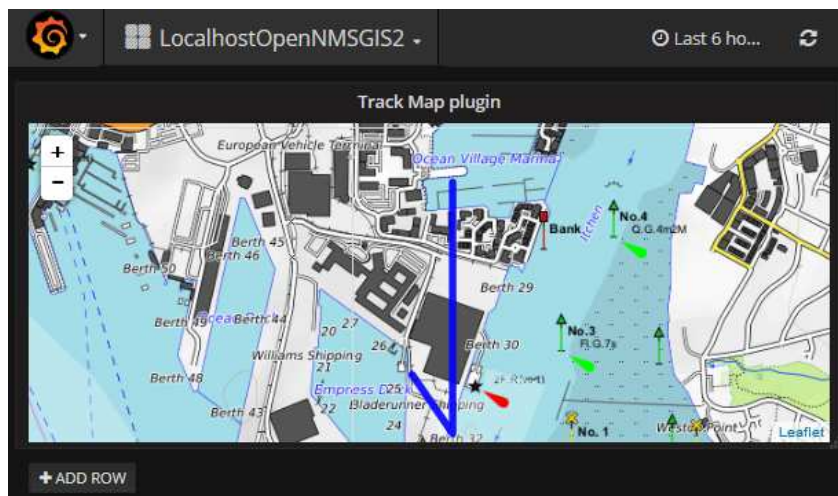


Grafana Measurements API

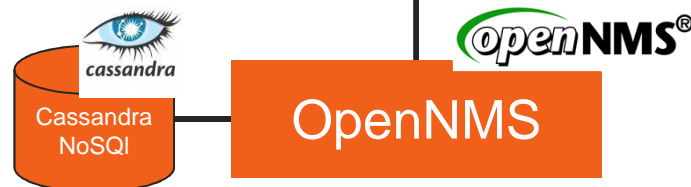


Grafana – Enhanced GIS Plugins

Grafana map plugins to display a path over time or values at coordinates



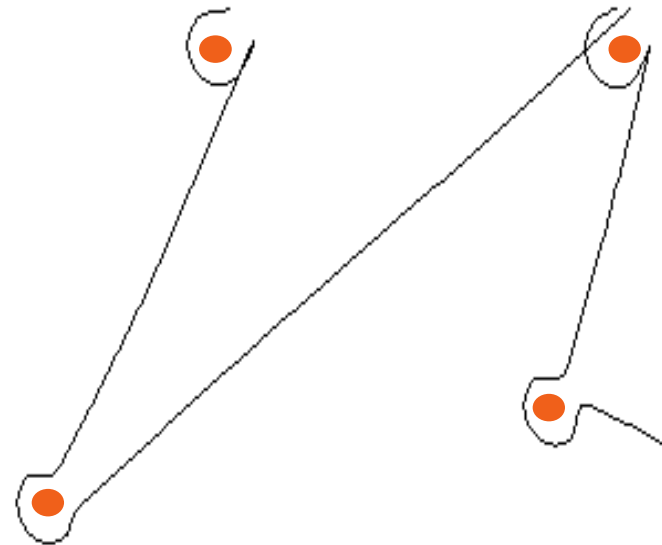
Code for plugins at
<https://github.com/gallenc/grafana-track-map>
<https://github.com/gallenc/worldmap-panel>



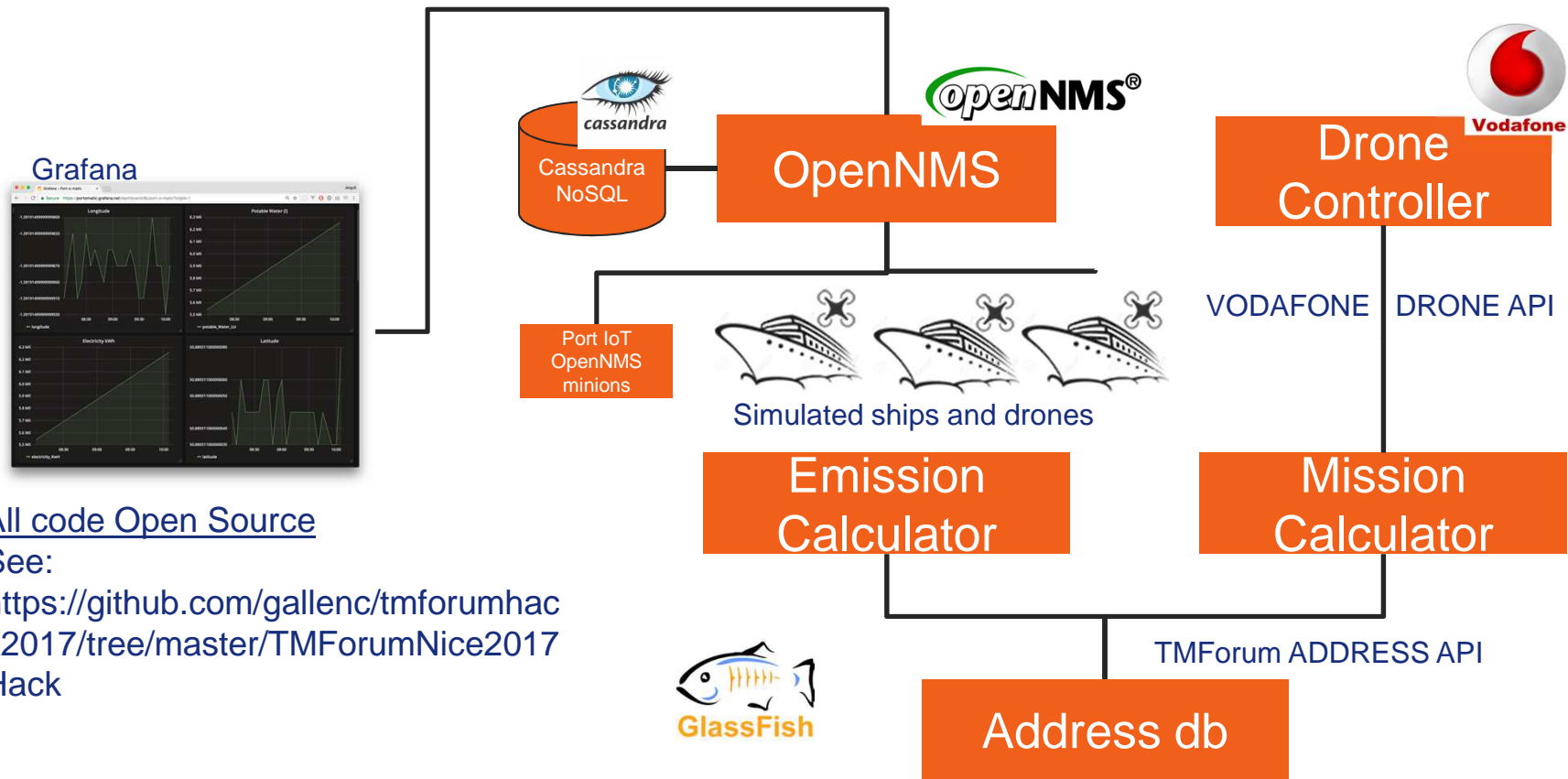
Calculating Measurements

- double measuredCy; is the total measured concentration ($\mu\text{g}/\text{m}^3$) at distance Dy;
- double distanceDz; // Dz is the distance from the ship (m) at which concentrations are to be predicted;
- **double predictionCz = ((measuredCy) / (2.7171)) * (-0.5476 * Math.log(distanceDz)+2.7171);**

calculated drone path



Architecture



All code Open Source

See:

<https://github.com/gallenc/tmforumhack2017/tree/master/TMForumNice2017Hack>



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THANK YOU QUESTIONS?



Southampton
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