# Chitharanjan Ganesh Kumar

BOSTON, MA | ganeshkumar.c@northeastern.edu | +1 8574659338 | LinkedIn-ChitharanjanG

### **EDUCATION**

**Master of Science in Robotics (Mechanical Engineering Concentration)** Dec 2025 Northeastern University, Boston, MA GPA:3.79 Coursework: Robot Mechanics and Controls, Robot Sensing and Technology, Machine Learning, Control Systems Engineering Jul 2021 **Bachelor of Engineering in Mechanical Engineering** RV College of Engineering, Bengaluru, India GPA:3.50 Coursework: Design of Machines, Kinematics and Dynamics, Control Engineering, Strength of Materials, Automotive Systems

#### **SKILLS**

Python, MATLAB, C/C++ Languages: **CAD Tools:** NX, SolidWorks, Catia V5

ANSYS WORKBENCH, HyperWorks, Simulink, MS Office Suite, KISSsoft **Analysis Tools:** 

Simulation Tools: ROS, Gazebo, KISSsys, IPG Carmaker, GT Suite

#### **WORK EXPERIENCE**

#### **Powertrain Mechanical Design Engineer**

Greaves Electric Mobility Pvt. Ltd, Bengaluru, India

Aug 21 - Dec 2023

- Managed the production drawings, and Bill of Materials, and conducted tolerance stack-up analysis for facilitating the mass production of components for the Motor Integrated with 2-Stage Gearbox, ensuring it met IP67 rating standards
- Commenced the development of comprehensive design documentation for E-motors and gearboxes, including DFMEA and DVP
- Engaged extensively in the prototyping, testing, and development phases of single-stage and two-stage reduction gearboxes coupled with e-motor and electrical components
- Developed an integrated motor with gearbox in 3 product development cycles, resulting in 15%-time reduction in mass production.
- Pioneered the design of Swingarm for two-wheelers, incorporating the e-motor and gearbox, marking the first such innovation

#### ACADEMIC PROJECTS

#### Indian Premier League (IPL) Score Predictor

Northeastern University - Boston, MA, United States of America

Jun 2024

- Collected and preprocessed historical IPL match data, handling missing values and encoding categorical variables
- Trained and evaluated multiple machine learning models (Linear Regression, Decision Trees, XG Boost, Ada Boost, Support Vector Regression) to predict match scores
- Focused on comparing model performance to determine the most effective approach for predicting IPL match scores

### Simultaneous Localization and Mapping (SLAM)

Northeastern University - Boston, MA, United States of America

Apl 2024

- Conducted a comprehensive comparative analysis of LiDAR-based 3D mapping techniques: LeGO-LOAM and LIO-SAM
- Compared trajectories with ground truth in simulation using Root mean square error and Absolute trajectory error metrics in Python
- Assessed RMSE and ATE values to evaluate performance across different environments with TurtleBot simulations

## **Exoskeleton for Assisted Stair Climb**

Northeastern University - Boston, MA

Mar 2024

- Developed a passive 3D-printed exoskeleton for assisted stair climbing with mobility analysis based on Grubler's equation
- Conducted kinematic analysis using the Newton-Raphson method in MATLAB, validating the accuracy of analytical method with results of SolidWorks
- Designed using torsion springs and levers to assist the elderly and those with lower limb weaknesses, effectively reducing stress

#### **Team Helios Racing (SAE BAJA)**

RV College of Engineering-Collegiate Club, India

Aug 2017- Jul 2021

- Embarked on the design and analysis of diverse drive train components, encompassing shafts, gears, and axles using CATIA V5 and KISSsoft software
- Acquired a deep comprehension of the design intricacies and conducted analysis using ANSYS Workbench for Axles, Shafts, Hubs, Open Differential, Reduction gearbox, and continuously variable transmission (CVT) components
- Developed jigs and fixtures for chassis and mounts for all subsystem parts components

# **Project on Robotics**

RV College of Engineering- Mechanical Engineering Department, India

Dec 2020

- Implemented pick-and-place tasks using Robo-Arduino and managed the robot through an RF signal.
- Supported the chassis with four Omni wheels to facilitate robotic arm movement and controlled by Python code.

#### ACHIEVEMENTS AND EXTRA-CURRICULAR ACTIVITIES

Engineer's Day Award winner in Greaves Electric Mobility Pvt. Ltd, Bengaluru, India

2023