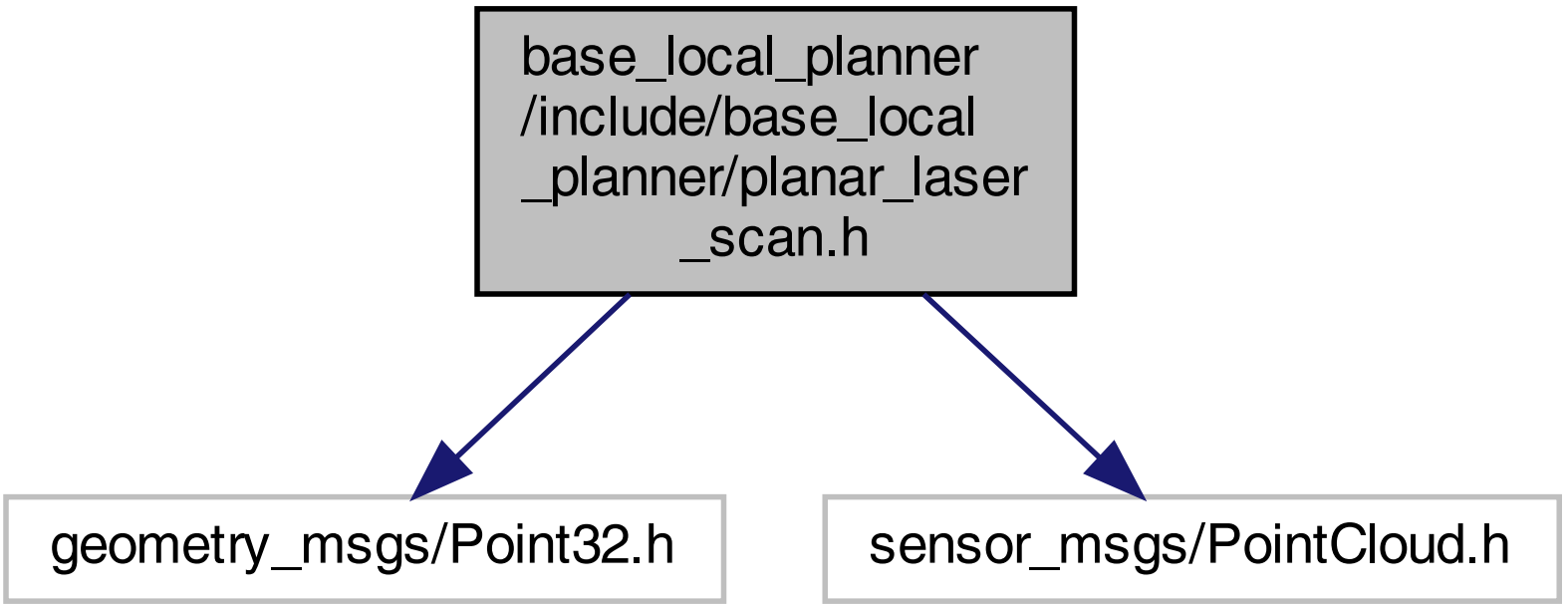
base_local_planner
/include/base_local
_planner/planar_laser
_scan.h
geometry_msgs/Point32.h
sensor_msgs/PointCloud.h