## MATH 635 Final Assessment

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**Problem 1.** Provide a rigorous proof of the case  $x_0 = a$  in the Fundamental Lemma of the Calculus of Variations:

**Theorem 1** (Fundamental Lemma of the Calculus of Variations). Suppose M(x) is a continuous function defined on the interval  $a \le x \le b$ . Suppose further that for every continuous function  $\zeta(x)$ ,

$$\int_{a}^{b} M(x)\zeta(x)dx = 0.$$

Then

$$M(x) = 0$$
 for all  $x \in [a, b]$ .

Solution. Suppose to the contrary that  $M(x) \neq 0$  at the point  $x_0 = a$ . In that case either M(a) > 0 or M(a) < 0. Let us first assume that M(a) > 0. Due to the continuity of M(x) there is some neighborhood of a where the function is positive, i.e. there is some  $\delta > 0$  such that if  $|x - a| < \delta$  then

$$|M(x) - M(a)| < \frac{M(a)}{2}$$
 for  $x \in [a, b]$ .

Thus, 0 < M(a)/2 < M(x) for  $x \in [a, a + \delta)$ . Choose the function  $\zeta(x)$  to be the linear spline interpolating the points (a, 3M(a)/2) and  $(a + \delta, 0)$  with support on  $[a, a + \delta)$ , i.e.

$$\zeta(x) := \begin{cases} \frac{-3M(a)}{2\delta} (x - (a + \delta)) & \text{if } a \le x < a + \delta \\ 0 & \text{if } a + \delta \le x \le b. \end{cases}$$

Clearly  $\zeta(x)$  is continuous and positive on the interval  $[a, a + \delta)$ . Thus,

$$\int_{a}^{b} M(x)\zeta(x)dx = \int_{a}^{a+\delta} M(x)\zeta(x)dx > \frac{M(a)}{2} \int_{a}^{a+\delta} \zeta(x)dx > 0.$$

However, by our supposition

$$\int_{a}^{b} M(x)\zeta(x)dx = 0,$$

a contradiction. Therefore, if M(a) > 0, the function  $M(x) \equiv 0$  on the interval [a, b].

If M(a) < 0, then we can repeat the argument above replacing M(x) with -M(x). To demonstrate, let us investigate the case when M(a) < 0. Due to the continuity of M(x) there is some neighborhood of a where -M(x) is positive, i.e. there is some  $\delta > 0$  such that if  $|x - a| < \delta$  then

$$|-M(x) + M(a)| < \frac{-M(a)}{2}$$
 for  $x \in [a, b]$ .

Thus, 0 < -M(a)/2 < -M(x) for  $x \in [a, a + \delta)$ . Choose the function  $\zeta(x)$  to be the linear spline interpolating the points (a, -3M(a)/2) and  $(a + \delta, 0)$  with support on  $[a, a + \delta)$ , i.e.

$$\zeta(x) := \begin{cases} \frac{3M(a)}{2\delta} (x - (a + \delta)) & \text{if } a \le x < a + \delta \\ 0 & \text{if } a + \delta \le x \le b. \end{cases}$$

Clearly  $\zeta(x)$  is continuous and positive on the interval  $[a, a + \delta)$ . Thus,

$$\int_{a}^{b} -M(x)\zeta(x)dx = \int_{a}^{a+\delta} -M(x)\zeta(x)dx > \frac{-M(a)}{2} \int_{a}^{a+\delta} \zeta(x)dx > 0.$$

However, by our supposition

$$\int_{a}^{b} M(x)\zeta(x)dx = 0,$$

a contradiction. Therefore, if M(a) < 0, the function  $M(x) \equiv 0$  on the interval [a,b] and we have proven both cases.

## **Problem 2.** Consider the differential equation

$$y'' - y = -x$$
,  $0 < x < 1$   $y(0) = y(1) = 0$  (1)

as in Example 15.12 on page 502. Use the basis  $\{\phi_j(x)\}=\{x^j(1-x)^j\}$ , as in section 15.5.1, to compute approximations to the exact solution using the finite-element method.

Provide relative errors at the points 0.25, 0.50, and 0.75 of the approximations using the first n = 2, 3, 4 basis functions. Plot the corresponding approximations  $y_2$ ,  $y_3$ ,  $y_4$ , and the exact solution y. Then find the first value of j for which the relative error at all three points is less than 0.5%.

Solution. We wish to approximate the solution to the above differential equation, y(x), with a linear combination of the basis functions, i.e. find an approximation  $y_n(x)$  where

$$y_n(x) = \sum_{j=1}^n a_j \phi_j(x). \tag{2}$$

Note that the basis functions  $\phi_j(x) = x^j(1-x)^j$  satisfy the boundary conditions  $\phi_j(0) = \phi_j(1) = 0$  so that  $y_n(x)$  also satisfies the boundary conditions.

Corollary 15.2 suggests that if

$$\int_0^1 (y_n'' - y_n + x)\phi_i(x)dx = 0 \text{ for } i = 1, \dots, n$$

then  $y_n'' - y_n + x = 0$ , i.e  $y_n(x)$  satisfies the differential equation (1). If  $y_n(x)$  satisfies the differential equation and the boundary conditions, then we know that  $y_n(x)$  approximates the exact solution y(x).

Therefore, we choose the coefficients  $a_k$  such that they satisfy the system of equations

$$\sum_{i=1}^{n} a_{i} \int_{0}^{1} \phi_{j}''(x)\phi_{i}(x) - \phi_{j}(x)\phi_{i}(x)dx = -\int_{0}^{1} x\phi_{i}(x)dx \quad \text{for } i = 1, \dots, n.$$