

base_local_planner
::OscillationCostFunction
::resetOscillationFlagsIfPossible



```
graph LR; A["base_local_planner  
::OscillationCostFunction  
::resetOscillationFlagsIfPossible"] --> B["base_local_planner  
::OscillationCostFunction  
::resetOscillationFlags"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'base_local_planner', '::OscillationCostFunction', and '::resetOscillationFlagsIfPossible'. The right box has a white background and contains the text 'base_local_planner', '::OscillationCostFunction', and '::resetOscillationFlags'.

base_local_planner
::OscillationCostFunction
::resetOscillationFlags