

Lecture 4: Priority Algorithms

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Recall the template for the fixed order priority algorithm template:

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1   $\mathcal{J}$  = set of all possible inputs
2   $\preceq$  = a total ordering on  $\mathcal{J}$  (typically induced by a function  $f$ )
3   $\mathcal{I} \subset \mathcal{J}$  = actual input to the algorithm
4   $S = \emptyset$  // items already examined by the algorithm
5   $i = 0$ 
6  while  $\mathcal{I} - S \neq \emptyset$ 
7       $i = i + 1$ 
8       $\mathcal{I} = \mathcal{I} - S$ 
9       $I_i = \min_{\preceq} \{I \in \mathcal{I}\}$  // select min element based on the ordering  $\preceq$ 
10     make an irrevocable decision  $D_i$  concerning  $I_i$ 
11      $S = S \cup \{I_i\}$ 

```

and the adaptive priority algorithm:

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1   $\mathcal{J}$  = set of all possible inputs
2   $\mathcal{I} \subset \mathcal{J}$  = actual input to the algorithm
3   $S = \emptyset$  // items already examined by the algorithm
4   $i = 0$ 
5  while  $\mathcal{I} - S \neq \emptyset$ 
6       $i = i + 1$ 
7       $\preceq_i$  = a total ordering on  $\mathcal{J}$  (typically induced by a function  $f_i$ )
8       $\mathcal{I} = \mathcal{I} - S$ 
9       $I_i = \min_{\preceq_i} \{I \in \mathcal{I}\}$  // select min element based on the ordering  $\preceq_i$ 
10     make an irrevocable decision  $D_i$  concerning  $I_i$ 
11      $S = S \cup \{I_i\}$ 
12      $\mathcal{J} = \mathcal{J} - \{I \in \mathcal{I} \mid I \preceq_i I_i\}$ 

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4.1 Inapproximations for Deterministic Priority Algorithms

Once we have a precise model, we can then argue that certain approximation bounds are impossible within this model. We first consider the weighted interval selection problem.

For the interval selection problem, we have a set of intervals and each interval has a weight w_j . No priority algorithm can achieve a constant approximation. In an undergraduate course, we have shown that the unweighted interval selection problem can be optimally solved using a greedy algorithm by ordering the inputs by the earliest finishing time. We will prove a weaker result.

Theorem 4.1. *There is no priority approximation algorithm can achieve an approximation ratio better than 3.*

Proof: We use a charging argument. ■

4.2 Set Cover

In the set cover problem, we are given a collection $\mathcal{S} = \{S_1, \dots, S_n\}$ of sets with $S_i \subseteq U$ for some universe U . In the weighted set cover problem, each set S_i has a cost or weight $c(S_i)$. The objective is to find a minimum cost subcollection \mathcal{S}' such that $\bigcup_{S \in \mathcal{S}'} S = U$.

For the set cover problem, the “natural adaptive greedy algorithm” is essentially the best priority algorithm.

GREEDY-SET-COVER(\mathcal{S})

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1   $\mathcal{S}' = \emptyset$ 
2  while  $U$  is uncovered
3       $j = \arg \min_i \{w(S_i) / |S_i \cap U|\}$ 
4       $\mathcal{S}' = \mathcal{S}' \cup \{S_j\}$ 
5       $U = U \setminus \{S_j\}$ 
```