

costmap_2d::Costmap2DROS
::copyParentParameters



```
graph LR; A["costmap_2d::Costmap2DROS  
::copyParentParameters"] --> B["costmap_2d::move_parameter"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'costmap_2d::Costmap2DROS' on the first line and '::copyParentParameters' on the second line. The right box is white with a black border and contains the text 'costmap_2d::move_parameter'. A dark blue arrow points from the right side of the left box to the left side of the right box.

costmap_2d::move_parameter