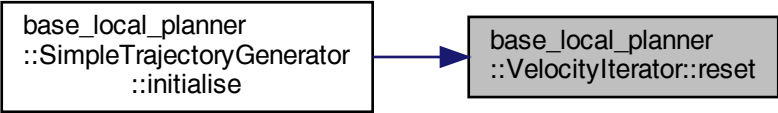


```
base_local_planner  
::SimpleTrajectoryGenerator  
::initialise
```



```
graph LR; A["base_local_planner::SimpleTrajectoryGenerator::initialise"] --> B["base_local_planner::VelocityIterator::reset"]
```

```
base_local_planner  
::VelocityIterator::reset
```