

Basic Ideas

Unit 1

content

1. What methods are “computational”
2. Analytical methods vs numerical methods
3. Computational experiments
4. Computational abstract algebra, computational topology, computational algebraic geometry
5. Journals

what methods are computational

Given a mathematical model of a phenomenon, e.g.

- definite integral – a model of ????

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- differential equation – a model of ????
- spline (piecewise polynomial) – a model of ????

Analytical solutions remain the best (if known).

analytical solutions

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Analytical solutions in many cases are not known.

numerical solutions

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How close is the numerical solution to the analytical one?

numerical solutions

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Which algorithm is better?

numerical solutions

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Which algorithm is faster?

computational experiment: splines

- analytically deduce dimension of C^1 quadratic splines over two triangles sharing an edge

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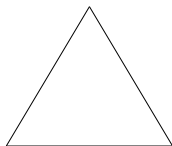


Figure: $ax^2 + by^2 + cxy + dx + ey + f$,

computational experiment: splines

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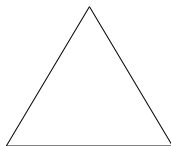


Figure: $ax^2 + by^2 + cxy + dx + ey + f$, $\dim S_2^1(\Delta_1) = 6$

computational experiment: splines

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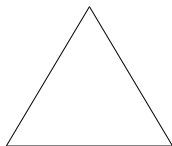


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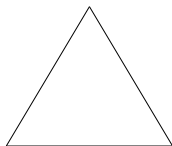


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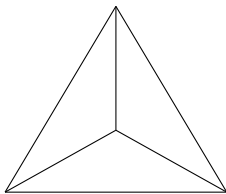
Why the computational experiment is not a proof?

computational experiment: splines

- analytically deduce dimension of C^1 quadratic splines over three triangles sharing a vertex

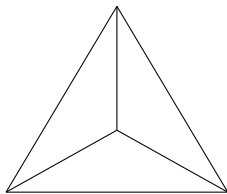
computational experiment: splines

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computational experiment: splines

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- Check numerically.

computational algebra, topology, algebraic geometry

- [▶ Link](#)

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journals, meetings, people

- SIAM [▶ Link](#)

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BREAK 10 min

content

1. Discretization (discrete vs continuous)
2. Stability
3. Well-posed vs ill-posed problems
4. Conditioning
5. Types of errors
6. Accuracy
7. Operation count
8. Loss of significant digits

discretization

continuous model $f'(a) = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h}$

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$$e(a, h) = \mathcal{O}(h)$$

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The problem of finding a solution $q = R(u)$ is well-posed, if for any $\varepsilon > 0$ there is a $\delta > 0$ such that for any u_1, u_2 such that $q_1 = R(u_1)$, $q_2 = R(u_2)$ and $|u_1 - u_2| < \delta$ it follows that $|q_1 - q_2| < \varepsilon$.

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- Example 1: $q = \frac{1}{u}$, $0 < u < 1$
- Example 2: $q = \frac{1}{u}$, $10^{-3} < u < 1$

well-posed vs ill-posed problems

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In this course we shall work with well posed problems. “Definitions and examples of inverse and ill-posed problems”, S. I. Kabanikhin

[▶ Link](#) See examples on p. 324

conditioning

- conditioning = sensitivity of the solution to perturbations of the input data.

low sensitivity = well conditioned

high sensitivity = ill conditioned

conditioning

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low sensitivity = well conditioned

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- a well posed problem can be ill conditioned
- Example: $q = \frac{1}{u}$, $10^{-3} < u < 1$

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- unavoidable error (input data, measurement, modeling)

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accuracy and operation count

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$$y = 1 + x + x^2 + \cdots + x^{215}$$

$$y = \frac{1-x^{216}}{1-x}$$

loss of significant digits: a famous example

$$\sqrt{x} - \sqrt{x-1}$$

Suppose we format short, and $x = 20157$. Then

$$\sqrt{x} \approx 141.9753, \sqrt{x-1} = 141.9718 \text{ and } \sqrt{x} - \sqrt{x-1} = 0.0035$$

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$$\frac{1}{\sqrt{x} + \sqrt{x-1}}$$

Try this with Matlab to see if it helps