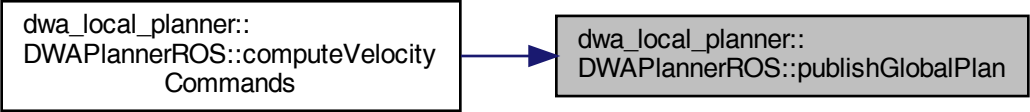


dwa_local_planner::
DWAPlannerROS::computeVelocity
Commands



dwa_local_planner::
DWAPlannerROS::publishGlobalPlan