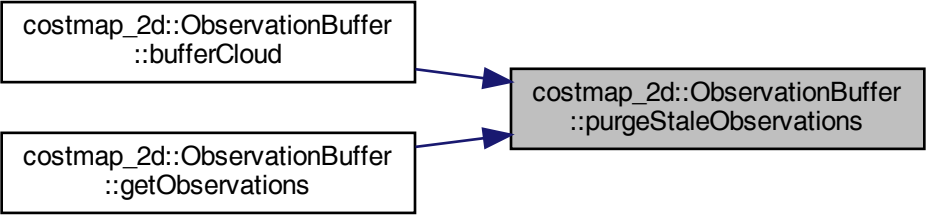


costmap\_2d::ObservationBuffer  
::bufferCloud

costmap\_2d::ObservationBuffer  
::getObservations

costmap\_2d::ObservationBuffer  
::purgeStaleObservations



```
graph LR; A["costmap_2d::ObservationBuffer  
::bufferCloud"] --> C["costmap_2d::ObservationBuffer  
::purgeStaleObservations"]; B["costmap_2d::ObservationBuffer  
::getObservations"] --> C;
```

The diagram illustrates a control flow or data dependency. On the left, there are two white rectangular boxes. The top box contains the text 'costmap\_2d::ObservationBuffer' followed by '::bufferCloud' on a new line. The bottom box contains 'costmap\_2d::ObservationBuffer' followed by '::getObservations' on a new line. On the right, there is a gray rectangular box containing 'costmap\_2d::ObservationBuffer' followed by '::purgeStaleObservations' on a new line. Two blue arrows originate from the right side of the two white boxes and point towards the left side of the gray box, indicating that both 'bufferCloud' and 'getObservations' are inputs or prerequisites for 'purgeStaleObservations'.