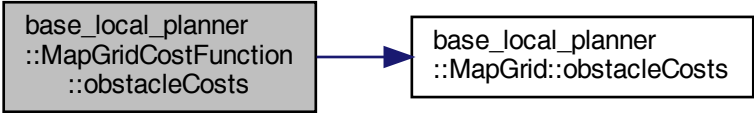


```
base_local_planner  
::MapGridCostFunction  
::obstacleCosts
```



```
graph LR; A["base_local_planner  
::MapGridCostFunction  
::obstacleCosts"] --> B["base_local_planner  
::MapGrid::obstacleCosts"]
```

```
base_local_planner  
::MapGrid::obstacleCosts
```