

# SH1106

# 132 X 64 Dot Matrix OLED/PLED Segment/Common Driver with Controller

#### Preliminary

#### **Features**

- Support maximum 132 X 64 dot matrix panel
- Embedded 132 X 64 bits SRAM
- Operating voltage:
  - Logic voltage supply: VDD1 = 1.65V 3.5V
  - DC-DC voltage supply: VDD2 = 3.0V 4.2V
- OLED Operating voltage supply:
   External VPP supply = 6.4V 13.0V
   Internal VPP generator = 6.4V 9.0V
- Maximum segment output current: 200µA
- Maximum common sink current: 27mA
- 8-bit 6800-series parallel interface, 8-bit 8080-series parallel interface, 3-wire & 4-wire serial peripheral interface, 400KHz fast <sup>12</sup>C bus interface
- Programmable frame frequency and multiplexing ratio

- Row re-mapping and column re-mapping (ADC)
- Vertical scrolling
- On-chip oscillator
- Programmable Internal charge pump circuit output
- 256-step contrast control on monochrome passive OLED panel
- Low power consumption
  - Sleep mode: <5μA
    - VDD1=0V, VDD2=3.0V 4.2V: <5μA
    - VDD1,2=0V, VPP=3.0V 4.2V: <5μA
- Wide range of operating temperatures: -40 to +85°C
- Available in COG form, thickness: 300µm

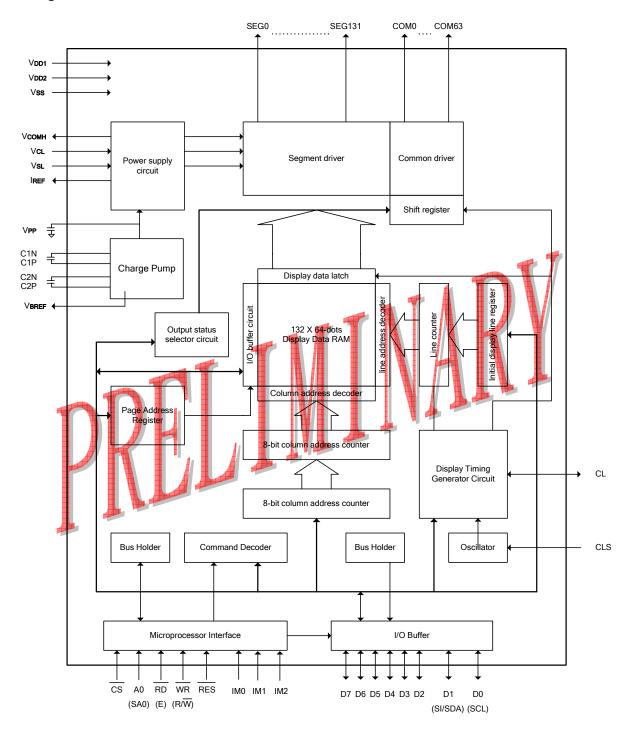
#### General Description

SH1106 is a single-chip CMOS OLED/PLED driver with controller for organic/polymer light emitting diode dot-matrix graphic display system. SH1106 consists of 132 segments, 64 commons that can support a maximum display resolution of 132 X 64. It is designed for Common Cathode type OLED panel.

SH1106 embeds with contrast control, display RAM oscillator and efficient DC-DC converter, which reduces the number of external components and power consumption. SH1106 is suitable for a wide range of compact portable applications, such as sub-display of mobile phone, calculator and MP3 player, etc.



# **Block Diagram**





# **Pad Description**

# **Power Supply**

Symbol	1/0	Description
VDD1	Supply	Power supply input: 1.65 - 3.5V
VDD2	Supply	3.0 – 4.2V power supply pad for Power supply for charge pump circuit.
V DD2	Supply	This pin can be disconnected or connect to VDD1 when VPP is supplied externally
Vss	Supply	Ground.
VsL	Cupply	This is a segment voltage reference pad.
VSL	Supply	This pad should be connected to Vss externally.
VCL	Supply	This is a common voltage reference pad.
VCL	Supply	This pad should be connected to Vss externally.

# **OLED Driver Supplies**

Symbol	I/O	Description
lref	0	This is a segment current reference pad. A resistor should be connected between this pad and Vss. Set the current at $10\mu A$ .
Vсомн	0	This is a pad for the voltage output high level for common signals.  A capacitor should be connected between this pad and Vss.
VBREF	NC	This is an internal voltage reference pad for booster circuit.  Keep floating.
VPP	P	OLED panel power supply. Generated by internal charge pump.  Connect to capacitor. It could be supplied externally.
C1N,	D	Connect to charge pump capacitor.
C1P		These pins are not used and should be disconnedted when Vpp is supplied externally.
C2P,	Р	Connect to charge pump capacitor.
C2N	17	These pins are not used and should be disconnedted when Vpp is supplied externally.



# **System Bus Connection Pads**

Symbol	1/0				Description	on										
		This pad	s pad is the system clock input. When internal clock is enabled, this pad should be to open. The internal clock is output from this pad. When internal oscillator is disabled, this pad													
CL	I/O	_	n. The internal	=	· ·		l oscillator is d	isabled, this pad								
					errial Glock Go	<u> </u>										
			This is the internal clock enable pad.  CLS = "H": Internal oscillator circuit is enabled.													
CLS	I		CLS = "L": Internal oscillator circuit is disabled (requires external input).													
					` .		• /	ormal operation.								
		These a	These are the MPU interface mode select pads.													
IMO		8080 I <sup>2</sup> C 6800 4-wire SPI 3-wire SPI														
IM1	- 1	IM0														
IM2		IM1														
		IM2	1	0	1	0	0									
<del>CS</del>		This pad	This pad is the chip select input. When $\overline{CS}$ = "L", then the chip select becomes active,													
CS	'	and data	and data/command I/O is enabled.													
DEO		This is a reset signal input pad. When RES is set to "L", the settings are initialized. The reset														
RES	'	operation is performed by the RES signal level.														
		400000000000000000000000000000000000000	This is the Data/Command control pad that determines whether the data bits are data or a													
		command.														
A0		A0 = "H": the inputs at D0 to D7 are treated as display data.  A0 = "L": the inputs at D0 to D7 are transferred to the command registers.														
							egisters. t address of OL	_ED driver.								
			MPU interface		o to aloui gall											
					is is active LO	W. This pad co	onnects to the	8080 MPU WR								
$\overline{WR}$		signal. Th	ne signals on the	e data bus are l	atched at the ris	sing edge of the	WR signal.									
(R/W)	'				: This is the rea	d/write control s	signal input term	inal.								
			/W = "H": Rea													
			$\sqrt{W} = \text{``L''}: Write MPU interface}$													
					OLL it is active I	OW This pad	is connected t	o the RD signal								
_		of the 808	inected to an 8 80 series MPU	and the data	bus is in an ou	LOVV. This pad Itput status wh	en this signal i	s "L".								
RD (E)	- 1	When cor	nected to a 68	300 series MPI			s used as an e									
(E)		· —	e 6800 series													
			) = "H": Enable													
			) = "L": Disable		that connects	to an 8 hit or	16 hit etandara	d MPU data bus.								
D0 - D7	I/O															
(SCL)	1/0						set to high imp	d (SCL) and D1 bedance								
(SI/SDA)	I/O		_		-		ock input pad									
,						me, D2 to D7		` ,								



# **OLED Drive Pads**

Symbol	I/O	Description
COM0,2, - 60, 62	0	These pads are even Common signal output for OLED display.
COM1,3 - 61,63	0	These pads are odd Common signal output for OLED display.
SEG0 - 131	0	These pads are Segment signal output for OLED display.

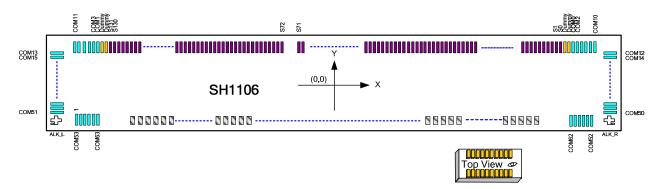
# **Test Pads**

Symbol	I/O	Description					
TEST1-3 I Test pad, internal pull low, no connection for user.							
Dummy	-	These pads are not used. Keep floating.					

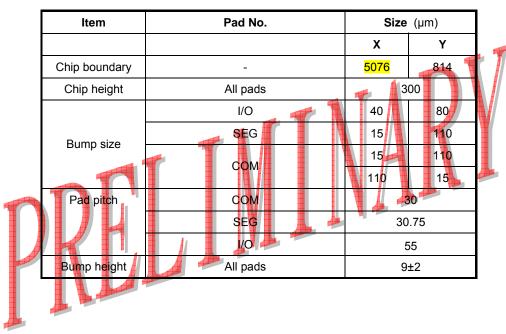




# **Pad Configuration**

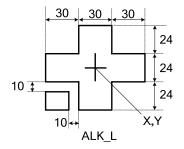


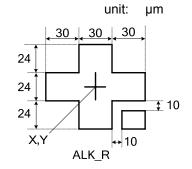
# **Chip Outline Dimensions**



# **Alignment Mark Location**

NO	Х	Υ
ALK_L	-2470	-348
ALK_R	2470	-348







Pad L	ocation (	Total: 2	266 pad	ls)										un	nit: µr
Pad No.	Designation	Х	Υ	Pad No.	Designation	Х	Υ	Pad No.	Designation	Х	Υ	Pad No.	Designation	Х	Υ
1	COM53	-2287.62	-329	69	VCOMH	1721.81	-299.95	137	SEG30	1122.38	329	205	SEG98	-1030.12	329
2	COM55	-2257.62	-329	70	VCOMH	1776.81	-299.95	138	SEG31	1091.63	329	206	SEG99	-1060.87	329
3 4	COM57 COM59	-2227.62 -2197.62	-329 -329	71 72	VPP VPP	1831.81 1886.81	-299.95 -299.95	139 140	SEG32 SEG33	1060.88 1030.13	329 329	207	SEG100 SEG101	-1091.62 -1122.37	329 329
5	COM61	-2167.62	-329	73	COM62	2137.62	-329	141	SEG34	999.38	329	209	SEG101	-1153.12	329
6	COM63	-2137.62	-329	74	COM60	2167.62	-329	142	SEG35	968.63	329	210	SEG103	-1183.87	329
7	C21N	-1688.19	-299.95	75	COM58	2197.62	-329	143	SEG36	937.88	329	211	SEG104	-1214.62	329
8 9	C21N C21N	-1633.19 -1578.19	-299.95 -299.95	76 77	COM56 COM54	2227.62 2257.62	-329 -329	144 145	SEG37 SEG38	907.13 876.38	329 329	212 213	SEG105 SEG106	-1245.37 -1276.12	329 329
10	C21N	-1523.19	-299.95	78	COM52	2287.62	-329	146	SEG39	845.63	329	214	SEG107	-1306.87	329
11	C21P	-1468.19	-299.95	79	COM50	2460	-285	147	SEG40	814.88	329	215	SEG108	-1337.62	329
12 13	C21P C21P	-1413.19 -1358.19	-299.95 -299.95	80 81	COM48 COM46	2460 2460	-255 -225	148 149	SEG41 SEG42	784.13 753.38	329 329	216 217	SEG109 SEG110	-1368.37 -1399.12	329 329
14	C21P	-1303.19	-299.95	82	COM44	2460	-225 -195	150	SEG42 SEG43	722.63	329	217	SEG111	-1429.87	329
15	C22P	-1248.19	-299.95	83	COM42	2460	-165	151	SEG44	691.88	329	219	SEG112	-1460.62	329
16	C22P	-1193.19	-299.95	84	COM40	2460	-135	152	SEG45	661.13	329	220	SEG113	-1491.37	329
17 18	C22P C22P	-1138.19 -1083.19	-299.95 -299.95	85 86	COM38 COM36	2460 2460	-105 -75	153 154	SEG46 SEG47	630.38 599.63	329 329	221	SEG114 SEG115	-1522.12 -1552.87	329 329
19	C22N	-1028.19	-299.95	87	COM34	2460	-45	155	SEG48	568.88	329	223	SEG116	-1583.62	329
20	C22N	-973.19	-299.95	88	COM32	2460	-15	156	SEG49	538.13	329	224	SEG117	-1614.37	329
21	C22N	-918.19	-299.95	89	COM30	2460	15	157	SEG50	507.38	329	225	SEG118	-1645.12	329
22	C22N VDD2	-863.19 -808.19	-299.95 -299.95	90 91	COM28 COM26	2460 2460	45 75	158 159	SEG51 SEG52	476.63 445.88	329 329	226 227	SEG119 SEG120	-1675,87 -17 <b>0</b> 6.62	329 329
24	VDD2	-753.19	-299.95	92	COM24	2460	105	160	SEG53	415.13	329	228	SEG121	-1737.37	329
25	VDD2	-698.19	-299.95	93	COM22	2460	135	161	SEG54	384.38	329	229	SEG122	-1768.12	329
26 27	VDD2 VBREF	-643.19 -588.19	-299.95 -299.95	94 95	COM20 COM18	2460 2460	165 195	162 163	SEG55 SEG56	353.63	329 329	23 <mark>0</mark> 231	SEG123 SEG124	-1798.87 -1829.62	329 329
28	VPP	-533.19	-299.95	96	COM16	2460	225	164	SEG57	292.13	329	232	SEG125	1860.37	329
29	VPP	-478.19	-299.95	97	COM14	2460	255	165	SEG58	<b>2</b> 61.38	3 <b>2</b> 9	233	SEG126	1891.12	329
30	VCOMH	-423.19	-299.95	98	COM12	2460	285	166	SEG59	<b>23</b> 0.63	329	234	SEG127	1921.87	329
31 32	VCOMH VSS(REF)	-368.19 -313.19	-299.95 -299.95	99 100	COM10	2287.62 2257.62	329 329	167 168	SEG60 SEG61	199.88 169.13	329 329	23 <mark>5</mark>	SEG128 SEG129	-1952.62 -1983.37	329 329
33	VSS	-258.19	-299.95	101	COM6	2227.62	329	169	SEG62	138.38	329	237	SEG130	-2014.12	329
34	VSS	-203.19	-299.95	102	COM4	2197.62	329	170	SEG63	107 <mark>.63</mark>	329	238	SEG131	-2044.87	329
35	VSS VCL	-148.19	-299.95	103	COM2	2167.62	329 329	171	SEG64	76.88	329 329	239	DUMMY	-2075.62	329
36 37	VCL	-93.19 -38.19	-299.9 <b>5</b> -299.9 <b>5</b>	104	COM0 DUMMY	2137.62 2105.63	329	172 173	SEG65 SEG66	46.13 15.38	329	240 241	DUMMY COM1	-2105.62 -2137.62	329 329
38	VSL	16.81	-299.95	106	DUMMY	2075.63	329	174	SEG67	-15.37	329	242	COM3	-2167.62	329
39	VSL	71.81	-299.95	107	SEG0	2044.88	329	175	SEG68	-46.12	329	243	COM5	-2197.62	329
40	TEST1 TEST2	126,81 181.81	-299.95 -299.95	108	SEG1	2014.13 1983.38	329	176 177	SEG69 SEG70	-76.87 -107.62	329 329	244 245	COM7 COM9	-2227.62 -2257.62	329 329
42	TEST3	236.81	-299.95	110	SEG3	1952.63	329	178	SEG70	-138.37	329	246	COM11	-2287.62	329
43	CL	291.81	-299.95	111	SEG4	1921.88	329	179	SEG72	-230.62	329	247	COM13	-2460	285
44	CLS	346.81	-299.95	112	SEG5	1891.13	329	180	SEG73	-261.37	329	248	COM15	-2460	255
45 46	VDD1 VDD1	401.81 <u>4</u>	-299.95 -299.95	113 114	SEG6 SEG7	1860.38 1829.63	329 329	181 182	SEG74 SEG75	-292.12 -322.87	329 329	249 250	COM17 COM19	-2460 -2460	225 195
47	IM1	511.81	-299.95	115	SEG8	1798.88	329	183	SEG76	-353.62	329	251	COM21	-2460	165
48	VSS	566.81	-299.95	116	SEG9	1768.13	329	184	SEG77	-384.37	329	252	COM23	-2460	135
49	IM2	621.81	-299.95 -299.95	117 118	SEG10	1737.38	329	185	SEG78	-415.12	329	253 254	COM25 COM27	-2460 -2460	105
50 51	VDD1 IM0	676.81 731.81	-299.95	119	SEG11 SEG12	1706.63 1675.88	329 329	186 187	SEG79 SEG80	-445.87 -476.62	329 329	255	COM27	-2460	75 45
52	VSS	786.81	-299.95	120	SEG13	1645.13	329	188	SEG81	-507.37	329	256	COM31	-2460	15
53	CSB	841.81	-299.95	121	SEG14	1614.38	329	189	SEG82	-538.12	329	257	COM33	-2460	-15
54 55	RESB A0	896.81 951.81	-299.95 -299.95	122 123	SEG15 SEG16	1583.63 1552.88	329 329	190 191	SEG83 SEG84	-568.87 -599.62	329 329	258 259	COM35 COM37	-2460 -2460	-45 -75
56	VSS	1006.81	-299.95	123	SEG17	1522.13	329	191	SEG85	-630.37	329	260	COM37	-2460	-75
57	WRB	1061.81	-299.95	125	SEG18	1491.38	329	193	SEG86	-661.12	329	261	COM41	-2460	-135
58	RDB	1116.81	-299.95	126	SEG19	1460.63	329	194	SEG87	-691.87	329	262	COM43	-2460	-165
59 60	D0 D1	1171.81 1226.81	-299.95 -299.95	127 128	SEG20 SEG21	1429.88 1399.13	329 329	195 196	SEG88 SEG89	-722.62 -753.37	329 329	263 264	COM45 COM47	-2460 -2460	-195 -225
61	D2	1281.81	-299.95	129	SEG22	1368.38	329	197	SEG90	-784.12	329	265	COM49	-2460	-255
62	D3	1336.81	-299.95	130	SEG23	1337.63	329	198	SEG91	-814.87	329	266	COM51	-2460	-285
63	D4	1391.81	-299.95	131	SEG24	1306.88	329	199	SEG92	-845.62	329		1		
64 65	D5 D6	1446.81 1501.81	-299.95 -299.95	132	SEG25 SEG26	1276.13 1245.38	329 329	200	SEG93 SEG94	-876.37 -907.12	329 329				
66	D7	1556.81	-299.95	134	SEG27	1214.63	329	202	SEG95	-937.87	329				
67	VSS	1611.81	-299.95	135	SEG28	1183.88	329	203	SEG96	-968.62	329				
68	IREF	1666.81	-299.95	136	SEG29	1153.13	329	204	SEG97	-999.37	329				



#### **Functional Description**

#### **Microprocessor Interface Selection**

The 8080-Parallel Interface, 6800-Parallel Interface, Serial Interface (SPI) or  $I^2C$  Interface can be selected by different selections of IM0~2 as shown in Table 1.

Table. 1

	C	Config Data signal								Control signal						
Interface	IM0	IM1	IM1 IM2 D7 D6 D5 D4 D3 D2						D1	D0	E/RD	WR	CS	A0	RES	
6800	0	0	1	D7	D6	D5	D4	D3	D2	D1	D0	Е	$R/\overline{W}$	cs	A0	RES
8080	0	1	1	D7	7 D6 D5 D4 D3 D2					D1	D0	RD	WR	cs	A0	RES
4-Wire SPI	0	0	0			Pull	Low			SI	SCL	Pull Low			A0	RES
3-Wire SPI	1	0	0		Pull Low						SCL	Pull Low				RES
I <sup>2</sup> C	0	1	0			Pull	Low			SDA	SCL		Pull Lov	V	SA0	RES

#### 6800-series Parallel Interface

The parallel interface consists of 8 bi-directional data pads (D7-D0),  $\overline{WR}$  (R/ $\overline{W}$ ),  $\overline{RD}$  (E), A0 and  $\overline{CS}$ . When  $\overline{WR}$  (R/ $\overline{W}$ ) = "H", read operation from the display RAM or the status register occurs. When  $\overline{WR}$  (R/ $\overline{W}$ ) = "L", Write operation to display data RAM or internal command registers occurs, depending on the status of A0 input. The  $\overline{RD}$  (E) input serves as data latch signal (clock) when it is "H", provided that  $\overline{CS}$  = "L" as shown in Table, 2.

Table, 2

IMO	IM1	IM2	Туре	CS	<b>A</b> 0	RD	WR	D0 to D7
0	0	1	6800 microprocessor bus	CS	<b>A</b> 0	E	R/W	D0 to D7

In order to match the operating frequency of display RAM with that of the microprocessor, some pipeline processing are internally performed, which require the insertion of a dummy read before the first actual display data read. This is shown in Figure. 1 below.

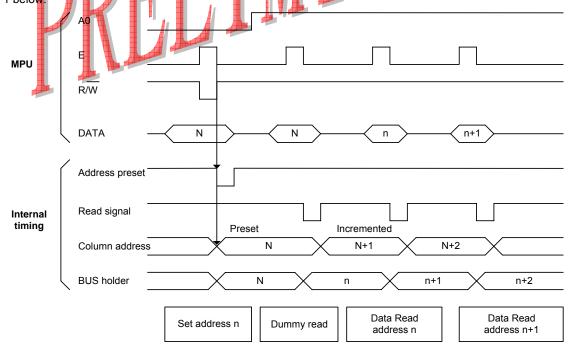


Figure. 1

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#### 8080-series Parallel Interface

The parallel interface consists of 8 bi-directional data pads (D7-D0),  $\overline{WR}$  ( $\overline{R/W}$ ),  $\overline{RD}$  (E), A0 and  $\overline{CS}$ . The  $\overline{RD}$  (E) input serves as data read latch signal (clock) when it is "L" provided that  $\overline{CS}$  = "L". Display data or status register read is controlled by A0 signal. The  $\overline{WR}$  ( $\overline{R/W}$ ) input serves as data write latch signal (clock) when it is "L" and provided that  $\overline{CS}$  = "L". Display data or command register write is controlled by A0 as shown in Table. 3.

Table. 3

IM	IM1	IM2	Туре	Type CS		RD	WR	D0 to D7
0	1	1	8080 microprocessor bus	CS	A0	RD	WR	D0 to D7

Similar to 6800-series interface, a dummy read is also required before the first actual display data read.

#### **Data Bus Signals**

The SH1106 identifies the data bus signal according to A0,  $\overline{\text{RD}}$  (E) and  $\overline{\text{WR}}$  ( $\overline{\text{R}/\overline{\text{W}}}$ ) signals.

Table. 4

Common	6800 processor	8080 pro	cessor	Function
A0	(R/W)	RD	WR	T Palcilo
1	1	0	1	Reads display data.
1	0	1	0	Writes display data.
0	1	0	1	Reads status.
0	0	1	0	Writes control data in internal register. (Command)
í	PK			



#### 4 Wire Serial Interface (4-wire SPI)

The serial interface consists of serial clock SCL, serial data SI, A0 and  $\overline{CS}$ . SI is shifted into an 8-bit shift register on every rising edge of SCL in the order of D7, D6, ... and D0. A0 is sampled on every eighth clock and the data byte in the shift register is written to the display data RAM (A0=1) or command register (A0=0) in the same clock. See Figure. 2.

Table. 5

IM	0 IM1	IM2	Туре	CS	A0	RD	$\overline{WR}$	D0	D1	D2 to D7
0	0	0	4-wire SPI	Pull Low	A0	ı	ı	SCL	SI	(HZ)

Note: "-" and Hz pin Must always be HIGH or LOW.

CS signal could always pull low in SPI-bus application.

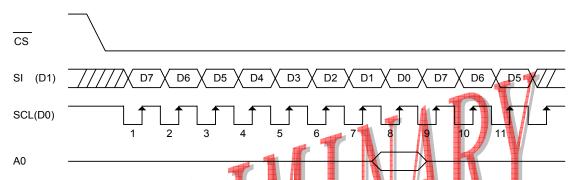


Figure. 2 4-wire SPI data transfer

- When the chip is not active, the shift registers and the counter are reset to their initial statuses.
- Read is not possible while in serial interface mode.
- Caution is required on the SCL signal when it comes to line-end reflections and external noise. We recommend the operation be rechecked on the actual equipment.



#### 3 Wire Serial Interface (3-wire SPI)

The 3 wire serial interface consists of serial clock SCL, serial data SI, and  $\overline{CS}$ . SI is shifted into an 9-bit shift register on every rising edge of SCL in the order of  $D/\overline{C}$ , D7, D6, ... and D0. The  $D/\overline{C}$  bit (first of the 9 bit) will determine the transferred data is written to the display data RAM ( $D/\overline{C}$  =1) or command register ( $D/\overline{C}$  =0).

Table. 6

IMO	IM1	IM2	Туре	CS	A0	RD	WR	D0	D1	D2 to D7
1	0	0	3-wire SPI	Pull Low	Pull Low	-	-	SCL	SI	(HZ)

Note: "-" and Hz pin Must always be HIGH or LOW.

CS signal could always pull low in SPI-bus application.

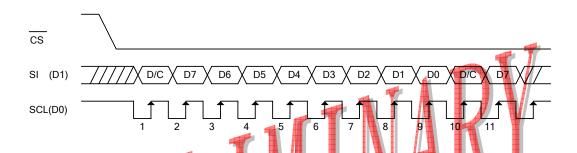


Figure. 2A -wire SPI data transfer

- When the chip is not active, the shift registers and the counter are reset to their initial statuses.
- Read is not possible while in serial interface mode.
- Caution is required on the SCL signal when it comes to line-end reflections and external noise. We recommend the operation be rechecked on the actual equipment.

#### I<sup>2</sup>C-bus Interface

The SH1106 can transfer data via a standard I<sup>2</sup>C-bus and has slave mode only in communication. The command or RAM data can be written into the chip and the status and RAM data can be read out of the chip.

IMO	IM1	IM2	Туре	cs	A0	RD	WR	D0	D1	D2 to D7
0	1	0	I <sup>2</sup> C Interface	Pull Low	SA0	1	-	SCL	SDA	(HZ)

Note: "-" and Hz pin Must always be HIGH or LOW.

CS signal could always pull low in I<sup>2</sup>C-bus application.

#### Characteristics of the I<sup>2</sup>C-bus

The I<sup>2</sup>C-bus is for bi-directional, two-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor. Data transfer may be initiated only when the bus is not busy.

Note: The positive supply of pull-up resistor must equal to the value of VDD1.



#### **Bit Transfer**

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse as changes in the data line at this time will be interpreted as a control signal.

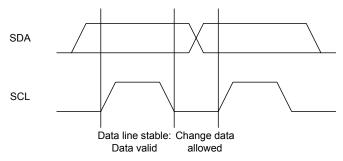


Figure. 3 Bit Transfer

#### Start and Stop conditions

Both data and clock lines remain HIGH when the bus is not busy. A HIGH-to-LOW transition of the data line, while the clock is HIGH is defined as the START condition (S). A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition (P).

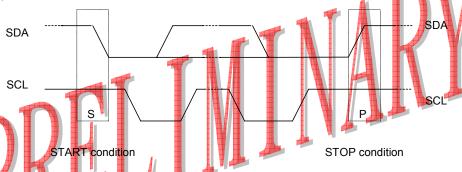


Figure. 4 Start and Stop conditions

# System configuration

- Transmitter: The device that sends the data to the bus.
- Receiver: The device that receives the data from the bus.
- Master: The device that initiates a transfer, generates clock signals and terminates a transfer.
- Slave: The device addressed by a master.
- Multi-Master: More than one master can attempt to control the bus at the same time without corrupting the message
- Arbitration: Procedure to ensure that, if more than one master simultaneously tries to control the bus, only one is allowed
  to do so and the message is not corrupted.
- Synchronization: Procedure to synchronize the clock signals of two or more devices.

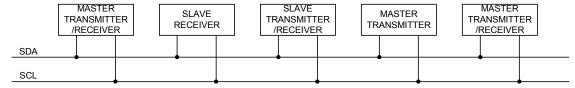
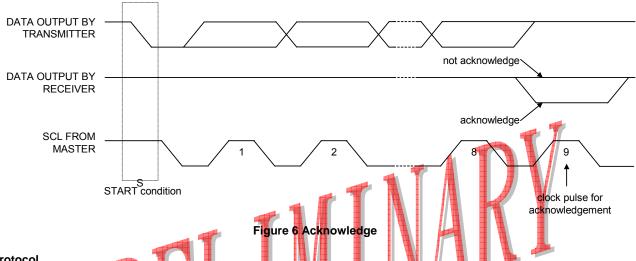


Figure. 5 System configuration



#### Acknowledge

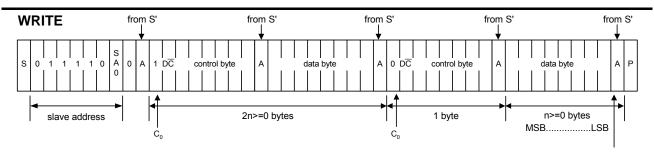
Each byte of eight bits is followed by an acknowledge bit. The acknowledge bit is a HIGH signal put on the bus by the transmitter during which time the master generates an extra acknowledge related clock pulse. A slave receiver which is addressed must generate an acknowledge after the reception of each byte. Also a master receiver must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges must pull-down the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse (set-up and hold times must be taken into consideration). A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event the transmitter must leave the data line HIGH to enable the master to generate a stop condition.

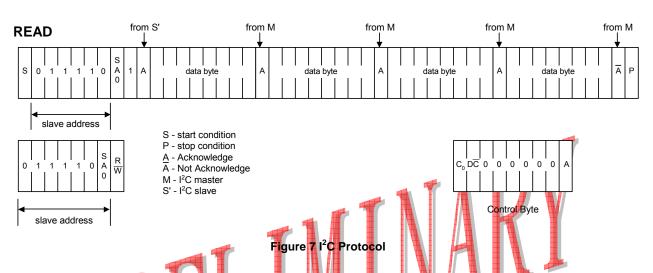


#### **Protocol**

The SH1106 supports both read and write access. The R/W bit is part of the slave address. Before any data is transmitted on the I<sup>2</sup>C-bus, the device that should respond is addressed first. Two 7-bit slave addresses (0111100 and 0111101) are reserved for the SH1106. The least significant bit of the slave address is set by connecting the input SA0 to either logic 0(VSS) or 1 (VDD1). The I<sup>2</sup>C-bus protocol is illustrated in Fig.7. The sequence is initiated with a START condition (S) from the I<sup>2</sup>C-bus master that is followed by the slave address. All slaves with the corresponding address acknowledge in parallel, all the others will ignore the I'C-bus transfer. After acknowledgement, one or more command words follow which define the status of the addressed slaves. A command word consists of a control byte, which defines Co and  $D/\overline{C}$  (note1), plus a data byte (see Fig.7). The last control byte is tagged with a cleared most significant bit, the continuation bit Co. After a control byte with a cleared Co-bit, only data bytes will follow. The state of the  $D/\overline{C}$  -bit defines whether the data-byte is interpreted as a command or as RAM-data. The control and data bytes are also acknowledged by all addressed slaves on the bus. After the last control byte, depending on the  $D/\overline{C}$  bit setting, either a series of display data bytes or command data bytes may follow. If the  $D/\overline{C}$  bit was set to '1', these display bytes are stored in the display RAM at the address specified by the data pointer. The data pointer is automatically updated and the data is directed to the intended SH1106 device. If the  $D/\overline{C}$  bit of the last control byte was set to '0', these command bytes will be decoded and the setting of the device will be changed according to the received commands. The acknowledgement after each byte is made only by the addressed slave. At the end of the transmission the I<sup>2</sup>C-bus master issues a stop condition (P). If the RIW bit is set to one in the slave-address, the chip will output data immediately after the slave-address according to the D/C bit, which was sent during the last write access. If no acknowledge is generated by the master after a byte, the driver stops transferring data to the master.







## Note1:

1. Co= "0" : The last control byte , only data bytes to follow,
Co= "1" : Next two bytes are a data byte and another control byte;

2.  $D/\overline{C} = "0"$ : The data byte is for command operation,

 $D/\overline{C} =$  "1" : The data byte is for RAM operation

## Access to Display Data RAM and Internal Registers

This module determines whether the input data is interpreted as data or command. When A0 = "H", the inputs at D7 - D0 are interpreted as data and be written to display RAM. When A0 = "L", the inputs at D7 - D0 are interpreted as command, they will be decoded and be written to the corresponding command registers.

#### **Display Data RAM**

The Display Data RAM is a bit mapped static RAM holding the bit pattern to be displayed. The size of the RAM is 132 X 64 bits. For mechanical flexibility, re-mapping on both segment and common outputs can be selected by software.

For vertical scrolling of the display, an internal register storing display start line can be set to control the portion of the RAM data to be mapped to the display.



#### The Page Address Circuit

As shown in Figure. 8, page address of the display data RAM is specified through the Page Address Set Command. The page address must be specified again when changing pages to perform access.

#### **The Column Address**

As shown in Figure. 8, the display data RAM column address is specified by the Column Address Set command. The specified column address is incremented (+1) with each display data read/ write command. This allows the MPU display data to be accessed continuously. Because the column address is independent of the page address, when moving, for example, from page0 column 83H to page 1 column 00H, it is necessary to re-specify both the page address and the column address.

Furthermore, as shown in Table. 7, the Column re-mapping (ADC) command (segment driver direction select command) can be used to reverse the relationship between the display data RAM column address and the segment output. Because of this, the constraints on the IC layout when the OLED module is assembled can be minimized.

Table, 7

Segment Output	SEG0		SEG131
ADC "0"	0 (H) →	Column Address	→ 83 (H)
ADC "1"	83 (H) ←	Column Address	← 0 (H)

#### The Line Address Circuit

The line address circuit, as shown in Figure. 8, specifies the line address relating to the common output when the contents of the display data RAM are displayed. Using the display start line address set command, what is normally the top line of the display can be specified (this is the COM0 output when the common output mode is normal, and the COM63 output for SH1106, when the common output mode is reversed. The display area is a 64-line area for the SH1106 from the display start line address.

If the line addresses are changed dynamically using the display start line address set command, screen scrolling, page swapping, etc. that can be performed relationship between display data RAM and address (if initial display line is 1DH).



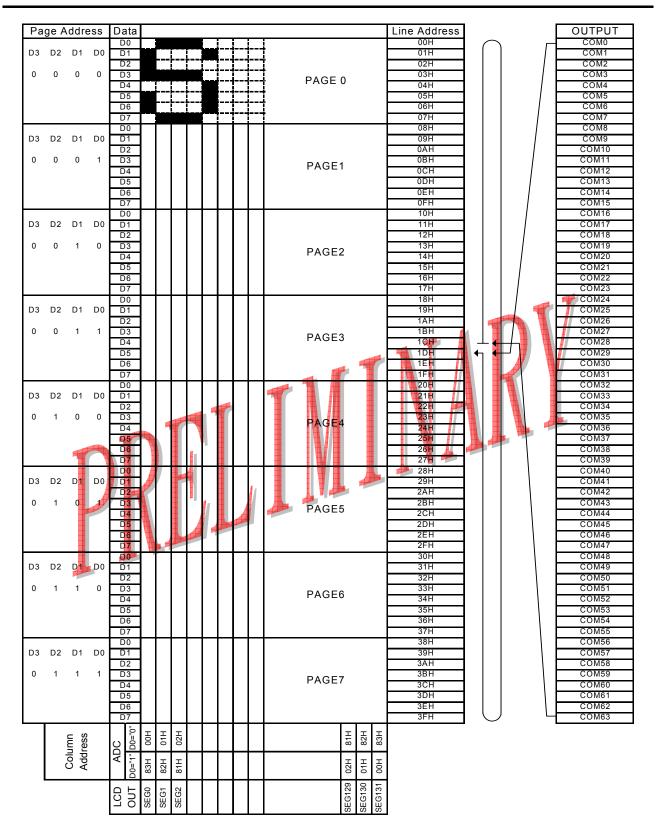


Figure. 8



# **The Oscillator Circuit**

This is a RC type oscillator (Figure. 9) that produces the display clock. The oscillator circuit is only enabled when CLS = "H". When CLS = "L", the oscillation stops and the display clock is inputted through the CL terminal.

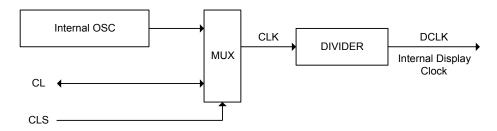


Figure. 9





#### **Charge Pump Regulator**

This block accompanying only 2 external capacitors, is used to generate a 9.0V voltage for OLED panel. This regulator can be turned ON/OFF by software command 8Bh setting.

#### **Charge Pump output voltage control**

This block is used to set the voltage value of charger pump output. The driving voltage can be adjusted from 6.4V up to 9.0V. This used to meet different demand of the panel.

#### **Current Control and Voltage Control**

This block is used to derive the incoming power sources into different levels of internal use voltage and current. VPP and VDD2 are external power supplies. IREF is a reference current source for segment current drivers.

#### **Common Drivers/Segment Drivers**

Segment drivers deliver 132 current sources to drive OLED panel. The driving current can be adjusted up to 200µA with 256 steps. Common drivers generate voltage scanning pulses.

#### **Reset Circuit**

When the RES input falls to "L", these reenter their default state. The default settings are shown below:

- 1. Display is OFF. Common and segment are in high impedance state
- 2. 132 X 64 Display mode.
- 3. Normal segment and display data column address and row address mapping (SEG0 is mapped to column address 00H and COM0 mapped to row address 00H).
- 4. Shift register data clear in serial interface.
- 5. Display start line is set at display RAM line address 00H.
- 6. Column address counter is set at 0.
- 7. Normal scanning direction of the common outputs.
- 8. Contrast control register is set at 80H.
- 9. Internal DC-DC is selected.



#### **Commands**

The SH1106 uses a combination of A0,  $\overline{\text{RD}}$  (E) and  $\overline{\text{WR}}$  ( $\overline{\text{R/W}}$ ) signals to identify data bus signals. As the chip analyzes and executes each command using internal timing clock only regardless of external clock, its processing speed is very high and its busy check is usually not required. The 8080 series microprocessor interface enters a read status when a low pulse is input to the  $\overline{\text{RD}}$  pad and a write status when a low pulse is input to the  $\overline{\text{WR}}$  pad. The 6800 series microprocessor interface enters a read status when a high pulse is input to the  $\overline{\text{R/W}}$  pad and a write status when a low pulse is input to this pad. When a high pulse is input to the E pad, the command is activated. (For timing, see AC Characteristics.). Accordingly, in the command explanation and command table,  $\overline{\text{RD}}$  (E) becomes 1(HIGH) when the 6800 series microprocessor interface reads status of display data. This is an only different point from the 8080 series microprocessor interface.

Taking the 8080 series, microprocessor interface as an example command will explain below.

When the serial interface is selected, input data starting from D7 in sequence.

#### **Command Set**

- 1. Set Lower Column Address: (00H 0FH)
- 2. Set Higher Column Address: (10H 1FH)

Specifies column address of display RAM. Divide the column address into 4 higher bits and 4 lower bits. Set each of them into successions. When the microprocessor repeats to access to the display RAM, the column address counter is incremented during each access until address 132 is accessed. The page address is not changed during this time.

	A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D <b>0</b>
Higher bits	10	1	0	0	0	0		<b>A</b> 7	A6	A5	A4
Lower bits	0	1	0	0	0	0	o	А3	A2	A1	A0
A7 A6	A5	A4	<b>A</b> 3	A2	A	1	A0		Line a	ddress	3
0 0	0	0 📗	0	0	(	)	0			0	
0 0	0	0	0	0	(	)	1			1	
										: .	
1 0	0 =	0	0	0			1		1	31	

Note: Don't use any commands not mentioned above.

# 3. Set Pump voltage value: (30H~33H)

Specifies output voltage (VPP) of the internal charger pump.

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
<mark>0</mark>	1	0	0	0	1	1	0	0	A1	<mark>A0</mark>

A1	A0	Pump output voltage (VPP)
<mark>0</mark>	0	<mark>6.4</mark>
<mark>0</mark>	<mark>1</mark>	<mark>7.4</mark>
<mark>1</mark>	<mark>0</mark>	8.0(Power on)
<mark>1</mark>	1	9.0



#### 4. Set Display Start Line: (40H - 7FH)

Specifies line address (refer to Figure. 8) to determine the initial display line or COM0. The RAM display data becomes the top line of OLED screen. It is followed by the higher number of lines in ascending order, corresponding to the duty cycle. When this command changes the line address, the smooth scrolling or page change takes place.

Ī	A0	$\frac{E}{RD}$	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
	0	1	0	0	1	A5	A4	А3	A2	A1	A0

A5	A4	A3	A2	A1	A0	Line address
0	0	0	0	0	0	0
0	0	0	0	0	1	1
		:				:
1	1	1	1	1	0	62
1	1	1	1	1	1	63

#### 5. Set Contrast Control Register: (Double Bytes Command)

This command is to set contrast setting of the display. The chip has 256 contrast steps from 00 to FF. The segment output current increases as the contrast step value increases.

Segment output current setting: ISEG = α/256 X IREF X scale factor

Where:  $\alpha$  is contrast step; IREF is reference current equals 10µA; Scale factor = 32.

#### ■ The Contrast Control Mode Set: (81H)

When this command is input, the contrast data register set command becomes enabled. Once the contrast control mode has been set, no other command except for the contrast data register command can be used. Once the contrast data set command has been used to set data into the register, then the contrast control mode is released.

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0		0	1	0	0	0	0	0	0	1

#### ■ Contrast Data Register Set: (00H - FFH)

By using this command to set eight bits of data to the contrast data register; the OLED segment output assumes one of the 256 current levels.

When this command is input, the contrast control mode is released after the contrast data register has been set.

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0	ISEG
0	1	0	0	0	0	0	0	0	0	0	Small
0	1	0	0	0	0	0	0	0	1	0	
0	1	0	0	0	0	0	0	0	1	1	
0	1	0					:				:
0	1	0	1	0	0	0	0	0	0	0	POR
0	1	0					:				:
0	1	0	1	1	1	1	1	1	1	0	
0	1	0	1	1	1	1	1	1	1	1	Large

When the contrast control function is not used, set the D7 - D0 to 1000,0000.



#### 6. Set Segment Re-map: (A0H - A1H)

Change the relationship between RAM column address and segment driver. The order of segment driver output pads can be reversed by software. This allows flexible IC layout during OLED module assembly. For details, refer to the column address section of Figure. 8. When display data is written or read, the column address is incremented by 1 as shown in Figure. 1.

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	0	0	0	0	ADC

When ADC = "L", the right rotates (normal direction). (POR)

When ADC = "H", the left rotates (reverse direction).

#### 7. Set Entire Display OFF/ON: (A4H - A5H)

Forcibly turns the entire display on regardless of the contents of the display data RAM. At this time, the contents of the display data RAM are held.

This command has priority over the normal/reverse display command.

A0	E RD	$R/\overline{W}$ $\overline{WR}$	D7	D6	D5	D4	D3	D2	D1	<b>D</b> 0
0	1	0	1	0	1	0	0	1	0	D

When D = "L", the normal display status is provided. (POR)

When D = "H", the entire display ON status is provided.

# 8. Set Normal/Reverse Display: (A6H -A7H)

Reverses the display ON/OFF status without rewriting the contents of the display data RAM.

A0	E RD	R/W WR	<b>D</b> 7	D6	D5	D4	D3	D2	D1	D0
0	1		1	0	1	0	0	1	1	D

When D = "L", the RAM data is high, being OLED ON potential (normal display). (POR)

When D = "H", the RAM data is low, being OLED ON potential (reverse display)



### 9 Set Multiplex Ration: (Double Bytes Command)

This command switches default 64 multiplex modes to any multiplex ratio from 1 to 64. The output pads COM0-COM63 will be switched to corresponding common signal.

#### ■ Multiplex Ration Mode Set: (A8H)

A0	$\frac{E}{RD}$	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	0	1	0	0	0

### ■ Multiplex Ration Data Set: (00H - 3FH)

A0	$\frac{E}{RD}$	$R/\overline{W}$ $\overline{WR}$	D7	D6	D5	D4	D3	D2	D1	D0	Multiplex Ratio
0	1	0	*	*	0	0	0	0	0	0	1
0	1	0	*	*	0	0	0	0	1	0	2
0	1	0	*	*	0	0	0	0	1	1	3
0	1	0					:				:
0	1	0	*	*	1	1	1	1	1	0	63
0	1	0	*	*	1	1	1	1	1	1	64 (POR)

## 10. Set DC-DC OFF/ON: (Double Bytes Command)

This command is to control the DC-DC voltage converter. The converter will be turned on by issuing this command then display ON command. The panel display must be off while issuing this command.

#### ■ DC-DC Control Mode Set: (ADH)

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	~	0	1	0	1	1	0	1

# ■ DC-DC ON/OFF Mode Set: (8AH - 8BH)

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	0	0	1	0	1	D

When D = DC-DC is disable.

When D = "H", DC-DC will be turned on when display on. (POR)

Table. 8

DC-DC STATUS	DISPLAY ON/OFF STATUS	Description
0	0	Sleep mode
0	1	External VPP must be used.
1	0	Sleep mode
1	1	Built-in DC-DC is used, Normal Display



# 11. Display OFF/ON: (AEH - AFH)

Alternatively turns the display on and off.

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	0	1	1	1	D

When D = "L", Display OFF OLED. (POR)

When D = "H", Display ON OLED.

When the display OFF command is executed, power saver mode will be entered.

#### Sleep mode:

This mode stops every operation of the OLED display system, and can reduce current consumption nearly to a static current value if no access is made from the microprocessor. The internal status in the sleep mode is as follows:

- 1) Stops the oscillator circuit and DC-DC circuit.
- 2) Stops the OLED drive and outputs HZ as the segment/common driver output.
- 3) Holds the display data and operation mode provided before the start of the sleep mode.
- 4) The MPU can access to the built-in display RAM.

#### 12. Set Page Address: (B0H - B7H)

Specifies page address to load display RAM data to page address register. Any RAM data bit can be accessed when its page address and column address are specified. The display remains unchanged even when the page address is changed.

A0		R/W D7 WR 0 1	D6 D5 D4 0 1 1	D3 D2 D1 D0 A3 A2 A1 A0
A3	A <sub>2</sub>	A1	A <sub>0</sub>	Page address
0	0	0	0	0
0	0	0	1	1
0	0	1	0	2
0	0	1	1	3
0	1	0	0	4
0	1	0	1	5
0	1	1	0	6
0	1	1	1	7

Note: Don't use any commands not mentioned above for user.



#### 13. Set Common Output Scan Direction: (C0H - C8H)

This command sets the scan direction of the common output allowing layout flexibility in OLED module design. In addition, the display will have immediate effect once this command is issued. That is, if this command is sent during normal display, the graphic display will be vertically flipped.

Α0	$\frac{E}{RD}$	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	0	0	D	*	*	*

When D = "L", Scan from COM0 to COM [N -1]. (POR)

When D = "H", Scan from COM [N -1] to COM0.

#### 14. Set Display Offset: (Double Bytes Command)

This is a double byte command. The next command specifies the mapping of display start line to one of COM0-63 (it is assumed that COM0 is the display start line, that equals to 0). For example, to move the COM16 towards the COM0 direction for 16 lines, the 6-bit data in the second byte should be given by 010000. To move in the opposite direction by 16 lines, the 6-bit data should be given by (64-16), so the second byte should be 100000.

■ Display Offset Mode Set: (D3H)

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	<b>D</b> 0
0	1	0	1	1	0	1	o 💻	0	1	1

■ Display Offset Data Set: (00H~3FH)

A0	E RD	R/W WR	D7	<b>D</b> 6	D <b>5</b>	D4	D3	D2	D1	D0	COMx
0	1	0	*	*	0	O	0	0	0	0	0 (POR)
0	1	0	*	*	0	þ	0	0	1	0	1
0	1 1	0	*		0	0	0	0	1	1	2
0	1	0				2180	:				:
0	1	0	*		1	1	1	1	1	0	62
0	1	0	*	*	1	1	1	1	1	1	63

Note: "\*" stands for "Don't care"



#### 15. Set Display Clock Divide Ratio/Oscillator Frequency: (Double Bytes Command)

This command is used to set the frequency of the internal display clocks (DCLKs). It is defined as the divide ratio (Value from 1 to 16) used to divide the oscillator frequency. POR is 1. Frame frequency is determined by divide ratio, number of display clocks per row, MUX ratio and oscillator frequency.

■ Divide Ratio/Oscillator Frequency Mode Set: (D5H)

	A0	$\frac{E}{RD}$	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
ſ	0	1	0	1	1	0	1	0	1	0	1

■ Divide Ratio/Oscillator Frequency Data Set: (00H - 3FH)

Α0	$\frac{E}{RD}$	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	A7	A6	A5	A4	Аз	A2	A1	Ao

A3 - A0 defines the divide ration of the display clocks (DCLK). Divide Ration = A[3:0]+1.

Аз	A2	A1	Ao	Divide Ration
0	0	0	0	1 (POR)
		:		
1	1	1	1	16

A7 - A4 sets the oscillator frequency. Oscillator frequency increase with the value of A[7:4] and vice versa.

А7	A6	A5	A4	Oscillator Frequency of fosc
		0	0	- <b>25</b> % -20%
0	0	1 1	0	-15%
0			1	-10%
0		0	0	-5%
0	1	0	1	fosc (POR)
0	1	1	0	+5%
0	1	1	1	+10%
1	0	0	0	+15%
1	0	0	1	+20%
1	0	1	0	+25%
1	0	1	1	+30%
1	1	0	0	+35%
1	1	0	1	+40%
1	1	1	0	+45%
1	1	1	1	+50%



16. Set Dis-charge/Pre-charge Period: (Double Bytes Command)

This command is used to set the duration of the pre-charge period. The interval is counted in number of DCLK. POR is 2 DCLKs.

■ Pre-charge Period Mode Set: (D9H)

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	0	1	1	0	0	1

■ Dis-charge/Pre-charge Period Data Set: (00H - FFH)

Α0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	A7	A6	A5	A4	Аз	A2	A1	Ao

Pre-charge Period Adjust: (A3 - A0)

Аз	A2	A1	Ao	Pre-charge Period
0	0	0	0	INVALID
0	0	0	1	1 DCLKs
0	0	1	0	2 DCLKs (POR)
		:		
1	1	1	0	14 DCLKs
1	1		1	15 DCLKs

Dis-charge Period Adjust: (A7 - A4)

A <sub>7</sub>	A <sub>6</sub>	A5	A4	Dis-charge Period
0	0	0 = =	0	INVALID
0	0	0	1	1 DCLKs
<b>a</b> \ <b>b</b>	0	1	0	2 DCLKs (POR)
	1.			:
	1 /		0	14 DCLKs
1	1	1	1	15 DCLKs

17. Set Common pads hardware configuration: (Double Bytes Command)

This command is to set the common signals pad configuration (sequential or alternative) to match the OLED panel hardware layout

■ Common Pads Hardware Configuration Mode Set: (DAH)

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	0	1	1	0	1	0

■ Sequential/Alternative Mode Set: (02H - 12H)

Α0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	0	0	0	D	0	0	1	0

When D = "L", Sequential.

COM31, 30 - 1, 0	SEG0, 1 - 130, 131	COM32, 33 - 62, 63
	,	

When D = "H", Alternative. (POR)

COM62, 60 - 2, 0	SEG0, 1 - 130, 131	COM1, 3 - 61, 63



### 18. Set VCOM Deselect Level: (Double Bytes Command)

This command is to set the common pad output voltage level at deselect stage.

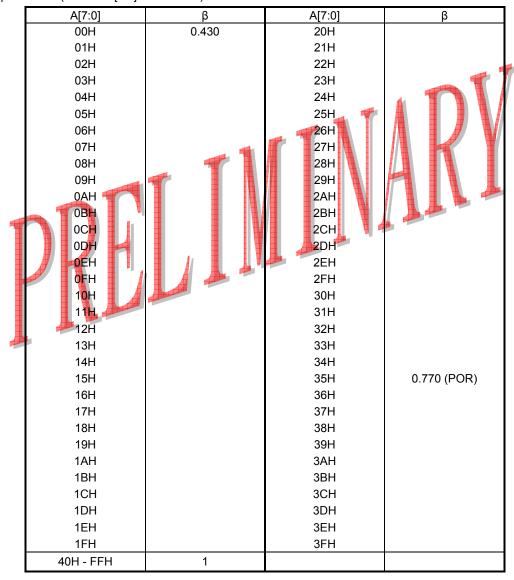
■ VCOM Deselect Level Mode Set: (DBH)

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	0	1	1	0	1	1

■ VCOM Deselect Level Data Set: (00H - FFH)

A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	A7	A6	A5	A4	Аз	A2	A1	Ao

VCOM =  $\beta$  X VREF = (0.430 + A[7:0] X <math>0.006415) X VREF





#### 19. Read-Modify-Write: (E0H)

A pair of Read-Modify-Write and End commands must always be used. Once read-modify-write is issued, column address is not incremental by read display data command but incremental by write display data command only. It continues until End command is issued. When the End is issued, column address returns to the address when read-modify-write is issued. This can reduce the microprocessor load when data of a specific display area is repeatedly changed during cursor blinking or others.

1	A0	E RD	R/W WR	D7	D6	D5	D4	D3	D2	D1	D0
	0	1	0	1	1	1	0	0	0	0	0

#### Cursor display sequence:

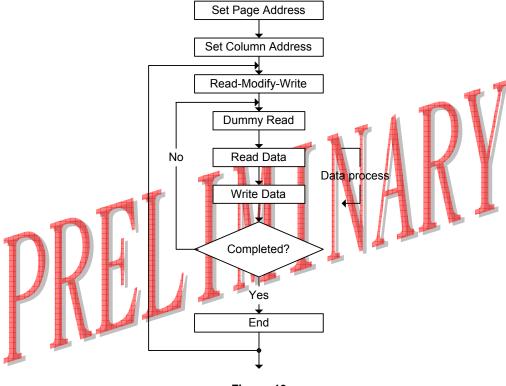


Figure. 10

#### 20. End: (EEH)

Cancels Read-Modify-Write mode and returns column address to the original address (when Read-Modify-Write is issued.)

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	1	0	1	1	1	0

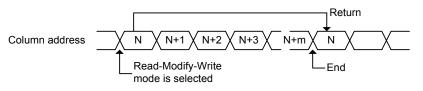


Figure. 11



#### 21. NOP: (E3H)

Non-Operation Command.

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	1	0	0	0	1	1

#### 22. Write Display Data

Write 8-bit data in display RAM. As the column address is incremental by 1 automatically after each write, the microprocessor can continue to write data of multiple words.

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
1	1	0			V	/rite R	AM da	ta		

#### 23. Read Status

A0	E RD	$\frac{R}{W}$	D7	D6	D5	D4	D3	D2	D1	D0
0	0	1	BUSY	ON/OFF	*	*	*	0	o	0

BUSY:

When high, the SH1106 is busy due to internal operation or reset. Any command is rejected until BUSY goes low. The busy check is not required if enough time is provided for each cycle.

ON/OFF:

Indicates whether the display is on or off. When goes low the display turns on. When goes high, the display turns off. This is the opposite of Display ON/OFF command.

#### 24. Read Display Data

Reads 8-bit data from display RAM area specified by column address and page address. As the column address is increment by 1 automatically after each write, the microprocessor can continue to read data of multiple words. A single dummy read is required immediately after column address being setup. Refer to the display RAM section of FUNCTIONAL DESCRIPTION for details. Note that no display data can be read via the serial interface.

A0	E/ RD	R W WR	D7	D6	D5	D4	D3	D2	D1	D0
	0	1			R	ead R	AM da	ta		



# **Command Table**

Commond						Code						Function
Command	Α0	RD	WR	D7	D6	D5	D4	D3	D2	D1	D0	Function
Set Column Address     4 lower bits	0	1	0	0	0	0	0	Lower column address			dress	Sets 4 lower bits of column address of display RAM in register. (POR = 00H)
Set Column     Address 4 higher     bits	0	1	0	0	0	0	1	Higher column address			dress	Sets 4 higher bits of column address of display RAM in register. (POR = 10H)
3. Set Pump voltage value	0	1	0	0	0	1	1	0				This command is to control the DC-DC voltage output value. (POR=32H)
Set Display Start     Line	0	1	0	0	1			Line a	ddress	•		Specifies RAM display line for COM0. (POR = 40H)
5. The Contrast Control Mode Set	0	1	0	1	0	0	0	0	0	0	1	This command is to set Contrast Setting of the display.
Contrast Data Register Set	0	1	0				Contra	st Data	a			The chip has 256 contrast steps from 00 to FF. (POR = 80H)
6. Set Segment Re-map (ADC)	0	1	0	1	0	1	0	0	0	0	ADC	The right (0) or left (1) rotation. (POR = A0H)
7. Set Entire Display OFF/ON	0	1	0	1	9	1	0	0		0		Selects normal display (0) or Entire Display ON (1). (POR = A4H)
8. Set Normal/ Reverse Display	0	1	O	1	0	1	0	0	1	1		Normal indication (0) when low, but reverse indication (1) when high. (POR = A6H)
9 Multiplex Ration Mode Set	0	1	o	1	О	1	0	1	0	0	0	This command switches default 63 multiplex mode to
Multiplex Ration Data Set	o	1	1 0	*			N	Multiple	ex Rati	0		any multiplex ratio from 1 to 64. (POR = 3FH)
10. DC-DC Control Mode Set	0	1	0	1	0	1	0	1	1	0	1	This command is to control the DC-DC voltage DC-DC
DC-DC ON/OFF Mode Set	0	1	0	1	0	0	0	1	0	1	D	will be turned on when display on converter (1) or DC-DC OFF (0). (POR = 8BH)



# **Command Table (Continued)**

Code									Function			
Command	Α0	RD	WR	D7	D6	D5	D4	D3	D2	D1	D0	Function
11. Display OFF/ON	0	1	0	1	0	1	0	1	1	1	D	Turns on OLED panel (1) or turns off (0). (POR = AEH)
12. Set Page Address	0	1	0	1	0	1	1	I	Page A	Address	8	Specifies page address to load display RAM data to page address register. (POR = B0H)
13. Set Common Output Scan Direction	0	1	0	1	1	0	0	D	*	*	*	Scan from COM0 to COM [N - 1] (0) or Scan from COM [N -1] to COM0 (1). (POR = C0H)
14. Display Offset Mode Set	0	1	0	1	1	0	1	0	0	1	1	This is a double byte command which specifies
Display Offset Data Set	0	1	0	*	*			CC	Мх			the mapping of display start line to one of COM0-63. (POR = 00H)
15. Set Display Divide Ratio/Oscillator Frequency Mode Set	0	1	0	1	1	0	1	0	1	0	1	This command is used to set the frequency of the internal display clocks. (POR = 50H)
Divide Ratio/Oscillator Frequency Data Set	- 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		Divide Ratio									
16. Dis-charge / Pre-charge Period Mode Set	0	1	0	1	1	O	1	1	0	0	1	This command is used to set the duration of the dis-charge and pre-charge
Dis-charge /Pre-charge Period Data Set	0	1	O	Di	s- <mark>c</mark> harç	ge Peri	od	Pr	e-char	ge Per	iod	period. (POR = 22H)
17. Common Pads Hardware Configuration Mode Set	0	1	0			0	1	1	0	1	0	This command is to set the common signals pad configuration. (POR = 12H)
Sequential/Alternative Mode Set	0	1	0	0	0	0	D	0	0	1	0	
18. VCOM Deselect Level Mode Set	0	1	0	1	1	0	1	1	0	1	1	This command is to set the common pad output voltage
VCOM Deselect Level Data Set	0	1	0			VC	COM (β	3 X VR	EF)			level at deselect stage. (POR = 35H)
19. Read-Modify-Write	0	1	0	1	1	1	0	0	0	0	0	Read-Modify-Write start.
20. End	0	1	0	1	1	1	0	1	1	1	0	Read-Modify-Write end.
21. NOP	0	1	0	1	1	1	0	0	0	1	1	Non-Operation Command
22. Write Display Data	1	1	0			٧	Vrite R	AM da	ta			
23. Read Status	0	0	1	BUSY	ON/ OFF	*	*	*	0	0	0	
24. Read Display Data	1	0	1			R	ead R	AM da	ta			

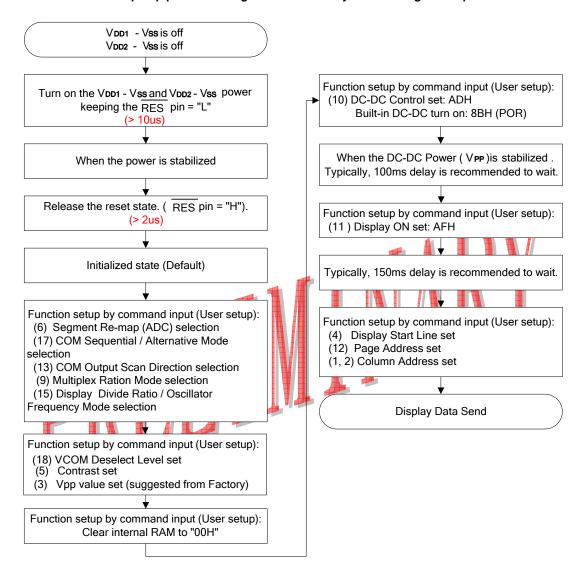
 $\textbf{Note:} \ \, \textbf{Do not use any other command, or the system malfunction may result.}$ 



### **Command Description**

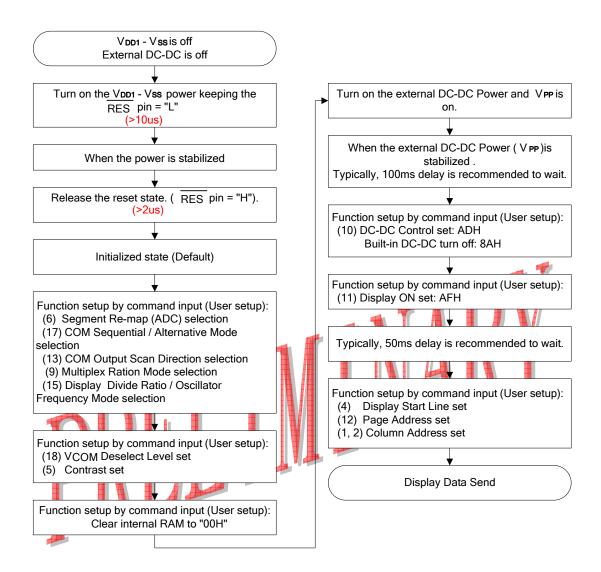
#### Instruction Setup: Reference

- 1. Power On and Initialization
- 1.1. When the built-in DC-DC pump power is being used immediately after turning on the power:





#### 1.2.When the external DC-DC pump power is being used immediately after turning on the power:





# 2. Power Off

Optional status

Function setup by command input (User setup):
(13) Display OFF set: AEH

Turn off the External DC-DC Power off and VPP is off.

When the external DC-DC Power (VPP) reach 0V.

Typically, 100ms delay is recommended to wait.

Turn off the VDD1 - Vss and VDD2 - Vss power





#### **Absolute Maximum Rating\***

# DC Supply Voltage (VDD1) -0.3V to +3.6V DC Supply Voltage (VDD2) -0.3V to +4.3V DC Supply Voltage (VPP) -0.3V to +13.5V Input Voltage -0.3V to VDD1 + 0.3V Operating Ambient Temperature -40°C to +85°C Storage Temperature -55°C to +125°C

#### \*Comments

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device under these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

#### **Electrical Characteristics**

DC Characteristics (Vss = 0V, VDD1 = 1.65 - 3.5V TA =+25°C, unless otherwise specified)

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
VDD1	Operating voltage	1.65	ı	3.5	V	
VDD2	Operating voltage	3.0	-	4.2	V	
VPP	OLED Operating voltage	6.4		13.0	V	
IDD1	Dynamic current consumption 1	-	-	110	μА	VDD1 = 3V, VDD2 = 3.7V, IREF = $12.5\mu$ A, Contrast $\alpha$ = 256, Internal charge pump QFF, Display ON, display data = All ON, No panel attached.
IDD2	Dynamic current consumption 2	-	-	2	mA	VDD1 = 3V, VDD2 = 3.7V, IREF = -12.5μA, Contrast $\alpha$ = .256, internal charge pump ON, Display ON, Display data = All ON, No panel attached.
lpp	OLED dynamic current consumption		-	1.5	mA	VDD1 = 3V, VDD2 = 3.7V, VPP =9V(external), IREF = -12.5 $\mu$ A, Contrast $\alpha$ = 256, Display ON, display data = All ON, No panel attached.
ISP	Sleep mode current consumption in VDD1 & VDD2	1	ı	5	μA	During sleep, TA = +25°C, VDD1 = 3V, VDD2 = 3V.
15P	Sleep mode current consumption in VPP	-	_	5	μА	During sleep, Ta = +25°C, Vpp = 9V (External)
ISEG	Segment output current	1-	-200		μА	VDD1 = 3V, VPP = 9V, IREF = -12.5 $\mu$ A, RLOAD = 20k $\Omega$ , Display ON. Contrast $\alpha$ = 256.
1323	oeginent output editerit		-25	-	μА	VDD1 = 3V, VPP = 9V, IREF = -12.5 $\mu$ A, RLOAD = 20k $\Omega$ , Display ON. Contrast $\alpha$ = 32.
ΔlSEG1	Segment output current uniformity	-	-	±3	%	$\Delta$ ISEG1 = (ISEG - IMID)/IMID X 100% IMID = (IMAX + IMIN)/2 ISEG [0:131] at contrast $\alpha$ = 256.
ΔISEG2	Adjacent segment output current uniformity	-	-	±2	%	$\triangle$ ISEG2 = (ISEG [N] - ISEG [N+1])/(ISEG [N] + ISEG [N+1]) X 100% ISEG [0:131] at contrast $\alpha$ = 256.



# **DC Characteristics (Continued)**

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
VIHC	High-level input voltage	0.8 X VDD1	-	VDD1	V	A0, D0 - D7, $\overline{RD}$ (E), $\overline{WR}$ (R/ $\overline{W}$ ), $\overline{CS}$ ,
VILC	Low-level input voltage	Vss	-	0.2 X VDD1	V	CLS, CL, IM0~2 and RES .
Vонс	High-level output voltage	0.8 X VDD1	-	VDD1	V	loн = -0.5mA (D0 - D7, and CL).
Volc	Low -level output voltage	Vss	-	0.2 X VDD1	V	loL = 0.5mA (D0, D2 - D7, and CL)
Volcs	SDA low -level output	Vss		0.2 X VDD1	V	VDD1<2V loL=3mA (SDA)
VOLCS	voltage	V 33	_	0.4	٧	VDD1>2V
lц	Input leakage current	-1.0	-	1.0	μΑ	VIN = VDD1 or Vss (A0, $\overline{RD}$ (E), $\overline{WR}$ (R/ $\overline{W}$ ), $\overline{CS}$ , CLS, IM0~2 and $\overline{RES}$ ).
lHZ	HZ leakage current	-1.0	-	1.0	μΑ	When the D0 - D7, and CL are in high impedance.
fosc	Oscillation frequency	315	360	420	kHz	TA = +25°C.
fFRM Frame frequency for 64 Commons		-	104	-	Hz	When fosc = 360kHz, Divide ratio = 1, common width = 54 DCLKs.



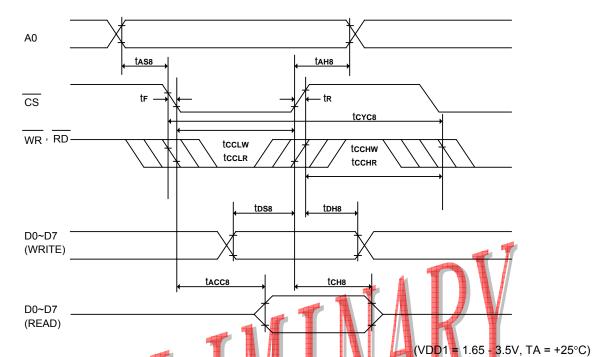


#### **AC Characteristics**

Fall time

tF

### (1) System buses Read/Write characteristics 1 (For the 8080 Series Interface MPU)



Symbol **Parameter** Min. Typ. Max. Unit Condition System cycle time 600 tcyc8 ns Address setup time tas8 ns Address hold time 0 tan8 ns Data setup time 80 tDS8 ns Data hold time 30 tDH8 ns Output disable time 140 tCH8 20 ns CL = 100pF tACC8 RD access time 280 ns CL = 100pF tcclw Control L pulse width (WR) 200 ns Control L pulse width (RD) 240 **tcclr** ns Control H pulse width (WR) tcchw 200 ns Control H pulse width (RD) **tcchr** 200 ns tR Rise time 30 ns

30

ns



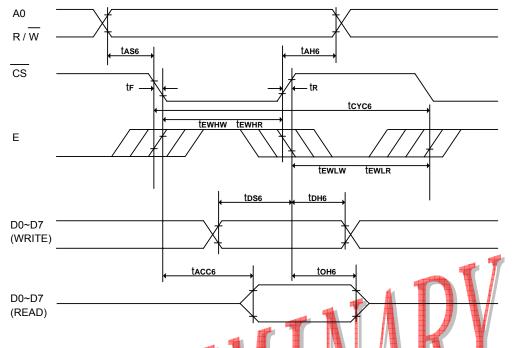
 $(VDD1 = 2.4 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
tcyc8	System cycle time	300	-	-	ns	
tAS8	Address setup time	0	-	-	ns	
tans	Address hold time	0	-	-	ns	
tDS8	Data setup time	40	-	-	ns	
tDH8	Data hold time	15	_	-	ns	
tcH8	Output disable time	10	-	70	ns	CL = 100pF
tACC8	RD access time	-	-	140	ns	CL = 100pF
tccLw	Control L pulse width (WR)	100	-	-	ns	
tCCLR	Control L pulse width (RD)	120	-	-	ns	
tccнw	Control H pulse width (WR)	100	-	-	ns	. #
tcchr	Control H pulse width (RD)	100	_	-	ns	
tr	Rise time	-	-	15	ns	* A
tF	Fall time	-	-	15	ns	





# (2) System buses Read/Write Characteristics 2 (For the 6800 Series Interface MPU)



 $(VDD1 = 1.65 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
tcyc6	System cycle time	600	-		ns	
tAS6	Address setup time	0	-	-	ns	
tan6	Address hold time	ρ	-		ns	
tDS6	Data setup time	80	-		ns	
tDH6	Data hold time	30	ı	ı	ns	
tон6	Output disable time	20	ı	140	ns	CL = 100pF
tACC6	Access time	ı	ı	280	ns	CL = 100pF
tewnw	Enable H pulse width (Write)	200	ı	ı	ns	
tewhr	Enable H pulse width (Read)	240	ı	ı	ns	
tewLw	Enable L pulse width (Write)	200	ı	ı	ns	
tewlr	Enable L pulse width (Read)	200	ı	ı	ns	
tr	Rise time	ı	ı	30	ns	
tF	Fall time	-	-	30	ns	



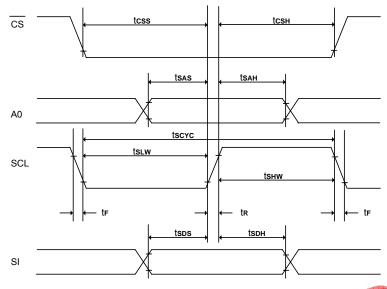
 $(VDD1 = 2.4 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition	
tCYC6	System cycle time	300	-	-	ns		
tAS6	Address setup time	0	-	-	ns		
tAH6	Address hold time	0	-	-	ns		
tDS6	Data setup time	40	-	-	ns		
tDH6	Data hold time	15	-	-	ns		
toH6	Output disable time	10	-	70	ns	CL = 100pF	
tACC6	Access time	-	-	140	ns	CL = 100pF	
tewnw	Enable H pulse width (Write)	100	-	-	ns		
tewhr	Enable H pulse width (Read)	120	-	-	ns		
tewLw	Enable L pulse width (Write)	100	-	-	ns		
tewlr	Enable L pulse width (Read)	100	-	-	ns		
tr	Rise time	-	-	15	ns		
tF	Fall time	-	-	15	ns		





# (3) System buses Write characteristics 3 (For 4 wire SPI)



VDD1 = 1.65 - 3.5V, IA = +25°C

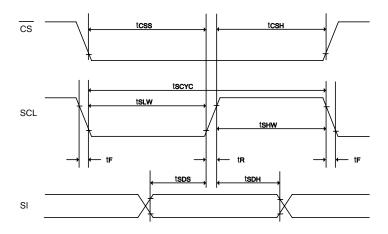
Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
tscyc	Serial clock cycle	500	-	- 1	ns 📗	
tsas	Address setup time	300	-		ns 🖣	
tsah	Address hold time	300 🚄	- 1	-	ns	
tsps	Data setup time	200	-	_	ns	
tsdh	Data hold time	200	-	-	ns	
tcss	CS setup time	240	- 1	_	ns	
tcsH	CS hold time time	120	-	_	ns	
tshw	Serial clock H pulse width	200	-	-	ns	F
tsLw	Serial clock L pulse width	200	-		ns	
tr	Rise time	-	-	30	ns	
tF	Fatt time	4-	-	30	ns	

$$(VDD1 = 2.4 - 3.5V, TA = +25^{\circ}C)$$

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
tscyc	Serial clock cycle	250	-	-	ns	
tsas	Address setup time	150	-	-	ns	
tsah	Address hold time	150	-	-	ns	
tsps	Data setup time	100	-	-	ns	
tsdh	Data hold time	100	-	-	ns	
tcss	CS setup time	120	-	-	ns	
tсsн	CS hold time time	60	-	-	ns	
tshw	Serial clock H pulse width	100	-	-	ns	
tsLw	Serial clock L pulse width	100	-	-	ns	
tr	Rise time	-	-	15	ns	
tF	Fall time	-	-	15	ns	
u	1 dii tiiric			10	113	



# (4) System buses Write characteristics 4(For 3 wire SPI)



 $(VDD1 = 1.65 - 3.5V, TA = +25^{\circ}C)$ 

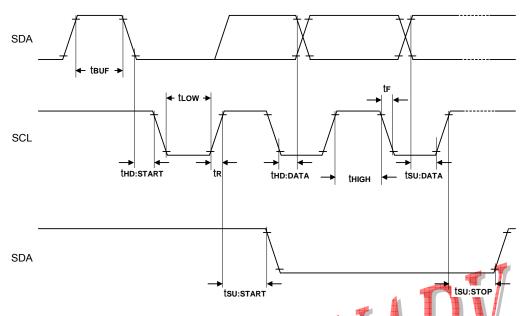
Symbol	Parameter	Min.	Тур.	Max.	Unit	<b>∠ Condition</b>
tscyc	Serial clock cycle	500	-	-	ns	
tsps	Data setup time	200	-	-	ns	
tsdh	Data hold time	200	-		ns	
tcss	CS setup time	240	- 1	_	ns	
tсsн	CS hold time time	120	-	_	ns	
tshw	Serial clock H pulse width	200	- 1	-	ns	
tslw	Serial clock L pulse width	200	- 1	-	ns	
tr	Rise time	-	- 1	30	ns	
tF	Fall time	-	-	30	ns	W -

 $(VDD1 = 2.4 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	P <mark>a</mark> rameter /	Min.	Тур.	Max.	Unit	Condition
tscyc	Serial clock cycle	250	-	-	ns	
tsds	Data setup time	100	-	-	ns	
tsdh	Data hold time	100	-	-	ns	
tcss	CS setup time	120	-	ı	ns	
tcsH	CS hold time time	60	-	ı	ns	
tshw	Serial clock H pulse width	100	-	ı	ns	
tsLw	Serial clock L pulse width	100	-	-	ns	
tr	Rise time	=	-	15	ns	
tF	Fall time	-	-	15	ns	



# (5) I<sup>2</sup>C interface characteristics

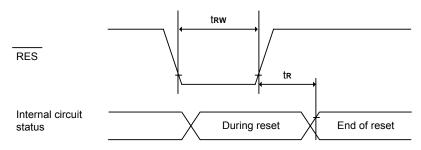


 $(VDD1 = 1.65 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	<b>T</b> yp.	Max.	Unit	Condition
fscL	SCL clock frequency	DC	<b>1</b> - <b>1</b>	4 <mark>0</mark> 0	kHz	
TLOW	SCL clock Low pulse width	1.3	-	-	uS	
Тнісн	SCL clock H pulse width	0.6	-	- 1 4	us	
TSU:DATA	data setup time	100	HI- A	-	nS	
THD:DATA	data hold time	1 0		0.9	uS	
Tr	SCL , SDA rise time	20+0.1Cb	-	300	nS	
TF	SCL , SDA fall time	20+0.1Cb	-	300	nS	
Cb	Capacity load on each bus	-	-	400	pF	
Tsu:start	Setup timefor re-START	0.6	=	=	uS	
THD:START	START Hold time	0.6	-	-	uS	
Tsu:stop	Setup time for STOP	0.6	-	-	uS	
TBUF	Bus free times between STOP and START condition	1.3	-	-	uS	



### (6) Reset Timing



 $(VDD1 = 1.65 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition
tr	Reset time	-	-	2.0	μS	
trw	Reset low pulse width	10.0	-	-	μS	

 $(VDD1 = 2.4 - 3.5V, TA = +25^{\circ}C)$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Condition	
tr	Reset time	-	-	1.0	μS		
trw	Reset low pulse width	5.0	-	-	μS		





### **Application Circuit (for reference only)**

### **Reference Connection to MPU:**

1. 8080 series interface: (Internal oscillator, Built-in DC-DC)

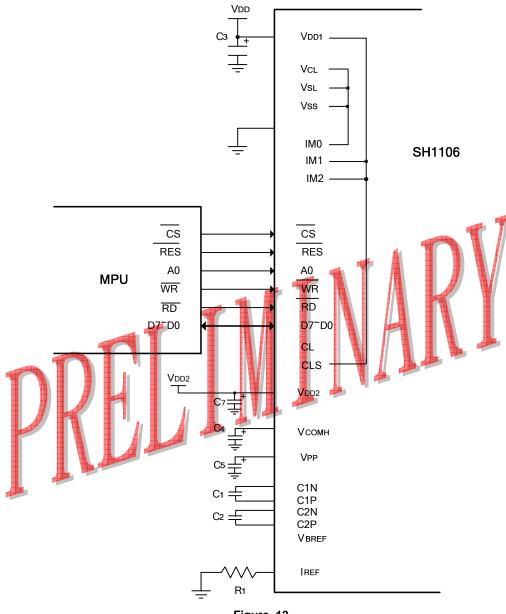


Figure. 12

# Note:

 $C_3$  -  $C_5$  ,C7: 4.7 $\mu F.~$  C1, C2 : 0.22  $\sim 1 \mu F.$ 

R1: about 510k $\Omega$ , R1 = (Voltage at IREF - Vss)/IREF



### 2. 6800 Series Interface: (Internal oscillator, Built-in DC-DC)

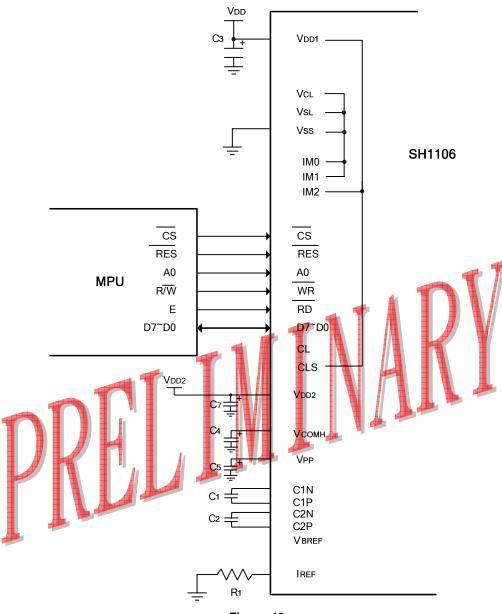


Figure. 13

### Note:

 $C_3$  -  $C_5$  ,  $C_7$ :  $4.7 \mu F. \ C_1$  ,  $C_2$  : 0.22 ~1  $\mu F$ 

R1: about 510k $\Omega$ , R1 = (Voltage at IREF - Vss)/IREF



### 3. Serial Interface(3-wire or 4-wire SPI): (External oscillator, External VPP, Max 13.0V)

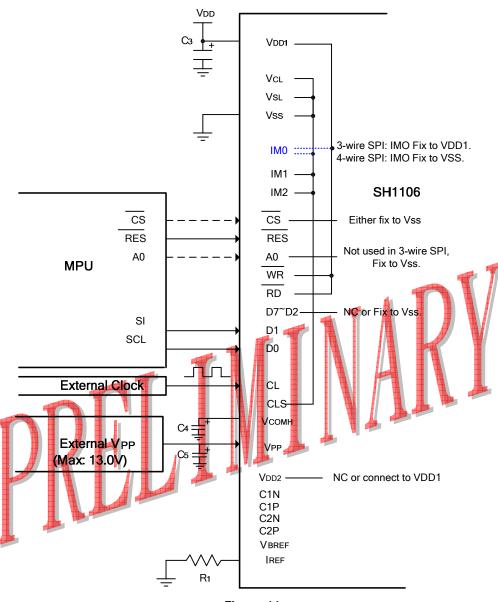


Figure. 14

#### Note:

C3 - C5: 4.7uF

R1: about  $510k\Omega$ , R1 = (Voltage at IREF - Vss)/IREF

 $\overline{\text{WR}}$  and  $\overline{\text{RD}}$  are not used in SPI mode, should fix to VSS or VDD1.

CS can fix to VSS in SPI mode.



### 4. I<sup>2</sup>C Interface: (Internal oscillator, Built-in DC-DC)

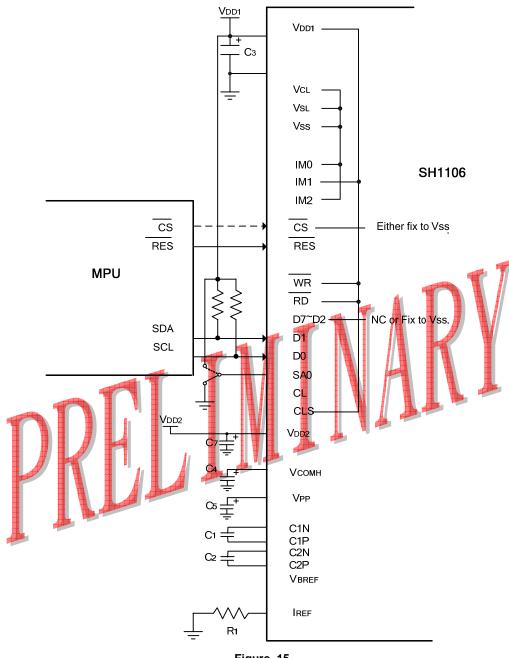


Figure. 15

#### Note:

 $C_3$  -  $C_5$ ,  $C_7$ : 4.7 $\mu$ F.  $C_1$ ,  $C_2$ : 0.22 ~1 $\mu$ F.

R1: about 510k $\Omega$ , R1 = (Voltage at IREF - Vss)/IREF

The least significant bit of the slave address is set by connecting the input SA0 to either logic 0(VSS) or 1 (VDD1).

 $\overline{WR}$  and  $\overline{RD}$  are not used in I<sup>2</sup>C mode, should fix to VSS or VDD1.

CS can fix to VSS in I<sup>2</sup>C mode.

The positive supply of pull-up resistor must equal to the value of VDD1.



# **Ordering Information**

Part No.	Package
SH1106G	Gold bump on chip tray

# **Spec Revision History**

Version	Content	Date
0.0	1. Original	Sep.2011
0.1	1. Add 3-wire SPI. 2. Interface select pin rename to IM0~2. (C86 rename to IM1, P/S rename to IM2.) 3. Update Application Circuit. 4. Add Set Pump voltage value command. (Page 17,18,29)	OCT.2011
0.2	Change the voltage output value of Set Pump voltage value command.     Add pad location and diagram.     Add AC Characteristics of 3-wire SPI. (Page 42)	Nov.2011

