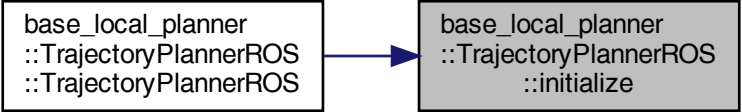


```
base_local_planner  
::TrajectoryPlannerROS  
::TrajectoryPlannerROS
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains three lines of C++ code: 'base_local_planner', '::TrajectoryPlannerROS', and another '::TrajectoryPlannerROS'. The right box is gray with a black border and contains two lines of C++ code: 'base_local_planner' and '::TrajectoryPlannerROS', followed by an indented line ':::initialize'. This represents a function call from the first box to the initialize method of the second box.

```
base_local_planner  
::TrajectoryPlannerROS  
    :::initialize
```