

# **LAB MANUAL**

## **OPERATING SYSTEMS LAB**

### **CS406PC**



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**COMPUTER SCIENCE AND ENGINEERING**  
**VAAGDEVI ENGINEERING COLLEGE**  
**BOLLIKUNTA, WARANGAL-506005**



# **VAAGDEVI ENGINEERING COLLEGE**

(Sponsored by Viswambhara Educational Society), Approved by AICTE, Affiliated to JNTU Hyderabad  
P.O. Bollikunta, Warangal– 506005 (Telangana State)

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## **VISION OF THE INSTITUTION**

- Striving continuously for global recognition through academic excellence in higher education for the betterment of society.

## **MISSION OF THE INSTITUTION**

- To produce technically competent and socially responsible engineers with ethical values through innovative teaching learning process.
- To promote research and entrepreneurship culture among faculty and students.



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## **DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING**

### **VISION**

- To become a Pioneer Department Imparting High Quality Education through technological advancements in the field of Computer science and Engineering.

### **MISSION**

- To provide state-of-the-art resources, high quality technical education and training for students to become competent in industry or research to serve the society.
- To enable students to develop life-long learning skills and ethical values suitable for accomplishing a successful career through higher education or entrepreneurship in India or Abroad.



## **DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING**

### **Program Educational Objectives (PEOs)**

**PEO 1:** To provide students with a foundation in the principles of computer science and engineering, including mathematics and basic engineering to solve technological issues of modern society.

**PEO 2:** To provide students a breadth of knowledge in computer science and related engineering disciplines in order to enable them to understand engineering trade-offs across multiple disciplines, work effectively as an individual and as a member.

**PEO 3:** To provide awareness of security and laws pertaining to cyber usage, ethical issues related to computing and to provide knowledge on subject protection through Intellectual Property Rights.

**PEO 4:** To provide students with specialized knowledge in focused areas of their choice, in order to strengthen them to make contributions to a specific discipline and pursue post-graduation or research.

**PEO 5:** To train students in problem solving skills in design, development and analysis for interpretation and synthesis of data and create awareness for lifelong learning.

### **Programme Specific Outcomes (PSOs)**

**PSO 1:** Apply the knowledge about principles of programming languages, Computer Algorithms, Databases, System Software and Computer Networks for the interconnection.

**PSO 2:** Interpret and analyse the problem, formulate an efficient hardware and software solution for the real world, socio-industry related problems and needs using computing methodologies and latest technologies.

**PSO 3:** Fulfilling desire by attaining Employment, Excel in competitive examinations, Higher studies, Research, and initiate start-ups.



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### Course Outcomes (COs) :

**CO 1:** Simulate and implement operating system concepts such as scheduling, deadlock management, file management and memory management.

**CO 2:** Able to implement C programs using Unix system calls.

## WEEK-1

Write C programs to simulate the following CPU Scheduling algorithms.

- a) FCFS
- b) SJF
- c) Round Robin
- d) Priority

### a) FCFS (First Come First Serve)

**Aim:** Write a C program to implement the various process scheduling mechanisms such as FCFS scheduling.

#### Algorithm:

- 1: Start the process
- 2: Accept the number of processes in the ready Queue
- 3: For each process in the ready Q, assign the process id and accept the CPU burst time4:  
Set the waiting of the first process as '0' and its burst time as its turn around time
- 5: for each process in the Ready Q calculate
  - a. Waiting time for process(n)= waiting time of process (n-1) + Burst time of process(n-1)
  - b. Turnaround time for Process(n)= waiting time of Process(n)+ Burst time for process(n)
- 6: Calculate
  - a. Average waiting time = Total waiting Time / Number of process
  - b. Average Turnaround time = Total Turnaround Time / Number of process
- 7: Stop the process

## Program:

```
#include<stdio.h>

int main()
{
    int bt[20],p[20],wt[20],tat[20],i,j,n,total=0,pos,temp;
    float avg_wt,avg_tat;
    printf("Enter number of process:");
    scanf("%d",&n);
    printf("\nEnter Burst Time:\n");
    for(i=0;i<n;i++)
    {
        printf("p %d:",i+1);
        scanf("%d",&bt[i]);
        p[i]=i+1;        //contains process number
    }
    wt[0]=0;        //waiting time for first process will be zero
    //calculate waiting time
    for(i=1;i<n;i++)
    {
        wt[i]=0;
        for(j=0;j<i;j++)
            wt[i]+=bt[j];

        total+=wt[i];
    }
    avg_wt=(float)total/n;    //average waiting time
    total=0;
    printf("\nProcess\t Burst Time \tWaiting Time\tTurnaround Time");
    for(i=0;i<n;i++)
    {
        tat[i]=bt[i]+wt[i];    //calculate turnaround time
        total+=tat[i];
        printf("\np%d\t\t %d\t\t %d\t\t\t %d",p[i],bt[i],wt[i],tat[i]);
    }
    avg_tat=(float)total/n;    //average turnaround time
    printf("\n\nAverage Waiting Time=%f",avg_wt);
    printf("\nAverage Turnaround Time=%f\n",avg_tat);
}
```

## Output:

```
[188r1a0501@localhost ~]$ vi w1.c
[188r1a0501@localhost ~]$ gcc w1.c
[188r1a0501@localhost ~]$ ./a.out
Enter number of process:3

Enter Burst Time:
p1:3
p2:4
p3:2

Process      Burst Time      Waiting Time      Turnaround Time
p1            3                0                 3
p2            4                3                 7
p3            2                7                 9

Average Waiting Time=3.333333
Average Turnaround Time=6.333333
[188r1a0501@localhost ~]$
```



## **b) SJF (Shortest Job First)**

**Aim:** Write a C program to implement the various process scheduling mechanisms such as SJF Scheduling.

### **Algorithm:**

- 1: Start the process
- 2: Accept the number of processes in the ready Queue
- 3: For each process in the ready Q, assign the process id and accept the CPU burst time
- 4: Start the Ready Q according to the shortest Burst time by sorting according to lowest to highest burst time.
- 5: Set the waiting time of the first process as '0' and its turnaround time as its burst time.
- 6:

For each process in the ready queue, calculate

- (a) Waiting time for process(n) = waiting time of process (n-1) + Burst time of process(n-1)
  - (b) Turn around time for Process(n) = waiting time of Process(n) + Burst time for process(n)
- 7: Calculate
- (c) Average waiting time = Total waiting Time / Number of process
  - Average Turnaround time = Total Turnaround Time / Number of process
- 8: Stop the process

## Program:

```
#include<stdio.h>int
main()
{
    int bt[20],p[20],wt[20],tat[20],i,j,n,total=0,pos,temp;
    float avg_wt,avg_tat;
    printf("Enter number of process:");
    scanf("%d",&n);

    printf("\nEnter Burst Time:\n");
    for(i=0;i<n;i++)
    {
        printf("p%d:",i+1);
        scanf("%d",&bt[i]);
        p[i]=i+1;        //contains process number
    }
    //sorting burst time in ascending order using selection sort
    for(i=0;i<n;i++)
    {
        pos=i;
        for(j=i+1;j<n;j++)
        {
            if(bt[j]<bt[pos])
                pos=j;
        }
        temp=bt[i];
        bt[i]=bt[pos];
        bt[pos]=temp;

        temp=p[i];
        p[i]=p[pos];
        p[pos]=temp;
    }
    wt[0]=0;        //waiting time for first process will be zero

    //calculate waiting time
    for(i=1;i<n;i++)
    {
        wt[i]=0;
```

```

        for(j=0;j<i;j++)wt[i]+=bt[j];

        total+=wt[i];
    }

    avg_wt=(float)total/n;    //average waiting time
    total=0;

    printf("\nProcess\t Burst Time \tWaiting Time\tTurnaround Time");
    for(i=0;i<n;i++)
    {
        tat[i]=bt[i]+wt[i];    //calculate turnaround time
        total+=tat[i];
        printf("\np%d\t\t %d\t\t \t %d\t\t\t %d",p[i],bt[i],wt[i],tat[i]);
    }

    avg_tat=(float)total/n;    //average turnaround time
    printf("\n\nAverage Waiting Time=%f",avg_wt);
    printf("\n\nAverage Turnaround Time=%f\n",avg_tat);
}

```

## Output:

```

[188r1a0501@localhost ~]$ vi w1a.c
[188r1a0501@localhost ~]$ gcc w1a.c
[188r1a0501@localhost ~]$ ./a.out
Enter number of process:3

Enter Burst Time:
p1:5
p2:3
p3:7

Process      Burst Time      Waiting Time      Turnaround Time
p2           3              0                3
p1           5              3                8
p3           7              8               15

Average Waiting Time=3.666667
Average Turnaround Time=8.666667
[188r1a0501@localhost ~]$ █

```

### c) Round Robin

**Aim:** Write a C program to implement the various process scheduling mechanisms such as Round Robin Scheduling.

#### Algorithm

1: Start the process

2: Accept the number of processes in the ready Queue and time quantum (or) time slice

3: For each process in the ready Q, assign the process id and accept the CPU burst time

4: Calculate the no. of time slices for each process where

No. of time slice for process(n) = burst time process(n)/time slice

5: If the burst time is less than the time slice then the no. of time slices = 1

6: Consider the ready queue is a circular Q, calculate

(a) Waiting time for process(n) = waiting time of process(n-1) + burst time of process(n-1) + the time difference in getting the CPU from process(n-1)

(b) Turn around time for process(n) = waiting time of process(n) + burst time of process(n) + the time difference in getting CPU from process(n).

7: Calculate

(a) Average waiting time = Total waiting Time / Number of process

(b) Average Turnaround time = Total Turnaround Time / Number of process  
Step 8: Stop the process

## Program:

```
#include<stdio.h>

Int main()

{
    int st[10],bt[10],wt[10],tat[10],n,tq; int
    i,count=0,swt=0,stat=0,temp,sq=0;float
    awt,atat;
    printf("enter the number of processes");
    scanf("%d",&n);
    printf("enter the burst time of each process /n");
    for(i=0;i<n;i++)
    {
        printf(("p%d",i+1);
        scanf("%d",&bt[i]);
        st[i]=bt[i];
    }
    printf("enter the time quantum");
    scanf("%d",&tq);
    while(1)
    {
        for(i=0,count=0;i<n;i++)
        {
            temp=tq;
            if(st[i]==0)
            {
                count++;
                continue;
            }
            if(st[i]>tq)
                st[i]=st[i]-tq;
```

```

        else
        if(st[i]>=0)
        {
            temp=st[i];
            st[i]=0;
        }
        sq=sq+temp;
        tat[i]=sq;
    }
    if(n==count)
    break;
}
for(i=0;i<n;i++)
{
    wt[i]=tat[i]-bt[i];
    swt=swt+wt[i];
    stat=stat+tat[i];
}
awt=(float)swt/n; atat=(float)stat/n;
printf("process no\t burst time\t waiting time\t turnaround time\n");
for(i=0;i<n;i++)
printf("%d\t\t %d\t\t %d\t\t %d\n",i+1,bt[i],wt[i],tat[i]); printf("avg
wt time=%f,avg turn around time=%f",awt,atat);
}

```

### Output:

```
[188r1a0501@localhost ~]$ vi wld.c
[188r1a0501@localhost ~]$ gcc wld.c
[188r1a0501@localhost ~]$ ./a.out
enter the number of processes 3
enter the burst time of each process
p1 7
p2 2
p3 8
enter the time quantum 2
process no      burst time      waiting time      turnaround time
1               7               8                15
2               2               2                 4
3               8               9                17
avg wt time=6.333333,avg turn around time=12.000000[188r1a0501@localhost ~]$
```

## d) Priority

**Aim:** Write a C program to implement the various process scheduling mechanisms such as Priority Scheduling.

### Algorithm:

1: Start the process

2: Accept the number of processes in the ready Queue

3: For each process in the ready Q, assign the process id and accept the CPU burst time 4: Sort the ready queue according to the priority number.

5: Set the waiting of the first process as '0' and its burst time as its turn around time 6:

For each process in the Ready Q calculate

(e) Waiting time for process(n) = waiting time of process (n-1) + Burst time of process(n-1)

(f) Turn around time for Process(n) = waiting time of Process(n) + Burst time for process(n)

7: Calculate

(g) Average waiting time = Total waiting Time / Number of process

(h) Average Turnaround time = Total Turnaround Time / Number of process Step 8: Stop the process



**Program:**

```
#include<stdio.h>int
main()
{
    int bt[20],p[20],wt[20],tat[20],pri[20],i,j,k,n,total=0,pos,temp;
    float avg_wt,avg_tat;
    printf("Enter number of process:");
    scanf("%d",&n);

    printf("\nEnter Burst Time:\n");
    for(i=0;i<n;i++)
    {
        printf("p%d:",i+1);
        scanf("%d",&bt[i]);
        p[i]=i+1;        //contains process number
    }
    printf(" enter priority of the process ");
    for(i=0;i<n;i++)
    {
        p[i] = i;
        //printf("Priority of Process");
        printf("p%d ",i+1);
        scanf("%d",&pri[i]);
    }
    for(i=0;i<n;i++)
    for(k=i+1;k<n;k++)
    if(pri[i] > pri[k])
    {
        temp=p[i];
        p[i]=p[k];
        p[k]=temp;

        temp=bt[i];
        bt[i]=bt[k];
        bt[k]=temp;
        temp=pri[i];
        pri[i]=pri[k];
        pri[k]=temp;
    }
}
```

```

wt[0]=0;           //waiting time for first process will be zero

//calculate waiting time
for(i=1;i<n;i++)
{
    wt[i]=0;
    for(j=0;j<i;j++)
        wt[i]+=bt[j];

    total+=wt[i];
}
avg_wt=(float)total/n;    //average waiting time
total=0;

printf("\nProcess\t Burst Time \tPriority \tWaiting Time\tTurnaround Time");
for(i=0;i<n;i++)
{
    tat[i]=bt[i]+wt[i];    //calculate turnaround time
    total+=tat[i];
    printf("\np%d\t\t %d\t\t %d\t\t %d\t\t%d",p[i],bt[i],pri[i],wt[i],tat[i]);
}

avg_tat=(float)total/n;    //average turnaround time
printf("\n\nAverage Waiting Time=%f",avg_wt);
printf("\nAverage Turnaround Time=%f\n",avg_tat);
}

```

### Output:

```

[188r1a0501@localhost ~]$ vi wlb.c
[188r1a0501@localhost ~]$ gcc wlb.c
[188r1a0501@localhost ~]$ ./a.out
Enter number of process:3

Enter Burst Time:
p1:5
p2:6
p3:7
enter priority of the process p1 1
p2 3
p3 2

```

| Process | Burst Time | Priority | Waiting Time | Turnaround Time |
|---------|------------|----------|--------------|-----------------|
| p0      | 5          | 1        | 0            | 5               |
| p2      | 7          | 2        | 5            | 12              |
| p1      | 6          | 3        | 12           | 18              |

```

Average Waiting Time=5.666667
Average Turnaround Time=11.666667

```

## WEEK-2

### Write programs using the I/O system calls of UNIX/LINUX operating system (open, read, write, close, fcntl, seek, stat, opendir, readdir)

**Aim:** C program using open, read, write, close system calls

#### Theory:

There are 5 basic system calls that Unix provides for file I/O.

1. **Create:** Used to Create a new empty file

**Syntax:** `int creat(char *filename, mode_t mode)`

filename : name of the file which you want to create

mode : indicates permissions of new file.

2. **open:** Used to Open the file for reading, writing or both.

**Syntax:** `int open(char *path, int flags [ , int mode ] );`

Path : path to file which you want to use

flags : How you like to use

O\_RDONLY: read only, O\_WRONLY: write only, O\_RDWR: read and write, O\_CREAT: create file if it doesn't exist, O\_EXCL: prevent creation if it already exists

3. **close:** Tells the operating system you are done with a file descriptor and Close the file which pointed by fd.

**Syntax:** `int close(int fd);`

fd : file descriptor

4. **read:** From the file indicated by the file descriptor fd, the read() function reads cnt bytes of input into the memory area indicated by buf. A successful read() updates the access time for the file.

**Syntax:** `int read(int fd, char *buf, int size);`

fd: file descriptor

buf: buffer to read data from

size: length of buffer

5. **write:** Writes cnt bytes from buf to the file or socket associated with fd. cnt should not be greater than INT\_MAX (defined in the limits.h header file). If cnt is zero, write() simply returns 0 without attempting any other action.

**Syntax:** `int write(int fd, char *buf, int size);`

fd: file descriptor

buf: buffer to write data to

size: length of buffer

\***File descriptor** is integer that uniquely identifies an open file of the process.

## Algorithm

1. Start the program.
2. Open a file for O\_RDWR for R/W, O\_CREAT for creating a file, O\_TRUNC for truncate a file.
3. Using getchar(), read the character and stored in the string[] array.
4. The string [] array is write into a file close it.
5. Then the first is opened for read only mode and read the characters and displayed it and close the file.
6. Stop the program.

## Program

```
#include<sys/stat.h>
#include<stdio.h>
#include<fcntl.h>
#include<sys/types.h>
int main()
{
    int n,i=0;
    int f1,f2;
    char c,strin[100];
    f1=open("data",O_RDWR|O_CREAT|O_TRUNC);
    while((c=getchar())!='\n')
    {
        strin[i++]=c;
    }
    strin[i]='\0';
    write(f1,strin,i);
    close(f1);
    f2=open("data",O_RDONLY);
    read(f2,strin,0);
    printf("\n%s\n",strin); close(f2);
    return 0;
}
```

## Output:

Hai  
Hai

**b) Aim:** C program using lseek

**Theory:**

lseek is a system call that is used to change the location of the read/write pointer of a file descriptor. The location can be set either in absolute or relative terms.

**Syntax :** off\_t lseek(int fildes, off\_t offset, int whence);

int fildes : The file descriptor of the pointer that is going to be moved.

off\_t offset : The offset of the pointer (measured in bytes).

int whence : Legal values for this variable are provided at the end which are  
SEEK\_SET (Offset is to be measured in absolute terms), SEEK\_CUR (Offset is to be measured relative to the current location of the pointer), SEEK\_END (Offset is to be measured relative to the end of the file)

**Algorithm:**

1. Start the program
2. Open a file in read mode
3. Read the contents of the file
4. Use lseek to change the position of pointer in the read process
5. Stop

## Program:

```
#include<stdio.h> #include
<unistd.h> #include
<fcntl.h> #include
<sys/types.h>

int main()
{
    int file=0;
    if((file=open("testfile.txt",O_RDONLY)) < -1)
        return 1;

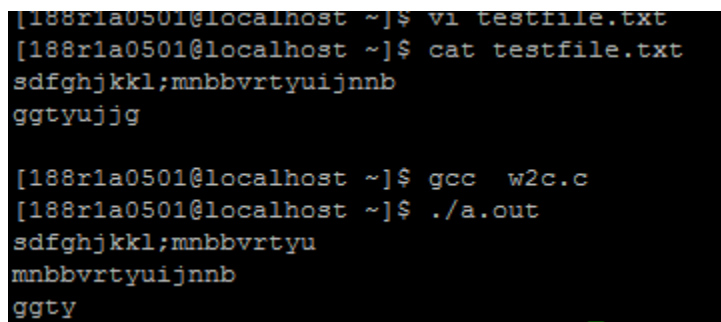
    char buffer[19];
    if(read(file,buffer,19) != 19)
        return 1;
    printf("%s\n",buffer);

    if(lseek(file,10,SEEK_SET) < 0)
        return 1;

    if(read(file,buffer,19) != 19)
        return 1;
    printf("%s\n",buffer);

    return 0;
}
```

## Output:



```
[188r1a0501@localhost ~]$ vi testfile.txt
[188r1a0501@localhost ~]$ cat testfile.txt
sdfghjkk;l;mnbbvrt;yuijnnb
ggtyujjg

[188r1a0501@localhost ~]$ gcc w2c.c
[188r1a0501@localhost ~]$ ./a.out
sdfghjkk;l;mnbbvrt;y
mnbbvrt;yuijnnb
ggty
```

c) **Aim:** C program using opendir(), closedir(), readdir()

## Theory:

The following are the various operations using directories

1. Creating directories.  
**Syntax :** int mkdir(const char \*pathname, mode\_t mode);
2. The 'pathname' argument is used for the name of the directory.
3. Opening directories  
**Syntax :** DIR \*opendir(const char \*name);
4. Reading directories.  
**Syntax:** struct dirent \*readdir(DIR \*dirp);
5. Removing directories.  
**Syntax:** int rmdir(const char \*pathname);
6. Closing the directory.  
**Syntax:** int closedir(DIR \*dirp);
7. Getting the current working directory.  
**Syntax:** char \*getcwd(char \*buf, size\_t size);

## Algorithm:

1. Start the program
2. Print a menu to choose the different directory operations
3. To create and remove a directory ask the user for name and create and remove the same respectively.
4. To open a directory check whether directory exists or not. If yes open the directory .If it does not exists print an error message.
5. Finally close the opened directory.
6. Stop



**Program:**

```
#include<stdio.h>
#include<fcntl.h>
#include<dirent.h>
main()
{
char d[10]; int c,op; DIR *e;
struct dirent *sd;
printf("**menu**\n1.create dir\n2.remove dir\n 3.read dir\n enter ur choice");
scanf("%d",&op);
switch(op)
{
case 1: printf("enter dir name\n"); scanf("%s",&d);
c=mkdir(d,777);
if(c==1)
printf("dir is not created");
else
printf("dir is created"); break;
case 2: printf("enter dir name\n"); scanf("%s",&d);
c=rmdir(d);
if(c==1)
printf("dir is not removed");
else
printf("dir is removed");
break;
case 3: printf("enter dir name to open");
scanf("%s",&d);
e=opendir(d);
if(e==NULL)
printf("dir does not exist");
else
{
printf("dir exist\n"); while((sd=readdir(e))!=NULL) printf("%s\t",sd->d_name);
}
closedir(e);
break;
}
}
```

### Output:

```
[188r1a0501@localhost f]$ gcc w2e.c
[188r1a0501@localhost f]$ ./a.out
**menu**
1.create dir
2.remove dir
3.read dir
enter ur choice1
enter dir name
d
dir is created[188r1a0501@localhost f]$ ls
a.out a.txt d w2d.c w2e.c
```

### WEEK -3

Write a C program to simulate Bankers Algorithm for Deadlock Avoidance and Prevention

#### a) Aim

Write a C program to simulate the Bankers Algorithm for Deadlock Avoidance.

#### Data structures

1. n- Number of process, m-number of resource types.
2. Available: Available[j]=k, k – instance of resource type R<sub>j</sub> is available.
3. Max: If max [i, j]=k, P<sub>i</sub> may request at most k instances resource R<sub>j</sub>.
4. Allocation: If Allocation [i, j]=k, P<sub>i</sub> allocated to k instances of resource R<sub>j</sub>
5. Need: If Need[I, j]=k, P<sub>i</sub> may need k more instances of resource type R<sub>j</sub>,
6. Need [I, j] =Max [I, j]-Allocation [I, j];

#### Safety Algorithm

1. Work and Finish be the vector of length m and n respectively, Work=Available and Finish[i] =False.
2. Find an i such that both
3. Finish[i] =False
4. Need<=Work
5. If no such I exist go to step 4.
6. work=work+Allocation, Finish[i] =True;
7. If Finish [1] =True for all I, then the system is in safe state.

#### Resource request algorithm

1. Let Request i be request vector for the process P<sub>i</sub>, If request i=[j]=k, then process P<sub>i</sub> wants k instances of resource type R<sub>j</sub>.
2. If Request<=Need I go to step 2. Otherwise raise an error condition.
3. If Request<=Available go to step 3. Otherwise P<sub>i</sub> must since the resources are available.
4. Have the system pretend to have allocated the requested resources to process P<sub>i</sub> by modifying the state as follows;
5. Available=Available-Request I;
6. Allocation I =Allocation+Request I;
7. Need i=Need i-Request I;

If the resulting resource allocation state is safe, the transaction is completed and process P<sub>i</sub> is allocated its resources. However, if the state is unsafe, the P<sub>i</sub> must wait for Request i and the old resource-allocation state is restore.

**Algorithm:**

1. Start the program.
2. Get the values of resources and processes.
3. Get the avail value.
4. After allocation find the need value.
5. Check whether it is possible to allocate.
6. If it is possible then the system is in safe state.
7. Else system is not in safety state.
8. If the new request comes then check that the system is in safety.
9. Or not if we allow the request.
10. Stop the program.

**Program:**

```
#include<stdio.h>
int main ()
{
    int allocated[15][15], max[15][15], need[15][15], avail[15], tres[15],
        work[15], flag[15];
    int pno, rno, i, j, prc, count, t, total;
    count = 0;
    //clrscr ();
    printf ("\n Enter number of process:");
    scanf ("%d", &pno);
    printf ("\n Enter number of resources:");
    scanf ("%d", &rno);
    for (i = 1; i <= pno; i++)
    {
        flag[i] = 0;
    }
    printf ("\n Enter total numbers of each resources:");
    for (i = 1; i <= rno; i++)
        scanf ("%d", &tres[i]);
    printf ("\n Enter Max resources for each process:");
    for (i = 1; i <= pno; i++)
    {
        printf ("\n for process %d:", i);
        for (j = 1; j <= rno; j++)
            scanf ("%d", &max[i][j]);
```

```

    }

    printf ("\n Enter allocated resources for each process:");for (i
= 1; i <= pno; i++)
    {
        printf ("\n for process %d:", i);for
        (j = 1; j <= rno; j++)
            scanf ("%d", &allocated[i][j]);
    }
    printf ("\n available resources:\n");for (j
= 1; j <= rno; j++)
    {
        avail[j] = 0;
        total = 0;
        for (i = 1; i <= pno; i++)
            {
                total += allocated[i][j];
            }
        avail[j] = tres[j] - total;
        work[j] = avail[j];
        printf ("    %d \t", work[j]);
    }

do
{

    for (i = 1; i <= pno; i++)
        {
            for (j = 1; j <= rno; j++)
                {
                    need[i][j] = max[i][j] - allocated[i][j];
                }

        }

    printf ("\n Allocated matrix    Max    need");for (i = 1; i <= pno; i++)
        {
            printf ("\n");
            for (j = 1; j <= rno; j++)
                {
                    printf ("%4d", allocated[i][j]);
                }
            printf ("|");
            for (j = 1; j <= rno; j++)

```

```

        {
            printf ("%4d", max[i][j]);
        }
    printf ("|");
    for (j = 1; j <= rno; j++)
    {
        printf ("%4d", need[i][j]);
    }
}

prc = 0;

for (i = 1; i <= pno; i++)
{
    if (flag[i] == 0)
    {
        prc = i;

        for (j = 1; j <= rno; j++)
        {
            if (work[j] < need[i][j])
            {
                prc = 0;
                break;
            }
        }
    }
}

if (prc != 0)
    break;

if (prc != 0)
{
    printf ("\n Process %d completed", i);
    count++;
    printf ("\n Available matrix:");
    for (j = 1; j <= rno; j++)
    {
        work[j] += allocated[prc][j];
        allocated[prc][j] = 0;
        max[prc][j] = 0;
        flag[prc] = 1;
        printf (" %d", work[j]);
    }
}

```

```

    }
}

}

while (count != pno && prc != 0);

if (count == pno)
    printf ("\nThe system is in a safe state!!");
else
    printf ("\nThe system is in an unsafe state!!");
return 0;

}

```

### Output:

```

[188r1a0501@localhost ~]$ vi dp.c
[188r1a0501@localhost ~]$ gcc dp.c
[188r1a0501@localhost ~]$ ./a.out

Enter number of process:5

Enter number of resources:3

Enter total numbers of each resources:10      5      7

Enter Max resources for each process:
for process 1:7      5      3
for process 2:3      2      2
for process 3:9      0      2
for process 4:2      2      2
for process 5:4      3      3

Enter allocated resources for each process:
for process 1:0      1      0
for process 2:2      0      0
for process 3:3      0      2
for process 4:2      1      1
for process 5:0      0      2

```

available resources:

| 3                |   |   | 3 |   |   | 2   |   |      |  |
|------------------|---|---|---|---|---|-----|---|------|--|
| Allocated matrix |   |   |   |   |   | Max |   | need |  |
| 0                | 1 | 0 | 7 | 5 | 3 | 7   | 4 | 3    |  |
| 2                | 0 | 0 | 3 | 2 | 2 | 1   | 2 | 2    |  |
| 3                | 0 | 2 | 9 | 0 | 2 | 6   | 0 | 0    |  |
| 2                | 1 | 1 | 2 | 2 | 2 | 0   | 1 | 1    |  |
| 0                | 0 | 2 | 4 | 3 | 3 | 4   | 3 | 1    |  |

Process 2 completed

| 5                |   |   | 3 |   |   | 2   |   |      |  |
|------------------|---|---|---|---|---|-----|---|------|--|
| Allocated matrix |   |   |   |   |   | Max |   | need |  |
| 0                | 1 | 0 | 7 | 5 | 3 | 7   | 4 | 3    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 3                | 0 | 2 | 9 | 0 | 2 | 6   | 0 | 0    |  |
| 2                | 1 | 1 | 2 | 2 | 2 | 0   | 1 | 1    |  |
| 0                | 0 | 2 | 4 | 3 | 3 | 4   | 3 | 1    |  |

Process 4 completed

| 7                |   |   | 4 |   |   | 3   |   |      |  |
|------------------|---|---|---|---|---|-----|---|------|--|
| Allocated matrix |   |   |   |   |   | Max |   | need |  |
| 0                | 1 | 0 | 7 | 5 | 3 | 7   | 4 | 3    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 3                | 0 | 2 | 9 | 0 | 2 | 6   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 2 | 4 | 3 | 3 | 4   | 3 | 1    |  |

Process 1 completed

| 7                |   |   | 5 |   |   | 3   |   |      |  |
|------------------|---|---|---|---|---|-----|---|------|--|
| Allocated matrix |   |   |   |   |   | Max |   | need |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 3                | 0 | 2 | 9 | 0 | 2 | 6   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 2 | 4 | 3 | 3 | 4   | 3 | 1    |  |

Process 3 completed

| 10               |   |   | 5 |   |   | 5   |   |      |  |
|------------------|---|---|---|---|---|-----|---|------|--|
| Allocated matrix |   |   |   |   |   | Max |   | need |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 0 | 0 | 0 | 0 | 0   | 0 | 0    |  |
| 0                | 0 | 2 | 4 | 3 | 3 | 4   | 3 | 1    |  |

Process 5 completed

| 10 |  |  | 5 |  |  | 7 |  |  |
|----|--|--|---|--|--|---|--|--|
|----|--|--|---|--|--|---|--|--|



**b) Aim:**

Write a C program to simulate Bankers Algorithm for Deadlock Prevention

**Algorithm:**

1. Start
2. Attacking Mutex condition : never grant exclusive access. but this may not be possible for several resources.
3. Attacking preemption: not something you want to do.
4. Attacking hold and wait condition : make a process hold at the most 1 resource at a time. make all the requests at the beginning. All or nothing policy. If you feel, retry. eg. 2- phase locking 34
5. Attacking circular wait: Order all the resources. Make sure that the requests are issued in the correct order so that there are no cycles present in the resource graph. Resources numbered 1 ... n. Resources can be requested only in increasing order. ie. you cannot request a resource whose no is less than any you may be holding.
6. Stop

**Program:**

```
#include<stdio.h>

int max[10][10],alloc[10][10],need[10][10],avail[10],i,j,p,r,finish[10]={0},flag=0;
main( )
{

printf("\n SIMULATION OF DEADLOCK PREVENTION \n ");
printf("Enter no. of processes, resources\n ");
scanf("%d%d",&p,&r);
printf("Enter allocation matrix");
for(i=0;i<p;i++)
for(j=0;j<r;j++)
scanf("%d",&alloc[i][j]);
printf("\n enter max matrix");
for(i=0;i<p;i++) /*reading the maximum matrix and available matrix*/
for(j=0;j<r;j++)
scanf("%d",&max[i][j]);
printf(" \n enter available matrix");for(i=0;i<r;i++)
scanf("%d",&avail[i]);

for(i=0;i<p;i++) for(j=0;j<r;j++)
need[i][j]=max[i][j]-alloc[i][j];fun();
/*calling function*/ if(flag==0)
{if(finish[i]!=1)
{
printf("\n Failing :Mutual exclusion");
for(j=0;j<r;j++)
```

```

{    /*checking for mutual exclusion*/if(avail[j]<need[i][j])
avail[j]=need[i][j];
}
fun();
printf("\n By allocating required resources to process %d dead lock is prevented ",i);
printf("\n lack of preemption");
for(j=0;j<r;j++)
{
if(avail[j]<need[i][j])
avail[j]=need[i][j];
alloc[i][j]=0;
}
fun( );
printf("\n dead lock is prevented by allocating needed resources");

printf(" \n failing:Hold and Wait condition ");
for(j=0;j<r;j++)
{ /*checking hold and wait condition*/
if(avail[j]<need[i][j])
avail[j]=need[i][j];
}
fun( );
printf("\n AVOIDING ANY ONE OF THE CONDITION, U CAN PREVENT DEADLOCK");
}
}
}
fun()
{
while(1)
{
for(flag=0,i=0;i<p;i++)
{
if(finish[i]==0)
{
for(j=0;j<r;j++)
{
if(need[i][j]<=avail[j])
continue;
else break;
}
if(j==r)
{
for(j=0;j<r;j++)
avail[j]+=alloc[i][j];
flag=1;

```

```
    finish[i]=1;
  }
}
}
```

### Output:

```
[188r1a0501@localhost ~]$ vi dp1.c
[188r1a0501@localhost ~]$ gcc dp1.c
[188r1a0501@localhost ~]$ ./a.out

SIMULATION OF DEADLOCK PREVENTION
Enter no. of processes, resources
3
2
Enter allocation matrix4
5
3
4
5
2

    enter max matrix4
3
4
5
6
1

    enter available matrix2
5

Failing :Mutual exclusion
By allocating required resources to process 3 dead lock is prevented
lack of preemption
dead lock is prevented by allocating needed resources
failing:Hold and Wait condition
AVOIDING ANY ONE OF THE CONDITION, U CAN PREVENT DEADLOCK[188r1a0501@localhost ~]$ █
```

## WEEK-4

Write a C program to implement the Producer – Consumer problem using semaphores using UNIX/LINUX system calls.

### Aim:

Write a C program to implement the Producer – Consumer problem using semaphores using UNIX/LINUX system calls.

### Algorithm:

1. The Semaphore mutex, full & empty are initialized.
2. In the case of producer process
3. Produce an item in to temporary variable.  
If there is empty space in the buffer check the mutex value for enter into the critical section. If the mutex value is 0, allow the producer to add value in the temporary variable to the buffer.
4. In the case of consumer process
  - i) It should wait if the buffer is empty
  - ii) If there is any item in the buffer check for mutex value, if the mutex==0, remove item from buffer
  - iii) Signal the mutex value and reduce the empty value by 1.
  - iv) Consume the item.
5. Print the result

### Program:

```
#include<stdio.h>
#include<stdlib.h>

int mutex = 1, full = 0, empty = 3, x = 0;

int main ()
{
    int n;
    void producer
    (); void
    consumer ();int
    wait (int);
    int signal (int);
    printf ("\n1.Producer\n2.Consumer\n3.Exit");
    while (1)
    {
```

```

printf ("\nEnter your
choice:");scanf ("%d", &n);
switch (n)
{
case 1:
    if ((mutex == 1) && (empty !=
        0))producer ();
    else
        printf ("Buffer is
full!!");break;
case 2:
    if ((mutex == 1) && (full !=
        0))consumer ();
    else
        printf ("Buffer is
empty!!");break;
case 3:
    exit
    (0);
    break;
}
}
return 0;
}

int wait (int s)
{
    return (--s);
}

int signal (int s)
{
    return (++s);
}

void producer ()
{
    mutex = wait (mutex);
    full = signal (full);
    empty = wait (empty);
    x++;
    printf ("\nProducer produces the item %d", x);mutex
    = signal (mutex);
}

void consumer ()

```

```

{
    mutex = wait
    (mutex);full = wait
    (full);
    empty = signal (empty);
    printf ("\nConsumer consumes item %d", x);x--;
    ;
    mutex = signal (mutex);
}

```

## Output:

```

[188r1a0501@localhost ~]$ vi pc.c
[188r1a0501@localhost ~]$ gcc pc.c
[188r1a0501@localhost ~]$ ./a.out

1.Producer
2.Consumer
3.Exit
Enter your choice:1

Producer produces the item 1
Enter your choice:1

Producer produces the item 2
Enter your choice:1

Producer produces the item 3
Enter your choice:2

Consumer consumes item 3
Enter your choice:2

Consumer consumes item 2
Enter your choice:2

Consumer consumes item 1
Enter your choice:2
Buffer is empty!!
Enter your choice:3
[188r1a0501@localhost ~]$ █

```

## Week: 5

Write C programs to illustrate the following IPC mechanisms

**Aim:** Write C programs to illustrate the following IPC mechanisms

### **ALGORITHM:**

1. Start the program.
2. Declare the variables.
3. Read the choice.
4. Create a piping processing using IPC.
5. Assign the variable lengths
6. “*strcpy*” the message lengths.
7. To join the operation using IPC .
8. Stop the program

### **Program :**

#### **a) PIPE PROCESSING**

```
#include <unistd.h>
#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#define MSG_LEN 64
int main()
{
    Int result;
    int fd[2];
    char message[MSG_LEN];
    char recvd_msg[MSG_LE];
    result = pipe (fd);
    //Creating a pipe//fd[0] is for reading and fd[1] is for writing if (result < 0)
    {
        perror("pipe ");
        exit(1);
    }
    strncpy(message,"Linux World!! ",MSG_LEN);
    result=write(fd[1],message,strlen(message));
    if (result< 0)
```

```

{
perror("write"); exit(2);
}
strncpy(message,"Understanding ",MSG_LEN);
result=write(fd[1],message,strlen(message));
if(result < 0)
{
perror("write");
exit(2);
}

strncpy(message,"Concepts of ",MSG_LEN);
result=write(fd[1],message,strlen(message));

if (result <0)

{
perror("write");
exit(2);
}

strncpy(message,"Piping ", MSG_LEN);
result=write(fd[1],message,strlen(message));
if (result < 0)
{
perror("write");
exit(2);
}

result=read(fd[0],recvd_msg,MSG_LEN);

if (result <0)
{
perror("read");

exit(3);
}

printf("%s\n",recvd_msg);

return 0;
}

```



## b) FIFO

### Program:

```
#include <stdio.h> #include
<stdlib.h> #include
<sys/stat.h>#include
<unistd.h>

#include <linux/stat.h>

#define FIFO_FILE      "MYFIFO"

int main(void)
{
    FILE *fp;
    char readbuf[80];

    /* Create the FIFO if it does not exist */
    umask(0);
    mknod(FIFO_FILE, S_IFIFO|0666, 0);

    while(1)
    {
        fp = fopen(FIFO_FILE,
            "r");fgets(readbuf, 80, fp);
        printf("Received string: %s\n", readbuf);
        fclose(fp);
    }

    return(0);
}
```

```

#include <stdio.h>
#include <stdlib.h>

#define FIFO_FILE      "MYFIFO"

int main(int argc, char *argv[])
{
    FILE *fp;

    if ( argc != 2 )
    {
        printf("USAGE: fifoclient [string]\n");
        exit(1);
    }

    if((fp = fopen(FIFO_FILE, "w")) == NULL)
    {
        perror("fopen");
        exit(1);
    }
    fputs(argv[1], fp);

    fclose(fp);
    return(0);
}

```

c) Program for Message Queue (Writer Process)

```
#include <stdio.h>
#include <sys/ipc.h>
#include <sys/msg.h>

// structure for message
queuestruct mesg_buffer {
    long msg_type;
    char
    msg_text[100];
} message;

int main()
{
    key_t
    key;int
    msgid;
    // ftok to generate unique key
    key = ftok("progfile", 65);
    // msgget creates a message queue
    // and returns identifier
    msgid = msgget(key, 0666 | IPC_CREAT);
    message.mesg_type = 1;

    printf("Write Data : ");
    gets(message.mesg_txtt)
    ;

    // msgsnd to send message
    msgsnd(msgid, &message, sizeof(message), 0);

    // display the message
    printf("Data send is : %s \n", message.mesg_text);

    return 0;
}
```

c) Program for Message Queue (Reader Process)

```
#include <stdio.h>
#include <sys/ipc.h>
#include <sys/msg.h>
// structure for message
queuestruct mesg_buffer {
    long mesg_type;
    char mesg_text[100];
} message;

int main()
{
    key_t
    key;int
    msgid;

    // ftok to generate unique
    keykey = ftok("progfile", 65);

    // msgget creates a message queue and returns identifier
    msgid = msgget(key, 0666 | IPC_CREAT);
    // msgrcv to receive message
    msgrcv(msgid, &message, sizeof(message), 1, 0);

    // display the message
    printf("Data Received is : %s
    \n",message.mesg_text);

    // to destroy the message queue
    msgctl(msgid, IPC_RMID,
    NULL);

    return 0;
}
```

**OUTPUT:** Thus the Piping process using IPC program was executed and verified successfully

```
[sree@localhost ~]$ cc pp.c
[sree@localhost ~]$ ./a.out

Enter string:1
os
er
a
tingEnter 1 array elementz:1
The string length=1
Sum=0[sree@localhost ~]$ er
bash: er: command not found
[sree@localhost ~]$ ating1
bash: ating1: command not found
[sree@localhost ~]$ gedit pp.c
[sree@localhost ~]$ cc pp.c
[sree@localhost ~]$ ./a.out
Linux World!!!
[sree@localhost ~]$ gedit pp.c
[sree@localhost ~]$ cc pp.c
[sree@localhost ~]$ ./a.out
Linux World!! Understanding Concepts of Piping ,
[sree@localhost ~]$ █
```

#### d) Shared Memory:

##### DESCRIPTION:

Inter Process Communication through shared memory is a concept where two or more process can access the common memory. And communication is done via this shared memory where changes made by one process can be viewed by another process.

The problem with pipes, fifo and message queue – is that for two process to exchange information. The information has to go through the kernel.

- Server reads from the input file.
- The server writes this data in a message using either a pipe, fifo or message queue.
- The client reads the data from the IPC channel, again requiring the data to be copied from kernel's IPC buffer to the client's buffer.
- Finally the data is copied from the client's buffer.

##### PROGRAM:

shwriter.c

```
#include <stdio.h>
```

```
#include <sys/ipc.h>
```

```
#include <sys/shm.h>
```

```
#include <sys/stat.h>
```

```
int main ( )
```

```
{
```

```
int segment_id;
```

```
char bogus;
```

```
char* shared_memory;
```

```
struct shmid_ds shmbuffer;
```

```
int segment_size;
```

```
const int shared_segment_size = 0x6400;
```

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```
/* Allocate a shared memory segment. */
```

```
segment_id = shmget (IPC_PRIVATE, shared_segment_size, IPC_CREAT
```

```

| IPC_EXCL | S_IRUSR | S_IWUSR | S_IRGRP | S_IWGRP);
/* Attach the shared memory segment. */
printf("Shared memory segment ID is %d\n", segment_id);
shared_memory = (char*) shmat (segment_id, 0, 0);
printf ("shared memory attached at address %p\n", shared_memory);
/* Determine the segment's size. */
/*
shmctl (segment_id, IPC_STAT, &shmbuffer);
segment_size = shmbuffer.shm_segsz;
printf ("segment size: %d\n", segment_size);
*/
/* Write a string to the shared memory segment. */
sprintf (shared_memory, "Hello, world.");
/* Detach the shared memory segment. */
shmdt (shared_memory);
printf("Wrote Hello World to the segment\n");
}

```

#### PROGRAM:

shreader.c

```

#include <stdio.h>
#include <sys/ipc.h>
#include <sys/shm.h>
#include <sys/stat.h>
int main ()
{
int segment_id;
char bogus;
char* shared_memory;
struct shmid_ds shmbuffer;

```

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```

int segment_size;
const int shared_segment_size = 0x6400;
printf("Enter the shared memory id: ");
scanf("%d", &segment_id);
/* Reattach the shared memory segment, at a different address. */
shared_memory = (char*) shmat (segment_id, (void*) 0x5000000, 0);

```

```
printf ("shared memory reattached at address %p\n", shared_memory);
/* Print out the string from shared memory. */
printf ("The contents of the shared memory is:\n%s\n",
shared_memory);
/* Detach the shared memory segment. */
shmdt (shared_memory);
return 0;
}
```

#### OUTPUT:

```
cc shwriter.c
./a.out
Shared memory segment ID is 3047442
shared memory attached at address 0xb7f2a000
Wrote Hello World to the segment
cc shreader.c
./a.out
Enter the shared memory id: 3047442
shared memory reattached at address 0x5000000
The contents of the shared memory is:
Hello, world.
```



## Week: 6

**Aim:** Write C programs to simulate the following memory management techniques

### a) Paging

**AIM:** To write a C program to implement memory management using paging technique.

#### ALGORITHM:

Step1 : Start the program.

Step2 : Read the base address, page size, number of pages and memory unit.

Step3 : If the memory limit is less than the base address display the memory limit is less than limit.

Step4 : Create the page table with the number of pages and page address.

Step5 : Read the page number and displacement value.

Step6 : If the page number and displacement value is valid, add the displacement value with the address corresponding to the page number and display the result.

Step7 : Display the page is not found or displacement should be less than page size.

Step8 : Stop the program.

#### Program:

```
#include<stdio.h>

#include<conio.h>

main()
{
    int ms, ps, nop, np, rempages, i, j, x, y, pa, offset; int s[10], fno[10][20];

    printf("\nEnter the memory size -- ");

    scanf("%d",&ms); printf("\nEnter the
    page size -- ");scanf("%d",&ps);

    nop = ms/ps;

    printf("\nThe no. of pages available in memory are -- %d ",nop);printf("\nEnter
    number of processes -- ");

    scanf("%d",&np);
    rempages = nop; for(i=1;i<=np;i++)
    {
```

```

printf("\nEnter no. of pages required for p[%d]-- ",i);
scanf("%d",&s[i]);
if(s[i] >rempages)
{
printf("\nMemory is Full");
break;
}
rempages = rempages - s[i]; printf("\nEnter
pagetable for p[%d] --- ",i);
for(j=0;j<s[i];j++)
scanf("%d",&fno[i][j]);
}
printf("\nEnter Logical Address to find Physical Address ");
printf("\nEnter process no. and pagenumber and offset -- ");
scanf("%d %d %d",&x,&y, &offset);
if(x>np || y>=s[i] || offset>=ps)
printf("\nInvalid Process or Page Number or offset");else
{
pa=fno[x][y]*ps+offset;
printf("\nThe Physical Address is -- %d",pa);
}
getch();
}

```

## OUTPUT:

```
Enter the memory size -- 1000

Enter the page size -- 200

The no. of pages available in memory are -- 5
Enter number of processes -- 2

Enter no. of pages required for p[1]-- 20

Memory is Full
Enter Logical Address to find Physical Address
Enter process no. and pagenumber and offset -- 1
2
5

The Physical Address is -- 5

..Program finished with exit code 0
Press ENTER to exit console.█
```

## b) Segmentation

**Aim:** To write a C program to implement memory management using segmentation

### Algorithm:

Step1 : Start the program.

Step2 : Read the base address, number of segments, size of each segment, memory limit.  
Step3 : If memory address is less than the base address display “invalid memory limit”.

Step4 : Create the segment table with the segment number and segment address and display it.  
Step5 : Read the segment number and displacement.

Step6 : If the segment number and displacement is valid compute the real address and display the same.  
Step7 : Stop the program.

### Program:

```
#include<stdio.h>
#include<conio.h>
struct list
{
    Int seg;
    int base;
    int limit;
    struct list *next;
}
*p;
void insert(struct list *q,int base,int limit,int seg)
{
    if(p==NULL)
    {
        p=malloc(sizeof(Struct list));p-
        >limit=limit;
        p->base=base;
        p->seg=seg;
        p->next=NULL;
    }
    else
    {
        while(q->next!=NULL)
        {
            Q=q->next;
            Printf(“yes”)
```

```

    }
    q->next=malloc(sizeof(Struct list));q-
    >next ->limit=limit;
    q->next ->base=base;
    q->next ->seg=seg;
    q->next ->next=NULL;
    }
    }
    int find(struct list *q,int seg)
    {
    while(q->seg!=seg)
    {
    q=q->next;
    }
    return q->limit;
    }
    int search(struct list *q,int seg)
    {
    while(q->seg!=seg)
    {
    q=q->next;
    }
    return q->base;
    }
    main()
    {
    p=NULL;
    int
    seg,offset,limit,base,c,s,physical;
    printf("Enter segment table/n");
    printf("Enter -1 as segment value for termination\n");
    do
    {
    printf("Enter segment
    number");scanf("%d",&seg);
    if(seg!=-1)
    {
    printf("Enter base
    value:");
    scanf("%d",&base);

    printf("Enter value for
    limit:");scanf("%d",&limit);
    insert(p,base,limit,seg);
    }
    }

```

```

}
while(seg!=-1)
printf("Enter offset:");
scanf("%d",&offset);
printf("Enter bsegmentation number:");
scanf("%d",&seg);
c=find(p,seg);
s=search(p,seg);
if(offset<c)
{
physical=s+offset;
printf("Address in physical memory %d\n",physical);
}
else
{
printf("error");
}

```

## OUTPUT:

```

Enter segment table
Enter -1 as segmentation value for termination
Enter segment number:1
Enter base value:2000
Enter value for
limit:100Enter segment
number:2Enter base
value:2500 Enter value
for limit:100
Enter segmentation number:-
1Enter offset:90
Enter segment number:2
Address in physical memory 2590

```

```

Enter segment table
Enter -1 as segmentation value for termination
Enter segment number:1
Enter base value:2000
Enter value for
limit:100Enter segment
number:2Enter base
value:2500 Enter value
for limit:100
Enter segmentation number:-

```

1Enter offset:90  
Enter segment number:1  
Address in physical memory  
20