

# TiGL Workshop

## Curve Network Interpolation with Gordon Surfaces

12.09.2018

Merlin Pelz

System Dynamics and Control | SR-FLS

DLR Oberpfaffenhofen



Wissen für Morgen

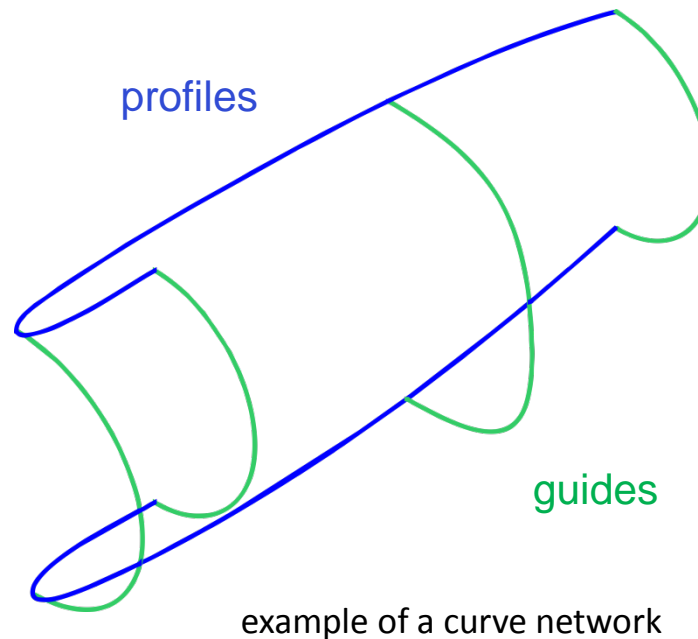


# Curve Network Interpolation with Gordon Surfaces



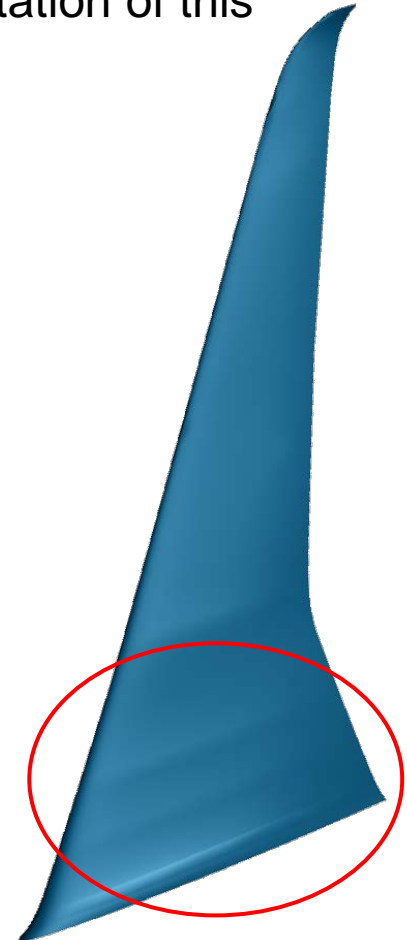
# The Curve Network Interpolation Problem

- Definition of the problem:
  - Given a network of profile and guide curves, find surface(s) which interpolate(s) these curves



# Why Gordon Surfaces? Problems with Old Method

- In Digital-X, Open CASCADE was contracted for the implementation of this algorithm (based on Coons Patches)
- Problems from aero simulations:
  - **Pressure oscillations** on the wing
  - Surface modelling probably the issue!
- Analysis:
  - Generated surfaces have small **bumps, waves** and **kinks**
  - The latter is caused by C1 or C2 **discontinuities** on the surface
- Conclusion:
  - Must implement a better algorithm by our own: **Gordon Surfaces**



DLR-SC / tigl

Watch16Star46Fork17

CodeIssues 35Pull requests 2Projects 2WikiInsights

Branch: cpacs\_3 - tigl / src / geometry /

Create new fileFind fileHistory

rainman110 Allow to use geom\_curves for surface creation Latest commit c51ed26 2 days ago

CCPACSSystems.cpp	made CCPACSTransformation automatically update its internal matrix if...	8 months ago
CCPACSSystems.h	made CCPACSTransformation automatically update its internal matrix if...	8 months ago
CCPACSFarField.cpp	Implemented new componentSegment coordsystem math	a year ago
CCPACSFarField.h	Added missing method overrides	8 months ago
CCPACSGenericSystem.cpp	fixed reading transformation from wrong xpath	4 months ago
CCPACSGenericSystem.h	Merge branch 'cpacs_3' into cpacs_3_parent_transformations	8 months ago
CCPACSGenericSystems.cpp	made CCPACSTransformation automatically update its internal matrix if...	8 months ago
CCPACSGenericSystems.h	made CCPACSTransformation automatically update its internal matrix if...	8 months ago
CCPACSTransformation.cpp	various refactorings and minor changes	4 months ago
CCPACSTransformation.h	made CCPACSTransformation automatically update its internal matrix if...	8 months ago
CCSTCurveBuilder.cpp	Added missing method overrides	8 months ago
CCSTCurveBuilder.h	Fixed compilation with occt 6 and 7	3 years ago
CFunctionToBSpline.cpp	Added missing method overrides	8 months ago
CFunctionToBSpline.h	Fixed compilation with occt 6 and 7	3 years ago
CNamedShape.cpp	Minor refactoring	6 days ago
CNamedShape.h	Minor refactoring	6 days ago
CPointsToLinearBSpline.cpp	Applied upgrade tool to sources	3 years ago
CPointsToLinearBSpline.h	Fixed compilation with occt 6 and 7	3 years ago
CTiglAbstractGeometricComponent.c...	removed svn \$Id\$ and \$Revision\$ comments	5 months ago
CTiglAbstractGeometricComponent.h	removed svn \$Id\$ and \$Revision\$ comments	5 months ago
CTiglAbstractSegment.h	removed svn \$Id\$ and \$Revision\$ comments	5 months ago
CTiglApproximateBSplineWire.cpp	removed svn \$Id\$ and \$Revision\$ comments	5 months ago
CTiglApproximateBSplineWire.h	removed svn \$Id\$ and \$Revision\$ comments	5 months ago
CTiglArcLengthReparameterization.cpp	Added missing method overrides	8 months ago
CTiglArcLengthReparameterization.h	Added more geometry algorithms to the python interface	4 months ago
CTiglBSplineAlgorithms.cpp	Allow to use geom_curves for surface creation	2 days ago
CTiglBSplineAlgorithms.h	Removed duplicate function GetCentripetalParameters	3 days ago
CTiglBSplineApproxInterp.cpp	Fixed performance bottleneck in CTiglBSplineApproxInterp	22 days ago
CTiglBSplineApproxInterp.h	Adaptions to compile with OCC 7.2.0 (#430)	3 months ago
CTiglBSplineFit.cpp	Fixed issue #440	3 months ago
CTiglBSplineFit.h	Adaptions to compile with OCC 7.2.0 (#430)	3 months ago
CTiglCurvesToSurface.cpp	Allow to use geom_curves for surface creation	2 days ago
CTiglCurvesToSurface.h	Allow to use geom_curves for surface creation	2 days ago
CTiglGordonSurfaceBuilder.cpp	Allow to use geom_curves for surface creation	2 days ago
CTiglGordonSurfaceBuilder.h	Removed gordon surface from CTiglBSplineAlgorithms	4 months ago



# B-splines



# B-splines

**Definition:** A *B-spline curve* of order  $k$  (and degree  $k - 1$ ) is defined as

$$C(t) = \sum_{i=0}^n B_i^k(t) P_i \quad , \quad t_{\min} < t < t_{\max}$$

with its *control points*  $P_0, \dots, P_n$  and *basis functions* of order  $k$   $B_i^k(t)$ .

Specify a *knot vector*  $T = (t_0, \dots, t_{n+k})$  where  $t_i \leq t_{i+1}$  for all  $i$ .

Then:

$$B_i^1(t) = \begin{cases} 1, & t_i < t < t_{i+1} \\ 0, & \text{otherwise} \end{cases}$$

$$B_i^k(t) = \frac{t - t_i}{t_{i+k-1} - t_i} B_i^{k-1}(t) + \frac{t_{i+k} - t}{t_{i+k} - t_{i+1}} B_{i+1}^{k-1}(t)$$





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**Definition:-** *uniform* knot vector: for all  $i$ :  $t_{i+1} - t_i = \text{const}$ , non-uniform otherwise

- *clamped* knot vector: for all  $i \in \{0, \dots, k - 1\}$ :  $t_i = t_0$

(endpoint interpolation) for all  $i \in \{n + 1, \dots, n + k\}$ :  $t_i = t_{n+k}$





# B-splines

- Some other properties:**
- $B_i^k(t) = 0$  for all  $t \notin [t_i, t_{i+k})$  (locality)
  - $C(t)$  is  $C^{k-2}$ -continuous
  - $2 \leq k \leq n + 1$
  - convex hull property



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**Changing the shape of a B-spline curve by:**

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- adding/removing control points



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## Changing the shape of a B-spline curve by:

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  - $\Rightarrow$  smoother and less close to the *control polygon* for bigger  $k$





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- using multiple knots



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  - ⇒ smoother and less close to the *control polygon* for bigger  $k$
- using multiple knots
  - ⇒ clamped curve
  - ⇒ for knot multiplicity  $p$ : curve is  $C^{k-p-1}$ -continuous at the corresp. point



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  - ⇒ smoother and less close to the *control polygon* for bigger  $k$
- using multiple knots
  - ⇒ clamped curve
  - ⇒ for knot multiplicity  $p$ : curve is  $C^{k-p-1}$ -continuous at the corresp. point
- changing the relative spacing of the knots
  - ⇒ closer knots: curve moves closer to corresponding control point



# B-splines

**Default setting:**

- cubic:  $k = 4$
- no multiple control points

**Remarks:**

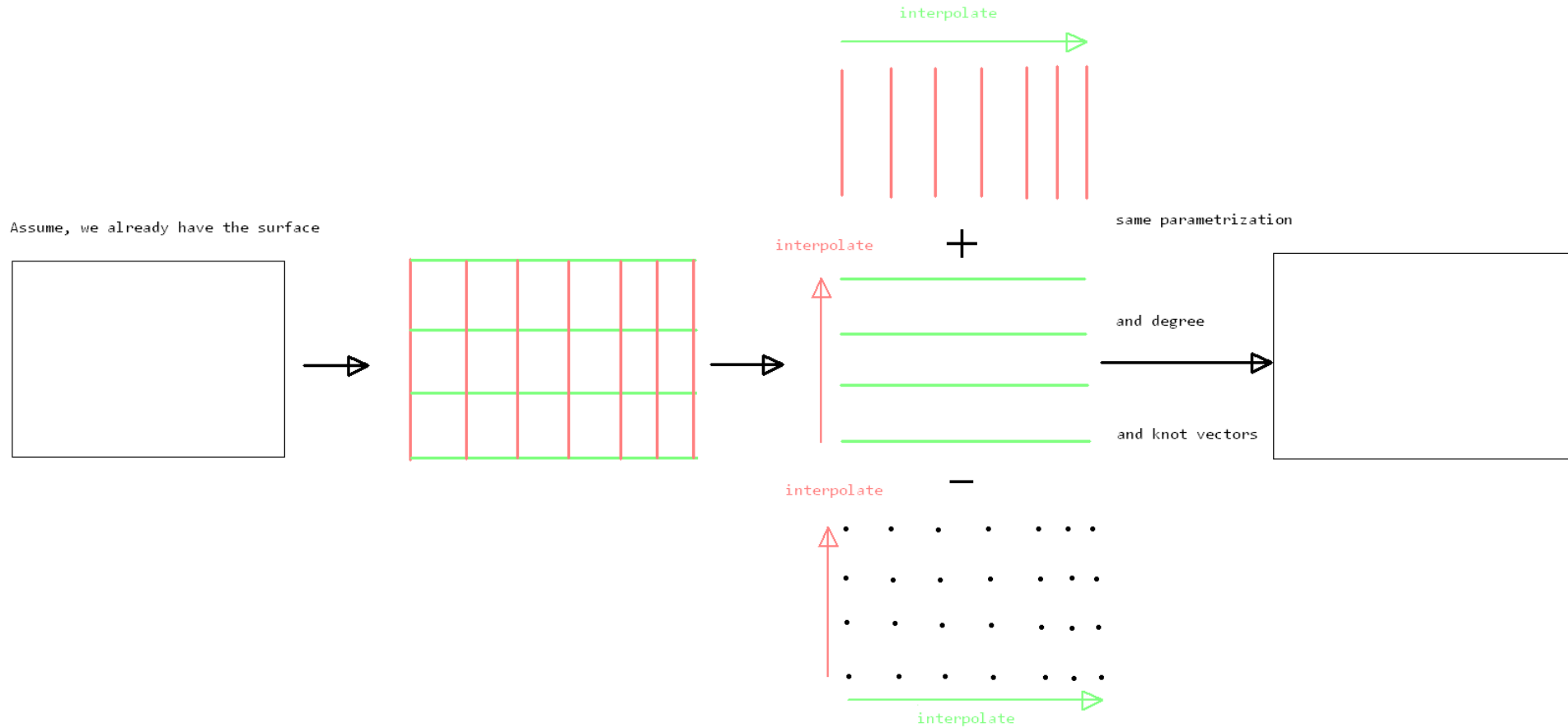
- Beziér curve for  $k = n + 1$  and no internal knots
- closed curve defined by the points  $P_1, \dots, P_M$ :  
control points:  $P_1, \dots, P_M, P_1, \dots, P_{k-1}$
- B-spline surface, also called **patch**:  
$$S(s, t) = \sum_{i=0}^m \sum_{j=0}^n B_i^k(s) B_j^l(t) P_{i,j} \quad , \quad s_{min} \leq s < s_{max} \quad , \quad t_{min} \leq t < t_{max}$$



# Mathematical Theory of Gordon Surfaces



# Gordon Surfaces





# Steps for Creating the Gordon Surface in Detail



# Main Steps

- ***Reparametrization*** of B-spline curves
- Creating a ***common knot vector*** for B-spline curves and surfaces
  - ***Degree elevation*** for B-spline curves and surfaces
  - ***Knot insertion*** for B-spline curves and surfaces
- Finding the ***intersection points*** of the curve network
- Creating the two ***skinned surfaces***
- Creating ***tensor product surface***
- Creating the ***Gordon Surface***



# $C^1$ -Continuous B-spline Curve Reparametrization

- Problem:
  - Make curve network compatible for the Gordon Surface theory
  - Therefore: reparametrize every curve  $C$  by giving certain new parameter values for all  $u$ -directional and all  $v$ -directional curves at their intersection parameter values
- So, find  $f(s)$  such that

$$C(u_i) = C(f(s_i))$$



# $C^1$ -Continuous B-spline Curve Reparametrization

- Compute sample points on the curve  $C$
- Interpolate these points at new parameter values by a B-spline curve  $D$  such that:

$$D(s_i) = C(f(s_i))$$

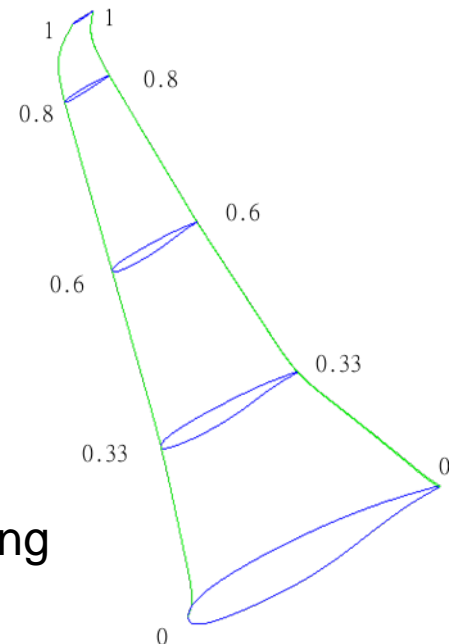


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- Compute sample points on the curve  $C$
- Interpolate these points at new parameter values by a B-spline curve  $D$  such that:

$$D(s_i) = C(f(s_i))$$

- The approximation by  $D(s)$  is done for not having to elevate the degree of the input curve
- Higher degree of B-spline curve ~ lower efficiency for computations
- Picture: example of a compatible curve network for a wing of an airplane after reparametrization



# Creating a Common Knot Vector

- Problem: all B-spline curves and surfaces shall have the same knot vector
- In case of curves:
  - Create a vector of all unique knots of all curves  $W$
  - Create a vector of the multiplicities of each knot in  $W$   $M$
  - Insert as many knots as needed in all knot vectors to get the vector  $W$  with multiplicities  $M$
- For surfaces, do this with both knot vectors  $U$  and  $V$



# Creating the Skinned Surfaces

- Problem: *skin* all  $u$ -directional curves of the curve network
- Write all control points of all B-spline curves  $\{P_{ij}\}$  in a matrix
- Interpolate control points by  $v$ -directional B-spline curves  $C_i$  at certain parameter values  $\{v_k\}$  to get  $\{Q_{ij}\}$ :

$$P_{ik} = C_i(v_k) = \sum_{j=0}^m B_j^l(v_k) Q_{ij}, \quad i \in \{1, \dots, n\}, j \in \{1, \dots, m\}$$

- Create skinned surface with control points  $\{Q_{ij}\}$ , knot vectors and degrees of  $u$ -directional and  $v$ -directional B-spline curves





# Creating the Skinned Surfaces

- Problem: *skin* all the  $v$ -directional B-spline curves
- Use the same method as before and flip the parameters  $u$  and  $v$  of the surface  $S(u, v)$  to get  $S(v, u)$
- Create the skinned surface by transposing the control point matrix, using the knot vector  $V$  for  $U$  and vice versa, and the  $v$ -directional degree for the  $u$ -directional degree and vice versa



# Creating the Tensor Product Surface

- Problem: create intersection points interpolating tensor product surface
- Find the intersection points  $\{X_{ij}\}$  of the curve network
- Interpolate all the points by  $u$ -directional B-spline curves at certain parameter values  $\{u_l\}$  :

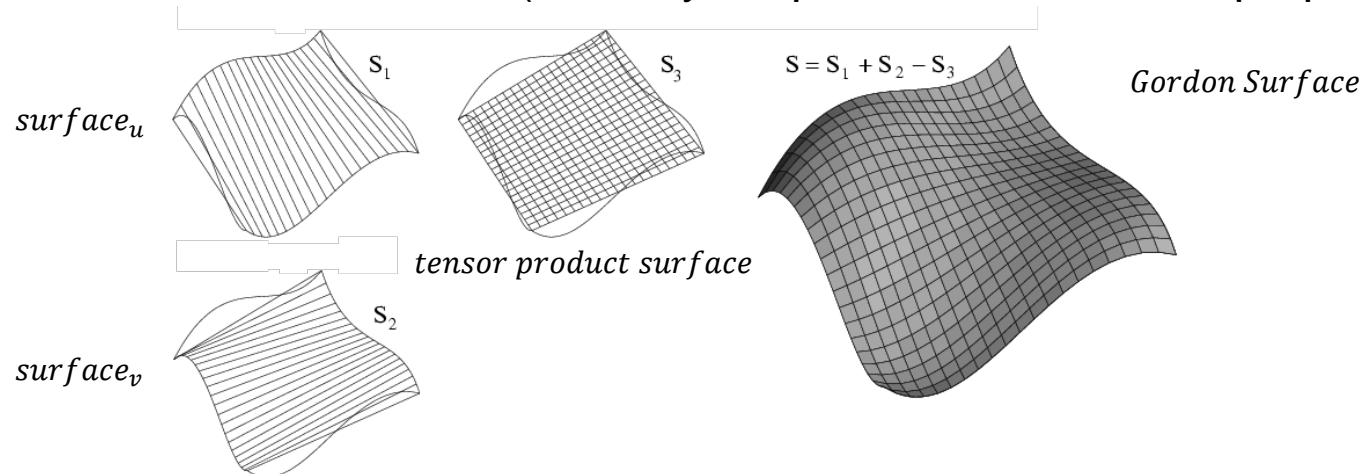
$$X_{jl} = \sum_{i=0}^n B_i^p(u_l) P_{ij}, \quad i, l \in \{1, \dots, n\}, j \in \{1, \dots, m\}$$

- Create a skinned surface with these curves



# Finally: Creating the Gordon Surface

1. Making the curve network **compatible by reparametrization**
2. Get **common degree** and **knot vector** of the curves in the two directions
3. Find the **intersection points** and their **parameters**
4. Create the **two skinned surfaces** with these parameters
5. Create the **tensor product surface** with these parameters
6. Create **common knot vector** for these three surfaces
7. Create B-spline **Gordon Surface** by *superposing the corresponding control points* of the three surfaces (this way B-spline surfaces are superposed)



# Results

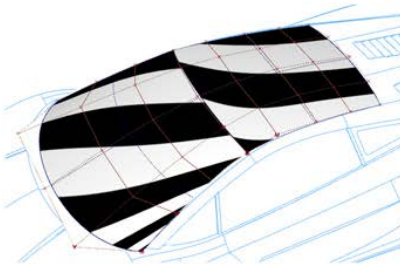


# Zebra Stripe Plot

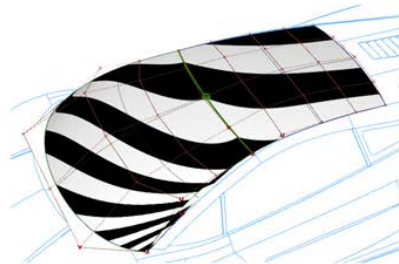
- Surface quality analysis with zebra stripe plot (in TiGL Viewer 3)



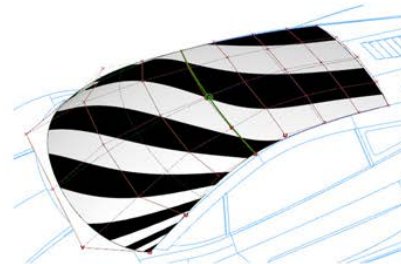
*Position : G0*  
When the zebra stripes are 'broken'



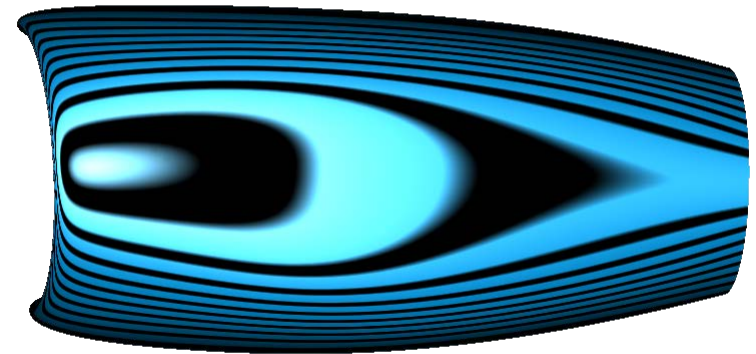
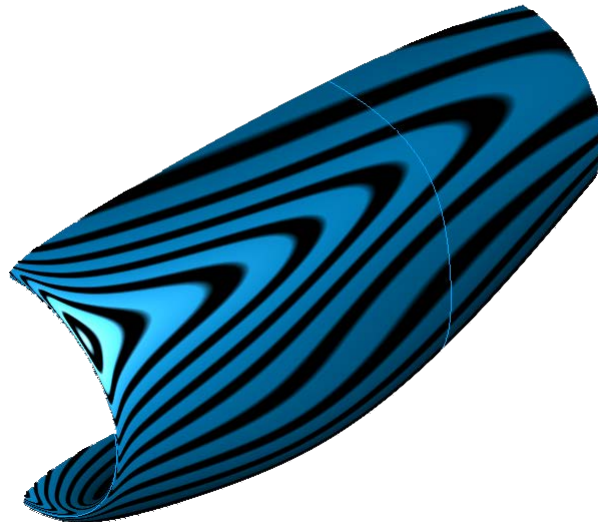
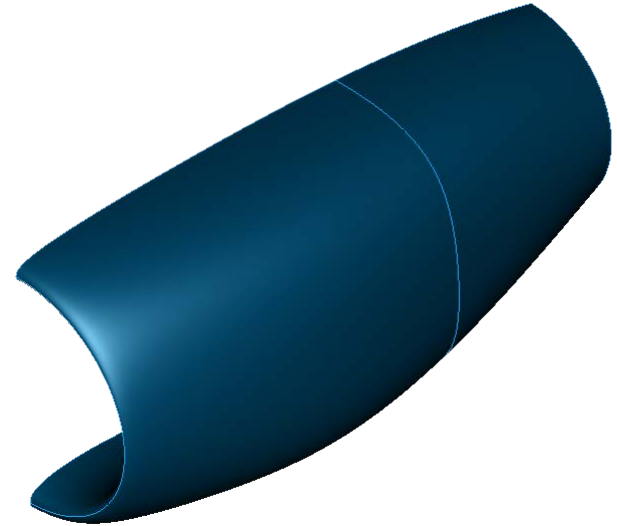
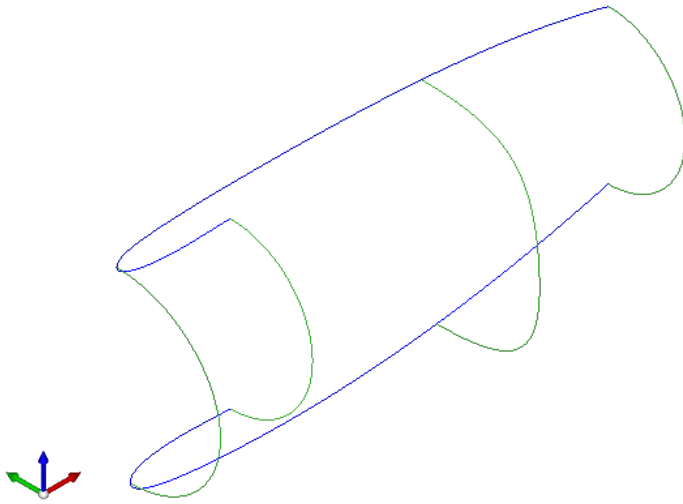
*Tangent : G1*  
When the zebra stripes are 'joined'



*Curvature : G2*  
When the zebra stripes are 'smooth'

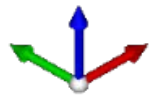
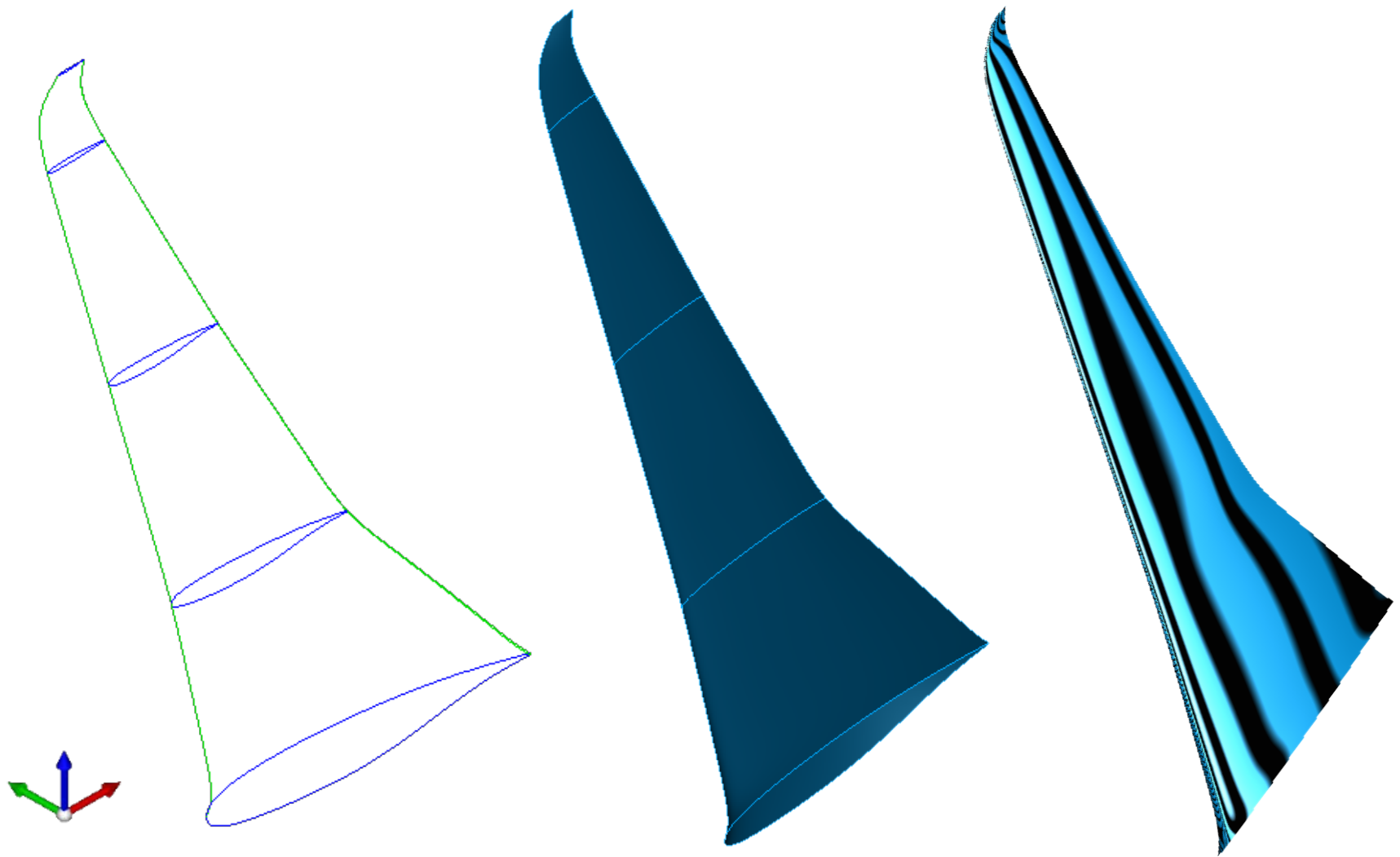


# Gordon Surfaces: Results for a Nacelle



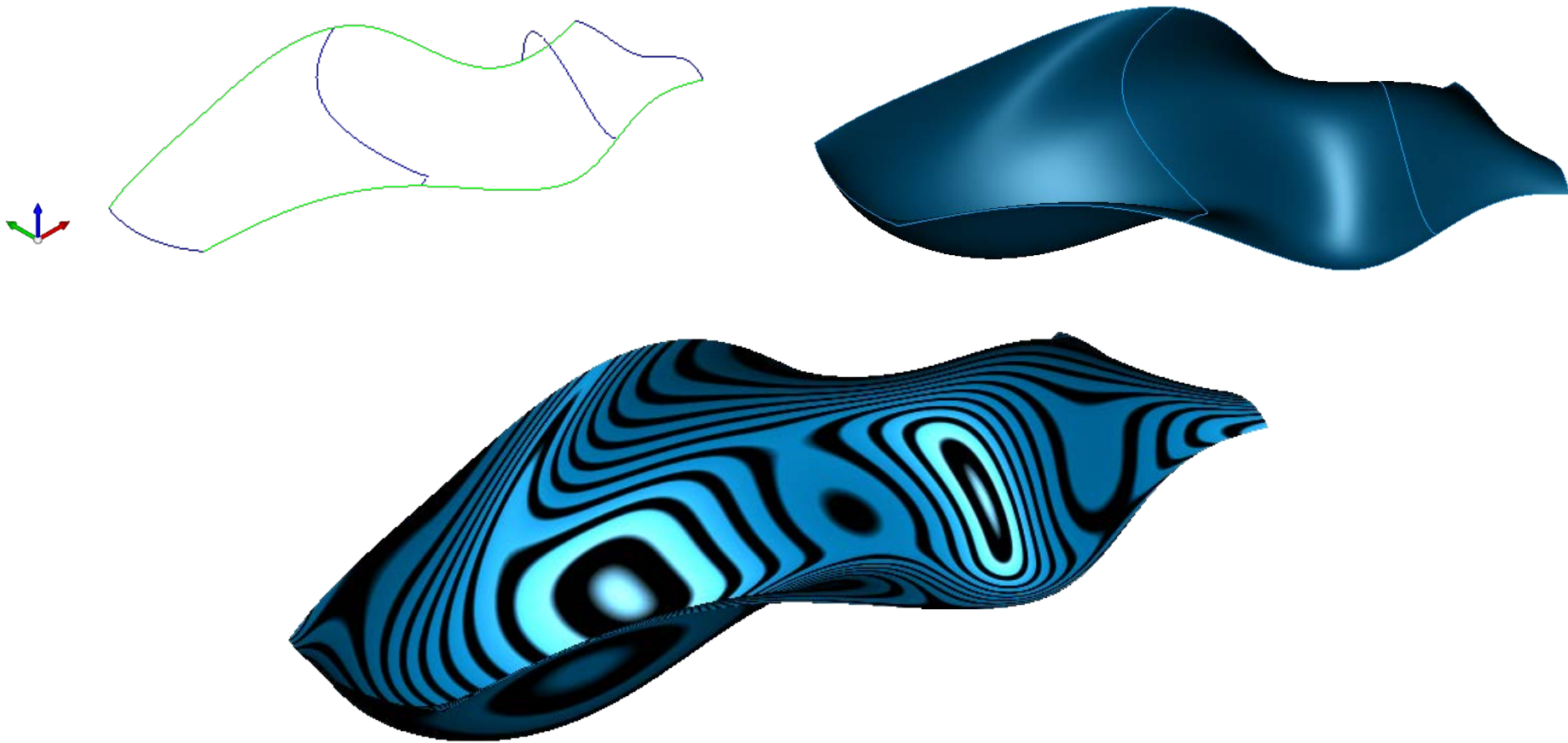


# Gordon Surfaces: Results for a Wing



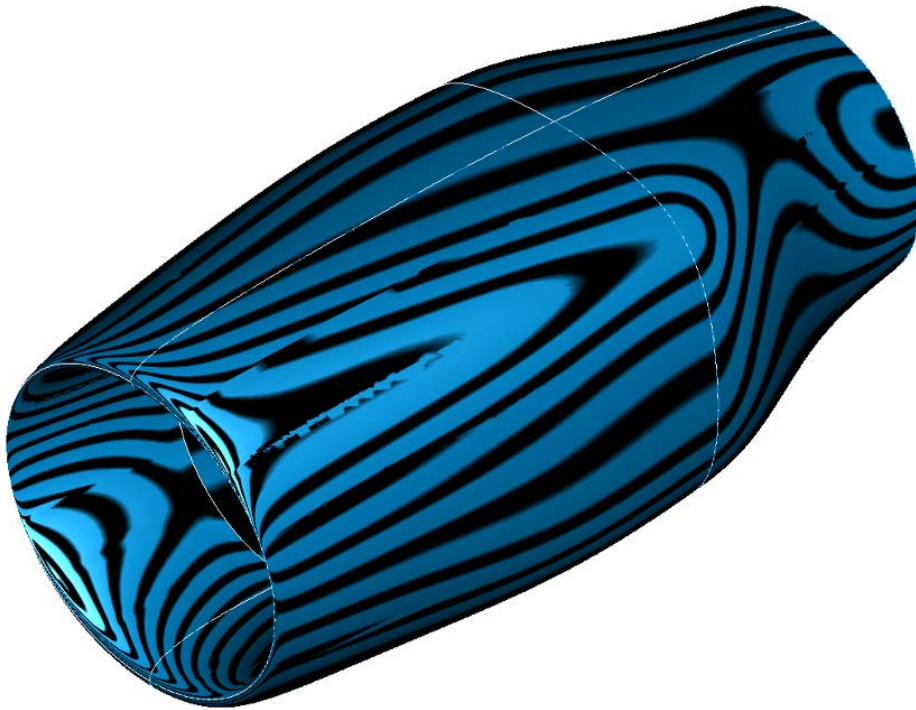


# Gordon Surfaces: Results for a General Surface



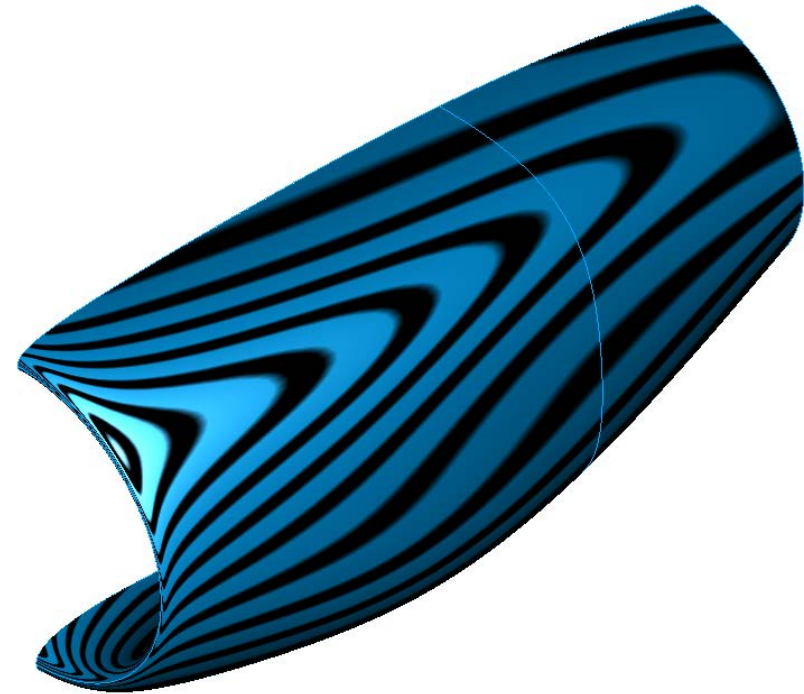
# Comparison of Coons and Gordon: Nacelle

## Coons Patches



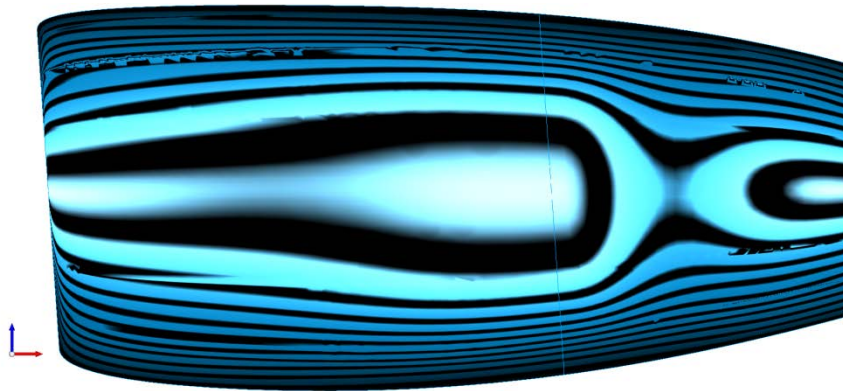
## Gordon Surface

(one half of the same nacelle)

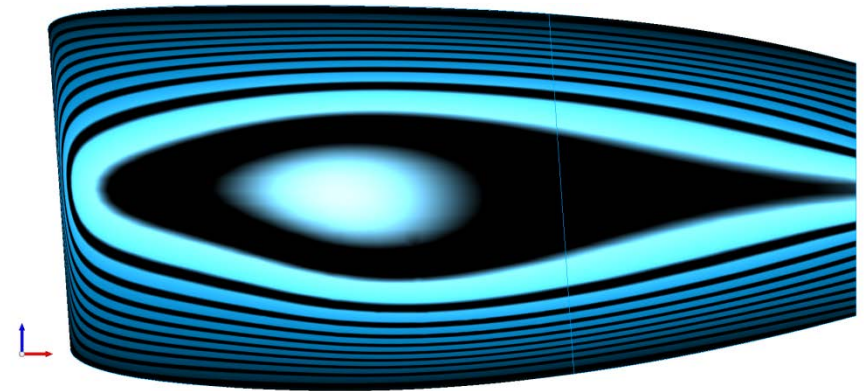


# Comparison of Coons and Gordon: Nacelle

**Coons Patches**



**Gordon Surface**

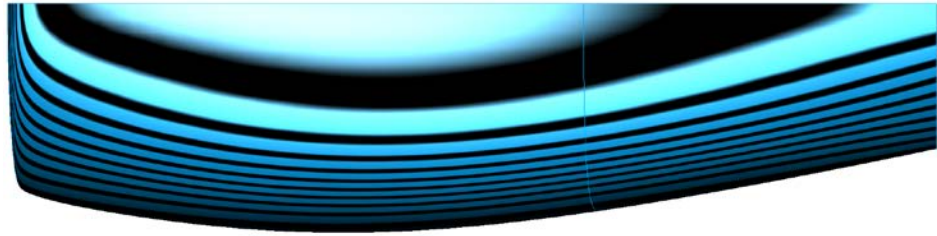
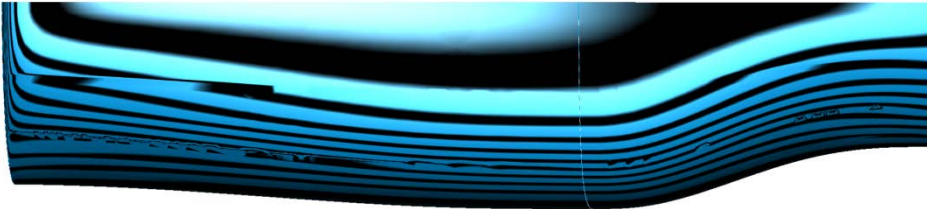




# Comparison of Coons and Gordon: Nacelle

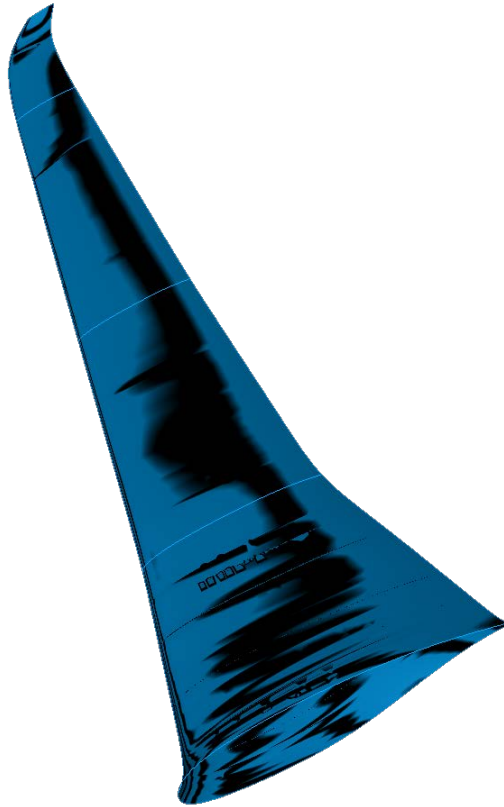
**Coons Patches**

**Gordon Surface**

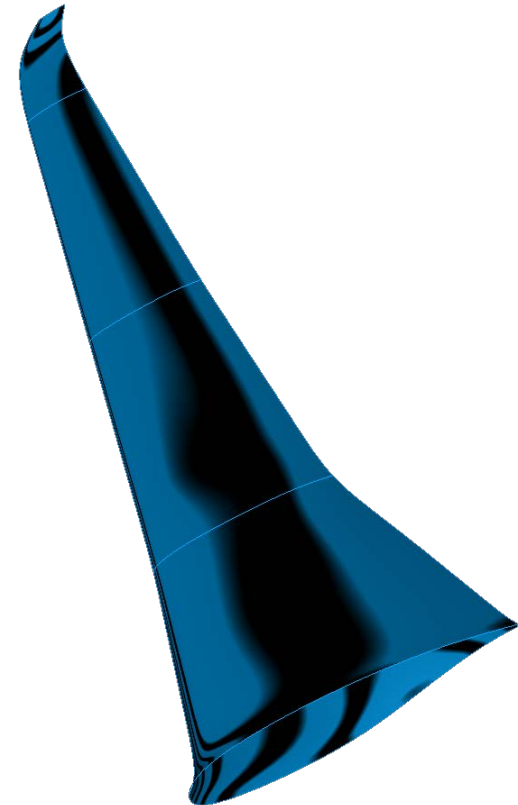


# Comparison of Coons and Gordon: Wing

**Coons Patches**

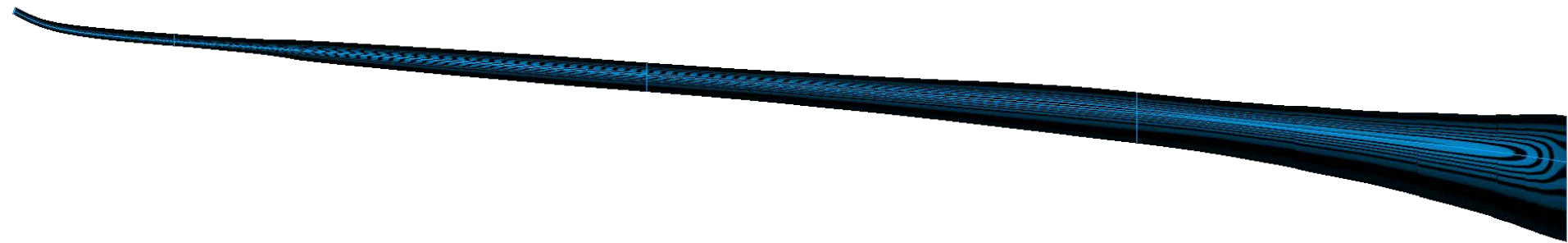


**Gordon Surface**



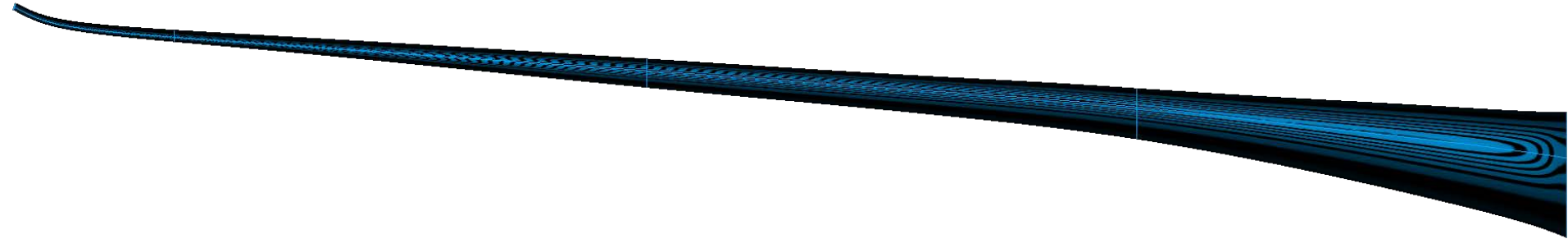
# Comparison of Coons and Gordon: Wing

## Coons Patches



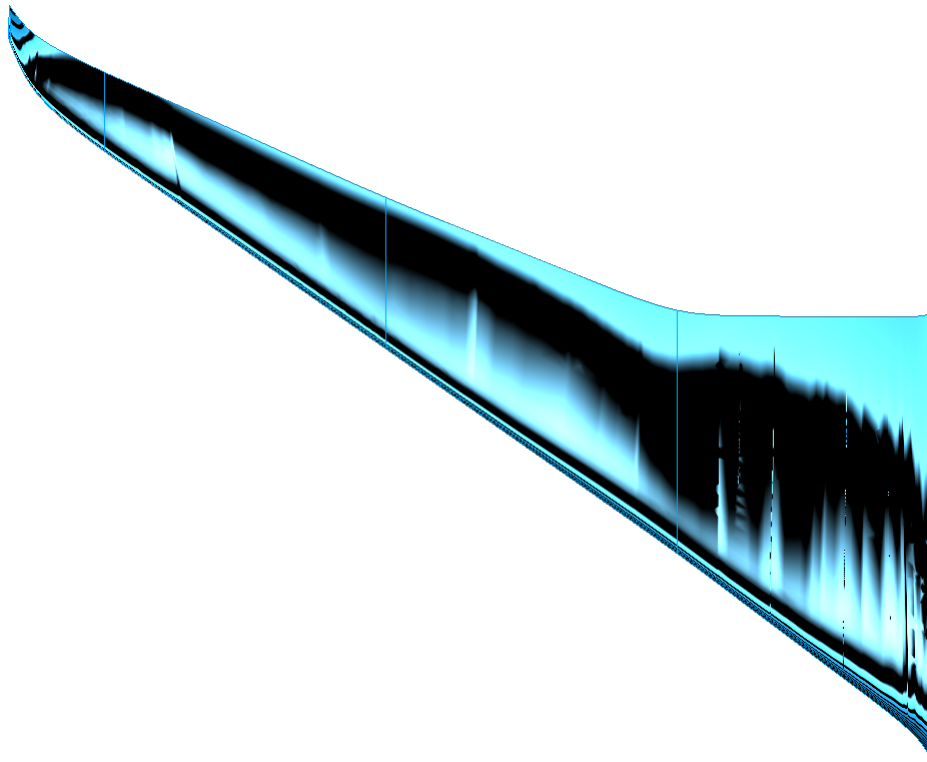
# Comparison of Coons and Gordon: Wing

## Gordon Surface

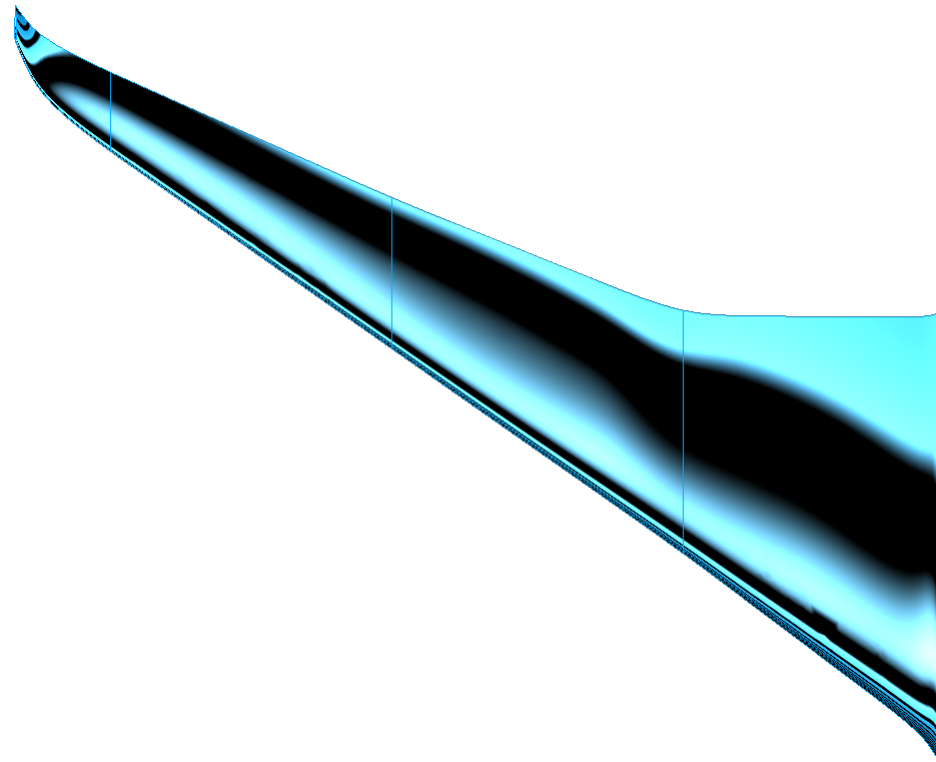


# Comparison of Coons and Gordon: Wing

**Coons Patches**



**Gordon Surface**

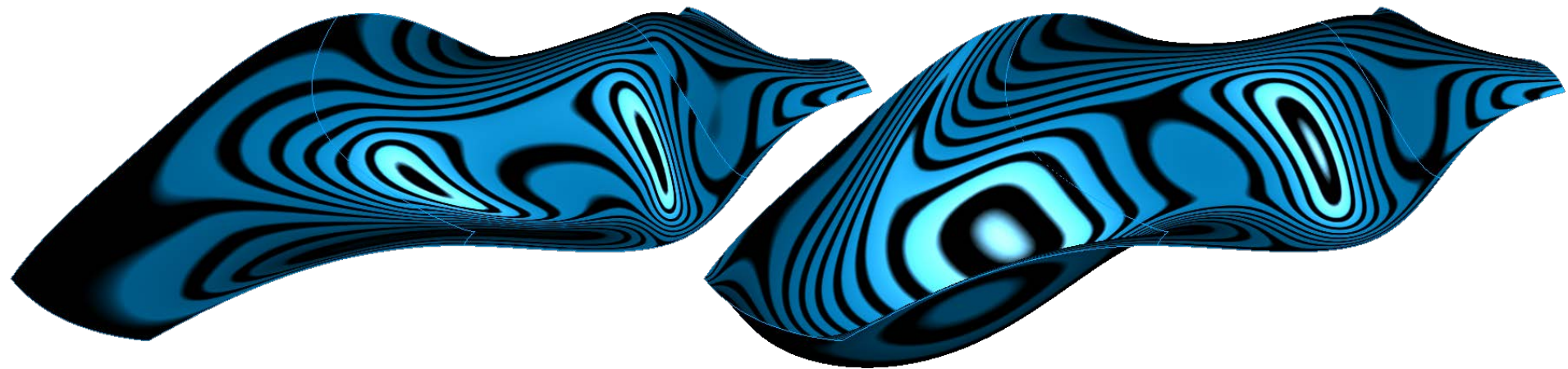




# Comparison of Coons and Gordon: General Surface

**Coons Patches**

**Gordon Surface**

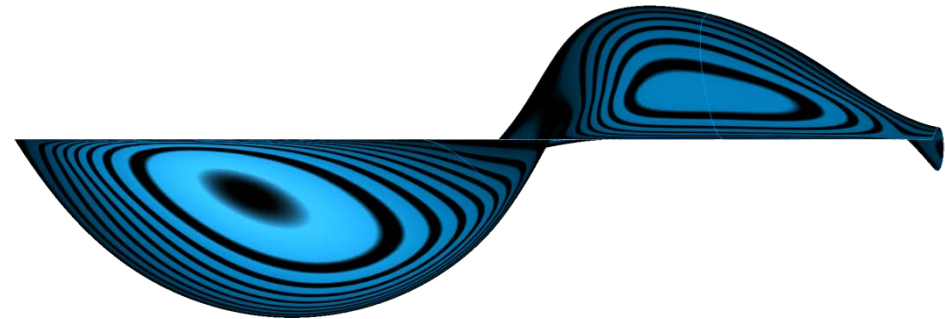


# Comparison of Coons and Gordon: General Surface

**Coons Patches**



**Gordon Surface**



# Summary

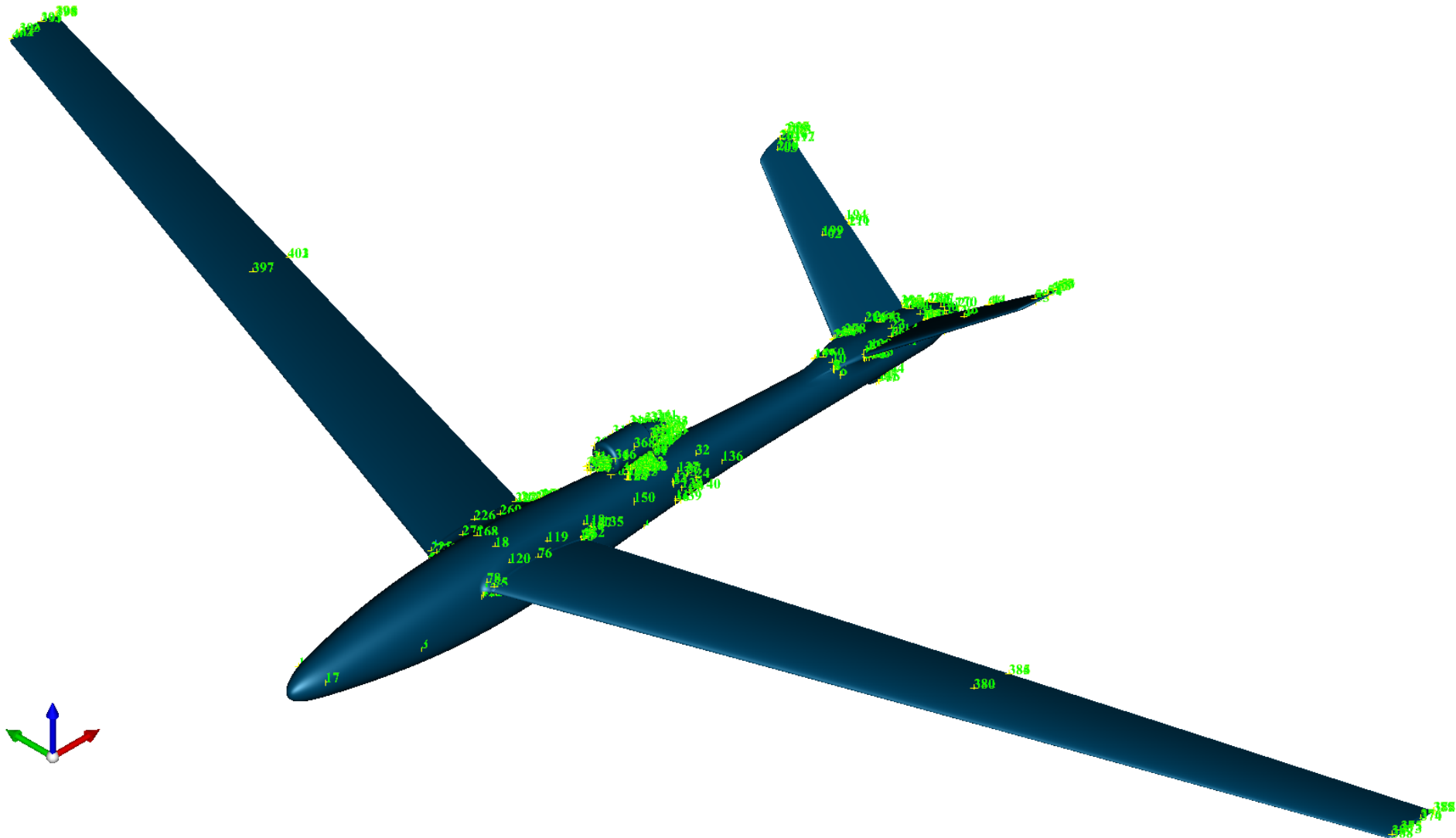


# Summary

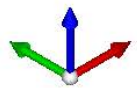
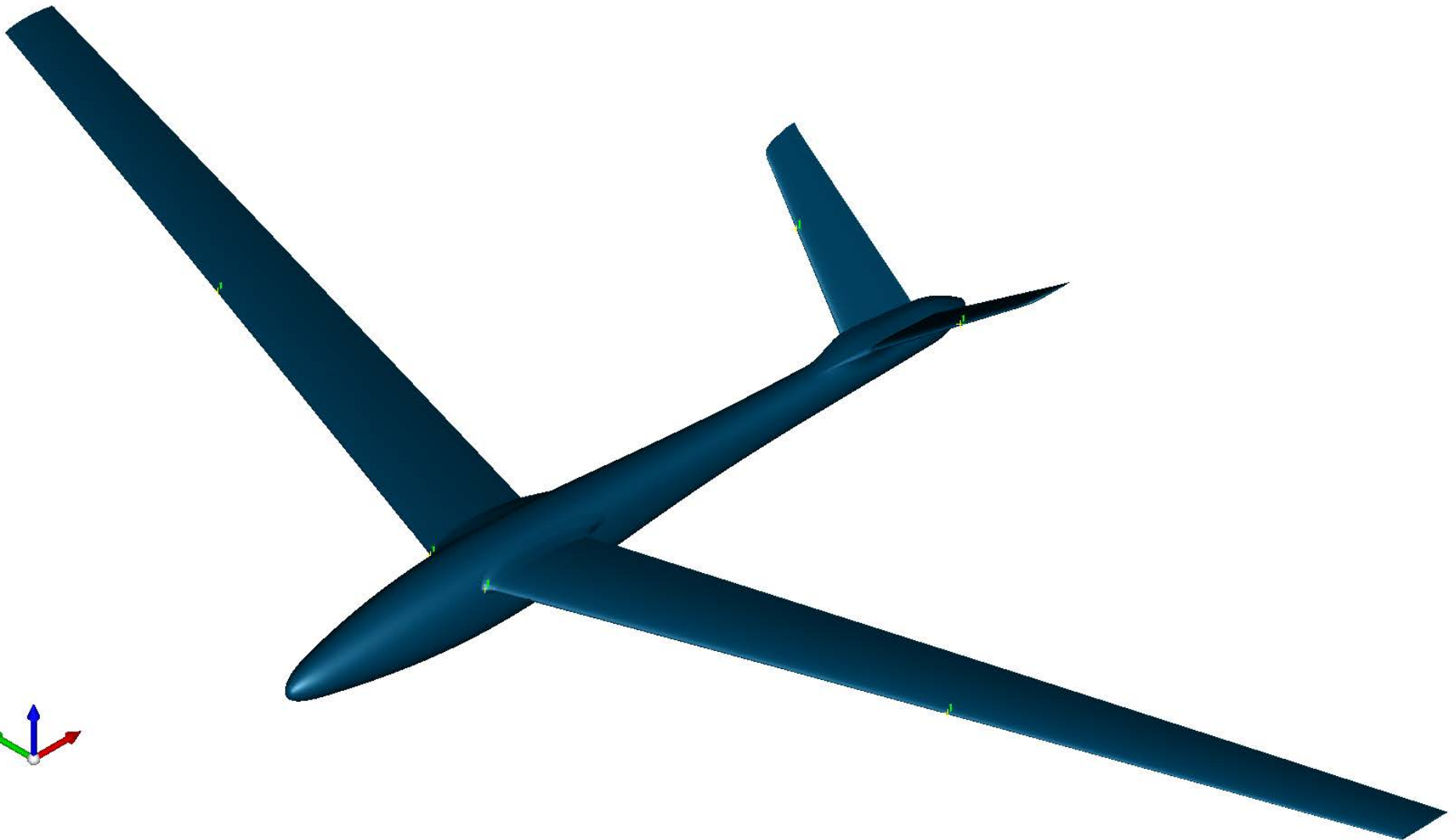
- Gordon Surface method was presented
- Curve reparametrization is crucial→ compatible curve network
- Results:
  - all the previous problems are eliminated now
  - but: because of global interpolation oscillations might occur
  - solution: different reparametrization



# My Current Work at SR-FLS

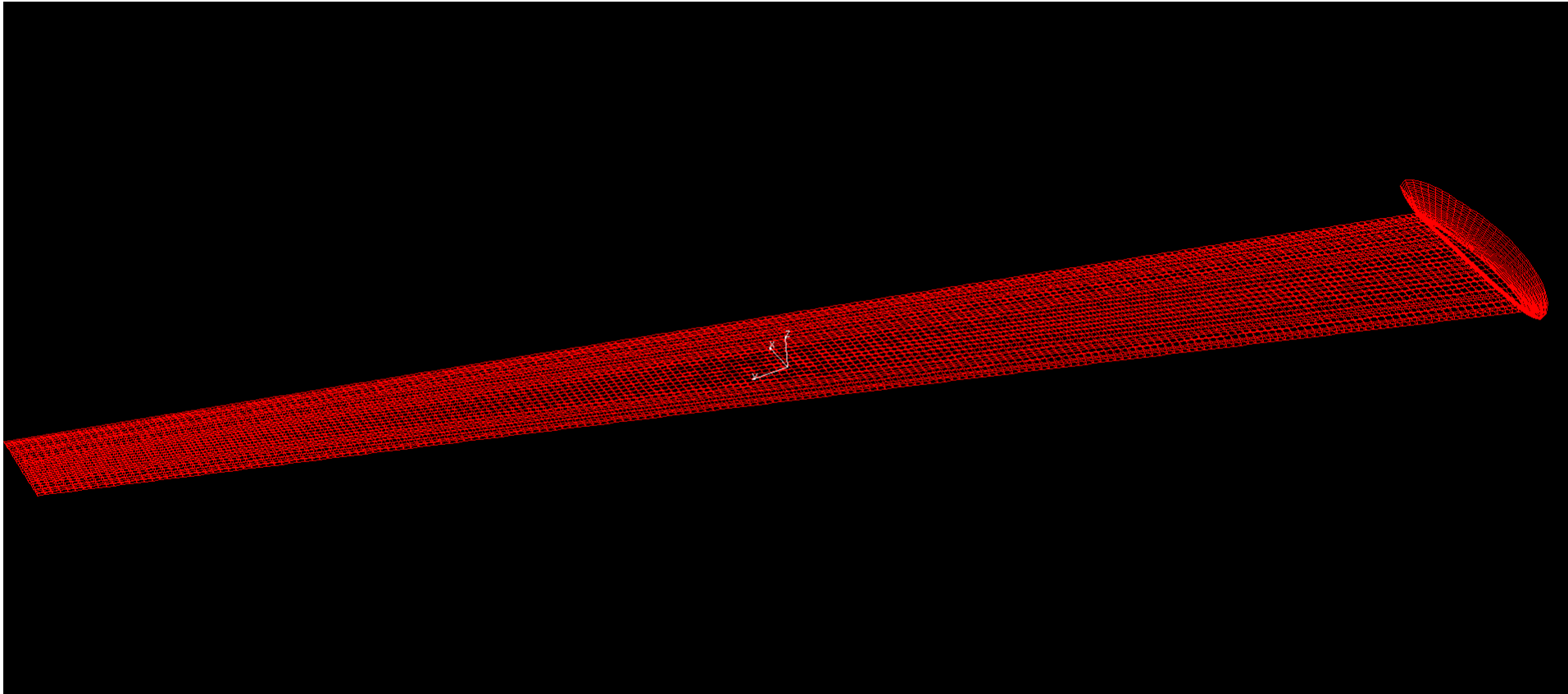


# My Current Work at SR-FLS

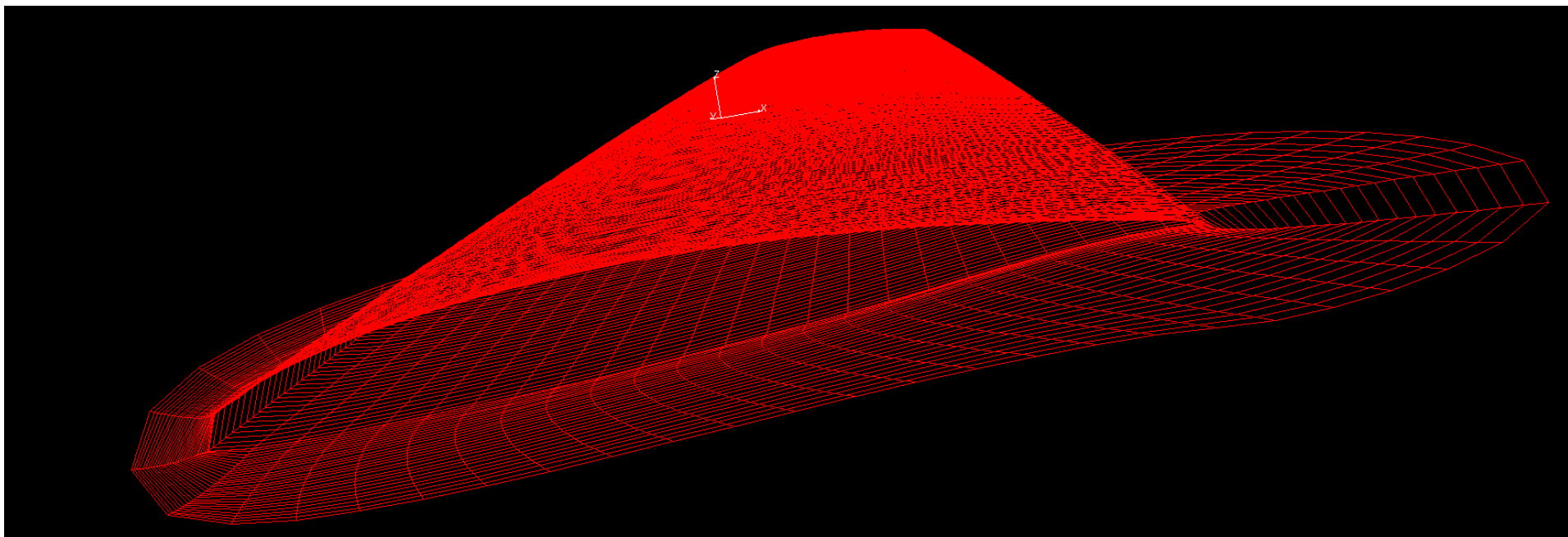




# My Current Work at SR-FLS



# My Current Work at SR-FLS





# References

- University of Cambridge, Department of Computer Science and Technology, <https://www.cl.cam.ac.uk/teaching/2000/AGraphHCI/SMEG/>
- Les Piegl and Wayne Tiller: **The NURBS book**, Springer Science & Business Media, 2012
- opencascade.com

Mathematical Theory of Gordon Surfaces:

- William J Gordon: **Spline-blended surface interpolation through curve networks**, Journal of Mathematics and Mechanics, pages 931–952, 1969.



**Thank you! 😊**



# Degree Elevation

- Problem: the B-spline curve or surface shall have a higher degree
- Knot vector before:

$$U = \{\underbrace{u_0, \dots, u_0}_{k \text{ times}}, \underbrace{u_1, \dots, u_1}_{m_1 \text{ times}}, \dots, \underbrace{u_s, \dots, u_s}_{m_s \text{ times}}, \underbrace{u_n, \dots, u_n}_{k \text{ times}}\}$$

- Knot vector afterwards:

$$\hat{U} = \{\underbrace{u_0, \dots, u_0}_{k+1 \text{ times}}, \underbrace{u_1, \dots, u_1}_{m_1+1 \text{ times}}, \dots, \underbrace{u_s, \dots, u_s}_{m_s+1 \text{ times}}, \underbrace{u_n, \dots, u_n}_{k+1 \text{ times}}\}$$

- The new control points are computed by evaluating the basis functions at certain  $\hat{n} + 1$  parameter values and solving:

$$\sum_{i=0}^{\hat{n}} B_i^{k+1}(u) Q_i = \sum_{i=0}^n B_i^k(u) P_i$$



# Knot Insertion

- Problem: insert knot  $\bar{u}$  in the knot vector after the knot with index  $l$
- New formula of the curve:

$$C(u) = \sum_{i=0}^{n+1} \bar{B}_i^k(u) Q_i$$

- The new control points  $Q_i$  are computed by:

$$Q_i = \alpha_i P_i + (1 - \alpha_i) P_{i-1}, \quad \text{where } \alpha_i = \begin{cases} 1, & i \leq l - k \\ \frac{\bar{u} - u_i}{u_{i+k} - u_i}, & l - k + 1 \leq i \leq l \\ 0, & i \geq l + 1 \end{cases}$$

- Knot insertion for B-spline surfaces analogue for both knot vectors  $U$  and  $V$

