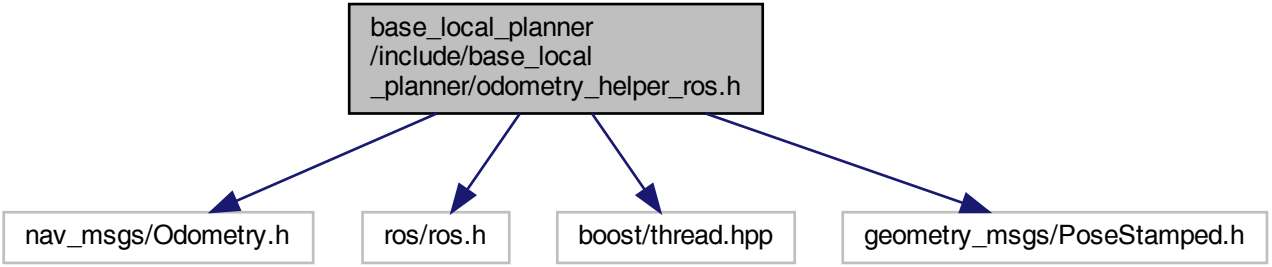


base\_local\_planner  
/include/base\_local  
\_planner/odometry\_helper\_ros.h



```
graph TD; A["base_local_planner  
/include/base_local  
_planner/odometry_helper_ros.h"] --> B["nav_msgs/Odometry.h"]; A --> C["ros/ros.h"]; A --> D["boost/thread.hpp"]; A --> E["geometry_msgs/PoseStamped.h"];
```

The diagram illustrates the include dependencies for the file `base_local_planner/include/base_local_planner/odometry_helper_ros.h`. It is represented as a central grey box with four arrows pointing downwards to four separate white boxes, each containing a header file name.

nav\_msgs/Odometry.h

ros/ros.h

boost/thread.hpp

geometry\_msgs/PoseStamped.h