


costmap\_2d::Costmap2DROS  
::movementCB



```
graph LR; A["costmap_2d::Costmap2DROS::movementCB"] --> B["costmap_2d::Costmap2DROS::getRobotPose"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'costmap\_2d::Costmap2DROS::movementCB'. The right box is white and contains the text 'costmap\_2d::Costmap2DROS::getRobotPose'. A blue arrow points from the right side of the left box to the left side of the right box.

costmap\_2d::Costmap2DROS  
::getRobotPose