

# Assignment-1

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Download all python codes from

<https://github.com/ganrajborade/EE3025/tree/main/A1/codes>

and latex-tikz codes from

<https://github.com/ganrajborade/EE3025/tree/main/A1>

## 1 PROBLEM

1.1. Let

$$x(n) = \left\{ \underset{\uparrow}{1}, 2, 3, 4, 2, 1 \right\} \quad (1.1.1)$$

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2) \quad (1.1.2)$$

1.2. Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (1.2.1)$$

and  $H(k)$  using  $h(n)$ .

1.3. Compute

$$Y(k) = X(k)H(k) \quad (1.3.1)$$

## 2 SOLUTION

2.1. The Impulse Response of the LTI system is the output of the system when Unit Impulse Signal is given as input to the system. Impulse response  $h(n)$  can be found from given difference equation as follows ( $h(n)$  is IIR Filter)

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2) \quad (2.1.1)$$

2.2. DFT of a Input Signal  $x(n)$  is

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (2.2.1)$$

2.3. Let  $W_N = e^{-j2\pi/N}$

We can express  $X$  as Matrix Multiplication of DFT Matrix and  $x$ .

$$X = \left[ W_N^{ij} \right]_{N \times N} x, \quad i, j = 0, 1, \dots, N-1 \quad (2.3.1)$$

2.4. Using the property of complex exponentials :

$$W_N^2 = W_{N/2} \quad (2.4.1)$$

$$X(k) = \sum_{n=0}^{N-1} x(n)W_N^{kn}, \quad k = 0, 1, \dots, N-1 \quad (2.4.2)$$

$$= \sum_{n=\text{even}} x(n)W_N^{kn} + \sum_{n=\text{odd}} x(n)W_N^{kn} \quad (2.4.3)$$

$$= \sum_{m=0}^2 x(2m)W_N^{2mk} + \sum_{m=0}^2 x(2m+1)W_N^{(2m+1)k} \quad (2.4.4)$$

using property above property, we get,

$$X(k) = \sum_{m=0}^2 x(2m)W_{N/2}^{mk} + W_N^k \sum_{m=0}^2 x(2m+1)W_{N/2}^{mk} \quad (2.4.5)$$

$$= X_1(k) + W_N^k X_2(k) \quad (2.4.6)$$

- Here,  $X_1(k)$  and  $X_2(k)$  are 3 point DFTs of  $x(2m)$  and  $x(2m+1)$ ,  $m=0,1,2$ .
- And  $X_1(k)$  and  $X_2(k)$  are periodic, Hence  $X_1(k+3) = X_1(k)$  and  $X_2(k+3) = X_1(k)$ .

2.5. Calculating  $X_1$  and  $X_2$

$$X_1(k) = \sum_{m=0}^2 x(2m)W_3^{mk} \quad (2.5.1)$$

$$X_2(k) = \sum_{m=0}^2 x(2m+1)W_3^{mk} \quad (2.5.2)$$

$$\begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_2(0) \\ X_2(1) \\ X_2(2) \end{bmatrix} = \begin{bmatrix} W_3^0 & W_3^0 & W_3^0 & 0 & 0 & 0 \\ W_3^0 & W_3^1 & W_3^2 & 0 & 0 & 0 \\ W_3^0 & W_3^2 & W_3^4 & 0 & 0 & 0 \\ 0 & 0 & 0 & W_3^0 & W_3^0 & W_3^0 \\ 0 & 0 & 0 & W_3^0 & W_3^1 & W_3^2 \\ 0 & 0 & 0 & W_3^0 & W_3^2 & W_3^4 \end{bmatrix} \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(1) \\ x(3) \\ x(5) \end{bmatrix} \quad (2.5.3)$$

## 2.6. Calculating X

$$X(k) = X_1(k) + W_N^k X_2(k) \quad (2.6.1)$$

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \\ X(4) \\ X(5) \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & W_6^0 & 0 & 0 \\ 0 & 1 & 0 & 0 & W_6^1 & 0 \\ 0 & 0 & 1 & 0 & 0 & W_6^2 \\ 1 & 0 & 0 & W_6^3 & 0 & 0 \\ 0 & 1 & 0 & 0 & W_6^4 & 0 \\ 0 & 0 & 1 & 0 & 0 & W_6^5 \end{bmatrix} \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_2(0) \\ X_2(1) \\ X_2(2) \end{bmatrix} \quad (2.6.2)$$

$$\Rightarrow \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \\ X(4) \\ X(5) \end{bmatrix} = \begin{bmatrix} 13 + 0j \\ -4 - \sqrt{3}j \\ 1 + 0j \\ -1 + 0j \\ 1 + 0j \\ -4 + \sqrt{3}j \end{bmatrix} \quad (2.6.3)$$

## 2.7. DFT of a Impulse Response $h(n)$ is

$$H(k) \triangleq \sum_{n=0}^{N-1} h(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (2.7.1)$$

2.8. Now to find  $H(k)$  we need to know  $h(n)$  first. So we will first calculate  $h(n)$ . For that we need to first find the  $H(z)$  by applying Z-transform on equation (2.1.1) i.e.,

$$H(z) = \frac{2(z^2 + 1)}{z(2z + 1)} \quad (2.8.1)$$

$$H(z) = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}} \quad (2.8.2)$$

From this we can say that  $h(n)$  is,

$$h(n) = Z^{-1} \left[ \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}} \right] \quad (2.8.3)$$

$$h(n) = \left[ \frac{-1}{2} \right]^n u(n) + \left[ \frac{-1}{2} \right]^{n-2} u(n-2) \quad (2.8.4)$$

Similarly, like  $X(k)$ , we can calculate  $H(k)$ .

$$W_1 = \begin{bmatrix} 1 & 0 & 0 & W_6^0 & 0 & 0 \\ 0 & 1 & 0 & 0 & W_6^1 & 0 \\ 0 & 0 & 1 & 0 & 0 & W_6^2 \\ 1 & 0 & 0 & W_6^3 & 0 & 0 \\ 0 & 1 & 0 & 0 & W_6^4 & 0 \\ 0 & 0 & 1 & 0 & 0 & W_6^5 \end{bmatrix} \quad (2.8.5)$$

$$W_2 = \begin{bmatrix} W_3^0 & W_3^0 & W_3^0 & 0 & 0 & 0 \\ W_3^0 & W_3^1 & W_3^2 & 0 & 0 & 0 \\ W_3^0 & W_3^2 & W_3^4 & 0 & 0 & 0 \\ 0 & 0 & 0 & W_3^0 & W_3^0 & W_3^0 \\ 0 & 0 & 0 & W_3^0 & W_3^1 & W_3^2 \\ 0 & 0 & 0 & W_3^0 & W_3^2 & W_3^4 \end{bmatrix} \quad (2.8.6)$$

Same as we done while calculating  $X(k)$  using Eq (2.6.2)

$$\begin{bmatrix} H(0) \\ H(1) \\ H(2) \\ H(3) \\ H(4) \\ H(5) \end{bmatrix} = W_1 W_2 \begin{bmatrix} h(0) \\ h(2) \\ h(4) \\ h(1) \\ h(3) \\ h(5) \end{bmatrix} \quad (2.8.7)$$

$$\Rightarrow \begin{bmatrix} H(0) \\ H(1) \\ H(2) \\ H(3) \\ H(4) \\ H(5) \end{bmatrix} = \begin{bmatrix} 1.28125 + 0j \\ 0.51625 - 0.5142j \\ -0.07813 + 1.1096j \\ 3.84375 + 0j \\ -0.07183 - 1.1096j \\ 0.51625 + 0.5142j \end{bmatrix} \quad (2.8.8)$$

## 2.9. We can now compute $Y(k)$ using Eq (2.9.1)

$$Y(k) = X(k)H(k) \quad (2.9.1)$$

So,  $Y(k)$  is obtained element wise multiplication of  $X(k)$  and  $H(k)$

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \\ Y(4) \\ Y(5) \end{bmatrix} = \begin{bmatrix} X(0) \cdot H(0) \\ X(1) \cdot H(1) \\ X(2) \cdot H(2) \\ X(3) \cdot H(3) \\ X(4) \cdot H(4) \\ X(5) \cdot H(5) \end{bmatrix} \quad (2.9.2)$$

Computing the above expression we get,

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \\ Y(4) \\ Y(5) \end{bmatrix} = \begin{bmatrix} 16.6562 + 0j \\ -2.95312 + 1.16372j \\ -0.07812 + 1.10959j \\ -3.84375 - 9.27556j \\ -0.07812 - 1.10959j \\ -2.95312 - 1.16372j \end{bmatrix} \quad (2.9.3)$$

2.10. The following code computes Y and generates magnitude and phase plots of X, H, Y

<https://github.com/ganrajborade/EE3025/blob/main/A1/codes/EE18BTECH11016.py>

2.11. The following plots are obtained

