## Homework Assignment 6

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**Problem 4.3.** Find the solutions of the following systems of equations with the initial data:

a. 
$$\frac{dx}{dt} = x - 2y$$
,  $x(0) = 1$   
 $\frac{dy}{dt} = y - 2x$ ,  $y(0) = 0$ 

Solution. a. Applying the Laplace transform to the system yields

$$\mathcal{L}\left\{\frac{dx}{dt}\right\} = s\bar{x}(s) - x(0) = \bar{x}(s) - 2\bar{y}(s) = \mathcal{L}\left\{x - 2y\right\}$$

$$\mathcal{L}\left\{\frac{dy}{dt}\right\} = s\bar{y}(s) - s\bar{y}(s) - \bar{y}(s) - 2\bar{y}(s) - \mathcal{L}\left\{x - 2y\right\}$$

 $\mathscr{L}\left\{\frac{dy}{dt}\right\} = s\bar{y}(s) - y(0) = \bar{y}(s) - 2\bar{x}(s) = \mathscr{L}\left\{y - 2x\right\}.$ 

Using the initial data, the transformed system becomes

$$(s-1)\bar{x}(s) + 2\bar{y}(s) = 1$$
  
 $2\bar{x}(s) + (s-1)\bar{y}(s) = 0$ 

or, equivalently,

$$\begin{bmatrix} s-1 & 2 \\ 2 & s-1 \end{bmatrix} \begin{bmatrix} \bar{x}(s) \\ \bar{y}(s) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

This implies that the solution to the transformed system of equations is given by

$$\begin{bmatrix} \bar{x}(s) \\ \bar{y}(s) \end{bmatrix} = \begin{bmatrix} s-1 & 2 \\ 2 & s-1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{s-1}{(s-3)(s+1)} & -\frac{2}{(s-3)(s+1)} \\ -\frac{2}{(s-3)(s+1)} & \frac{s-1}{(s-3)(s+1)} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{s-1}{(s-3)(s+1)} \\ -\frac{2}{(s-3)(s+1)} \end{bmatrix}$$

i.e. the solution is given by  $\bar{x}(s) = \frac{s-1}{(s-3)(s+1)}$  and  $\bar{y}(s) = -\frac{2}{(s-3)(s+1)}$ .

From our table of Laplace Transforms, we know that

$$\mathscr{L}\left\{e^{at} - e^{bt}\right\} = \frac{a - b}{(s - a)(s - b)}$$

and

$$\mathscr{L}\left\{\frac{ae^{at} - be^{bt}}{a - b}\right\} = \frac{s}{(s - a)(s - b)}.$$

Therefore, the solution to the original system of differential equations is given by

$$\begin{split} x(t) &= \mathscr{L}^{-1}\left\{\bar{x}(s)\right\} = \mathscr{L}^{-1}\left\{\frac{s-1}{(s-3)(s+1)}\right\} \\ &= \mathscr{L}^{-1}\left\{\frac{s}{(s-3)(s+1)}\right\} - \mathscr{L}^{-1}\left\{\frac{1}{(s-3)(s+1)}\right\} \\ &= \frac{3e^{3t} + e^{-t}}{4} - \frac{e^{3t} - e^{-t}}{r} \\ &= \frac{e^{3t} + e^{-t}}{2} \end{split}$$

and

$$y(t) = \mathcal{L}^{-1} \{ \bar{y}(s) \} = \mathcal{L}^{-1} \left\{ -\frac{2}{(s-3)(s+1)} \right\}$$
$$= \frac{e^{-t} - e^{3t}}{2}$$

**Problem 4.12.** Solve the following initial value problems:

a. 
$$\ddot{x} + \omega^2 x = \cos nt$$
,  $x(0) = 1$ ,  $\dot{x}(0) = 0$  where  $\omega \neq n$ .

Solution. a. We begin by applying the Laplace transform to the equation. Doing so yields

$$\mathscr{L}\{\ddot{x} + \omega^2 x\} = (s^2 + \omega^2)\bar{x}(s) - sx(0) - \dot{x}(0) = \frac{s}{s^2 + n^2} = \mathscr{L}\{\cos nt\}.$$

Using the initial data, the transformed equation becomes

$$(s^2 + \omega^2)\bar{x}(s) - s = \frac{s}{s^2 + n^2}.$$

Solve the above equation yields that the solution to the transformed equation is

$$\bar{x}(s) = \frac{s^3 + (n^2 + 1)s}{(s^2 + n^2)(s^2 + \omega^2)}.$$

From the partial fractions method we see that

$$\bar{x}(s) = \frac{s^3 + (n^2 + 1)s}{(s^2 + n^2)(s^2 + \omega^2)} = \frac{a_1 s + a_0}{s^2 + n^2} + \frac{b_1 s + b_0}{s^2 + \omega^2}.$$

Combining the rational fractions on the right side under a common denominator and equating the coefficients in the numerator we arrive at the following system of equations

$$a_1 + b + 1 = 1$$

$$a_0 + b_0 = 0$$

$$a_1 \omega^2 + b_1 n^2 = n^2 + 1$$

$$a_0 \omega^2 + b_0 n^2 = 0$$

Solving this system, we see that  $a_0 = b_0 = 0$ ,  $a_1 = \frac{1}{\omega^2 - n^2}$ , and  $b_1 = \frac{\omega^2 - n^2 - 1}{\omega^2 - n^2}$ .

Thus, the solution to the transformed system is given by

$$\bar{x}(s) = \frac{s^3 + (n^2 + 1)s}{(s^2 + n^2)(s^2 + \omega^2)} = \left(\frac{1}{\omega^2 - n^2}\right) \frac{s}{s^2 + n^2} + \left(\frac{\omega^2 - n^2 - 1}{\omega^2 - n^2}\right) \frac{s}{s^2 + \omega^2}.$$

From our table of Laplace transforms, we know that

$$\mathscr{L}\left\{\cos at\right\} = \frac{s}{s^2 + a^2}.$$

Therefore, the solution to the original differential equation is

$$x(t) = \mathcal{L}^{-1}\left\{\bar{x}(s)\right\} = \left(\frac{1}{\omega^2 - n^2}\right) \mathcal{L}^{-1}\left\{\frac{s}{s^2 + n^2}\right\} + \left(\frac{\omega^2 - n^2 - 1}{\omega^2 - n^2}\right) \mathcal{L}^{-1}\left\{\frac{s}{s^2 + \omega^2}\right\}$$
$$= \left(\frac{1}{\omega^2 - n^2}\right) \cos nt + \left(\frac{\omega^2 - n^2 - 1}{\omega^2 - n^2}\right) \cos \omega t.$$

## Problem 4.14.

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## Problem 4.22.

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## Problem 4.25.

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