



Modelling and Identification

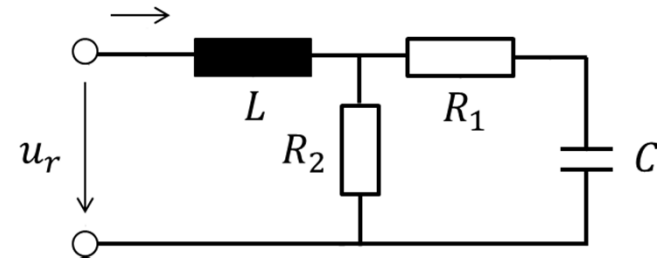
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Institute for Automatic Control

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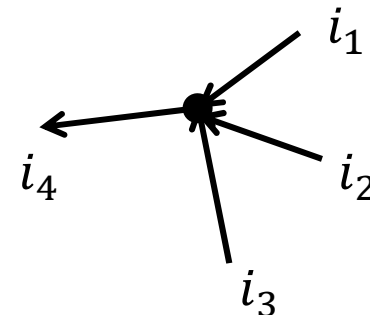
- Resistor: $u(t) = Ri(t)$,
- Capacitor: $i(t) = C \frac{du}{dt}$
- Inductor: $u(t) = L \frac{di}{dt}$
- **Kirchhoff voltage law:** The sum of voltages along an **arbitrary closed path** in the circuit is 0.

$$\sum_j u_j(t) = 0$$

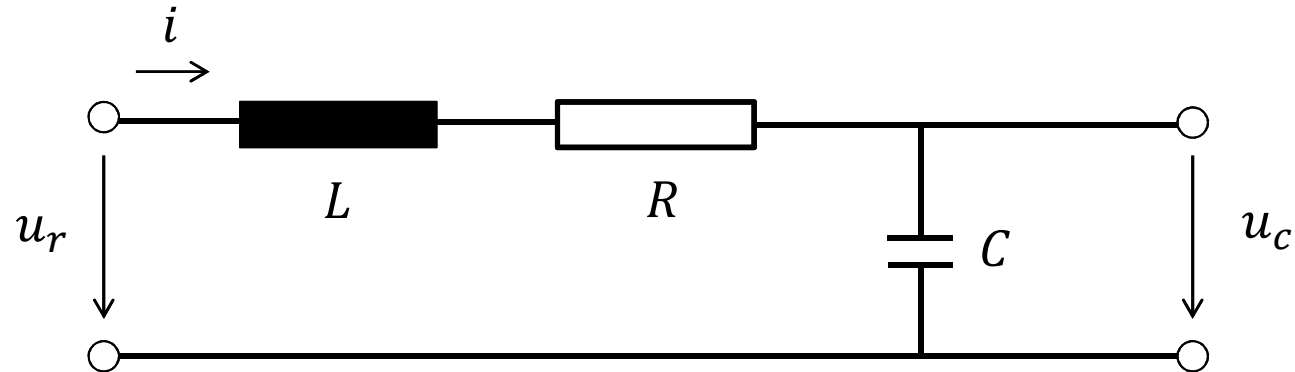


- **Kirchhoff current law:** The sum of the currents at **a node** is 0.

$$\sum_j i_j(t) = 0$$



Example: Input: u_r , Output: u_c



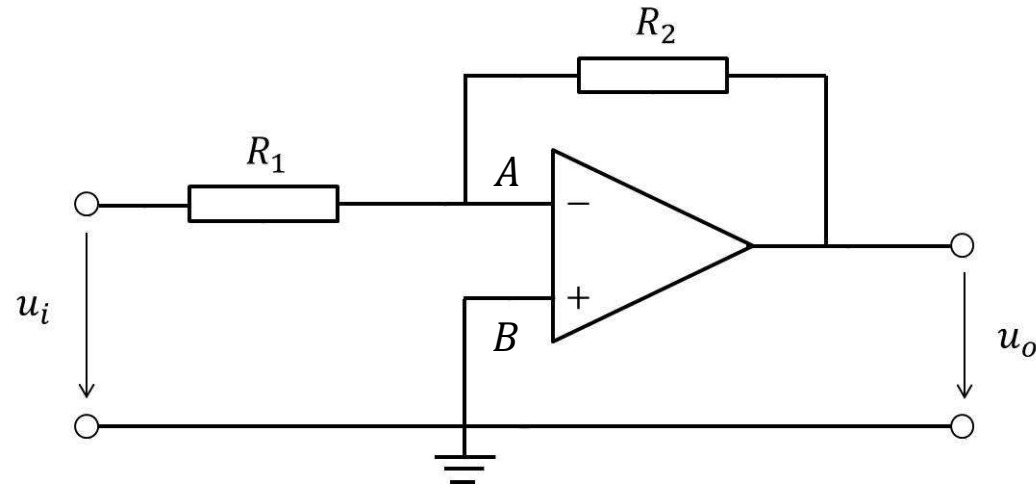
Kirchhoff voltage law: $L \frac{di}{dt} + Ri + u_c = u_r$

Capacitor: $i = C \frac{du_c}{dt}$



$$LC \frac{d^2 u_c}{dt^2} + RC \frac{du_c}{dt} + u_c = u_r$$

Example: Input: u_i , Output: u_o



Kirchhoff current law: $\frac{u_i}{R_1} + \frac{u_o}{R_2} = 0$



$$u_o = -\frac{R_2}{R_1} u_i$$

- **Law of motors:** A wire in a magnetic field that carries a current will have a force exerted on it

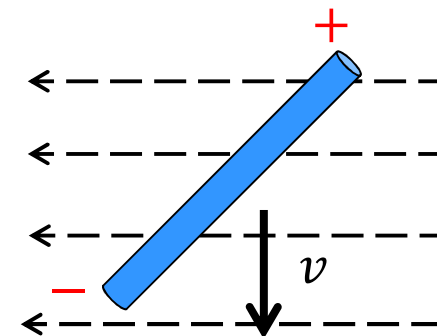
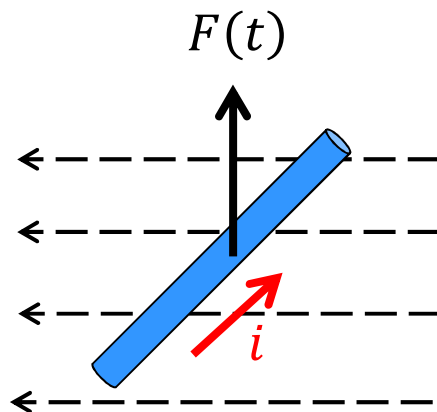
$$F(t) = Bli$$

B : flux density of the magnetic field

l : length of the conductor

- **Law of generators:** A voltage will be induced in a wire that moves relative to the magnetic field

$$e(t) = Blv$$



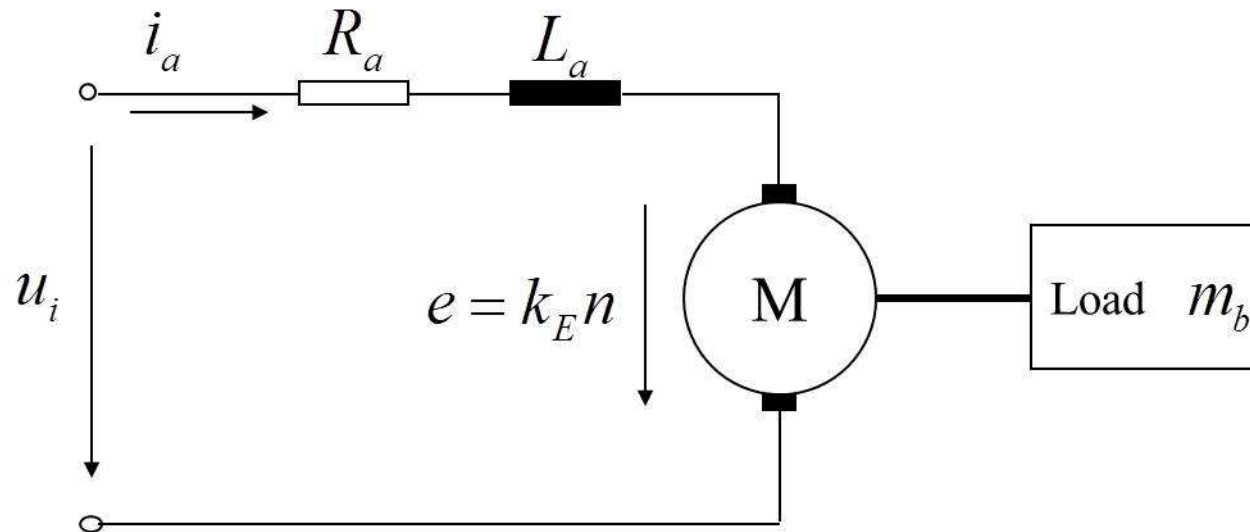
DC motor:

- Often used as actuator in control systems
- Torque exerted on the rotor:

$$M(t) = k_I i_a$$

- The voltage induced:

$$e(t) = k_E n$$



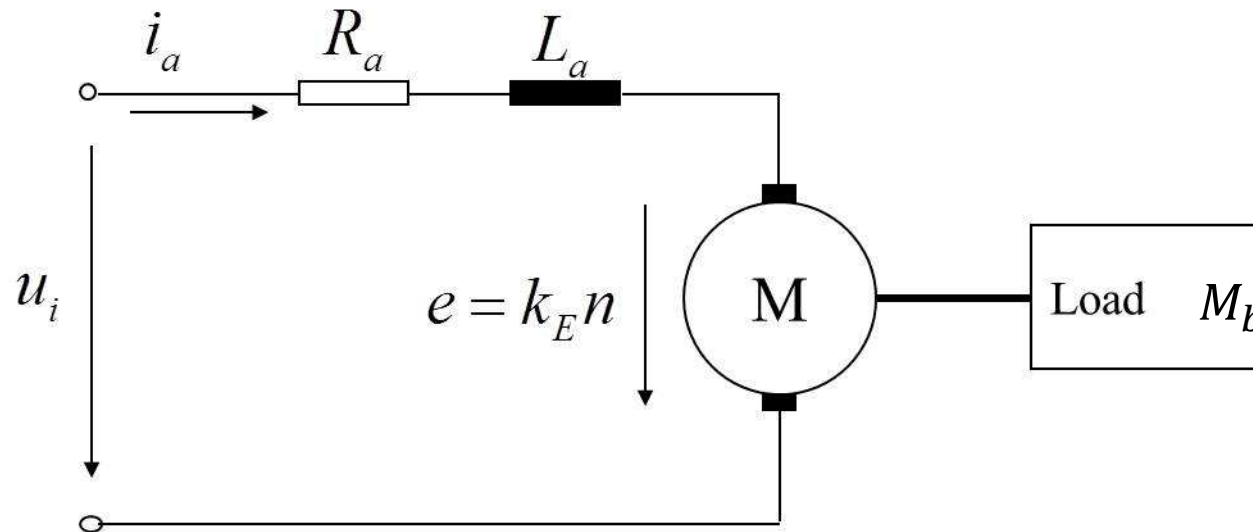
Model of DC motor:

Kirchhoff voltage law

$$u_i(t) = R_a i_a(t) + L_a \frac{di_a(t)}{dt} + k_E n(t)$$

Torque balance

$$J \frac{dn}{dt} = k_I i_a - M_b$$



The behaviour of a thermal system is described by

- Temperature T
- Heat flow rate q

Element laws:

➤ Thermal resistance

The heat flow rate from a body of temperature T_1 to a body of temperature T_2 is

$$q(t) = \frac{1}{R} (T_1(t) - T_2(t))$$

R : Thermal resistance of the path between two bodies. Unit: $K \cdot s/J$

➤ Thermal capacitance

The rate of temperature change is related to the instantaneous net heat flow rate into the body by

$$\frac{dT}{dt} = \frac{1}{C} (q_{in}(t) - q_{out}(t))$$

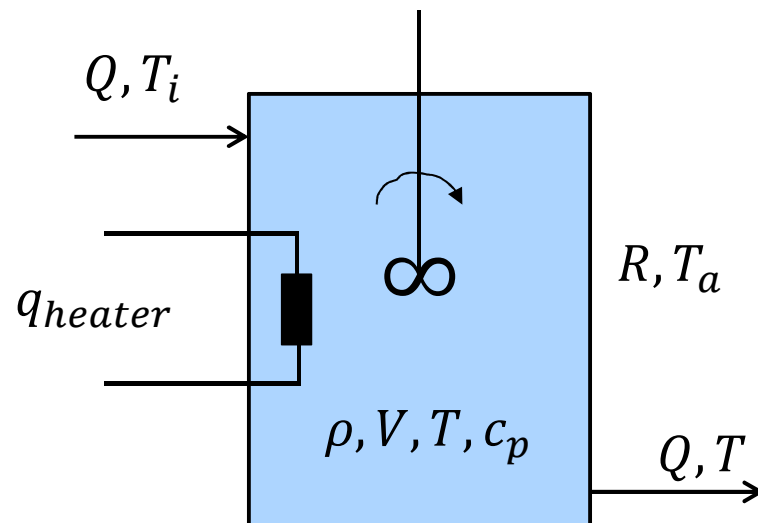
C : Thermal capacitance of the object. Unit: J/K .

For an object with mass m and specific heat c_p , the heat capacitance is

$$C = mc_p$$

Assumptions: The thermal gradients within the object is not too big. Otherwise, a distributed parameter model is needed.

Example 1: electrically heated stirred tank



Consider the temperature change of the liquid in the tank

$$\frac{dT}{dt} = \frac{1}{C} (q_{in}(t) - q_{out}(t))$$

$$C = mc_p = \rho V c_p$$

The heat flow rate entering the tank

$$q_{in}(t) = q_{heater} + \rho Q c_p T_i(t)$$

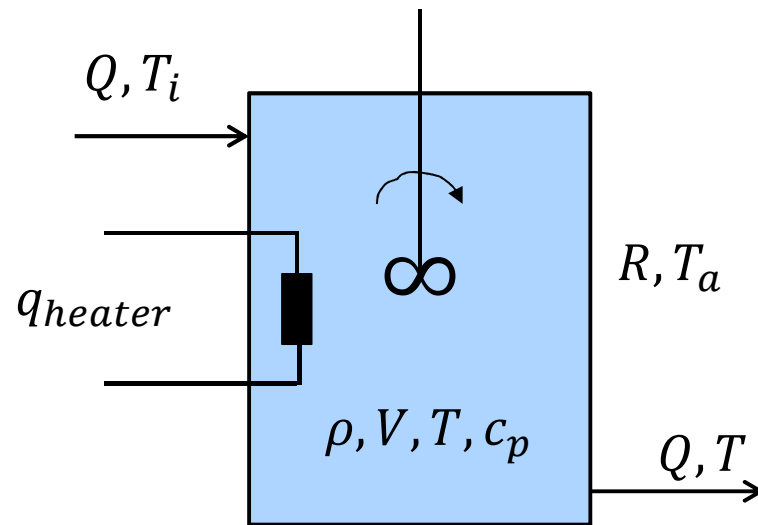
Q : volume flow rate

q_{heater} : heat rate of the heater

The heat flow rate leaving the tank

$$q_{out}(t) = \rho Q c_p T(t) + \frac{1}{R} (T(t) - T_a(t))$$

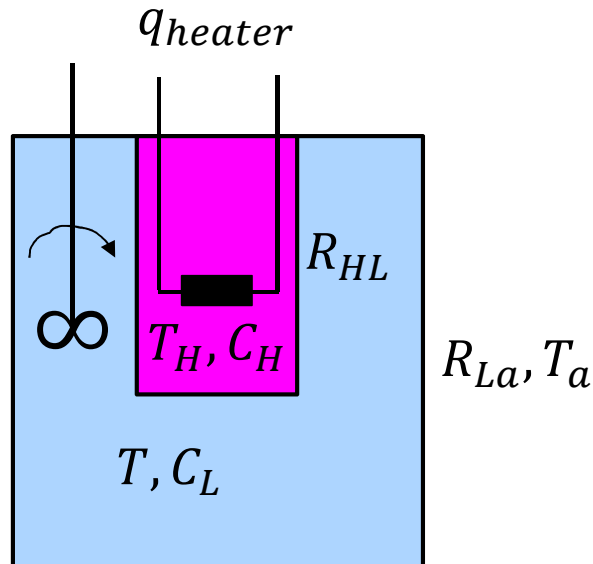
Example 1: electrically heated stirred tank



Total model:

$$\rho V c_p \frac{dT}{dt} = \rho Q c_p (T_i(t) - T(t)) - \frac{1}{R} (T(t) - T_a(t)) + q_{heater}$$

Example 2: tank with heater for batch processing (Close, 2002)



Consider the temperature change of the liquid in the tank

$$\frac{dT}{dt} = \frac{1}{C_L} (q_{HL}(t) - q_{La}(t))$$

Consider the temperature change of the heating element

$$\frac{dT_H}{dt} = \frac{1}{C_H} (q_{heater}(t) - q_{HL}(t))$$

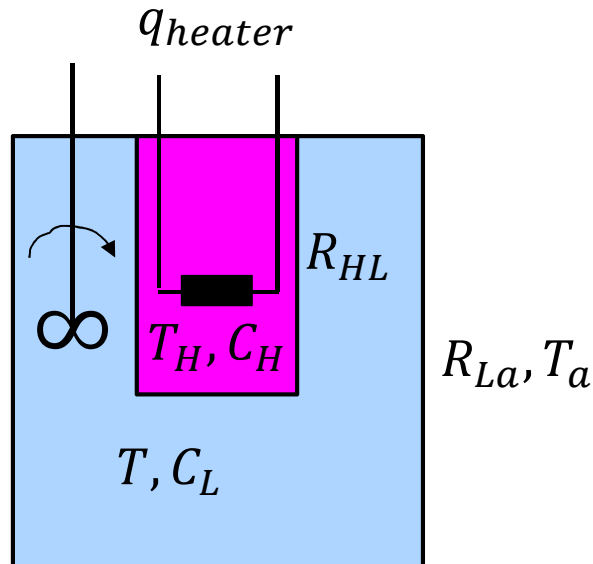
Heat flow from liquid to atmosphere

$$q_{La}(t) = \frac{1}{R_{La}} (T - T_a)$$

Heat flow from heating element to liquid

$$q_{HL}(t) = \frac{1}{R_{HL}} (T_H - T)$$

Example 2: tank with heater for batch processing (Close, 2002)

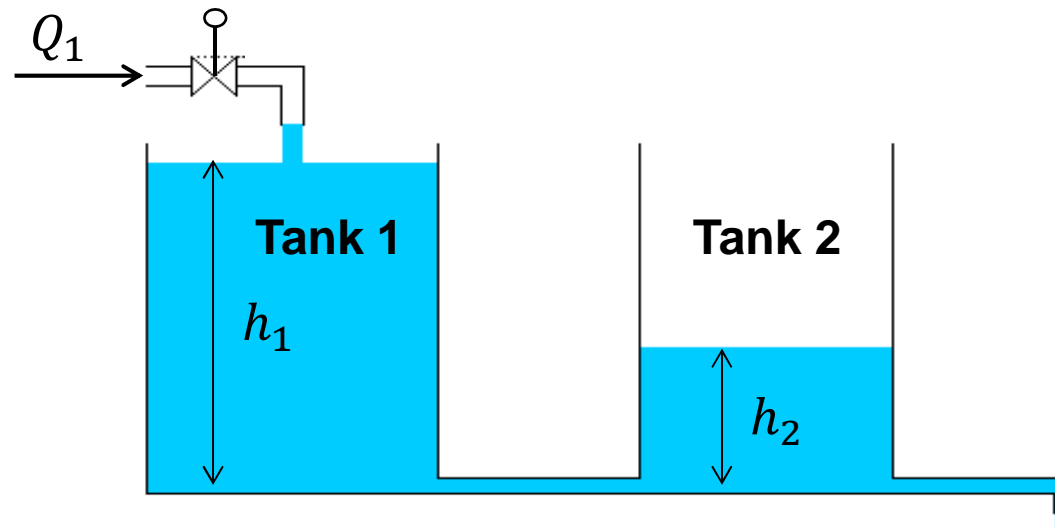


Total model:

$$\frac{dT_H}{dt} = \frac{1}{C_H} \left(q_{heater}(t) - \frac{1}{R_{HL}} (T_H - T) \right)$$

$$\frac{dT}{dt} = \frac{1}{C_L} \left(\frac{1}{R_{HL}} (T_H - T) - \frac{1}{R_{La}} (T - T_a) \right)$$

Example: fluid system

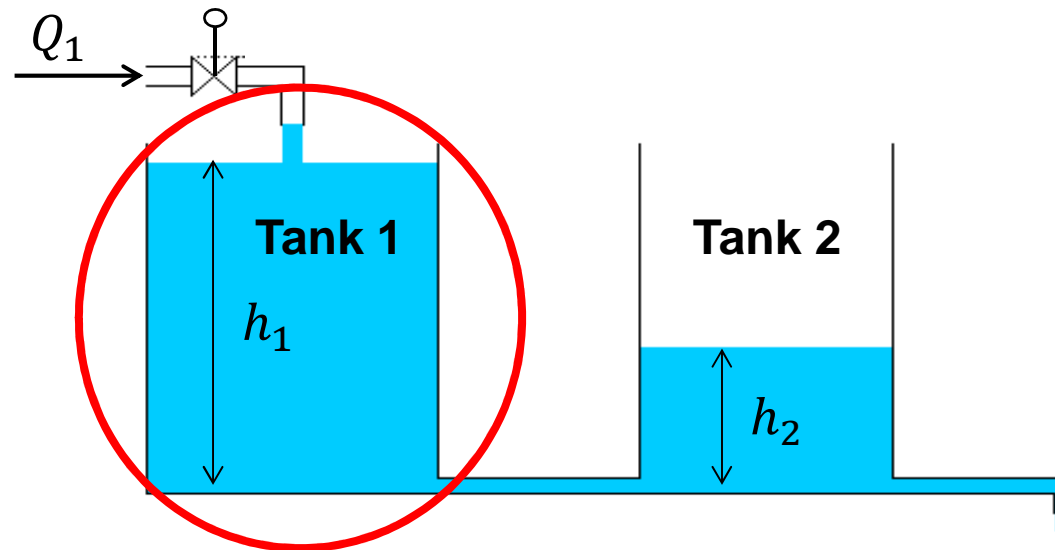


Q_1 : volume flow rate

A_{12}, A_{20} : cross section of the pipelines

A_1, A_2 : cross section of the tanks

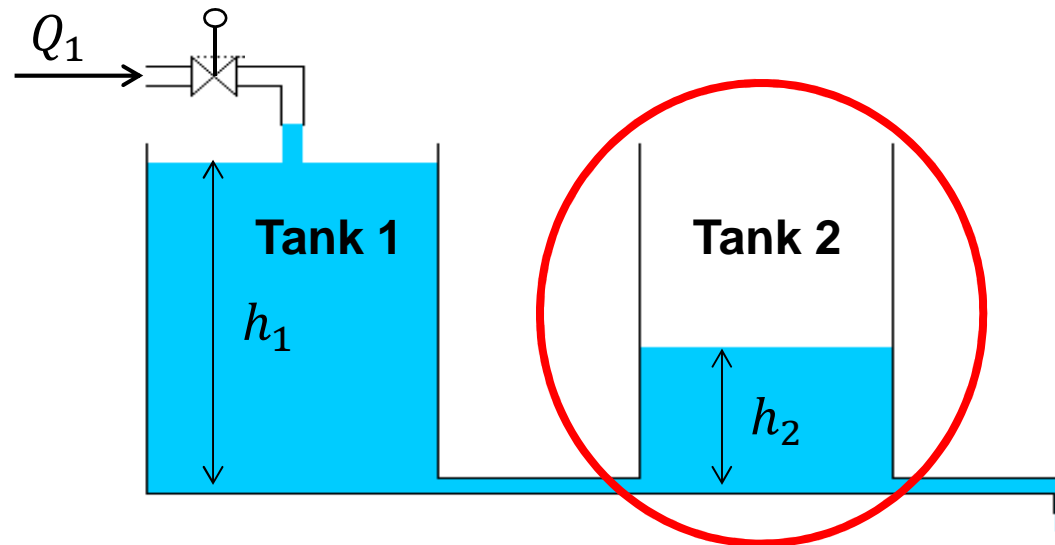
Example: fluid system



Mass balance for Tank 1

$$A_1 \dot{h}_1 = Q_1 - Q_{12}$$

Example: fluid system



Mass balance for Tank 1

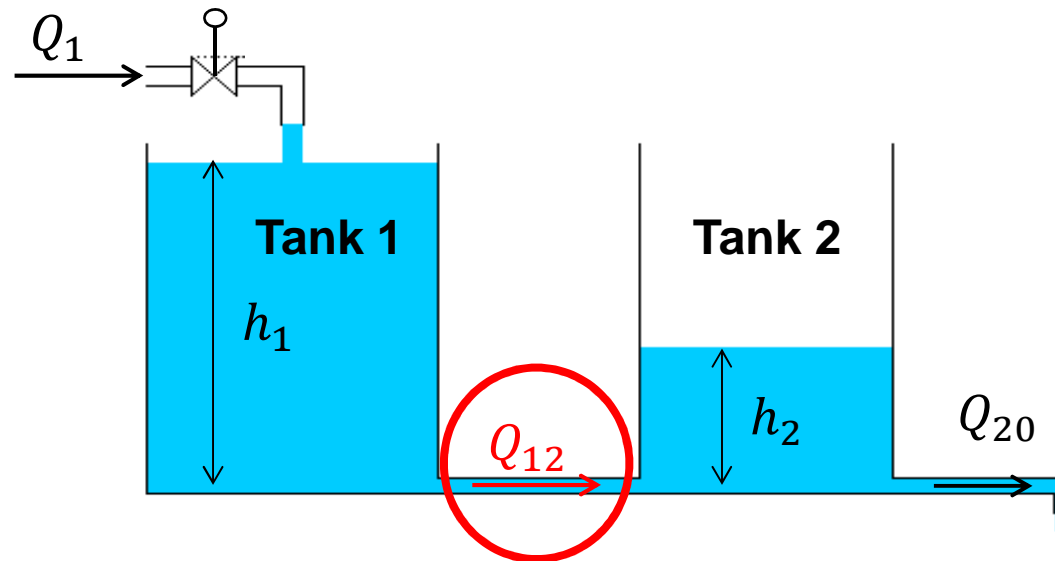
$$A_1 \dot{h}_1 = Q_1 - Q_{12}$$

Mass balance for Tank 2

$$A_2 \dot{h}_2 = Q_{12} - Q_{2o}$$

Coupling between two subsystems?

Example: fluid system



Mass balance for Tank 1

$$A_1 \dot{h}_1 = Q_1 - Q_{12}$$

Mass balance for Tank 2

$$A_2 \dot{h}_2 = Q_{12} - Q_{20}$$

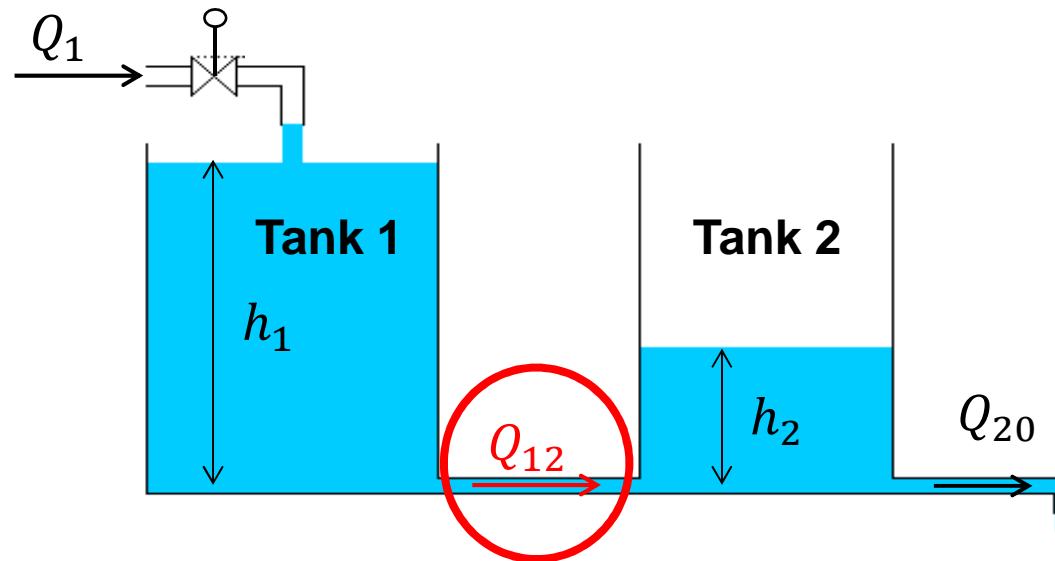
Torricelli's law

$$Q_{12} = aA_{12} \operatorname{sgn}(h_1 - h_2) \sqrt{2g|h_1 - h_2|}$$

Torricelli's law

$$Q_{20} = aA_{20} \sqrt{2gh_2}$$

Example: fluid system



System model

$$\begin{cases} A_1 \dot{h}_1 = Q_1 - aA_{12} \operatorname{sgn}(h_1 - h_2) \sqrt{2g|h_1 - h_2|} \\ A_2 \dot{h}_2 = aA_{12} \operatorname{sgn}(h_1 - h_2) \sqrt{2g|h_1 - h_2|} - aA_{20} \sqrt{2gh_2} \end{cases}$$