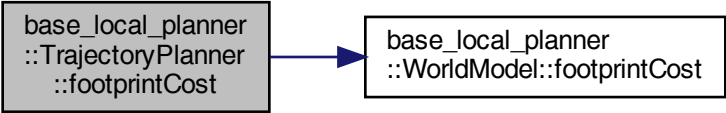


base\_local\_planner  
::TrajectoryPlanner  
::footprintCost



```
graph LR; A["base_local_planner  
::TrajectoryPlanner  
::footprintCost"] --> B["base_local_planner  
::WorldModel::footprintCost"]
```

A diagram illustrating a transition or relationship between two cost functions. On the left, a gray rectangular box contains the text 'base\_local\_planner', '::TrajectoryPlanner', and '::footprintCost' stacked vertically. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'base\_local\_planner', '::WorldModel::footprintCost', and 'footprintCost' stacked vertically.

base\_local\_planner  
::WorldModel::footprintCost  
footprintCost