

navfn::NavfnROS::initialize



```
graph LR; A[navfn::NavfnROS::initialize] --> B[navfn::NavfnROS::makePlan Service];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'navfn::NavfnROS::initialize'. The right box is gray with a black border and contains the text 'navfn::NavfnROS::makePlan Service' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

navfn::NavfnROS::makePlan  
Service