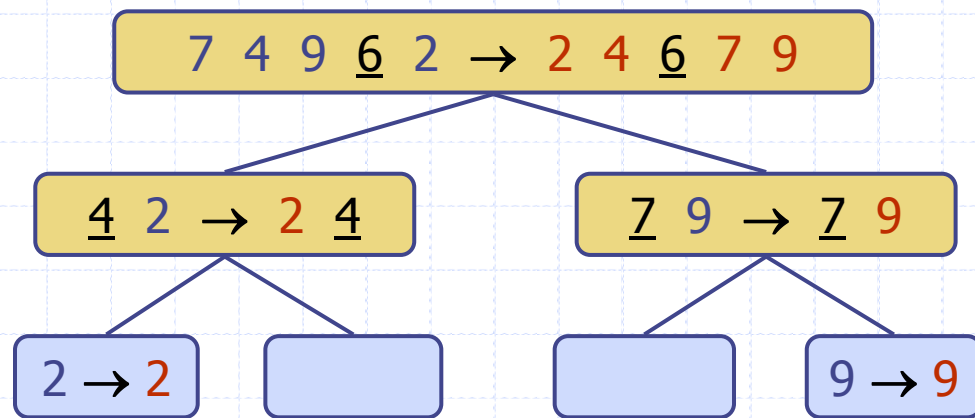


Quick-Sort



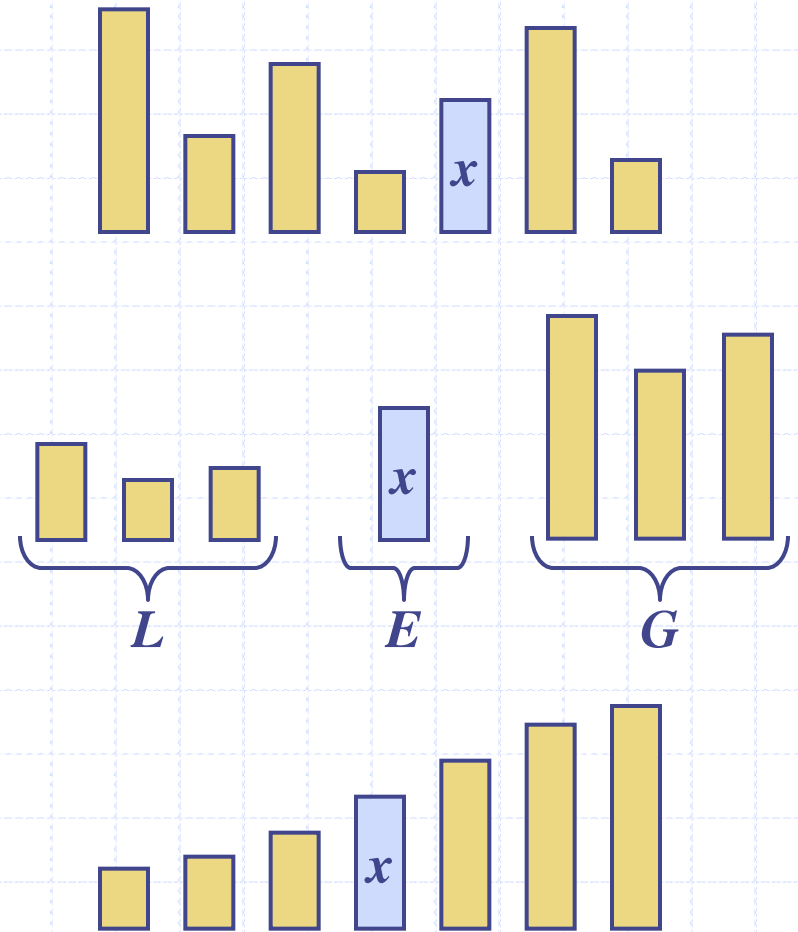
Outline and Reading

- ◆ Quick-sort
 - Algorithm
 - Partition step
 - Quick-sort tree
 - Execution example
- ◆ Analysis of quick-sort
- ◆ In-place quick-sort
- ◆ Summary of sorting algorithms

Quick-Sort

◆ Quick-sort is a randomized sorting algorithm based on the divide-and-conquer paradigm:

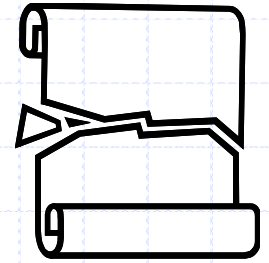
- **Divide**: pick a random element x (called **pivot**) and partition S into
 - ◆ L elements less than x
 - ◆ E elements equal x
 - ◆ G elements greater than x
- **Recur**: sort L and G
- **Conquer**: join L , E and G



Isn't that Merge-Sort?

- ◆ Quick-Sort is similar to Merge-Sort but with several key differences – details later

Partition



- ◆ We partition an input sequence as follows:
 - We remove, in turn, each element y from S and
 - We insert y into L , E or G , depending on the result of the comparison with the pivot x
- ◆ Each insertion and removal is at the beginning or at the end of a sequence, and hence takes $O(1)$ time
- ◆ Thus, the partition step of quick-sort takes $O(n)$ time

Algorithm *partition*(S, p)

Input sequence S , position p of pivot
Output subsequences L , E , G of the elements of S less than, equal to, or greater than the pivot, resp.

$L, E, G \leftarrow$ empty sequences

$x \leftarrow S.remove(p)$

while $\neg S.isEmpty()$

$y \leftarrow S.remove(S.first())$

if $y < x$

$L.insertLast(y)$

else if $y = x$

$E.insertLast(y)$

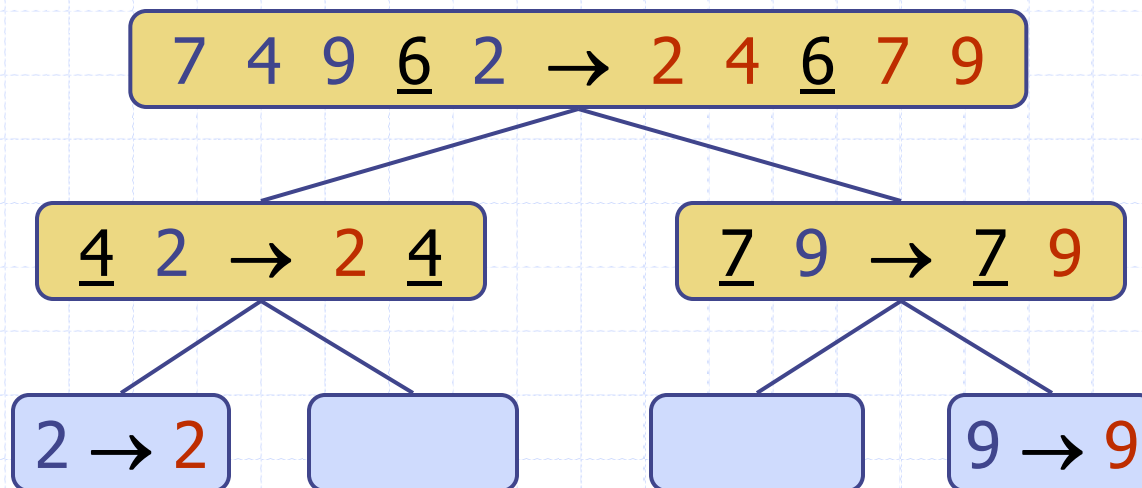
else $\{ y > x \}$

$G.insertLast(y)$

return L, E, G

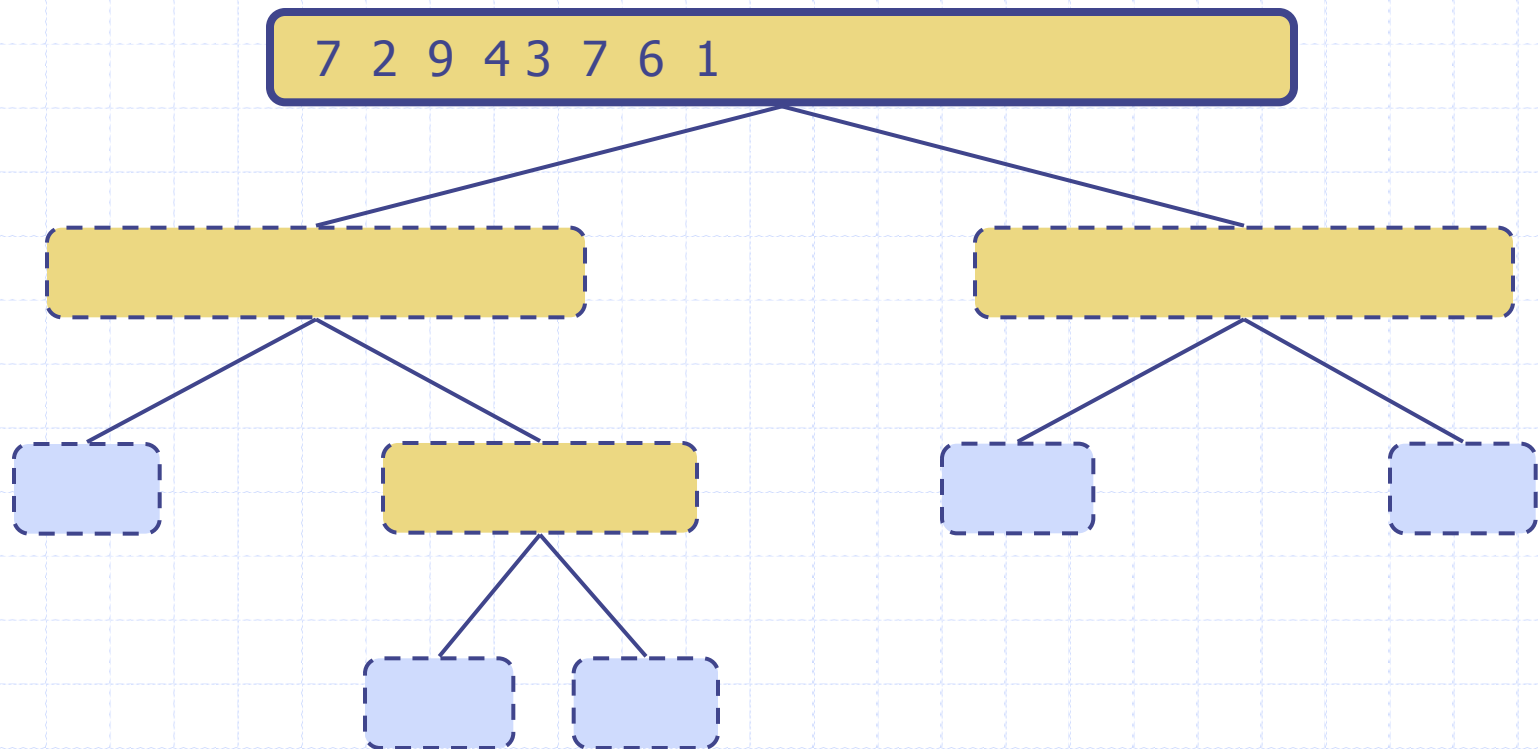
Quick-Sort Tree

- ◆ An execution of quick-sort is depicted by a binary tree
 - Each node represents a recursive call of quick-sort and stores
 - ◆ Unsorted sequence before the execution and its pivot
 - ◆ Sorted sequence at the end of the execution
 - The root is the initial call
 - The leaves are calls on subsequences of size 0 or 1



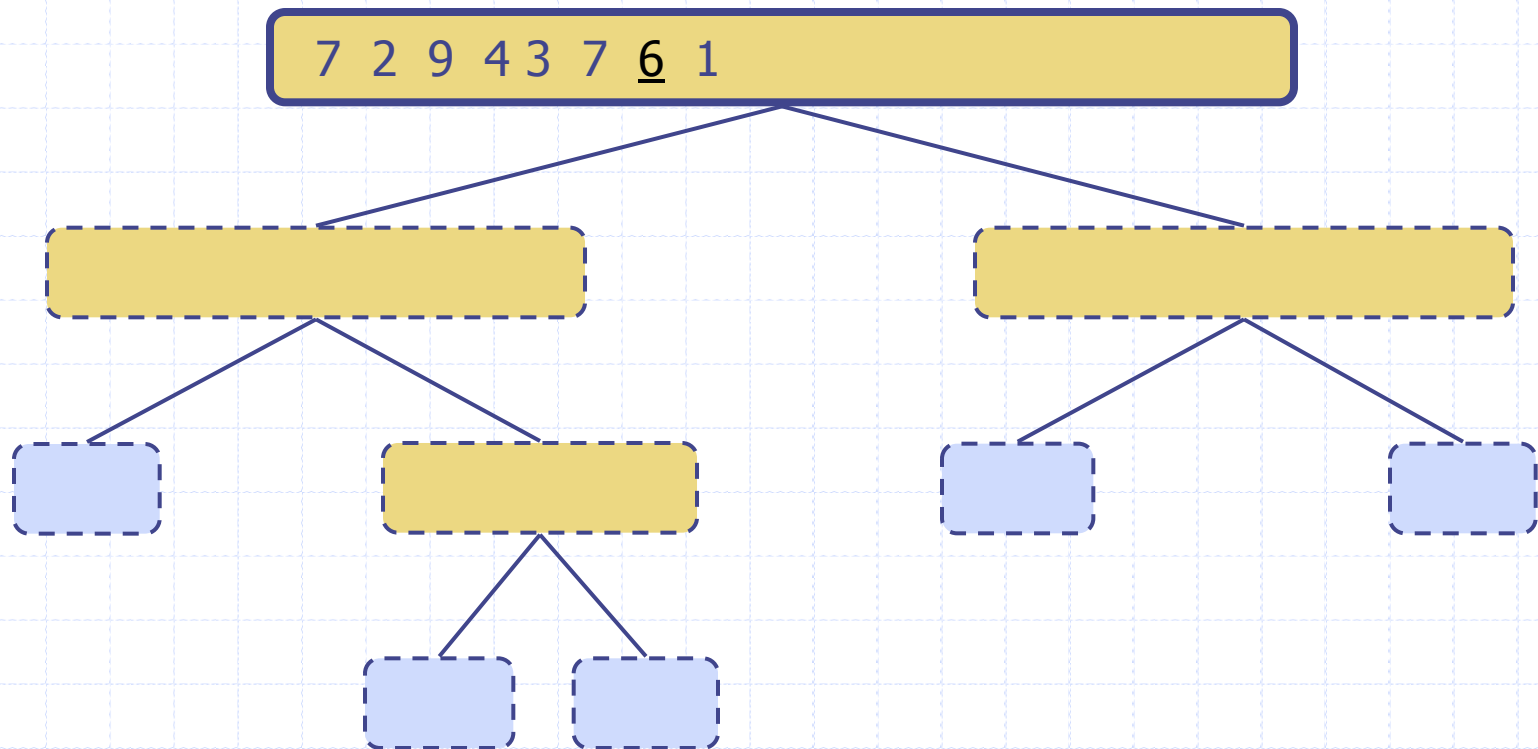
Execution Example

◆ Pivot selection



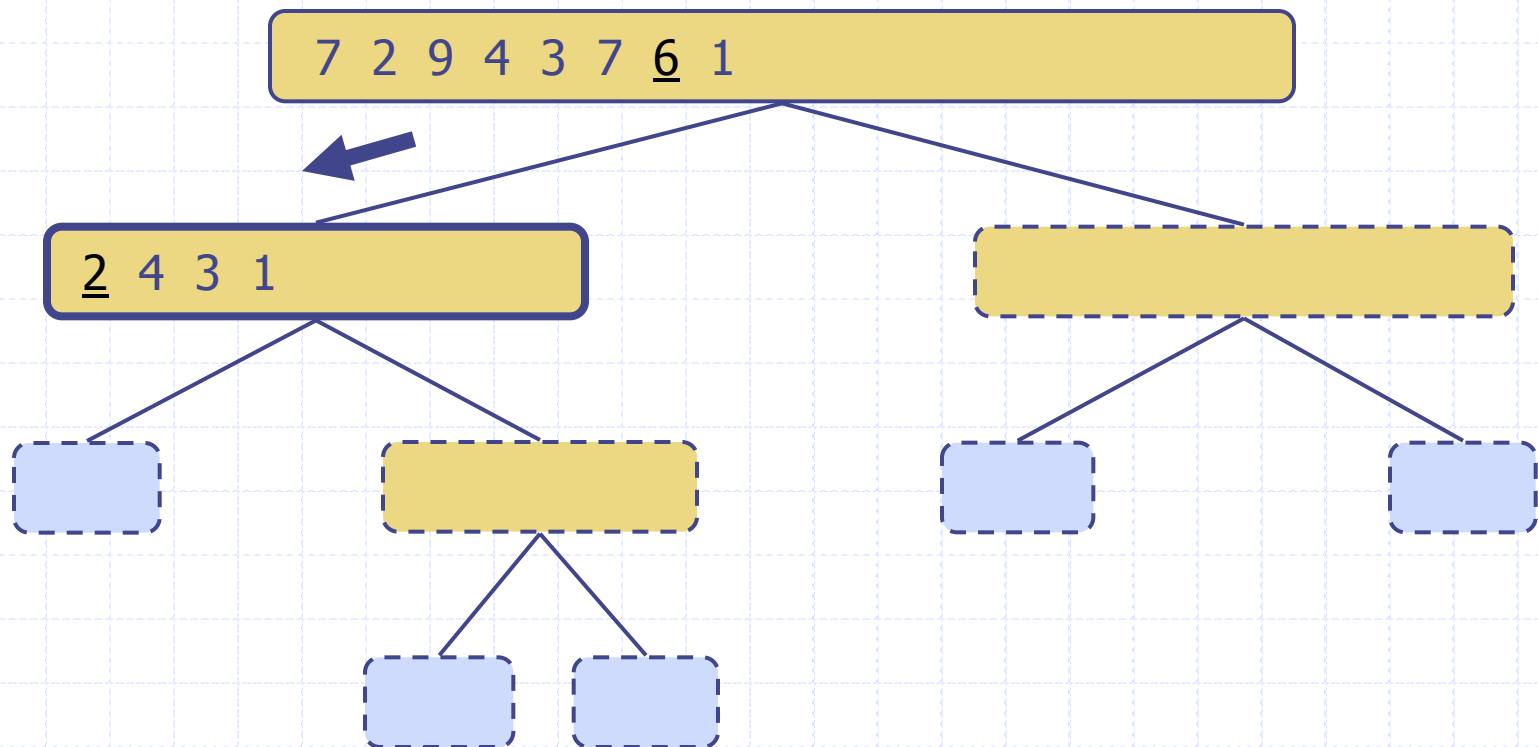
Execution Example

◆ Pivot selection, e.g. "6"



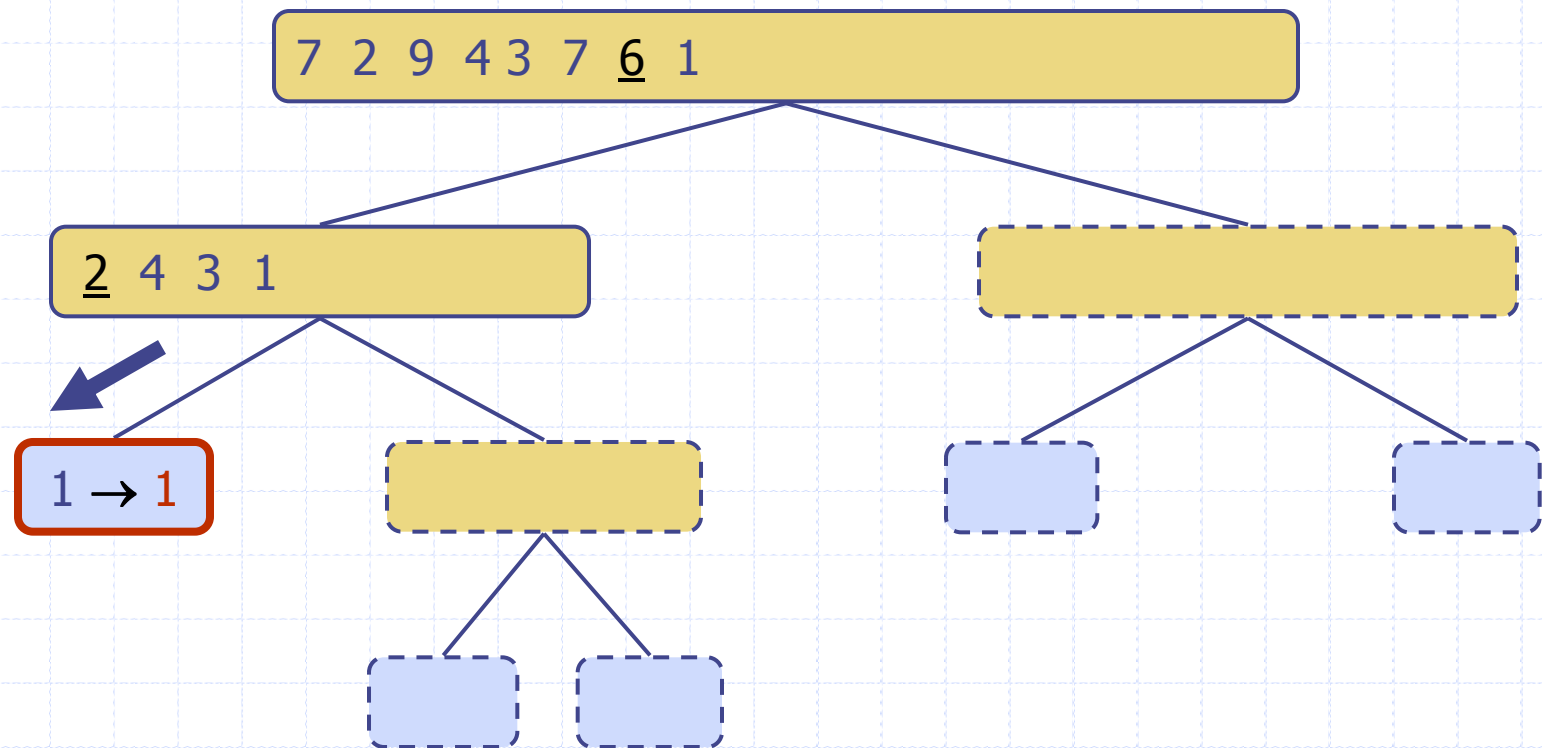
Execution Example (cont.)

◆ Partition, recursive call, pivot selection



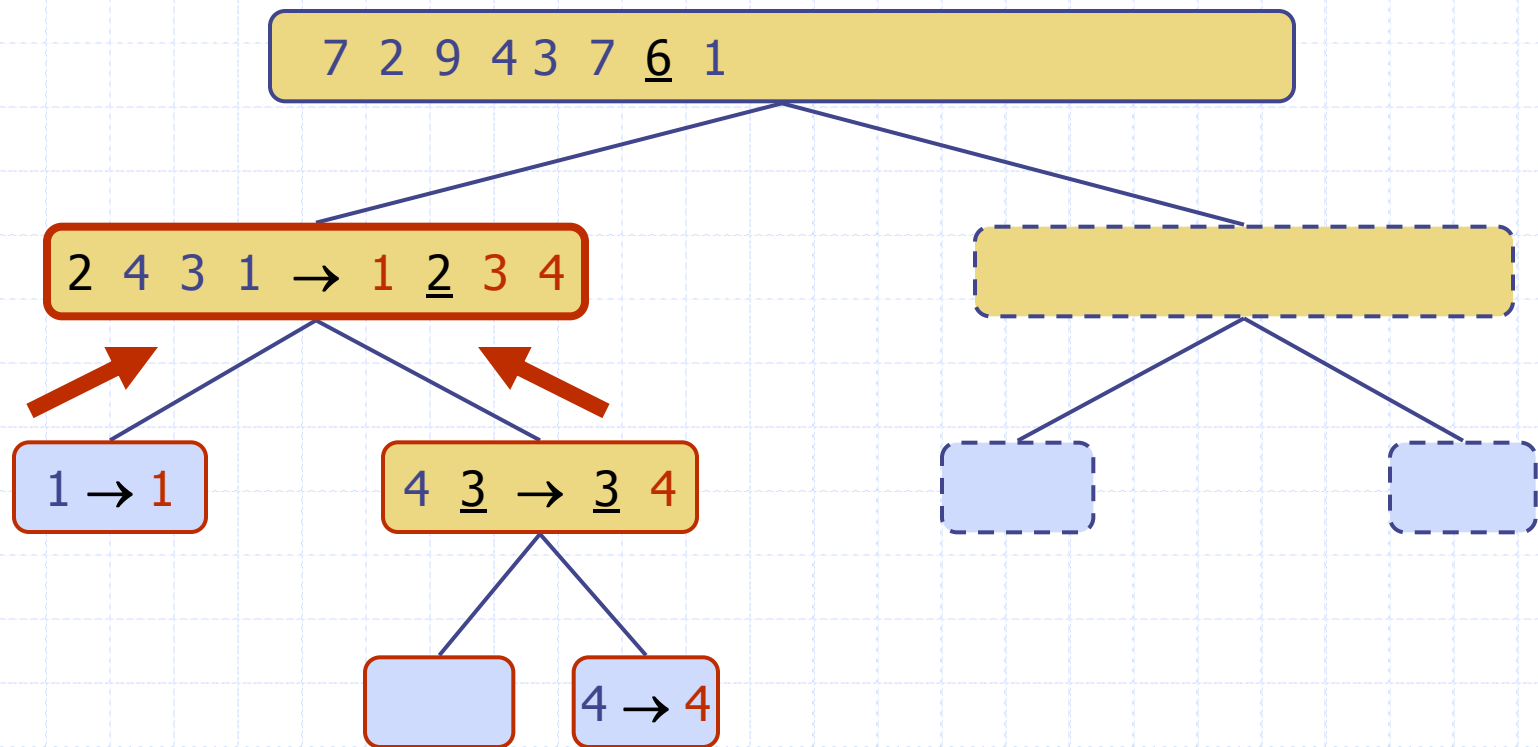
Execution Example (cont.)

◆ Partition, recursive call, base case



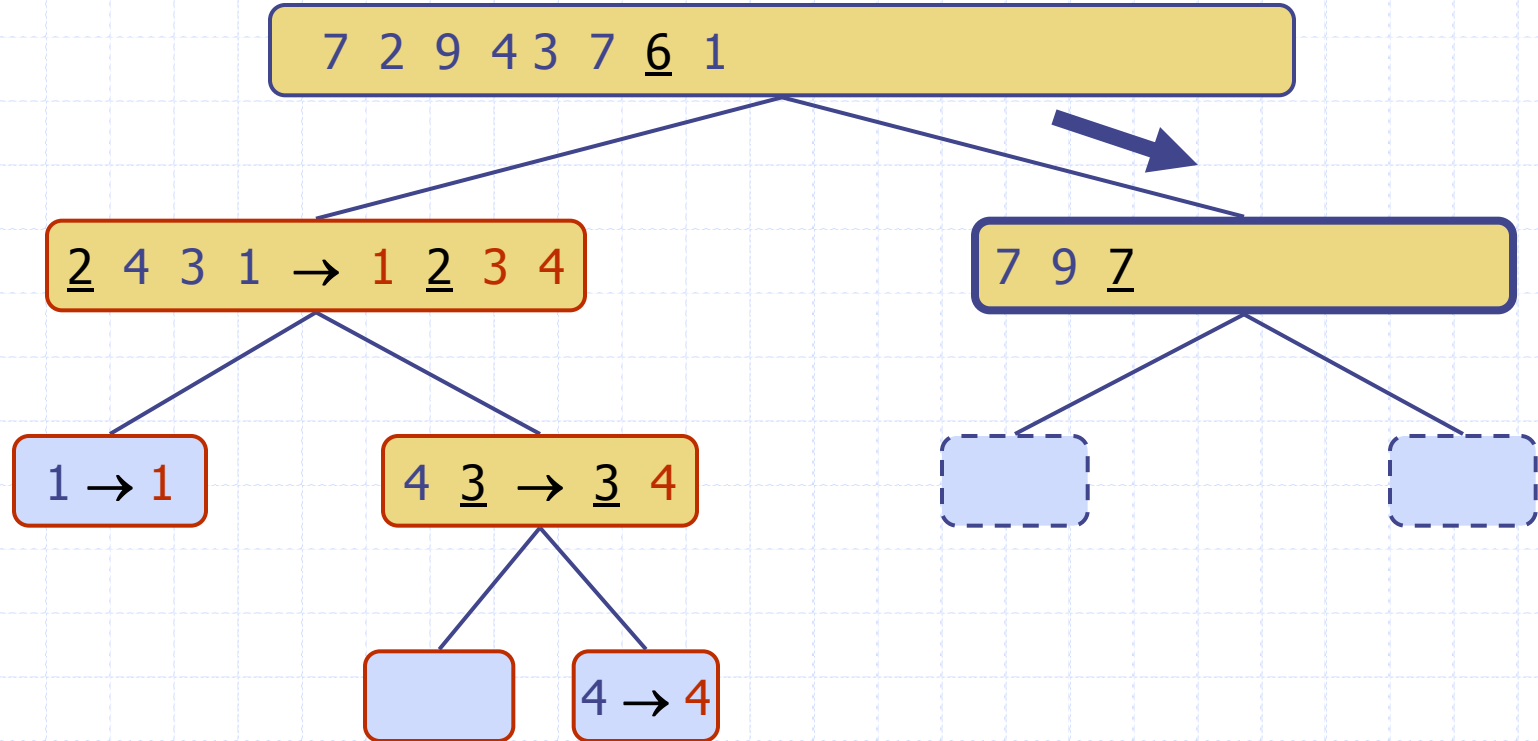
Execution Example (cont.)

◆ Recursive call, ..., base case, join



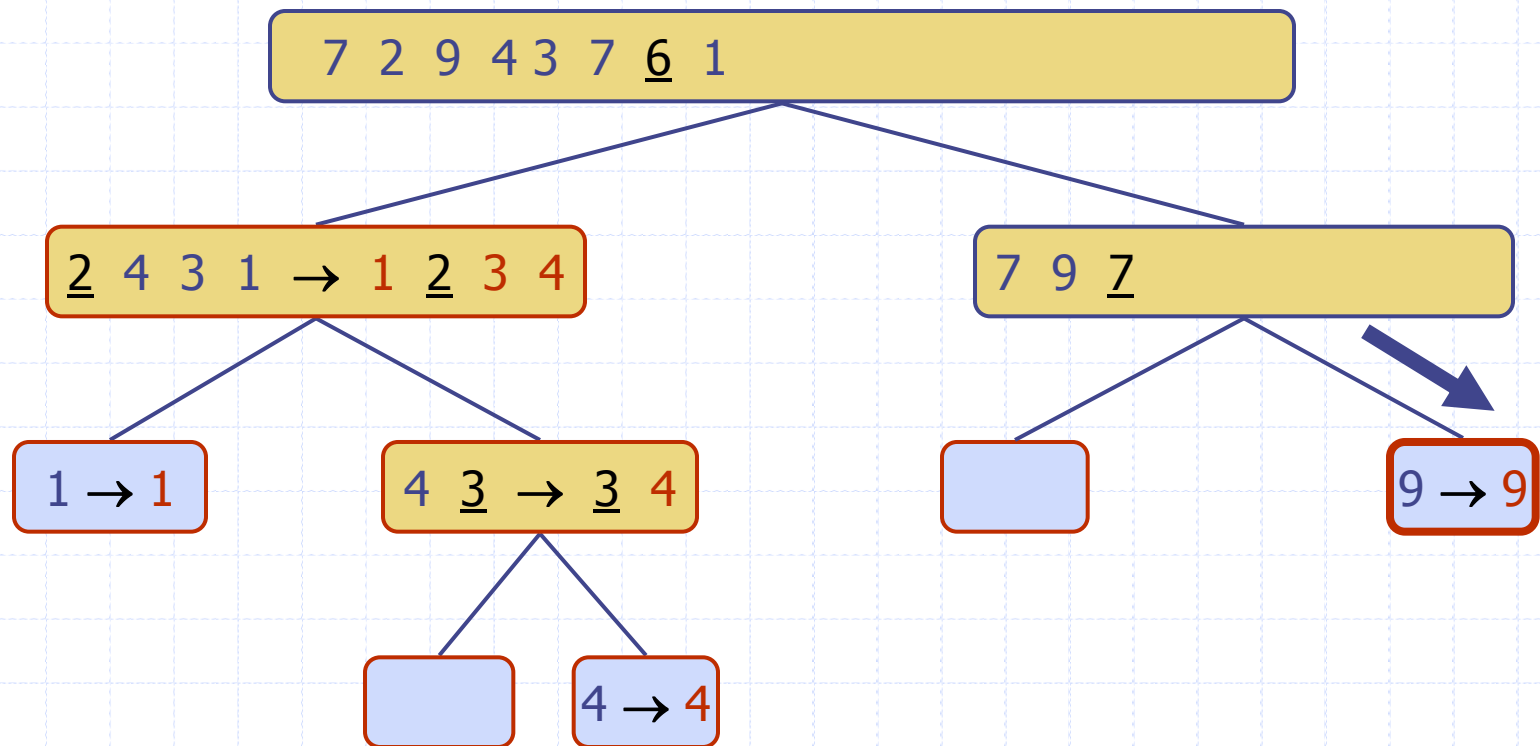
Execution Example (cont.)

◆ Recursive call, pivot selection



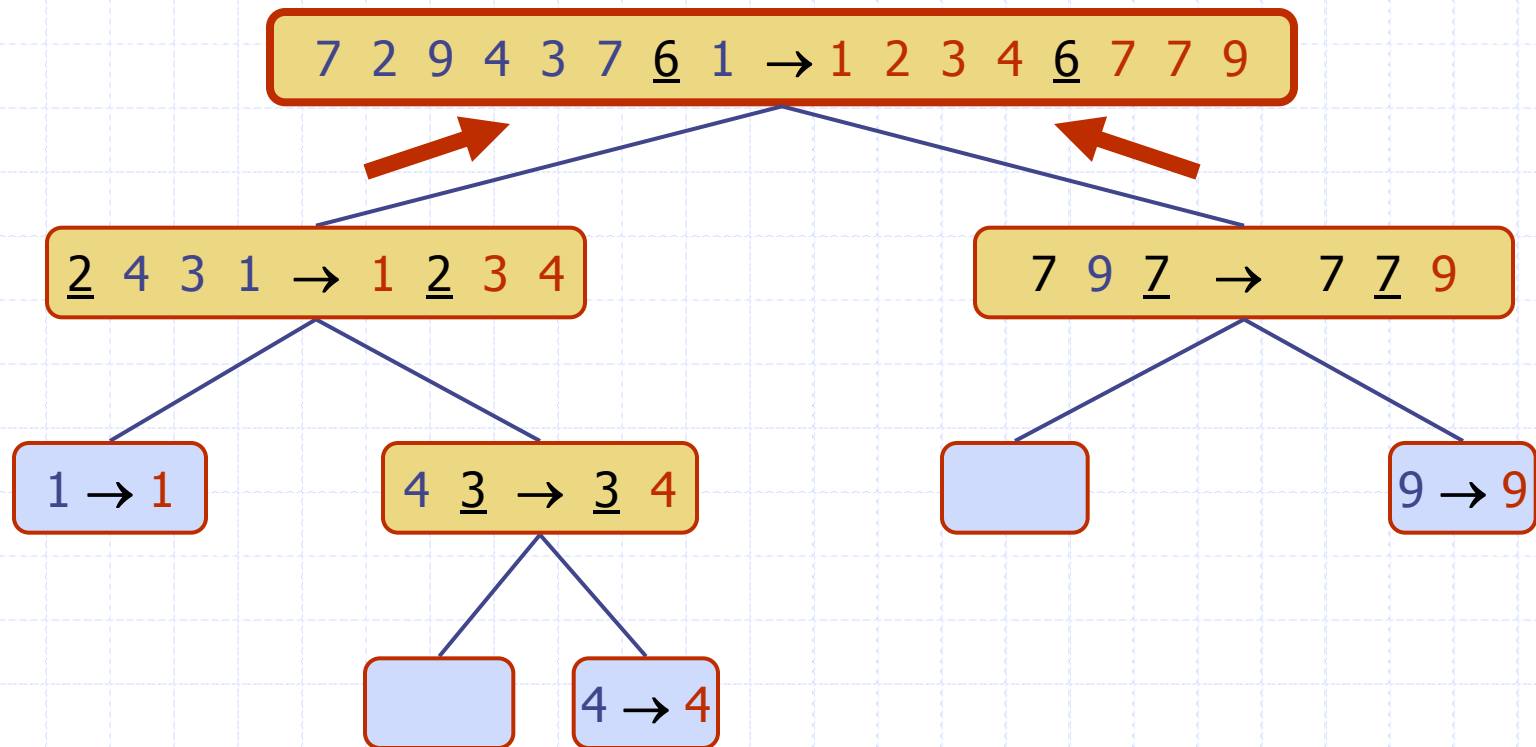
Execution Example (cont.)

◆ Partition, ..., recursive call, base case



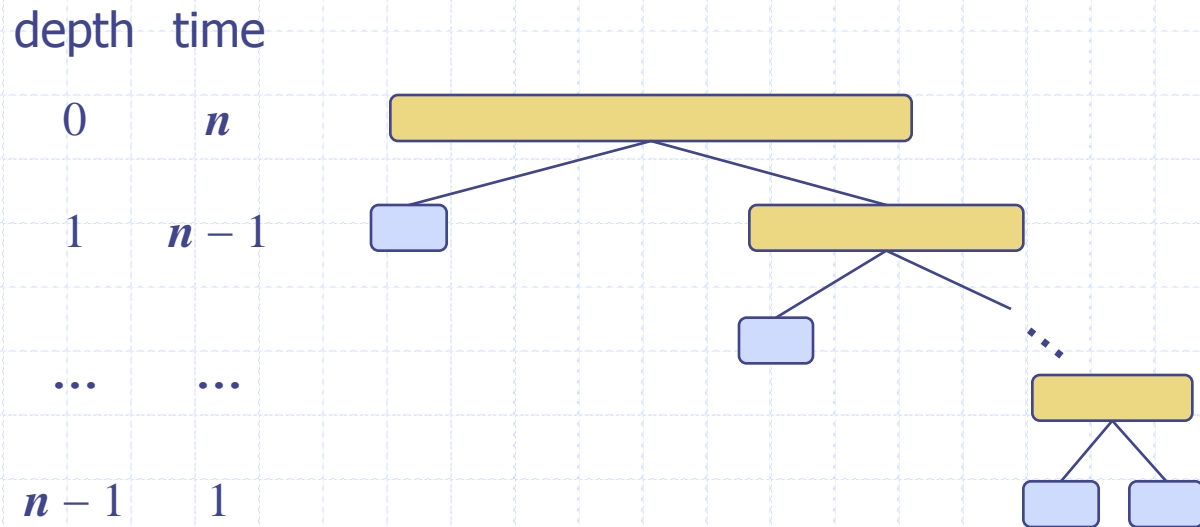
Execution Example (cont.)

◆ Join, join



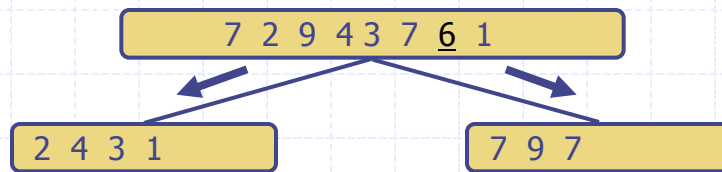
Worst-case Running Time

- ◆ When does the worst-case running time occur?
 - When the pivot is the unique minimum or maximum element
- ◆ In such cases, one of L and G has size $n - 1$ and the other size 0
- ◆ The running time is proportional to the sum
$$n + (n - 1) + \dots + 2 + 1$$
- ◆ Thus, the worst-case running time of quick-sort is
 - $O(n^2)$

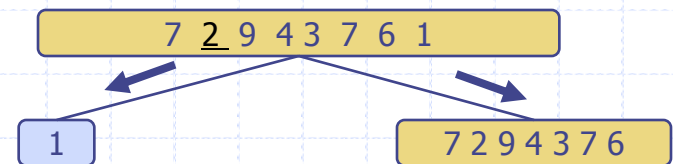


Expected Running Time

- ◆ Consider a recursive call of quick-sort on a sequence of size s
 - **Good call:** the sizes of L and G are each less than $3s/4$
 - **Bad call:** one of L and G has size greater than $3s/4$



Good call



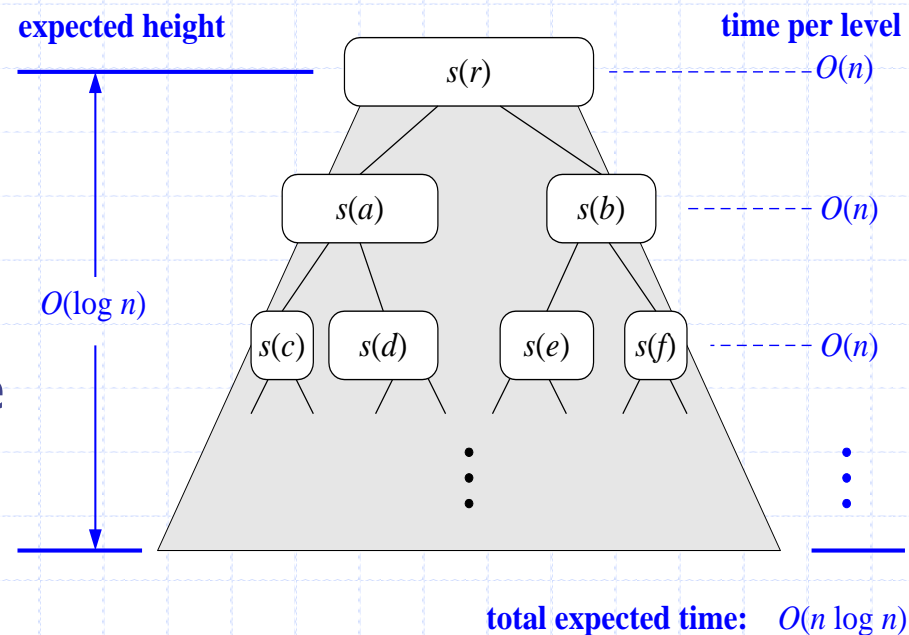
Bad call

- ◆ A call is **good** with what probability?
 - 1/2 of the possible pivots cause good calls:



Expected Running Time, Part 2

- ◆ (Probabilistic Fact: The expected number of coin tosses required in order to get k heads is $2k$)
- ◆ For a node of depth i , we expect
 - How many of the ancestor calls to be good?
 - ◆ $i/2$ ancestors
 - The size of the input sequence for the current call is at most
 - ◆ $(3/4)^{i/2}n$
- ◆ Therefore, we have
 - For a node of depth $2\log_{4/3}n$, the expected input size is one
 - Thus, the expected height of the quick-sort tree is $O(\log n)$
- ◆ The amount of work done at the nodes of the same depth is $O(n)$
- ◆ Hence, the expected running time of quick-sort is $O(n \log n)$



In-Place Quick-Sort



- ◆ Quick-sort can be implemented to run in-place
- ◆ In the partition step, we use replace operations to rearrange the elements of the input sequence such that
 - the elements less than the pivot have rank less than h
 - the elements equal to the pivot have rank between h and k
 - the elements greater than the pivot have rank greater than k
- ◆ The recursive calls consider
 - elements with rank less than h
 - elements with rank greater than k

Algorithm *inPlaceQuickSort*(S, l, r)

Input sequence S , ranks l and r

Output sequence S with the elements of rank between l and r rearranged in increasing order

if $l \geq r$

return

$i \leftarrow$ a random integer between l and r

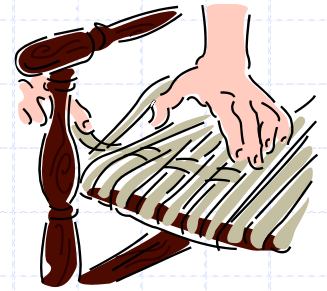
$x \leftarrow S.\text{elemAtRank}(i)$

$(h, k) \leftarrow \text{inPlacePartition}(x)$

inPlaceQuickSort($S, l, h - 1$)

inPlaceQuickSort($S, k + 1, r$)

In-Place Partitioning



- ◆ Perform the partition with pivot Y using two indices to split S into L and EYG (a similar method can split EYG into E and G)

3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9

In-Place Partitioning



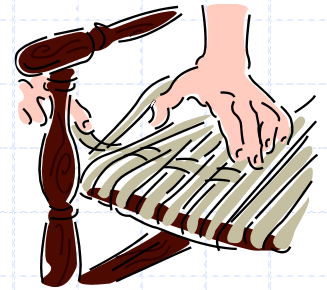
- ◆ Perform the partition with pivot Y using two indices to split S into L and EYG (a similar method can split EYG into E and G)

j k
3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9 ("Y" pivot = 6)

- ◆ Repeat
 - Scan j to the right until finding an element $\geq x$
 - Scan k to the left until finding an element $< x$
 - Swap elements at indices j and k

→ j k ←
3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9

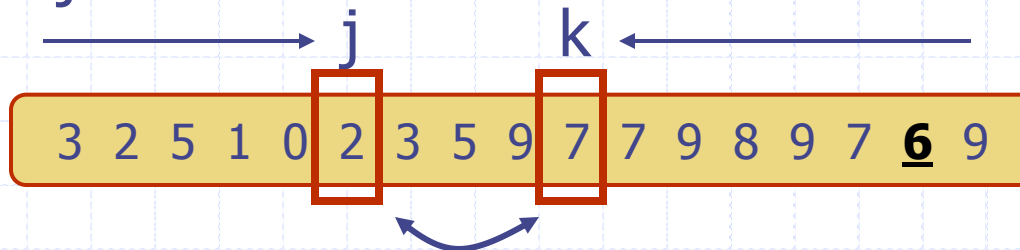
In-Place Partitioning



- ◆ Perform the partition with pivot Y using two indices to split S into L and EYG (a similar method can split EYG into E and G)

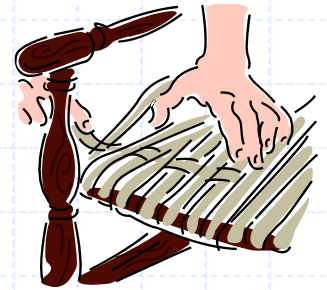
j k
3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9 ("Y" pivot = 6)

- ◆ Repeat
 - Scan j to the right until finding an element $\geq x$
 - Scan k to the left until finding an element $< x$
 - Swap elements at indices j and k
- ◆ Until j and k meet



Quick-Sort

In-Place Partitioning



- ◆ Perform the partition with pivot Y using two indices to split S into L and EYG (a similar method can split EYG into E and G)

j k
3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9 ("Y" pivot = 6)

- ◆ Repeat
 - Scan j to the right until finding an element $\geq x$
 - Scan k to the left until finding an element $< x$
 - Swap elements at indices j and k
- ◆ Until j and k meet

→ j ← k
3 2 5 1 0 2 3 5 9 7 7 9 8 9 7 6 9

(done with all partitioning operations and eventually sorting the array)

Isn't all this Merge-Sort?

- ◆ Quick-Sort is similar to Merge-Sort but with the following key differences
 - (In-place) Quick-Sort uses at most $O(\log n)$ space vs. Merge-Sort uses $O(n)$ space
 - Quick-Sort is $O(n^2)$ vs. Merge-Sort which is $O(n \log n)$
 - ◆ But a “good” Quick-Sort is $O(n \log n)$ or better
 - Quick-Sort implementation details are more friendly towards current computer architecture and thus in practice the “constant” is very small

3-Way Quicksort

- ◆ Instead of partitioning into 2 sets each time, partition into 3 sets:
 - Less than set
 - Equal than set
 - Greater than set
- ◆ Helps slightly with many repeated keys

Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	◆ in-place ◆ slow (good for small inputs)
insertion-sort	$O(n^2)$	◆ in-place, $O(n)$ for almost sorted ◆ slow (good for small inputs)
quick-sort	$O(n \log n)$ expected	◆ in-place, randomized ◆ fastest (good for large inputs)
heap-sort	$O(n \log n)$	◆ in-place, $O(n)$ first results ◆ fast (good for large inputs)
merge-sort	$O(n \log n)$	◆ sequential data access ◆ fast (good for huge inputs)

Demo

- ◆ <https://www.youtube.com/watch?v=kPRA0W1kECg>
- ◆ <https://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html>
- ◆ <https://www.toptal.com/developers/sorting-algorithms>