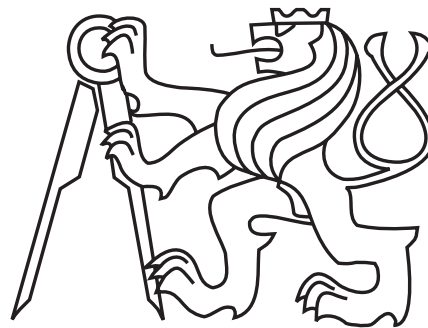


MI-ARI

(Computer arithmetics)
winter semester 2017/18

D2. Division II.

© Alois Pluháček Pavel Kubalík, 2017
Department of digital design
Faculty of Information technology
Czech Technical University in Prague



D2. Division II.

- Principle of skip over 0's
- Principle of skip over 1's
- SRT methods
- Using fast multipliers
 - Fraction extension
 - Iteration
- Division in decimal system

Next we will assume **division of unsigned numbers**
and **divisor B satisfy condition**

$$\frac{1}{2} \leq B < 1,$$

i.e. that it is **normalized**.

We can process analogous in a case, that $1 \leq B < 2$.

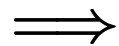
<i>Principle of skip over 0's</i>		
example of division:		
0 , 1 0 0 0	: 0 , 1 1 1 1 = 0 , 1 0 0 0	
0 1 0 0 0		
1 0 0 0 1		
<hr/>		
0 1 1 0 0 1 0	0 ,	−0,1111 ▷ 0
0 1 1 1 1		
<hr/>		
1 0 0 0 0 1 0	1	+0,1111 ▷ 1
1 0 0 0 1		
<hr/>		
0 1 0 0 1 1	0	−0,1111 ▷ 2
0 0 1 0 0		
1 0 0 0 1		
<hr/>		
0 1 0 1 0 1	0	−0,1111 ▷ 3
0 1 0 0 0		
1 0 0 0 1		
<hr/>		
0 1 1 0 0 1	0	−0,1111 ▷ 4
0 1 0 0 0		
<hr/>		
0 1 0 0 0		

Principle of skip over 0's ii

$$0,1000 : 0,1111 = 0,1000$$

$$\begin{array}{r}
 01000 \\
 10001 \\
 \hline
 0110010 \\
 01111 \\
 \hline
 100001000 \\
 10001 \\
 011001 \\
 01111 \\
 \hline
 01000
 \end{array}$$

3 zeroes



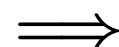
record 2 zeroes into quotient and
shift of partial remainder by 3 positions

$$\begin{array}{r}
 0, \\
 100 \\
 -0,1111 \triangleright 0 \\
 +0,1111 \triangleright 1 \\
 -0,1111 \triangleright 4 \\
 0
 \end{array}$$

restoring

generally:

k zeroes



record $k-1$ zeroes in quotient and
shift partial remainder by k positions

Principle of skip over 1's

example of division:

$$0,1110 : 0,1111 = 0,1110$$

$$\begin{array}{r} 01110 \\ 10001 \\ \hline \end{array}$$

$$\begin{array}{r} 011110 \\ 01111 \\ \hline \end{array}$$

$$101101$$

$$\begin{array}{r} 11100 \\ 01111 \\ \hline \end{array}$$

$$101011$$

$$\begin{array}{r} 11000 \\ 01111 \\ \hline \end{array}$$

$$100111$$

$$\begin{array}{r} 10000 \\ 01111 \\ \hline \end{array}$$

$$011111$$

$$01110 \text{ (after restoring)}$$

$$-0,1111 \triangleright 0$$

$$+0,1111 \triangleright 1$$

$$+0,1111 \triangleright 2$$

$$+0,1111 \triangleright 3$$

$$-0,1111 \triangleright 4$$

Principle of skip over 1's ii

$$0,1110 : 0,1111 = 0,1110$$

$ \begin{array}{r} 01110 \\ 10001 \\ \hline 0111110000 \end{array} $	$ \begin{array}{r} 01111 \\ 01111 \\ \hline 01111 \\ 01111 \\ \hline 01110 \end{array} $	$ \begin{array}{l} -0,1111 \triangleright 0 \\ +0,1111 \triangleright 4 \\ 0 \end{array} $
<p>4 ones \Rightarrow record 3 ones into quotient and shift partial remainder by 4 positions</p>	<p>restoring</p>	<p>0,111</p>

generally:

k ones \Rightarrow record $k-1$ ones into quotient and shift partial remainder by k positions

SRT ... Sweeney - Robertson - Tocher

- Representation of quotient is determined in signed-digit number system and next is converted into standard number system.
- Partial remainder is normalized after each partial operation addition / subtraction by using principle of (skip over 0's and 1's).
- Redundant number of signed-digit number system is used.
 - Only several (few) first bits of partial remainder is sufficient to determine one digit of quotient.
 - The principle of skipping 0's and 1's is used as much as possible.
- The number system with bases $z > 2$ are also used.

Robertsons diagram

$A \in \langle 0, 5, 1 \rangle$... **dividend**

$B \in \langle 0, 5, 1 \rangle$... **divisor**

$Q \in \langle 0, 1 \rangle$... **quotient**

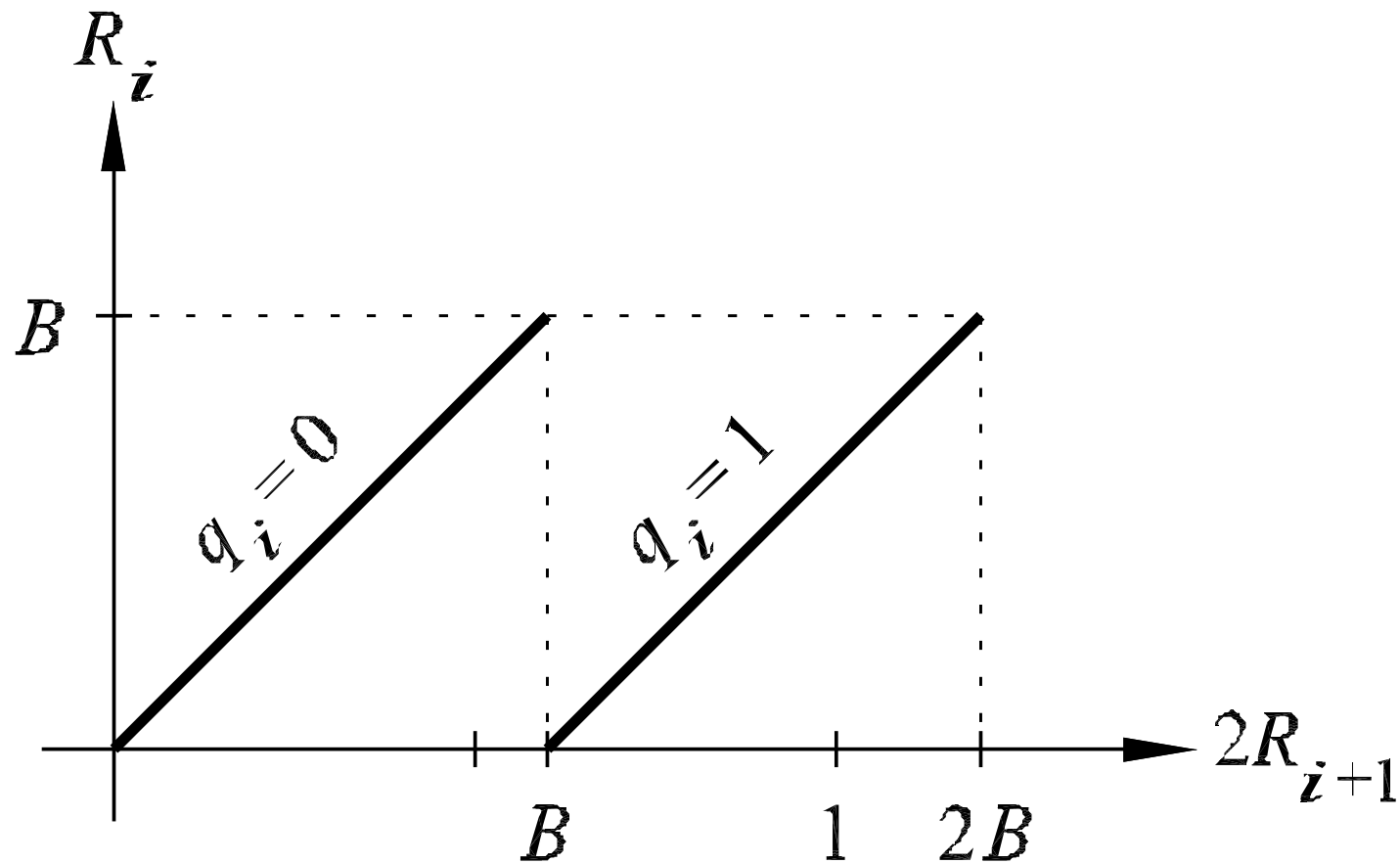
$q_0, q_{-1} q_{-2} \dots q_{-m}$ ← notation Q

$R \in (-1, 1)$... **remainder**

$R_i \in (-1, 1)$... **partial remainder belonging to q_i
shifted by m position to the left**

**Dividend A is considered as a first
partial remainder.**

division with restoring:



ex.: division with restoring:

$$A = 0,101$$

$$B = 0,110$$

$$Q = 0,110$$

$$R = 0,000\ 100$$

$$\begin{array}{r} \\ -B \\ \hline \end{array}$$

$$A \sim 2R_1$$

$$q_0 = 0$$

$$R_0$$

restoring and shift

$$\begin{array}{r} \\ -B \\ \hline \end{array}$$

$$q_{-1} = 1$$

$$R_{-1}$$

↓ ↓ ↓

$$\begin{array}{r} \\ -B \\ \hline \end{array}$$

$$q_{-2} = 1$$

$$R_{-2}$$

↓ ↓ ↓

$$\begin{array}{r} \\ -B \\ \hline \end{array}$$

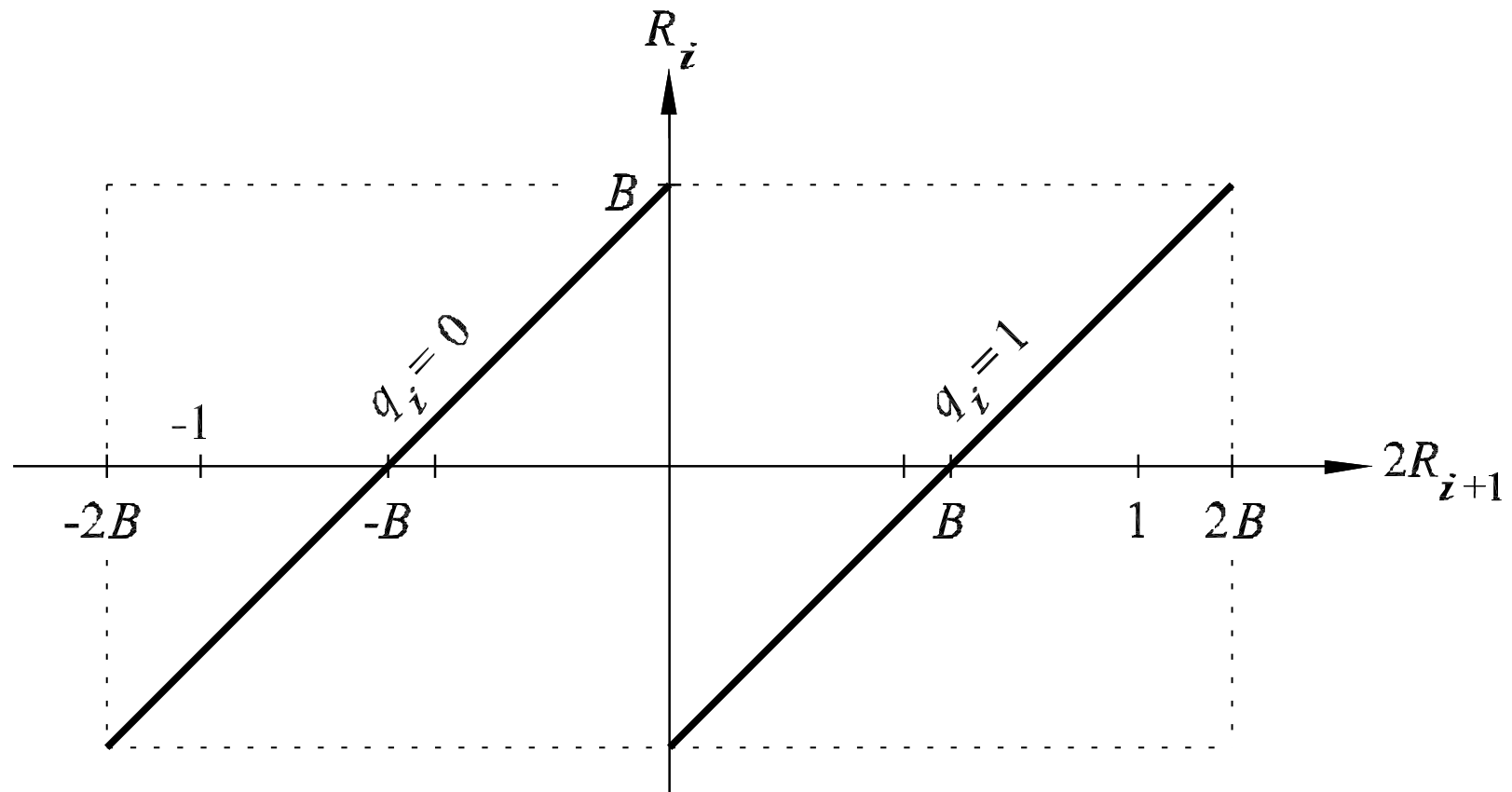
$$q_{-3} = 0$$

$$R_{-3}$$

$$0\ 1\ 0\ 0$$

(after restoring)

division without restoring:



ex.: division without restoring:

$$A = 0,101$$

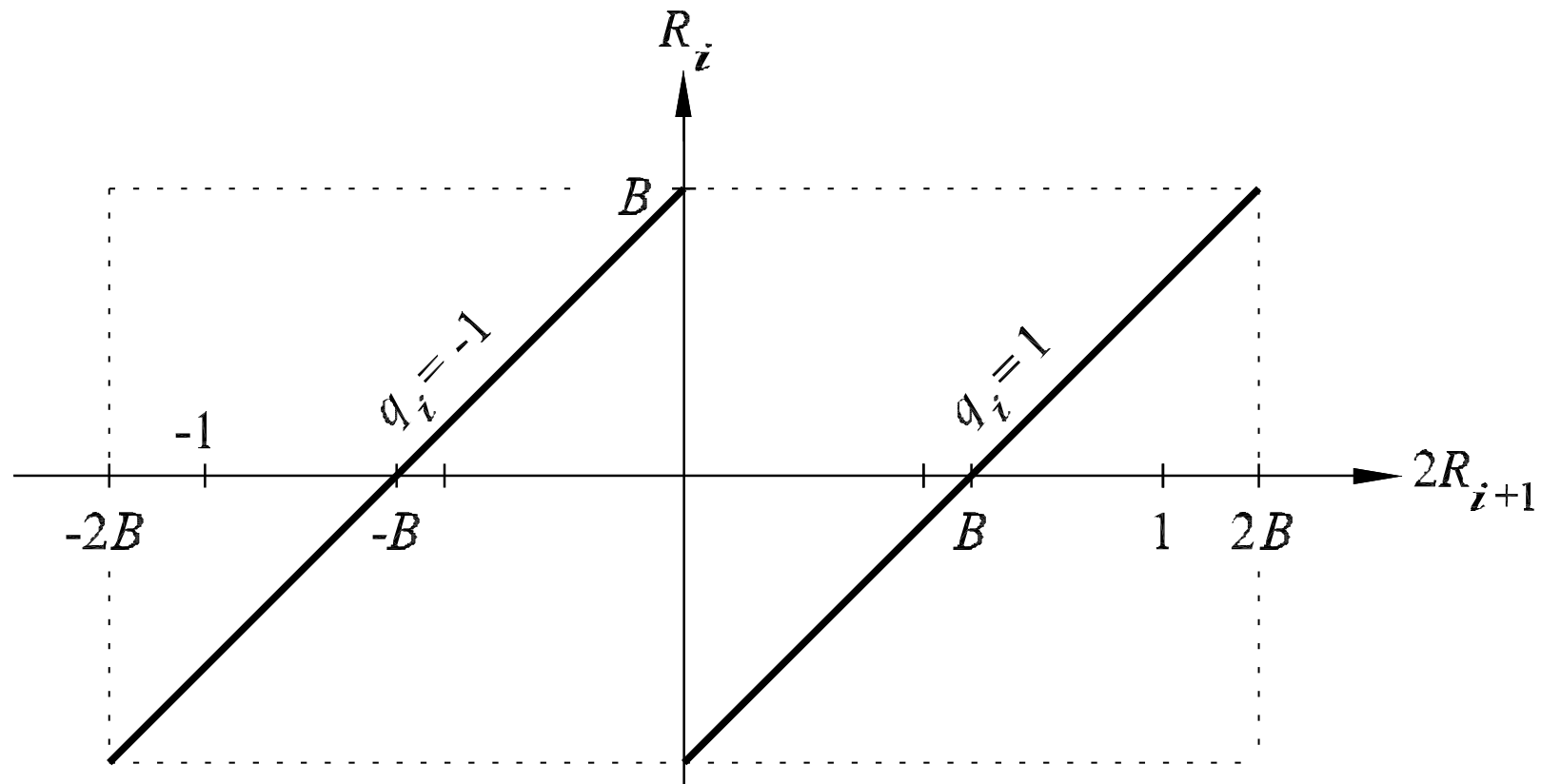
$$B = 0,110$$

$$Q = 0,110$$

$$R = 0,000\ 100$$

		0 1 0 1	$A \sim 2R_1$
$-B$		1 0 1 0	$q_0 = 0$
	0	<u>1 1 1 1</u>	R_0
		↓ ↓ ↓	
		1 1 1 0	
$+B$		0 1 1 0	$q_{-1} = 1$
	1	<u>0 1 0 0</u>	R_{-1}
		↓ ↓ ↓	
		1 0 0 0	
$-B$		1 0 1 0	$q_{-2} = 1$
	1	<u>0 0 1 0</u>	R_{-2}
		↓ ↓ ↓	
		0 1 0 0	
$-B$		1 0 1 0	$q_{-3} = 0$
	0	<u>1 1 1 0</u>	R_{-3}
		0 1 0 0	(after restoring)

using of signed-digit numbers (division without restoring):



ex.: using of signed-digit
numbers

(division without restoring):

$$A = 0,101$$

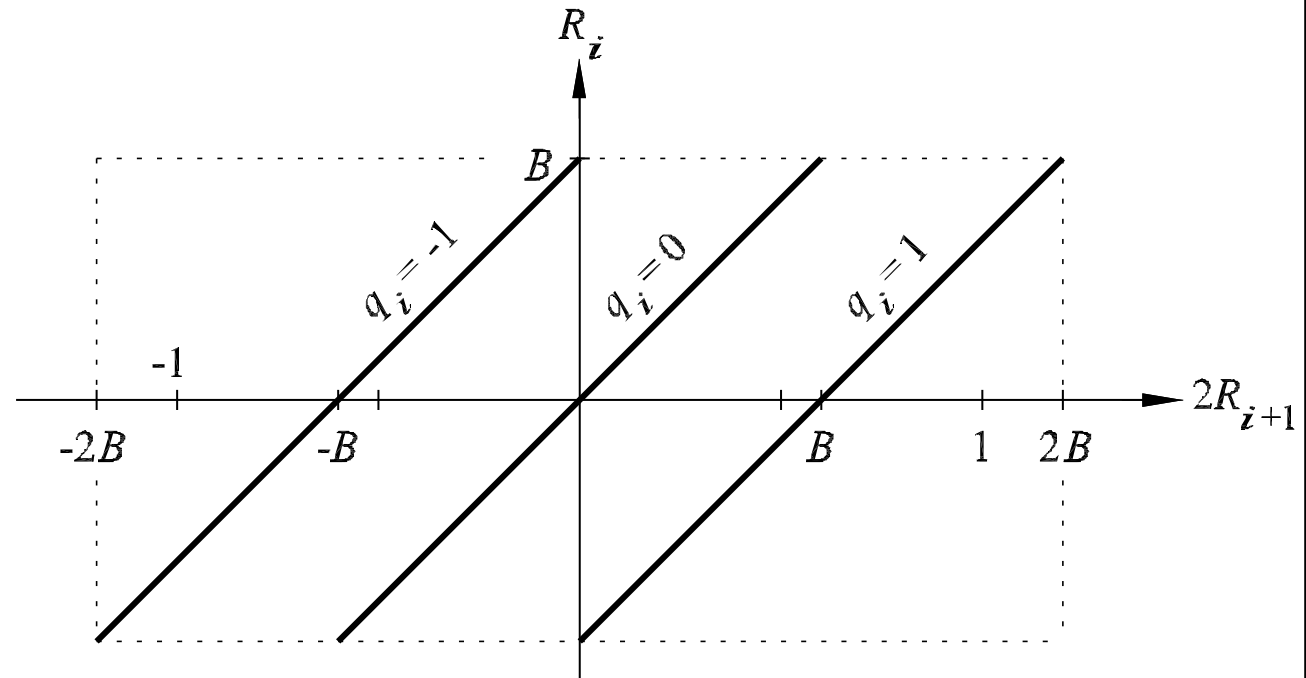
$$B = 0,110$$

$$Q = 1,\hat{1}10 = 0,111$$

$$R = -0,000\ 010$$

	0 1 0 1	$A \sim 2R_1$
$-B$	1 0 1 0	$q_0 = 1$
	0 <u>1 1 1 1</u>	R_0
	↓ ↓ ↓	
	1 1 1 0	
$+B$	0 1 1 0	$q_{-1} = -1$
	1 <u>0 1 0 0</u>	R_{-1}
	↓ ↓ ↓	
	1 0 0 0	
$-B$	1 0 1 0	$q_{-2} = 1$
	1 <u>0 0 1 0</u>	R_{-2}
	↓ ↓ ↓	
	0 1 0 0	
$-B$	1 0 1 0	$q_{-3} = 1$
	0 <u>1 1 1 0</u>	R_{-3}

using of redundant signed-digit numbers
(division without restoring):



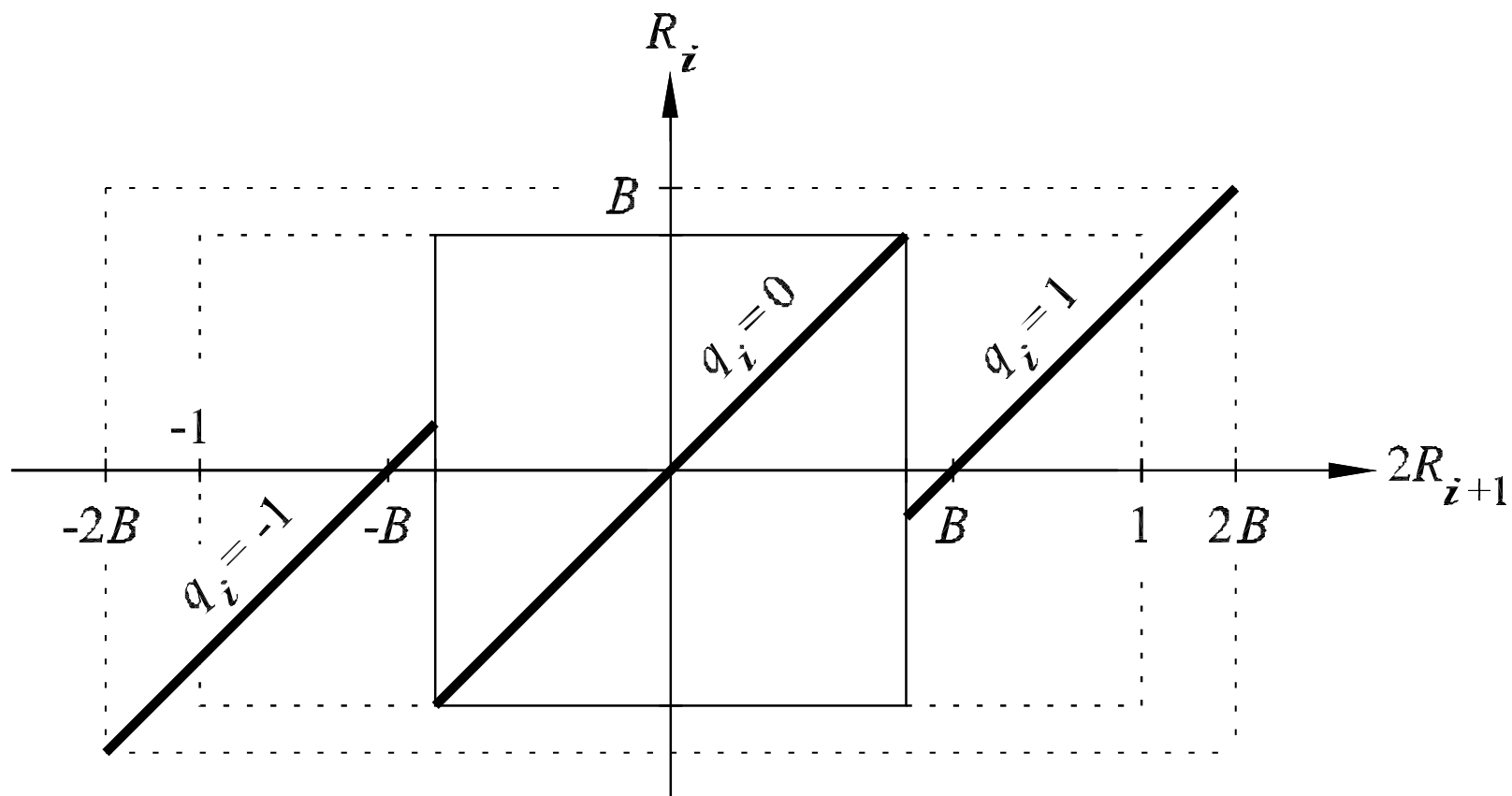
$B \in \langle 0, 5, 1 \rangle \Rightarrow$ condition

$2R_{i+1} \geq B$, resp. $2R_{i+1} \leq -B$,

can be replaced with condition

$2R_{i+1} \geq 0.5$, resp. $2R_{i+1} \leq -0.5$.

\Rightarrow First bits are enough for „correct“ selection.



ex.: $A = 0,101$

$B = 0,110$

$Q = 1,00\hat{1} = 0,111$

$R = -0,000\ 010$

comment

(Binary point is
before 3th bits
from right.)

$A > 1/2$

$R_0 = -1/8$

$2R_0 \in \langle -1/2, 1/2 \rangle$

$R_{-1} = -1/4$

$2R_{-1} \in \langle -1/2, 1/2 \rangle$

$R_{-2} = -1/2$

$2R_{-2} < -1/2$

	$0\ 1\ 0\ 1$	$A \sim 2R_1$
$-B$	$1\ 0\ 1\ 0$	$q_0 = 1$
	$0\ 1\ 1\ 1\ 1$	R_0
	$\downarrow\ \downarrow\ \downarrow$	
nic	$1\ 1\ 1\ 0$	$q_{-1} = 0$
	$\downarrow\ \downarrow\ \downarrow$	
nic	$1\ 1\ 0\ 0$	$q_{-2} = 0$
	$\downarrow\ \downarrow\ \downarrow$	
	$1\ 0\ 0\ 0$	
$+B$	$0\ 1\ 1\ 0$	$q_{-3} = -1$
	$0\ 1\ 1\ 1\ 0$	R_{-3}

Fraction extension

$$\frac{A}{B} = \frac{A_0}{B_0} = \frac{A_1}{B_1} = \frac{A_2}{B_2} = \frac{A_3}{B_3} = \dots \quad \begin{aligned} A_{i+1} &= A_i \cdot K_i \\ B_{i+1} &= B_i \cdot K_i \end{aligned}$$

$$A_0 = A \quad B_0 = B$$

$$B_i \rightarrow 1 \implies A_i \rightarrow \frac{A}{B}$$

$$\boxed{B = 1 - \delta} \quad \frac{1}{2} \leq B < 1 \implies 0 < \delta \leq \frac{1}{2}$$

$$B_i = 1 - \delta_i$$

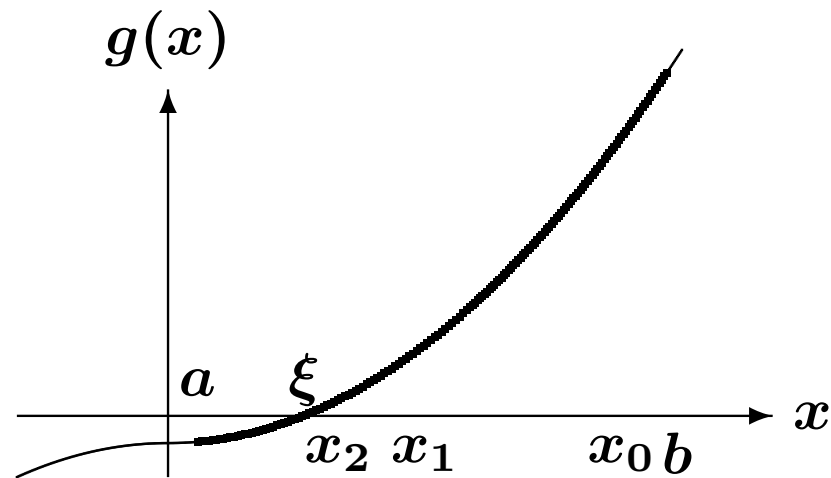
$$K_i = 1 + \delta_i = 2 - B_i \implies \boxed{K_i = \overline{B_i} + \varepsilon}$$

$$B_{i+1} = B_i \cdot K_i = (1 - \delta_i) \cdot (1 + \delta_i) \implies \boxed{B_{i+1} = 1 - \delta_i^2}$$

If $\delta_i \ll 1$ then double valid digits is obtained by each step.

Newton's method (method of tangent) [Newton – Raphson]

Observation:



Assumption: **The function $g(x)$ is gaining for interval $\langle a , b \rangle$ value 0**

(pro $x = \xi$) and it is continuous, growing and perfectly convex.

$$\begin{aligned} g'(x_0) &= \frac{g(x_0)}{x_0 - x_1} & \implies & x_1 = x_0 - \frac{g(x_0)}{g'(x_0)} \\ g'(x_1) &= \frac{g(x_1)}{x_1 - x_2} & \implies & x_2 = x_1 - \frac{g(x_1)}{g'(x_1)} \end{aligned}$$

Therefor

$$x_{i+1} = x_i - \frac{g(x_i)}{g'(x_i)}$$

for $i = 0, 1, 2, \dots$

Equation

$$g(x) = 0$$

has root in interval $\langle a, b \rangle$ namely, that is

$$\xi = \lim_{i \rightarrow \infty} x_i.$$

exactly — see next slide

If there exist such as a and $b > a$, that

- function $g(x)$ is continuous in interval $\langle a, b \rangle$ and has there continuous first derivation $g'(x)$ and continuous second derivation $g''(x)$,
- $g(a) \cdot g(b) < 0$,
- $(\forall x \in \langle a, b \rangle) \quad g'(x) \cdot g'(a) > 0$,
- $(\forall x \in \langle a, b \rangle) \quad g''(x) \cdot g''(a) > 0$ and
- $(\exists x_0 \in \langle a, b \rangle) \quad g(x_0) \cdot g''(x_0) > 0$,

the equation $g(x) = 0$ has only one root in $\langle a, b \rangle$, that is

$$\xi = \lim_{i \rightarrow \infty} x_i,$$

where

$$x_{i+1} = x_i - \frac{g(x_i)}{g'(x_i)}$$

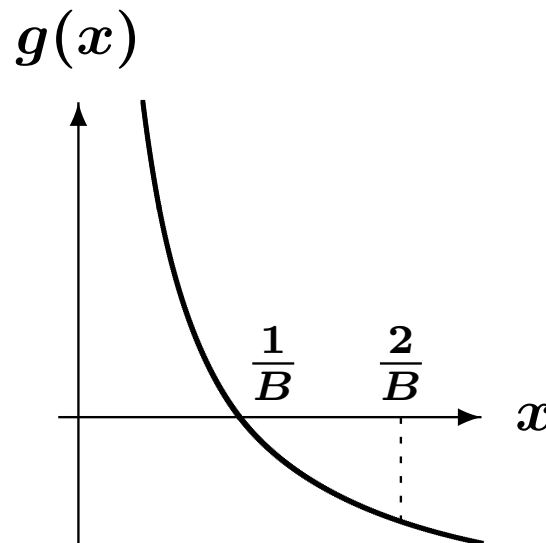
for $i = 0, 1, 2, 3, \dots$.

Conditions are sufficient but not necessary. The equation $g(x) = 0$ can have in interval $\langle a, b \rangle$ only one root, which can be determined with given procedure, also in a case, when some of conditions are not met.

$$\frac{A}{B} = A \cdot \frac{1}{B}$$

$\xi = \frac{1}{B}$ is a root of equation $\frac{1}{x} - B = 0$.

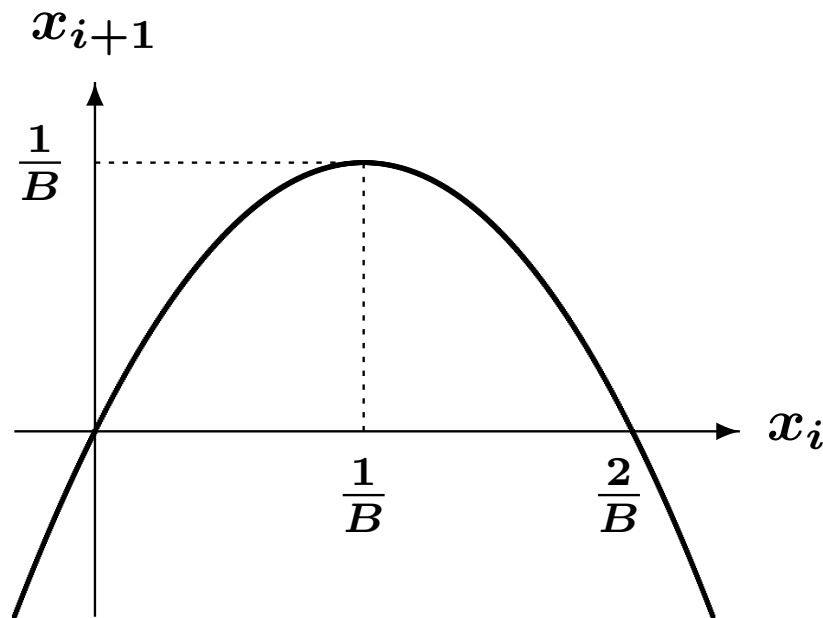
ξ is therefor a root of equation $g(x) = 0$, where
 $g(x) = \frac{1}{x} - B$, $g'(x) = -\frac{1}{x^2}$ a $g''(x) = \frac{2}{x^3}$.



Therefor $x_{i+1} = x_i - \frac{g(x_i)}{g'(x_i)} = x_i \cdot (2 - B \cdot x_i)$

and suit any $a \in (0, \frac{1}{B})$,
any $b \in (\frac{1}{B}, \infty)$ a
any $x_0 \in (0, \frac{1}{B})$.

Note.: It can be also used any $x_0 \in (\frac{1}{B}, \frac{2}{B})$



Calculation value of $\frac{1}{B}$

$$x_{i+1} = x_i \cdot (2 - B \cdot x_i)$$

normalized B : $\frac{1}{2} \leq B < 1 \implies 1 < \frac{1}{B} \leq 2$

$[\forall x_0 \in (0, 1)] \ x_0 \in (0, \frac{1}{B})$

speed of convergence:

$$x_i = \frac{1}{B} \cdot (1 - \delta) \implies x_{i+1} = \frac{1}{B} \cdot (1 - \delta^2)$$

$|\delta| \ll 1 \implies$ **double number of valid positions are obtained with each iteration**

It is suitable to choose x_0 so that, $|\delta|$ was as small as possible.

→ small table in memory ROM addressed by some of first bits B

Division in decimal system

Division can be converted on subtraction (or addition) and shifts.

ex.: 9 876 : 312 = ?

quotient = 31

remainder = 204

987		516	
<u>-312</u>		<u>-312</u>	
675	1	204	1
<u>-312</u>		<u>-312</u>	
363	2	-108	< 0
<u>-312</u>			
51	3		
<u>-312</u>			
-261	< 0		

It is also possible use division without restoring but it is not so advantageous such as in binary system (see next slide).

Division in decimal system ii

