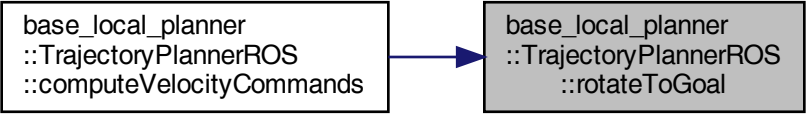


```
base_local_planner  
::TrajectoryPlannerROS  
::computeVelocityCommands
```



A diagram showing a call from the `computeVelocityCommands` method of the `base_local_planner::TrajectoryPlannerROS` class to the `stopWithAccLimits` method of the same class. A blue arrow points from the left box to the right box.

```
base_local_planner  
::TrajectoryPlannerROS  
::stopWithAccLimits
```