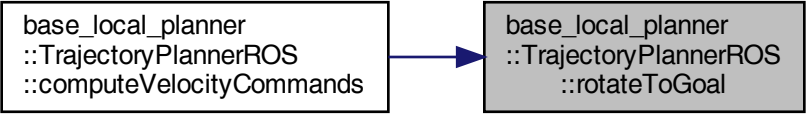


```
base_local_planner  
::TrajectoryPlannerROS  
::computeVelocityCommands
```



A diagram showing a call from the `computeVelocityCommands` method to the `rotateToGoal` method. A blue arrow points from the left box to the right box.

```
base_local_planner  
::TrajectoryPlannerROS  
::rotateToGoal
```