COMP 215 Assignment #3

Due October 4th (note this is a Thursday) at 11:55PM

1 Description

In this assignment, you will be asked to provide two implementations for the ISparseArray<T> interface. Note that you already used this interface when you used the SparseArray<T> class in the 2^{nd} assignment.

Here are the specific requirements for the assignment:

- 1. The two ISparseArray<T> classes you implement should be called TreeSparseArray<T> and LinearSparseArray<T>, respectively. The latter class should have a constructor that takes a single integer, which is the initial number of slots to allocate (this will make more sense when you read on). The former class should have a no-argument constructor.
- 2. You need to implement iterators for both of these classes. The iterators will both implement the Iterator<IIndexedData<T>> interface. The iterator for the TreeSparseArray<T> class should be called TreeIndexedIterator<T>, and the iterator for LinearSparseArray<T> should be called LinearIndexedIterator<T>. Note that in order to do this, you will need a concrete implementation of the IIndexedData<T> interface. You can use the same implementation for both iterators.
- 3. TreeSparseArray<T> must be based upon the TreeMap generic, and it is almost trivial to implement. You might find that most/all methods are one line long. As an aside, the SparseArray<T> class we provided you in A2 was also based upon a TreeMap.
- 4. LinearSparseArray<T> is a bit more complicated. It should have the following two private member variables:

```
private int [] indices;
private Vector<T> data;
```

The first is an array that should store the indices of all of the data that have been added into the LinearSparseArray. The second is a vector that stores all of the data objects that have been added into the LinearSparseArray. It is assumed that the *i*th item in indices is the index for the *i*th item in data. In addition to these two member variables, you can add whatever other member variables you want.

2 Optimizing Performance

This assignment primarily is meant to provide you with more practice building class hiearchies so that you can gain a better understanding of object-oriented design principles. One reason, among many, that such class hierarchies can be valuable is that they allow you to swap in different implementations of the same abstraction for performance optimization without modifying the code that uses the abstraction. A small part of this assignment (2 test cases) deals with exploring such performance optimizations. We encourage you not to begin optimizing performance until you have a functional implementation of the required classes. You may, however, want to keep in mind the optimizations discussed below as you implement LinearSparseArray so that you don't do something that will make such optimization more difficult.

At first glance, the required LinearSparseArray implementation may seem odd. The reason for this somewhat strange setup is that it will allow you to come up with an implementation that is very, very fast for certain access patterns—raw arrays (such as indices) are very fast when they store primitive types and are accessed sequentially. As such, this particular setup can be used to implement myArray (a LinearSparseArray) so that the following code runs very quickly (much faster than the SparseArray implementation we provided you in A2):

```
LinearSparseArray<Double> myArray;
...
double total = 0.0;
for (int i = 0; i < 100000000; i++) {
  Double temp = myArray.get (i);
  if (temp != null)
    total += temp;
}</pre>
```

At first glance, this loop may seem silly. For vectors of length n (100000000 in this example) with m elements actually contained in the sparse array, this loop would have a running time of $O(n \log m)$ with a TreeSparseArray. (You should convince yourself this is true.) Using the iterator that all ISparseArray implementations must provide, you could trivially reduce the running time of this computation to O(m) by only iterating over the elements actually contained in the sparse array. (Again, you should convince yourself this is true.)

However, there are many real-world situations in which you cannot successfully use an iterator to traverse the sparse array. As we all know by now, an instance of the SparseDoubleVector class contains an ISparseArray object. It is common for a user of a SparseDoubleVector to scan the array from front to back, perhaps skipping a few entries here and there, calling SparseDoubleVector.getItem to access each element in sequence. The effect of using the SparseDoubleVector class in this way is that a sequence of calls to ISparseArray.get must be executed. Those calls will look very similar to the calls in the loop given above, motivating this as an important test case.

A naive implementation of LinearSparseArray.get will yield a running time of O(nm) on the above loop. By getting that down to O(n), you will be able to get good performance on the aforementioned real use cases.

Because we will be using this in the overall application we are building throughout the semester, you will be graded on not only the correctness, but also the performance of your LinearSparseArray implementation. So, a few of the test cases focus on the speed of your implementation for certain operations. One test checks to see if LinearSparseArray<Double> runs is less than 2/3 of the time of the tree-based SparseArray<Double> we gave you for A2, for a series of very well-behaved put and get operations. Another checks whether LinearSparseArray<Double> runs in less than 1/2 of the time for the same test.

3 Optimization Hints

The required speedups require careful optimization, but they are not pushing the limits of what is possible. For example, on my machine, my reference implementation of LinearSparseArray<Double> takes less than 1/5 as long as SparseArray<Double> for this particular test. You can do whatever you need to do in order to make your LinearSparseArray<T> implementation fast for these speed tests,

as long as you use the indices and data member variables described above. Here are some suggestions that you might consider:

- 1. Always maintain indices and data so that positions stored in indices are always in sorted order. But don't make any calls to sort to do this. If someone puts an item with a position that is greater than you've ever seen before, just append the index and the data to the end of indices and data, respectively. This will take O(1) time. It is this situation where the test cases require you to be super fast, and you will! If, however, someone adds to a position that is not at the end, then just use a slow, O(m) algorithm to add the item in, sliding everything down to maintain a sorted order for indices. You'll be slow for out-of-order insertions, but that's not what you'll be timed on.
- 2. Always keep some empty space at the end of indices and data so that you can very quickly append new data. Then, when you run out of space, use a "doubling" algorithm. Just make both indices and data twice as long as they were before—now they'll have a bunch of empty space at the end. So each time they fill up, you double them. That way, the number of times you need to increase the size of both is logarithmic in the number of insertions, and you allocate more space very infrequently.
- 3. When someone calls get, the naive thing would be for you to just linearly search through indices to find the item they are looking for. Instead, you could remember the last slot in indices that you retrieved a value from, and start your search from there—if you don't find the position you are looking for, then you do an O(m) search. The great thing about this is that if someone goes through the array in order, you will have a super-fast O(1) retrieval time for each element.

4 Grading

Passing all of the test cases is 70% of your grade. Your design (that is, your class hierarchy) is 10% of your grade. And documentation counts for 20% of your grade. The guidelines from A1 for commenting your code apply to A3 as well.

As before, keep in mind that we will be looking over your code. If you don't meet the requirements outlined in the previous section, we reserve the right to not give credit for some of the test cases that you passed.

5 What You Need To Do

You should first download the .jar file, the file of test cases (SparseArrayTester.java), and the two interface files IIndexedData.java and ISparseArray.java. Note that every file except for the test code is identical to what you used for A2. Once you do this, create a project, name it HW3.drjava, add all of the interfaces to it, and add the .jar file (which contains the SparseArray class implementation) to it. When you are ready to test, you can add the test code to your project.

Just like last time, you may not modify any of the interfaces or the sparsearray.jar file in any way.

6 Turnin

You should add all of your source files and the .jar file into a DrJava project as described above. On Owlspace, you should turn in the HW3.drjava project file that DrJava creates when you create your project, as well as any and all .java source files or .jar files that you create or use in your project. The goal here is for us to be able to simply fire up DrJava using your HW3.drjava project, and everything

should work without having to move files around or add files to the project. Please comment out any debugging output from your code before you turn it in.

Please upload each file directly. Do not create an archive (zip, rar, etc.).

7 Academic Honesty

Please keep the academic honesty policy in mind as you work on the assignment.