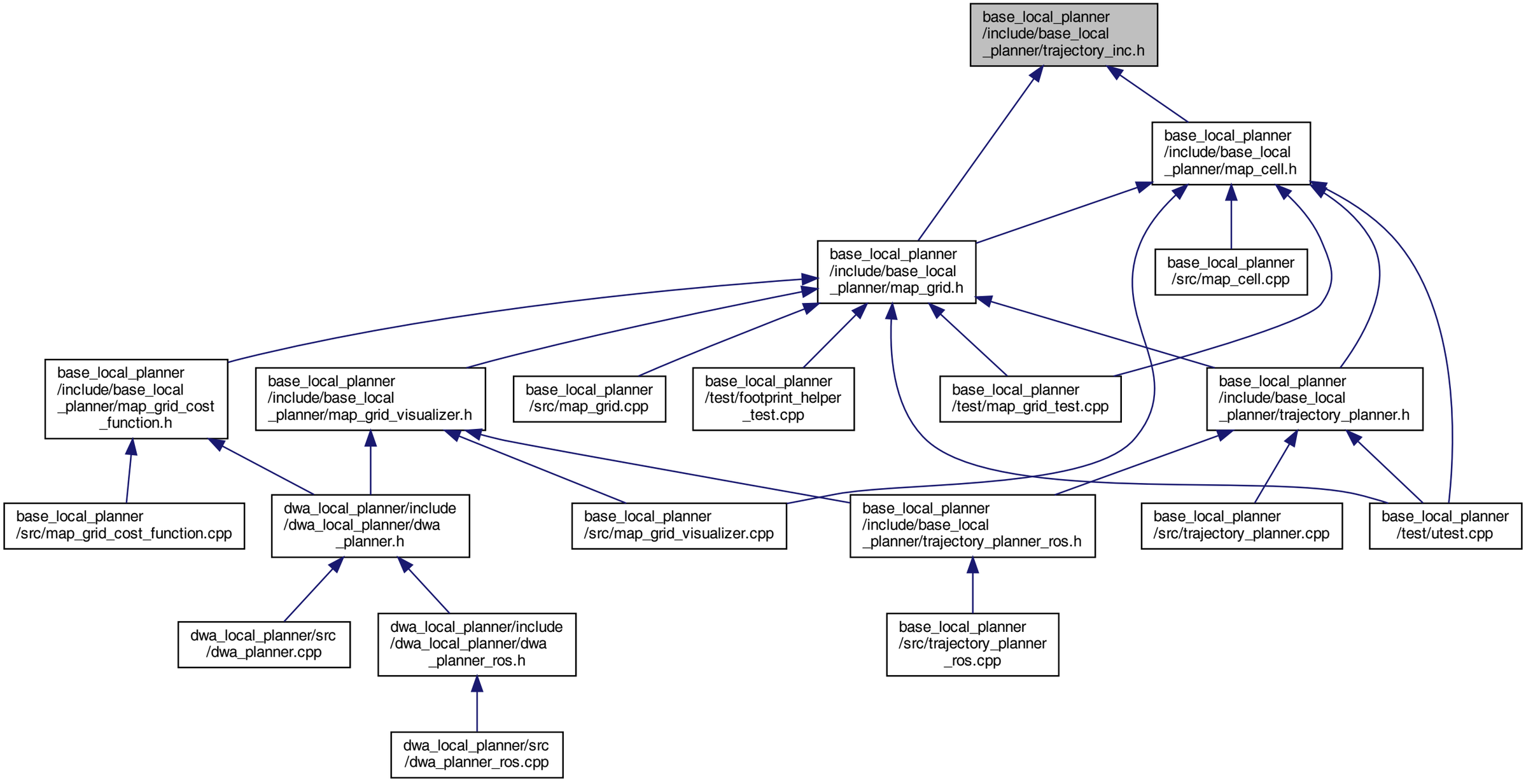
base_local_planner /include/base_local _planner/trajectory_inc.h
base_local_planner /include/base_local _planner/map_cell.h
base_local_planner /include/base_local _planner/map_grid.h
base_local_planner /src/map_cell.cpp
base_local_planner /include/base_local _planner/map_grid_cost _function.h
base_local_planner /include/base_local _planner/map_grid_visualizer.h
base_local_planner /src/map_grid.cpp
base_local_planner /test/footprint_helper _test.cpp
base_local_planner /test/map_grid_test.cpp
base_local_planner /include/base_local _planner/trajectory_planner.h
base_local_planner /src/map_grid_cost_function.cpp
dwa_local_planner/include /dwa_local_planner/dwa _planner.h
base_local_planner /src/map_grid_visualizer.cpp
base_local_planner /include/base_local _planner/trajectory_planner_ros.h
base_local_planner /src/trajectory_planner.cpp
base_local_planner /test/utest.cpp
dwa_local_planner/src /dwa_planner.cpp
dwa_local_planner/include /dwa_local_planner/dwa _planner_ros.h
base_local_planner /src/trajectory_planner _ros.cpp
dwa_local_planner/src /dwa_planner_ros.cpp