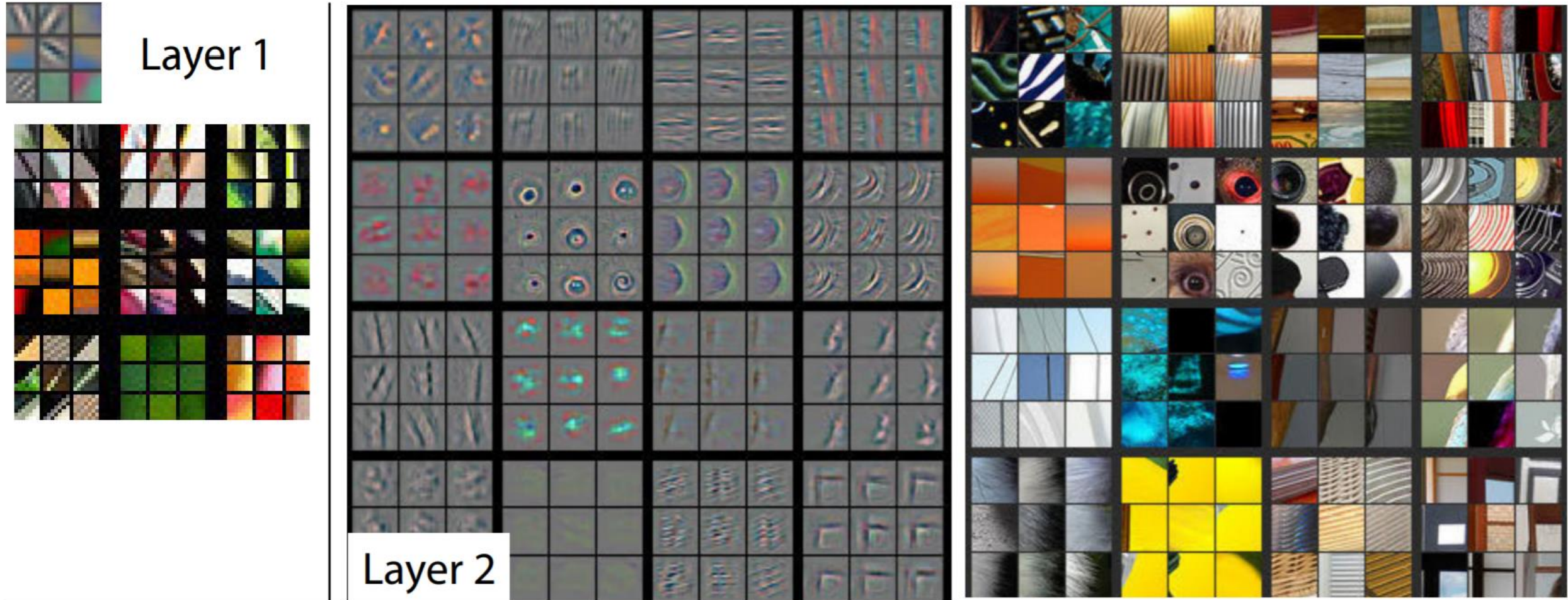


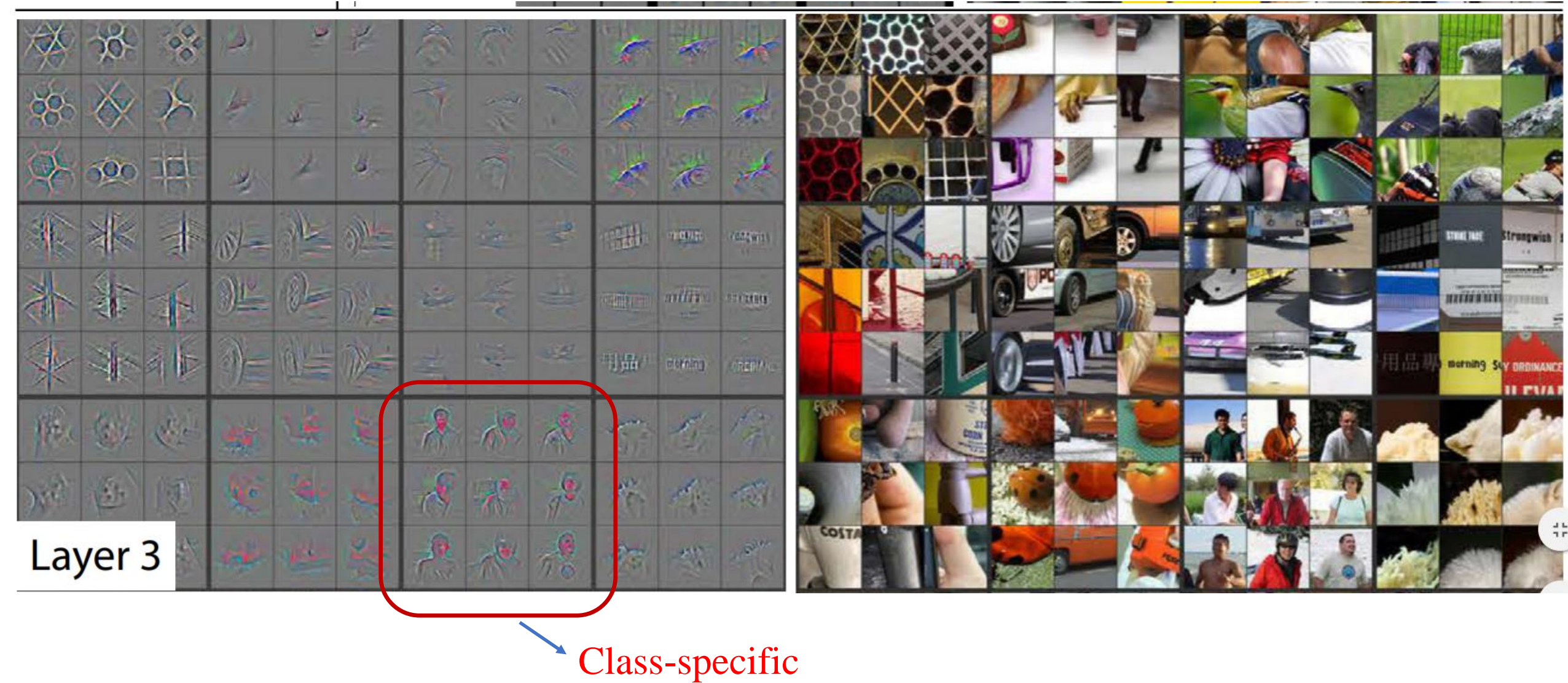
# Understanding the Convolutional Network

➤ What kind of feature does every layer learn?



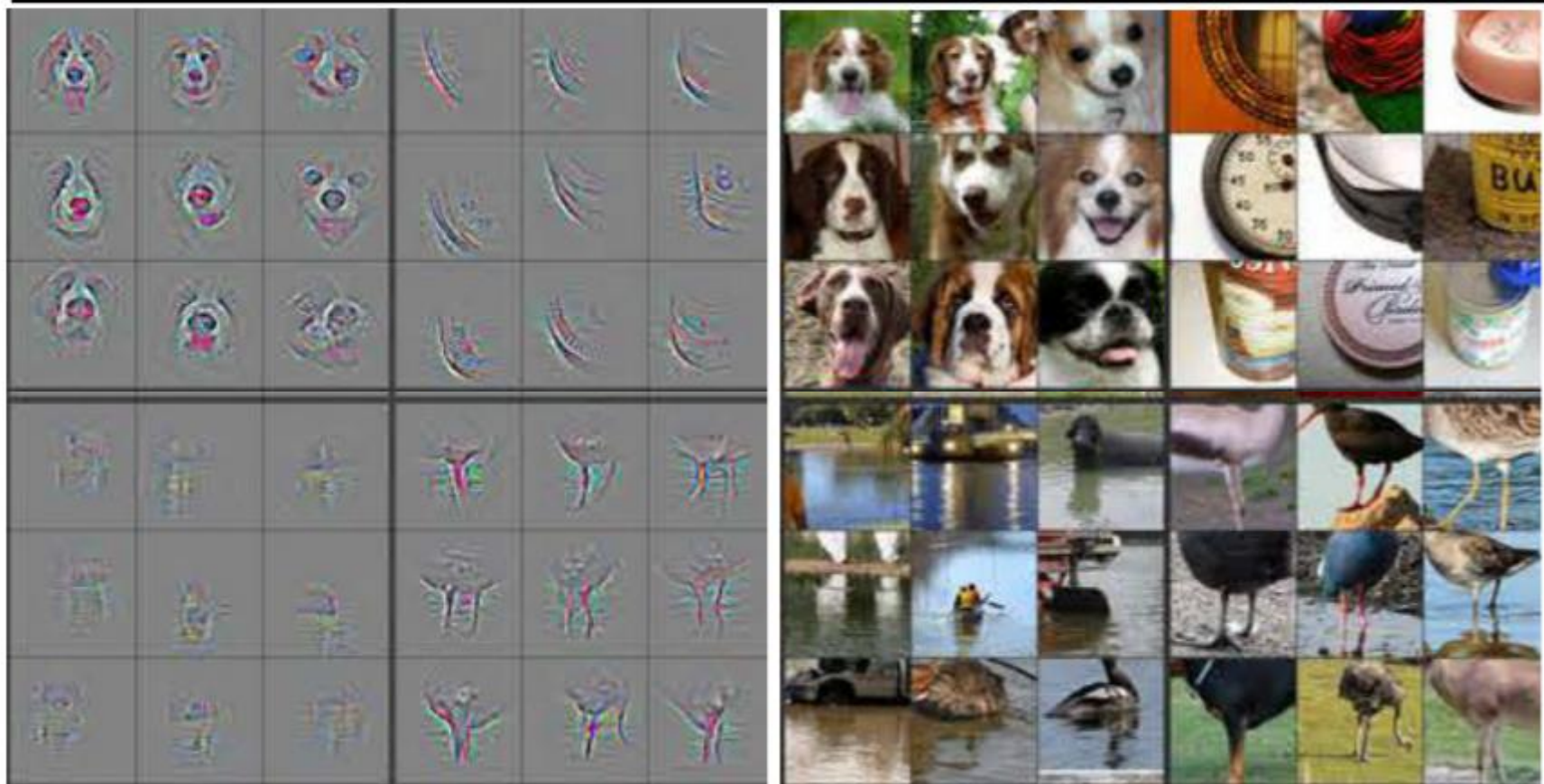


➤ What kind of feature does every layer learn?



# Understanding the Convolutional Network

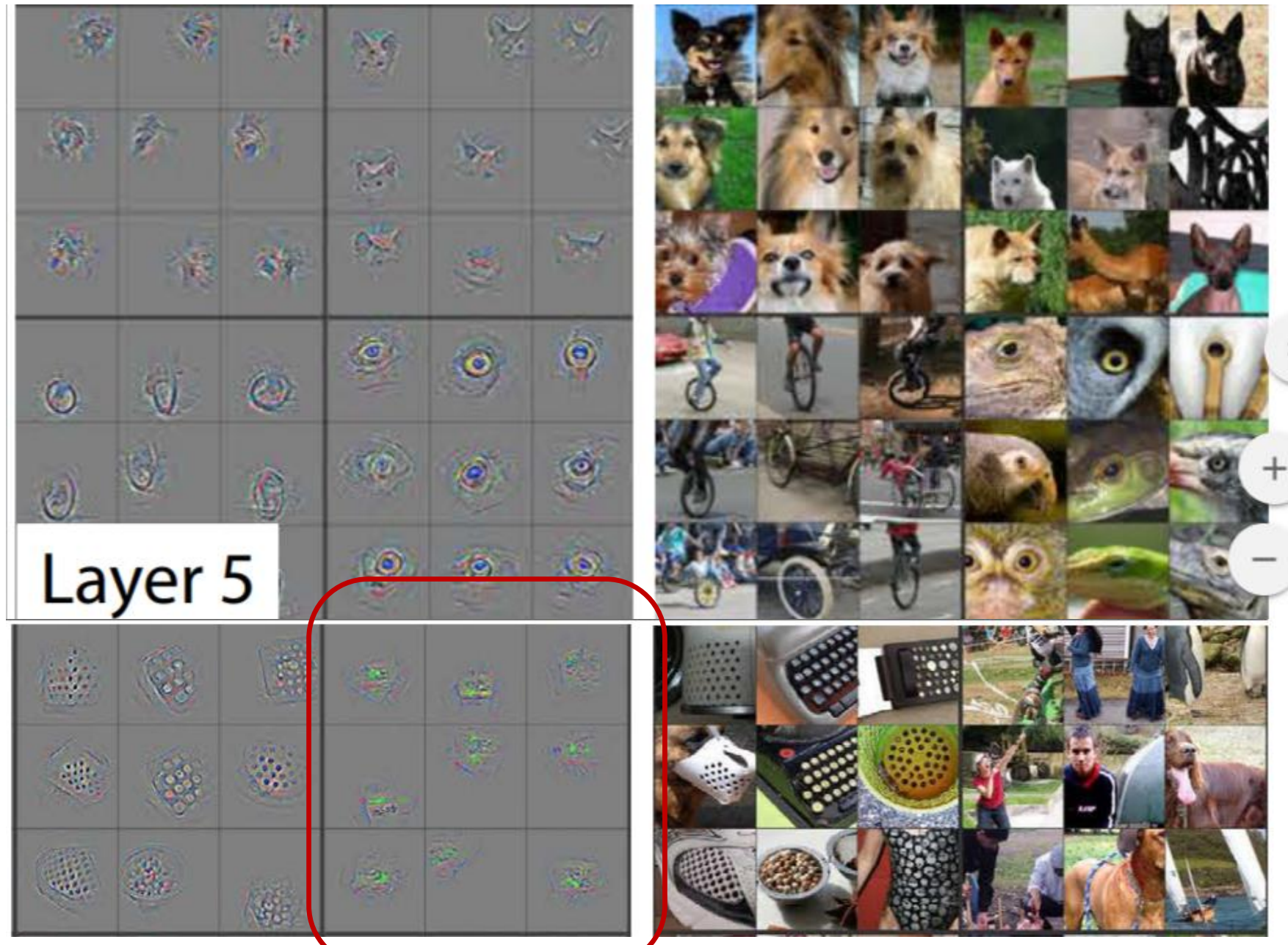
➤ What kind of feature does every layer learn?



Become more and more class-specific

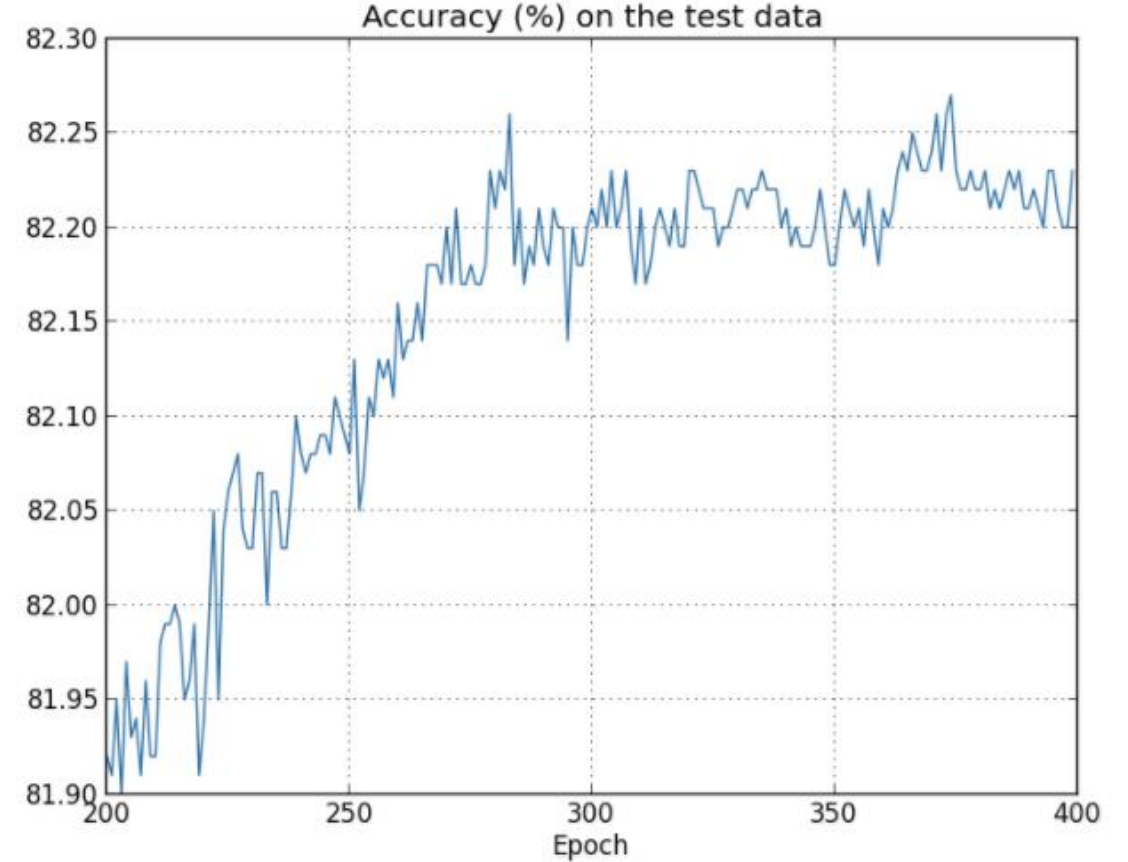
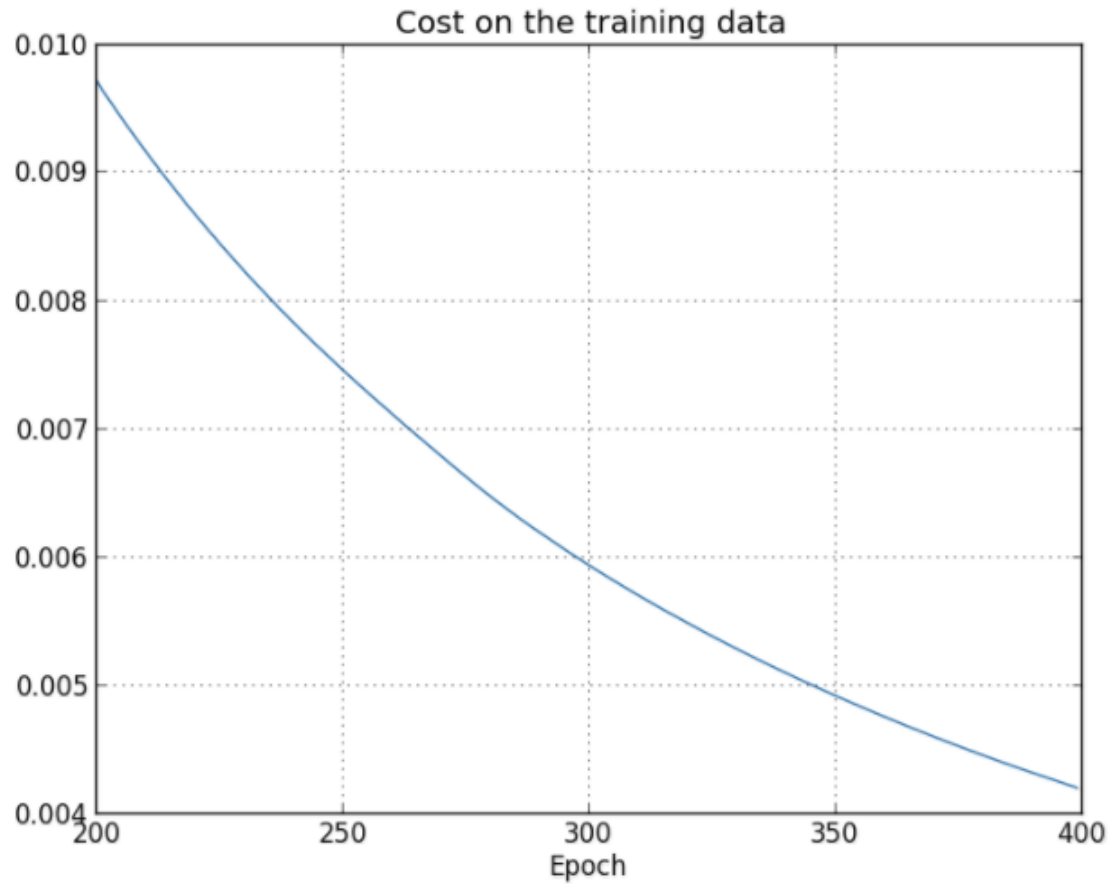


➤ What kind of feature does every layer learn?



Object of the same class with different pose variations

## ➤ How to decide that a network is overfitting?



The training loss keeps decreasing while the test accuracy stops improving or start to decrease

## ➤ How to prevent overfitting

- Early stop choose the right time to stop
- Increasing the size of training set Sometimes large dataset is not available

Data Augmentation<sup>[1]</sup>  $\left\{ \begin{array}{l} \text{noise, cropping, transformation (flipping, rotating)} \\ \text{Generative model (VAE or GAN)} \end{array} \right.$

- Regularization L2 regularization

$$C = -\frac{1}{n} \sum_{x_j} \left[ y_j \ln a_j^L + (1 - y_j) \ln(1 - a_j^L) \right] + \frac{\lambda}{2n} \sum_w w^2.$$

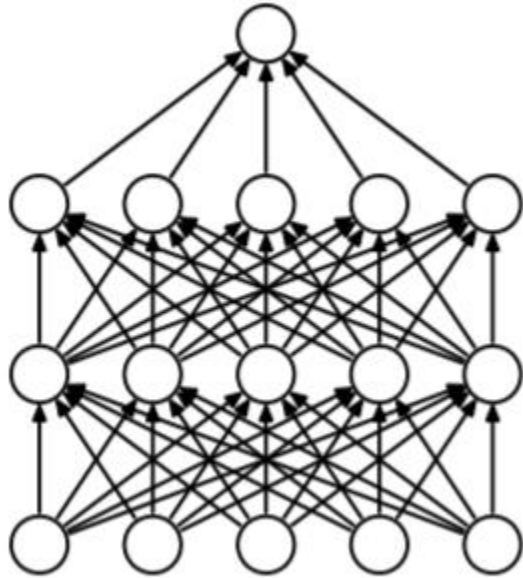
- Dropout<sup>[2]</sup>

[1] The Effectiveness of Data Augmentation in Image Classification using Deep Learning

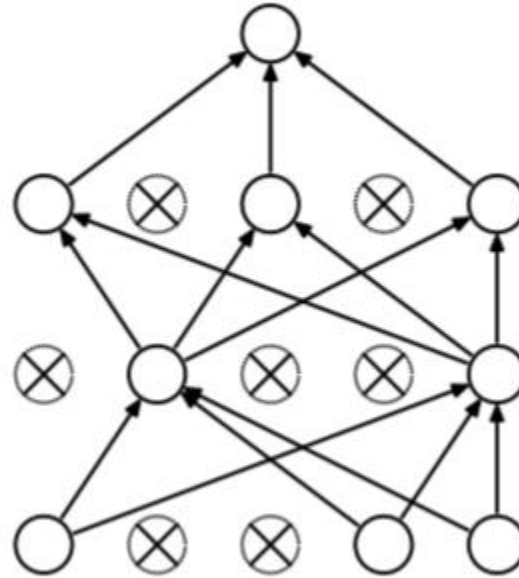
[2] Dropout: A Simple Way to Prevent Neural Networks from Overfitting

## ➤ How to prevent overfitting

- Dropout



(a) Standard Neural Net

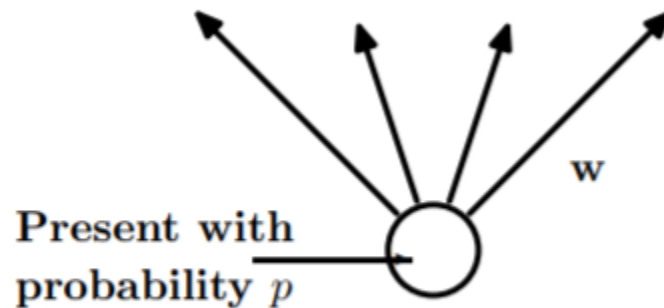


(b) After applying dropout.

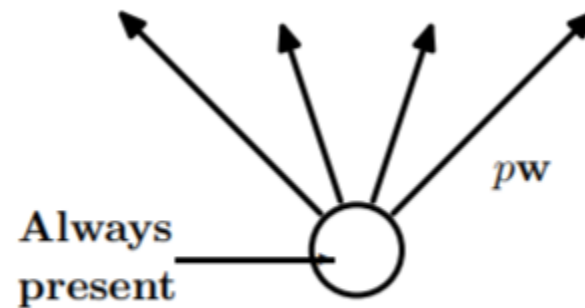
Inspiration: Combining smaller network together has better performance than one large network

A network with  $n$  neurons and  $p=0.5$ ,  
 $2^n$  possible thinned network

Generally  $p$  is set to 0.5, while for the input unit, the optimal  $p$  should be closer to 1.



(a) At training time



(b) At test time



## ➤ How to prevent overfitting

- Batch Normalization [3]

**Input:** Values of  $x$  over a mini-batch:  $\mathcal{B} = \{x_{1...m}\}$ ;

Parameters to be learned:  $\gamma, \beta$

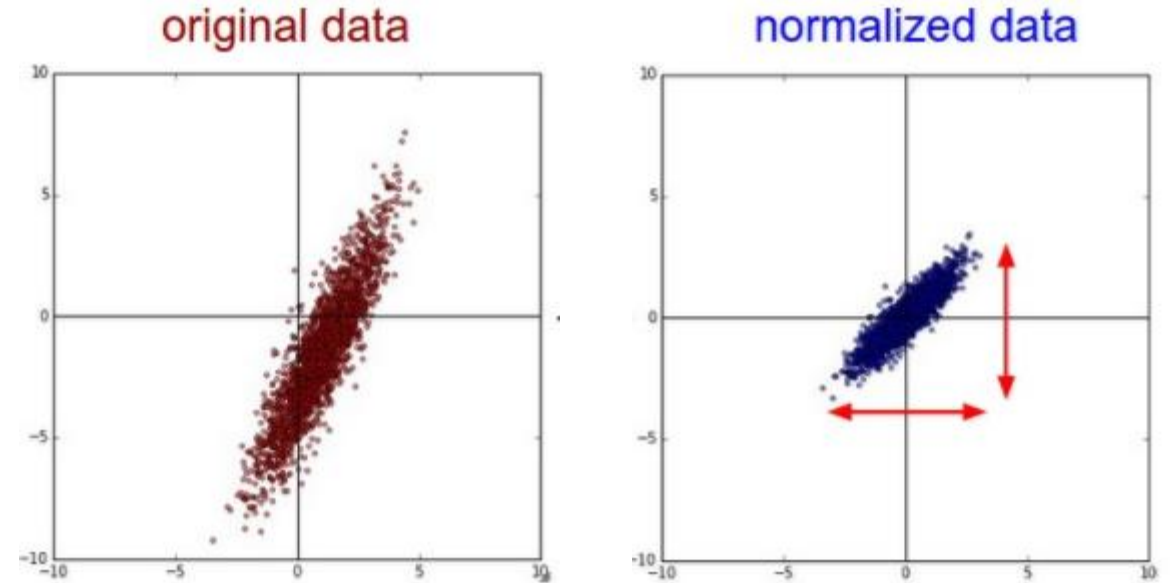
**Output:**  $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$

$$\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \quad // \text{ mini-batch mean}$$

$$\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2 \quad // \text{ mini-batch variance}$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \quad // \text{ normalize}$$

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i) \quad // \text{ scale and shift}$$



Normalization process is different during training and inference, need to specify in BN Layer.



Thank you !