Effective C++ Programming

NIE-EPC (v. 2021):

COSTS OF DYNAMIC ALLOCATIONS, ALIGNMENT, PADDING, PLACEMENT NEW, OWNING OBJECTS

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Runtime costs of dynamic allocations

- Statically and dynamically allocated objects differ only in the way how their storage is (de)allocated.
 - Initialization and destruction is the same.
- Dynamic allocations typically involve a heap a very complex mechanism that needs to be able to:
 - satisfy request for allocations of different sizes,
 - communicate with a kernel to ask for memory blocks (such as pages),
 - synchronize request in multi-threaded programs (which, generally, brings some overhead into single-threaded programs as well),
 - •
- ◆ ⇒ Allocation of the storage on the heap is a relatively complex task, when compared, for instance to allocation on the stack.
 - Recall allocation on the stack involves just decrementing the stack pointer register (which is "super-fast").

Runtime costs of dynamic allocs (cont.)

 Experiment — comparison of static and dynamic allocation of a storage for an object of type int:

```
// I. static allocation experiment:
int i = 1;
... // make sure storage for i is allocated in memory (on the stack)

// II. dynamic allocation experiment:
int* pi = new int(1);
... // make sure storage for *pi is allocated in memory (on the heap)
```

- Benchmark:
 - Used tool *Google Benchmark*, namely its online form *Quick C++ Benchmark*.
 - Repeated execution in the loop.
 - Relative comparison of the average time of a single iteration.
 - Link: https://quick-bench.com/q/d_ENZrzvO_jwby2Qy7bisugNVr8.
- Results:



• Dynamic allocation was 20-40× 5 OWEr than static allocation.

Memory costs of dynamic allocations

- Is slower performance the only drawback of dynamic storage allocation?
- Unfortunately, NO :(
- Another disadvantage memory overhead.
- Two causes:

1) Alignment:

Padding caused by alignment produces wasted memory bytes.

2) Housekeeping data:

- Heap needs some auxiliary data to be stored in memory for each allocation to keep track of them.
- Effect with typical heap implementations:
 - Each allocation even of a single byte consumes at least 32 bytes
 of memory on 64-bit systems.

Storage alignment

- Storage for an object (= each object) of type T needs to be aligned to alignof(T)-byte address.
 - Alignment to an N-byte address means alignment to an address A, where A=0 (modulo N).
- Alignment requirements for particular types are implementationdefined.
- Example GCC/Linux/x86_64:

```
std::cout << alignof( char</pre>
                                    ); // prints out
                                                         "1"
                                    ); // prints out
std::cout << alignof( int</pre>
                                                         "4"
std::cout << alignof( long</pre>
                                    ); // prints out
                                                         "8"
                               ); // prints out
std::cout << alignof( float</pre>
std::cout << alignof( double</pre>
                                 ); // prints out
                                                         "8"
std::cout << alignof( long double ); // prints out "16"</pre>
std::cout << alignof( void*</pre>
                                    ); // prints out
                                                         "8"
```

- Class types alignment requirements typically equal the maximum of alignment requirements for types of its subobjects.
- Note: Subobjects = non-static member variables and base class objects.

Storage alignment (cont.)

- Fundamental alignment (simplified definition):
 - Alignment less than or equal to the maximum alignment for "fundamental" language-intrinsic types.
 - Is equal to the alignof(std::max_align_t) expression.
 - In typical C++ implementations, it equals alignment requirements for the long double type:

- Over-aligned types:
 - Types with alignment requirements that are higher than the maximal fundamental alignment.
 - Exemplary use cases:
 - Cache line aligned data (efficiency reasons, avoiding false sharing,...)
 typically, 64-byte alignment.
 - SIMD-processed data (data processed by vectorization instructions), for example — AVX2 (32-byte alignment), AVX512 (64-byte alignment),...

Statically-allocated storage alignment

- How is alignment provided when a storage for an object is allocated?
- 1) Function non-static local variables (automatic storage duration) + typical stack-based implementation:
 - Recall storge allocation = decreasing stack pointer (SP) register.
 - How much it needs to be decreased?
 - For example, decreasing by 4 bytes does not guarantee that SP will point to a 4-byte aligned address.
 - Generally, calculation of a properly aligned address would need additional instructions.
 - This would impose into functions additional (static) allocation overhead.
- Common real-world solution of this problem:
 - ABI prescribes that when the function is executed, SP must point to an A-byte aligned address, where A is defined in that ABI.
 - Example Linux/x86_64 A = 16:
 - When the call instruction calls some function, RSP must be 16-byte aligned.

Statically-allocated storage alignment (cont.)

• Example:

```
void g(int*);
void f() {
  int i = 1;
  g(&i);
}
```

```
f():

push rax

mov dword ptr [rsp + 4], 1

lea rdi, [rsp + 4]

call g(int*)

pop rax

ret
```

- When the function f is called somewhere, rsp is guaranteed to be 16-bytes aligned \Rightarrow rsp = 0 modulo 16.
- The corresponding call instruction decreases rsp by 8 (it "pushes" the return instruction address to the stack).
 - \Rightarrow When the function f is started, rsp = 8 modulo 16.-
- Before g is called, rsp needs to be again 16-byte aligned.
 - \Rightarrow rsp needs to be decreased by another 8 bytes.
- Those 8 bytes are used for allocation of storage for i:
 - They are guaranteed to be 8-byte aligned, int requires 4-byte alignment.
 - \Rightarrow Storage for i can be allocated in upper 4 bytes or lower 4 bytes.
 - In our case, compiler decided to use the upper 4 bytes (rsp+4).
 - Lower 4 bytes will remain unused (wasted).

Statically-allocated storage alignment (cont.)

Modified example:

```
void g(long*);
void f() {
   long i = 1;
   g(&i);
}
```

```
f():
   push rax
   mov qword ptr [rsp], 1
   mov rdi, rsp
   call g(long*)
   pop rax
   ret
```

- Storage for an object of type long takes 8 bytes and requires 8byte alignment ⇒ there are no bytes wasted.
- Summary:
 - Thanks to the ABI-required stack pointer alignment when functions are called, (static) allocations of storage for function-local variables can be performed extremely efficiently namely, by decreasing stack pointer.
 - This holds for all non-over-aligned types.
 - For over-aligned types, some additional calculation at runtime is still needed (for instance, 16-byte alignment may or may not be 32-byte aligned at the same time).

Dynamically-allocated storage alignment

- How is alignment provided when a storage for an object is allocated (cont.)?
- 2) Dynamically-allocated objects (*dynamic storage duration*) + typical heap-based implementation:
 - Recall storge allocation = calling some heap allocation function (through operator new C++ allocation function).
 - Typically, malloc is used.
- malloc takes a single argument number of allocated bytes.
 - $\bullet \Rightarrow$ It allows a caller to specify the storage (byte) size :).
 - ullet \Rightarrow It does not allow a caller to specify alignment requirements :(.
- Common real-world solution of this problem:
 - Each dynamically-allocated block of memory is guaranteed to be aligned at least to the maximal fundamental alignment.

Dynamically-allocated storage alignment (cont.)

- Our *Linux/x86_64* system:
 - Heap implementation is (by default) provided by GNU C library (GLIBC).
 - This is a common case in Linux.
 - Maximum fundamental alignment alignof(std::max_align_t) is 16.
 - Accordingly, malloc-allocated memory blocks are guaranteed to be 16-byte aligned.
 - Note heap implementations may guarantee even higher/stronger alignment (for details, see __STDCPP_DEFAULT_NEW_ALIGNMENT__ C++ macro).
- What about over-aligned types?
 - Since C++17, operator new has overloaded versions where alignment requirements may be specified.
 - Internally, other function than malloc needs to be used by a C++ standard library implementation (such as the posix_memalign allocation function).
 - Before C++17, there was no portable way to dynamically-allocate storge for over-aligned types.

Memory costs of dynamic allocations (cont.)

- Consequences (our platform):
 - All dynamic allocations are 16-byte aligned.
 - ⇒ Even if a storage for an object of some type requires only 1 byte, its dynamic allocation will effectively consume 16 bytes.
 - The remaining bytes are wasted.
- Moreover, heap implementations require for each allocation some housekeeping data ⇒ additional memory overhead.
 - In our case, these data take another 16 bytes per allocation.
- Experiment:

```
void g(int*);  // NOOP function defined in another TU
int main() {
  for (int i = 0; i < 100'000'000; i++) {
    int* pi = new int{};
    g(pi);
} }</pre>
```

- "Effective data" = 100M objects of type int ⇒ 400M bytes of storage.
- Measured memory consumption (maximum RSS): 3200M bytes.
- ⇒ Each allocation consumes 32 bytes:
 - 4 effective bytes (storage of int object), 12 bytes wasted, 16 bytes housekeeping.

Intermezzo — padding

- Previous observation alignment can cause wasted bytes in memory in case of both:
 - static storage allocation (on the stack),
 - dynamic storage allocation (on the heap).
- These bytes are out of the allocated storage itself.
- Alignment requirements can cause wasted bytes even inside storage of a single object:
 - In the storage of a class type object, its *subobjects* are stored (base class objects and non-static member variables).
 - Due to alignment requirements, they may not be store next to each other in memory.
 - "Gaps" between subobjects are referred to as padding.
 - Padding represents wasted bytes inside the storage of a single object.

Intermezzo — padding (cont.)

Example — Clang/x86_64/Linux:

```
struct X { void* v; char c; int i; float f; };
```

- Storage for an object of type X starts at address A.
- X::v requires 8-byte aligned storage, which is 8 bytes long.
 - \Rightarrow A is 8-byte aligned.
 - \Rightarrow X::v is stored from address A to A + 7.
- X::c requires 1-byte aligned storage, which is 1 byte long.
 - \Rightarrow X::c is stored at address A + 8 only.
- X::i requires 4-byte aligned storage, which is 4 byte long.
 - \Rightarrow X::i cannot be stored next to X::c at address A + 9; this address is not 4-byte aligned.
 - \Rightarrow The lowest 4-byte aligned address where X::i may be stored is A + 12.
 - \Rightarrow X::i is stored from address A + 12 to A + 15.
 - Bytes from A + 9 to A + 11 represent padding (are wasted).
- X::f requires 4-byte aligned storage, which is 4 byte long.
 - \Rightarrow X::f is stored from address A + 16 to A + 19.

Intermezzo — padding (cont.)

```
struct X { void* v; char c; int i; float f; };
```

- Previous analysis: Subobjects member variables X::v, X::c,
 X::i, and X::f are stored at addresses A to A + 19.
- If two objects of type X are stored in an array next to each other, and the first one is stored at address A, is the next element stored at A + 20? NO!
 - Its first member X::v needs to be 8-byte aligned.
 - \Rightarrow The lowest available 8-byte aligned address higher than A+19 is A+24.
- Those 4 wasted bytes from A + 20 to A + 23 at the end also represent padding.
 - Even this final padding is a part of a binary representation of X.
 - \Rightarrow These 4 bytes are part of the storage for each object of type X.
- Proof:

```
std::cout << sizeof(X); // prints out 24</pre>
```

Storage of X consists of 17 data bytes and 7 padding bytes.

Intermezzo — padding (cont.)

- *C++ rule:*
 - Class member variables with same access rights (*private*, *protected*, *public*) must be stored at growing addresses in order of their declaration.
 - ⇒ Implementation may not reorder their placement in the storage of the class object.
- → Padding may be sometimes reduced by "better" order of (non-static) member variable declarations.
- Example:

```
struct Y {
  char c;
  int i;
  bool b;
  float f;
};

std::cout << sizeof(Y); // prints out 16

struct Z {
    char c;
    bool b;
    int i;
    float f;
};

std::cout << sizeof(Z); // prints out 12</pre>
```

Static vs dynamic allocations

- Summary in comparison with static allocations, allocation of storage for dynamically-allocated objects:
 - is much slower,
 - consumes much more memory.
- Efficiency with collection of objects:
 - = objects stored in dynamic data structures.
 - C++ standard library defines different types of such data structures called containers.
 - Comparison of containers with respect to the number of required allocations for insertion of n objects:
 - std::vector without reserving space $\rightarrow \log(n)$,
 - std::vector with reserving space $\rightarrow 1$,
 - std::list $\rightarrow n_i$
 - std::set or std::map $\rightarrow n_1$
 - std::unordered_set or std::unordered_map $\rightarrow n + \log(n)$.

Static vs dynamic allocations (cont.)

Experimental evaluation:

- Comparison of time and memory consumption when the same number of objects is inserted into different C++ library containers.
- Measurements are *normalized* to the case where a vector was used without reserving memory.

container	time	memory (RSS)
std::vector "as-is" (baseline)	1	1
std::vector + reserve	2.8× faster	1.3× lower
std::list	17× slower	5.9× higher
std::set	95× slower	8.9× higher
std::unordered_set	46× slower	7.4× higher

• Analysis:

- Vector is so efficient since it allocates storage for multiple objects (its elements) at once.
- All other containers are node-based each new element requires
 allocation of a separate storage for a single node, in which it is then stored.

Static vs dynamic allocations (cont.)

- Vector stores its elements contiguously in memory.
- Nodes are placed in memory at unrelated locations.
- ⇒ Vector provides efficient element access.
- Vector vs set/map:
 - Set/map = binary search tree $\Rightarrow O(\log(n))$ lookup time.
 - Sorted vector with binary search $\Rightarrow O(\log(n))$ lookup time as well.

container	insertion (+sort)	lookup
std::vector "as-is" (baseline) + sorting	1	1
std::vector + reserve + sorting	1.2× faster	1
std::set	16× slower	2.1× slower
std::unordered_set	7.3× slower	4.6× faster

- Fastest lookup provides unordered set = hash table.
 - $\Rightarrow O(1)$ lookup time.
 - At a price of significantly slower data structure construction and higher memory consumption.

Placement new

- Up to now, all mechanisms we have seen for both static and dynamic object allocations automatically "attached":
 - storage allocations together with object initialization,
- and:
 - object destruction together with storage deallocation.
- Vector container:
 - Allocates storage for multiple objects (its elements) at once.
 - → Needs to "detach" storage allocation from object initialization (as well as object destruction from storage deallocation).
- How can this be done in C++?
 - For storage (de)allocation alone, we have (de)allocation functions
 operator new and operator delete.
 - ⇒ What we need is to initialize object in this storage (uninitialized memory), and in the end to destruct it.

- Vector highly complex data structure.
- Simpler case for the sake of explanation:
 - Optional object existence object that optionally may or may not exist at runtime.
- In case of dynamically-allocated object, the solution is simple:
 - A pointer itself can contain information whether the object exist or not:

```
int* pi = (some_condition == true) ? new int(1) : nullptr;
```

Or, better:

```
std::unique_ptr<int> pi = (some_condition == true) ? new int(1) : nullptr;
```

- But what if we want to achieve the same without the overhead of dynamic storage allocation?
- ⇒ We need optional object initialization in a staticallyallocated storage.

Class wrapper for such an optionally existing object:

```
class optional_int {
    ??? buffer_[ ??? ];
    bool exist_;
public:
    optional_int() : exists_(false) { }
    optional_int(int i) : exists_(true) { ??? }
    operator int&() { return ???; }
};
```

- Storage for optional object is a class member variable.
 - \Rightarrow It is a part of the storage of the class object itself.
 - \Rightarrow No need to dynamically allocate it.
- This storage needs to be:
 - Large enough to hold an object of type int \Rightarrow sizeof(int) bytes long.
 - Aligned suitably to hold an object of type int ⇒ alignof(int) bytealigned.

- Such storage can be provided as a buffer of a form of an array, which:
 - is aligned to alignof(int)-byte address,
 - 2) has type of elements unsigned char or std::byte (since C++17),
 - 3) has sizeof(int) elements.

```
class optional_int {
    alignas(int) unsigned char buffer_[ sizeof(int) ];
    bool exist_;
public:
    optional_int() : exists_(false) { }
    optional_int(int i) : exists_(true) { ??? }
    operator int&() { return ???; }
};
```

- Such a storage is now suitable to hold an object of type int.
- Next, we need to:
 - Construct (=initialize) such an object in this storage (buffer).
 - Provide access to it (to allow its update and reading).

- Initialization of an object in existing storage = placement new.
 - Another form of new.
 - Basically, it is a new expression with an additionally provided pointer as its "argument".

```
class optional_int {
  alignas(int) unsigned char buffer_[ sizeof(int) ];
  bool exist_;
public:
  optional_int() : exists_(false) { }
  optional_int(int i) : exists_(true) { new (buffer_) int(i); }
  operator int&() { return ???; }
};
```

- Placement new initializes an object:
 - in memory at the address passed as a pointer,
 - of the specified type,
 - by initialization expression the same way as for "ordinary" (nonplacement) new expression.

- Object access:
 - There is no direct access (through some name/identifier).
 - But we know, where it is stored ⇒ we can derive its pointer (a pointer-to-this-object).
 - buffer_ is an array ⇒ is implicitly convertible to a pointer-tounsigned char.
 - We need a pointer-to-int.
 - \Rightarrow Solution = cast (conversion) of these pointers:

```
class optional_int {
  alignas(int) unsigned char buffer_[ sizeof(int) ];
  bool exist_;
  int* ptr() { return reinterpret_cast<int*>(buffer_); } // helper function
public:
  optional_int() : exists_(false) { }
  optional_int(int i) : exists_(true) { new (buffer_) int(i); }
  operator int&() { return *ptr(); }
};
```

 Note: since the operator int&() returns a reference to the stored object, the casted pointer is dereferenced.

Object destruction:

- Placement new initializes an object starts its lifetime.
- How to end this lifetime?
- Is there any "placement delete"? No.

Two different cases:

- Class types objects lifetime needs to be ended explicitly by calling their destructors.
- 2) Non-class types objects lifetime ends automatically when their storage is deallocated.
- int belongs to ad 2)
 - No explicit action is needed for destruction of the object initialized by placement new.
 - ⇒ The class optional_int does not require manual definition of a destructor (it is auto-generated).
- What about ad 1) cases?

Class wrapper for such an optionally existing class object:

```
struct X {
    X(int);
    ~X();
};

class optional_X {
    alignas(X) unsigned char buffer_[ sizeof(X) ];
    bool exist_;
    X* ptr() { return reinterpret_cast<X*>(buffer_); }

public:
    optional_X() : exists_(false) { }
    optional_X(int i) : exists_(true) { new (buffer_) X(i) }
    operator X&() { return *ptr(); }
    ~X() { if (exist_) ptr()->~X(); }
};
```

- Placement new initializes an object of type X ⇒ it calls its constructor.
- If the object was (optionally) initialized, then must be explicitly destructed by calling its destructor.
 - Destructor can be called as any other member function.

Comparison of non-class (int; left) and class (X; right) cases:

```
optional_int::optional_int(int):
   mov BYTE PTR [rdi+4], 1
   mov DWORD PTR [rdi], esi
   ret

optional_int::~optional_int():
   ret
```

```
optional_X::optional_X(int) :
   mov BYTE PTR [rdi+1], 1
   jmp X::X(int) 

optional_X::~optional_X() :
   cmp BYTE PTR [rdi+1], 0
   jne .L10
   ret
.L10:
   jmp X::~X()
```

Non-class case:

- Initialization of an object of type int requires just setting its memory representation to a desired value (value of constructor argument passed in the esi register).
- Destruction does not require any action.

2. Class case:

- Initialization of an object of type X requires calling its constructor.
- Destruction requires calling its destructor. -

Problem with explicit destructor call:

```
class optional_string {
  alignas(std::string) unsigned char buffer_[ sizeof(std::string) ];
  bool exist_;
  std::string* ptr() { return reinterpret_cast<std::string*>(buffer_); }
public:
  optional_string() : exists_(false) { }
  optional_string(char* s) : exists_(true) { new (buffer_) std::string(s) }
  operator std::string&() { return *ptr(); }
  ~optional_string() { if (exist_) ptr()->~string(); } // compilation error
};
```

- std::string = a type alias for an instance of std::basic_string<char> class template.
- \Rightarrow There is no destructor named \sim string().
- → The destructor is called ~basic_string().

```
~X() { if (exist_) operator X&().~basic_string(); } // OK
```

- Generally, this is a problem, if we do not know whether some type is a type name or a type alias.
- First possible solution templates:

```
template <typename T>
class optional {
  alignas(T) unsigned char buffer_[ sizeof(T) ];
  bool exist_;
  T* ptr() { return reinterpret_cast<T*>(buffer_); }
  public:
    optional() : exists_(false) { }
    ??? // constructor - to be explained later
    operator T&() { return *reinterpret_cast<T*>(buffer_); }
    ~optional() { if (exist_) operator ptr()->~T(); }
};
```

- Generic solution will work for any type (template argument).
- For class types, correct destructor name is "encoded" in ~T() call;
- For non-class types, there is no destructor, such as ~int().
 - In such case, ~T() call is valid, but will have no effect.
 - This mechanism is called pseudo-destructor call and allows us to write unified generic code where objects need to be explicitly destructed.

Teaser — perfect forwarding

- How to write a constructor of optional?
- Constructors of T may take any number of arguments having different types and different value categories.
- ⇒ We need a constructor of optional class that will:
 - take any number of argument of any types and any value categories,
 - and "pass" them as-they-are to the constructor of T.
- This can be solved by combining three fundamental modern C++ techniques:
 - variadic templates,
 - forwarding references,
 - std::forward function,
- which is together called perfect forwarding.
- More: later lectures.

```
template <typename T>
class optional {
    ...
    template <typename Ts...>
    optional(Ts&&... args) : exists_(true)
    {
        new (buffer_) T(std::forward<Ts>(args)...)
    }
    ...
};
```

Second possible solution: std::destroy_at() library function:

```
~optional_string() {    if (exist_) std::destroy_at(ptr());  }
```

- std::destroy_at() is a function template.
- It derives the type name (template parameter T) from the type of the passed pointer (template argument deduction).
 - Internally, it calls it destructor as ~T().
- Advantage the code is more readable and explicit.
- Counterpart of std::destroy_at is std::construct_at:

```
optional_string(char* s) : exists_(true) {
   std::construct_at<std::string>(ptr(), s);
}
```

- Internally, it constructs an object with placement new:
 - its template argument represents a type of the constructed object,
 - its first function argument is a pointer to the storage,
 - all other function arguments are perfectly forwarded to the initializer.
- Availability: std::destroy_at C++17, std::construct_at C++20.

- Using standard library improves readability and understandability of code; seen examples:
 - placement new vs std::construct_at,
 - explicit destructor call vs std::destroy_at.
- Another useful replacement from the standard library for our optimal class — std::aligned_storage.
 - Class (struct) template, which member type "type" provides a type of storage that is aligned to the desired value and have desired length.
 - Length and alignment are specified as template arguments.

```
alignas(T) unsigned char buffer_[ sizeof(T) ];
```

can be replaced by:

```
typename std::aligned_storage<sizeof(T), alignof(T)>::type buffer_;
```

or, since C++14, by:

```
std::aligned_storage_t<sizeof(T), alignof(T)>::type buffer_; // shortcut
```

optional class in C++20 with library entities:

```
template <typename T>
class optional {
    std::aligned_storage_t<sizeof(T), alignof(T)> buffer_;
    bool exist_;
    T* ptr() { return reinterpret_cast<T*>(buffer_); }
public:
    optional() : exists_(false) { }
    template<typename... Ts>
    optional(Ts&&... args) : exist_(true) {
        std::construct_at<T>(ptr(), std::forward<Ts>(args)...); }
    operator T&() { return *ptr(); }
    ~optional() { if (exist_) std::destroy_at(ptr()); }
};
```

- Such a class template in a more sophisticated form is available in the C++ standard library itself since C++17 as std::optional<T>.
- Common use case optional returning an object from a function:

- Drawback of (3) vs (1):
 - An optional class needs a flag with the information about whether it does or does not "hold" an object.
 - This flag, for example, controls destruction.

```
template <typename T>
class optional {
  bool exist_;
  ...
  optional() : exists_(false) { }
  template<typename... Ts> optional(Ts&&... args) : exist_(true) { ... }
  ~optional() { if (exist_) std::destroy_at(ptr()); }
};
```

- Boolean flag generally requires only 1 byte.
- However, due to alignment requirements, there may be some padding introduced.
- Flag + padding represent "housekeeping" memory overhead:

```
std::cout << sizeof( std::string );  // prints out 32
std::cout << sizeof( std::optional<std::string> );  // prints out 40 (+1B flag, +7B padding)
```

"Owning" objects — "owners"

- An object of type std::optional<T> a "wrαpper" that (optionally) "owns/manages" an object of type T.
 - ⇒ The "content" of std::optional
 object of type T.
- The same holds, for instance, for an object of type std::unique_ptr<T>.

```
std::optional< std::string > os( "..." );
std::unique_ptr< std::string > us( new std::string( "..." ) );
```

- Further assumption stack/heap-based C++ implementation.
- Difference between optional and unique_ptr:
- unique_ptr the storage of the owned object is allocated dynamically.
 - $\bullet \Rightarrow$ The owned object itself is stored on the heap.
- optimal the storage of the owned object is "included" in the storage of the owning (optimal) object itself.
 - ⇒ For instance, if the optimal object is stored on the stack, so is also the owned object.

"Owners" (cont.)

- Physical ownership owned object is stored in the storage of its owner (= included storage).
- Logical ownership owner takes care about owned object(s)
 (manages lifetime etc.).
- std::optional<T> both *physical* and *logical* ownership:
 - Object is, for example, initialized and destructed by its optional owner.
 - Included storage example with GCC/x86_64:

- \Rightarrow The owner oi is stored on the stack, so is the owned object.
- ⇒ Storage size of the optional owner depends on the storage size of the owned object.

"Owners" (cont.)

- std::unique_ptr<T> logical ownership only:
 - Object is, for example, destructed by its unique_ptr owner.
 - Dynamically allocated storage:

```
std::unique_ptr<int> ui(new int(1));
std::cout << &ui; // address of owner: "0x7ffe276c8450"
std::cout << &*ui; // address of owned: "0x23faec0"</pre>
```

- ⇒ The owner ui is stored on the stack, but the owned object is stored on the heap.
- ⇒ Storage size of the unique_ptr owner does not depend on the storage size of the owned object.

 Note: std::unique_ptr<T> is typically implemented as a wrapper of the raw pointer member variable of type T*.

"Owners" (cont.)

- C++ standard library provides multiple generic "owner" types.
- Some single-object owners...
 - ...with included storage:
 - std::optional<T>, std::variant<T1,T2,...>;
 - ...with dynamically-allocated storage:
 - std::unique_ptr<T>, std::shared_ptr<T>, std::any.
- Some multiple-object owners...
 - ...with *included storage*:
 - std::pair<T1,T2>, std::tuple<T1,T2,...>, std::array<T,N>;
 - ...with dynamically-allocated storage:
 - dynamic containers std::vector<T>, std::list<T>, std::set<T>,...
- What about std::string?
 - An object of type std::string can handle/own a string of characters of any length, generally unknown at compile time.
 - \bullet \Rightarrow ? Must the string of characters be stored in dynamically-allocated storage?

Owners — std::string case

Experiment — Clang/x86_64/libc++:

- Observation:
 - The owner s is stored on the stack.
 - The string of characters "..." managed/owned by s is stored also on the stack.
 - Namely, it is stored in the included storage of its owner s.
- Similar experiment:

- Observation:
 - Now, the string of characters "... some different string ..." is stored
 on the heap (in a dynamically allocated storage).
- Explanation see next presentation.