

## Assignment 8

class-SEN

ROII NO -21430

Batch- F4

D.O.P - 23/10/2020

DOS-29/10/2020

Title -: Basic 2D transformation

Problem Statement:

write C++ program to draw 2 probject + perform following task +ransformation scaling, transformation, rotation apply concept of operator overloding.

SIH requirement:

1. QT creator

2 Hindows 10.

H/kl requirement -:

1 4 Gb ram.

Theory -:

Transformation means changing 2D graphic into something else by applying rules. He can have various types of transformation as translation. Scaling updrown, rotation, shearing, reflection etc. When a transformation takes place on a 2D plane it is colled 2p transformation. Transformation play an important role in computer graphics to reposition the graphics on screen and change



and rotation are basic transformation.

Translation is the process of changing the co-ordinates of 20 objects by adding translation co-ordinate.

Basic Formula:

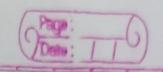
Resultant points = Currents pts x translating matrix

Ra,	RY,	1	1	Pai	Py, 1	1		0	0
R72	Ryz	1	=	Pala	Py2 1		0	1	0
		1		1	1 1	×	ta	<b>L</b>	1
Ran	Ryn			Pan	Pyn.	1001		- 4	

Scaling -:

This is the process of magnifying or diminishing the 2D object by given factors. These are casual types of scaling, symmetric/unsymme. tric, magnifical, dimensionary etc.

1	Rai	RYI I		Pai	Pyil	1	57	0	0	
	Raz	Ry2 1.	2	Pnz	Py2 1	×	0	54	6	
	175	donal	nott	1	1		0	6	ı	
	Ran	Ryn 1		[Pnn	Pyn 1		5 00	-11	-	



Rotation-1

particular point in need that can be done by the object to origin then rotate the it and then translate it to the Origin. The rotation is to done as follow.

Rai	RYI	17		Pai	PYI	1		CO2 &	sino	6
Rnz	Ry2	1	2	Pn2	Pyz	1	×	-sino	coso	0
:	1	1		219	- 19	-	0 00	0	0	1
LRan	Ryn	. 1		Pan	Pyn	-		1		781

Algorithm / Psudocode:

class Matrix

double mat[4][3];

int n

operator \* (matnx M)

void multiply matrix (int a ( ][3], int b[3][b], int m)

Int m2 = 3, m2 = 3;

for ( i = 0 ; i < n ; i + )

for(j=0;j<n2;j++)

Intsum=0:

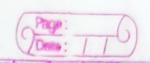
mt k;

for ( K=0; i<M2; K++)

sum: mat[i][k] + mat2[k][j];



```
K[i][j]=Sum:
 return k;
Translation (P)
 the input(1);
ty = input(2);
  matrix (tx, ty);
  Matrix R = P * T;
      han been lead the
Rotation (matrix P)
   Angle = input();
   Matrix R = { ((050, 5m0,0),
      (-sing | cose, 0)
           (0,0,1),
   Matrix Res = P * R;
scaling (matrix P)
   Sn = input();
   sy = inputz();
   Matrix S = { ( Sn, 0, 0),
       10,54,0).
          (0,0,1)
   Matrix Res = S * P;
(114)-too + [4](1) to no : 114)
```



6 9

12 1

6

## ii) Scaling

4 6 1

## iii) Rotation

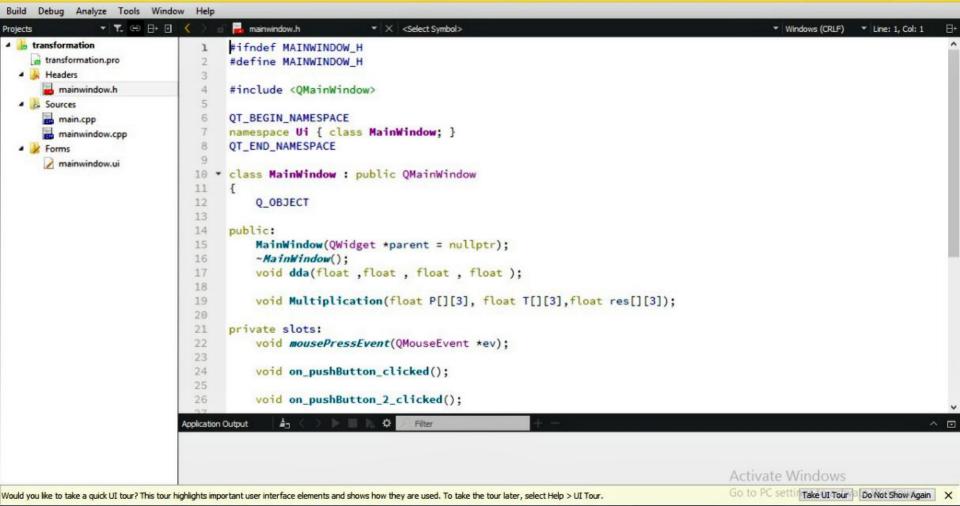
$$\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} \cos 90 & \sin 90 & 0 \\ -5 & \cos 90 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 1 & 1 \end{bmatrix}$$

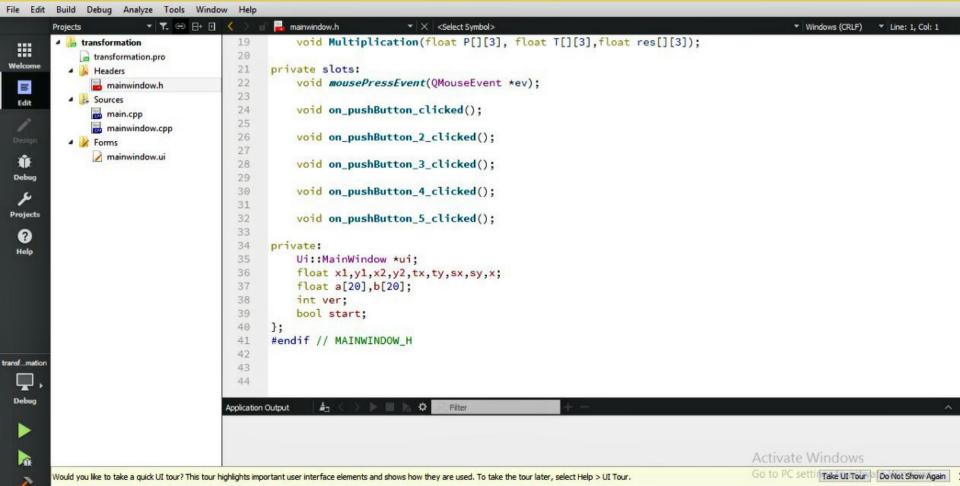
0

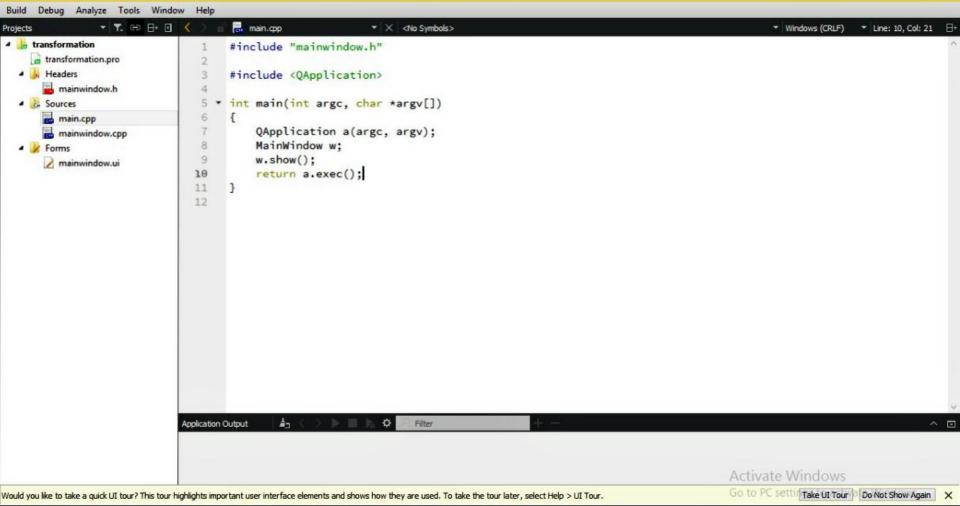
3

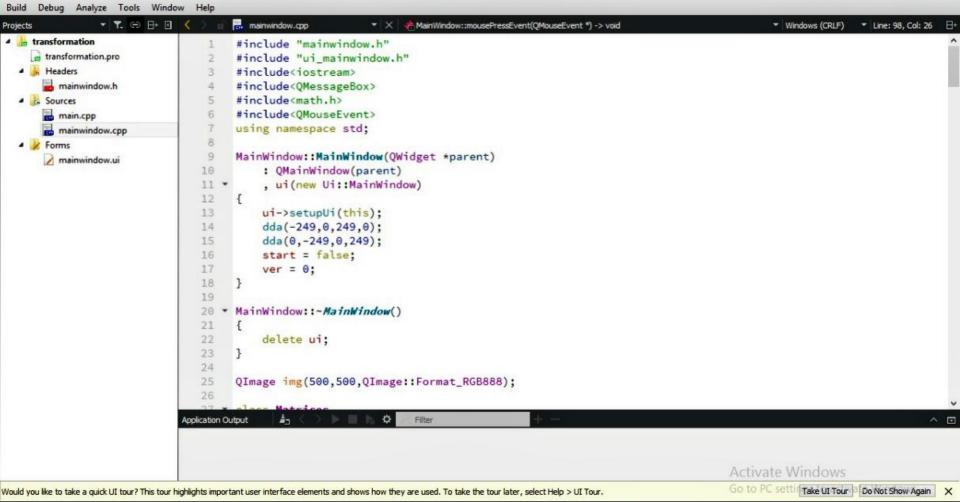


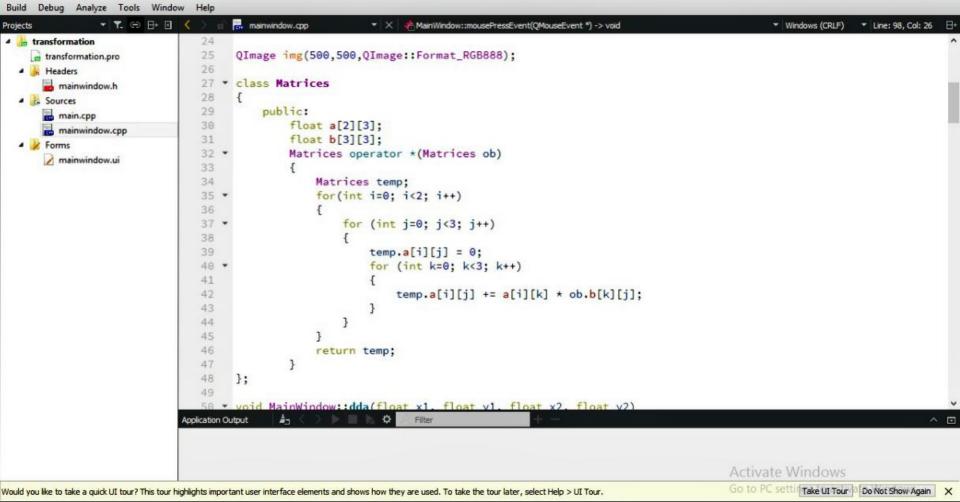
Conclusion:	
The 2D transformation have done Succe implemented and applied on triangle	
rhombus.	
Tas 2 - I yes as	
1 2 3 . 1 9 9 1 1 9 P	
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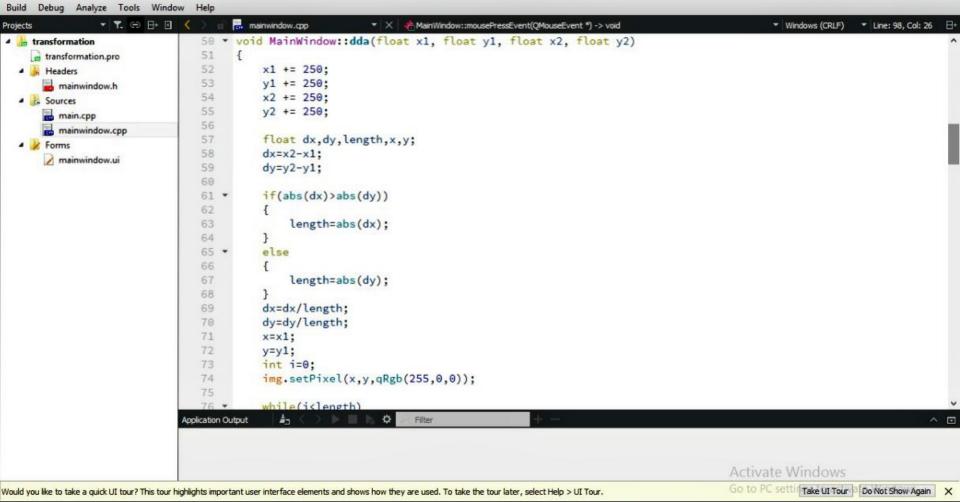


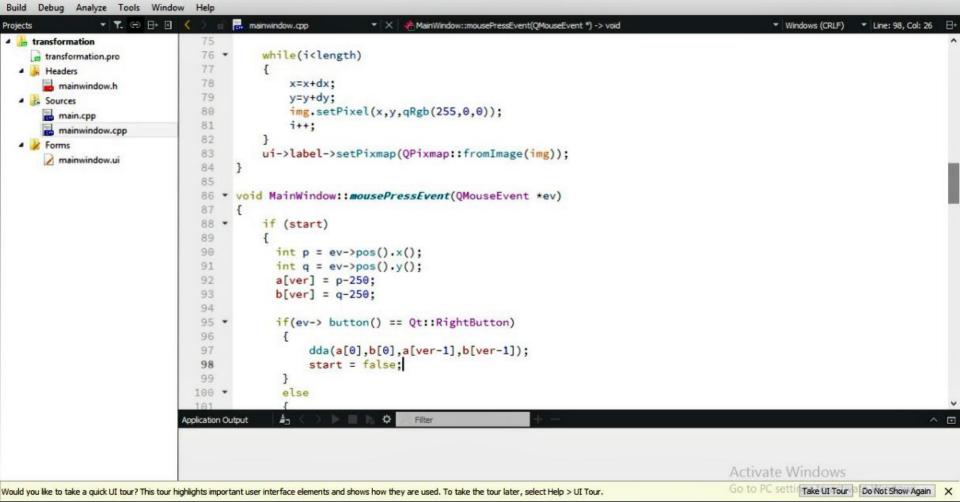


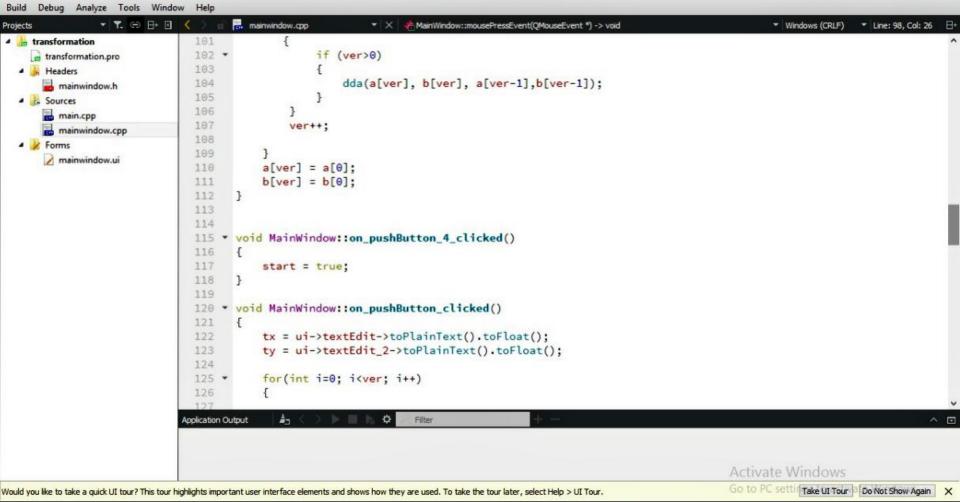


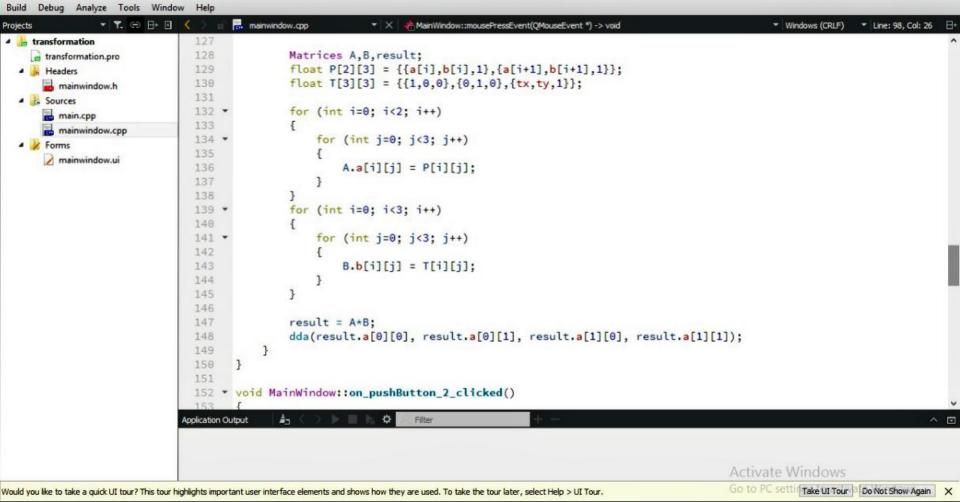


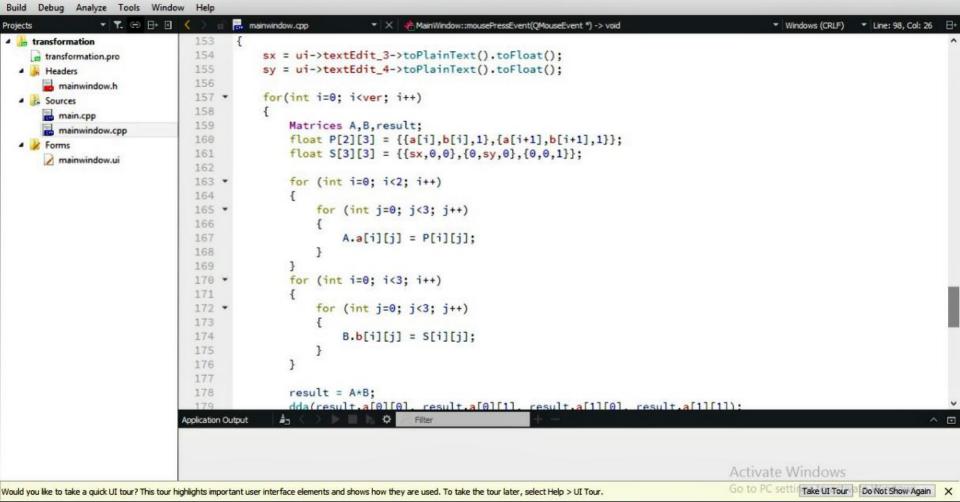


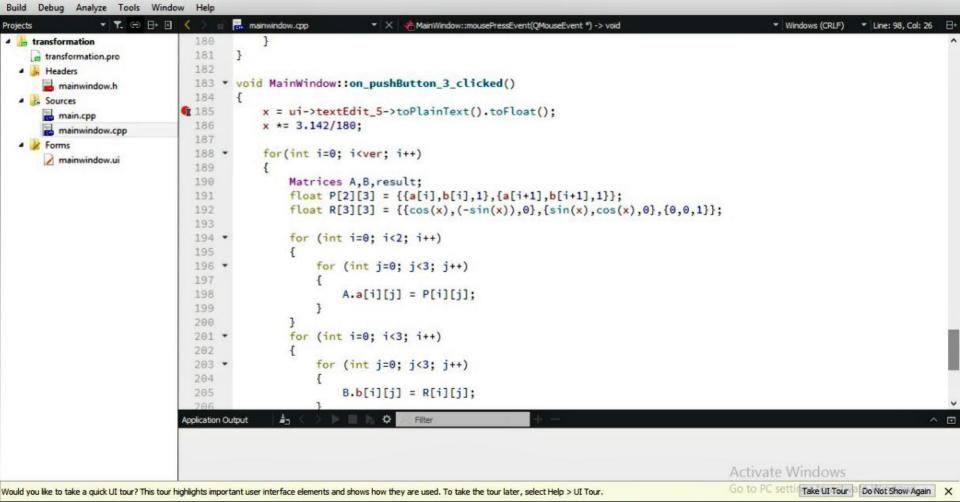


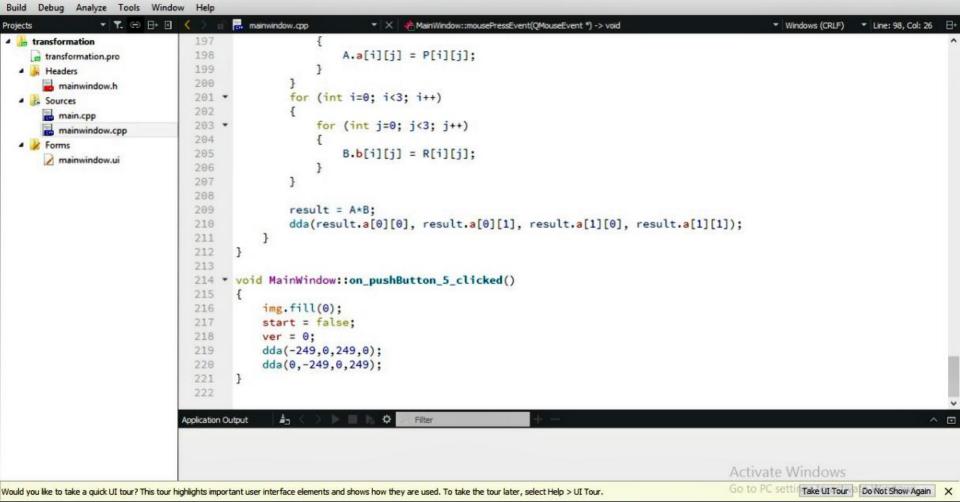


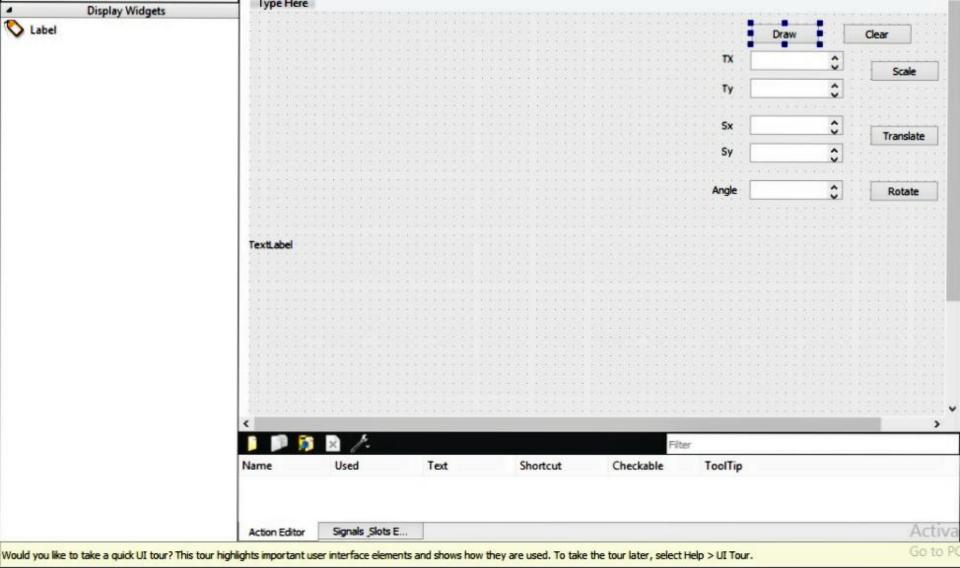


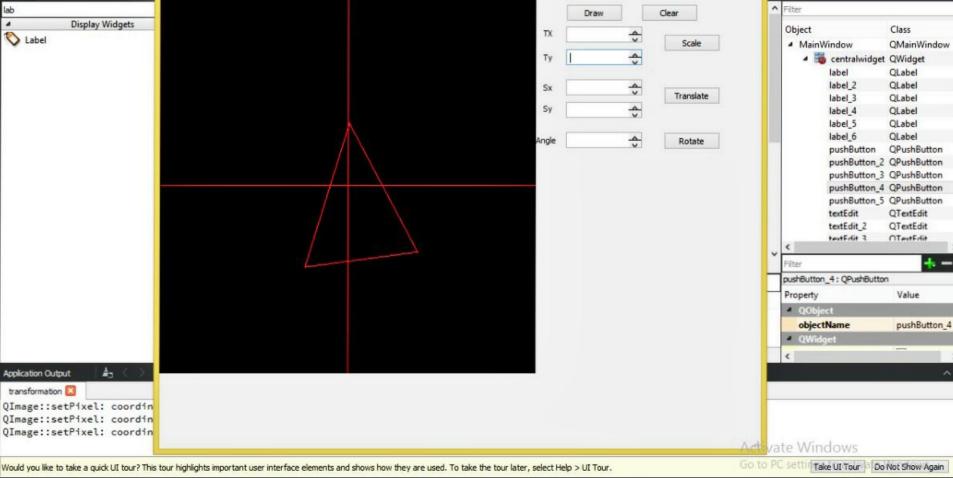


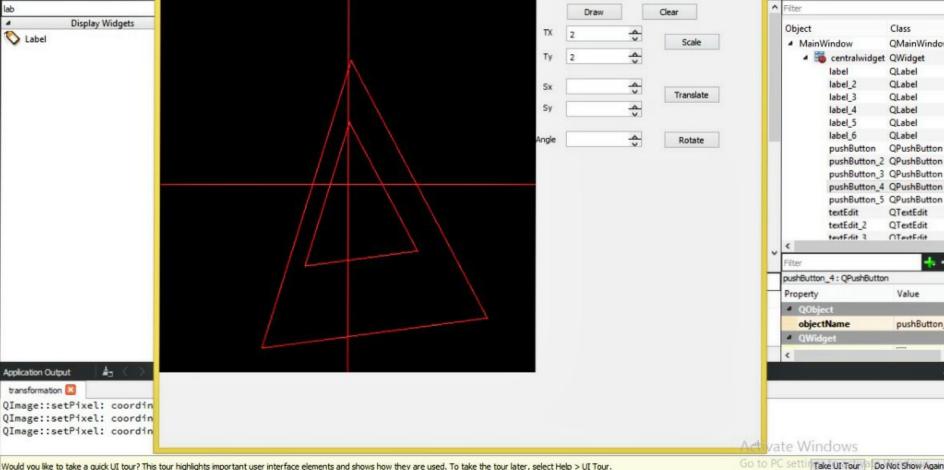












Would you like to take a quick UI tour? This tour highlights important user interface elements and shows how they are used. To take the tour later, select Help > UI Tour.

Go to PC setti Take UI Tour Do Not Show Again

Class

OLabel

OLabel

OLabel

OLabel

OLabel

OLabel

**OPushButton** 

**OTextEdit** 

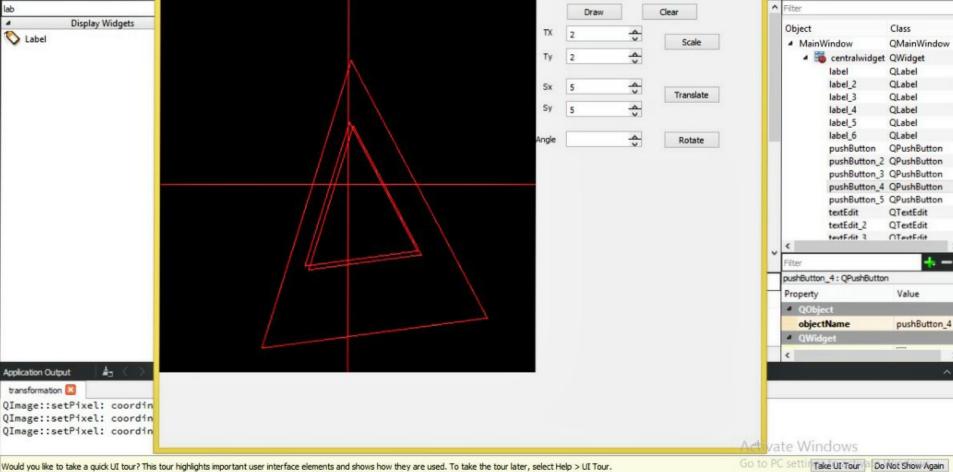
**OTextEdit** 

OTextEdit.

Value

pushButton 4

**OMainWindow** 



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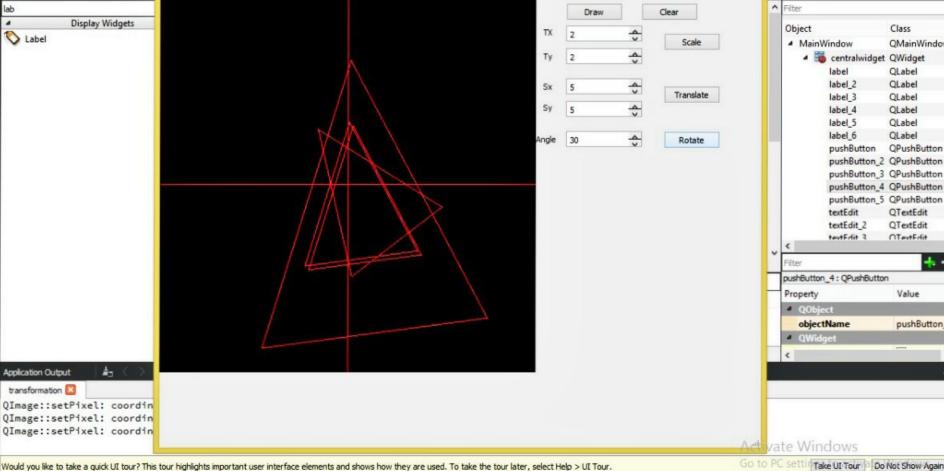
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