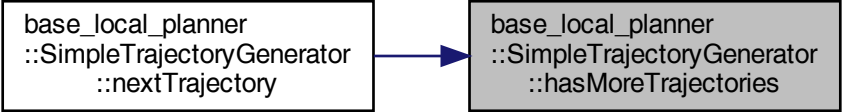


```
base_local_planner  
::SimpleTrajectoryGenerator  
  ::nextTrajectory
```



A diagram illustrating a transition or mapping between two C++ code snippets. A blue arrow points from the left box to the right box. The left box contains a function call to `nextTrajectory`, while the right box contains a call to the `hasMoreTrajectories` member function.

```
base_local_planner  
::SimpleTrajectoryGenerator  
  ::hasMoreTrajectories
```