In [0]: # Importing Libraries

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_i d=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redi rect_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response_type=code&scope=email%20h ttps%3a%2f%2fwww.googleapis.com%2fauth%2fdcs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fpeopleapi.readonly (https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redirect_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response_type=code&scope=email%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdcs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos

Enter your authorization code:
.....
Mounted at /content/drive

In [2]: !pip3 install patool
 import patoolib
 patoolib.extract_archive('/content/drive/My Drive/HumanActivityRecognition.zip')

Collecting patool

Downloading https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d 8110964320ab4851134a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl (https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d8110964320ab48511 34a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl) (77kB)

| 81kB 2.5MB/s eta 0:00:011

Installing collected packages: patool

Successfully installed patool-1.12

patool: Extracting /content/drive/My Drive/HumanActivityRecognition.zip ...
patool: running /usr/bin/7z x -o./Unpack_wny74lr4 -- "/content/drive/My Drive/H
umanActivityRecognition.zip"

patool: ... /content/drive/My Drive/HumanActivityRecognition.zip extracted to `HumanActivityRecognition' (multiple files in root).

Out[2]: 'HumanActivityRecognition'

In [0]: import pandas as pd
import numpy as np

Data

```
In [0]: # Data directory
        DATADIR = 'UCI HAR Dataset'
In [0]: # Raw data signals
        # Signals are from Accelerometer and Gyroscope
        # The signals are in x,y,z directions
        # Sensor signals are filtered to have only body acceleration
        # excluding the acceleration due to gravity
        # Triaxial acceleration from the accelerometer is total acceleration
        SIGNALS = [
             "body acc x",
             "body_acc_y",
            "body_acc_z",
            "body_gyro_x",
            "body_gyro_y",
             "body_gyro_z",
             "total_acc_x",
             "total_acc_y",
             "total acc z"
        ]
```

```
In [0]: # Utility function to read the data from csv file
        def read csv(filename):
            return pd.read csv(filename, delim whitespace=True, header=None)
        # Utility function to load the load
        def load_signals(subset):
            signals data = []
            for signal in SIGNALS:
                filename = f'/content/HumanActivityRecognition/HAR/UCI_HAR_Dataset/{subs
                signals data.append(
                    _read_csv(filename).as_matrix()
                )
            # Transpose is used to change the dimensionality of the output,
            # aggregating the signals by combination of sample/timestep.
            # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
            return np.transpose(signals data, (1, 2, 0))
In [0]:
        def load_y(subset):
            The objective that we are trying to predict is a integer, from 1 to 6,
            that represents a human activity. We return a binary representation of
            every sample objective as a 6 bits vector using One Hot Encoding
            (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.ht
            filename = f'/content/HumanActivityRecognition/HAR/UCI HAR Dataset/{subset}/
            y = _read_csv(filename)[0]
            return pd.get dummies(y).as matrix()
In [0]: def load data():
            Obtain the dataset from multiple files.
            Returns: X_train, X_test, y_train, y_test
            X_train, X_test = load_signals('train'), load_signals('test')
            y_train, y_test = load_y('train'), load y('test')
            return X_train, X_test, y_train, y_test
In [0]: # Importing tensorflow
        np.random.seed(42)
        import tensorflow as tf
        tf.set random seed(42)
In [0]: # Configuring a session
        session conf = tf.ConfigProto(
            intra op parallelism threads=1,
            inter op parallelism threads=1
        )
```

```
In [0]: # Import Keras
          from keras import backend as K
          sess = tf.Session(graph=tf.get default graph(), config=session conf)
          K.set session(sess)
 In [0]: # Importing libraries
          from keras.models import Sequential
          from keras.layers import LSTM
          from keras.layers.core import Dense, Dropout
 In [0]:
          # Initializing parameters
          epochs = 28
          batch size = 16
          n hidden1 = 31
          n hidden2 = 34
 In [0]: # Utility function to count the number of classes
          def _count_classes(y):
              return len(set([tuple(category) for category in y]))
In [120]: # Loading the train and test data
          X_train, X_test, Y_train, Y_test = load_data()
          /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:11: FutureWarning:
          Method .as matrix will be removed in a future version. Use .values instead.
            # This is added back by InteractiveShellApp.init_path()
          /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:13: FutureWarning:
          Method .as matrix will be removed in a future version. Use .values instead.
            del sys.path[0]
In [121]: timesteps = len(X train[0])
          input_dim = len(X_train[0][0])
          n_classes = _count_classes(Y_train)
          print(timesteps)
          print(input dim)
          print(len(X train))
          128
          7352
```

· Defining the Architecture of LSTM

```
In [122]: # Initiliazing the sequential model
    model = Sequential()
    from keras.callbacks import EarlyStopping
    from keras.callbacks import ModelCheckpoint
    from keras.models import load_model

# Configuring the parameters
    model.add(LSTM(n_hidden1, input_shape=(timesteps, input_dim),return_sequences = 
# Adding a dropout layer
    model.add(Dropout(0.4))

model.add(LSTM(n_hidden2, input_shape=(timesteps, input_dim)))
    # Adding a dropout Layer
    model.add(Dropout(0.7))
# Adding a dense output layer with sigmoid activation
    model.add(Dense(n_classes, activation='sigmoid'))
    model.summary()
```

Model: "sequential_14"

Layer (type)	Output Shape	Param #
lstm_27 (LSTM)	(None, 128, 31)	5084
dropout_27 (Dropout)	(None, 128, 31)	0
lstm_28 (LSTM)	(None, 34)	8976
dropout_28 (Dropout)	(None, 34)	0
dense_14 (Dense)	(None, 6)	210

Total params: 14,270 Trainable params: 14,270 Non-trainable params: 0

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/28
c: 0.4544 - val loss: 1.0180 - val acc: 0.5779
Epoch 2/28
c: 0.5975 - val_loss: 0.8259 - val_acc: 0.6271
c: 0.6285 - val_loss: 0.8054 - val_acc: 0.6227
Epoch 4/28
c: 0.6409 - val_loss: 0.7818 - val_acc: 0.6210
Epoch 5/28
c: 0.6457 - val_loss: 0.7894 - val_acc: 0.6223
Epoch 6/28
c: 0.6499 - val_loss: 0.9027 - val_acc: 0.6054
Epoch 7/28
c: 0.6568 - val_loss: 0.7988 - val_acc: 0.6200
Epoch 8/28
c: 0.6536 - val loss: 0.8979 - val acc: 0.6125
c: 0.6643 - val_loss: 0.7197 - val_acc: 0.6210
Epoch 10/28
7352/7352 [=============== - - 73s 10ms/step - loss: 0.6020 - ac
c: 0.6712 - val_loss: 0.7570 - val_acc: 0.6152
Epoch 11/28
c: 0.6808 - val loss: 0.6153 - val acc: 0.6284
Epoch 12/28
c: 0.7157 - val loss: 0.6488 - val acc: 0.6196
Epoch 13/28
c: 0.7946 - val loss: 0.6463 - val acc: 0.8782
Epoch 14/28
c: 0.8357 - val_loss: 0.5451 - val_acc: 0.8911
Epoch 15/28
c: 0.8828 - val loss: 0.4545 - val acc: 0.8850
```

```
Epoch 16/28
c: 0.9063 - val_loss: 0.5114 - val_acc: 0.8578
Epoch 17/28
c: 0.9053 - val_loss: 0.5672 - val_acc: 0.8775
Epoch 18/28
c: 0.9241 - val_loss: 0.5785 - val_acc: 0.8975
Epoch 19/28
c: 0.9274 - val_loss: 0.8392 - val_acc: 0.8649
Epoch 20/28
c: 0.9234 - val loss: 0.5132 - val acc: 0.8839
Epoch 21/28
c: 0.9297 - val_loss: 0.5169 - val_acc: 0.8924
Epoch 22/28
c: 0.9275 - val_loss: 0.6168 - val_acc: 0.8887
Epoch 23/28
c: 0.9334 - val loss: 0.7760 - val acc: 0.8697
Epoch 24/28
c: 0.9331 - val loss: 0.8598 - val acc: 0.8697
Epoch 25/28
c: 0.9368 - val_loss: 0.7258 - val_acc: 0.8843
Epoch 26/28
c: 0.9329 - val_loss: 0.6014 - val_acc: 0.8887
Epoch 27/28
c: 0.9316 - val loss: 0.7234 - val acc: 0.8985
Epoch 28/28
c: 0.9336 - val loss: 0.5799 - val acc: 0.9043
```

Out[124]: <keras.callbacks.History at 0x7f976d5e9518>

In [125]: # Confusion Matrix print(confusion_matrix(Y_test, model.predict(X_test)))

Pred	LAYING	SITTING	 WALKING_DOWNSTAIRS	WALKING_UPSTAIRS
True				
LAYING	510	0	 0	0
SITTING	1	382	 5	3
STANDING	0	68	 0	0
WALKING	0	0	 8	29
WALKING_DOWNSTAIRS	0	0	 408	11
WALKING_UPSTAIRS	0	0	 8	448

[6 rows x 6 columns]

Summary

• With a two layer architecture we got 90.4% accuracy and a loss of 0.57