

EECS 370 - Lecture 6

Function Calls



Announcements



- Project 1a due tonight
- Project 1s+m due next Thursday
- HW 1 Posted
 - Due Monday 9/22
- Let us know about exam conflicts in the **next week**
 - Form on Ed

Datatype	size (bytes)
char	1
short	2
int	4
double	8

Reminder: Memory Alignment

```
short  a[100];  
char   b;  
int    c;  
double d;  
short  e;  
struct {  
    char f;  
    int  g[1];  
    char h;  
} i;
```

- *Problem:* Assume data memory starts at address 100 and no reordering, calculate the total amount of memory needed

$a = 2 \text{ bytes} * 100 = 200$

$b = 1 \text{ byte}$

$c = 4 \text{ bytes}$

$d = 8 \text{ bytes}$

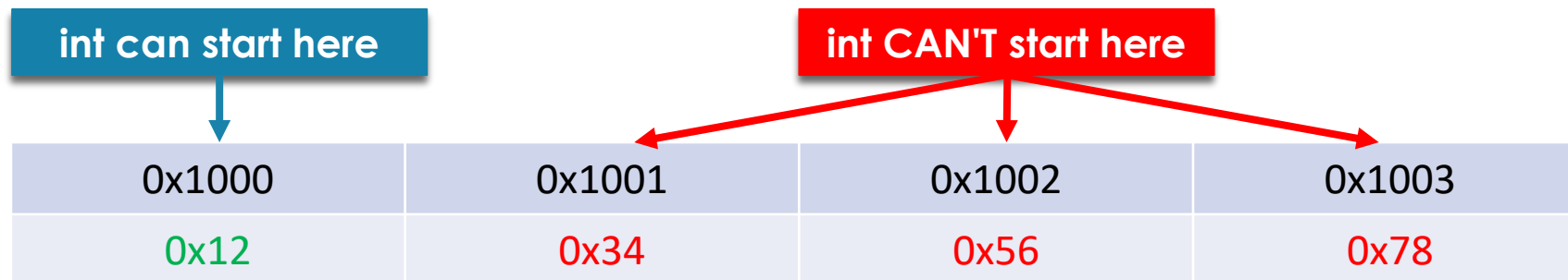
$e = 2 \text{ bytes}$

$i = 1 + 4 + 1 = 6 \text{ bytes}$

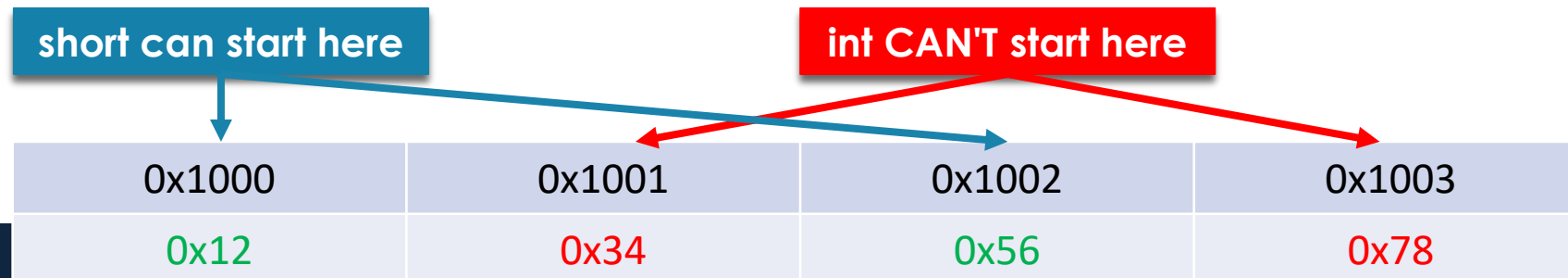
total = 221, right or wrong?

Reminder: Memory Alignment

- Most modern ISAs require that data be aligned
 - An N-byte variable must start at an address A, such that $(A\%N) == 0$
- For example, starting address of a 32 bit **int** must be divisible by 4



- Starting address of a 16 bit **short** must be divisible by 2



Reminder: Golden Rule of Alignment

```
char  c;  
short s;  
int   i;
```

- Every (primitive) object starts at an address divisible by its size
- "Padding" is placed in between objects if needed

0x1000	0x1001	0x1002	0x1003	0x1004	0x1005	0x1006	0x1007
[c]	[padding]	[s]		[i]			

- But what about non-primitive data types?
 - Arrays? Treat as independent objects
 - Structs? Trickier...

Structure Alignment

- In addition, for structs...
 - Identify largest (potentially nested) **primitive** component
 - Starting address of overall struct is aligned based on the largest component
 - Padded in the back so total size is a multiple of the largest component

```
char c;  
  
struct {  
    char c;  
    int i;  
} s[2];
```

1000	1001	1002	1003	1004	1005	1006	1007	1008	1009	100A	100B	100C	100D	100E	100F
c	[pad]	[pad]	[pad]	s[0].c	[pad]	[pad]	[pad]	s[0].i				s[1].c	[pad]	[pad]	[pad]

Guaranteed to lay
out each instance
identically

Structure Alignment

- Solution: in addition to laying out each field according to Golden Rule...
 - Identify largest (primitive) field
 - Starting address of overall struct is aligned based on the largest field
 - Padded in the back so total size is a multiple of the largest primitive

```
char c;  
  
struct {  
    char c;  
    int i;  
} s[2];
```

1000	1001	1002	1003	1004	1005	1006	1007	1008	1009	100A	100B	100C	100D	100E	100F
c	[pad]	[pad]	[pad]	s[0].c	[pad]	[pad]	[pad]	s[0].i				s[1].c	[pad]	[pad]	[pad]

Guaranteed to lay
out each instance
identically

Structure Example

```
struct {  
    char w;  
    int x[3];  
    char y;  
    short z;  
}
```

Poll: What boundary should this struct be aligned to?

- a) 1 byte
- b) 4 bytes
- c) 12 bytes
- d) 2 bytes
- e) 19 bytes

- Assume struct starts at location 1000,
 - char w → 1000
 - x[0] → 1004-1007, x[1] → 1008 – 1011, x[2] → 1012 – 1015
 - char y → 1016
 - short z → 1018 – 1019

Total size = 20 bytes!

Calculating Load/Store Addresses for Variables

Datatype	size (bytes)
char	1
short	2
int	4
double	8

```
short a[100];  
char b;  
int c;  
double d;  
short e;  
struct {  
    char f;  
    int g[1];  
    char h;  
} i;
```

- Problem:* Assume data memory starts at address 100 and no reordering, calculate the total amount of memory needed

a = 200 bytes (100-299)

b = 1 byte (300-300)

c = 4 bytes (304-307)

d = 8 bytes (312-319)

e = 2 bytes (320-321)

struct: largest field is 4 bytes, start at 324

f = 1 byte (324-324)

g = 4 bytes (328-331)

h = 1 byte (332-332)

i = 12 bytes (324-335)

236 bytes total!! (compared to 221, originally)

Data Layout – Why?

- Does gcc (or another compiler) reorder variables in memory to avoid padding?
- Only outside structs
- C99 forbids reordering elements inside a struct
- The programmer (i.e., you) are expected to manage data layout of variables for your program and structs.
- Two optimal strategies:
 - Order fields in struct by datatype size, smallest first
 - Or by largest first

Instruction Set Architecture (ISA) Design Lectures

- Lecture 2: ISA - storage types, binary and addressing modes
- Lecture 3 : LC2K
- Lecture 4 : ARM
- Lecture 5 : Converting C to assembly – basic blocks
- **Lecture 6 : Converting C to assembly – functions**
- Lecture 7 : Translation software; libraries, memory layout



LEGv8 Conditional Instructions

- Two varieties of conditional branches
 1. One type compares a register to see if it is equal to zero.
 2. Another type checks the condition codes set in the status register.

Conditional branch	compare and branch on equal 0	CBZ X1, 25	if (X1 == 0) go to PC + 100	Equal 0 test; PC-relative branch
	compare and branch on not equal 0	CBNZ X1, 25	if (X1 != 0) go to PC + 100	Not equal 0 test; PC-relative branch
	branch conditionally	B.cond 25	if (condition true) go to PC + 100	Test condition codes; if true, branch

- Let's look at the first type: CBZ and CBNZ
 - CBZ: Conditional Branch if Zero
 - CBNZ: Conditional Branch if Not Zero

LEGv8 Conditional Instructions

- CBZ/CBNZ: test a register against zero and branch to a PC relative address
 - The relative address is a 19 bit signed integer representing the number of instructions (not bytes) to branch. Recall instructions are 4 bytes

Conditional branch	compare and branch on equal 0	CBZ X1, 25	if (X1 == 0) go to PC + 100	Equal 0 test; PC-relative branch
	compare and branch on not equal 0	CBNZ X1, 25	if (X1 != 0) go to PC + 100	Not equal 0 test; PC-relative branch
	branch conditionally	B.cond 25	if (condition true) go to PC + 100	Test condition codes; if true, branch

- Example: CBNZ X3, Again
 - If X3 doesn't equal 0, then branch to label "Again"
 - "Again" is an offset from the PC of the current instruction (CBNZ)
 - Why does "25" in the above table result in PC + 100?1

LEGv8 Conditional Instructions

- Motivation:
 - Some types of branches makes sense to check if a certain value is zero or not
 - while(a)
 - But not all:
 - if(a > b)
 - if(a == b)
 - Using an extra **program status register** to check for various conditions allows for a greater breadth of branching behavior

LEGv8 Conditional Instructions Using FLAGS

- FLAGS: NZVC record the results of (arithmetic) operations
Negative, Zero, oVerflow, Carry—not present in LC2K
- We explicitly set them using the “set” modification to ADD/SUB etc.
- Example: ADDS causes the 4 flag bits to be set according as the outcome is negative, zero, overflows, or generates a carry

Category	InstructionExample		Meaning	Comments
Arithmetic	add	ADD X1, X2, X3	$X1 = X2 + X3$	Three register operands
	subtract	SUB X1, X2, X3	$X1 = X2 - X3$	Three register operands
	add immediate	ADDI X1, X2, 20	$X1 = X2 + 20$	Used to add constants
	subtract immediate	SUBI X1, X2, 20	$X1 = X2 - 20$	Used to subtract constants
	add and set flags	ADDS X1, X2, X3	$X1 = X2 + X3$	Add, set condition codes
	subtract and set flags	SUBS X1, X2, X3	$X1 = X2 - X3$	Subtract, set condition codes
	add immediate and set flags	ADDIS X1, X2, 20	$X1 = X2 + 20$	Add constant, set condition codes
	subtract immediate and set flags	SUBIS X1, X2, 20	$X1 = X2 - 20$	Subtract constant, set condition codes



ARM Condition Codes Determine Direction of Branch--continued

	Encoding	Name (& alias)	Meaning (integer)	Flags
→	0000	EQ	Equal	Z==1
→	0001	NE	Not equal	Z==0
	0010	HS (CS)	Unsigned higher or same (Carry set)	C==1
	0011	LO (CC)	Unsigned lower (Carry clear)	C==0
	0100	MI	Minus (negative)	N==1
	0101	PL	Plus (positive or zero)	N==0
	0110	VS	Overflow set	V==1
	0111	VC	Overflow clear	V==0
	1000	HI	Unsigned higher	C==1 && Z==0
	1001	LS	Unsigned lower or same	!(C==1 && Z==0)
→	1010	GE	Signed greater than or equal	N==V
→	1011	LT	Signed less than	N!=V
→	1100	GT	Signed greater than	Z==0 && N==V
→	1101	LE	Signed less than or equal	!(Z==0 && N==V)
→	1110	AL	Always	Any
	1111	NV [†]		

Need to know
the 7 with the
red arrows

```
CMP X1, X2  
B.LE Label1
```

For this example,
we branch if X1 is
≥ to X2

Conditional Branches: How to use

- CMP instruction lets you compare two registers.
 - Could also use SUBS etc.
 - That could save you an instruction.
- B.cond lets you branch based on that comparison.

- Example:

```
CMP    X1, X2  
B.GT   Label1
```

- Branches to Label1 if X1 is greater than X2.

Branch—Example

- Here's how we can convert an if/else statement to ARM (assume x is in X1, y in X2):

```
int x, y;  
if (x == y)  
    x++;  
else  
    y++;  
// ...
```

Using Labels

```
CMP X1, X2  
B.NE L1  
ADD X1, X1, #1  
B L2  
L1: ADD X2, X2, #1  
L2: ...
```

Note that conditions in assembly are often the inverse of the "if" condition. Why?

Without Labels

```
CMP X1, X2  
B.NE 3  
ADD X1, X1, #1  
B 2  
ADD X2, X2, #1
```

Assemblers must deal with labels and assign displacements

Loop—Example

// assume all variables are long long integers (64 bits or 8 bytes)
// i is in X1, start of a is at address 800, sum is in X2

```
sum = 0;  
for (i=0 ; i < 10 ; i++) {  
    if (a[i] >= 0) {  
        sum += a[i];  
    }  
}
```

of branch instructions
= $3 \times 10 + 1 = 31$

a.k.a. while-do template

	MOV	X1, XZR
	MOV	X2, XZR
Loop1:	CMPI	X1, #10
	B.EQ	endLoop
	LSL	X6, X1, #3
	LDUR	X5, [X6, #800]
	CMPI	X5, #0
	B.LT	endif
	ADD	X2, X2, X5
endif:	ADDI	X1, X1, #1
	B	Loop1
endLoop:		

Agenda

- Using branches more generally
- **Function calls and the call stack**
- Assigning variables to memory locations
- Saving registers
- Caller/callee example

Implementing Functions

Poll: What's wrong with this approach?

- Does this assembly code do what we need?

```
int mult_2(int x) {  
    int temp = x*2;  
    return temp;  
}  
  
int GLOBAL = 6;  
  
int main() {  
    int result = mult_2(GLOBAL+1);  
    other(result);  
}
```

```
LDURSW X1, [XZR, GLOBAL]  
ADD     X2, X1, #1           // Inc GLOBAL  
STURW   X2, [XZR, X]        // Pass arg  
B       MULT_2              // Execute func  
  
RETURN:  
LDURSW X3, [XZR, TEMP]      // load result  
STURW   X3, [XZR, STRING]   // Pass arg  
B       OTHER              // Execute func  
  
...  
MULT_2:  
LDURSW X1, [XZR, X]         // load arg  
ADD     X2, X1, X1          // mult by 2  
STURW   X2, [XZR, TEMP]     // return result  
B       RETURN             // return
```

Problem 1: Returning from Functions

- Branches so far have hard-coded destination

```
B.NE L1
ADD X1, X1, #1
B L2
L1: ADD X2, X2, #1
L2: ...
```

```
B.NE 3
ADD X1, X1, #1
B 2
ADD X2, X2, #1
```

- This is fine for if-statements, for-loops etc
- But functions can be called from multiple places
 - Meaning we'll return to different spots on each func call! Can't hardcode offset!

```
int func(int x) {
    printf(x * 10);
    return;
}
int helper() {
    func(7);
}
int main() {
    helper();
    func(13);
}
```

Should this return to
"helper" or "main"?

Solution: Indirect Jumps

- Indirect branches or "jumps" don't hardcode destination in instruction
- They index a register whose value holds destination

Unconditional branch	branch	B	2500	go to PC + 10000	Branch to target address; PC-relative
	branch to register	BR	X30	go to X30	For switch, procedure return
	branch with link	BL	2500	X30 = PC + 4; PC + 10000	For procedure call PC-relative

- Use "BL" to **call a function**
 - Destination is hardcoded
 - PC +4 (return address) stored in X30
- Use "BR" to **return from a function**
 - X30 is read for return address
 - Allows us to return to different places

Solution: Indirect Jumps

```
int mult_2(int x) {  
    int temp = x*2;  
    return temp;  
}
```

```
int GLOBAL = 6;
```

```
int main() {  
    int result = mult_2(GLOBAL+1);  
    other(result);  
}
```

Also don't
need "return"
labels

Now MULT_2
can return to
whatever
function
called it

```
LDURSW X1, [XZR, GLOBAL]  
ADD     X2, X1, #1           // Inc GLOBAL  
STURW   X2, [XZR, X]         // Pass arg  
BL      MULT_2               // Execute func  
  
RETURN:  
LDURSW X3, [XZR, TEMP]       // load result  
STURW   X3, [XZR, STRING]    // Pass arg  
BL      OTHER                // Execute func  
  
...  
MULT_2:  
LDURSW X1, [XZR, X]           // load arg  
ADD     X2, X1, X1            // mult by 2  
STURW   X2, [XZR, TEMP]       // return result  
BR      ...                  // return
```


Problem 2: Passing Parameters

For recursive functions,
global variables could be
overwritten

```
int mult_2(int x) {  
    int temp = x*2;  
    return temp;  
}  
  
int GLOBAL = 6;  
  
int main() {  
    int result = mult_2(GLOBAL+1);  
    other(result);  
}
```

```
LDURSW X1, [XZR, GLOBAL]  
ADD     X2, X1, #1           // Inc GLOBAL  
STURW   X2, [XZR, X]        // Pass arg  
BL      MULT_2              // Execute func  
LDURSW  X3, [XZR, TEMP]     // load result  
STURW   X3, [XZR, STRING]   // Pass arg  
BL      OTHER               // Execute func  
  
...  
MULT_2:  
LDURSW  X1, [XZR, X]        // load arg  
ADD     X2, X1, X1          // mult by 2  
STURW   X2, [XZR, TEMP]     // return result  
BR
```

Task 1: Passing parameters

- Where should you put all of the parameters?
 - Registers?
 - Fast access but few in number and wrong size for some objects
 - Memory?
 - Where to put it? And, memory is slow
- ARMv8 solution—and the usual answer:
 - Both
 - Put the first few parameters in registers (if they fit) (X0 – X7)
 - Put the rest in memory on the call stack— **important concept**

Call stack

- ARM conventions (and most other architectures) allocate a region of memory for the “call” stack
 - This memory is used to manage all the storage requirements to simulate function call semantics
 - Parameters (that were not passed through registers)
 - Local variables
 - Temporary storage (when you run out of registers and need somewhere to save a value)
 - Return address
 - Etc.
- Sections of memory on the call stack [**stack frames**] are allocated when you make a function call, and de-allocated when you return from a function
- Grows “down” to lower addresses, usually (but not for LC2K projects)

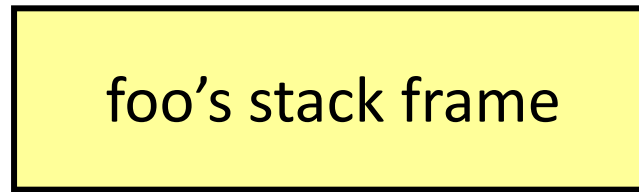
The stack grows as functions are called

FUNCTION CALLS

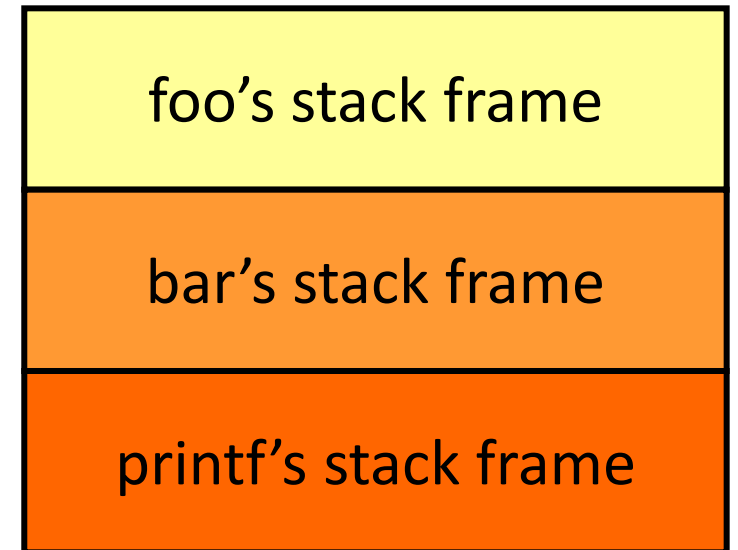
```
void foo()  
{  
    int x, y[2];  
    bar(x);  
}
```

```
void bar(int x)  
{  
    int a[3];  
    printf();  
}
```

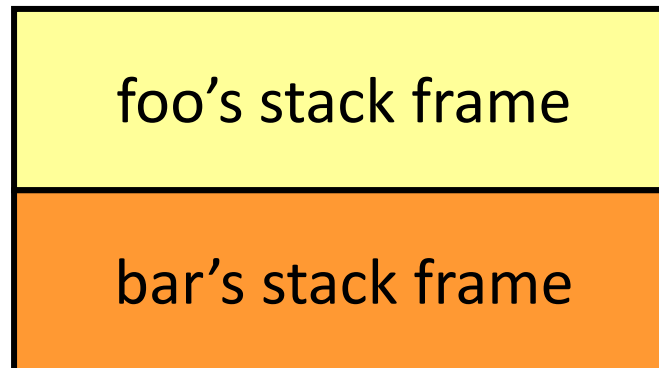
inside foo



bar calls printf



foo calls bar



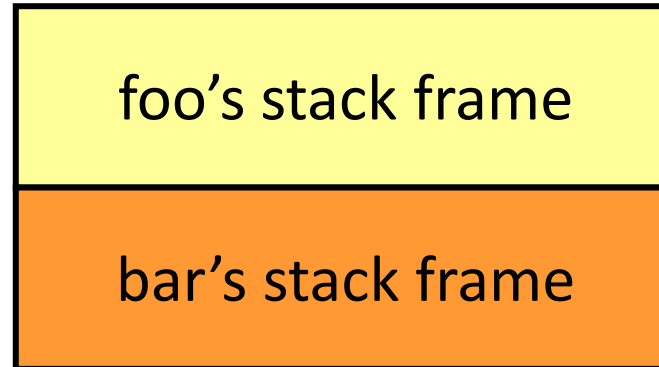
The stack shrinks as functions return

FUNCTION CALLS

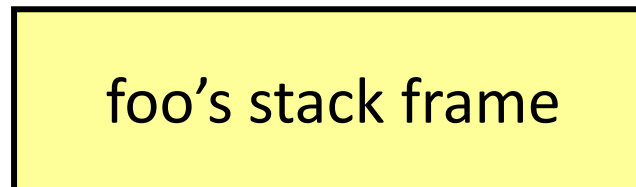
```
void foo()  
{  
    int x, y[2];  
    bar(x);  
}
```

```
void bar(int x)  
{  
    int a[3];  
    printf();  
}
```

printf returns



bar returns



Stack frame contents

FUNCTION CALLS

```
void foo()  
{  
    int x, y[2];  
    bar(x);  
}  
  
void bar(int x)  
{  
    int a[3];  
    printf();  
}
```

foo's stack frame

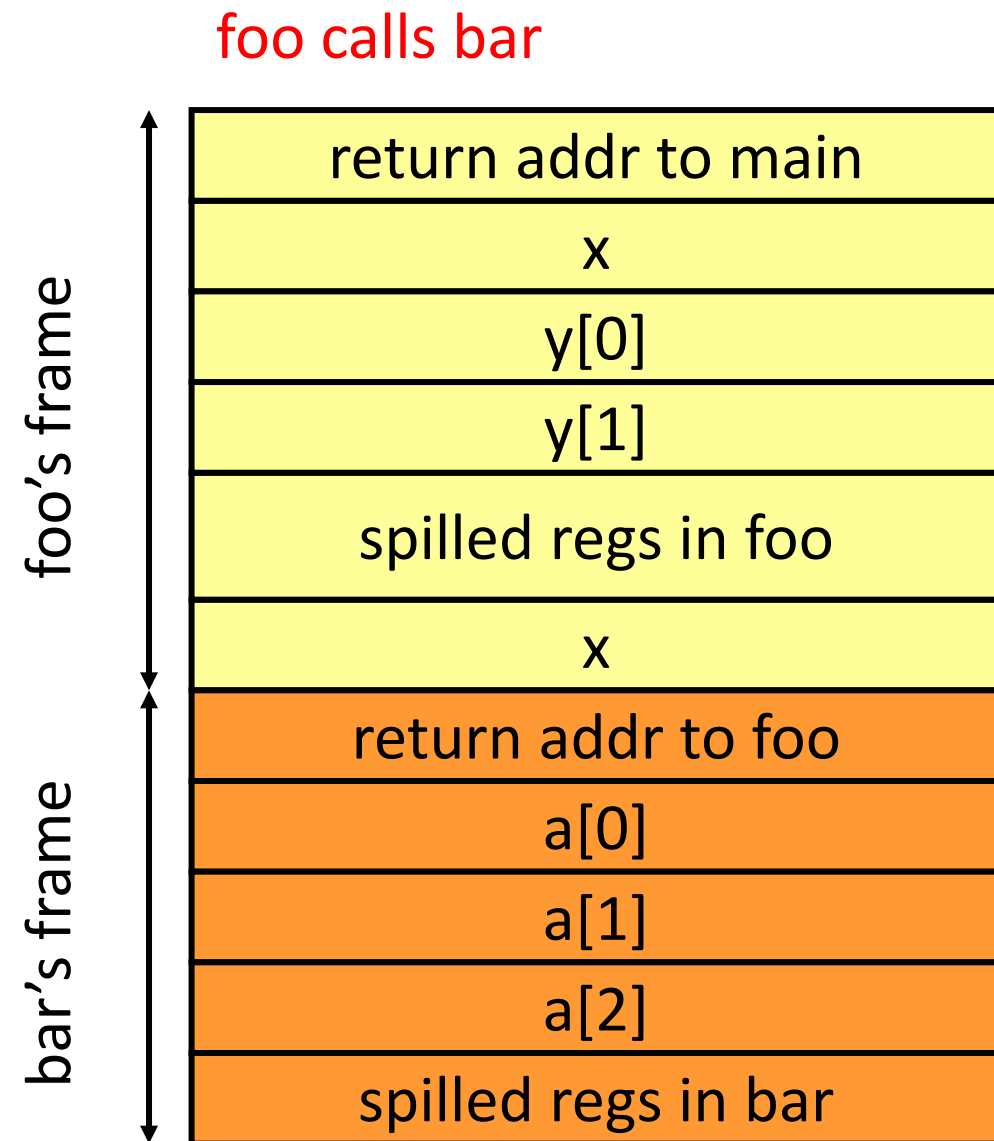
return addr to main
x
y[0]
y[1]
spilled registers in foo

Stack frame contents (2)

```
void foo()
{
    int x, y[2];
    bar(x);
}

void bar(int x)
{
    int a[3];
    printf();
}
```

Spill data—not enough room in x0-x7 for
params and also caller and callee saves



Agenda

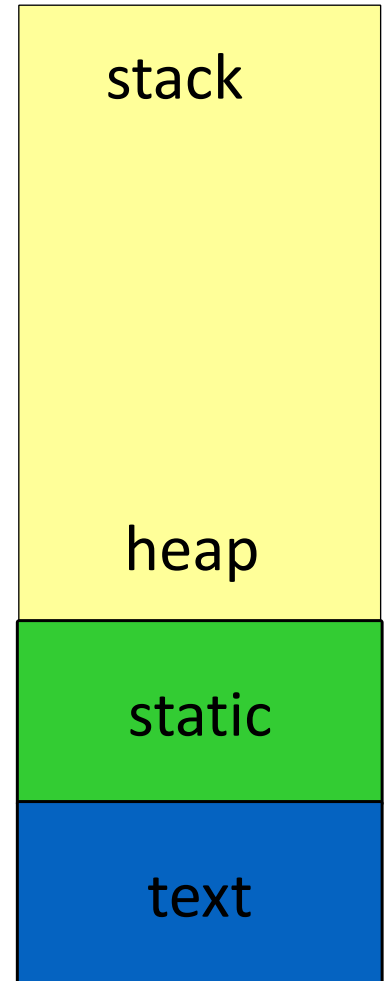
- Using branches more generally
- Function calls and the call stack
- **Assigning variables to memory locations**
- Saving registers
- Caller/callee example

Review: Where do the variables go?

Assigning variables to memory spaces

FUNCTION CALLS

```
int w;  
void foo(int x)  
{  
    static int y[4];  
    char* p;  
    p = malloc(10);  
    //...  
    printf("%s\n", p);  
    free(p);  
}
```



Assigning variables to memory spaces

FUNCTION CALLS

```
int w;  
void foo(int x)  
{  
    static int y[4];  
    char* p;  
    p = malloc(10);  
    //...  
    printf("%s\n", p);  
    free(p);  
}
```

w goes in static, as it's a global

x goes on the stack, as it's a parameter

y goes in static, 1 copy of this!!

p goes on the stack

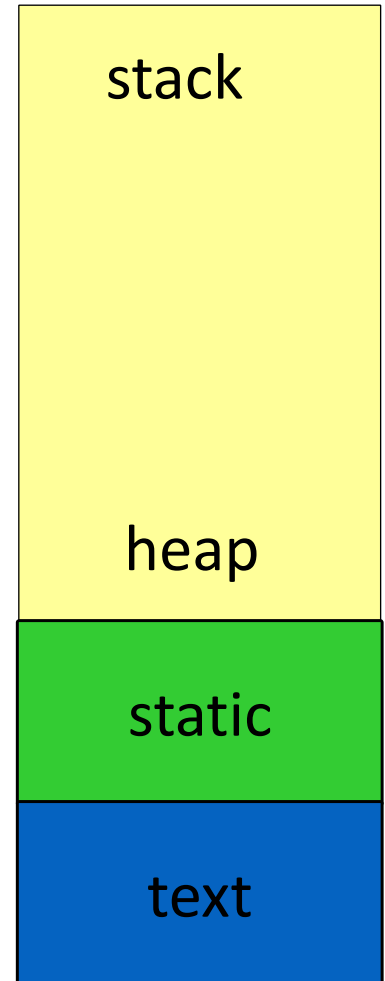
allocate 10 bytes on heap, ptr

set to the address

string literal "%s\n" goes in static,

implicit pointer to string on stack, p goes
on stack

The addresses of local variables
will be different depending on
where we are in the call stack



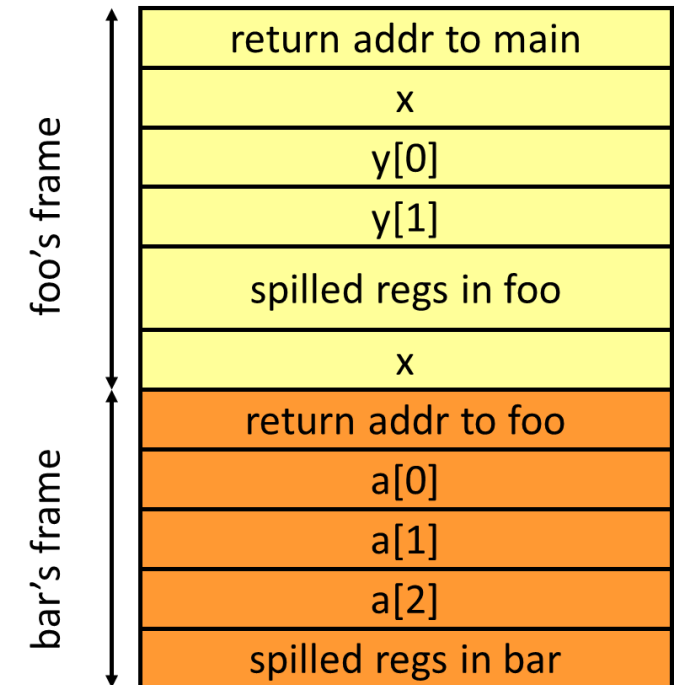
Accessing Local Variables

- Stack pointer (SP):
 - register intended keeps track of current top of stack
 - Aliases to “X28” in LEGv8
- Compiler (or assembly writer) knows relative offsets of objects in stack
- Can modify SP or use load/store offsets
- **DOESN'T USE LABELS!**

```
sub    sp, sp, #16    // make room on stack

mov    x0, #42        // put 42 in x0
stur   x0, [sp, 0]    // store local var on stack

ldur   x1, [sp, 0]    // load back into x1
```

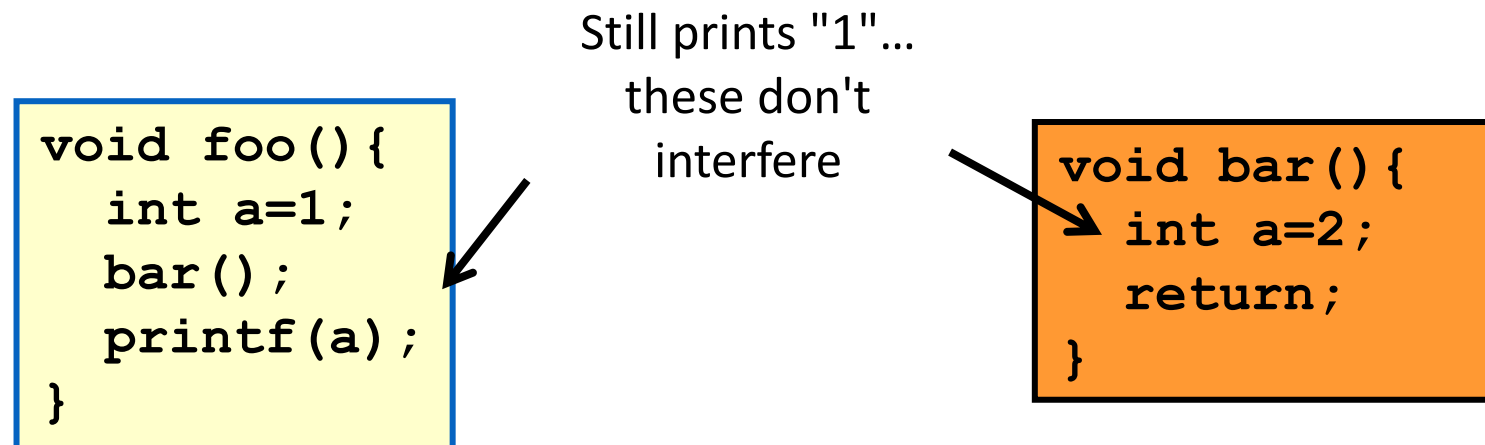


Agenda

- Using branches more generally
- Function calls and the call stack
- Assigning variables to memory locations
- **Saving registers**
- Caller/callee example

Problem 3: Reusing registers

- Higher level languages (like C/C++) provide many abstractions that don't exist at the assembly level
- E.g. in C, each function has its own local variables
 - Even if different function have local variables with the same name, they are independent and guaranteed not to interfere with each other!



What about registers?

- But in assembly, all functions share a small set (e.g. 32) of registers
 - Called functions will overwrite registers needed by calling functions

```
main: movz X0, #1  
      bl  foo  
      bl  printf
```

foo() overwrites
X0 if we don't
do something!!

```
foo: movz X0, #2  
     br  X30
```

- "Someone" needs to save/restore values when a function is called to ensure this doesn't happen

Two Possible Solutions

- Either the **called** function **saves** register values before it overwrites them and **restores** them before the function returns (**callee** saved)...

```
main: movz X0, #1
      bl  foo
      bl  printf
```

```
foo:  stur X0, [stack]
      movz X0, #2
      ldur X0, [stack]
      br  X30
```

- Or the **calling** function **saves** register values before the function call and **restores** them after the function call (**caller** saved)...

```
main: movz X0, #1
      stur X0, [stack]
      bl  foo
      ldur X0, [stack]
      bl  printf
```

```
foo:  movz X0, #2
      br  X30
```

Next Time

- Finish Up Function Calls
- Talks about linking – the final puzzle piece of software

Extra problems

Extra Example: Do-while Loop

// assume all variables are long long integers (64 bits or 8 bytes)
// i is in X1, start of a is at address 100, sum is in X2

```
sum = 0;  
for (i=0 ; i < 10 ; i++) {  
    if (a[i] >= 0) {  
        sum += a[i];  
    }  
}
```

of branch instructions
= $2 * 10 = 20$

a.k.a. do-while template

	MOV	X1, XZR
	MOV	X2, XZR
Loop1:	LSL	X6, X1, #3
	LDUR	X5, [X6, #100]
	CMPI	X5, #0
	B.LT	endif
	ADD	X2, X2, X5
endif:	ADDI	X1, X1, #1
	CMPI	X1, #10
	B.LT	Loop1
endLoop:		

Extra Example: Do-while Loop

// assume all variables are long long integers (64 bits or 8 bytes)
// i is in X1, start of a is at address 100, sum is in X2

```
sum = 0;  
for (i=0 ; i < 10 ; i++) {  
    if (a[i] >= 0) {  
        sum += a[i];  
    }  
}
```

of branch instructions
= $2 \times 10 = 20$

a.k.a. do-while template

Extra Problem – For Your Reference

- Write the ARM assembly code to implement the following C code:

```
// assume ptr is in X1  
// struct {int val; struct node *next;} node;  
// struct node *ptr;
```

```
if ((ptr != NULL) && (ptr->val > 0))  
    ptr->val++;
```

Extra Problem

- Write the ARM assembly code to implement the following C code:

```
// assume ptr is in X1
// struct {int val; struct node *next;} node;
// struct node *ptr;
```

```
if ((ptr != NULL) && (ptr->val > 0))
    ptr->val++;
```

```
cmp r1, #0
beq Endif
ldursw r2, [r1, #0]
cmp r2, #0
b.le Endif
add r2, r2, #1
str r2, [r1, #0]
Endif : ....
```

Extra Class Problem

- How much memory is required for the following data, assuming that the data starts at address 200 and is a 32 bit address space?

```
int a;  
struct {double b, char c, int d} e;  
char* f;  
short g[20];
```

Poll: How much memory?

- a) $x < 40$ bytes
- b) $40 < x < 50$ bytes
- c) $50 < x < 60$ bytes
- d) $60 < x$ bytes