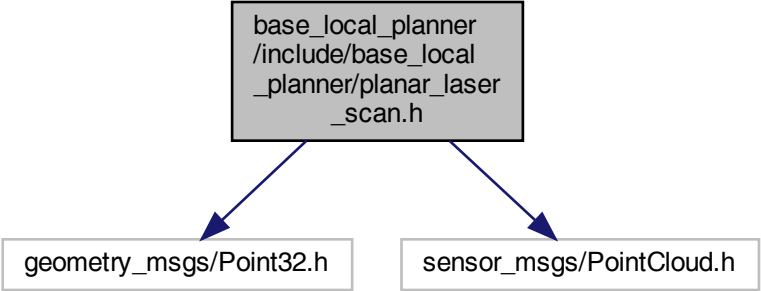


base_local_planner
/include/base_local
_planner/planar_laser
_scan.h



```
graph TD; A["base_local_planner  
/include/base_local  
_planner/planar_laser  
_scan.h"] --> B["geometry_msgs/Point32.h"]; A --> C["sensor_msgs/PointCloud.h"]
```

The diagram illustrates the include relationships for the header file `base_local_planner/include/base_local_planner/planar_laser_scan.h`. This header file includes two other header files: `geometry_msgs/Point32.h` and `sensor_msgs/PointCloud.h`. The relationships are shown as arrows pointing from the top box to the two bottom boxes.

geometry_msgs/Point32.h

sensor_msgs/PointCloud.h