#### In [0]: # Importing Libraries

## In [24]: from google.colab import drive drive.mount('/content/drive')

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client\_i d=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redi rect\_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response\_type=code&scope=email%20h ttps%3a%2f%2fwww.googleapis.com%2fauth%2fdocs.test%20https%3a%2f%2fwww.googleap is.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fpeopleapi.readonly (https://accounts.google.com/o/oauth2/auth?client\_id=947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redirect\_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response\_type=code&scope=email%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdocs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.photos.

Enter your authorization code:

Mounted at /content/drive

# In [25]: !pip3 install patool import patoolib patoolib.extract\_archive('/content/drive/My Drive/HumanActivityRecognition.zip')

#### Collecting patool

Downloading https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d8110964320ab4851134a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl (https://files.pythonhosted.org/packages/43/94/52243ddff508780dd2d8110964320ab4851134a55ab102285b46e740f76a/patool-1.12-py2.py3-none-any.whl) (77kB)

| 81kB 1.4MB/s

Installing collected packages: patool
Successfully installed patool-1.12

patool: Extracting /content/drive/My Drive/HumanActivityRecognition.zip ...

patool: running /usr/bin/7z x -o./Unpack\_awsrkuu\_ -- "/content/drive/My Drive/H
umanActivityRecognition.zip"

patool: ... /content/drive/My Drive/HumanActivityRecognition.zip extracted to `HumanActivityRecognition' (multiple files in root).

### Out[25]: 'HumanActivityRecognition'

```
In [0]: import pandas as pd
import numpy as np
```

#### **Data**

```
In [0]: # Data directory
        DATADIR = 'UCI HAR Dataset'
In [0]: # Raw data signals
        # Signals are from Accelerometer and Gyroscope
        # The signals are in x,y,z directions
        # Sensor signals are filtered to have only body acceleration
        # excluding the acceleration due to gravity
        # Triaxial acceleration from the accelerometer is total acceleration
        SIGNALS = [
             "body acc x",
             "body_acc_y",
            "body_acc_z",
             "body_gyro_x",
            "body_gyro_y",
             "body_gyro_z",
             "total_acc_x",
             "total_acc_y",
             "total acc z"
        ]
```

```
In [0]: # Utility function to read the data from csv file
        def _read_csv(filename):
            return pd.read csv(filename, delim whitespace=True, header=None)
        # Utility function to load the load
        def load_signals(subset):
            signals data = []
            for signal in SIGNALS:
                filename = f'/content/HumanActivityRecognition/HAR/UCI_HAR_Dataset/{subset/
                signals data.append(
                    _read_csv(filename).as_matrix()
                )
            # Transpose is used to change the dimensionality of the output,
            # aggregating the signals by combination of sample/timestep.
            # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
            return np.transpose(signals data, (1, 2, 0))
In [0]:
        def load_y(subset):
            The objective that we are trying to predict is a integer, from 1 to 6,
            that represents a human activity. We return a binary representation of
            every sample objective as a 6 bits vector using One Hot Encoding
            (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get dummies.ht
            filename = f'/content/HumanActivityRecognition/HAR/UCI HAR Dataset/{subset}/
            y = _read_csv(filename)[0]
            return pd.get dummies(y).as matrix()
In [0]: def load_data():
            Obtain the dataset from multiple files.
            Returns: X_train, X_test, y_train, y_test
            X_train, X_test = load_signals('train'), load_signals('test')
            y_train, y_test = load_y('train'), load y('test')
            return X_train, X_test, y_train, y_test
In [0]: # Importing tensorflow
        np.random.seed(42)
        import tensorflow as tf
        tf.set random seed(42)
In [0]: # Configuring a session
        session conf = tf.ConfigProto(
            intra op parallelism threads=1,
            inter op parallelism threads=1
         )
```

```
In [0]: # Import Keras
         from keras import backend as K
         sess = tf.Session(graph=tf.get_default_graph(), config=session_conf)
         K.set session(sess)
 In [0]: # Importing libraries
         from keras.models import Sequential
         from keras.layers import LSTM
         from keras.layers.core import Dense, Dropout
 In [0]:
         # Initializing parameters
         epochs = 32
         batch size = 16
         n hidden1 = 66
         # n hidden2 = 66
 In [0]: # Utility function to count the number of classes
         def _count_classes(y):
             return len(set([tuple(category) for category in y]))
In [46]: # Loading the train and test data
         X_train, X_test, Y_train, Y_test = load_data()
         /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:11: FutureWarning:
         Method .as matrix will be removed in a future version. Use .values instead.
           # This is added back by InteractiveShellApp.init_path()
         /usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:13: FutureWarning:
         Method .as matrix will be removed in a future version. Use .values instead.
           del sys.path[0]
In [47]: timesteps = len(X train[0])
         input_dim = len(X_train[0][0])
         n_classes = _count_classes(Y_train)
         print(timesteps)
         print(input dim)
         print(len(X train))
         128
         7352
```

· Defining the Architecture of LSTM

```
In [48]: # Initiliazing the sequential model
    model = Sequential()
    from keras.callbacks import EarlyStopping
    from keras.models import ModelCheckpoint
    from keras.models import load_model

# Configuring the parameters
    model.add(LSTM(n_hidden1, input_shape=(timesteps, input_dim))) #,,return_sequence
# Adding a dropout Layer
    model.add(Dropout(0.2))

# model.add(LSTM(n_hidden2, input_shape=(timesteps, input_dim)))
# # Adding a dropout Layer
# model.add(Dropout(0.7))
# Adding a dense output Layer with sigmoid activation
    model.add(Dense(n_classes, activation='sigmoid'))
    model.summary()
```

#### Model: "sequential\_2"

Layer (type)	Output Shape	Param #
lstm_2 (LSTM)	(None, 66)	20064
dropout_2 (Dropout)	(None, 66)	0
dense_2 (Dense)	(None, 6)	402

Total params: 20,466 Trainable params: 20,466 Non-trainable params: 0

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/32
7352/7352 [============== ] - 42s 6ms/step - loss: 1.1468 - acc:
0.4974 - val loss: 0.9718 - val acc: 0.5779
Epoch 2/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.8351 - acc:
0.6129 - val_loss: 0.8328 - val_acc: 0.6074
Epoch 3/32
7352/7352 [=============== ] - 40s 5ms/step - loss: 0.6960 - acc:
0.6748 - val_loss: 0.7534 - val_acc: 0.7085
Epoch 4/32
0.7871 - val_loss: 0.5295 - val_acc: 0.8127
Epoch 5/32
7352/7352 [=============== ] - 40s 5ms/step - loss: 0.3648 - acc:
0.8799 - val_loss: 0.5936 - val_acc: 0.8303
Epoch 6/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.2763 - acc:
0.9052 - val_loss: 0.4078 - val_acc: 0.8493
Epoch 7/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.2198 - acc:
0.9252 - val_loss: 0.3227 - val_acc: 0.8931
Epoch 8/32
7352/7352 [=============== ] - 40s 5ms/step - loss: 0.1823 - acc:
0.9374 - val loss: 0.2567 - val acc: 0.9138
Epoch 9/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.1705 - acc:
0.9388 - val loss: 0.2990 - val acc: 0.9046
Epoch 10/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.1581 - acc:
0.9403 - val_loss: 0.2954 - val_acc: 0.9016
Epoch 11/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.1477 - acc:
0.9484 - val loss: 0.3717 - val acc: 0.9057
Epoch 12/32
0.9391 - val loss: 0.3181 - val acc: 0.8972
Epoch 13/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.1407 - acc:
0.9502 - val loss: 0.2872 - val acc: 0.8992
Epoch 14/32
7352/7352 [============== ] - 40s 5ms/step - loss: 0.1376 - acc:
0.9478 - val_loss: 0.3902 - val_acc: 0.8999
Epoch 15/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1338 - acc:
0.9491 - val_loss: 0.6023 - val_acc: 0.8789
```

```
Epoch 16/32
0.9501 - val loss: 0.4209 - val acc: 0.8979
Epoch 17/32
7352/7352 [=============== ] - 40s 6ms/step - loss: 0.1693 - acc:
0.9384 - val_loss: 0.3419 - val_acc: 0.8989
Epoch 18/32
7352/7352 [=============== ] - 40s 5ms/step - loss: 0.1356 - acc:
0.9513 - val_loss: 0.5303 - val_acc: 0.8850
Epoch 19/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1378 - acc:
0.9498 - val_loss: 0.4059 - val_acc: 0.8968
Epoch 20/32
7352/7352 [=============== ] - 40s 5ms/step - loss: 0.1368 - acc:
0.9512 - val loss: 0.4248 - val acc: 0.9023
Epoch 21/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1331 - acc:
0.9486 - val_loss: 0.4898 - val_acc: 0.8829
Epoch 22/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1323 - acc:
0.9516 - val_loss: 0.5119 - val_acc: 0.8951
Epoch 23/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1397 - acc:
0.9501 - val loss: 0.3859 - val acc: 0.9019
Epoch 24/32
0.9501 - val loss: 0.3200 - val acc: 0.9135
Epoch 25/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1290 - acc:
0.9498 - val loss: 0.2496 - val acc: 0.9294
Epoch 26/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1279 - acc:
0.9494 - val_loss: 0.3840 - val_acc: 0.9097
Epoch 27/32
7352/7352 [============== ] - 41s 6ms/step - loss: 0.1546 - acc:
0.9456 - val loss: 0.3094 - val acc: 0.9057
Epoch 28/32
7352/7352 [============= ] - 41s 6ms/step - loss: 0.1279 - acc:
0.9521 - val loss: 0.3303 - val acc: 0.9057
Epoch 29/32
7352/7352 [============== ] - 40s 6ms/step - loss: 0.1188 - acc:
0.9520 - val loss: 0.3774 - val acc: 0.9101
Epoch 30/32
7352/7352 [=============== ] - 41s 6ms/step - loss: 0.1120 - acc:
0.9553 - val_loss: 0.3410 - val_acc: 0.9172
Epoch 31/32
0.9521 - val loss: 0.2935 - val acc: 0.9070
Epoch 32/32
0.9521 - val loss: 0.3748 - val acc: 0.9162
```

Out[50]: <keras.callbacks.History at 0x7fc0cb4d3a58>

```
In [52]: # Confusion Matrix
         print(confusion_matrix(Y_test, model.predict(X_test)))
                             LAYING SITTING
                                                   WALKING_DOWNSTAIRS
                                                                       WALKING_UPSTAIRS
         Pred
                                              . . .
         True
                                                                                      0
         LAYING
                                510
                                           0
                                                                    0
                                                                    2
                                                                                      0
         SITTING
                                  0
                                         415
         STANDING
                                  0
                                         100
                                                                    0
                                                                                      0
         WALKING
                                  0
                                                                   17
                                                                                      8
                                           1
         WALKING_DOWNSTAIRS
                                  0
                                                                  419
                                           0
                                                                                      0
         WALKING_UPSTAIRS
                                  0
                                                                    0
                                                                                    454
         [6 rows x 6 columns]
In [53]: | score = model.evaluate(X_test, Y_test)
         2947/2947 [===========] - 2s 560us/step
In [54]:
         score
Out[54]: [0.37476612998923525, 0.9161859518154055]
```

#### **Summary**

• With a simple single layer architecture and a dropout of 0.2 we got 92.94% accuracy and a loss of 0.24 from the best model.

```
In [ ]:
```