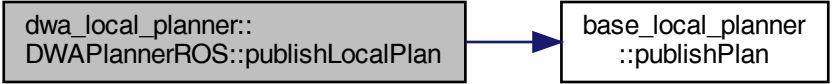


dwa\_local\_planner::  
DWAPlannerROS::publishLocalPlan



```
graph LR; A[dwa_local_planner::DWAPlannerROS::publishLocalPlan] --> B[base_local_planner::publishPlan];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray fill and a black border, containing the text 'dwa\_local\_planner::' on the first line and 'DWAPlannerROS::publishLocalPlan' on the second line. The right box has a white fill and a black border, containing the text 'base\_local\_planner' on the first line and '::publishPlan' on the second line. A solid blue arrow points from the right side of the left box to the left side of the right box.

base\_local\_planner  
::publishPlan