

# MATH 635 Final Assessment

Matthew Tiger

December 10, 2015

**Problem 1.** Provide a rigorous proof of the case  $x_0 = a$  in the Fundamental Lemma of the Calculus of Variations:

**Theorem 1** (Fundamental Lemma of the Calculus of Variations). *Suppose  $M(x)$  is a continuous function defined on the interval  $a \leq x \leq b$ . Suppose further that for every continuous function  $\zeta(x)$ ,*

$$\int_a^b M(x)\zeta(x)dx = 0.$$

*Then*

$$M(x) = 0 \text{ for all } x \in [a, b].$$

*Solution.* Suppose to the contrary that  $M(x) \neq 0$  at the point  $x_0 = a$ . In that case either  $M(a) > 0$  or  $M(a) < 0$ . Let us first assume that  $M(a) > 0$ . Due to the continuity of  $M(x)$  there is some neighborhood of  $a$  where the function is positive, i.e. there is some  $\delta > 0$  such that if  $|x - a| < \delta$  then

$$|M(x) - M(a)| < \frac{M(a)}{2} \quad \text{for } x \in [a, b].$$

Thus,  $0 < M(a)/2 < M(x)$  for  $x \in [a, a + \delta)$ . Choose the function  $\zeta(x)$  to be the linear spline interpolating the points  $(a, 3M(a)/2)$  and  $(a + \delta, 0)$  with support on  $[a, a + \delta)$ , i.e.

$$\zeta(x) := \begin{cases} \frac{-3M(a)}{2\delta}(x - (a + \delta)) & \text{if } a \leq x < a + \delta \\ 0 & \text{if } a + \delta \leq x \leq b. \end{cases}$$

Clearly  $\zeta(x)$  is continuous and positive on the interval  $[a, a + \delta)$ . Thus,

$$\int_a^b M(x)\zeta(x)dx = \int_a^{a+\delta} M(x)\zeta(x)dx > \frac{M(a)}{2} \int_a^{a+\delta} \zeta(x)dx > 0.$$

However, by our supposition

$$\int_a^b M(x)\zeta(x)dx = 0,$$

a contradiction. Therefore, if  $M(a) > 0$ , the function  $M(x) \equiv 0$  on the interval  $[a, b]$ .

If  $M(a) < 0$ , then we can repeat the argument above replacing  $M(x)$  with  $-M(x)$ . To demonstrate, let us investigate the case when  $M(a) < 0$ . Due to the continuity of  $M(x)$  there is some neighborhood of  $a$  where  $-M(x)$  is positive, i.e. there is some  $\delta > 0$  such that if  $|x - a| < \delta$  then

$$|-M(x) + M(a)| < \frac{-M(a)}{2} \quad \text{for } x \in [a, b].$$

Thus,  $0 < -M(a)/2 < -M(x)$  for  $x \in [a, a + \delta)$ . Choose the function  $\zeta(x)$  to be the linear spline interpolating the points  $(a, -3M(a)/2)$  and  $(a + \delta, 0)$  with support on  $[a, a + \delta)$ , i.e.

$$\zeta(x) := \begin{cases} \frac{3M(a)}{2\delta}(x - (a + \delta)) & \text{if } a \leq x < a + \delta \\ 0 & \text{if } a + \delta \leq x \leq b. \end{cases}$$

Clearly  $\zeta(x)$  is continuous and positive on the interval  $[a, a + \delta)$ . Thus,

$$\int_a^b -M(x)\zeta(x)dx = \int_a^{a+\delta} -M(x)\zeta(x)dx > \frac{-M(a)}{2} \int_a^{a+\delta} \zeta(x)dx > 0.$$

However, by our supposition

$$\int_a^b M(x)\zeta(x)dx = 0,$$

a contradiction. Therefore, if  $M(a) < 0$ , the function  $M(x) \equiv 0$  on the interval  $[a, b]$  and we have proven both cases.  $\square$

**Problem 2.** Consider the differential equation

$$y'' - y = -x, \quad 0 < x < 1 \quad y(0) = y(1) = 0 \quad (1)$$

as in Example 15.12 on page 502. Use the basis  $\{\phi_j(x)\} = \{x^j(1-x)^j\}$ , as in section 15.5.1, to compute approximations to the exact solution using the finite-element method.

Provide relative errors at the points 0.25, 0.50, and 0.75 of the approximations using the first  $j = 2, 3, 4$  basis functions. Plot the corresponding approximations  $y_2, y_3, y_4$ , and the exact solution  $y$ . Then find the first value of  $j$  for which the relative error at all three points is less than 0.5%.

*Solution.* We wish to approximate the solution to the above differential equation,  $y(x)$ , with a linear combination of the basis functions, i.e. find an approximation  $y_n(x)$  where

$$y_n(x) = \sum_{j=1}^n a_j \phi_j(x). \quad (2)$$

Note that the basis functions  $\phi_j(x) = x^j(1-x)^j$  satisfy the boundary conditions  $\phi_j(0) = \phi_j(1) = 0$  so that  $y_n(x)$  also satisfies the boundary conditions.

Corollary 15.2 suggests that if

$$\int_0^1 (y_n'' - y_n + x) \phi_i(x) dx = 0 \quad \text{for } i = 1, \dots, n$$

then  $y_n'' - y_n + x = 0$ , i.e the approximation satisfies the differential equation (1). If  $y_n(x)$  satisfies the differential equation and the boundary conditions, then we know that  $y_n(x)$  approximates the exact solution  $y(x)$ .

Therefore, we choose the coefficients  $a_k$  such that they satisfy the system of equations

$$\sum_{j=1}^n a_j \int_0^1 \phi_j''(x) \phi_i(x) - \phi_j(x) \phi_i(x) dx = - \int_0^1 x \phi_i(x) dx \quad \text{for } i = 1, \dots, n.$$

□