# Reverse Engineering

2. Introduction into Reverse Engineering II.

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# Breaking a Function into Basic Blocks

With stack pointer analyzed and local variables identified, we can start analyzing the code flow to reconstruct at first a Code Flow Graph (CFG) and later higher level constructs such as **if-then-else** and loops **do-while/for/while**.

Creating a CFG starts by breaking the code into basic blocks.

# Basic Block [MIE-GEN]

Basic Block (BB) is the maximal sequence of consecutive instructions where the flow of control can only enter and can only leave the block through the first instruction and the last instruction of the block, respectively.

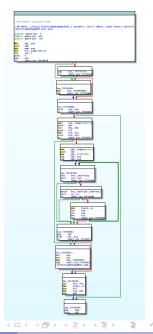
# Constructing a Code Flow Graph

Once we have a function divided into basic blocks, we can construct a Code Flow Graph (CFG), where:
each BB is a vertex;

- code flow is denoted by oriented edges between BBs.

CFG gives us an initial higher-level insight into the function being analyzed.

CFG serves as one of the inputs into a decompiler, which tries to recognize known patterns and reconstruct high-level code. Creating CFG is not always a straightforward task, especially if obfuscation techniques are used (eg. Opaque Predicates).



# If-statements I

#### Without a CMP/TEST Instruction

This is the easiest case of a conditional jump. The statement being analyzed looks like this:

```
Assembly Pseudo Code
    if (condition)
                                            arithmetic ops calculating the condition
       expression;
                                            jxx skip_away
                                            expression
                                          skip_away:
77e3c798 kernel32!StringCbPrintfW
77e3c798 mov edi, edi
                             // A 2-byte NOP for hot patching
77e3c79a push ebp
77e3c79b mov ebp, esp
77e3c79d mov ecx, [ebp+c]
                           // Load 2nd parameter into ECX
77e3c7a0 shr ecx, 1
                             // Divide unsigned by 2, set ZF and CF
77e3c7a2 push 0
77e3c7a4 pop eax
// The shr instruction sets/clears ZF in EFL if the result is/isn't zero
// Push and pop do not manipulate flags in EFL
77e3c7a5 jz short loc_77e3c7e5
77e3c7e5 mov
             eax, 80070057h
                           // HRESULT FROM WIN32( ERROR INVALID PARAMETER )
77e3c7ea jmp
             short loc_77e3c7af
```

# If-statements II

#### With a CMP/TEST Instruction

This statement is the same as the previous one, except that is uses a cmp instruction to set flags in the EFL register.

```
if (condition)
  expression;
```

```
77e3c798 kernel32!StringCbPrintfW
77e3c7a0 shr ecx, 1
77e3c7a2 push 0
77e3c7a4 pop eax
77e3c7a5 jz short loc_77e3c7e5
// The cmp instruction sets flags, based on the comparison result
```

short loc\_77e3c7e5

short loc\_77e3c7af

77e3c7a7 cmp ecx, 7fffffffh

77e3c7e5 mov eax, 80070057h

77e3c7ad ja

77e3c7ea jmp

# Assembly Pseudo Code

```
arithmetic ops calculating the condition
  cmp instr. sets flags based on the condition
  jxx skip_away
  expression
skip_away:
```

// HRESULT FROM WIN32( ERROR INVALID PARAMETER )

#### If-then-else statements

This statement is the same as the previous one, except that it adds an alternative branch.

```
if( condition )
  expression1;
else
  expression2;
```

#### Assembly Code 77e2a8cd kernel32!UIntPtrToInt 77e2a8cd mov edi. edi 77e2a8cf push ebp 77e2a8d0 mov ebp, esp 77e2a8d2 mov eax, [ebp+8] 77e2a8d5 cmp eax, 7fffffffh 77e2a8da ja loc\_77e5547c 77e2a8e0 mov ecx, [ebp+c] 77e2a8e3 mov [ecx], eax 77e2a8e5 xor eax, eax // Fall thru 77e2a8e7 loc 77e2a8e7: 77e2a8e7 pop ebp 77e2a8e8 retn 8 77e5547c loc\_77e5547c: 77e5547c mov eax, [ebp+c] dword ptr [eax], Offffffffh 77e5547f or 77e55482 mov eax, 80070216h // HRESULT\_FROM\_WIN32( ERROR\_ARITHMETIC\_OVERFLOW )

77e55487

imp loc 77e2a8e7 // Jump back

# Loops I

# While Loop

#### C

while( condition )
 body;

# Assembly Code 00401561 push ebp 00401562 mov ebp,esp

```
00401564 loc_0401564:
00401564
           mov
                   eax, dword ptr [ebp+c]
00401567
                   ecx, byte ptr [eax]
           movsx
                   ecx,ecx // Test the condition
0040156a
           test
0040156c
           jе
                   loc_040158c // Jump after the loop if failed
                   edx, dword ptr [ebp+8]
0040156e
           mov
                   eax, dword ptr [ebp+c]
00401571
           mov
00401574
                   cl.byte ptr [eax]
           mov
00401576
           mov
                   byte ptr [edx],cl
00401578
                   edx, dword ptr [ebp+8]
           mov
0040157b
           add
                   edx.1
                   dword ptr [ebp+8],edx
0040157e
           mov
                   eax, dword ptr [ebp+c]
00401581
           mov
00401584
           add
                   eax,1
                   dword ptr [ebp+c],eax
00401587
           mov
0040158a
           jmp
                   loc_0401564 // Perform next iteration
0040158c loc 040158c:
0040158c
           pop
                   ebp
00401584
           ret
```

# Loops II

#### Do-while Loop

```
do {
  body;
} while(condition);
```

```
Assembly Code

00401340 mov edx,dword ptr [esp+4]
00401344 mov eax,dword ptr [esp+8]
00401348 loc_0401348:
00401348 movzx ecx,byte ptr [eax]
0040134b lea eax,[eax+1]
```

loc\_0401348h // Perform next iteration

// Test the condition

Note that this function does not create a stack frame. The parameters are referred to directly using the ESP register. This approach produces a code which is both smaller and faster, but note that each push instruction changes the offset of parameters and local variables on the stack.

byte ptr [edx],cl

movzx ecx, byte ptr [eax-1]

cl.cl

Omission of stack frames can be achieved at compile time by setting -fomit-frame-pointer GCC flag, or /Oy MSVC flag.

0040134e

00401350

00401354

00401356

00401358

mov

test

jne

ret.

# Loops III

For Loop

```
for(
  initialization;
  condition:
  increment
```

body;

```
Assembly Code
00401280
                  ecx, dword ptr [esp+4]
           mov
00401284
                  eax.eax
           Yor
                  ecx.ecx
                                    // Enter the loop?
00401286
           test
00401288
                  loc_040129c
                                    // No - jump after it
           jle
0040128a
                  ebx.[ebx]
           lea
00401290 loc 0401290:
00401290
                  dword ptr [eax*4+403020h].eax
           mov
                                    // Perform the increment
00401297
           inc
                  ear
00401298
                  eax,ecx
                                    // Test the condition
           cmp
0040129a
           il
                  loc 0401290
                                    // Perform next iteration
0040129c loc 040129:
c0040129c ret
```

The for statement can be used with any part empty. This effectively allows us to construct a while loop by omitting both the initialization and the increment. The generated code would then be the same as in case of the while loop; for this reason it is not possible to determine whether the original code used for or while. The decompiler usually sticks to only one of them.

# Switch I

using sub/dec

```
switch( arg ) {
  case 1:
    statement 1:
    break;
  case 2:
    statement_2;
    break:
  case 4:
    break:
  default:
    statement n:
    break;
```

#### Assembly Code

```
00401000
                  eax, [ebp+8]
           mov
00401004
           dec
                  eax
00401005
           jz
                  short loc 401042
00401007
           dec
                  eax
00401008
                  short loc 401031
           iz
0040100A
           sub
                  eax. 2
0040100D
                  short loc 401020
           jz
0040100F
                  offset defaultCase
           push
00401014
           call
                  ds:printf
0040101A
           add
                  esp, 4
0040101D
                                    // return 0, duplicated
           xor
                  eax, eax
                                    // Function exit, duplicated
0040101F
           retn
                  offset threeParameters
00401020
           push
00401025
           call
                  ds:printf
0040102B
           add
                  esp. 4
0040102E
                  eax. eax
                                    // return 0, duplicated
           xor
00401030
           retn
                                    // Function exit, duplicated
00401031
           push
                  offset oneParameter
00401036
           call
                  ds:printf
0040103C
           add
                  esp, 4
                                    // return 0, duplicated
0040103F
           xor
                  eax, eax
00401041
           retn
                                    // Function exit, duplicated
00401042
           push
                  offset noParameter
00401047
           call
                  ds:printf
0040104D
           add
                  esp. 4
                                    // return 0, duplicated
00401050
                  eax. eax
           xor
00401052
                                    // Function exit, duplicated
           retn
```

# Switch II

using cmp instruction

# switch( arg ) { case 1: statement\_1; break; case 2: statement\_2; break; case 3: statement\_3; break; case 4:

statement 4:

statement\_n;

break:

break;

default:

}

# Assembly Code

```
8048389
                   0x8(%ebp), %eax // Load arg. into EAX
           mov
804838c
           cmp
                   $0x2, %eax
804838f
           jе
                   0x80483df
8048391
                   0x80483c0
           jle
8048393
           cmp
                   $0x3, %eax
8048396
           ie
                   0x80483b2
8048398
                   $0x4, %eax
           cmp
804839b
           nop
804839c
           lea
                   0x0(%esi,%eiz,1),%esi
80483a0
           jne
                   0x80483d1
80483a2
                   $0x8048595, (%esp)
           movl
80483a9
           call
                   0x8048350 <puts@plt>
80483ae
                   %eax,%eax
                                     // Return 0:
           xor
80483b0
           leave
80483b1
           ret
80483b2
           movl
                   $0x8048589, (%esp)
80483b9
           call
                   0x8048350 <puts@plt>
80483he
           dmi
                   0x80483ae
                                     // Dec/sub instruction commonly used!
80483c0
           dec
                   %eax
80483c1
                   0x80483d1
           jne
80483c3
                   $0x8048570,(%esp)
           movl
80483ca
           call
                   0x8048350 <puts@plt>
80483cf
           jmp
                   0x80483ae
80483d1
           movl
                   $0x80485a1,(%esp)
8048348
           call
                   0x8048350 <puts@plt>
8048344
           jmp
                   0x80483ae
80483df
           movl
                   $0x804857e,(%esp)
                   0x8048350 <puts@plt>
80483e6
           call
80483eb
           jmp
                   0x80483ae
```

# Switch III

#### using table

```
switch( arg ) {
  case 1:
    statement_1;
    break;
  case 2:
    statement_2;
    break:
  case 3:
    statement_3;
    break:
  case 4:
    statement 4:
    break;
  default:
    statement n:
    break;
```

#### Jump Table

```
00401068 dd offset loc_401011
0040106C dd offset loc_401022
00401070 dd offset loc_401033
00401074 dd offset loc_401044
```

#### Assembly Code

```
00401000
                  eax, [ebp+8]
           mov
00401004
           dec
                  eax
00401005
           cmp
                  eax. 3
00401008
                  short loc_401055
           ja
                  ds:off 401068[eax*4]
                                          // Jump to a table item
0040100A
           jmp
                  offset zeroParameters
00401011
           push
00401016
           call.
                  ds:printf
0040101C
           add
                  esp, 4
0040101F
           xor
                  eax. eax
                                    // return 0. duplicated
00401021
           retn
                                    // Function exit, duplicated
00401022
                  offset oneParameter
           push
00401027
           call
                  ds:printf
0040102D
                  esp, 4
           add
00401030
                                    // return 0, duplicated
           xor
                  eax, eax
00401032
                                    // Function exit, duplicated
           retn
00401033
           push
                  offset twoParameters
00401038
           call
                  ds:printf
0040103E
           add
                  esp, 4
                                    // return 0, duplicated
00401041
                  eax. eax
           yor
00401043
                                    // Function exit, duplicated
           retn
00401044
           push
                  offset threeParameters
00401049
           call
                  ds:printf
0040104F
           add
                  esp, 4
00401052
           xor
                  eax, eax
                                    // return 0, duplicated
                                    // Function exit, duplicated
00401054
           retn
00401055
           push
                  offset defaultCase
0040105A
           call.
                  ds:printf
00401060
           add
                  esp. 4
00401063
                  eax. eax
                                    // return 0, duplicated
           xor
00401065
                                    // Function exit, duplicated
           retn
```

# Summary

#### Now we should:

- understand the prologue and epilogue;
- understand the stack frame and its structure;
- understand what a Basic Block is;
- be able to construct a Code Flow Graph of a function, and
- understand how C constructs are compiled into assembly and be able to translate them back into human readable code at a higher level of abstraction.

Now, let's look closer what runtime does when your program is run. This includes:

- what the entry point is and what it does;
- calling initializer functions;
- calling your main function;
- calling terminator functions.



# The Main Entry Point

The main/wmain/\_tmain functions are not the real entry points. The real entry point is the function whose Relative Virtual Address (RVA) is specified in the AddressOfEntryPoint field in the PE optional header.

#### Entry point, where are you?

```
Entry point address: 00402390
```

Now we should ask **who** provides the main entry point, **where is it called from**, and **why** this is not the main function?

# Who calls the Main Entry Point?

We have already seen this in Lec. 1.

```
Entry point address: 00402390
```

# Main entry point Call Stack

```
004136C0 Tokens.exe!main(int argc, const char* * argv) // The C entry point
00402259 Tokens.exe!__tmainCRTStartup()

0040239D Tokens.exe!mainCRTStartup() // The main entry point

75C4EE0A kernel32.dll!@BaseThreadInitThunk@12()

775A37C4 ntdll.dll!__RtlUserThreadStart@8()

775A37A3 ntdll.dll!__RtlUserThreadStart@8()
```

# Who provides the main entry point?

It's the Runtime who provides the main entry point. It can be found in crtexe.c:

```
int mainCRTStartup( void )
{
    /*
    * The /GS security cookie must be initialized before any exception
    * handling targetting the current image is registered. No function
    * using exception handling can be called in the current image until
    * after __security_init_cookie has been called.
    */
    __security_init_cookie();
    return __tmainCRTStartup();
}
```

#### Notes

This function can have various names depending on the setup (whether the "Use Unicode Character Set" is specified aka. #define UNICODE 1) or whether main or WinMain are used. These names include:

- mainCRTStartup
- 2 wmainCRTStartup
- WinMainCRTStartup
- wWinMainCRTStartup

# $_{--}$ tmainCRTStartup()

# Each C/C++ program starts with this code:

```
__declspec(noinline) int __tmainCRTStartup( void )
 trv {
   // Run initializers placed into .crt$xia ... .crt$xiz segs (merged into .rdata)
   // xi a and xi z bound initializer data start and end
   // calls pre_c_init(), by default initialize C, sets default FPU mode,
   // sets the unhandled exception filter to __CxxUnhandledExceptionFilter
   if( _initterm_e( __xi_a, __xi_z ) != 0 )
     return 255:
   // Run initializers placed into .crt$xca ... .crt$xcz segs (placed into .rdata)
   // calls pre_cpp_init(), sets atexit(_RTC_Terminate), prepares parameters for main,
   // calls all constructors of static objects and registers a stub calling appropriate
   // destructors using the atexit function.
   initterm( xc a, xc z):
   // Call whichever main function we have!
   mainret = main(argc, argv, envp):
   exit(mainret);
 __except( _XcptFilter( GetExceptionCode(), GetExceptionInformation() ) ) {
   // _XcptFilter terminates, inaccessible
   mainret = GetExceptionCode();
   ExitProcess(mainret):
 return mainret;
```

#### Initialization Code

The compiler can do a lot for us without involving us in runtime details. In order to use a global C++ class, all we have to do is:

#### A Sample Initializer Code

```
// A globally initialized class
Initializer g_InitializerClassInstance;
class Initializer {
  public:
    Initializer() {
      printf("Hello pre-main code.\n");
    ~Initializer() {
      printf("Hello post-main code.\n");
};
```

**Note:** GCC uses special keywords \_\_attribute\_\_((constructor)) and \_\_attribute\_\_((destructor)); this allows initializers to be used from C and get a function called during the initialization or termination phase.

# Initializing the Hard Way

If we need a finer grained control, we need to use #pragmas.

```
Fine Grained Initialization
```

```
#pragma section(".CRT$XIB")
   __declspec(allocate(".CRT$XIB")) int (*g_MyInit_PreC)(void) = MyInit_PreC;

#pragma section(".CRT$XIY")
   __declspec(allocate(".CRT$XIY")) int (*g_MyInit_PostC)(void) = MyInit_PostC;

// XCT = pre static objects constructors

// XCU = post static objects constructors

#pragma section(".CRT$XCB")
   __declspec(allocate(".CRT$XCB")) void (*g_MyInit_PreCPP)(void) = MyInit_PreCPP;

#pragma section(".CRT$XCZ")
   __declspec(allocate(".CRT$XCZ")) void (*g_MyInit_PostCPP)(void) = MyInit_PostCPP;
```

Initializers in .CRT\$XIxxx sections can return a value. Returning a non-zero value causes program initialization to abort with error 255.

#### Where are the Initializers? I

\_initterm\_e and \_initterm functions take the beginning and end pointer of a portion of the .rdata section of the image (following the IAT). Let's inspect this section:

Offset	0	1	2	3	4	- 5	- 6	7	- 8	9	A	В	С	D	Ε	F	Ascii
00000540 00000550		00 00	00 00	00	00	00 00	00 00		00 00	00	00 00	00	00 00	00 00	00 00	00	
00000610 00000620 00000630	00 00 00	00 40 00	00 39 00	00 41 00	00 00 00	00 00 00	00 00 00	00 00 00	00 00 00	@9A							
00000710 00000720 00000730	őő	00 00 00		00 00 00	00 00 00	00	00	0.0	00 00 00	0.0	00 00 00	00 00 00		00 10 00	00 41 00		
00000820 00000830 00000840	C3	00 10 00		00 00 00	0.0	00 00 00	00 00 00	00	00 00 00	À+A							
00000920 00000930 00000940	00 00 00	00 00 00	00 00 00	00 00 00	00 B3 00	00 11 00	00 41 00	ŌŌ	00 22 00	00 11 00	00 41 00	00 00 00	00 00 00	00 00 00	00 00 00	00 00 00	³∢À. "∢À
00000A30 00000A40	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	1

Figure : \_\_xi\_a through \_\_xi\_z in debug version.

Each entry in this list is a pointer to a C-style initialization function:

```
413940 pre_c_init
41108c jmp MyInit_PreC in debug, MyInit_PreC in release
4110c3 jmp __atonexitinit in debug, __atonexitinit in release
411103 jmp MyInit_PostC in debug, MyInit_PostC in release
411122 jmp ___CxxSetUnhandledExceptionFilter in debug, direc
```

# Where are the Initializers? II

```
int _initterm_e(int (**pSegStart)(void), int (**pSegEnd)(void))
{
   int initResult = 0;
   while ( pSegStart < pSegEnd && !initResult )
   {
     if ( *pSegStart )
        initResult = (*pSegStart)();
     ++pSegStart;
   }
   return initResult;
}</pre>
```

The array holds pointers to initialization functions; if non-null, the function is called. Note that this C-initializer function aborts (in contrast to C++ initializers) as soon as any initializer returns a non-zero value.

# Where are the Initializers? III

Offset	0	1	2	3	4	- 5	- 6	- 7	- 8	- 9	A	В	С	D	E	F	Ascii
00000080	86	25	0.0	0.0	98	25	0.0	00	DE	23	00	0.0	F0	23	00	00	% %Þ#8#
00000090	E8	23	00	00	86	24	0.0	00	00	00	00	0.0	00	00	00	00	è#\$ %1@.0+@ +@.0+@.
000000A0	DD	12	40	00	30	10	40	00	00	10	40	00	30	10	40	00	Ý]:@.O +@ +@.O +@.
000000B0	00	00	00	00	00	00	0.0	00	24	12	40	00	20	10	40	00	1+@.

Figure : \_\_xc\_a through \_\_xc\_z in release version.

Each entry in this list is a pointer to a C++-style initialization function:

```
000000
 4012dd
         pre_cpp_init
         MyInit_PreCPP
 401030
         Initializer ctor stub
 401000
         MvInit PostCPP
 401020
00401000
                 ecx,4031B8h // This pointer
          mov
00401005
          call
                 Initializer::Initializer
0040100A
          push
                 401930h
                          // Address of the destructor stub
0040100F
          call
                              // Register to be called at exit
                 atexit
00401014
          pop
                 ecx
00401015
          ret.
                 ecx,4031B8h // This pointer
00401930
          mov
                 Initializer::~Initializer
00401935
          jmp
```

#### Terminators I

As we have seen, the atexit API was heavily used to register stubs to call static object's destructors at the program's exit time. Atexit uses a dynamically allocated array pointed to by two encoded pointer globals \_\_onexitbegin and \_\_onexitend. Encoded function pointers are registered in this array. When the C API exit (but not TerminateProcess) is called, atexit registered functions are called. Moreover, if we are using a statically linked runtime library, pre-termination and termination functions registered in .crt\$xpXXX and .crt\$xtXXX segments are called in the same manner as the initializers.

# Terminators II

# atexit code (atonexit.c)

```
int __cdecl atexit(void (__cdecl *func)()) {
  return _onexit(func) == NULL ? -1 : 0;
}
_onexit_t __cdecl _onexit(_onexit_t Func) {
  int (__cdecl *pfnFunc)();
  _lockexit();
  pfnFunc = _onexit_nolock(Func);
  _unlockexit();
  return pfnFunc;
}
```

#### exit code (crt0dat.c)

```
void __cdecl exit( int code ) {
  doexit(code, 0, 0); /* full term, kill process */
}
```

#### Terminators III

# doexit pseudocode (crt0dat.c)

```
void __cdecl doexit(int code, int quick, int retcaller) {
 if (!retcaller && check_managed_app()) // If the process is managed, call CorExitProcess
    __crtCorExitProcess(uExitCode);
 if (!quick) {
    onexitbegin = DecodePointer(__onexitbegin); onexitend = DecodePointer(__onexitend);
   while (1) { // Iterate over all exit functions
     // Find the first "non-zero" func
     while ( --onexitend >= onexitbegin && *onexitend == EncodePointer(NULL) ):
     // Ending condition
     if ( onexitend < pfn__onexitbegin ) break;</pre>
     // Decode, call, and remove the atexit registered function from the list
     pfnExitProc = (void (*)(void))DecodePointer(*onexitend);
      *onexitend = EncodePointer(0):
     pfnExitProc();
    #ifndef CRTDLL
     _initterm(__xp_a, __xp_z); // Call pre-terminators
    #endif
 #ifndef CRTDLL
    initterm( xt a, xt z): // Call terminators
 #endif
 if ( ret ) return:
 if ( !ret ) crtExitProcess(code);
```

# Pointer Encoding

Pointers on the stack/heap could be overwritten and used to run exploit code. EncodePointer and DecodePointer APIs are used to make this difficult. These calls are internally mapped to RtlEncodePointer and RtlDecodePointer APIs in NTDLL.DLL:

```
77F1A290
           db 5 dup(90h)
77F1A295 RtlEncodePointer:
77F1A295
           mov edi, edi
77F1A297
           push ebp
77F1A298
           mov ebp, esp
77F1A29A
           push ecx
77F1A29B
           push 0
                                    ; ReturnLength
77F1A29D
           push 4
                                    : ProcessInformationLength
77F1A29F
           lea eax. [ebp+ProcessInformation]
77F1A2A2
           push eax
                                   ; ProcessInformation
77F1A2A3
           push 24h
                                   : ProcessInformationClass = process cookie
           push OFFFFFFFh
                                   : ProcessHandle = GetCurrentProcess()
77F1A2A5
77F1A2A7
           call _ZwQueryInformationProcess@20
77F1A2AC
           test eax, eax
77F1A2AE
           il loc 77F4276F
           mov eax, [ebp+ProcessInformation]
77F1A2B4
77F1A2B7
           mov cl, al
77F1A2B9
           xor eax, [ebp+arg_0]
77F1A2RC
           and cl. 1Fh
77F1A2BF
           ror eax, cl
77F1A2C1
           leave
77F1A2C2
           retn 4
```

# Hot Patching Support

You might have noticed there's a mov edi,edi instruction at the beginning of the previous function. Moreover there are 5 nop instructions ahead of the function start. These serve for the purpose of hot patching, a mechanism allowing us to easily replace the function at runtime without having to restart the application. The instructions above provide 7 bytes of free space which we can use to replace the function. The mov edi,edi instruction is replaced by a jump short instruction to the start of nops, where jmp [addr] instruction is placed. The code then looks like this:

#### Non-patched code 90 nop 90 nop 90 nop 90 nop 90 nop function\_start: 8B FF mov edi,edi push ebp mov ebp, esp

#### Patched code

# Call to a jmp? I

In debug version all functions were called via an extra level of indirection. This indirection was common to all functions. What was the point of this?

```
main:
00413130
         push ebp
00413131
         mov
               ebp,esp
00413133 sub
               esp.48h
00413136 push ebx
         push
               esi
00413137
00413138 push edi
00413139 mov
               dword ptr [result].0
00413140 call PEDUMP (4110BEh)
PEDUMP real:
004125F0 push ebp
004125F1 mov
               ebp.esp
               esp.50h
004125F3 sub
```

```
GetCurrentProcess@0:
004110B4 imp
               GetCurrentProcess (4131D0h)
___report_securityfailure:
004110B9 imp
              report securityfailure (413640h)
PEDUMP real:
004110BE jmp PEDUMP (4125F0h)
___atonexitinit:
004110C3 imp atonexitinit (413220h)
___report_securityfailureEx:
              __report_securityfailureEx (413750h)
FindPESection:
004110CD jmp _FindPESection (413FCOh)
MyInit_PreCPP:
004110D2 jmp
               MyInit_PreCPP (412340h)
LoadLibrarvW@4:
004110D7 jmp LoadLibraryW (4131EEh)
__configthreadlocale:
004110DC imp configthreadlocale (4143EEh)
Initializer: Initializer:
004110E1 jmp Initializer:: Initializer (412390h)
```

# Call to a jmp? II

When incremental linking is enabled, all calls in the program are made via an extra level of indirection. This allows us to replace any function at program run-time. New code is simply compiled, copied into the process's memory and the redirection address is updated so that it points to the new implementation. MSVC uses "Apply Code Changes", Apple uses "Fix and Continue", but the principle is the same.

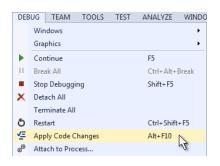


Figure : MSVC Apply Code Changes.

# Import Address Table I

A module can depend on other modules. The modules depended on and symbol names and/or their ordinal numbers can be found in the Import Directory (ID) of the PE file.

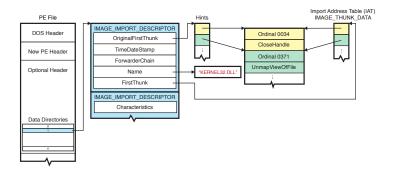


Figure: The PE Import Directory and Import Address Table.

# Import Address Table II

# Traversing the Import Directory

```
PIMAGE IMPORT DESCRIPTOR pImports = (PIMAGE IMPORT DESCRIPTOR)(((BYTE*)pDosHeader)
  + pNTHeaders->OptionalHeader.DataDirectory[IMAGE_DIRECTORY_ENTRY_IMPORT].VirtualAddress);
PIMAGE_IMPORT_DESCRIPTOR pImportsEnd = (PIMAGE_IMPORT_DESCRIPTOR)(((BYTE*)pImports)
  + pNTHeaders->OptionalHeader.DataDirectory[IMAGE_DIRECTORY_ENTRY_IMPORT].Size);
for (; pImports < pImportsEnd && pImports->OriginalFirstThunk != NULL; ++pImports)
 char* pszDLLName = (char*)((BYTE*)pDosHeader + pImports->Name);
 printf("DLL: %s\n", pszDLLName );
 if (pImports->Characteristics != NULL)
    PIMAGE THUNK DATA pSymbolData = (PIMAGE THUNK DATA)(((BYTE*)pDosHeader) + pImports->OriginalFirstThunk);
   for (; pSymbolData->u1.AddressOfData != NULL; ++pSymbolData )
     PIMAGE_IMPORT_BY_NAME pImport = (PIMAGE_IMPORT_BY_NAME)(((BYTE*)pDosHeader)
        + pSymbolData->u1.AddressOfData);
     printf("%04hx %s\n", pImport->Hint, pImport->Name);
   }
```

# Import Address Table III

Once an image is loaded, the loader replaces all IAT references (RVAs of IMAGE\_THUNK\_DATA32 in a 32-bit PE file) (on the left) pointing to IMAGE\_IMPORT\_BY\_NAME (bottom right) with real function pointers (on the right).

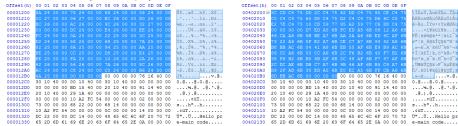


Figure: IAT on disk.

Figure: IAT in memory.

The first IMAGE\_THUNK\_DATA (4 bytes) contains a RVA of 0000248A (left). This address, when mapped into the executable's memory,



points to an IMAGE\_IMPORT\_BY\_NAME structure containing an ordinal number (0267) followed by a zero-terminated function name (GetModuleHandleW) (bottom right). The function is from kernel32.dll and resolves to address 75C4CD5C, which is written back to the IAT (right). The IAT is found in the .rdata section, thus it is read-only.

# Import Address Table IV

When an external symbol is bound, its address is resolved and all references to that symbol are updated according to the relocation table (see BIE-BEK, lec. 2). This approach is used for object files; with executables, we would have to relocate every external call during the application's startup. Instead, indirection is used and only **a single** entry per symbol is modified — the one in the IAT!

#### Calling a function through the IAT

```
// A function call
00401072 push 0
00401074 call dword ptr [__imp__GetModuleHandleW@4 (402000h)]
// TAT
00402000
         .dd 075C4CD5Ch
                            // KERNEL32.DLL!GetModuleHandleW
00402004
         .dd 075C42CDDh
                            // KERNEL32.DLL!VirtualProtect
004020B0 .dd 06BACBB8Dh
                            // MSVCR120.DLL!__amsg_exit
                            // - end -
004020B4 dd 0
// Implementation
GetModuleHandleWStub@4:
75C4CD5C mov
             edi,edi
75C4CD5E push ebp
75C4CD5F mov
              ebp,esp
```

# IAT Hacking I

As you have seen, calls to the same external API are made through a single point in the program — its entry in the IAT. What happens if we change that entry in the IAT?

# IAT Hacking II

As you have seen, calls to the same external API are made through a single point in the program — its entry in the IAT. What happens if we change that entry in the IAT?

All calls to that API throughout the entire program divert!

# IAT Hacking III

As you have seen, calls to the same external API are made through a single point in the program — its entry in the IAT. What happens if we change that entry in the IAT?

All calls to that API throughout the entire program divert!

The IAT is read-only by default, but it is possible to use eg. VirtualProtect to make IAT writtable and divert all calls throughout the entire program to that function to your function.

# IAT Hacking IV

Can we get beyond our process boundary? The answer is a definite YES. We have to either use functions such as VirtualAllocEx, ReadProcessMemory, WriteProcessMemory, VirtualProtectEx, CreateRemoteThread to hack another process(es) and to inject code/DLL into them, or use the Native API!

#### Win32 API

```
BOOL WINAPI VirtualProtectEx(
   _In_ HANDLE hProcess,
   _In_ LPVOID lpAddress,
   _In_ SIZE_T dwSize,
   _In_ DWORD flNewProtect,
   _Out_ PDWORD lpflOldProtect
);
```

#### NT API

```
NTSYSAPI NTSTATUS NTAPI
NtProtectVirtualMemory(
IN HANDLE ProcessHandle,
IN OUT PVOID *BaseAddress,
IN OUT PULONG NumOfBytesToProtect,
IN ULONG NewAccessProtection,
OUT PULONG OldAccessProtection);
```

# **Bibliography**



Russinovich M., Solomon D. A., Ionescu A.: Windows Internals Part 2,  $6^{\rm th}$  ed., 2012.