# Matrices and Linear Systems Continued

Unit 3

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- Work through Ex. 3.1 (1,2,4), Ex. 3.2, and Ex. 3.4. Do not submit.

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QR algorithm produces QR-factorization A=QR, where Q is unitary and R is upper triangular.

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  $\mathbf{q_i} = \frac{\mathbf{a_i'}}{||\mathbf{a_i'}||}$ 

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where 
$$\mathbf{a}_{i}' = \mathbf{a}_{i} - \sum_{k=1}^{i-1} (\mathbf{q}_{k}^{\mathsf{T}} \mathbf{a}_{i}) \mathbf{q}_{k}, \quad i = 1, 2, \dots, n$$

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Entries of 
$$R$$
  $r_{ii} = ||\mathbf{a}_i'||, r_{ij} = \mathbf{q}_i^\mathsf{T} \mathbf{a}_j, i = 1, \dots, n, j = i+1, \dots, n$ 

# hw due next meeting

- 1. Create a random triadiagonal symmetric matrix of size n
- 2. Write your own single iteration QR code for triadiagonal symmetric matrices.
- 3. Test running time of your code vs the Matlab qr for n = 3, ... as as far as you can go hoping to outrun Matlab.
- 4. Write you own code to iterate your QR for triadiagonal symmetric matrices. Use several reasonable thresholds for stopping.
- 5. Test running time of your code vs the Matlab eig for n = 3, ... as as far as you can go hoping to outrun Matlab.

# Operator norm

$$||A|| = \max_{x \neq 0} \frac{||Ax||}{||x||} = \max_{||x||=1} ||Ax||$$

$$||AB|| \le ||A|| ||B||$$

Note that it requires a vector norm. We use the following

- 1.  $||x||_1 = \sum_{j=1}^n |x_j|$
- 2.  $||x||_2 = \sqrt{\sum_{j=1}^n x_j^2}$
- $3. \|x\|_{\infty} = \max_{1 \le j \le n} |x_j|$

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What are the subordinate matrix norms?

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Ex. 4.1 Please write up and turn in