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In[1]:= Quiet@Remove["`*"]

In[2]:= (*Prevents Mathematica from using Sec=1/Cos, Csc=1/Sin and Cot=1/Tan*)
$PrePrint = # /. {
    Csc[z_] => 1/Defer@Sin[z],
    Sec[z_] => 1/Defer@Cos[z],
    Cot[z_] => 1/Defer@Tan[z]
} &;

```

Solve $q_{j,j+1}$ equations

Compared with report, we use notation R_1 instead of R_{i+1} , R_0 instead of R_i etc.

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In[3]:= eqn1 = R1 == Br1 * h + R0;

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In[4]:= eqn2 =  $\theta_1 = \frac{B\theta_1}{R_1^2} h + \theta_0$ ;

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In[5]:= eqn3 =  $\phi_1 = \frac{B\phi_1}{R_1^2 \sin[\theta_1]^2} h + \phi_0$ ;

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In[6]:= qsols = Solve[{eqn1, eqn2, eqn3}, {R1,  $\theta_1$ ,  $\phi_1$ }] [[1]] // FullSimplify;

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... **Solve:** Inconsistent or redundant transcendental equation. After reduction, the bad equation is $B\theta_1 h + Br_1^2 h^2 \theta_0 + 2 Br_1 h R_0 \theta_0 + R_0^2 \theta_0 - Br_1^2 h^2 \text{ArcCsc}[\text{Csc}[\theta_1]] - 2 Br_1 h R_0 \text{ArcCsc}[\text{Csc}[\theta_1]] - R_0^2 \text{ArcCsc}[\text{Csc}[\theta_1]] == 0$.

... **Solve:** Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information.

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In[7]:= qsols // TableForm

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Out[7]/TableForm=

$$\begin{aligned}
 R_1 &\rightarrow Br_1 h + R_0 \\
 \theta_1 &\rightarrow \frac{B\theta_1 h}{(Br_1 h + R_0)^2} + \theta_0 \\
 \phi_1 &\rightarrow \phi_0 + \frac{B\phi_1 h}{(Br_1 h + R_0)^2 \sin\left[\frac{B\theta_1 h}{(Br_1 h + R_0)^2} + \theta_0\right]^2}
 \end{aligned}$$

Using Solve gives us incomplete solutions (and as it turns out, incomplete simplifying). We will use Reduce instead, with some number domain assumptions:

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In[8]:= qreds = Reduce[{eqn1, eqn2, eqn3}, {R1,  $\theta_1$ ,  $\phi_1$ }] // FullSimplify;

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In[9]:= qreds // TableForm

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Out[9]/TableForm=

$$\begin{aligned}
 &(\text{Im}[Br_1] \text{Im}[h] \neq \text{Re}[R_0 + Br_1 \text{Re}[h]] \mid \mid \\
 &\quad \text{Im}[Br_1] \text{Im}[h] \neq \text{Im}[R_0] + \text{Re}[R_0 + h \text{Im}[Br_1] + Br_1 (\text{Im}[h] + \text{Re}[h])]) \& \\
 &Br_1 h + R_0 == R_1 \& \theta_1 == \frac{B\theta_1 h}{R_1^2} + \theta_0 \& \phi_1 == \phi_0 + \frac{B\phi_1 h}{R_1^2 \sin[\theta_1]^2}
 \end{aligned}$$

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In[10]:= Refine[qreds, {Br1 ∈ Reals, h ∈ Reals, R0 ∈ Reals}] // FullSimplify // TableForm

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Out[10]/TableForm=

$$Br_1 h + R_0 \neq 0 \& Br_1 h + R_0 == R_1 \& \theta_1 == \frac{B\theta_1 h}{R_1^2} + \theta_0 \& \phi_1 == \phi_0 + \frac{B\phi_1 h}{R_1^2 \sin[\theta_1]^2}$$