```
\mathsf{Module}\big[\,\{\mathsf{R0}\,,\,\theta\mathsf{0}\,,\,\phi\mathsf{0}\,,\,\mathsf{BR0}\,,\,\mathsf{B}\theta\mathsf{0}\,,\,\mathsf{B}\phi\mathsf{0}\,,\,\mathsf{R1}\,,\,\theta\mathsf{1}\,,\,\phi\mathsf{1}\,,\,\mathsf{BR1}\,,\,\mathsf{B}\theta\mathsf{1}\,,\,\mathsf{B}\phi\mathsf{1}\,,\,\mathsf{Rk1}\,,\,\theta\mathsf{k1}\,,\,\phi\mathsf{k1}\,\}\,,
   \{R0, \theta0, \phi0\} = Q;
   \{BR0, B\theta0, B\phi0\} = B;
   {Rk1, \thetak1, \phik1} = ephCoords;
   R1 = R0 + h (BR0);
 \theta 1 = \theta 0 + h \left( \frac{B\theta 0}{D1^2} \right);
\phi 1 = \phi 0 + h \left( \frac{B\phi 0}{R1^2 \sin (\Theta 1)^2} \right);
 BR1 = BR0 + h \left( \frac{B\theta0^2}{R1^3} + \frac{B\phi0^2}{R1^3} + \frac{B\phi0^2}{R1^3 \sin[\theta 1]^2} + Total \left[ \frac{\eta k \left( -R1 + Rk1 \left( Cos[\theta 1] Cos[\theta k1] + Sin[\theta 1] Sin[\theta k1] Cos[\phi 1 - \phi k1] \right) \right)}{\left( R1^2 + Rk1^2 - 2R1Rk1 \left( Cos[\theta 1] Cos[\theta k1] + Sin[\theta 1] Sin[\theta k1] Cos[\phi 1 - \phi k1] \right) \right)^2 \left( 3/2 \right)} \right];
 B\theta 1 = B\theta 0 + h \left( \frac{B\phi 0^2}{R1^2 \sin[\theta 1]^2 \tan[\theta 1]} + Total \left[ \frac{\eta k \left(R1 Rk1 \left(-Sin[\theta 1] Cos[\theta k1] + Cos[\theta 1] Sin[\theta k1] Cos[\phi 1 - \phi k1]\right)\right)}{\left(R1^2 + Rk1^2 - 2 R1 Rk1 \left(Cos[\theta 1] Cos[\theta k1] + Sin[\theta 1] Sin[\theta k1] Cos[\phi 1 - \phi k1]\right)\right)^{3/2}} \right] \right);
 B\phi 1 = B\phi 0 + h \left( \text{Total} \left[ \frac{\eta k \left( -\text{R1 Rk1 Sin}[\theta 1] \, \text{Sin}[\theta k1] \, \text{Sin}[\phi 1 - \phi k1] \right)}{\left( \text{R1}^2 + \text{Rk1}^2 - 2 \, \text{R1 Rk1 (Cos}[\theta 1] \, \text{Cos}[\theta k1] + \text{Sin}[\theta 1] \, \text{Sin}[\theta k1] \, \text{Cos}[\phi 1 - \phi k1] \right) \right)^{3/2}} \right] \right);
   \{\{R1, \theta1, \phi1\}, \{BR1, B\theta1, B\phi1\}\}
```

In[\*]:= eulerStepSymplectic[h\_, Q\_, B\_, ephCoords\_] :=