

costmap_2d/include
/costmap_2d/observation.h

```
graph TD; A["costmap_2d/include  
/costmap_2d/observation.h"] --> B["geometry_msgs/Point.h"]; A --> C["sensor_msgs/PointCloud2.h"];
```

The diagram illustrates the include relationships for the `costmap_2d/observation.h` header file. It is shown in a grey box at the top, with two blue arrows pointing down to two white boxes below it. The left box contains `geometry_msgs/Point.h` and the right box contains `sensor_msgs/PointCloud2.h`.

geometry_msgs/Point.h

sensor_msgs/PointCloud2.h