

6. (a) Define  $L : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$  by  $L(A) = A + A^T$

(a) Show that  $L$  is a linear operator.

We need to check

$$L(\alpha A + \beta B) = \alpha L(A) + \beta L(B)$$

for any scalars  $\alpha, \beta$  and  $A, B \in \mathbb{R}^{2 \times 2}$

$$\begin{aligned} \text{LHS} &= \alpha A + \beta B + (\alpha A + \beta B)^T \\ &= \alpha A + \beta B + \alpha A^T + \beta B^T \end{aligned}$$

$$\begin{aligned} \text{RHS} &= \alpha (A + A^T) + \beta (B + B^T) \\ &= \alpha A + \alpha A^T + \beta B + \beta B^T \end{aligned}$$

the same

So  $\text{LHS} = \text{RHS}$ .  $L$  is a linear transformation.

(b) Find  $\ker L$  and its dimension.

Solve  $L(A) = 0$ ,  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathbb{R}^{2 \times 2}$

$$A + A^T = 0$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} + \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 2a & b+c \\ c+b & 2d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 2a & b+c \\ c+b & 2d \end{pmatrix} = \begin{pmatrix} 0 & 0 \end{pmatrix}$$

$$2a = 0 \rightarrow a = 0$$

$$b+c = 0 \rightarrow b = -c$$

$$c+b = 0 \rightarrow c = -b$$

$$2d = 0 \rightarrow d = 0$$

$$\left. \begin{array}{l} 2a = 0 \rightarrow a = 0 \\ b+c = 0 \rightarrow b = -c \\ c+b = 0 \rightarrow c = -b \\ 2d = 0 \rightarrow d = 0 \end{array} \right\} \rightarrow A = \begin{pmatrix} 0 & b \\ -b & 0 \end{pmatrix}$$

$$\text{Ker } L = \left\{ \begin{pmatrix} 0 & b \\ -b & 0 \end{pmatrix} \right\} = \text{span} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

$$\rightarrow \dim(\text{Ker } L) = 1.$$

(c) Find the matrix representation of  $L$ .

$$L(A) = \begin{pmatrix} 2a & b+c \\ b+c & 2d \end{pmatrix}, A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$E = \{ \text{standard basis of } \mathbb{R}^{2 \times 2} \}$$

$$\rightarrow [A]_E = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}; [L(A)]_E = \begin{pmatrix} 2a \\ b+c \\ c+b \\ 2d \end{pmatrix}$$

$$\begin{pmatrix} 2a \\ b+c \\ c+b \\ 2d \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$E = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

5. Determine whether the following are linear transformation in  $C^1[-1, 1]$ , the set of all differentiable functions in  $[-1, 1]$ :

(a)  $L(f(x)) = x^2 + f(x)$  for  $f \in C^1[-1, 1]$ .

Check  $L(\alpha f + \beta g) = \alpha L(f) + \beta L(g)$

for any  $\alpha, \beta \in \mathbb{R}$ ,  $f, g$  are functions.

LHS  $= x^2 + (\alpha f + \beta g)(x)$

$= x^2 + \alpha f(x) + \beta g(x)$

RHS  $= \alpha (x^2 + f(x)) + \beta (x^2 + g(x))$

$= \alpha x^2 + \alpha f(x) + \beta x^2 + \beta g(x)$

B/c  $\alpha x^2 + \beta x^2 = (\alpha + \beta)x^2 \neq x^2$ ,  $LHS \neq RHS$ .

\*  $E = \{v_1, v_2, \dots, v_n\}$  is a basis of  $V$ .

Any vector  $v \in V$  has a coordinate  $[v]_E = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$  if

$v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$

1b)  $E = \{ \underbrace{(1, 1)^T}_{v_1}, \underbrace{(1, 2)^T}_{v_2} \}$

$x = (2, 3)^T$

Whether  $[x]_E = (1, 1)^T \rightarrow x = 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 1 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \text{ (true)}$

(d)  $L(x_1, x_2) = (x_1 x_2, x_2)$  is a linear operator from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ .

$L(0, 1) = (0, 1)$

$$\begin{aligned}
 L(\underbrace{(0,1)}_x) &= (0,1) \\
 L(\underbrace{(1,2)}_y) &= (2,2) \\
 L(\underbrace{(1,3)}_{x+y}) &= (3,3)
 \end{aligned}
 \left. \vphantom{\begin{aligned} L(\underbrace{(0,1)}_x) &= (0,1) \\ L(\underbrace{(1,2)}_y) &= (2,2) \\ L(\underbrace{(1,3)}_{x+y}) &= (3,3) \end{aligned}} \right\} \rightarrow \underbrace{L(x+y)}_{(3,3)} \neq \underbrace{L(x) + L(y)}_{(0,1) + (2,2)} = (2,3)$$

not a linear transformation.

8. (5 pts for each) Given an  $5 \times 4$  matrix  $A$  with  $\text{rank}(A) = 4$ .

(a) How many solutions are there for equation  $Ax = 0$ ? Explain your answer.

$$\underbrace{\text{rank}(A)}_{\# \text{ leading variables}} + \underbrace{\text{nullity}(A)}_{\# \text{ free variable}} = n$$

$$4 + 0 = 4$$

A unique solution of  $Ax = 0$ .

(b) How many solutions are there for equation  $A^T y = 0$ ? Explain your answer.

$$\underbrace{\text{rank}(A^T)}_{\text{rank}(A)} + \underbrace{\text{nullity}(A^T)}_{n-m} = m$$

$$4 + 1 = 5$$

$$\text{nullity}(A^T) = 1$$

→ one free variable → infinitely many solutions

7,  $A$  is an  $6 \times n$  matrix of rank  $r$ .

7/3.6  $A$  is an  $6 \times n$  matrix of rank  $r$ .

(a)  $n = 7, r = 5$ . How many solutions of  $Ax = b$ ?

$$\underbrace{\text{rank } A}_5 + \underbrace{\text{nullity}(A)}_2 = n = 7$$

→ 2 free variables.

↙ no solution  
or  
↘ infinitely many solutions.

(c)  $n = 5, r = 5$

$$\underbrace{\text{rank}(A)}_5 + \underbrace{\text{nullity}(A)}_0 = n = 5$$

→ no free variable

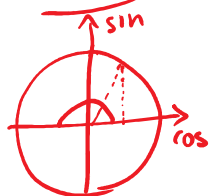
$(A|b) \xrightarrow{\text{Gaussian}} \dots \left( \begin{array}{ccc|ccc} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)_{6 \times 7}$  zero or non zero.

No solution or a unique solution.

$$\sqrt{4} = 2$$

$$x^2 = 4$$

$$\rightarrow x = 2 \text{ or } -2$$



4. Given  $v = (1, -1, 1, 1)^T$  and  $w = (4, 2, 2, 1)^T$ .

(a) Determine the angle between  $v$  and  $w$ .

$$\cos \theta = \frac{v^T w}{\|v\| \cdot \|w\|} = \frac{1 \cdot 4 - 2 + 2 + 1}{\sqrt{1+1+1+1} \cdot \sqrt{16+4+4+1}} = \frac{5}{\sqrt{4} \sqrt{25}} = \frac{5}{2 \cdot 5} = \frac{1}{2}$$

$$\theta = \cos^{-1}\left(\frac{1}{2}\right)$$

(b) Find the orthogonal complement of  $V = \text{span}\{v, w\}$ .

$$V^\perp = \{x \mid x \perp v \text{ for any } v \in V\}$$

$$= \{x \mid \underbrace{x \perp v} \text{ and } \underbrace{x \perp w}\}$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \quad x \perp v \rightarrow x^T v = 0 \rightarrow x_1 - x_2 + x_3 + x_4 = 0$$

$$x \perp w \rightarrow x^T w = 0 \rightarrow 4x_1 + 2x_2 + 2x_3 + x_4 = 0$$

$$\left( \begin{array}{cccc|c} 1 & -1 & 1 & 1 & 0 \\ 4 & 2 & 2 & 1 & 0 \end{array} \right) \xrightarrow{R_2 - 4R_1} \left( \begin{array}{cccc|c} 1 & -1 & 1 & 1 & 0 \\ 0 & 6 & -2 & -3 & 0 \end{array} \right)$$

$$\xrightarrow{R_2/6} \left( \begin{array}{cccc|c} 1 & -1 & 1 & 1 & 0 \\ 0 & 1 & -\frac{1}{3} & -\frac{1}{2} & 0 \end{array} \right) \xrightarrow{R_1 + R_2} \left( \begin{array}{cccc|c} 1 & 0 & \frac{2}{3} & \frac{1}{2} & 0 \\ 0 & 1 & -\frac{1}{3} & -\frac{1}{2} & 0 \end{array} \right)$$

$$\begin{cases} x_3 = t \\ x_4 = s \end{cases} \rightarrow \begin{aligned} x_2 &= \frac{1}{3}t + \frac{1}{2}s \\ x_1 &= -\frac{2}{3}t - \frac{1}{2}s \end{aligned}$$

$$\rightarrow x = \begin{pmatrix} -\frac{2}{3}t - \frac{1}{2}s \\ \frac{1}{3}t + \frac{1}{2}s \\ t \\ s \end{pmatrix} \rightarrow V^\perp$$

$$V^\perp = \text{span} \left\{ \begin{pmatrix} -\frac{2}{3} \\ \frac{1}{3} \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \\ 1 \end{pmatrix} \right\} \rightarrow \underline{\underline{\dim V^\perp = 2}}$$

3. Let  $A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & -3 & -2 \\ 3 & 3 & 0 & 2 \end{pmatrix}$ .

(a) Find a basis of  $N(A)$ , row space of  $A$ , column space of  $A$ .

$$\left( \begin{array}{cccc|c} 1 & 2 & 3 & 4 & 0 \\ 2 & 1 & -3 & -2 & 0 \\ 3 & 3 & 0 & 2 & 0 \end{array} \right) \xrightarrow{\dots} \left( \begin{array}{cccc|c} 1 & 0 & -3 & -8 & 0 \\ 0 & 1 & 3 & \frac{10}{3} & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\begin{cases} x_3 = t \\ x_4 = s \end{cases}$$

↑  
column  
1, 2

$$RS(A) = \text{span} \left\{ \left( 1, 0, -3, -\frac{8}{3} \right), \left( 0, 1, 3, \frac{10}{3} \right) \right\}$$

$$\rightarrow CS(A) = \text{span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} \right\}$$

$$(a+b)^2 = a^2 + 2ab + b^2$$

7. Let  $\|\cdot\|$  be the Euclidean norm in  $\mathbb{R}^n$ . For any  $x, y \in \mathbb{R}^n$ ,

(a) Show that  $\|x+y\|^2 = \|x\|^2 + \|y\|^2 + 2x^T y$

$$\|x\| = \sqrt{x^T x}$$

$$\|x\|^2 = x^T x$$

$$LHS = (x+y)^T (x+y)$$

$$= (x^T + y^T) (x+y)$$

$$= \underbrace{x^T x} + \underbrace{x^T y} + \underbrace{y^T x} + \underbrace{y^T y}$$

$$= \|x\|^2 + 2x^T y + \|y\|^2$$

(b) Show that  $\|x+y\|^2 + \|x-y\|^2 = 2(\|x\|^2 + \|y\|^2)$

$$\underbrace{\|x\|^2} + \underbrace{\|y\|^2} + \underbrace{2x^T y} + \underbrace{\|x\|^2} + \underbrace{\|y\|^2} - \underbrace{2x^T y}$$

$$2\|x\|^2 + 2\|y\|^2$$

RHS