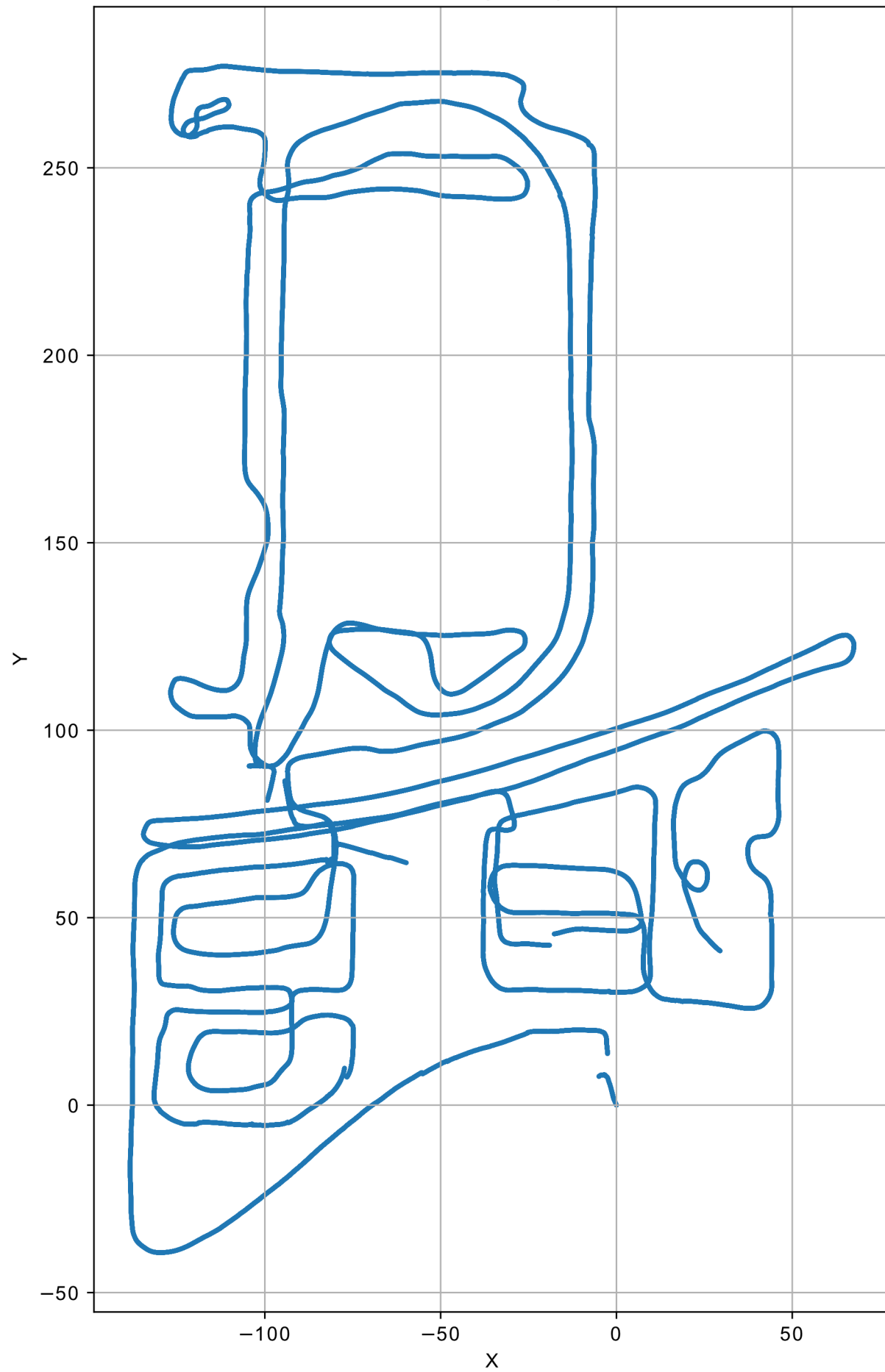
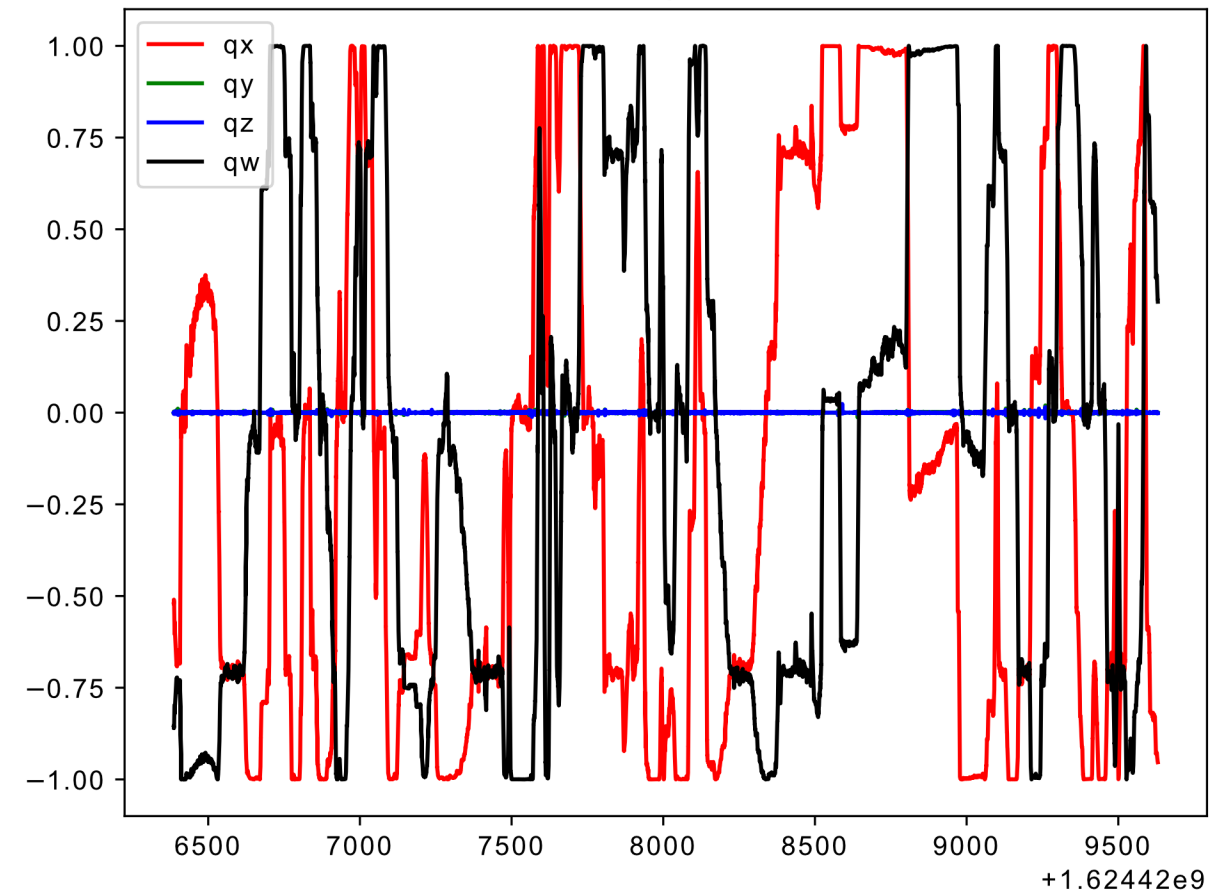


2D trajectory



q



v

