

EE 779 Advanced Topics in Signal Processing
Assignment 5
Assigned: 08/10/16, Due: 20/10/16
Indian Institute of Technology Bombay

Note

- Submit the written part and print out of simulations, together.

Problems

1. [*]When estimating \mathbf{x} using least-squares approach to solve

$$\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{n}$$

determine the bounds on the error

$$\|\tilde{\mathbf{x}} - \mathbf{x}\|_2^2,$$

where we estimate $\tilde{\mathbf{x}}$ as $\tilde{\mathbf{x}} = \mathbf{A}^{-1}\mathbf{y}$.

2. Show that the minimizer $\hat{\mathbf{x}}$ of

$$\min_{\mathbf{x}} \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 + \delta\|\mathbf{x}\|_2^2$$

for \mathbf{A} a $M \times N$ matrix with $M > N$ is

$$\hat{\mathbf{x}} = (\mathbf{A}^T \mathbf{A} + \delta \mathbf{I})^{-1} \mathbf{A}^T \mathbf{y}.$$

This modification to the standard least-squares problem is a special case of the Tikhonov Regularization. Compare the above solution with the least-squares solution by using SVD representation of \mathbf{A} .

3. Suppose \mathbf{U} is an $N \times N$ matrix with orthonormal columns $\mathbf{U}^T \mathbf{U} = \mathbf{I}$. Show that $\|\mathbf{U}\mathbf{x}\|_2^2 = \|\mathbf{x}\|_2^2$ for every $\mathbf{x} \in \mathbb{R}^N$.
4. [*]Use the file `blocks_deconv.mat` from moodle data file. This contains the vectors
 - \mathbf{x} : a 512×1 signal
 - \mathbf{h} : a 30×1 filter
 - \mathbf{y} : a 541×1 vector of observations of \mathbf{h} convolved with \mathbf{x} .
 - \mathbf{yn} : a noisy observation of \mathbf{y} . The noise is iid Gaussian with standard deviation 0.01.
 - (a) Write a function which takes a vector \mathbf{h} of length L and input signal length N , and returns the $M \times N$ with $M = N + L - 1$ matrix \mathbf{A} such that for any vector $\mathbf{x} \in \mathbb{R}^N$, the product $\mathbf{A}\mathbf{x}$ is the vector of non-zero values of \mathbf{h} convolved with \mathbf{x} .
 - (b) Use MATLAB's `svd` command to calculate the SVD of \mathbf{A} . What are the largest and smallest singular values? Calculate $\mathbf{A}^\dagger \mathbf{y}$ and plot it.
 - (c) Apply \mathbf{A}^\dagger to the noisy \mathbf{yn} . Plot the result. Calculate the mean square error $\|\mathbf{x} - \hat{\mathbf{x}}\|_2^2$ and compare to the measurement error $\|\mathbf{y} - \mathbf{yn}\|_2^2$.
 - (d) Approximate \mathbf{A} by truncating the last q terms in the SVD to obtain:

$$\mathbf{A}' = \sum_{k=1}^{p-q} \sigma_k \mathbf{u}_k \mathbf{v}_k^T.$$

Apply the new pseudo-inverse \mathbf{A}'^\dagger to \mathbf{yn} and plot the result. Try different values for q and choose the one which gives the best result. Mention the value you choose for q . Calculate the mean-square reconstruction error.

- (e) Form another approximate inverse using the Tikhonov regularization (See Problem 2, above). Try different values of δ and choose the best one. What value of δ gave the best result. Calculate the mean-square reconstruction error.
- (f) Summarize your observations and findings by comparing (c), (d), and (e). Include the error for $\|\mathbf{x} - \mathbf{y}\mathbf{n}'\|_2^2$ using appropriate part of $\mathbf{y}\mathbf{n}$.