#### Long-Range Dependence

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A stochastic process  $\{X(t)\}_{t\in T}$  is **stationary** if

$${X(t)}_{t\in T} \stackrel{d}{=} {X(t+h)}_{t\in T}$$

But this assumption is often too strong in practice. A way to relax this assumption is to limit the constraints to mean and covariance. We define a stochastic process  $\{X(t)\}_{t\in T}$  to be **weak stationary** (or second-order stationary) if for any  $s < t \in T$  the two following hold:

$$\mathbb{E}X(t)=\mathbb{E}X(0)$$

and

$$Cov(X(t), X(s)) = Cov(X(t - s), X(0))$$
$$= \gamma_X(t - s)$$

Let h=t-s, we call  $\gamma_X(h)$  the autocovariance function and  $\rho(h)=\gamma_X(h)/\gamma_X(0)$  the autocorrelation function of the time series  $\{X(t)\}_{t\in\mathbb{Z}}$ . This is enough to fully characterize the dependence structure and therefore the process itself. Sample counterparts of the ACF and ACVF are good measures of the dependence structure of the time series. They can also allow us to uncover simpler processes that together model our process.

A stochastic process  $\{X(n)\}_{n\in\mathbb{Z}}$  is called a **Moving Average process of order q** if

$$X(n) = X_n = Z_n + \sum_{k=1}^{q} \theta_k Z_{n-k}$$
 (1)

where  $Z_n \sim WN(0, \sigma_Z^2)$ . Using (1), let  $X_n$  be MA(1):

$$X_n = Z_n + \theta Z_{n-1}$$

Hence we can find the ACVF and ACF of  $X_n$ :

$$\gamma_X(h) = \mathbb{E}X_h X_0 = \begin{cases} \sigma_Z^2(1+\theta^2), & h = 0\\ \sigma_Z^2\theta, & h = 1\\ 0, & h \ge 2 \end{cases}$$

A weak stationary time series  $\{X(n)\}_{n\in\mathbb{Z}}$  is called **autoregressive of order p** if

$$X_n = \sum_{k=1}^p \varphi_k X_{n-k} + Z_n \tag{2}$$

with  $Z_n \sim WN(0, \sigma_Z^2)$ .

Let p = 1 and notice that because (2) is equivalent to

$$X_n = \varphi(\varphi X_{n-2} + Z_{n-1}) + Z_n$$

We have that

$$X_n = \sum_{k=0}^{\infty} \varphi^k Z_{n-k} \tag{3}$$

Since WLOG X(0) = 0. Which by geometric series properties only converges in L<sup>2</sup> for  $|\varphi| < 1$ 

When this is the case, it is easy to show that  $\rho_X(h) = \varphi^{|h|}$ . That is, (3) is well-defined when

$$\sum_{h=0}^{\infty} |\varphi^h| = \sum_{h=0}^{\infty} |\rho_X(h)| < \infty$$
 (4)

Let  $d \in \mathbb{Z}$  be positive. In an AR process of order d, if the first d-1  $\varphi_j$ 's are zero and  $\varphi_d=1$  then  $X_n$  becomes

$$X_n - X_{n-d} = Z_n (5)$$

Such a process is called **Integrated of order d**.

Combining (1) and (2) we get the ARMA(p,q):

$$X_{n} - \sum_{k=1}^{p} \varphi_{k} X_{n-k} = Z_{n} + \sum_{k=1}^{q} \theta_{k} Z_{n-k}$$
 (6)

which exists if the characteristic polynomial  $1 - \varphi_1 z - ... \varphi_p z^p = 0$  does not have roots on the unit circle. This is consistent with (3).

At this point it becomes more convenient to express processes in terms of an operator B, called the **backshift operator**, defined as:

$$B^k X_n = X_{n-k}, B^0 = I, k \in \mathbb{Z}$$

We write:

$$\varphi(B)X_n = \theta(B)Z_n \tag{7}$$

where 
$$\varphi(z) = 1 - \varphi_1 z - ... - \varphi_p z^p$$
  
and  $\theta(z) = 1 + \theta_1 z + ... + \theta_p z^p$ 



Adding an integrated component to the ARMA(p,q) process, we get the following process we call ARIMA(p,d,q)

$$\varphi(B)(1-B)^d X_n = \theta(B) Z_n \tag{8}$$

Attempting to extend the definition of ARIMA where d is only integer valued, we define a FARIMA(0, d, 0) process  $X_n$  as

$$X_n = (I - B)^{-d} Z_n$$

For  $d \in I$  where I is some interval to be determined later. Notice that we can also write this as

$$X_n = \sum_{j=0}^{\infty} b_j^{(-d)} B^j Z_n = \sum_{j=0}^{\infty} b_j^{(-d)} Z_{n-j}$$
 (9)

where

$$b_j^{(-d)} = \frac{\Gamma(j+d)}{\Gamma(j+1)\Gamma(d)} \tag{10}$$

are the coefficients of the Taylor expansion of the above  $(I - B)^{-d}$ 

As we have seen before in I.2, (9) is well defined if

$$\sum_{j=0}^{\infty} b_j^2 < \infty \tag{11}$$

Using Stirling's approximation formula, we find that (9) is well defined for  $d<\frac{1}{2}$ . So  $I=(-\infty,1/2)$ 

The F in FARIMA stands for Fractional.



If d < 0 but not a negative integer,

$$\sum_{h=-\infty}^{\infty} |\gamma_X(h)| \le \sigma^2 \left(\sum_j |b_j|\right)^2 < \infty$$

If d=-1 then  $X_n=Z_n-Z_{n-1}=\Delta Z_n$  and hence for d=-1,-2,...,  $X_n=\Delta^{-d}Z_n$ . Hence in these cases,  $\gamma_X(h)=0$  for |h|>|d| by Remark 1. Hence, for d<0 the autocovariances of the times series are absolutely summable.

If d = 0, then  $X_n = Z_n$  is just white noise, so the autocovariances are absolutely summable.

If 0 < d < 1/2 then the autocovariances are not absolutely summable.

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A time series  $X_n$  is **short range dependent** (SRD) if

$$\sum_{h=-\infty}^{\infty} |\gamma_X(h)| < \infty$$

That is, the so called **long-run variance** of the times series is constant.

This corresponds to  $d \leq 0$  above.

A special case of SRD time series is when the long-run variance is 0. Such a process is called **antipersistent**.

**Condition I.** The times series  $X_n$  has a linear representation

$$X_n = \mu_X + \sum_{k=0}^{\infty} \psi_k Z_{n-k} = \mu_X + \sum_{k=-\infty}^{\infty} \psi_{n-j} Z_j$$

with  $\{\psi_k\}_{k\geq 0}$  satisfying

$$\psi_k = L_1(k)k^{d-1}$$

where  $d \in (0,1/2)$  and  $L_1(k)$  is positive on  $[c,\infty]$  for some  $c \geq 0$  satisfies, for any a>0

$$\lim_{k\to\infty}\frac{L(ak)}{L(k)}=1$$

we call such a function slowly varying at infinity.

**Condition II.** The autocovariance function of  $X_n$  satisfies

$$\gamma_X(k) = L_2(k)k^{2d-1}, \ k = 0, 1, 2, ...$$

with d as before and  $L_2$  slowly varying at infinity,  $\square$ 

**Condition III.** The autocovariances of the time series of  $X_n$  are not absolutely summable, that is,

$$\sum_{h=-\infty}^{\infty} |\gamma_X(h)| = \infty$$

**Condition V.** The time series  $X_n$  satisfies

$$Var(X_1 + ... + X_N) = L_5(N)N^{2d+1}$$

**Definition** A weak stationary time series  $X_n$  is called **long-range dependent** (LRD) if one of the non-equivalent conditions above are satisfied. The parameter  $d \in (0, 1/2)$  is called the **long-range dependence parameter**.

Note: It can be shown that

$$I \Longrightarrow II \Longrightarrow III, V$$

**Example 1:** Let  $X = X_n$  be a Markov Chain with finite state space. Let P be the transition matrix. Assume X is is irreducible (all states are connected) and aperiodic. Then, let  $\pi_i > 0$ , i = 1, ..., m be the invariant probabilities.

A Markov Chain X with initial distribution  $\mathbb{P}(X_0 = i) = \pi_i$  is strictly stationary

It can be shown that if P has distinct eigenvalues, then

$$|\gamma_{g(X)}(k)| \le Cs^k$$
, some  $0 < s < 1$ 

for some function g and some s that depends on the eigenvalues of P. That is,  $g(X_n)$  has at least exponentially decreasing autovariances and hence is SRD.

**Example 2:** The series  $X_n$  is called FARIMA(p, d, q) if it satisfies

$$X_n = \varphi^{-1}(B)\theta(B)(I - B)^{-d}Z_n$$

with d < 1/2

**Remark** The operator  $(1-B)^{-d}$  is responsible for LRD features of  $X_n$  while  $\varphi^{-1}(B)\theta(B)$  is responsible for SRD behavior.

If the  $\varphi(z)$  has roots outside of the unit circle, then the FARIMA(p, d, q) series with 0 < d < 1/2 is LRD in the sense of conditions I, II, III, and V.

**Definition** A process  $\{X(t)\}_{t\in\mathbb{R}}$  is self-similar if there is an H>0, called the self-similarity parameter such that for all c>0,

$$\{X(ct)\}_{t\in\mathbb{R}} \stackrel{d}{=} \{c^H X(t)\}_{t\in\mathbb{R}}$$
 (12)

**Theorem** If X = X(t) is H-SS, then  $Y(t) = e^{-tH}X(e^t)$  is stationary. Conversely, If Y = Y(t) is stationary, then  $X(t) = t^HX(\log(t))$  is H-SS.

**Definition** A process  $\{X(t)\}_{t\in\mathbb{R}}$  has stationary increments if, for any  $h\in\mathbb{R}$ 

$$\{X(t+h) - X(t)\}_{t \in \mathbb{R}} \stackrel{d}{=} \{X(t) - X(0)\}_{t \in \mathbb{R}}$$



**Proposition** Let  $\{X(t)\}_{t\in\mathbb{R}}$  be an H-SSSI process. Then, if  $\mathbb{E}|X(1)|^2<\infty$ , then for  $s,t\in\mathbb{R}$ 

$$\mathbb{E}X(t)X(s) = \frac{\mathbb{E}X(1)^2}{2}\{|t|^{2H} + |s|^{2H} - |t-s|^{2H}\}\$$

**Definition** A Gaussian H-SSSI process  $\{B_H(t)\}_{t \in \mathbb{R}}$  with  $0 < H \le 1$  is called Fractional Brownian Motion.

**Corollary** If  $\{X(t)\}_{t\in\mathbb{R}}$  satisfies the following conditions:

- (i) It is a Gaussian process with zero mean and X(0) = 0
- (ii)  $\mathbb{E}(X(t))^2 = \sigma^2 |t|^{2H}$  for all  $t \in \mathbb{R}$ ,  $\sigma > 0$ , and  $0 < H \le 1$
- (iii)  $\mathbb{E}(X(t)-X(s))^2=\mathbb{E}(X(t-s))^2$  for all  $s,t\in\mathbb{R}$

Then,  $\{X(t)\}_{t\in\mathbb{R}}$  is fractional Brownian Motion.



**Proposition** For  $H \in (0,1)$ , standard FBM admits the following integral representation

$$\{B_{H}(t)\}_{t\in\mathbb{R}} = \{\frac{1}{c_{1}(H)} \int_{\mathbb{R}} \left( (t-u)_{+}^{H-1/2} - (-u)_{-}^{H-1/2} \right) B(du) \}_{t\in\mathbb{R}}$$
(13)

**Proof** Must show that RHS is well defined (i.e. the integrand is square integrable), and show that the three conditions of the Corollary are satisfied.

**Values of H** If 1/2 < H < 1, then we can express (13) as

$$\left\{\frac{H-1/2}{c_1(H)}\int_{\mathbb{R}}\left(\int_0^t(s-u)_+^{H-3/2}ds\right)B(du)\right\}_{t\in\mathbb{R}}$$

If H = 1/2 then FBM reduces to Brownian Motion.



**Definition** Bifractional Brownian Motion is a natural extension to FBM and is defined as a zero mean Gaussian process with covariance function

$$\mathbb{E}B_{H,K}(t)B_{H,K}(s) = \frac{1}{2^K} \left( (t^{2H} + s^{2H})^K - |t - s|^{2HK} \right)$$

where  $H, K \in (0,1)$ 

**Note** When K = 1, or H = 1/2, biFBM reduces to FBM.

**Proposition** Let  $B_{H,K}$  be biFBM, then:

- (i) It is (HK)-self-similar
- (ii) It has stationary increments iff K=1
- (iii) For all  $s, t \geq 0$ ,

$$2^{-K}|t-s|^{2HK} \leq \mathbb{E}(B_{H,K}(t)-B_{H,K}(s))^2 \leq 2^{1-K}|t-s|^{2HK}$$



Let Y = Y(t) be an H-SSSI process with 0 < H < 1 and consider the stationary process

$$X_n = Y(n) - Y(n-1), n \in \mathbb{Z}$$

Notice that  $X_n$  has zero mean,  $\mathbb{E} X_n^2 = \mathbb{E} Y(1)^2$ , and

$$\gamma_X(k) = \frac{\mathbb{E}X(1)^2}{2} \{ |k+1|^{2H} + 2|k|^{2H} - |k-1|^{2H} \}$$
$$\sim \mathbb{E}Y(1)^2 H (2H-1)k^{2H-2}$$

By the above observation, if 1/2 < H < 1 then the series X is LRD in the sense of condition II (and hence III) with

$$d = H - \frac{1}{2} \in \left(0, \frac{1}{2}\right) \tag{14}$$

So d and H are closely related.

**Note** When *Y* is FBM, *X* is called fractional Gaussian Noise.

#### **Bibliography**

Long-Range Dependence and Self-Similarity (Cambridge Series in Statistical and Probabilistic Mathematics) **1st Edition, 2017**, Murad Taqqu, Vladas Pipiras