

dwa_local_planner::
DWAPlanner::findBestPath



```
graph LR; A[dwa_local_planner::DWAPlanner::findBestPath] --> B[base_local_planner::SimpleScoredSamplingPlanner::findBestTrajectory];
```

A diagram showing a function call. On the left, a white box with a black border contains the text 'dwa_local_planner::DWAPlanner::findBestPath'. A blue arrow points from the right side of this box to the left side of a gray box with a black border on the right. The gray box contains the text 'base_local_planner::SimpleScoredSamplingPlanner::findBestTrajectory'.

base_local_planner
::SimpleScoredSamplingPlanner
::findBestTrajectory