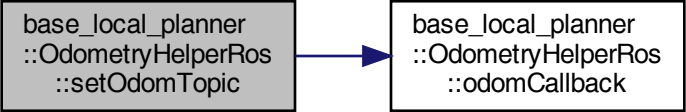


```
base_local_planner  
::OdometryHelperRos  
::setOdomTopic
```



A diagram showing a call from the `setOdomTopic` method to the `odomCallback` method. A blue arrow points from the left box to the right box.

```
base_local_planner  
::OdometryHelperRos  
::odomCallback
```