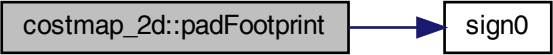


costmap_2d::padFootprint



```
graph LR; A[costmap_2d::padFootprint] --> B[sign0]
```

A diagram showing a flow from a gray box labeled 'costmap_2d::padFootprint' to a white box labeled 'sign0'. A blue arrow points from the right side of the gray box to the left side of the white box.

sign0