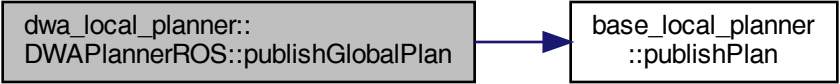


dwa_local_planner::
DWAPlanerROS::publishGlobalPlan



```
graph LR; A[dwa_local_planner::DWAPlanerROS::publishGlobalPlan] --> B[base_local_planner::publishPlan];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'dwa_local_planner::DWAPlanerROS::publishGlobalPlan'. The right box is white and contains the text 'base_local_planner::publishPlan'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

base_local_planner
::publishPlan