
Introduction to High-Performance Computing

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Agenda

- ✓ **HPC: What it is?**
 - ✓ **Spoiler...**
 - ✓ **Hardware: how it works**
 - ✓ **Algorithm vs. Implementation**
 - ✓ Compiler
 - ✓ Parallel Paradigm
 - ✓ Conclusions & Comments
-

HPC: what it is?

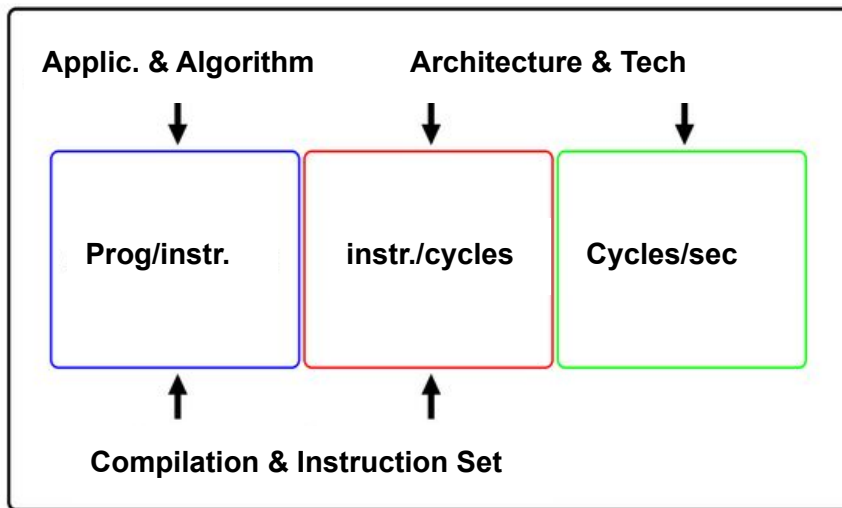
- ✓ These are the main skills for an efficient HPC



Who is in charge of what?

High performance is the joint effort of different “players”

- ✓ **Programmer**: in charge of the choice of the algorithm
- ✓ **Compiler**: in charge of the traduction in instructions
- ✓ **HW**: in charge of execute the instructions



Algorithm

Definition:

a process or set of rules to be followed in calculations or other problem-solving operations, especially by a computer.....

- ✓ From previous lesson we have learned that, for a computer, different instruction can have different impact in time
 - ✓ We are not talking about “correctness” (when time is not an issue) but about “computational complexity”
 - ✓ As example
 - $O(N^2) \ll O(N^4)$ for N big enough (still to define)
 - ✓ The choice, at the beginning, of an inefficient algorithm can be really “dangerous”!
-

Complexity

In computer science, the computational complexity or simply complexity of an algorithm is the amount of resources required to run it. Particular focus is given to computation time (generally measured by the number of needed elementary operations) and memory storage requirements.

- ✓ Each algorithm has its own complexity, i.e. the number of instructions to be performed to complete the work
 - ✓ If ***N*** is the size of the problem ***O(N[?])*** is the problem complexity
 - $MMM \rightarrow O(N^3)$
 - $MMM \text{ (Stressen)} \rightarrow O(N^{2.80})$
 - ✓ Hint:
 - Try to understand complexity of your algorithm
 - Verify if your assumption is correct: it scales as it is supposed to?
 - Stress test algorithm for “real-size” problem: usually development is done using very little problem (in size). too little to be “killed” by high complexity (e.g. cache effects)
 - For little problems size the prefactor could “hide” real performance
-

HW Evolution

Hardware evolution (from 1947 to 1985)

✓ From: More Programming Pearls: Confessions of a Coder, Bentley

HW	Year	Mflops
Manchester Mark 1	1947	0.0002
IBM 701	1954	0.003
IBM Stretch	1960	0.3
CDC 6600	1964	2
CDC 7600	1969	5
Cray-1	1976	50
Cray-2	1985	125

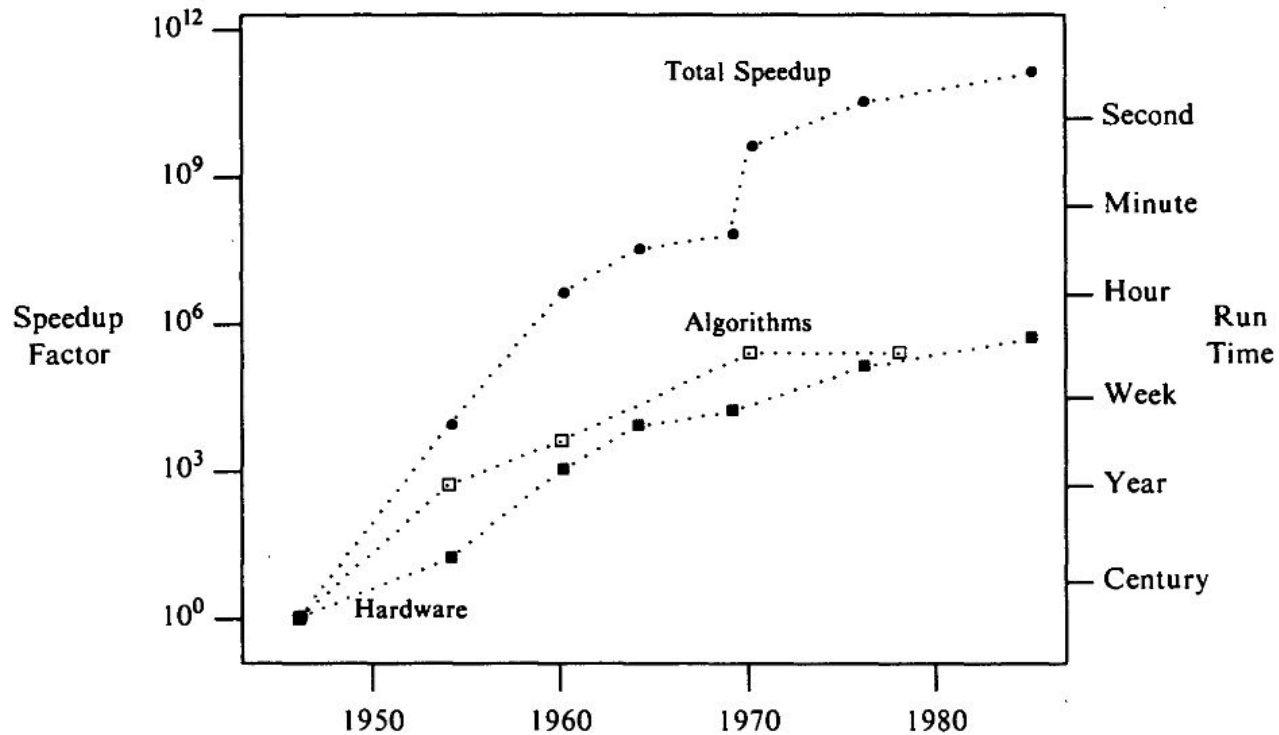
Algorithm Evolution

Algorithm evolution (from 1945 to 1978) for 3D elliptic equation (e.g. pressure)

✓ From: More Programming Pearls: Confessions of a Coder, Bentley

Algorithm	Year	Complexity
Gaussian Elimination	1947	N^7
SOR (suboptimal)	1954	$8N^5$
SOR (optimal)	1960	$8N^4 \log(N)$
Cyclic Reduction	1964	$8N^3 \log(N)$
Multigrid	1969	$60N^3$

Which is more important?



Which the limit?

In HPC is mandatory to know which is the limit do the optimization process?

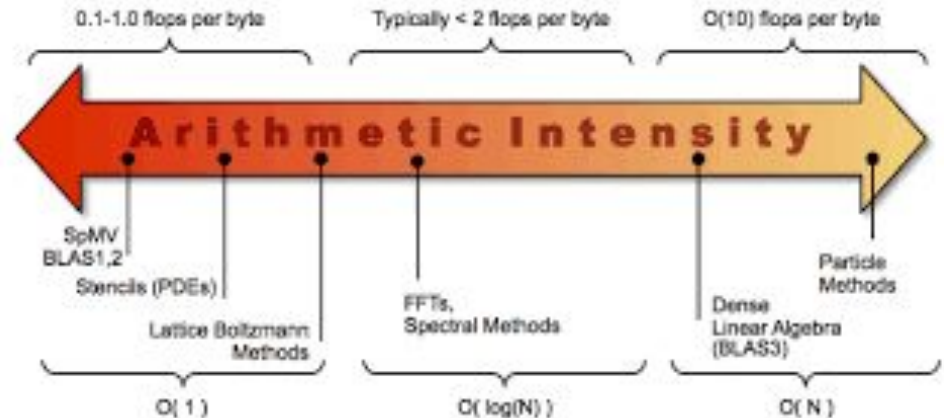
- ✓ How far I am for the limit?
- ✓ I'm inside my time constraint?

A HW system has 2 key figures

- ✓ How many floating point operation I can perform? → FLOPS
- ✓ How many data i can move back and forth → BW

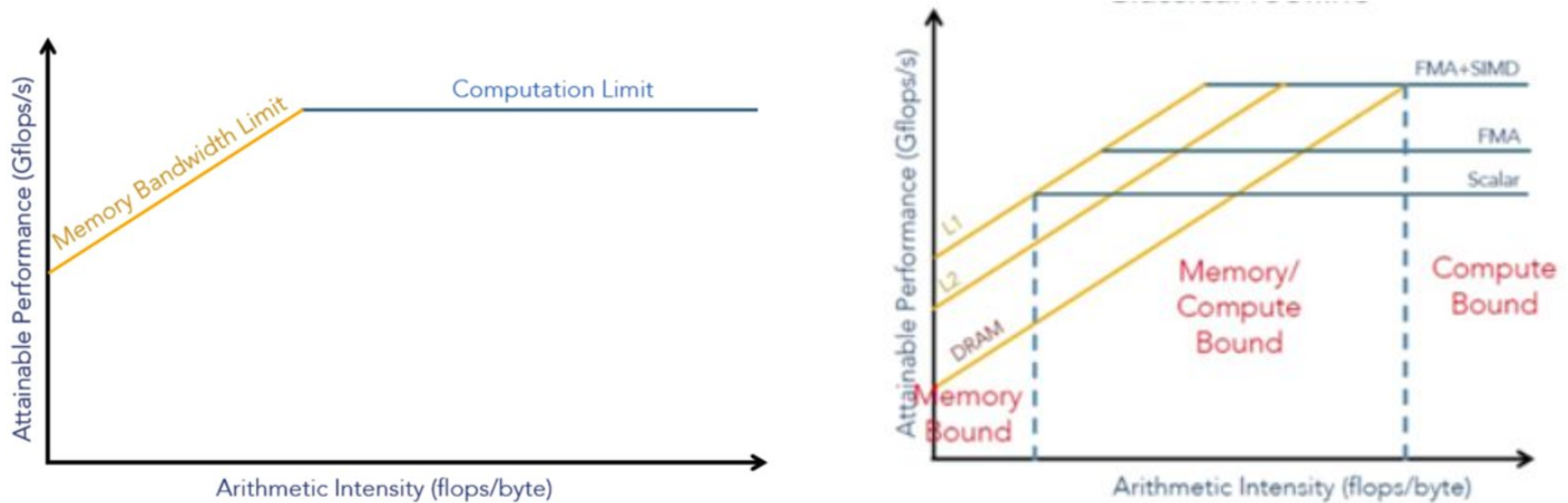
Arithmetic Intensity of a code

- ✓ $A.I = \text{ratio } \#Flops / \#Byte \text{ moved}$



Roofline Model

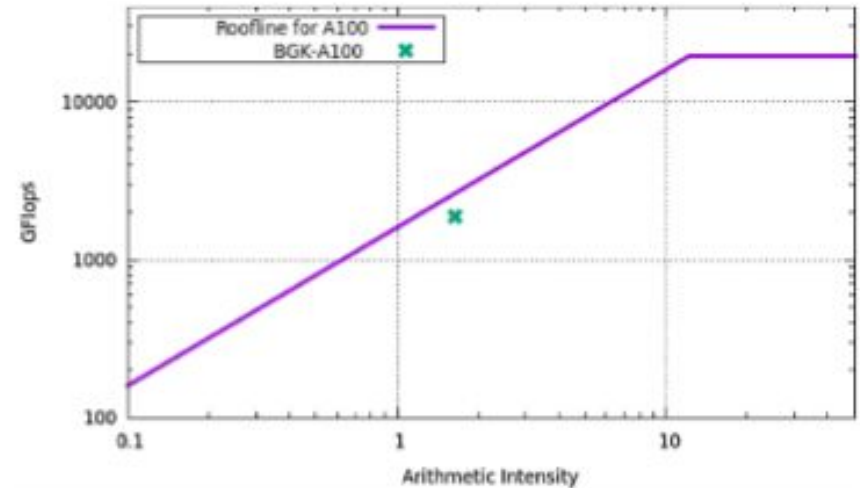
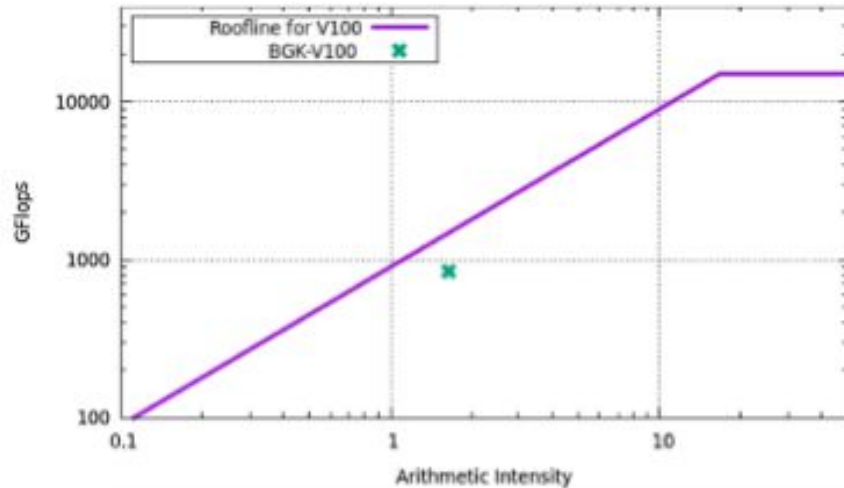
✓ <https://www.nersc.gov/assets/Uploads/Tutorial-ISC2019-Intro-v2.pdf>



Roofline Model

How increase performance?

- ✓ Reduce data movement
- ✓ Increase Floating point operations (?)



Performance evolution/Intel

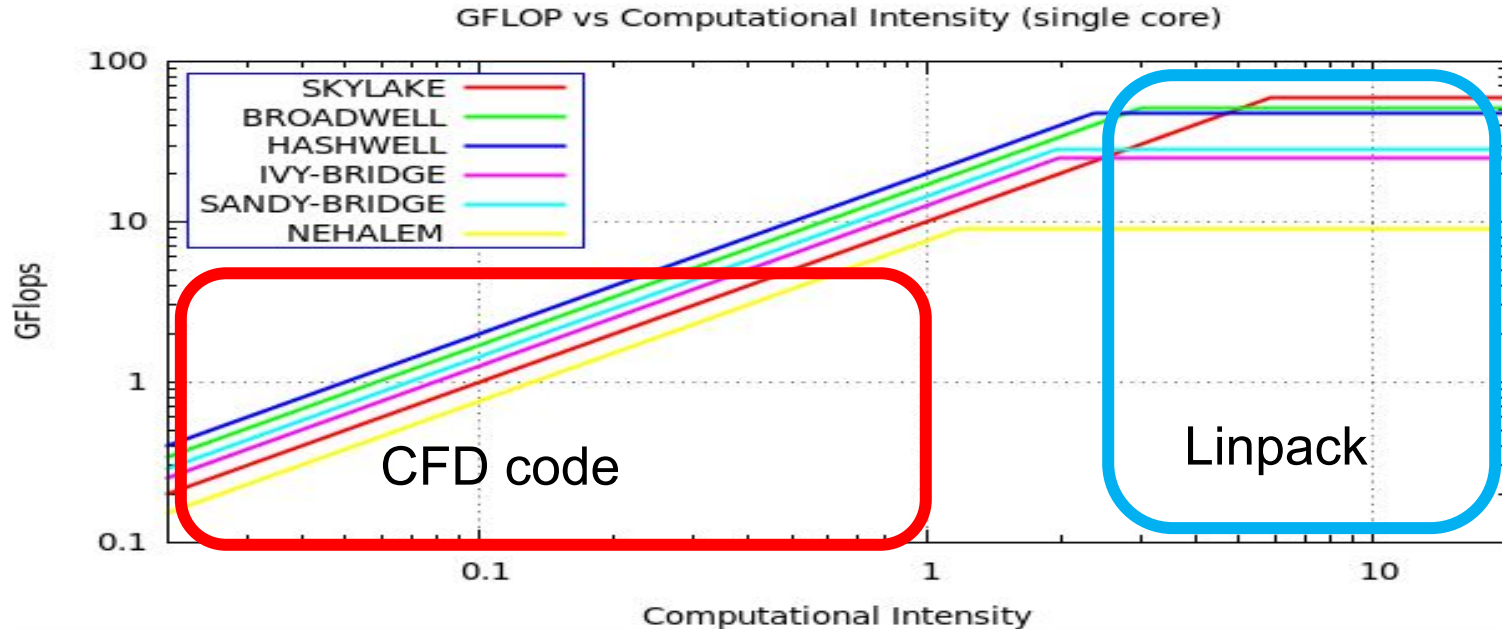
CPU (codename)	Clock Frequency	Number of core	Flops cycle (DP)	Peak Perf. (Gflops)
Xeon E5645 (Westmere)	2.4 GHz	2x6	4	115
Xeon E5-2687W0 (S.Bridge)	3.1 GHz	2x8	8	396
Xeon E5-2670v2 (I. Bridge)	2.5 GHz	2x10	8	400
Xeon E5-2630v3 (Haswell)	2.4 GHz	2x8	16 (AVX-256bit)	614
Xeon E5-2697v4 (Broadwell)	2.3 GHz	2x18	16 (AVX-256bit)	1325
Xeon Platinum (Skylake)	2.1 GHz	2x24	32 (AVX-512bit)	3225



Real performance: serial

Performance ordered with respect to computational intensity (AI) = #flops/#byte

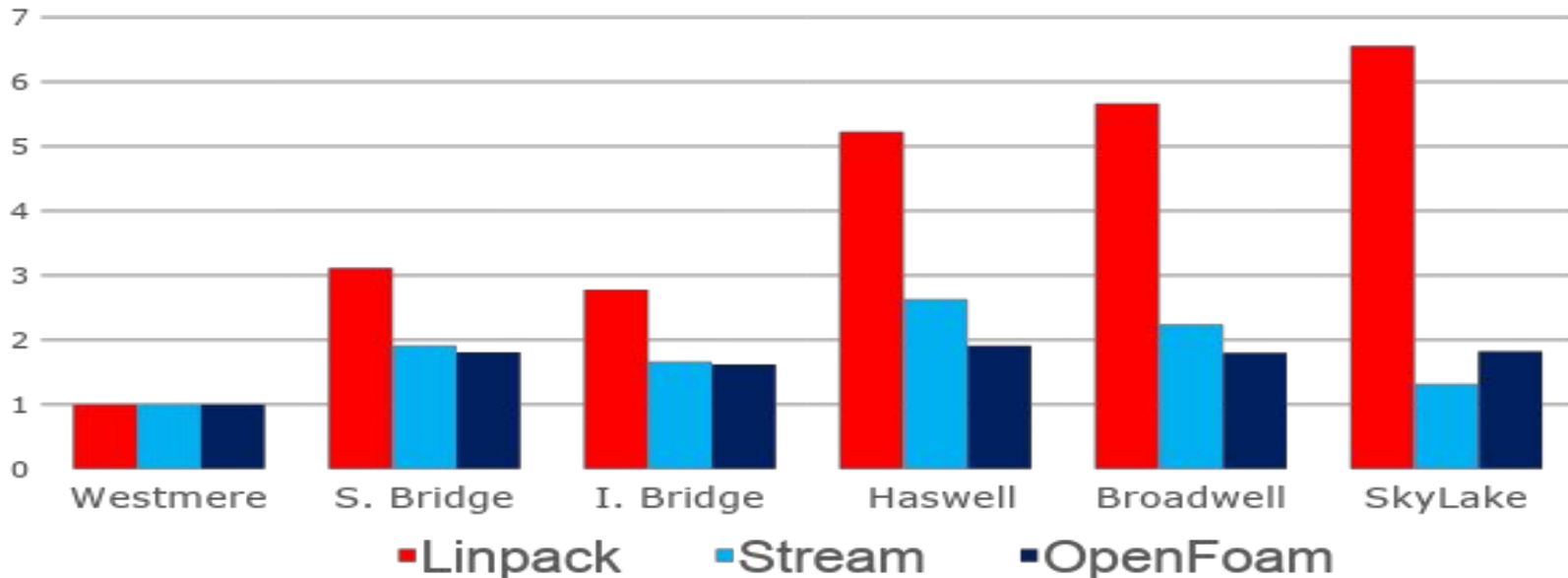
- $CI > 1$ FLOPs limited
- $CI < 1$ BW limited



Real performance Improvements

Performance for single core performance

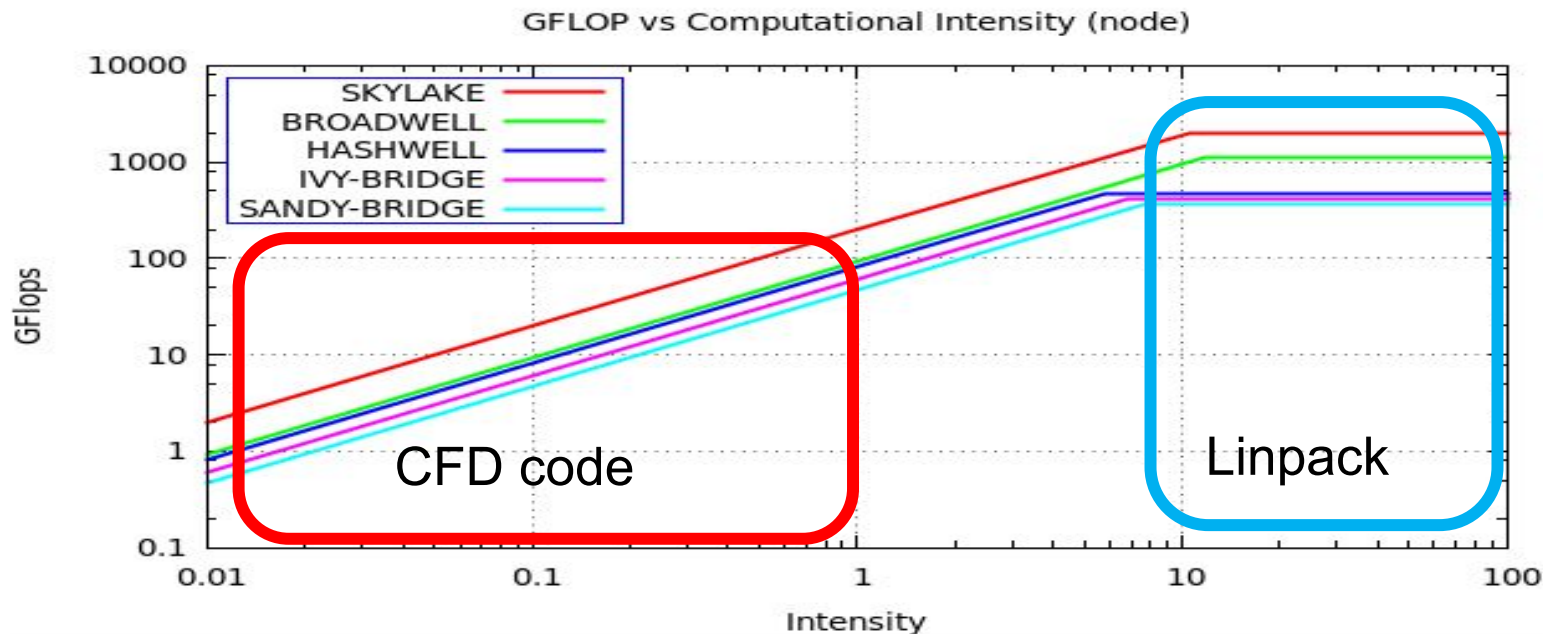
- OpenFoam, 3D lid-driven cavity, 80^3 grid-point, serial
- Linpack
- Stream



Real performance: parallel

Performance ordered with respect to computational intensity (AI): #flops/#byte

- $CI > 1$ FLOPs limited
- $CI < 1$ BW limited



Implementation

Implementation is the execution or practice of a plan, a method or any design, idea, model, specification, standard or policy for doing something.

- ✓ Starting from a well defined Algorithm the programmer write the program
 - Programming languages
 - data allocation
 - data movement
 - I/O
 - compiler, tools
 - HW
 - ✓ Each of these points can improve/depress performance: are implementation issues
-

Instrument your code

Hint

- ✓ Instrument your code with timing functions
- ✓ Not all function but “logical” block (e.g. I/O, FFT, init, diagnostic)

```
call SYSTEM_CLOCK(countD0, count_rate, count_max)
// do something //
call SYSTEM_CLOCK(countD1, count_rate, count_max)
time_loop = real(countD1-countD0)/(count_rate)
```

```
#include <time.h>
...
time1 = clock();
// do something //
time2 = clock();
dub_time = (time2 - time1)/(double) CLOCKS_PER_SEC;
```

Many tool are (or were) used to (also) to profile/monitoring a code and much more, for example

- ✓ GNU perf
 - ✓ GNU gprof
 - ✓ Intel vtune
 - ✓ Nvidia nsight
 - ✓ AMD μ prof
 - ✓ scalasca
 - ✓ [likwid](#)
 - ✓
-

- ✓ Old but useful: gprof flat profile

....

Flat profile:

Each sample counts as 0.01 seconds.

% time	cumulative seconds	self seconds	calls	self ms/call	total ms/call	name
34.25	0.13	0.13	3628800	0.00	0.00	check1
31.61	0.25	0.12	36288000	0.00	0.00	d
10.54	0.29	0.04	1	40.04	40.04	getgeom
9.22	0.33	0.04	12470600	0.00	0.00	swap
7.90	0.36	0.03	72576000	0.00	0.00	sqr
5.27	0.38	0.02	1	20.02	340.34	search1
1.32	0.38	0.01	3628800	0.00	0.00	save
0.00	0.38	0.00	1	0.00	340.34	solve1

- ✓ Sld but useful: gprof call profile

```

index      %      time self  children  called  name
                                <spontaneous>
[1] 100.0      0.00 0.38
                        0.00 0.34      1/1      solve1 [3]
                        0.04 0.00      1/1      getgeom [6]
-----
                        6235300
                        0.02 0.32      1/1      solve1 [3]
[2] 89.5      0.02 0.32      1+6235300  search1 [2]
                        0.13 0.16 3628800/3628800  check1 [4]
                        0.04 0.00 12470600/12470600  swap [7]
                        6235300
                        search1 [2]
-----

```

gprof syntax

A three step procedure

1. compile (all) the code with option “-pg”
 - `gcc -pg myfile.c -o myfile.x`
2. run the exe: it will create a gmon.out binary file
3. process the gmon.out file (standard output)
 - `gprof ./myfile.x > gprof.txt`

Caveat

- ✓ I could be intrusive
 - ✓ Also linking step with flag “-pg”
 - ✓ (unfortunately) is no more supported by some compilers :-)
-

Profile: Best Practices

- ✓ Check with your code complexity which performance are you expecting
 - If they don't agree there's an issue
 - ✓ Verify to be big enough not to fit entirely in cache
 - Verify performance for all code/function/subroutines
 - Cache hide real code latencies
 - ✓ Take care of profiling intrusivity
 - Always take care of timing with or without profiling
 - ✓ Use different Hw/Sw
 - Can help to detect "strange" behaviour
 - ✓ Useful to understand the code flow
 - especially if you don't have written the code!
-

MMM: implementation issues

Performance in Mflops (higher is better)

- ✓ HW: Intel(R) Xeon(R) Platinum 8260 CPU @ 2.40GHz
- ✓ Compiler intel 2021.5
 - `ifort -O1`
- ✓ Matrix size: 2048 (96 MB)

Optimization	Mflops	Ratio
simple	2210	1
blocking (32)	2928	1.32x
unrolling x 4 (j)	3267	1.48x
unrolling x 4 (i)	2530	1.14x
unrolling x 2 (k)	3420	1.55x
All together	5653	2.56x

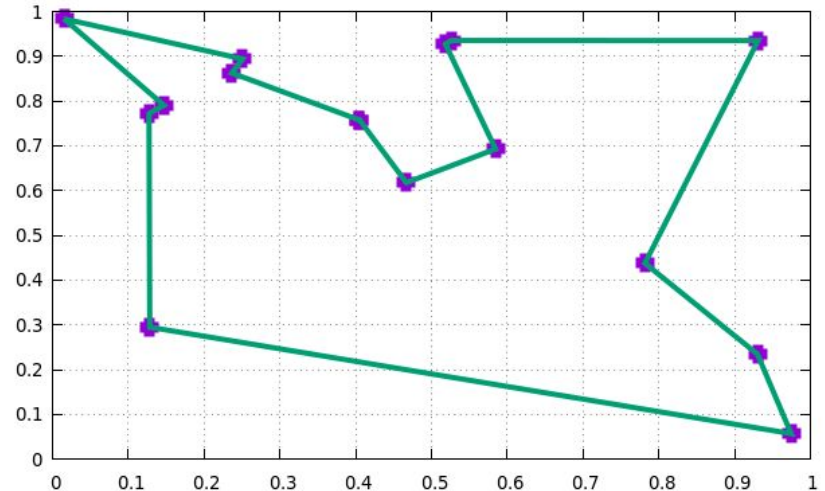
Example: Travel Salesman

https://en.wikipedia.org/wiki/Travelling_salesman_problem

Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?

It is NP-complex problem: our approach

1. Brute force
2. Reducing combinations
3. Reducing functions
4. Reducing comparison
5. Precomputing distances



Travel Salesman/1

Brute-force approach: compute all $N!$ combinations, where N is the number of cities to visit, unfortunately

- ✓ $10! = 3628800$
- ✓ $11! = 479001600$
- ✓ ...
- ✓ $20! = 2432902008176640000$

Really unfeasible! Any Idea?

time	seconds	seconds	calls	ms/call	ms/call	name
34.25	0.13	0.13	3628800	0.00	0.00	check1
31.61	0.25	0.12	36288000	0.00	0.00	d
10.54	0.29	0.04	1	40.04	40.04	getgeom
9.22	0.33	0.04	12470600	0.00	0.00	swap
7.90	0.36	0.03	72576000	0.00	0.00	sqr
5.27	0.38	0.02	1	20.02	340.34	search1
...						

Travel Salesman/2

Reducing combinations

- ✓ We don't need to compute ALL the distances. A lot are computed many times
- ✓ the distances with 4 cities (A,B,C,D)
 - $ABCD = BCDA = CDAB = DABC$
- ✓ You don't have to compute $N!$ distances but (only) $(n+1)!$ starting from a fixed city
- ✓ Big gain as N increase

time	seconds	seconds	calls	ms/call	ms/call	name
66.73	0.02	0.02	362880	0.00	0.00	check1
33.37	0.03	0.01	3628800	0.00	0.00	d
0.00	0.03	0.00	7257600	0.00	0.00	sqr
0.00	0.03	0.00	1247058	0.00	0.00	swap
0.00	0.03	0.00	362880	0.00	0.00	save

Travel Salesman/3

Reducing functions

- ✓ We don't need to recompute all the distances for every single tour.
- ✓ Fix the distance between m cities and compute distance for remaining $n-m$ cities

time	seconds	seconds	calls	ms/call	ms/call	name
35.75	0.03	0.03	1349289	0.00	0.00	d
21.45	0.04	0.02	1	15.02	65.07	search3
14.30	0.05	0.01	1247058	0.00	0.00	swap
14.30	0.06	0.01	362880	0.00	0.00	check3
7.15	0.07	0.01	2698578	0.00	0.00	sqr

Travel Salesman/4

Check distances

- ✓ instead of check the final distance of a tour for the minimal stop the search if the (partial) tour is longer of the minimum found

time	seconds	seconds	calls	ms/call	ms/call	name
100.10	0.01	0.01	111515	0.00	0.00	d
0.00	0.01	0.00	223030	0.00	0.00	sqr
0.00	0.01	0.00	213374	0.00	0.00	swap
0.00	0.01	0.00	2414	0.00	0.00	check3
0.00	0.01	0.00	2414	0.00	0.00	save

Travel Salesman/5

Precomputing distances

- ✓ The distance between A and B will be computed many time (i.e. build a **look-up table**)
- ✓ Precompute once and then access (matrix of n^2 elements)

time	seconds	seconds	calls	ms/call	ms/call	name
100.10	0.01	0.01	1	10.01	10.01	search5
0.00	0.01	0.00	213374	0.00	0.00	swap
0.00	0.01	0.00	2414	0.00	0.00	check5
0.00	0.01	0.00	2414	0.00	0.00	save
0.00	0.01	0.00	200	0.00	0.00	sqr

Travel Salesman: some figures

Results, in seconds, using IBM Power4@1100 Mhz (many time ago)

	9	10	11	12	13	14	15
1	0.92	10.3	123	1538	-	-	-
2	0.10	1.03	11.2	134	-	-	-
3	-	0.46	4.59	50.5	606	-	-
4	-	-	0.29	1.50	11.3	98.7	-
5	-	-	0.11	0.57	4.29	37.6	288

- ✓ Reducing unnecessary operation
- ✓ Removing repetition
- ✓ profiling help to focus on function to remove!

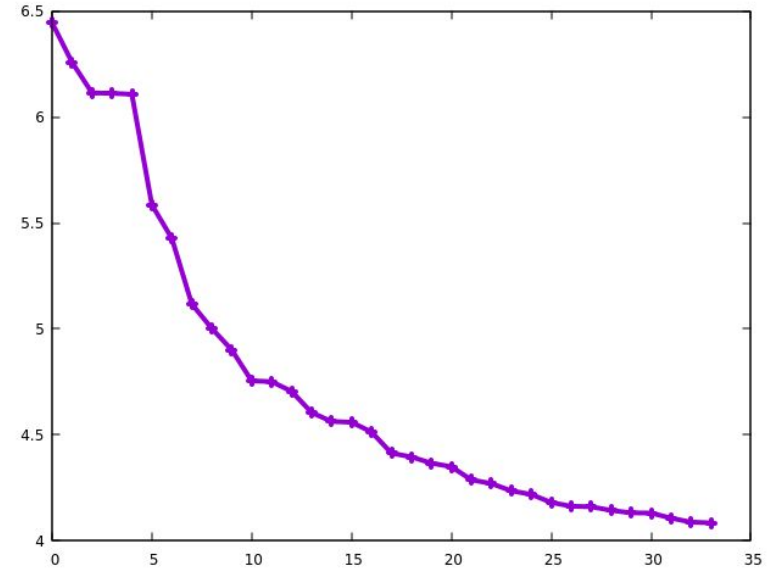
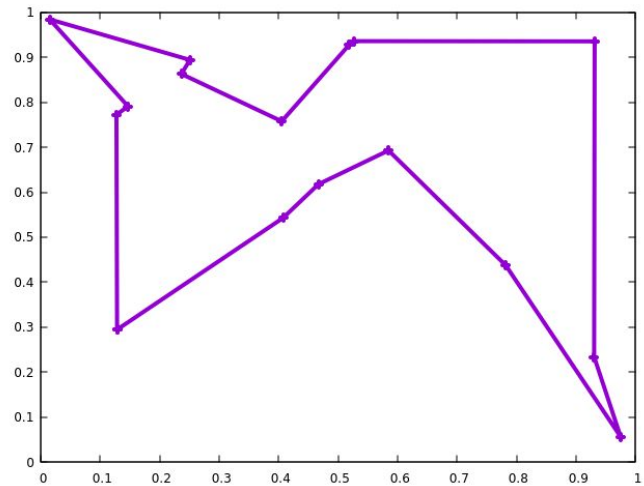
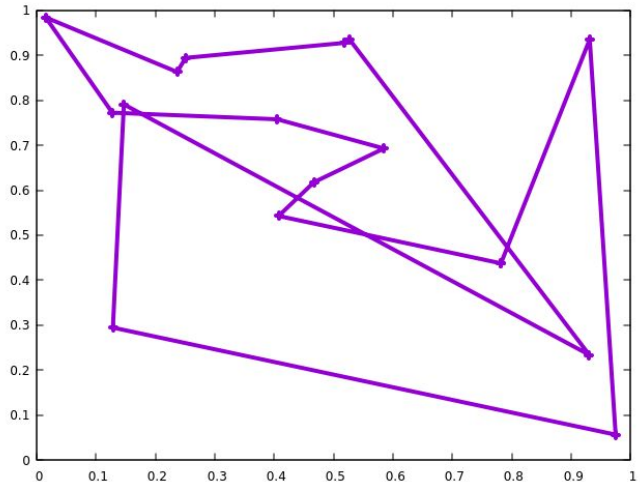
Travel Salesman: some (new) figures

Results, in seconds, using the AMD Ryzen 5 5625U (with gcc)

	13	14	15	16
4	0.66''	5.75''	43.6''	-
5	0.39''	3.33''	24.6''	170''
5 - initial condition	-	-	-	24.7''

- ✓ Reducing unnecessary operation
 - ✓ Removing repetition
 - ✓ a good initial condition can help (from rel. 4)
 - ✓ profiling help to focus on operations to remove/optimize!
 - ✓ HW improvement helps, but SW are bigger!!!
-

Travel Salesman: 16 cities



Sieve of Eratosthenes

- ✓ https://en.wikipedia.org/wiki/Sieve_of_Eratosthenes
- ✓ One of the first known Algorithm for finding prime numbers
 - much older than computers!
 - It is an iterative algorithm

	2	3	4	5	6	7	8	9	10	Prime numbers
11	12	13	14	15	16	17	18	19	20	
21	22	23	24	25	26	27	28	29	30	
31	32	33	34	35	36	37	38	39	40	
41	42	43	44	45	46	47	48	49	50	
51	52	53	54	55	56	57	58	59	60	
61	62	63	64	65	66	67	68	69	70	
71	72	73	74	75	76	77	78	79	80	
81	82	83	84	85	86	87	88	89	90	
91	92	93	94	95	96	97	98	99	100	
101	102	103	104	105	106	107	108	109	110	
111	112	113	114	115	116	117	118	119	120	

Sieve of Eratosthenes: step0

- ✓ https://en.wikipedia.org/wiki/Sieve_of_Eratosthenes
- ✓ First implementation

```
parameter(nd=50000)                ! max number to check
...
do i = 2, nd
    a(i) = 0                        ! possible prime number
enddo
...
do icheck = 2, nd
    do i = icheck+1, nd
        if (mod(i,icheck).eq.0) then
            a(i) = 1                ! i is not a prime number
        endif
    enddo
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-

Sieve of Eratosthenes: step 1

- ✓ The original code performs a lot of “useless” check.
- ✓ It checks, for example, all the number that are divisible by 4, that are a subset of those divisible by 2.
- ✓ You have to check only with numbers that you know are candidate as prime, i.e. those with $a(i)=0$

```
parameter(nd=50000)                ! max number to check
...
do  icheck = 2, nd
  do  i = icheck+1, nd
    if (a(i).eq.0) then
      if (mod(i,icheck).eq.0) then
        a(i) = 1                ! i is not a prime number
      endif
    endif
  enddo
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%

Sieve of Eratosthenes: step 2

- ✓ Other “useless” operation to skip
- ✓ If you know that a number is not a prime you can skip the check

```
parameter(nd=50000)                ! max number to check
...
do icheck = 2, nd
  if (a(icheck).eq.0) then
    do i = icheck+1, nd
      if (a(i).eq.0) then
        if (mod(i,icheck).eq.0) then
          a(i) = 1                ! i is not a prime number
        endif
      endif
    enddo
  endif
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%
Step2	212	95.8%

Sieve of Eratosthenes: step 3

- ✓ Other “useless” operation to skip
- ✓ If m is the biggest prime number found you must start the search from $m*m$

```
parameter(nd=50000)                ! max number to check
...
do icheck = 2, nd
  if (a(icheck).eq.0) then
    do i = icheck*icheck, nd
      if (a(i).eq.0) then
        if (mod(i,icheck).eq.0) then
          a(i) = 1                ! i is not a prime number
        endif
      endif
    enddo
  endif
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%
Step2	212	95.8%
Step3	1.21	99.976%

Sieve of Eratosthenes: step 4

- ✓ Instead of check modulo (i.e. a division) we mark directly the multiple (i.e. multiplication)

```
parameter(nd=50000)                ! max number to check
...
do icheck = 2, nd
  if (a(icheck).eq.0) then
    imax = INT(nd/i)
    do i=1,imax
      a(i*icheck) = 1                ! i is not a prime number
    enddo
  endif
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%
Step2	212	95.8%
Step3	1.21	99.976%
Step4	0.13	99.9974%

Sieve of Eratosthenes: step 5 (fine tuning)

- ✓ Mark as non-prime number up to 30 in the initialization step
- ✓ Where is the problem?

```
a( 2) = 0           ! prime
a( 3) = 0           ! prime
a( 4) = 1
a( 5) = 0           ! prime
....
a(30) = 1
do i=30,nd,30
  a(i+ 1) = 0       ! could be a prime
  a(i+ 2) = 1
  a(i+ 3) = 1
  a(i+ 4) = 1
  a(i+ 5) = 1
  ....
  a(i+29) = 0       ! could be a prime
  a(i+30) = 1
enddo
```

Sieve of Eratosthenes: figures

✓ Intel PentiumIII, 700 Mhz (old stuff)

	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%
Step2	212	95.8%
Step3	1.21	99.976%
Step4	0.13	99.9974%
Step5	0.094	99.9982%

Sieve of Eratosthenes: step 6 (fine tuning)

- ✓ Limit the search up to \sqrt{nd}
 - it could be is the biggest prime number up to nd

```
parameter(nd=50000)                ! max number to check
...
do icheck = 7, INT(sqrt(float(nd)))
  if (a(icheck).eq.0) then
    imax = INT(nd/i)
    do i=1,imax
      a(i*icheck) = 1              ! i is not a prime number
    enddo
  endif
enddo
```

Sieve of Eratosthenes: figures

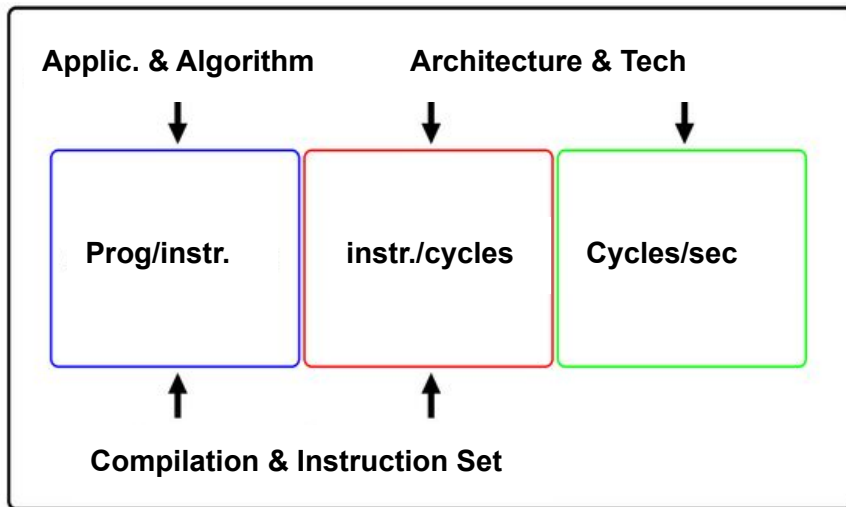
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	Time (s)	Gain (%)
Step0	5118	-
Step1	2383	53.5%
Step2	212	95.8%
Step3	1.21	99.976%
Step4	0.13	99.9974%
Step5	0.094	99.9982%
Step6	0.078	99.9985%

Who is in charge of what (reprise)?

High performance is the joint effort of different “players”

- ✓ **Programmer**: in charge of the choice of the algorithm
- ✓ **Compiler**: in charge of the traduction in instructions
- ✓ **HW**: in charge of execute the instructions



Different operations, different cost

✓ Different costs

- sum → few cycles
- product → few cycles
- division → many cycles
- square root → many many cycles
- exponent → many cycles
- trigonometric functions → many cycles
- data access → few/many access

✓ (possible) Solutions

- Lookup table
 - If range limited
 - polynomial approximation
 - taylor series
 - prostaferesi formula
-

Recap

- ✓ Take care of the chosen Algorithm
 - You (should) know how it works and which operations perform or remove (e.g. TSP)
 - ✓ Take care of Algorithm Implementation
 - Data allocation
 - Data access
 - Operation to be performed
 - ✓ timing/profiling could help
 - in finding bottlenecks
 - in understanding where you're wrong
 - ✓ In general: coding style could seriously affect performance
 - Loop ordering
 - ✓ Some operation are more “expensive” with respect to others
-

(some) Keywords

- ✓ **Look-up table:** precomputed data. It could be a gain in time (size dependent)
 - ✓ **Roofline model**
 - ✓ **Algorithm complexity**
 - ✓ **Bandwidth limited code**
 - ✓ **FP limited code**
-

Some references

- ✓ [Bentley, More Programming Pearls \(2nd Ed.\), ACM Press/Addison-Wesley, 1989](#)
 - ✓ [Bentley, DDJ, 1999](#)
 - ✓ [Discovering faster matrix multiplication algorithms with reinforcement learning, Nature, 2023,](#)
 - ✓ [Dispense Master HPC 2007](#)
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