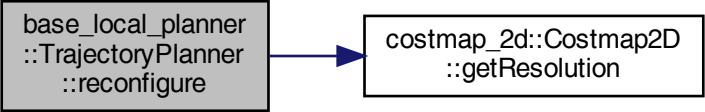


base\_local\_planner  
::TrajectoryPlanner  
::reconfigure



```
graph LR; A["base_local_planner::TrajectoryPlanner::reconfigure"] --> B["costmap_2d::Costmap2D::getResolution"]
```

costmap\_2d::Costmap2D  
::getResolution