In [0]: # Importing Libraries

In [24]: from google.colab import drive drive.mount('/content/drive')

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_i d=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redi rect_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response_type=code&scope=email%20h ttps%3a%2f%2fwww.googleapis.com%2fauth%2fdcs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fpeopleapi.readonly (https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redirect_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response_type=code&scope=email%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdcs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos

Enter your authorization code:
.....
Mounted at /content/drive

,

In [25]: !pip3 install patool import patoolib patoolib.extract archive('/content/drive/My Drive/HumanActivityRecognition.zip')

Collecting patool

Downloading https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d 8110964320ab4851134a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl (https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d8110964320ab48511 34a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl) (77kB)

| 81kB 1.4MB/s

Installing collected packages: patool

Successfully installed patool-1.12

patool: Extracting /content/drive/My Drive/HumanActivityRecognition.zip ...
patool: running /usr/bin/7z x -o./Unpack_awsrkuu_ -- "/content/drive/My Drive/H
umanActivityRecognition.zip"

patool: ... /content/drive/My Drive/HumanActivityRecognition.zip extracted to `HumanActivityRecognition' (multiple files in root).

Out[25]: 'HumanActivityRecognition'

```
In [0]: import pandas as pd
import numpy as np
```

Data

```
In [0]: # Data directory
        DATADIR = 'UCI HAR Dataset'
In [0]: # Raw data signals
        # Signals are from Accelerometer and Gyroscope
        # The signals are in x,y,z directions
        # Sensor signals are filtered to have only body acceleration
        # excluding the acceleration due to gravity
        # Triaxial acceleration from the accelerometer is total acceleration
        SIGNALS = [
             "body acc x",
             "body_acc_y",
            "body_acc_z",
            "body_gyro_x",
            "body_gyro_y",
             "body_gyro_z",
             "total_acc_x",
             "total_acc_y",
             "total acc z"
        ]
```

```
In [0]: # Utility function to read the data from csv file
        def _read_csv(filename):
            return pd.read csv(filename, delim whitespace=True, header=None)
        # Utility function to load the load
        def load_signals(subset):
            signals data = []
            for signal in SIGNALS:
                filename = f'/content/HumanActivityRecognition/HAR/UCI_HAR_Dataset/{subs
                signals data.append(
                    _read_csv(filename).as_matrix()
                )
            # Transpose is used to change the dimensionality of the output,
            # aggregating the signals by combination of sample/timestep.
            # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
            return np.transpose(signals data, (1, 2, 0))
In [0]:
        def load_y(subset):
            The objective that we are trying to predict is a integer, from 1 to 6,
            that represents a human activity. We return a binary representation of
            every sample objective as a 6 bits vector using One Hot Encoding
            (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.ht
            filename = f'/content/HumanActivityRecognition/HAR/UCI HAR Dataset/{subset}/
            y = _read_csv(filename)[0]
            return pd.get dummies(y).as matrix()
In [0]: def load data():
            Obtain the dataset from multiple files.
            Returns: X_train, X_test, y_train, y_test
            X_train, X_test = load_signals('train'), load_signals('test')
            y_train, y_test = load_y('train'), load y('test')
            return X_train, X_test, y_train, y_test
In [0]: # Importing tensorflow
        np.random.seed(42)
        import tensorflow as tf
        tf.set random seed(42)
In [0]: # Configuring a session
        session conf = tf.ConfigProto(
            intra op parallelism threads=1,
            inter op parallelism threads=1
        )
```

```
In [0]: # Import Keras
         from keras import backend as K
         sess = tf.Session(graph=tf.get default graph(), config=session conf)
         K.set session(sess)
 In [0]: # Importing libraries
         from keras.models import Sequential
         from keras.layers import LSTM
         from keras.layers.core import Dense, Dropout
 In [0]:
         # Initializing parameters
         epochs = 32
         batch size = 16
         n hidden1 = 66
         \# n hidden2 = 33
 In [0]: # Utility function to count the number of classes
         def _count_classes(y):
             return len(set([tuple(category) for category in y]))
In [72]: # Loading the train and test data
         X_train, X_test, Y_train, Y_test = load_data()
         /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:11: FutureWarning:
         Method .as matrix will be removed in a future version. Use .values instead.
           # This is added back by InteractiveShellApp.init_path()
         /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:13: FutureWarning:
         Method .as matrix will be removed in a future version. Use .values instead.
           del sys.path[0]
In [73]: timesteps = len(X train[0])
         input_dim = len(X_train[0][0])
         n_classes = _count_classes(Y_train)
         print(timesteps)
         print(input dim)
         print(len(X train))
         128
         7352
```

· Defining the Architecture of LSTM

```
In [74]: # Initiliazing the sequential model
model = Sequential()
from keras.callbacks import EarlyStopping
from keras.callbacks import ModelCheckpoint
from keras.models import load_model

# Configuring the parameters
model.add(LSTM(n_hidden1, input_shape=(timesteps, input_dim))) #,,return_sequence
# Adding a dropout layer
model.add(Dropout(0.6))

# model.add(LSTM(n_hidden2, input_shape=(timesteps, input_dim)))
# # Adding a dropout layer
# model.add(Dropout(0.7))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()
```

WARNING:tensorflow:Large dropout rate: 0.6 (>0.5). In TensorFlow 2.x, dropout() uses dropout rate instead of keep_prob. Please ensure that this is intended. Model: "sequential 5"

Output Shape	Param #
(None, 66)	20064
(None, 66)	0
(None, 6)	402
	(None, 66)

Total params: 20,466 Trainable params: 20,466 Non-trainable params: 0

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/32
7352/7352 [============== ] - 43s 6ms/step - loss: 1.2165 - acc:
0.4804 - val loss: 1.0231 - val acc: 0.5351
Epoch 2/32
7352/7352 [=============== ] - 42s 6ms/step - loss: 0.9784 - acc:
0.5722 - val_loss: 1.1168 - val_acc: 0.4679
Epoch 3/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.8013 - acc:
0.6260 - val_loss: 0.8258 - val_acc: 0.6067
Epoch 4/32
0.6340 - val_loss: 0.9166 - val_acc: 0.6498
Epoch 5/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.7224 - acc:
0.6887 - val_loss: 0.8064 - val_acc: 0.7011
Epoch 6/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.7062 - acc:
0.6751 - val_loss: 0.8184 - val_acc: 0.7089
Epoch 7/32
7352/7352 [============== ] - 42s 6ms/step - loss: 0.5461 - acc:
0.7769 - val_loss: 0.6499 - val_acc: 0.7184
Epoch 8/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.4655 - acc:
0.8428 - val loss: 0.9957 - val acc: 0.7228
7352/7352 [============== ] - 41s 6ms/step - loss: 0.4051 - acc:
0.8619 - val_loss: 0.7026 - val_acc: 0.8117
Epoch 10/32
7352/7352 [============== ] - 42s 6ms/step - loss: 0.3175 - acc:
0.8995 - val_loss: 0.3685 - val_acc: 0.8653
Epoch 11/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.2710 - acc:
0.9074 - val loss: 0.5330 - val acc: 0.8717
Epoch 12/32
0.9151 - val loss: 0.4381 - val acc: 0.8768
Epoch 13/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.2383 - acc:
0.9256 - val loss: 0.4444 - val acc: 0.8721
Epoch 14/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1921 - acc:
0.9347 - val_loss: 0.4037 - val_acc: 0.8687
Epoch 15/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1919 - acc:
0.9374 - val loss: 0.3120 - val acc: 0.8992
```

```
Epoch 16/32
0.9400 - val_loss: 0.2919 - val_acc: 0.9057
Epoch 17/32
7352/7352 [=============== ] - 43s 6ms/step - loss: 0.2576 - acc:
0.9267 - val_loss: 0.4852 - val_acc: 0.8531
Epoch 18/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1717 - acc:
0.9387 - val_loss: 0.3191 - val_acc: 0.9026
Epoch 19/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1755 - acc:
0.9382 - val_loss: 0.3675 - val_acc: 0.9009
Epoch 20/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1639 - acc:
0.9416 - val loss: 0.2869 - val acc: 0.9084
Epoch 21/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1648 - acc:
0.9399 - val_loss: 0.3324 - val_acc: 0.8945
Epoch 22/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1687 - acc:
0.9391 - val_loss: 0.5019 - val_acc: 0.9053
Epoch 23/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1644 - acc:
0.9429 - val_loss: 0.3353 - val_acc: 0.9206
Epoch 24/32
0.9425 - val loss: 0.3182 - val acc: 0.9209
Epoch 25/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1568 - acc:
0.9467 - val loss: 0.2759 - val acc: 0.9240
Epoch 26/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1363 - acc:
0.9461 - val_loss: 0.3511 - val_acc: 0.8918
Epoch 27/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1583 - acc:
0.9472 - val_loss: 0.3457 - val_acc: 0.9067
Epoch 28/32
7352/7352 [============== ] - 42s 6ms/step - loss: 0.1756 - acc:
0.9446 - val loss: 0.7317 - val acc: 0.8738
Epoch 29/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1448 - acc:
0.9517 - val loss: 0.3776 - val acc: 0.9125
Epoch 30/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1397 - acc:
0.9476 - val loss: 0.4637 - val acc: 0.9101
Epoch 31/32
0.9490 - val loss: 0.3766 - val acc: 0.9036
Epoch 32/32
7352/7352 [================ ] - 41s 6ms/step - loss: 0.1437 - acc:
0.9509 - val loss: 0.4356 - val acc: 0.8972
```

Out[76]: <keras.callbacks.History at 0x7fc0c9adf518>

```
In [78]: # Confusion Matrix
         print(confusion_matrix(Y_test, model.predict(X_test)))
         Pred
                             LAYING SITTING
                                                   WALKING_DOWNSTAIRS
                                              . . .
                                                                       WALKING_UPSTAIRS
         True
                                505
                                                                     0
                                                                                       0
         LAYING
                                          32
         SITTING
                                  5
                                                                     0
                                                                                       4
                                         382
                                              . . .
         STANDING
                                  0
                                         110
                                                                     0
                                                                                       1
         WALKING
                                  0
                                                                     3
                                                                                      22
                                           1
         WALKING_DOWNSTAIRS
                                  0
                                           0
                                                                   414
                                                                                       4
         WALKING_UPSTAIRS
                                  0
                                           0
                                                                     9
                                                                                     453
         [6 rows x 6 columns]
In [79]:
         score = model.evaluate(X_test, Y_test)
         2947/2947 [===========] - 2s 568us/step
In [80]:
         score
Out[80]: [0.4355118162471876, 0.8971835765184933]
```

• With a simple single layer architecture we got 92.4% accuracy and a loss of 0.37 from the best model.