

base\_local\_planner  
::TEST



```
graph LR; A["base_local_planner  
::TEST"] --> B["base_local_planner  
::TrajectoryPlannerTest  
::correctFootprint"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains the text 'base\_local\_planner' followed by '::TEST' on the next line. The right box has a white background and contains the text 'base\_local\_planner' followed by '::TrajectoryPlannerTest' on the next line, and '::correctFootprint' on the third line.

base\_local\_planner  
::TrajectoryPlannerTest  
::correctFootprint