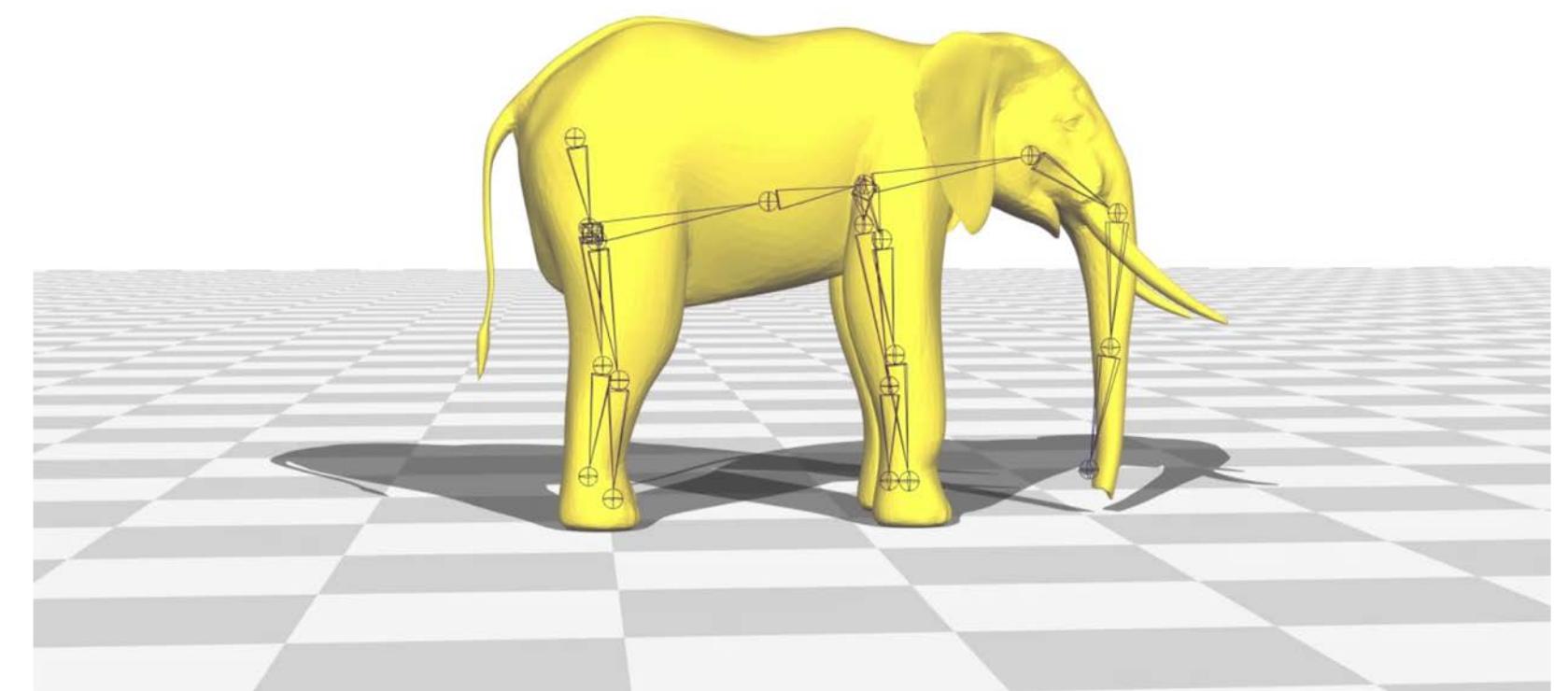
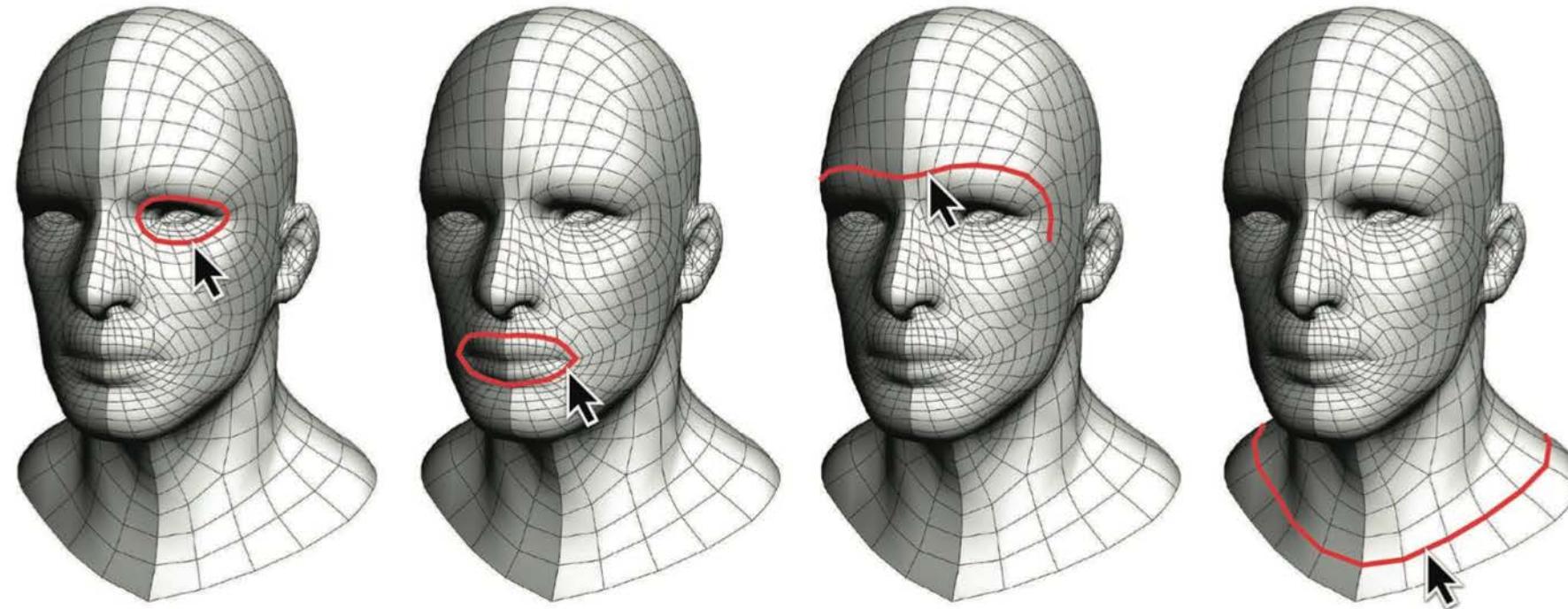


# Summary

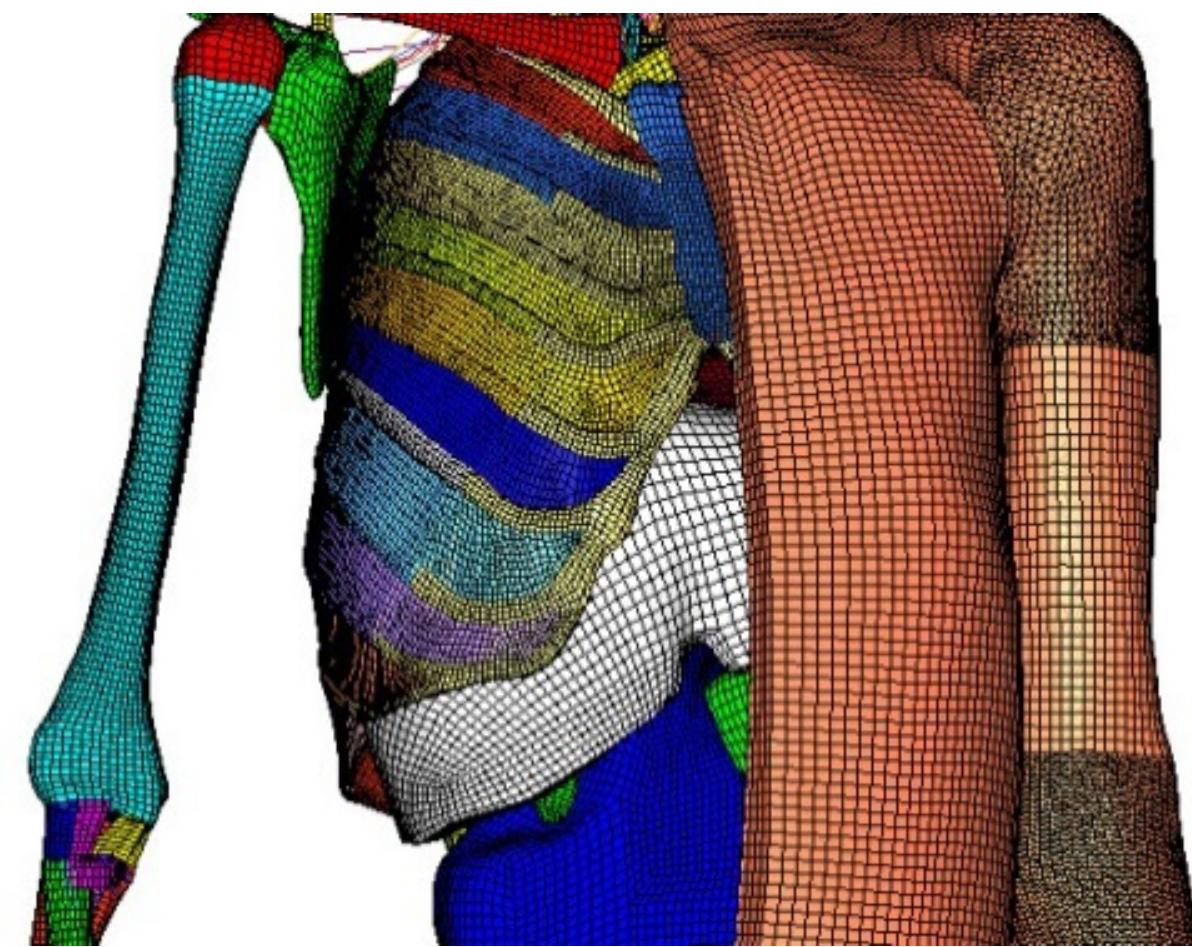
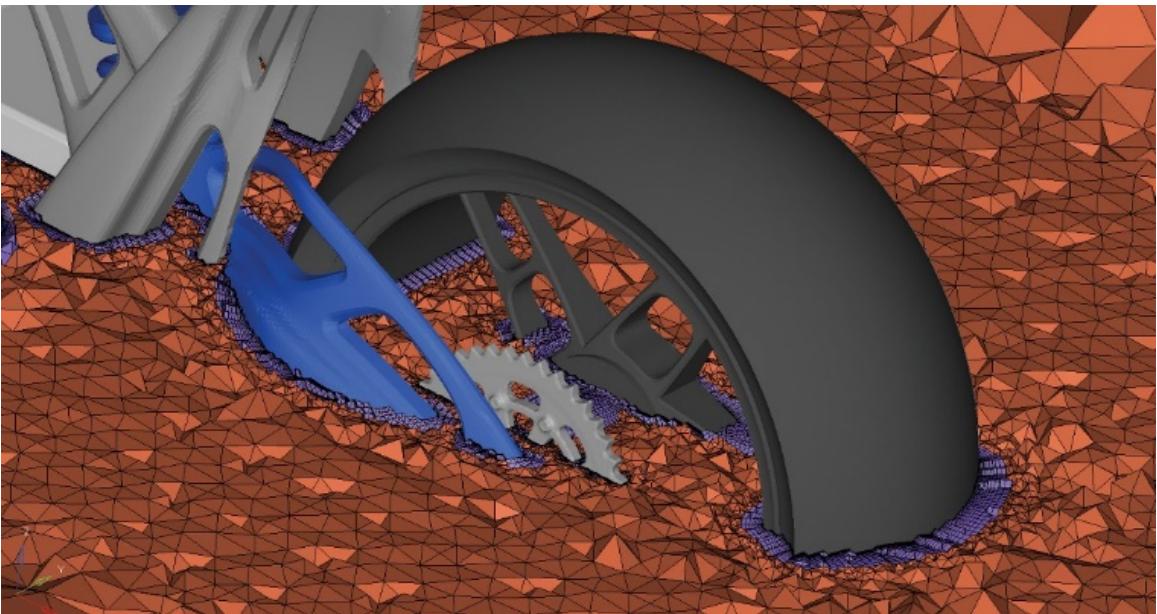
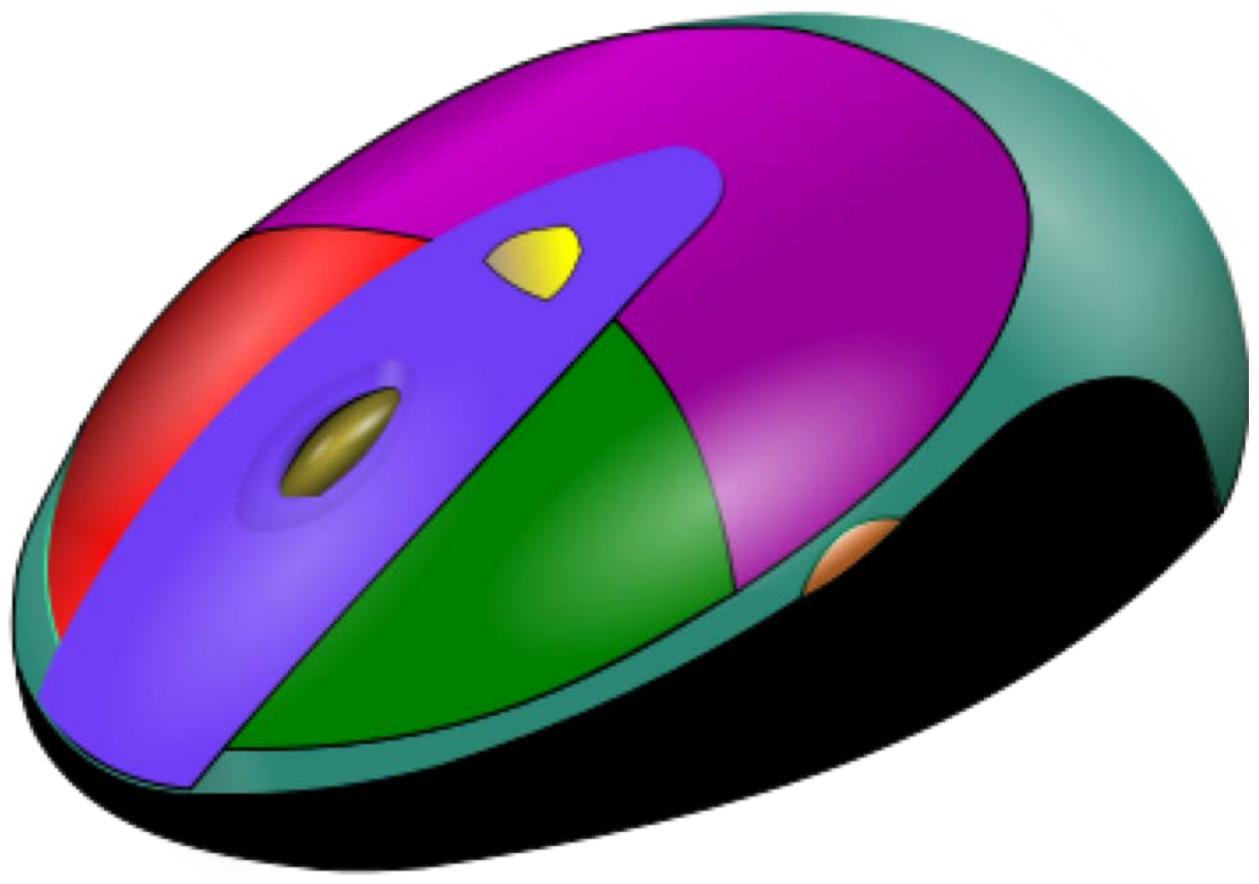


# What is Computer Graphics?

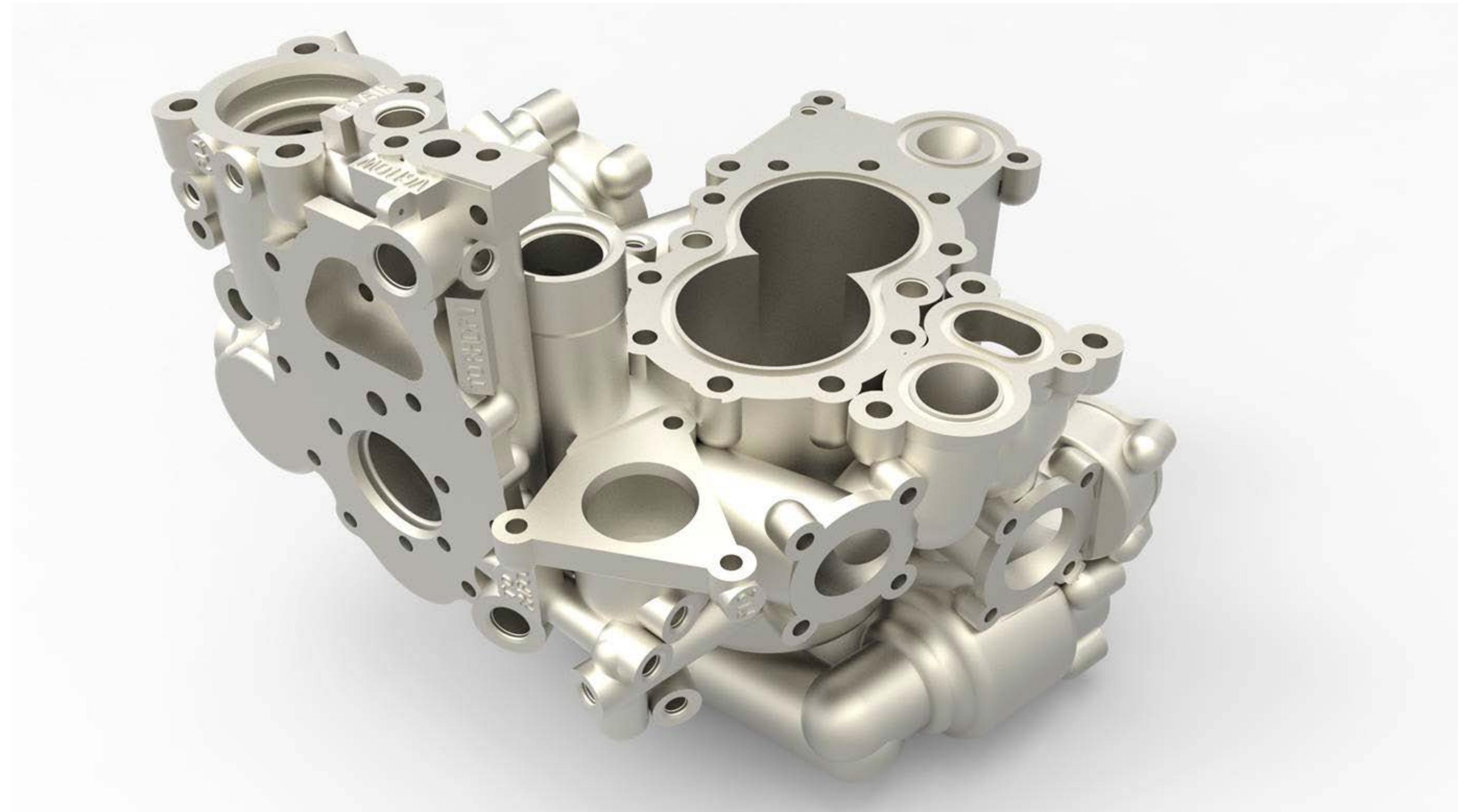


Involves the creation and manipulation of 2D and 3D data

# Why is Computer Graphics?



# Modeling

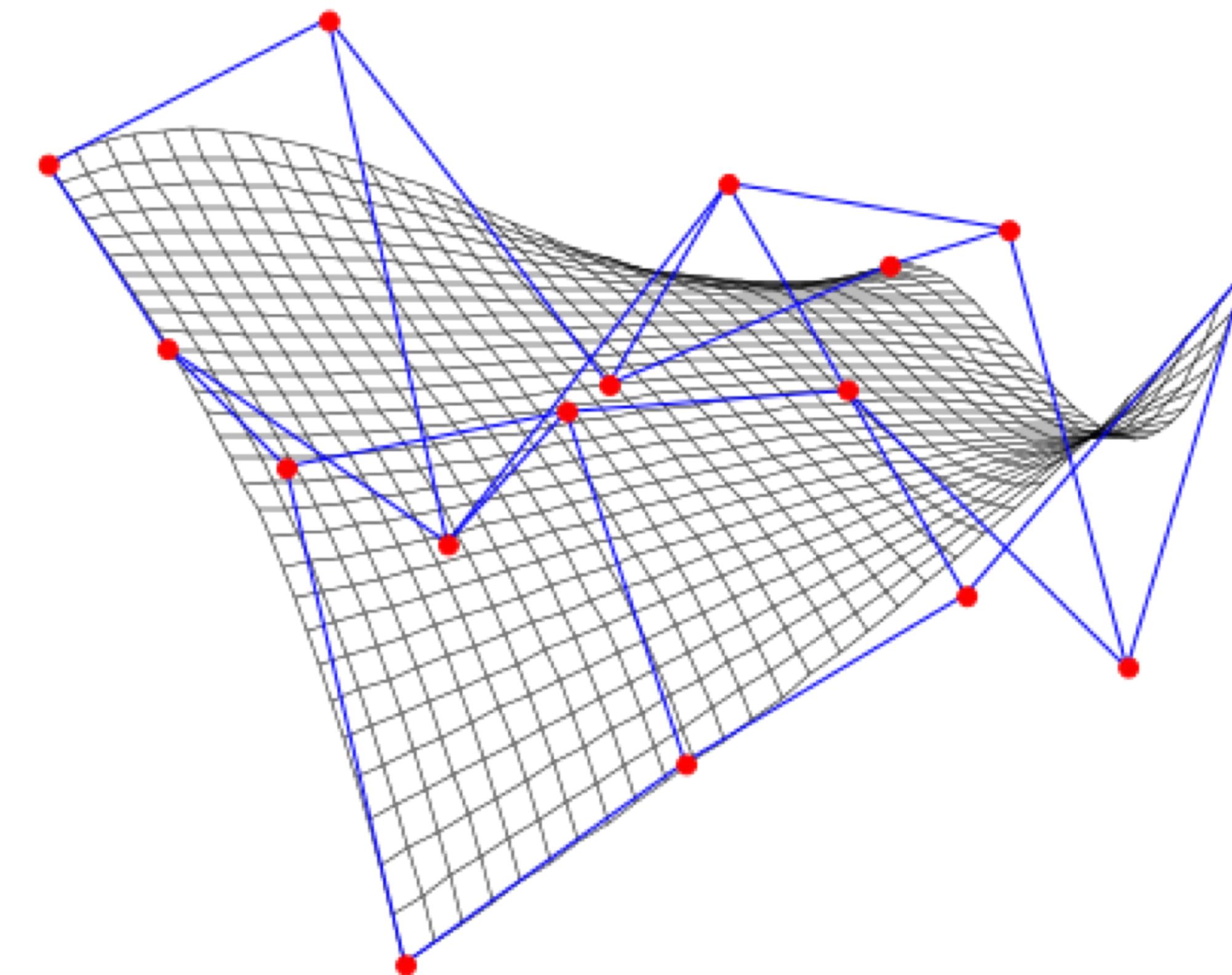
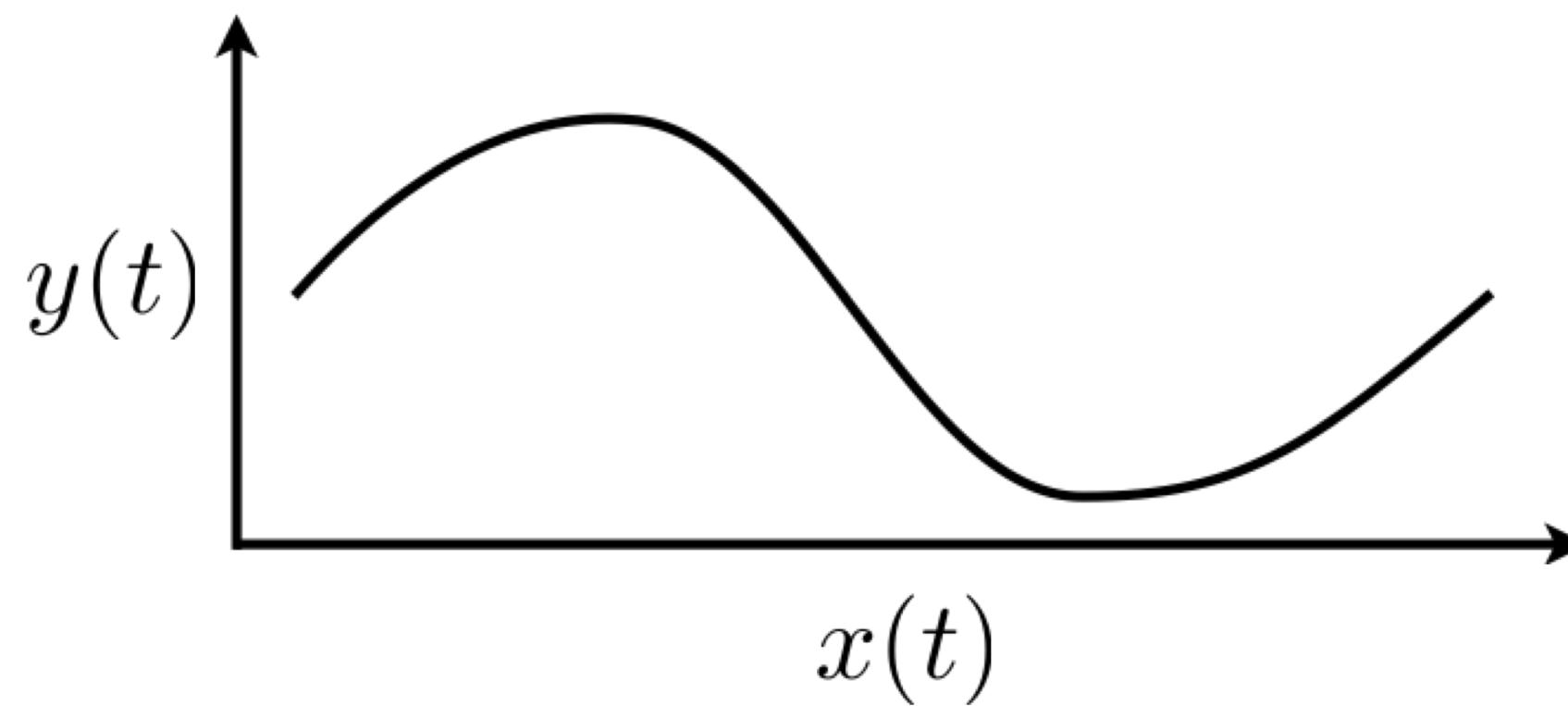


Delcam Plc. [CC BY-SA 3.0 (<http://creativecommons.org/licenses/by-sa/3.0>) or GFDL (<http://www.gnu.org/copyleft/fdl.html>)], via Wikimedia Commons

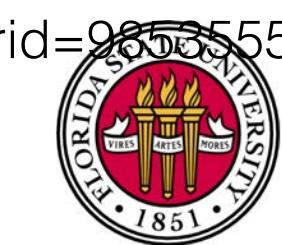


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# Building blocks: curves and surfaces

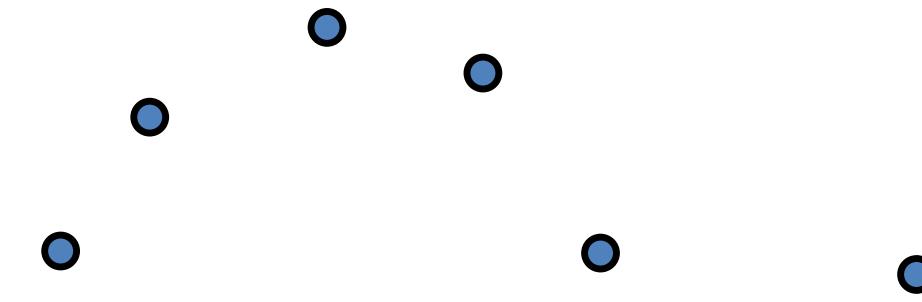


By Wojciech mula at Polish Wikipedia, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=9355555>



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# Polynomial curves



- Polynomials

$$\begin{aligned}\mathbf{p}(t) &= \begin{pmatrix} x_0 + x_1 t + x_2 t^2 + \dots \\ y_0 + y_1 t + y_2 t^2 + \dots \end{pmatrix} = \\ &= \mathbf{p}_0 + \mathbf{p}_1 t + \mathbf{p}_2 t^2 + \dots\end{aligned}$$

- For degree  $d$  we need  $d + 1$  points (“coefficients”)



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# Interpolation (1D)

- Polynomial fitting can be done explicitly:

$$y(t) = \sum_i p_i \prod_{j \neq i} \frac{t - t_j}{t_i - t_j} = \sum_i p_i L_i(t)$$

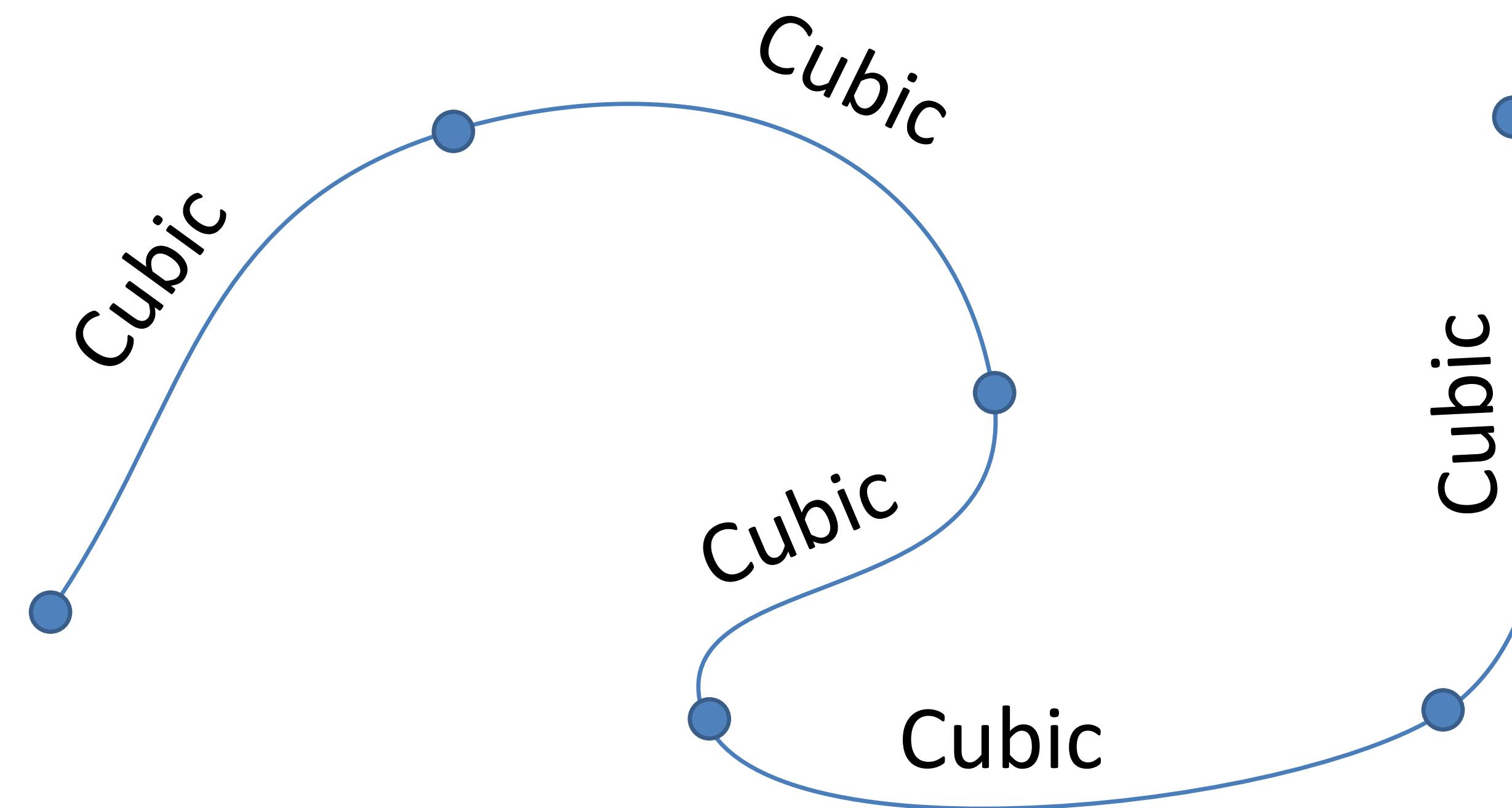
- Check that  $y(t_i) = p_i$
- Products  $L_i(t)$  are called Lagrange polynomials



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# Splines

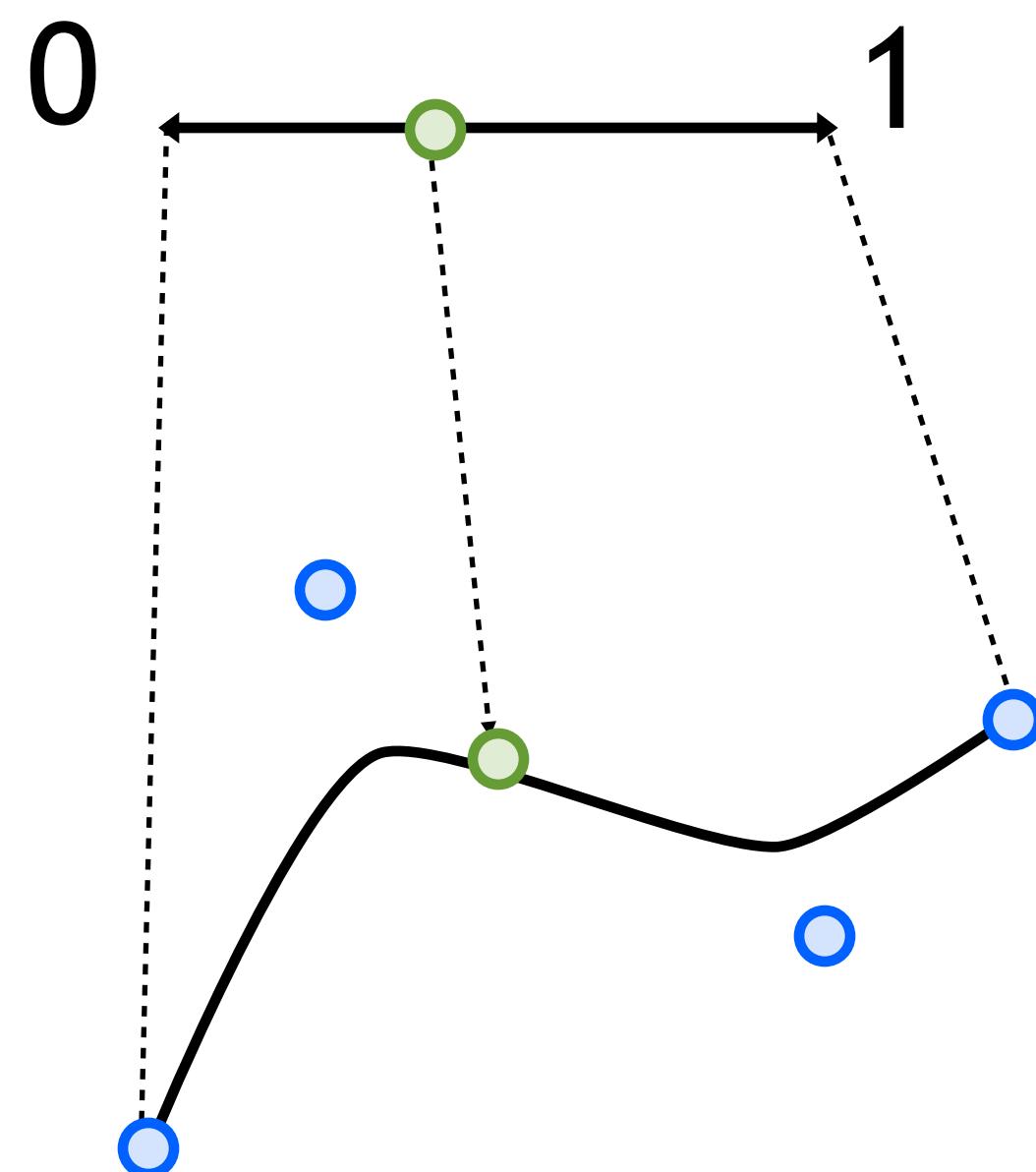
- Paste together low-degree polynomials



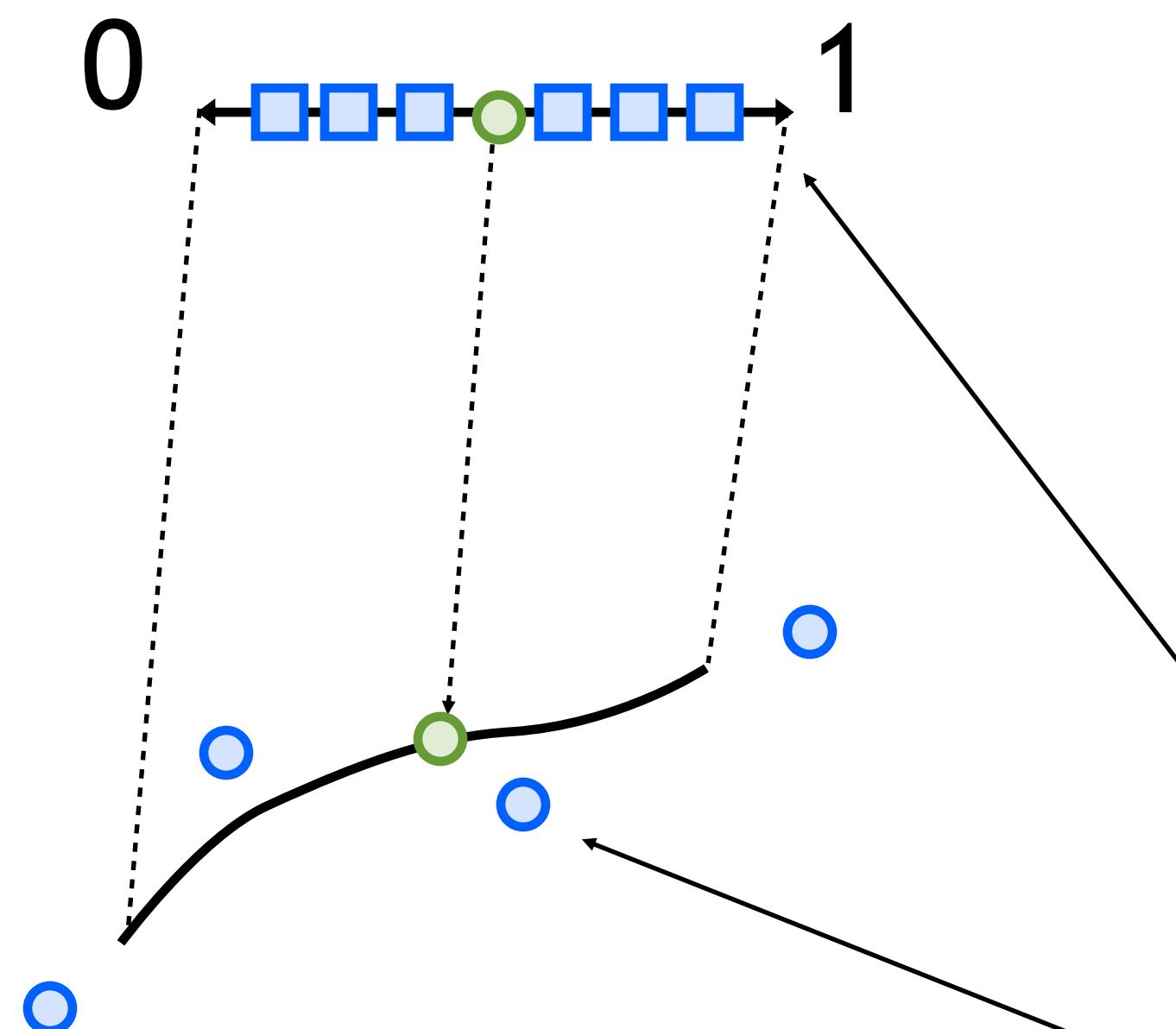
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# Ingredients

Bezier



B-spline



$$m = n + p + 1$$

Basis degree

$p$

Knots Points

$m + 1$

Control Points  $n + 1$

# Bézier Patches

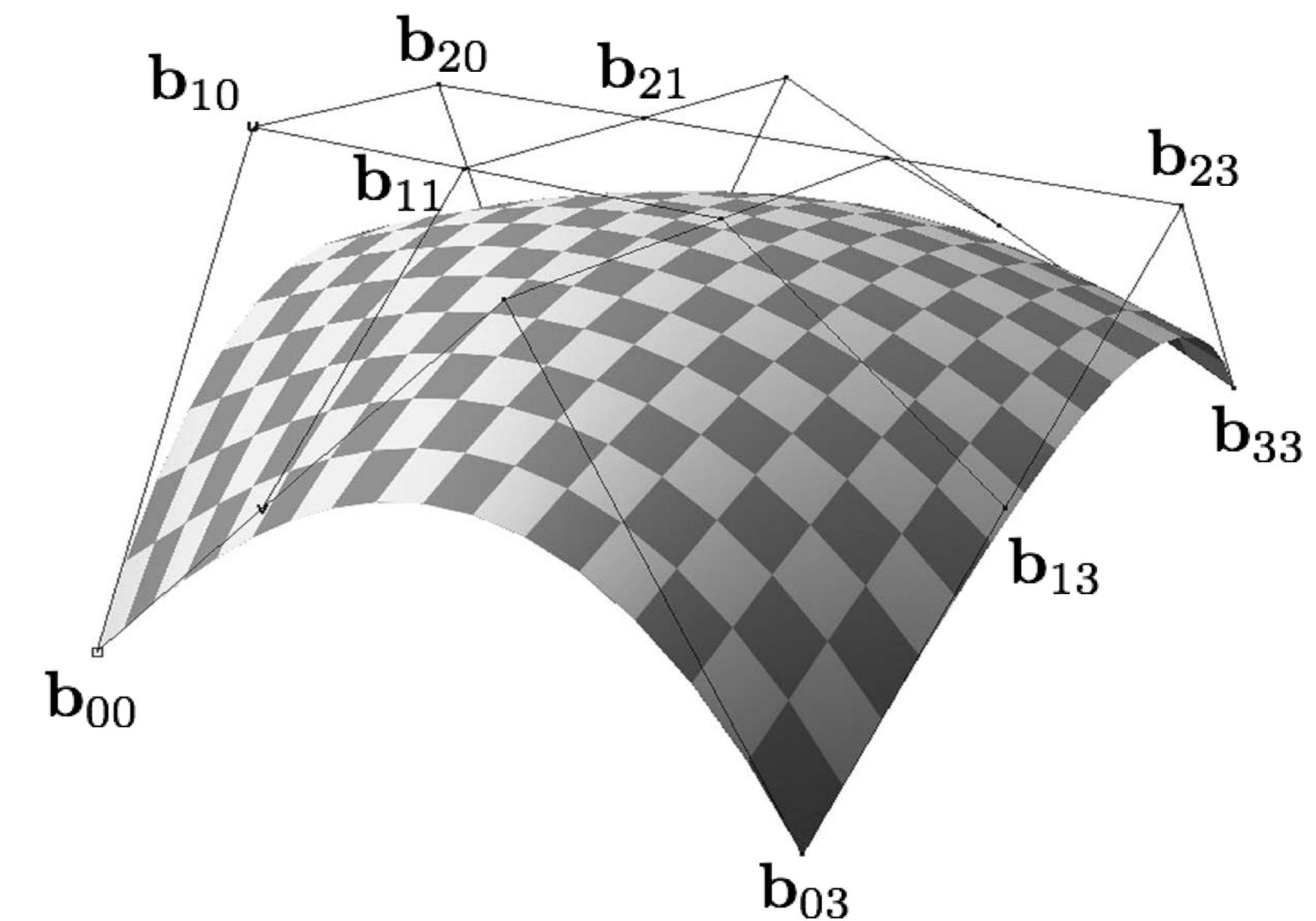
- Build on Bézier curves

$$b^m(u) = \sum_{i=0}^m b_i B_i^m(u)$$

- Control points as curves

$$b_i = b_i(v) = \sum_{j=0}^n b_{ij} B_j^n(v)$$

$$b^{mn}(u, v) = \sum_{i=0}^m \sum_{j=0}^n b_{ij} B_i^m(u) B_j^n(v)$$

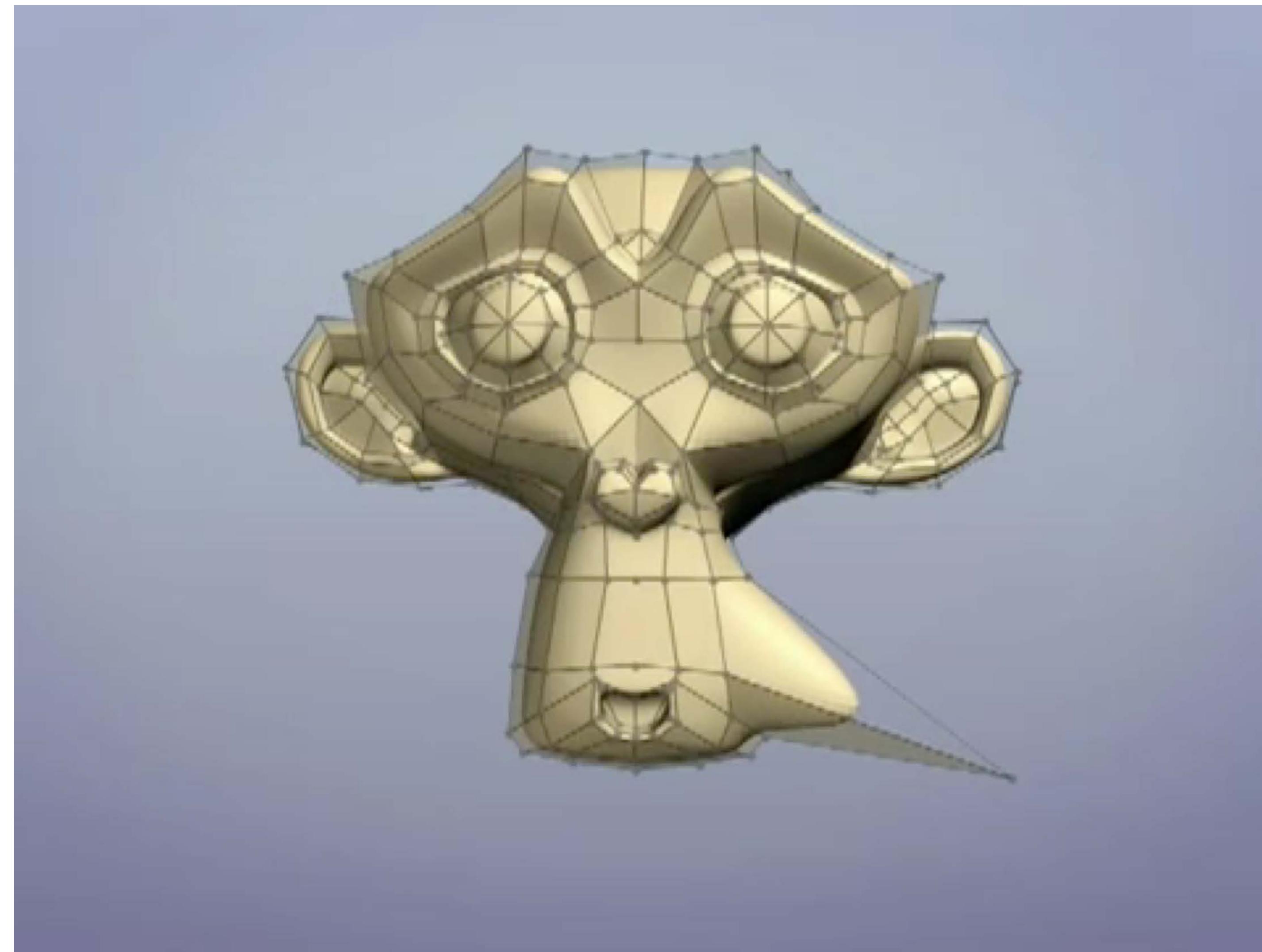


- Keep one parameter fixed: iso-parameter curves



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# How are they used in practice?

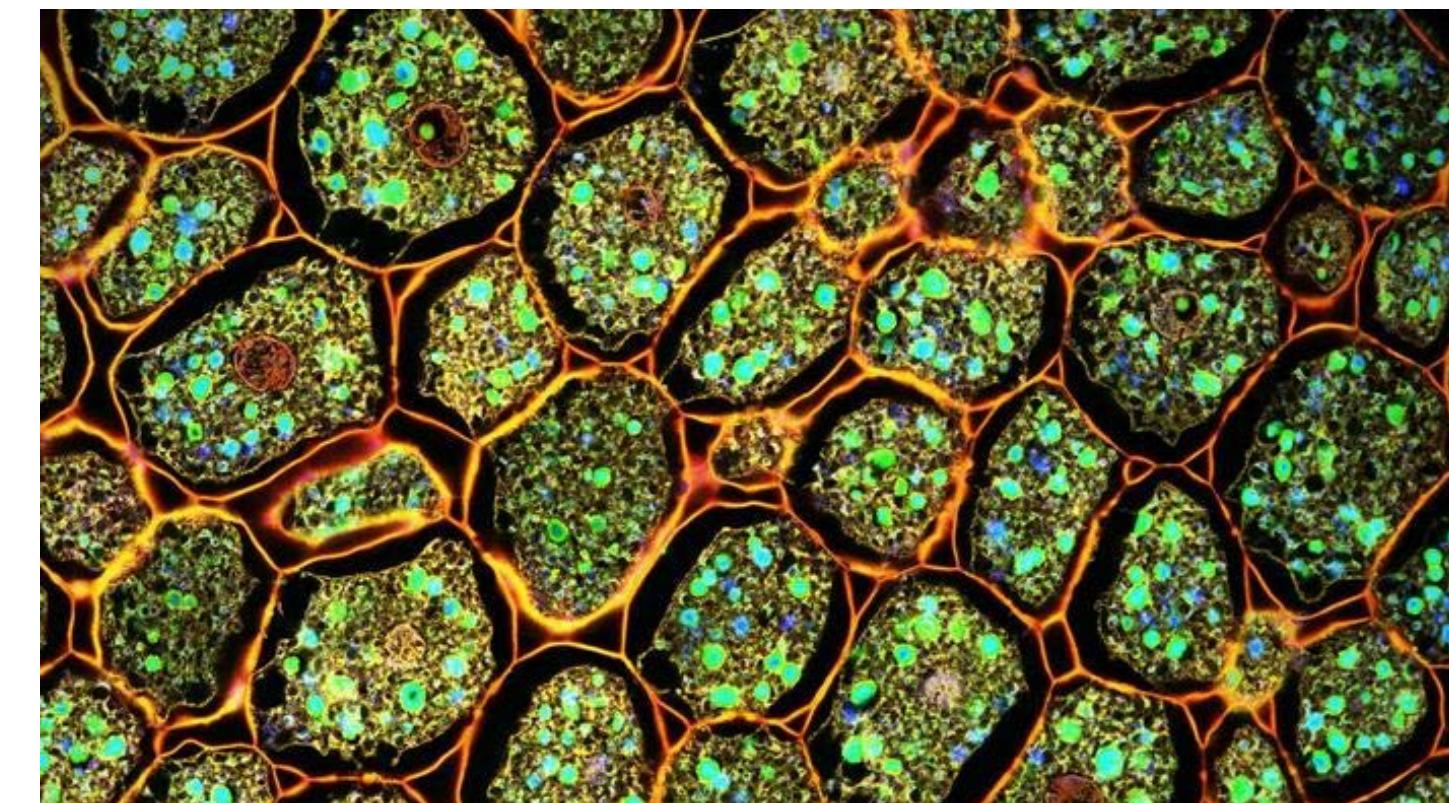


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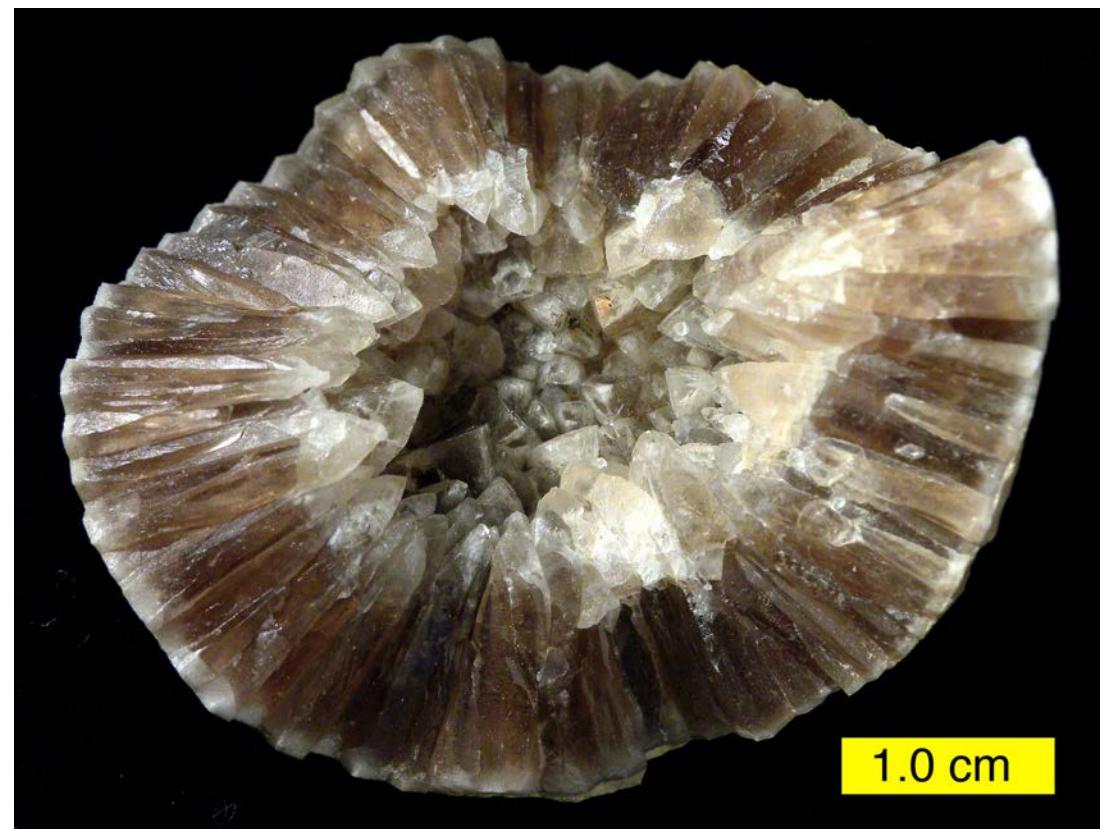
# Origin of Meshes

- In nature, meshes arise in a variety of contexts:

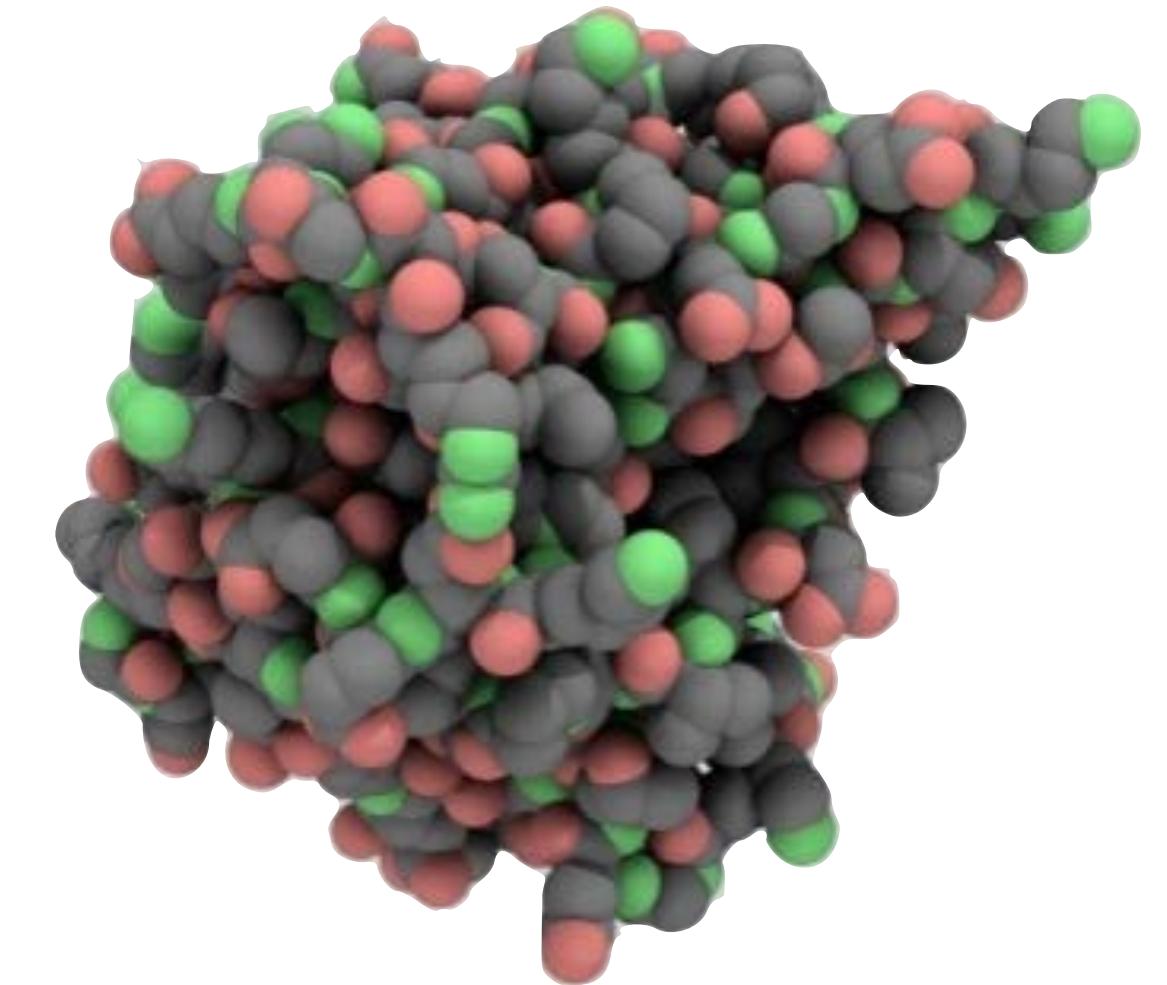
- Cells in organic tissues



- Crystals



- Molecules

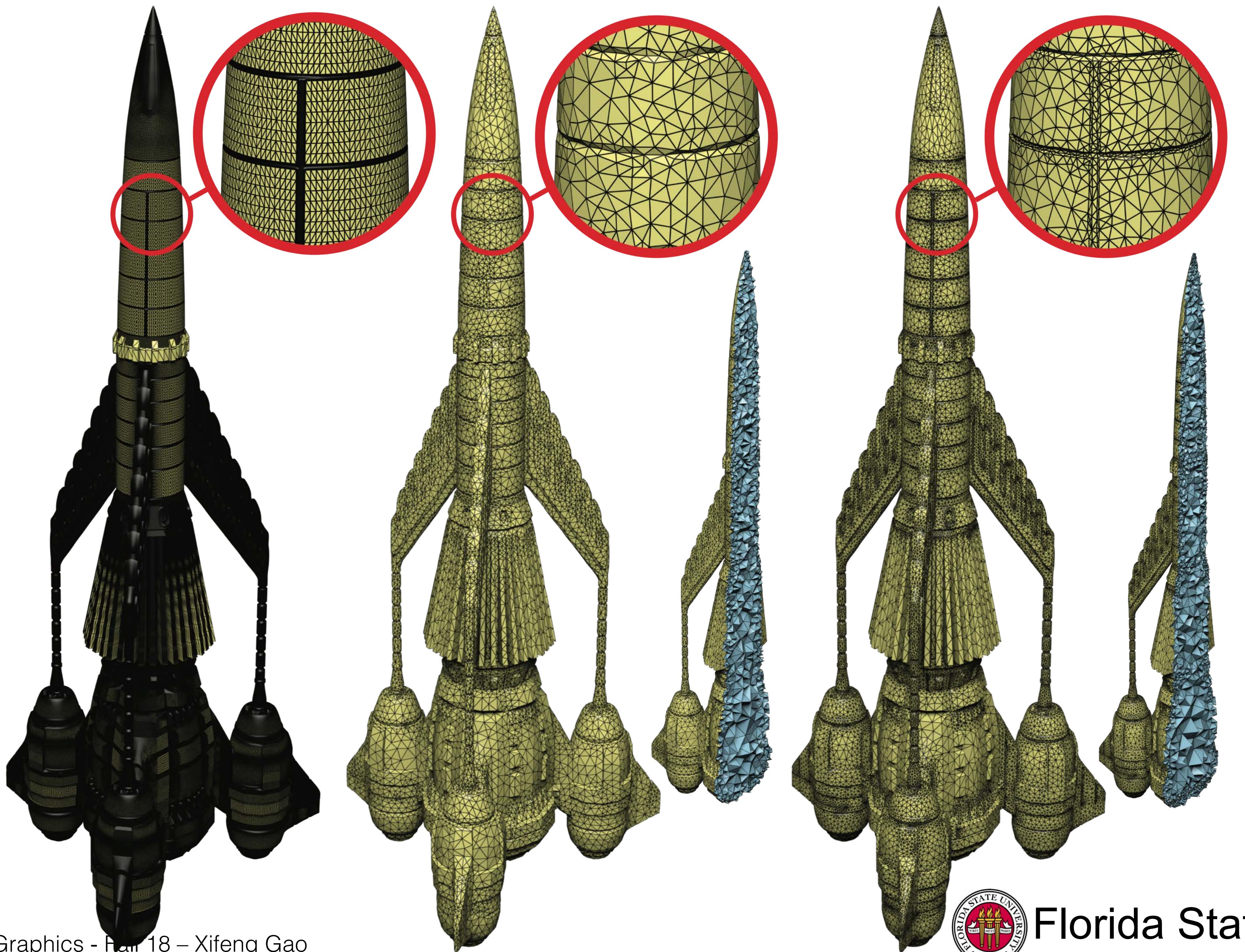


- Mostly *convex* but *irregular* cells

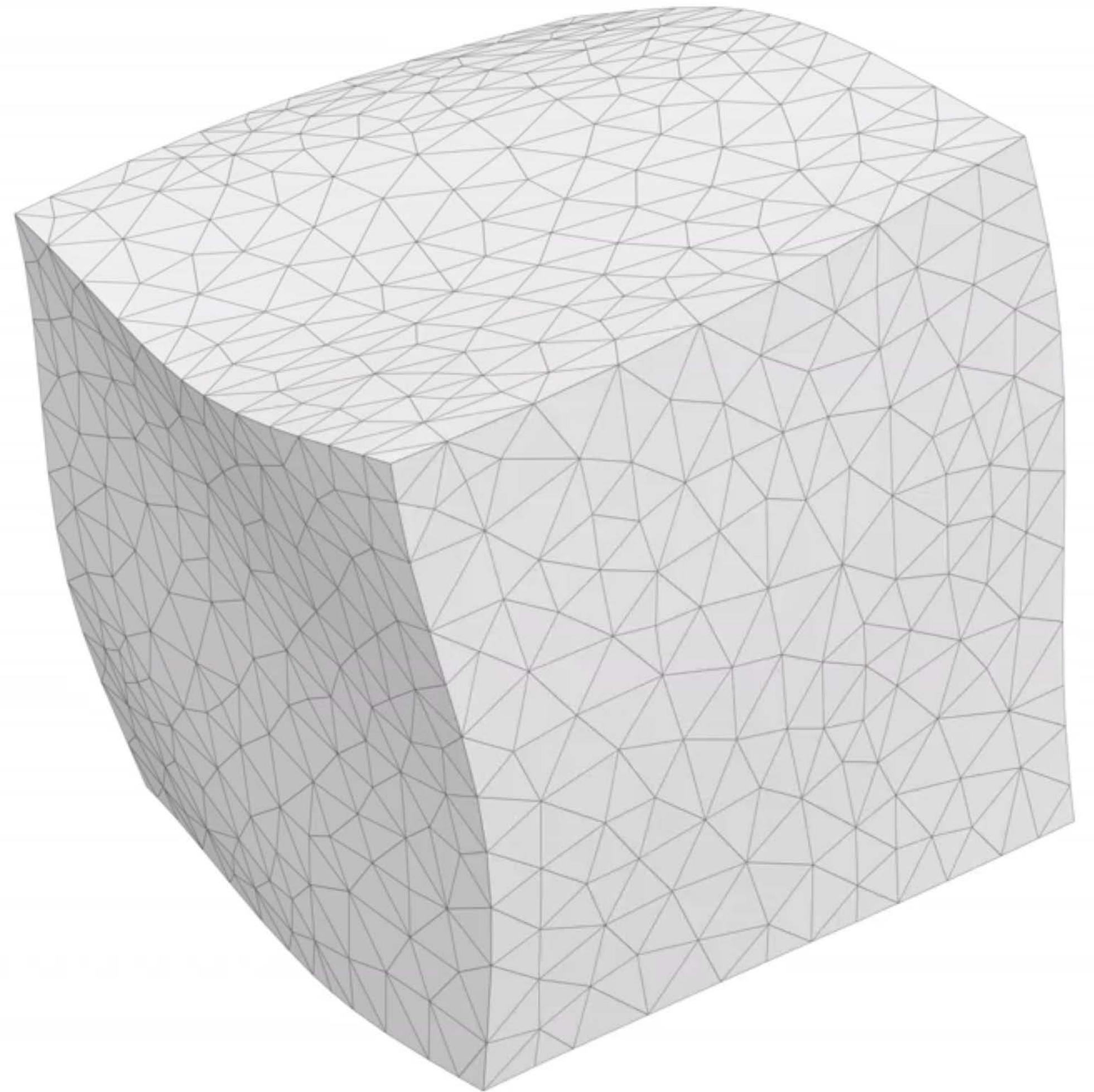
- Common concept: *complex* shapes can be described as *collections* of *simple building blocks*

**Credit:** Fernan Federici Moment Getty Images

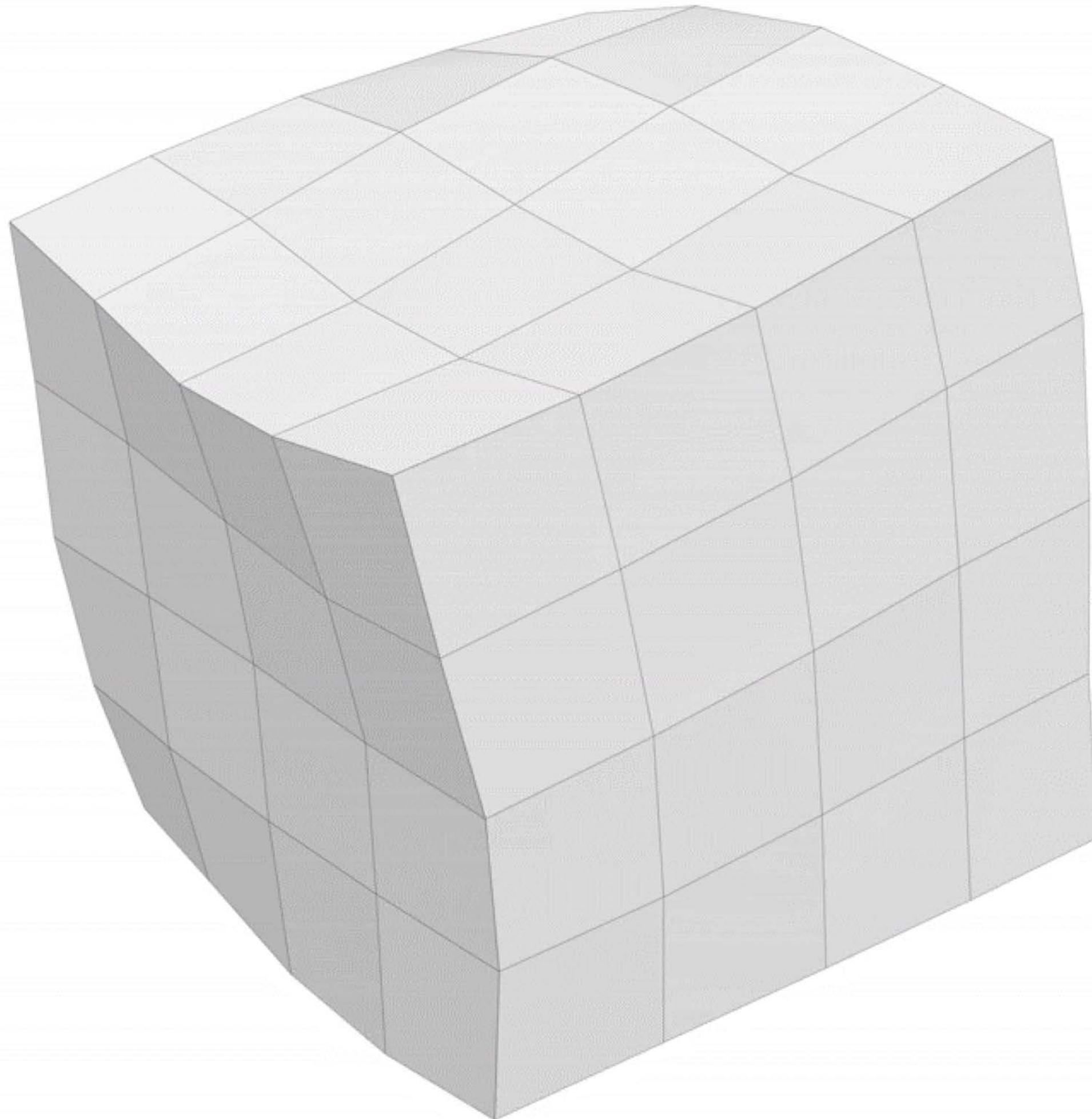
By Mark A. Wilson (Department of Geology, The College of Wooster).[1] -  
Own work, Public Domain, <https://commons.wikimedia.org/w/index.php?curid=12666593>



# Volumetric Meshing



Tet-meshing



Hex-meshing



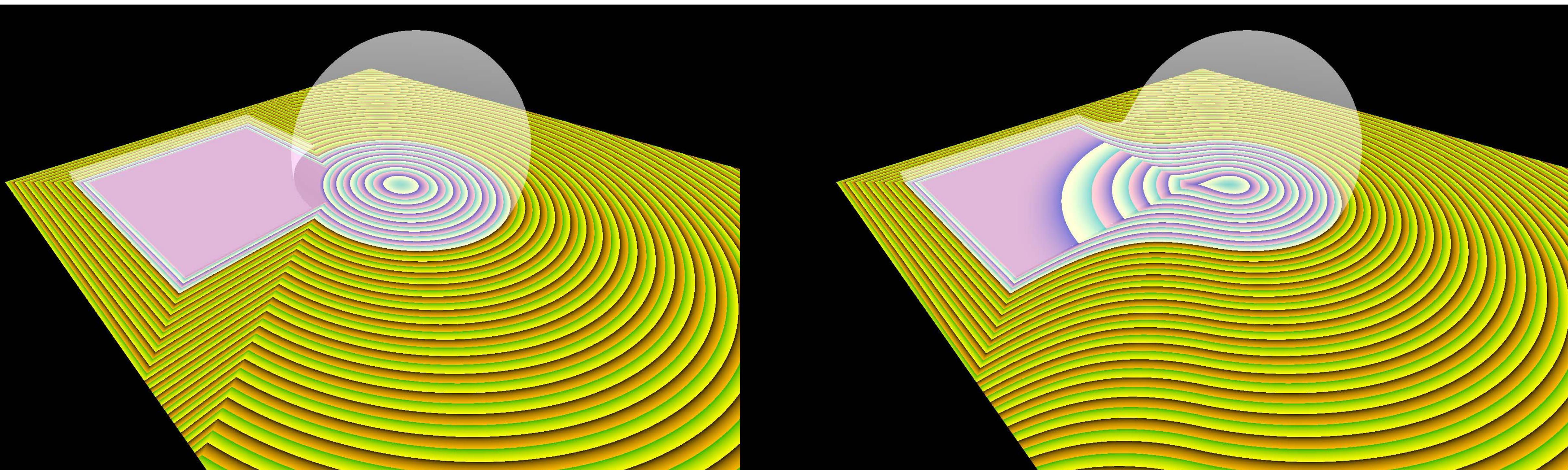
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# Stitch meshing



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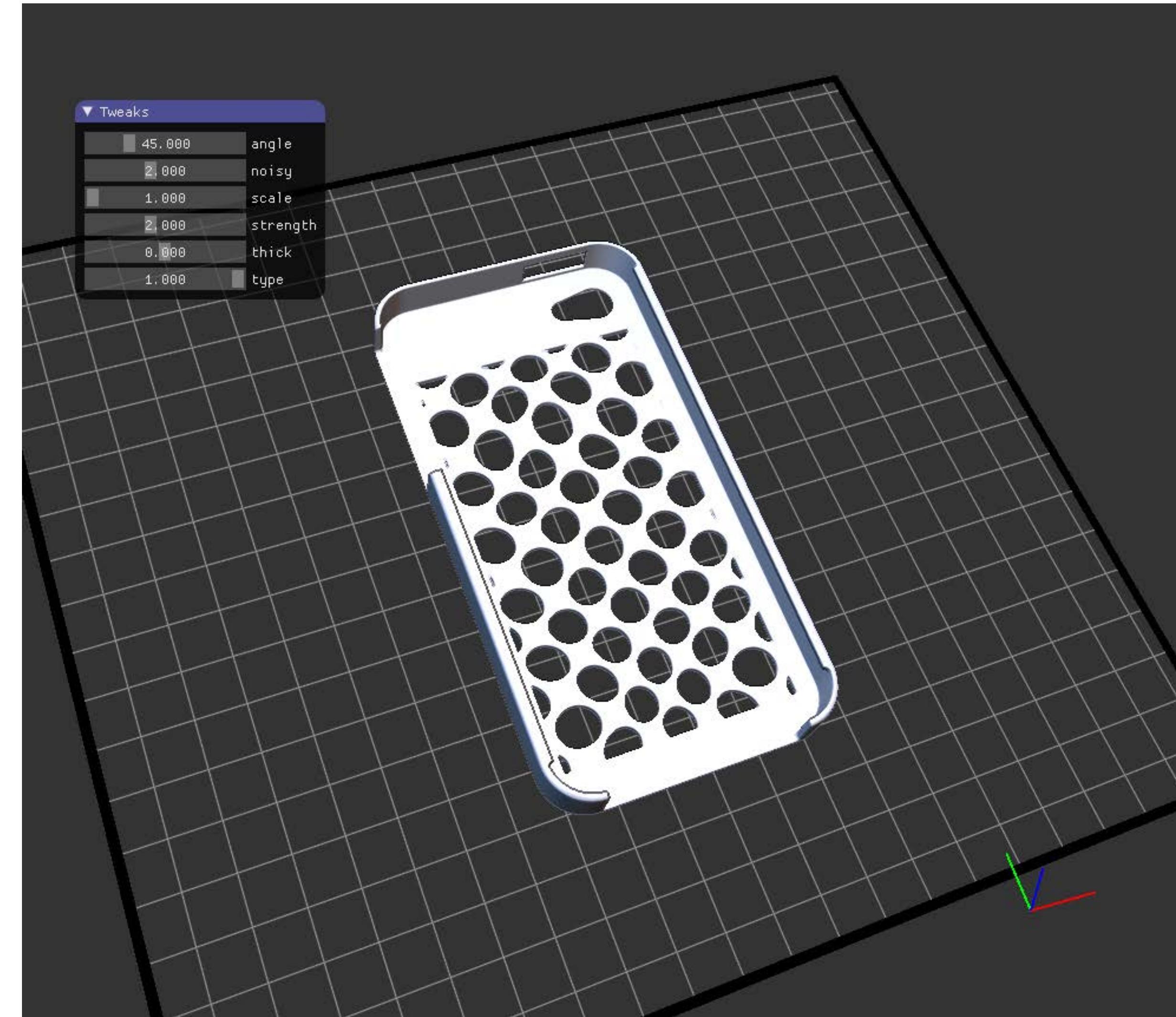
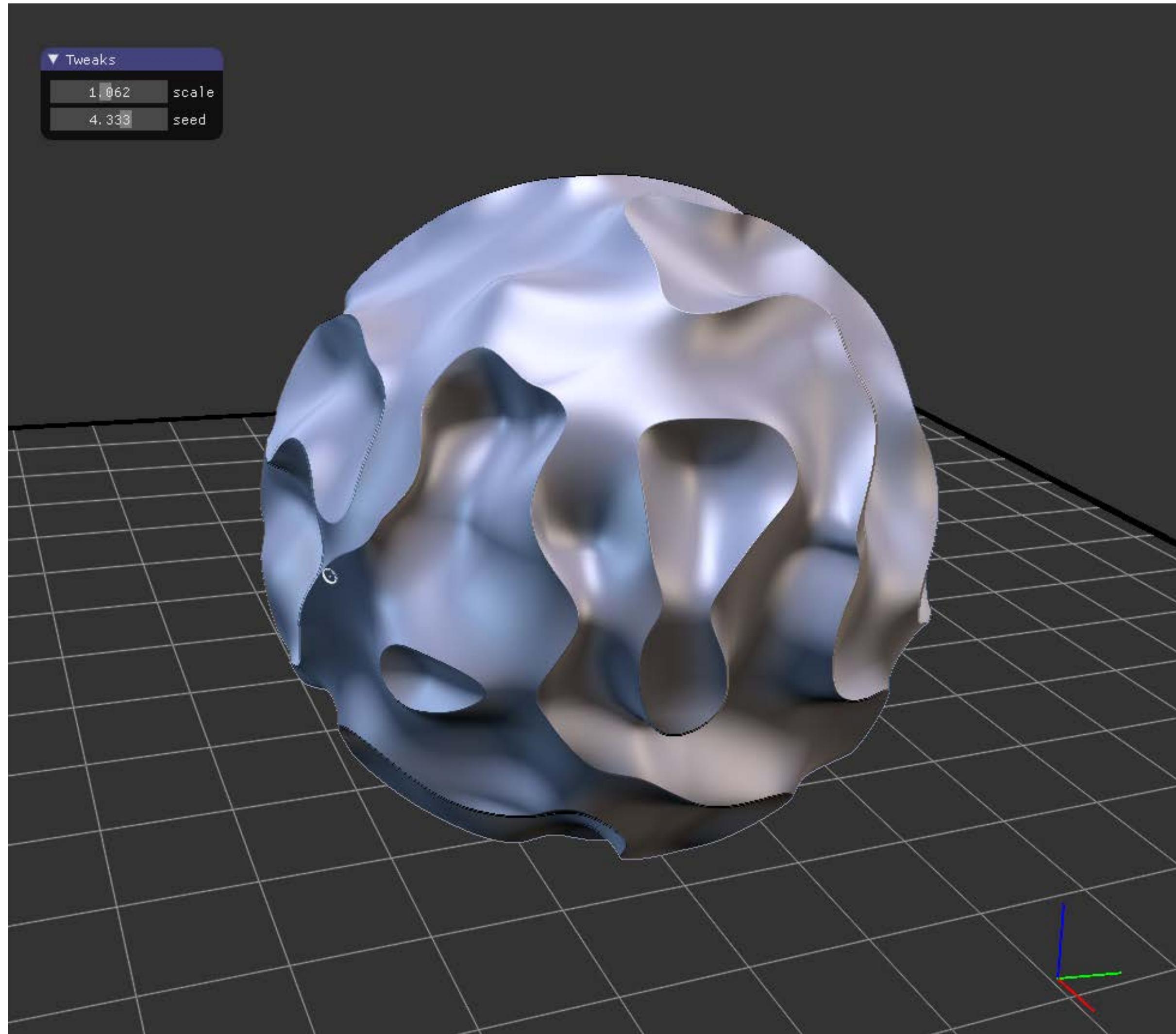
# Modeling With Implicit functions



Alex Evans at SIGGRAPH 2015

[https://www.mediamolecule.com/blog/article/siggraph\\_2015](https://www.mediamolecule.com/blog/article/siggraph_2015)

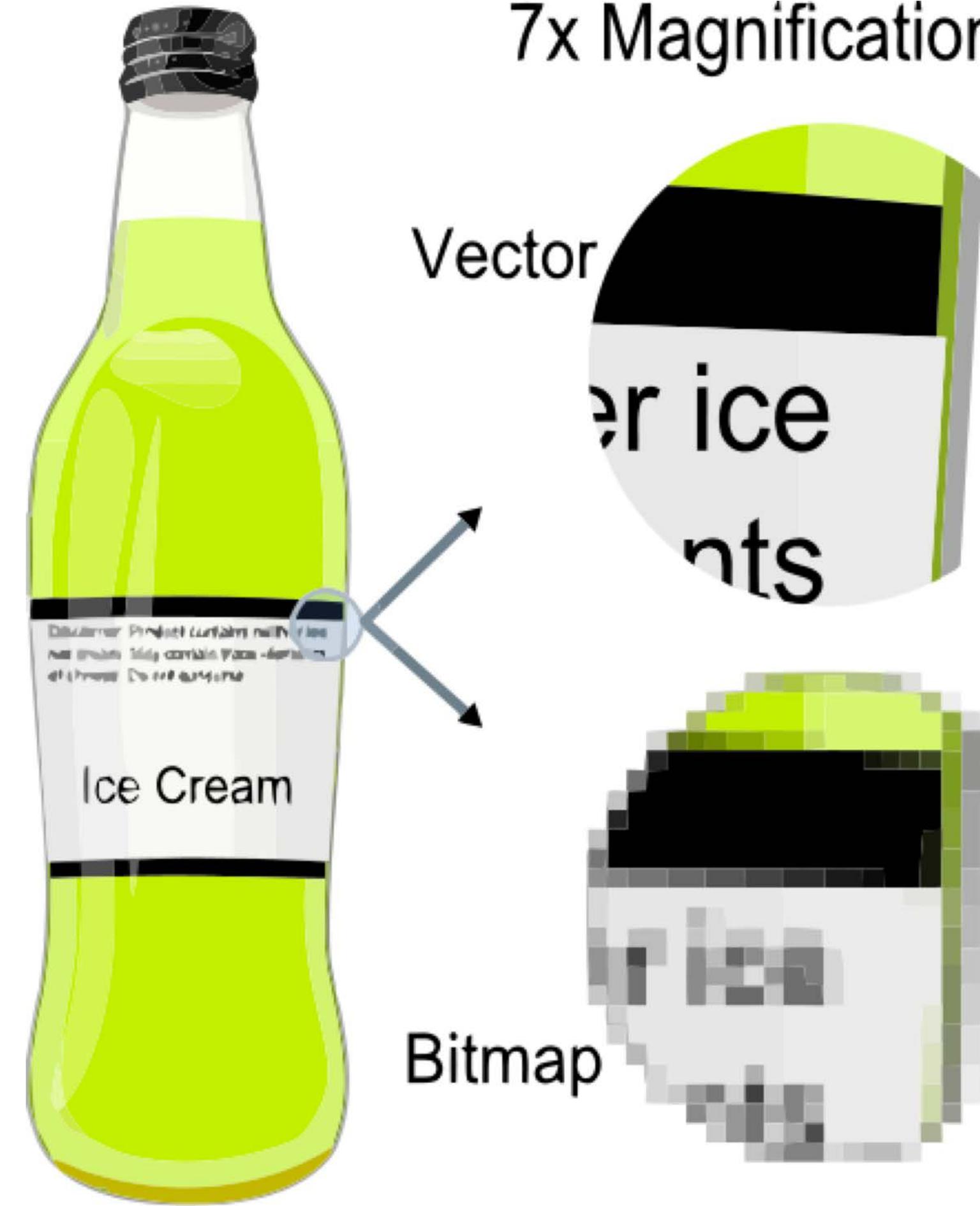
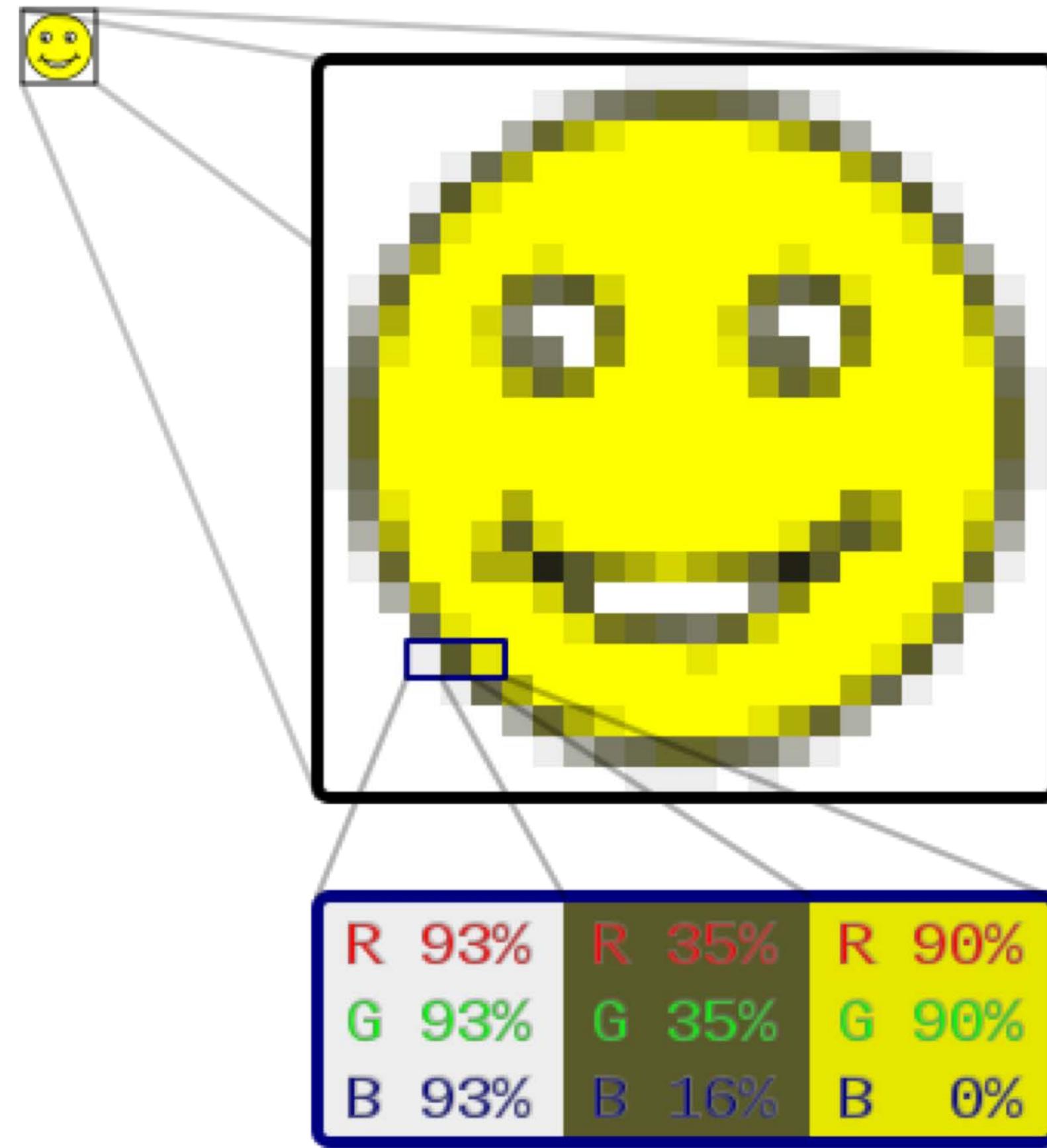
# IceSL



<http://shapeforge.loria.fr/icesl/>

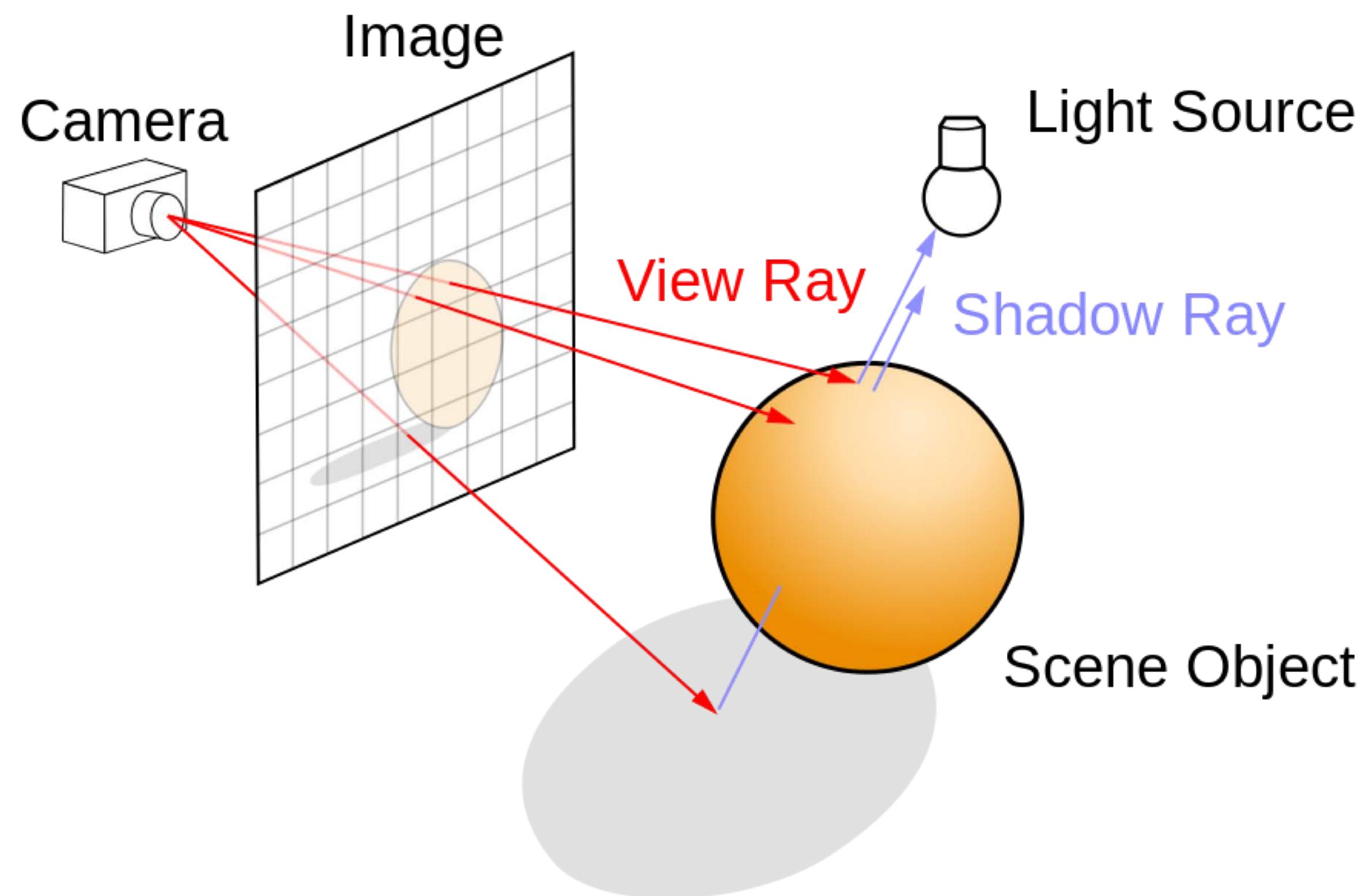


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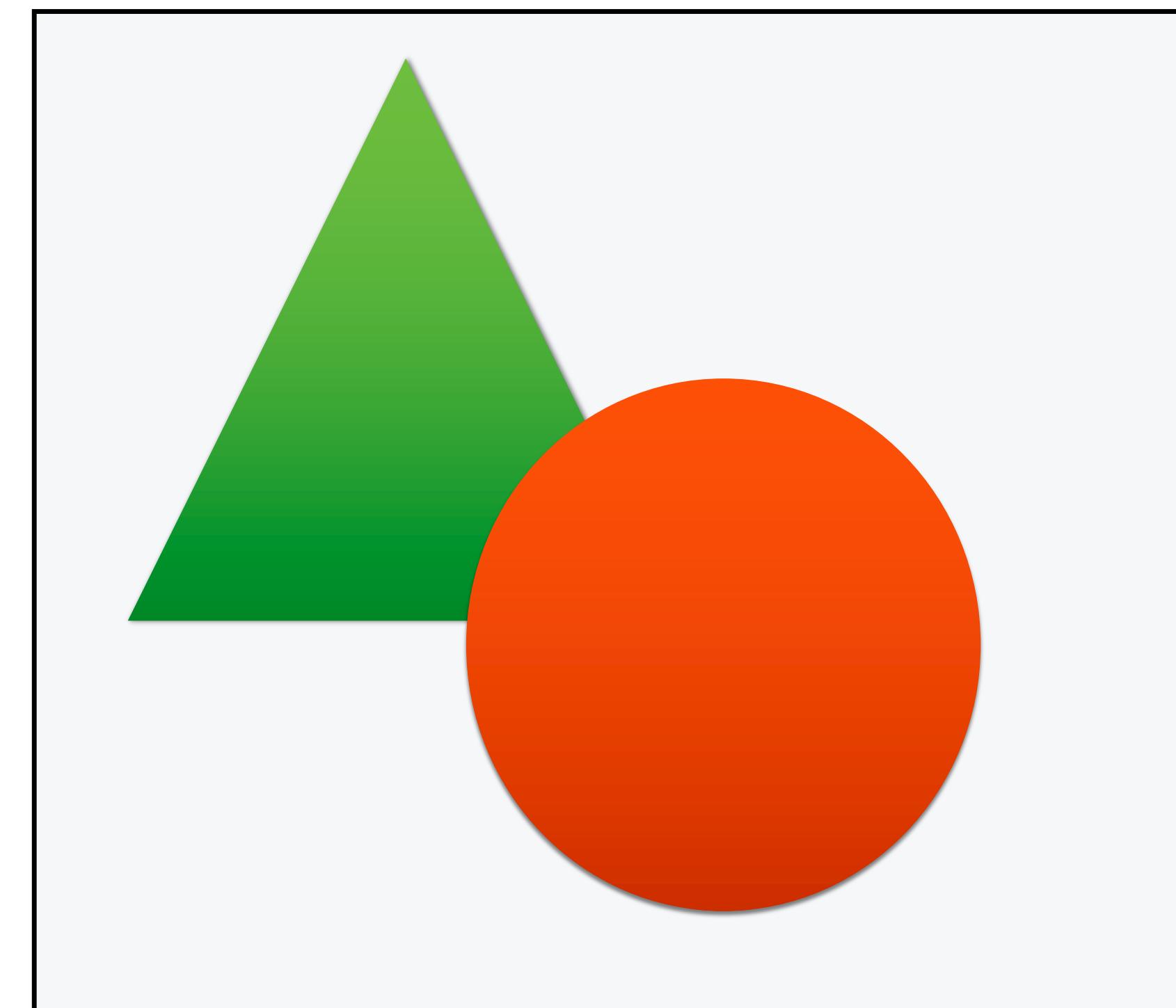


# Two major approaches

## Per-pixel - “Raytracing”



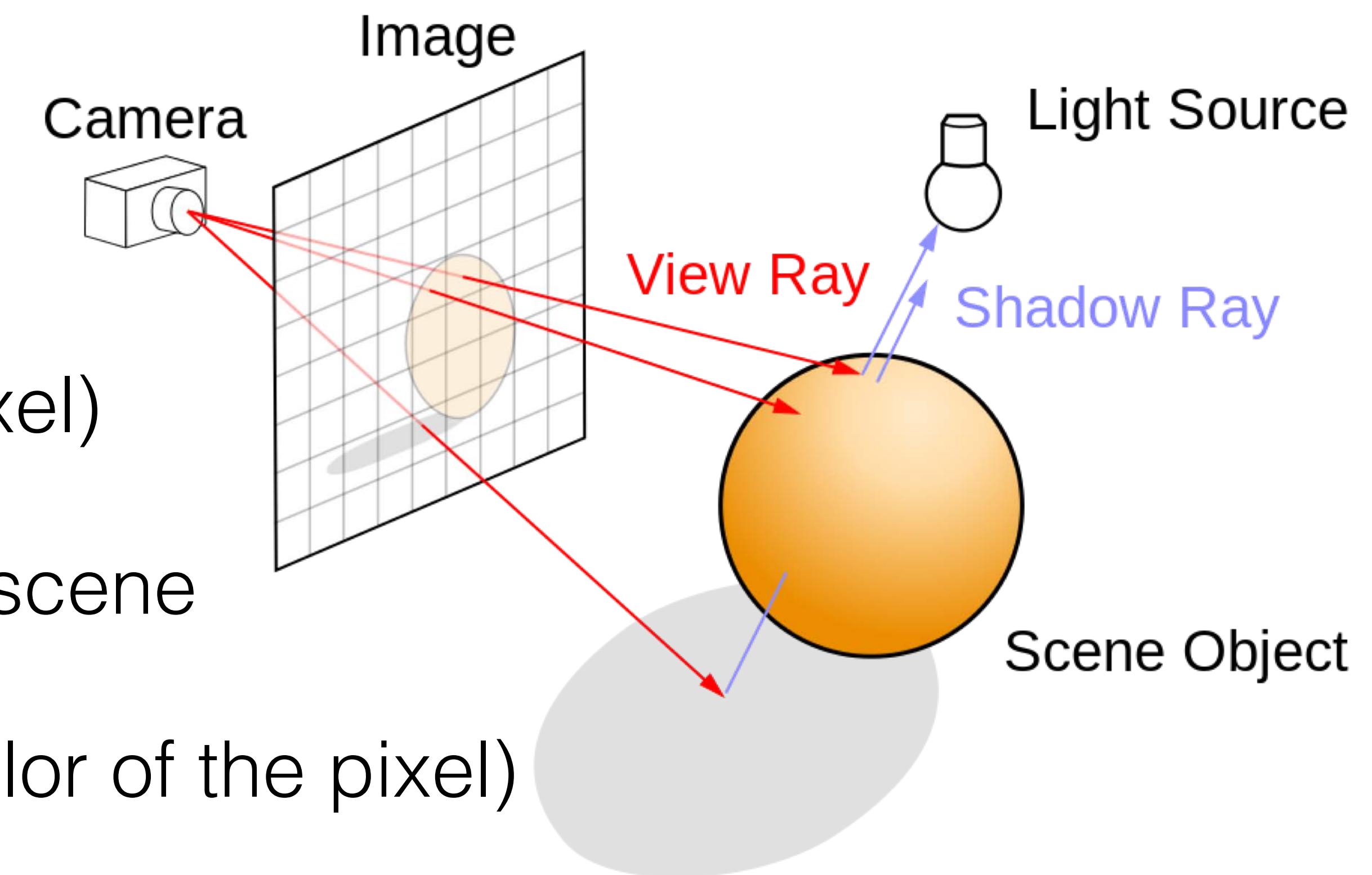
## Per-object - “Rasterization”



By Henrik - Own work, GFDL, <https://commons.wikimedia.org/w/index.php?curid=3869326>

# Basic Raytracing

1. Generation of Rays (one per pixel)
2. Intersection with objects in the scene
3. Shading (computation of the color of the pixel)



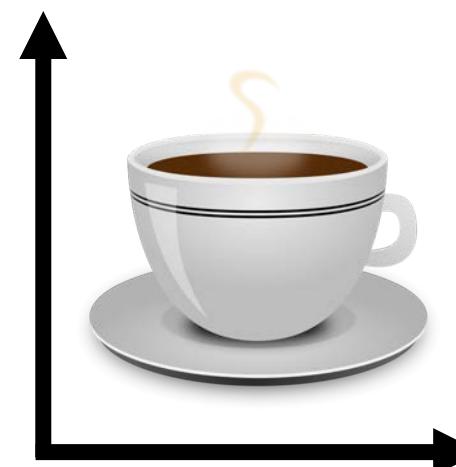
By Henrik - Own work, GFDL, <https://commons.wikimedia.org/w/index.php?curid=3869326>



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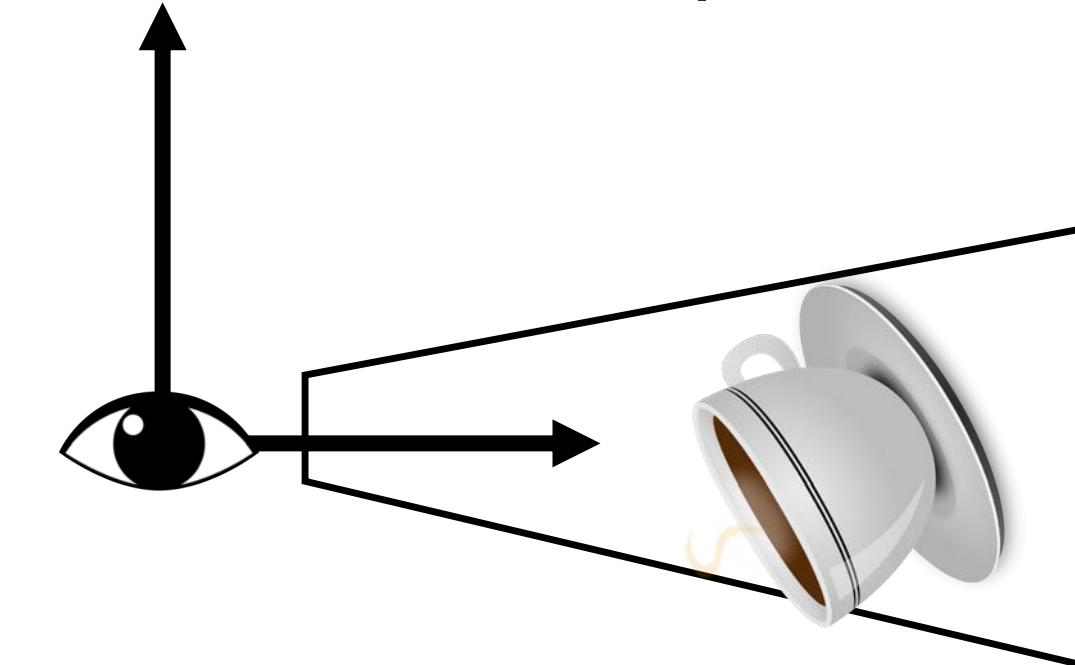
# Viewing Transformation

object space



model

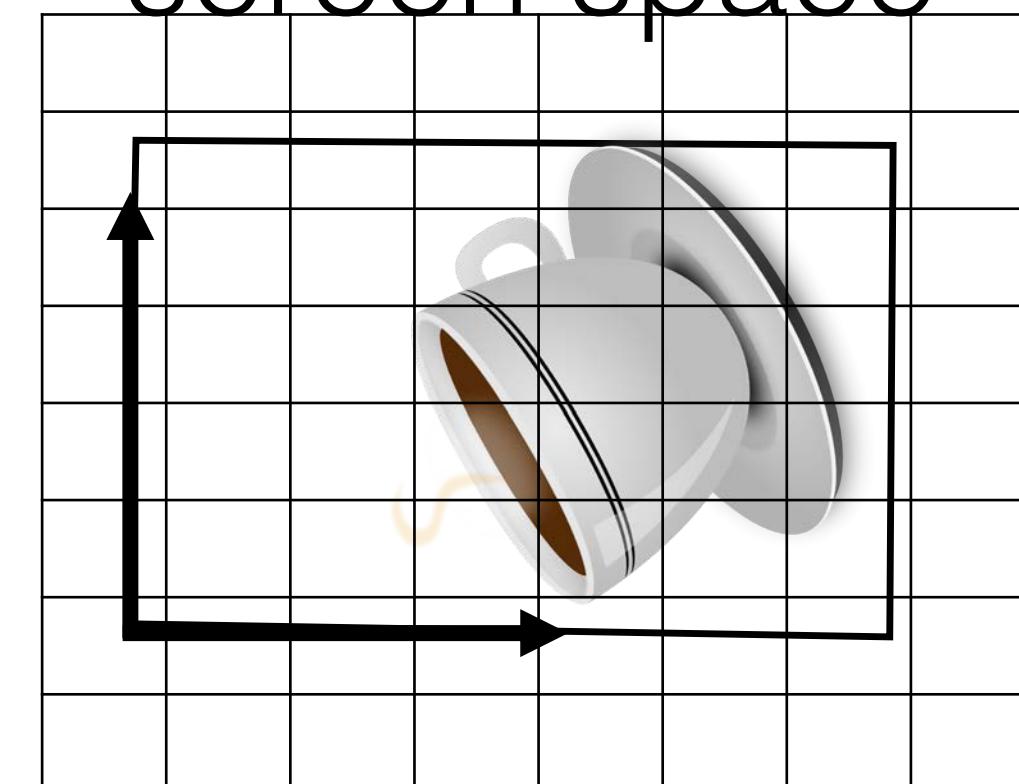
camera space



camera

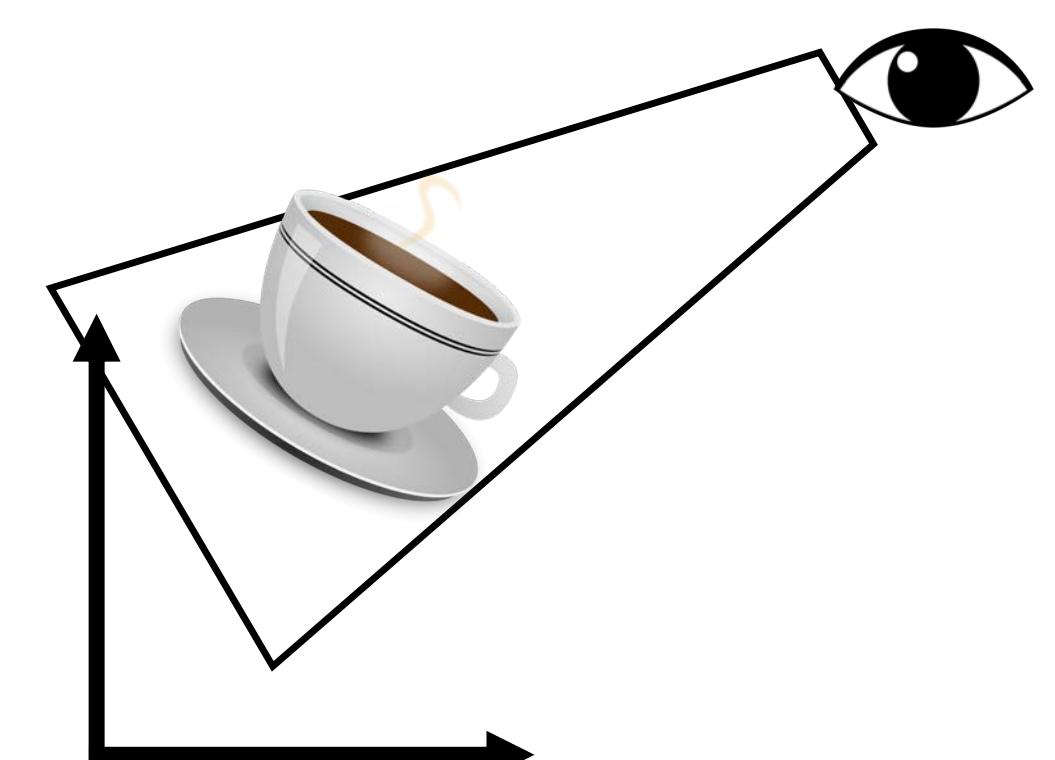
projection

screen space

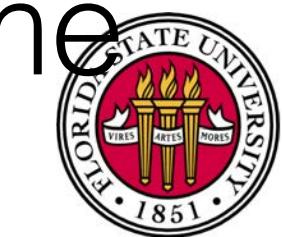
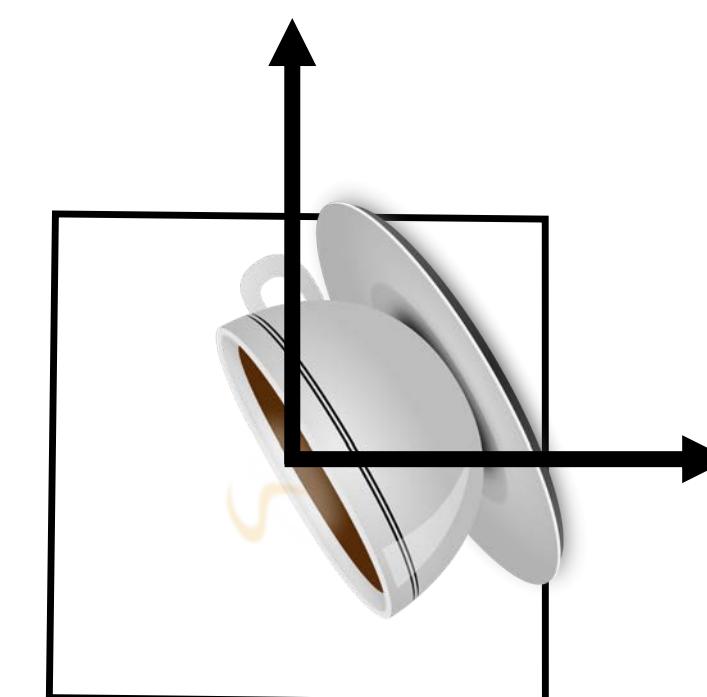


viewport

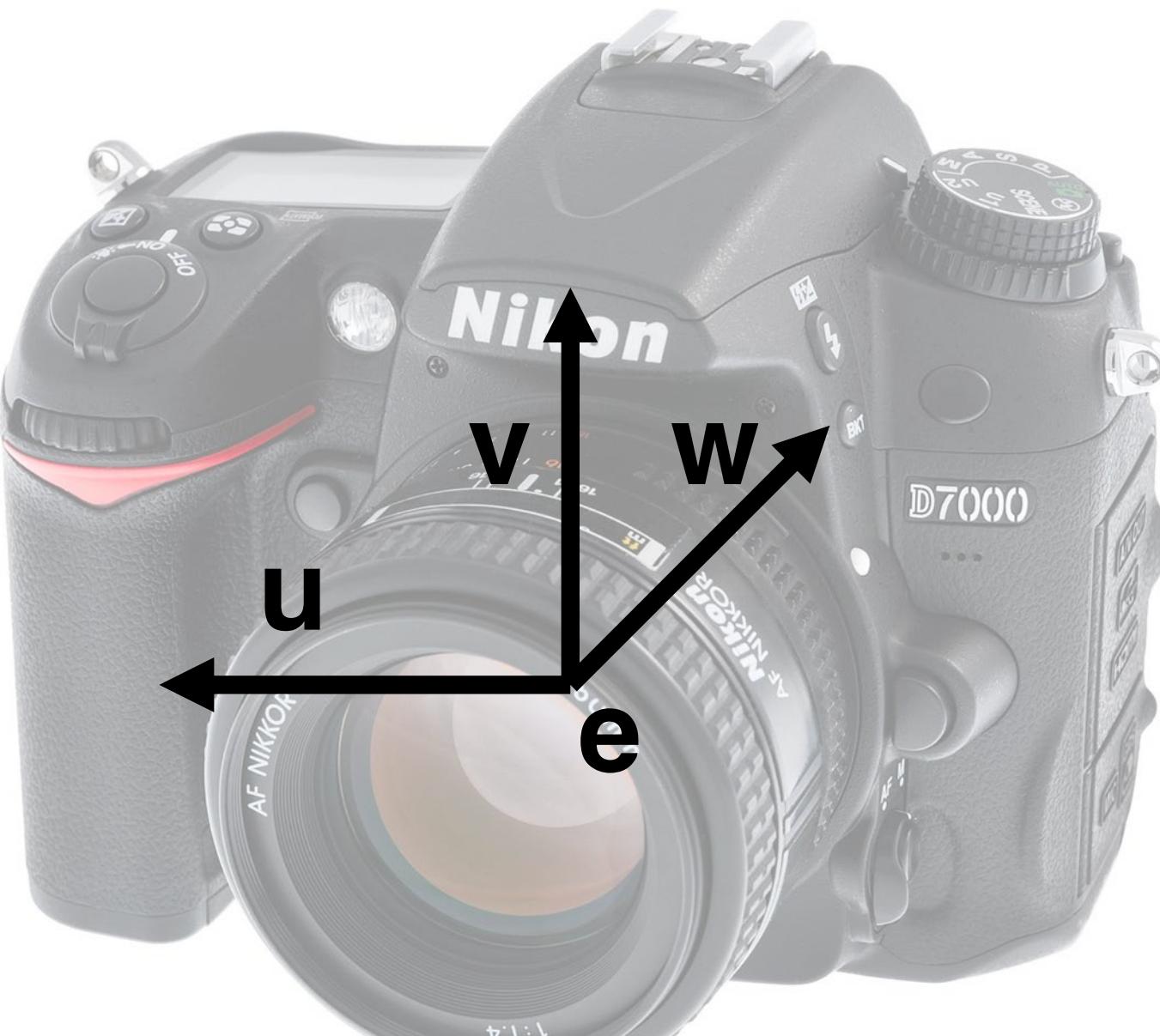
world space



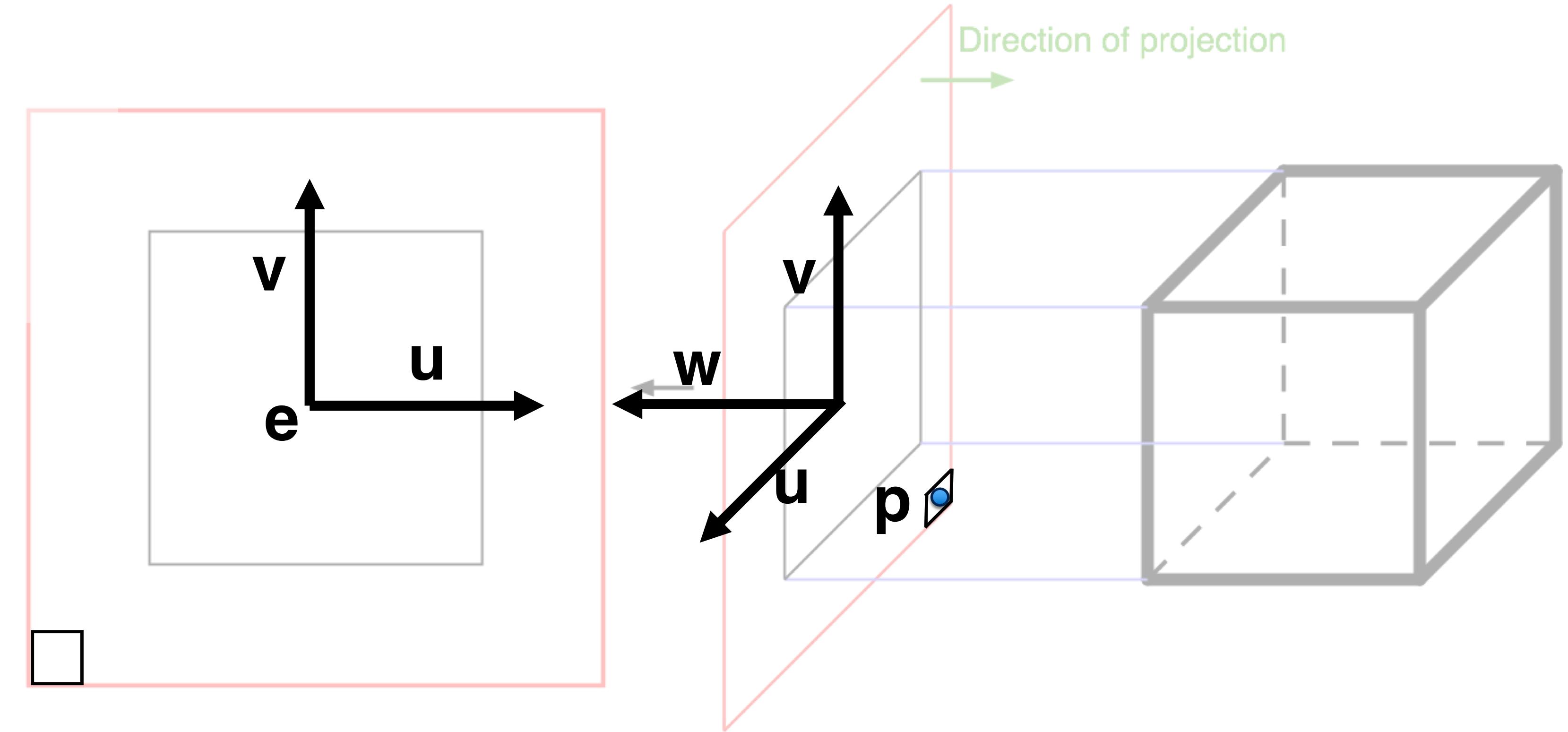
canonical  
view volume



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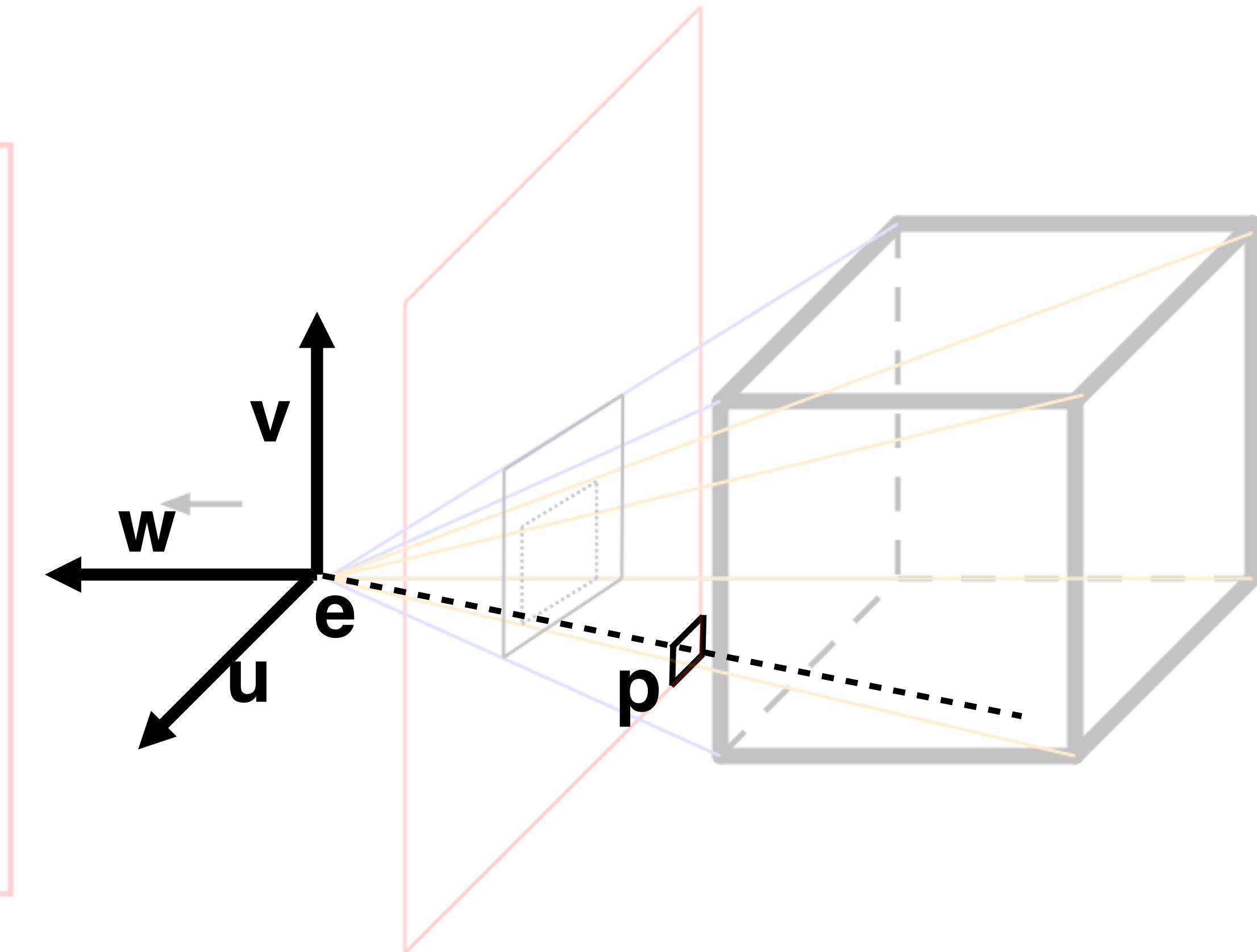
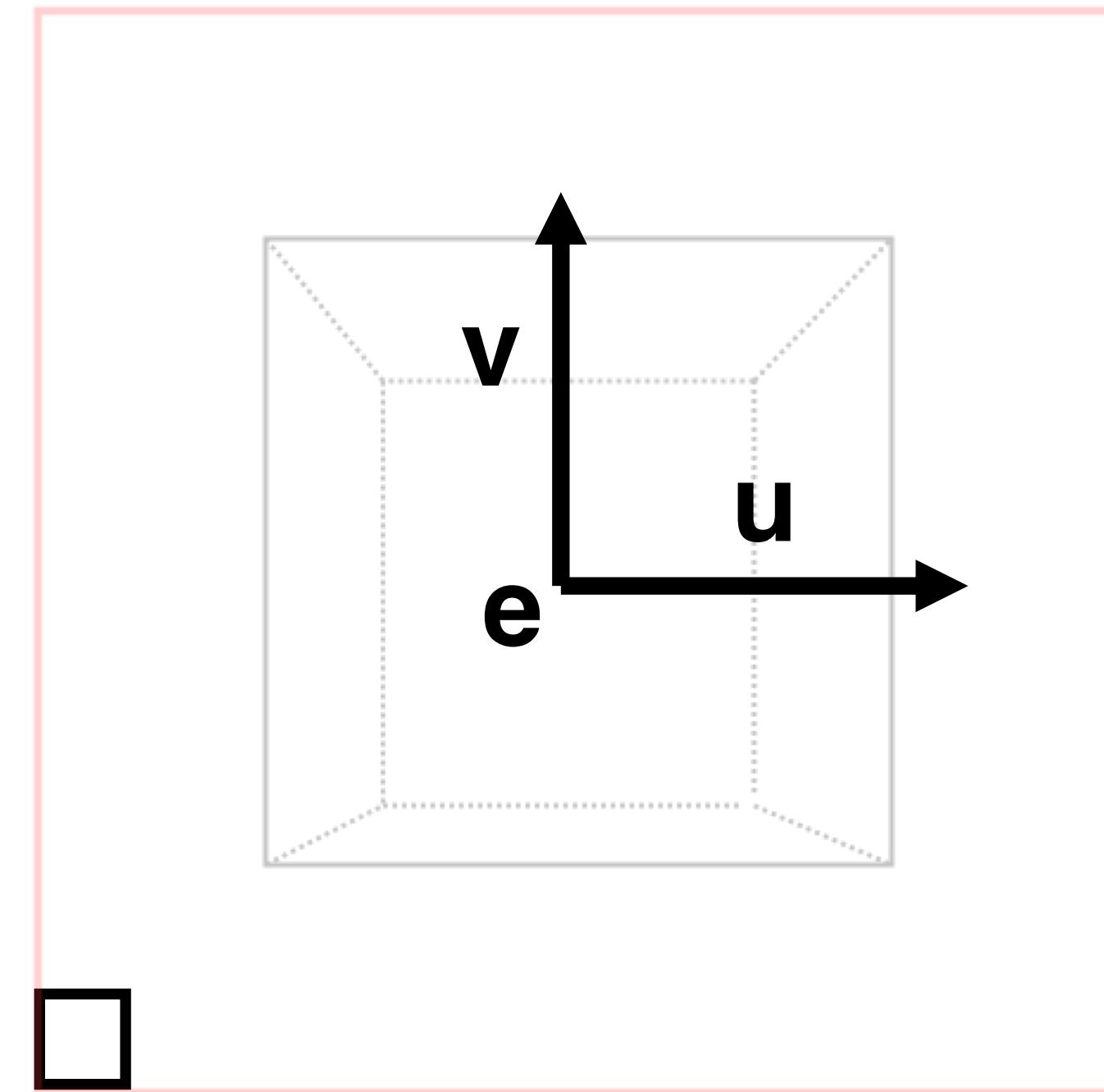
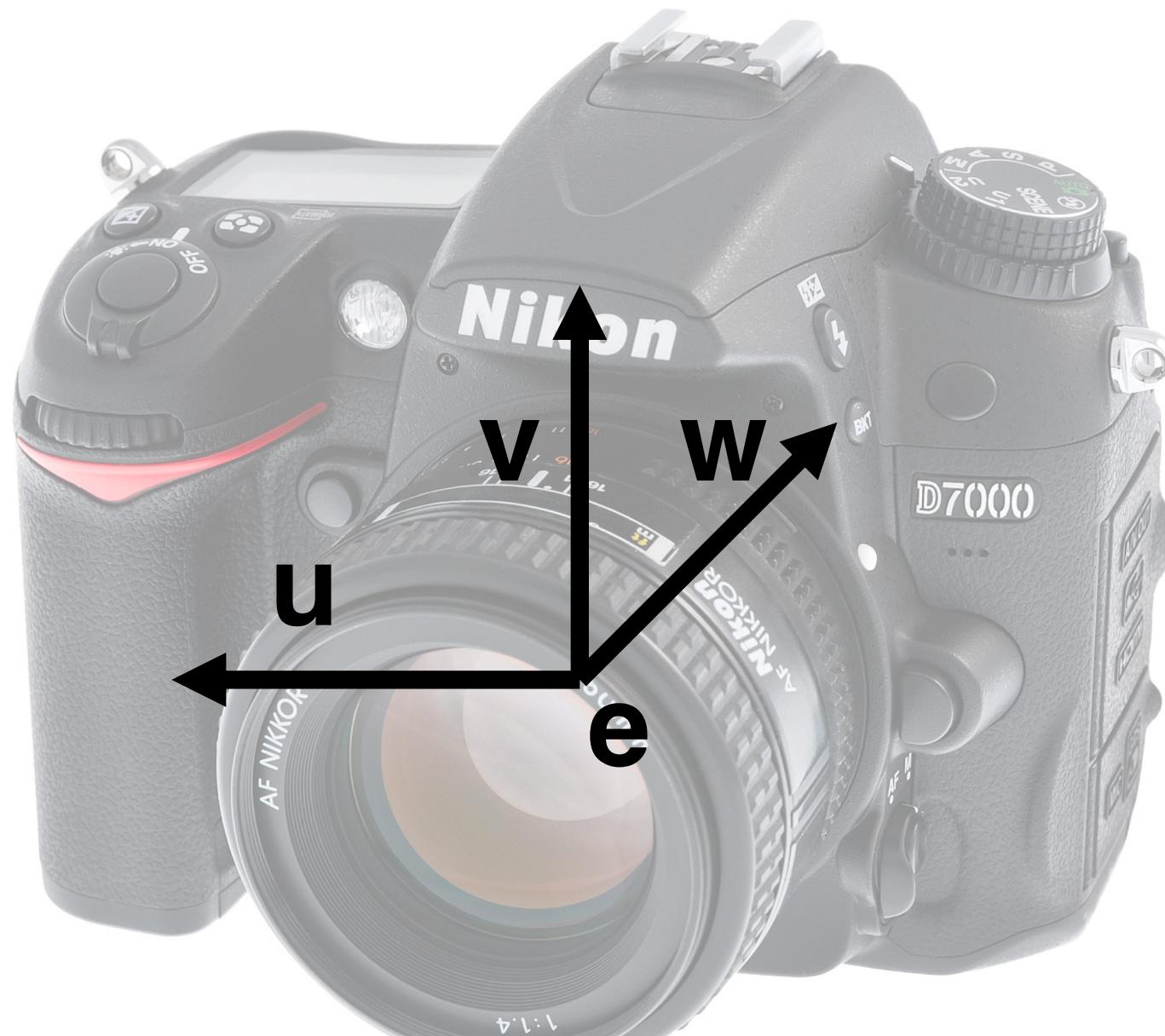


# Orthographic



- For the ray assigned to pixel  $\mathbf{p}$ :
  - Origin:  $\mathbf{p}$
  - Direction:  $-\mathbf{w}$

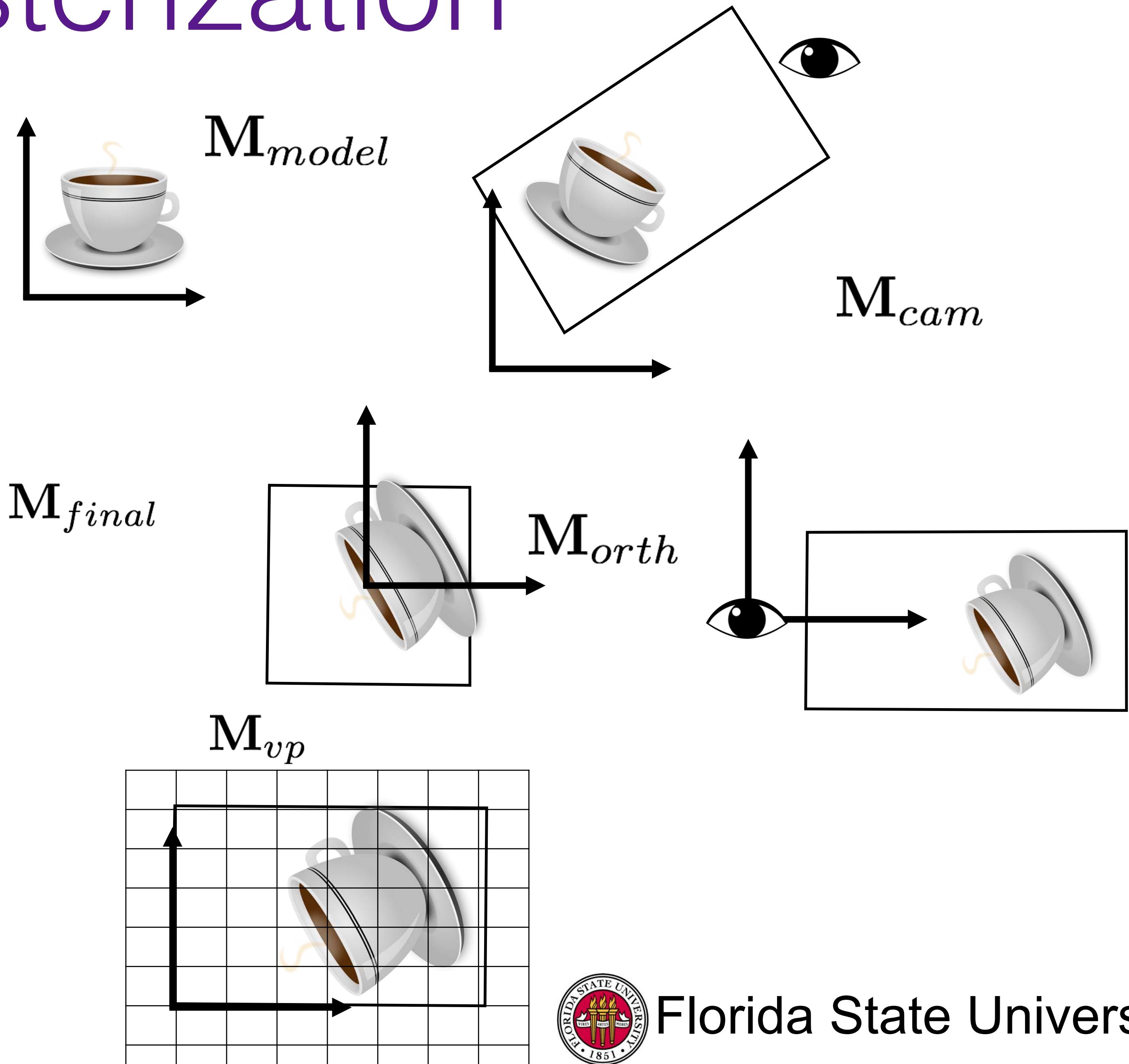
# Perspective

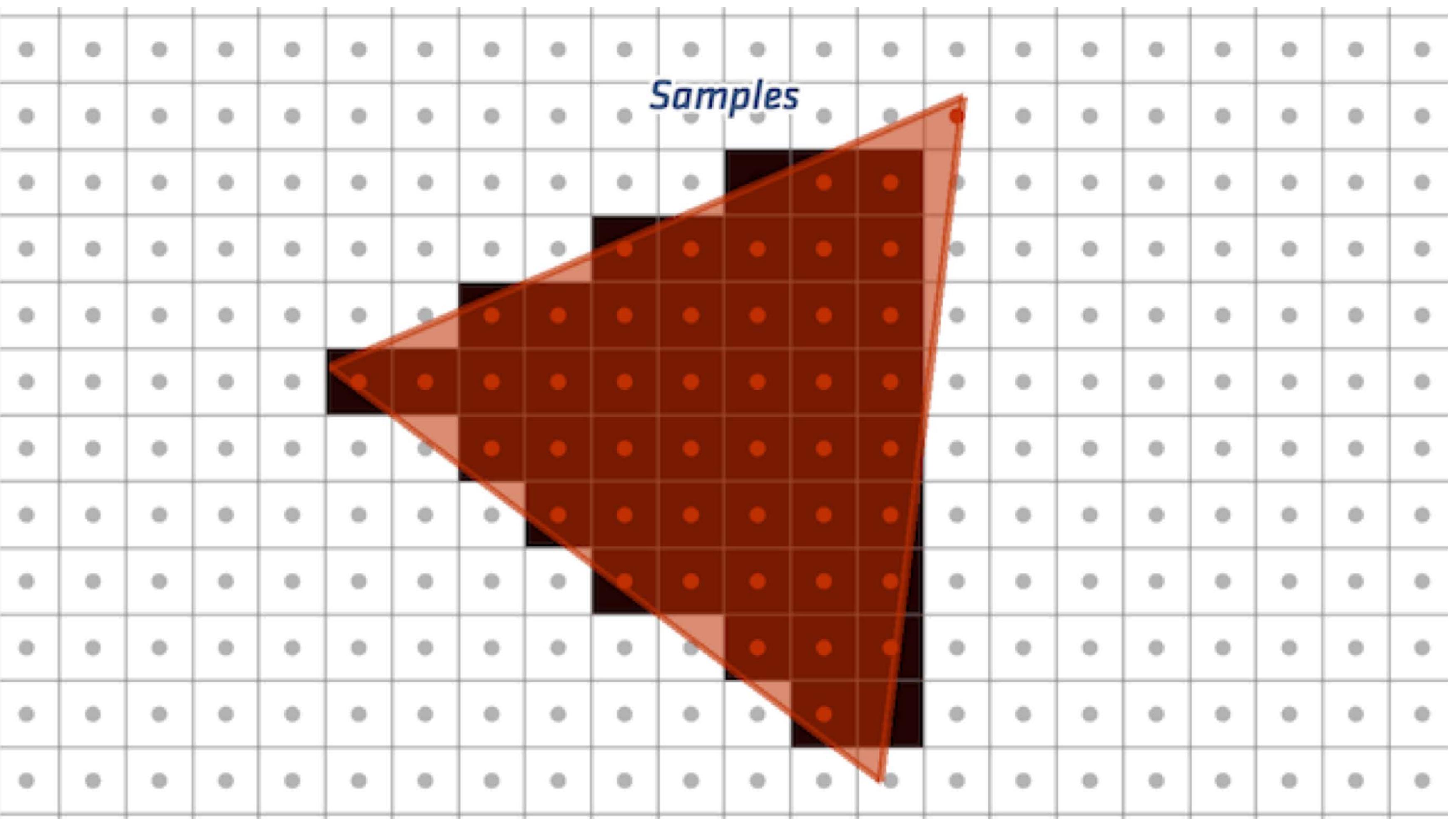


- For the ray assigned to pixel  $\mathbf{p}$ :
  - Origin:  $\mathbf{e}$
  - Direction:  $\mathbf{p} - \mathbf{e}$

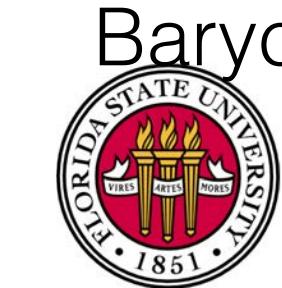
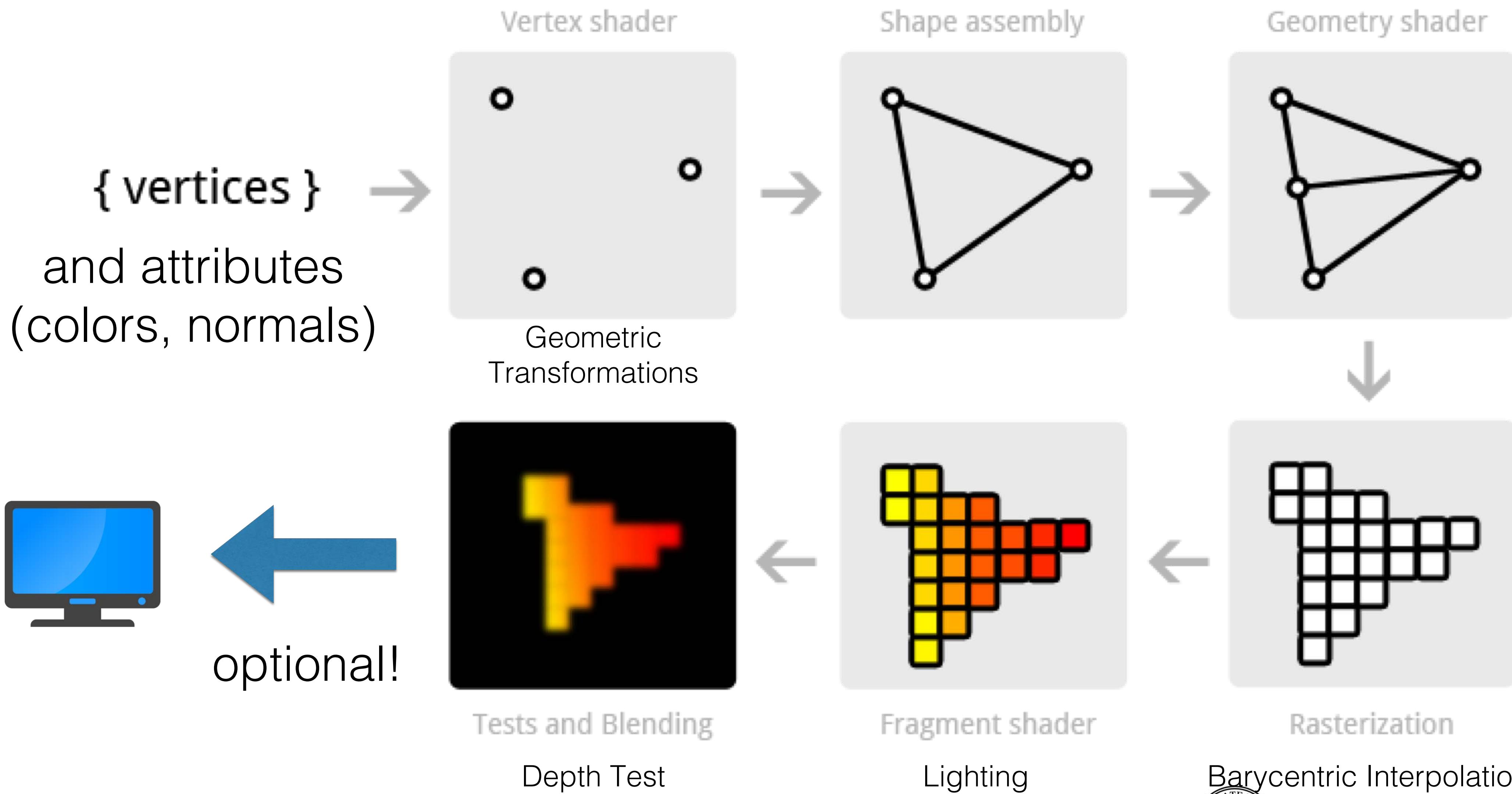
# Rasterization

- Construct Viewport Matrix  $\mathbf{M}_{vp}$
- Construct Projection Matrix  $\mathbf{M}_{orth}$
- Construct Camera Matrix  $\mathbf{M}_{cam}$
- $\mathbf{M} = \mathbf{M}_{vp}\mathbf{M}_{orth}\mathbf{M}_{cam}$
- For each model
  - Construct Model Matrix  $\mathbf{M}_{model}$
  - $\mathbf{M}_{final} = \mathbf{M}\mathbf{M}_{model}$
  - For every point  $\mathbf{p}$  in each primitive of the model
    - $\mathbf{p}_{final} = \mathbf{M}_{final}\mathbf{p}$
    - Rasterize the model



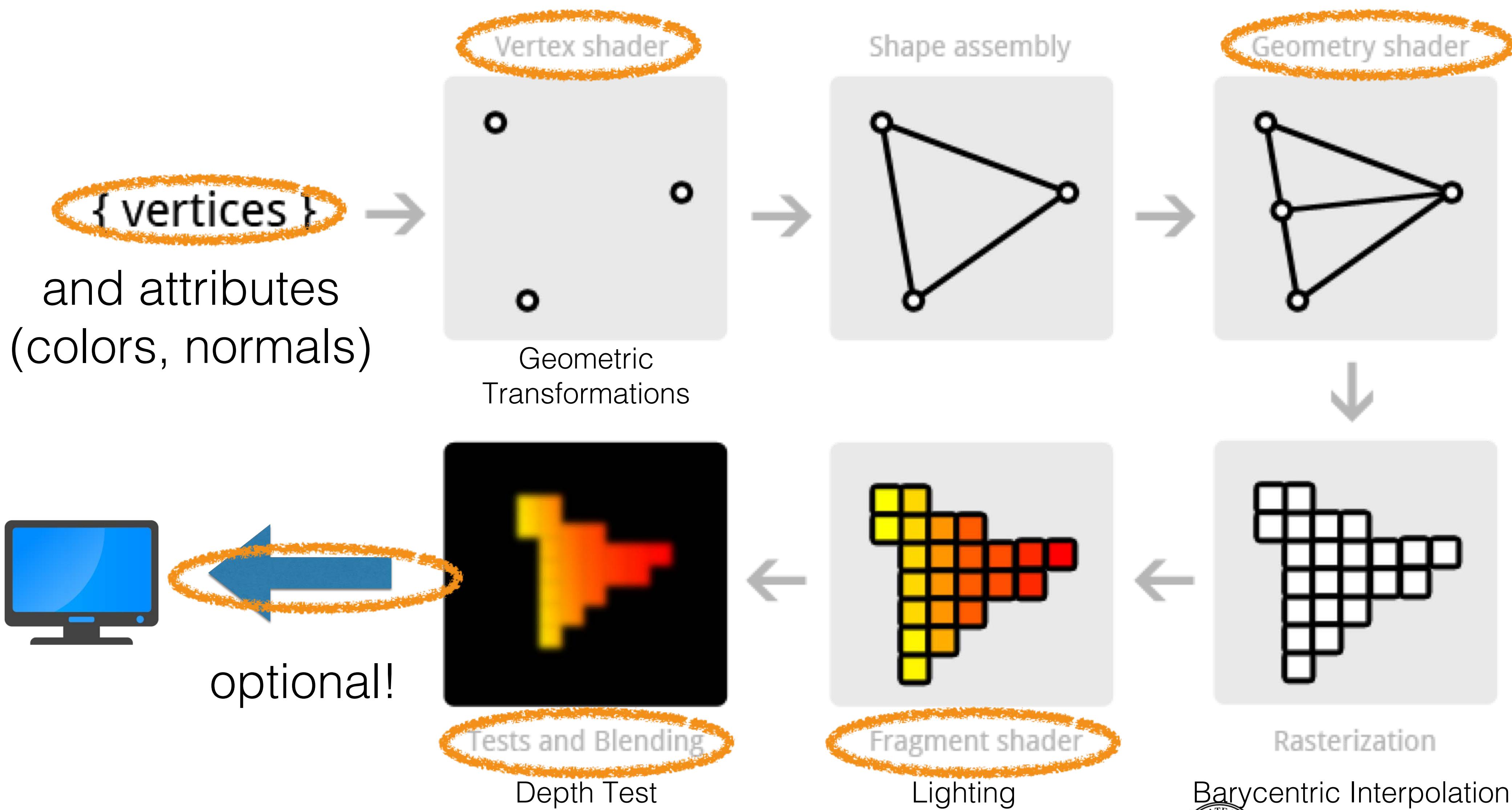


# OpenGL pipeline



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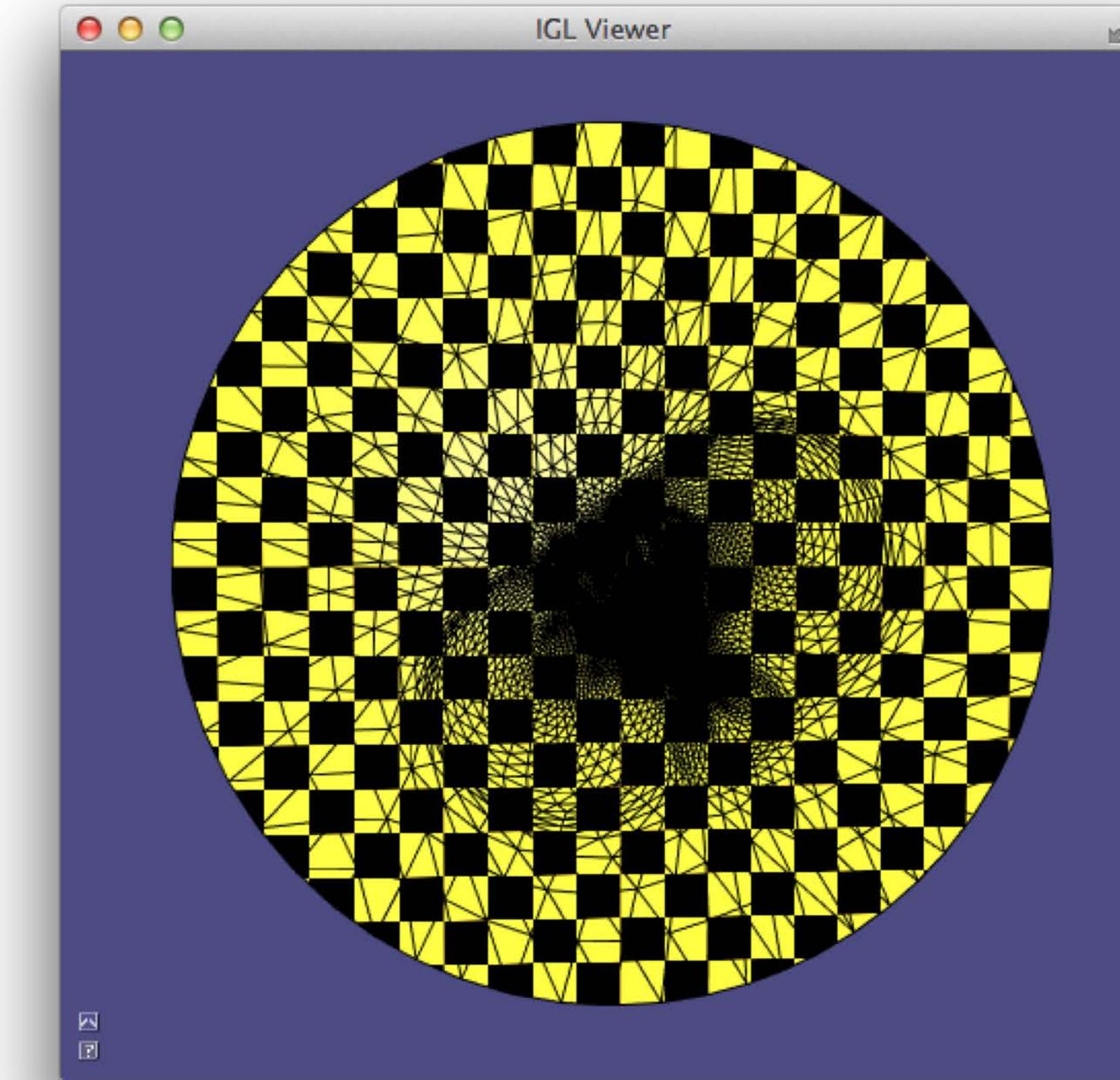
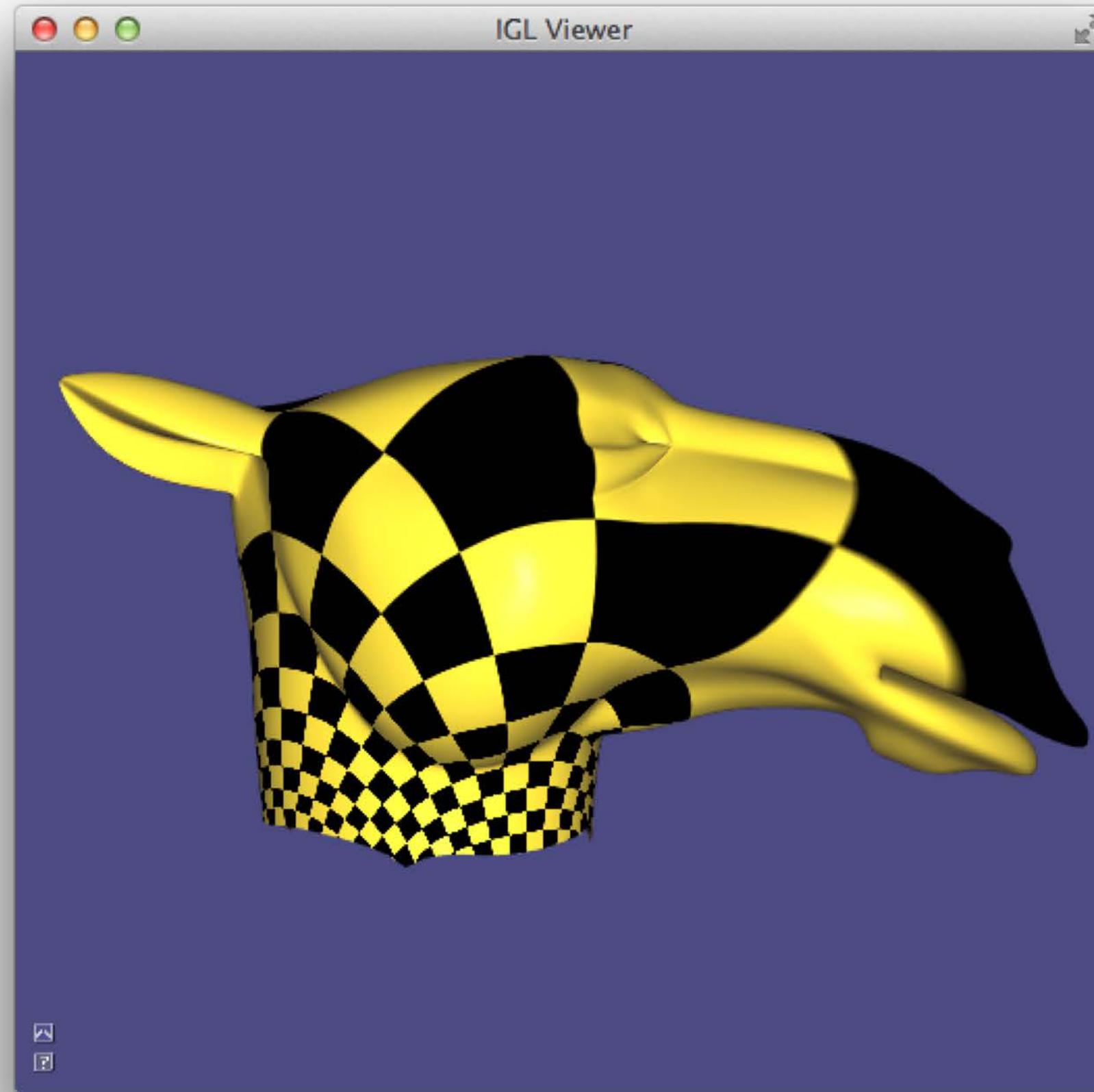
# OpenGL pipeline



Barycentric Interpolation

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# Demo



<https://libigl.github.io/libigl/tutorial/tutorial.html#harmonicparametrization>



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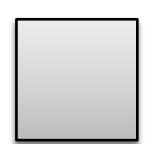
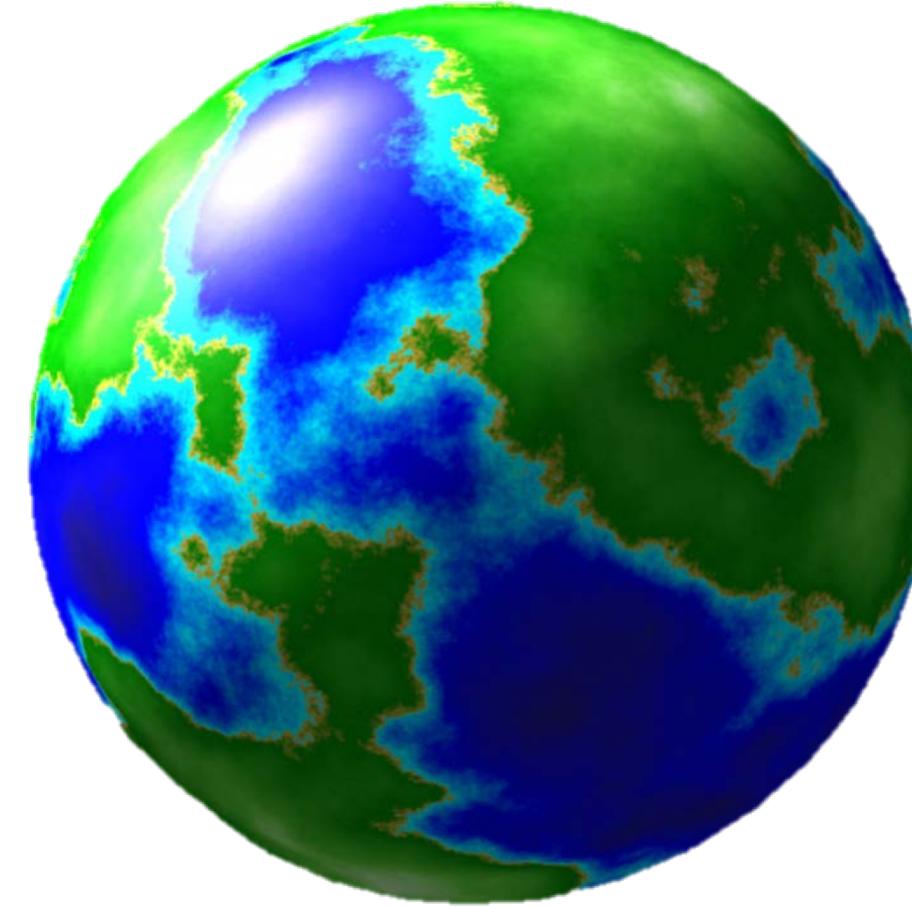
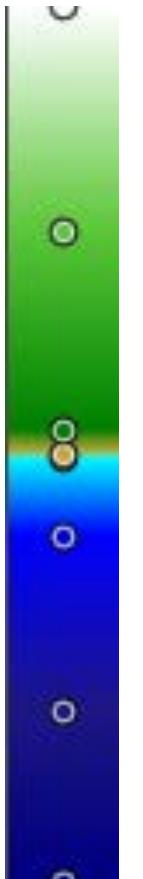
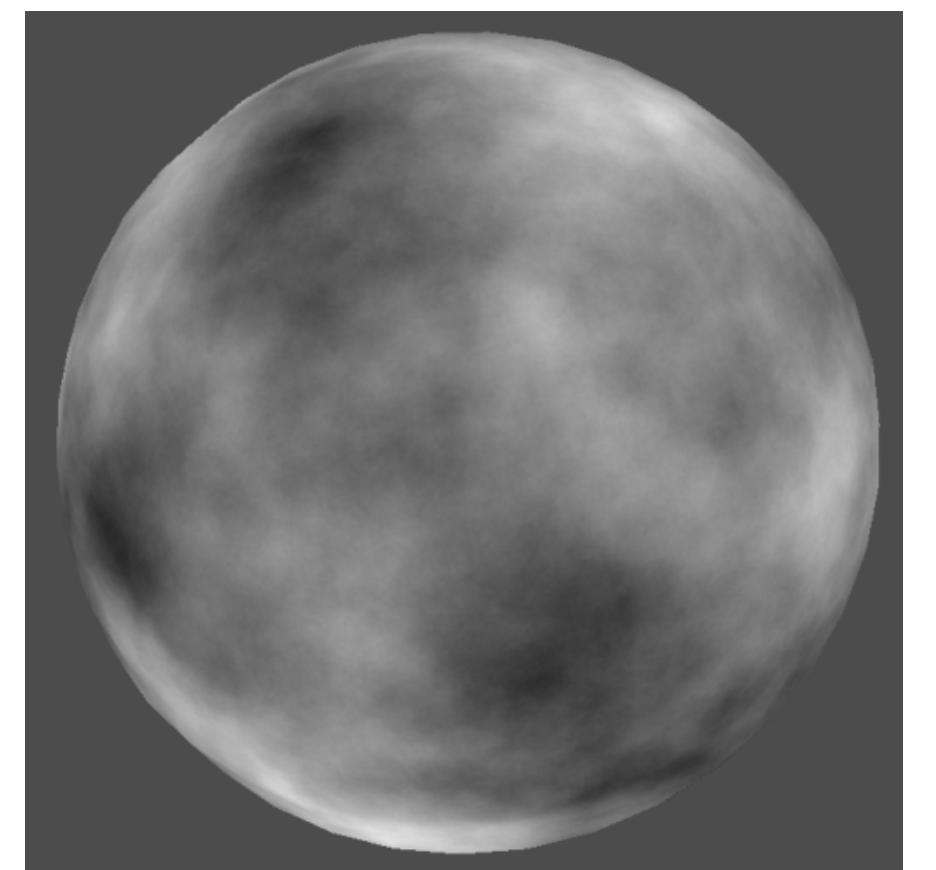
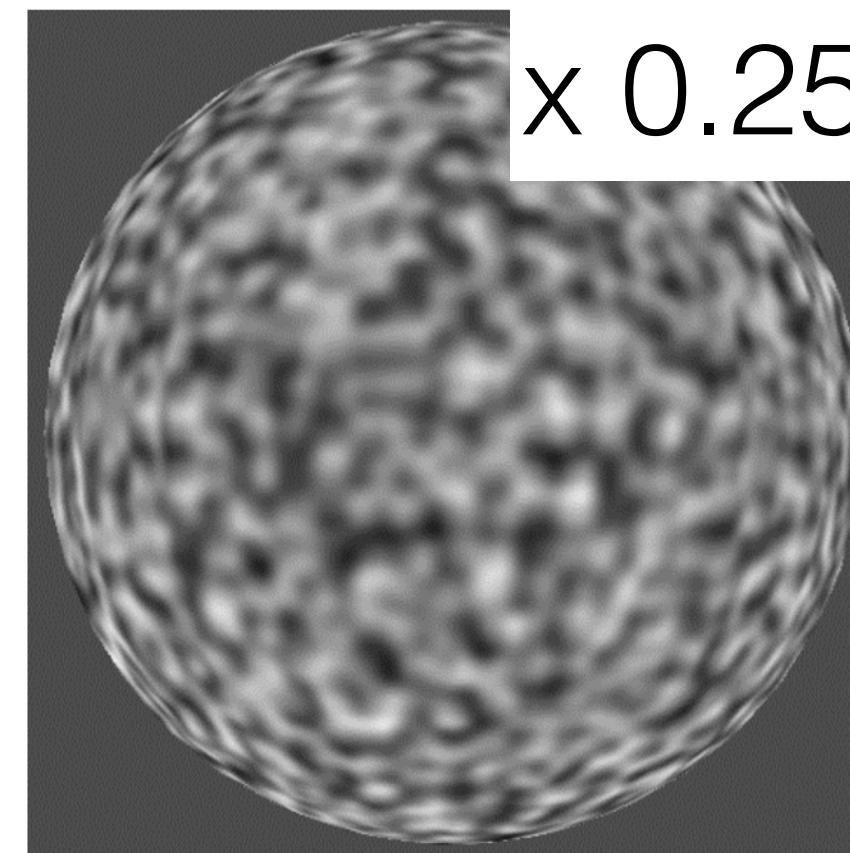
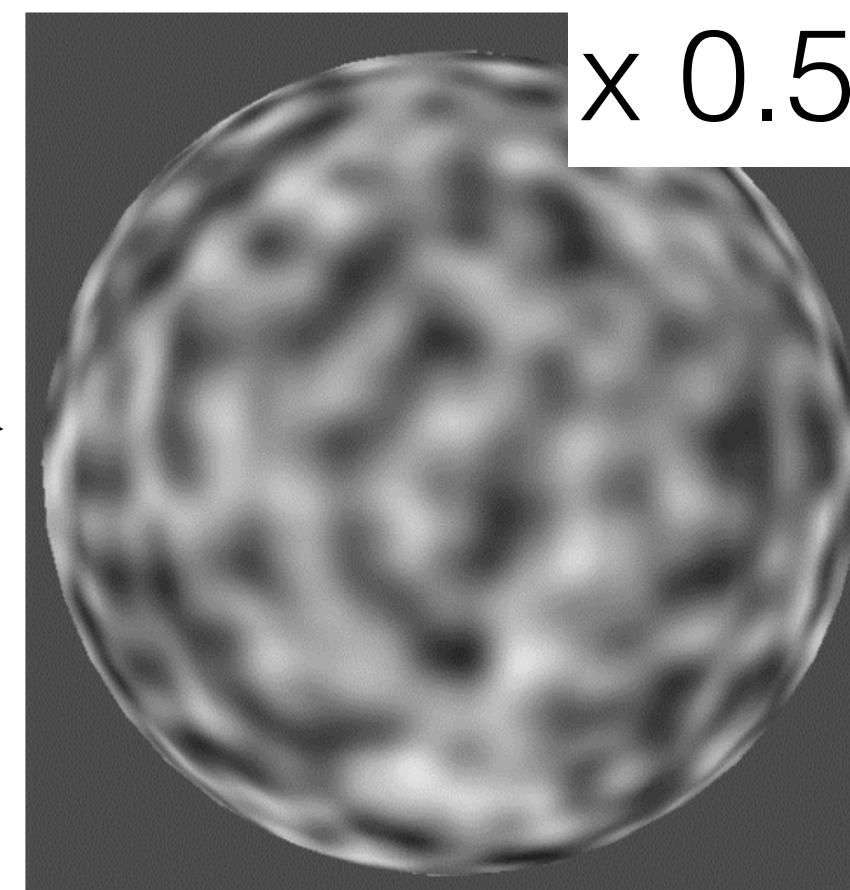
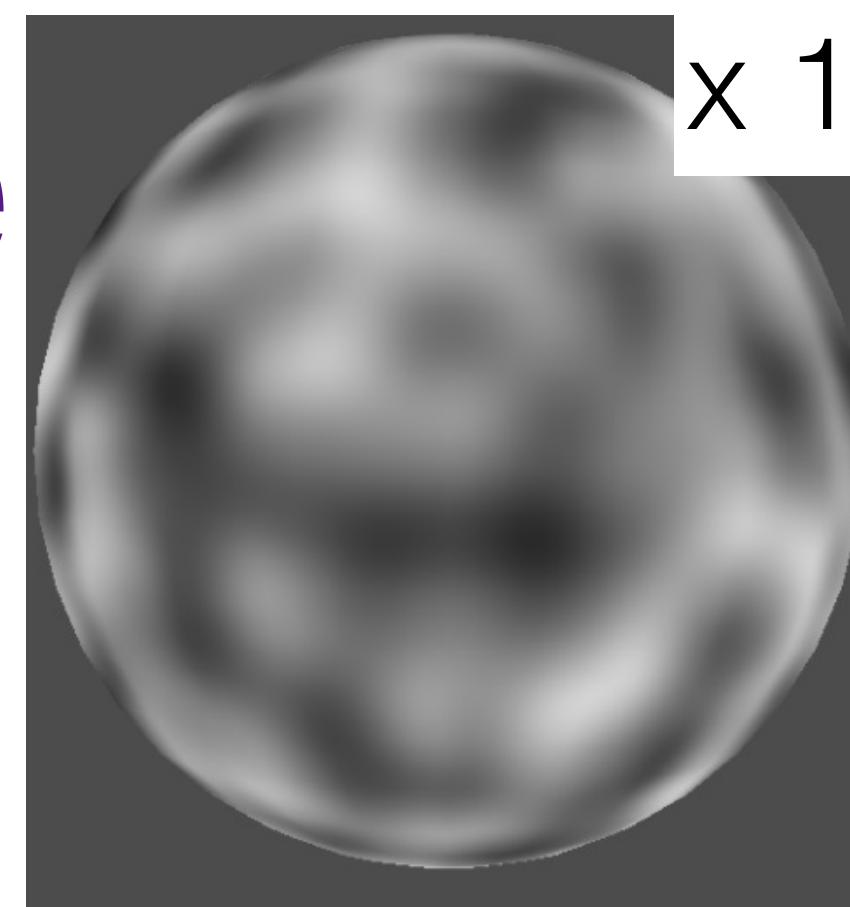
# “Seams” are needed for complex objects



Image from Vallet and Levy, techreport INRIA

# Combine

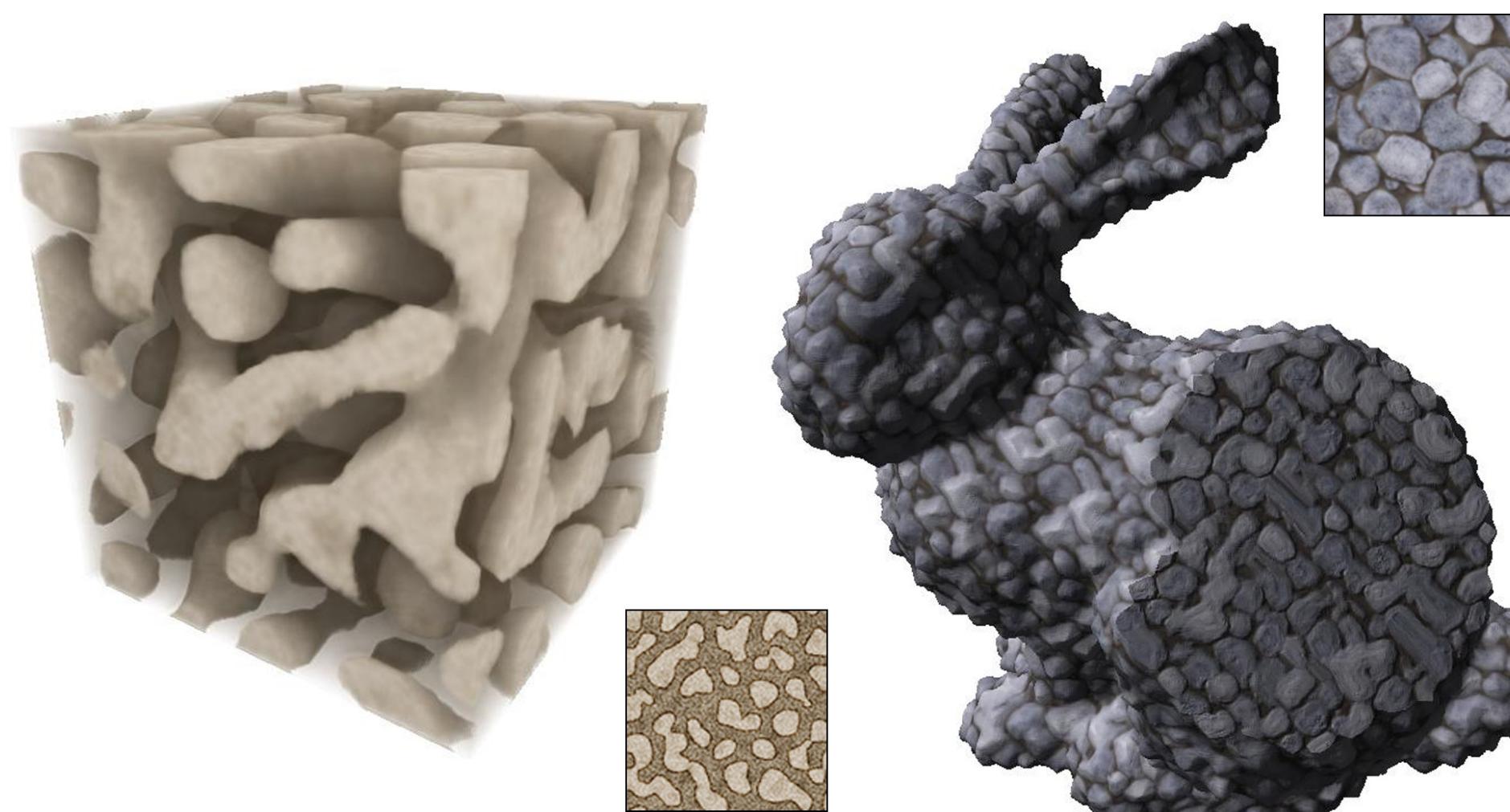
42 →  
seed



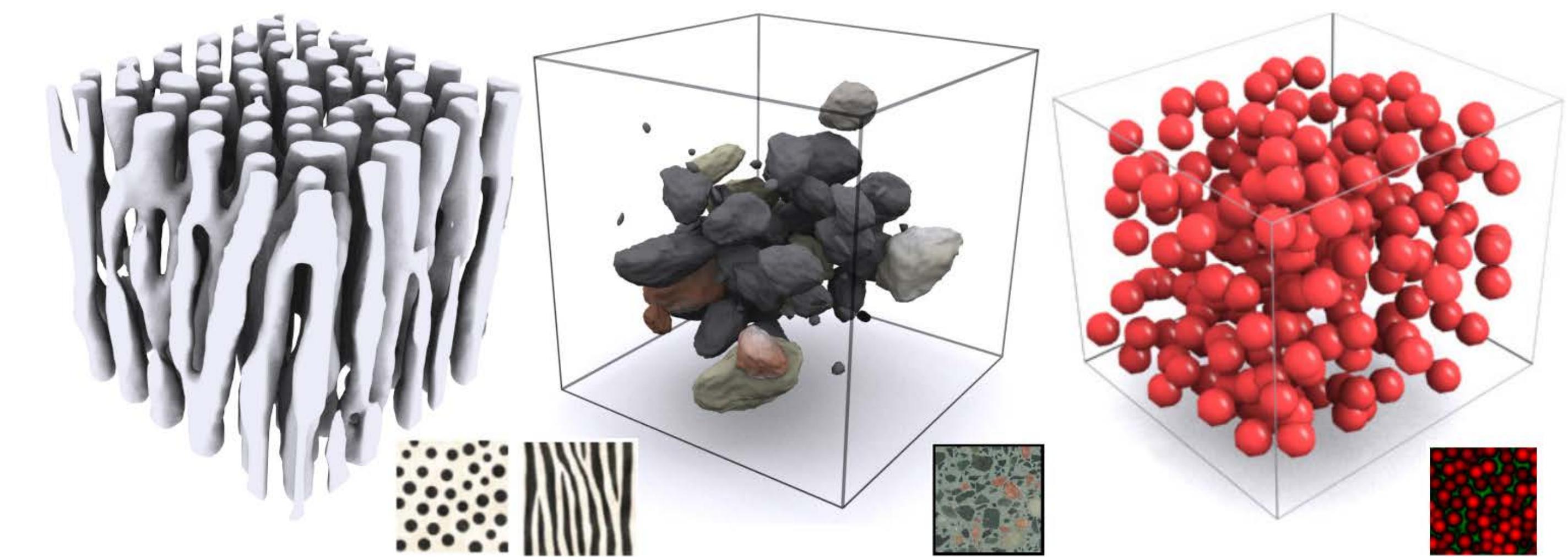
color =  $f(x,y,z)$

# and add colors!

# By-Example Solid Textures



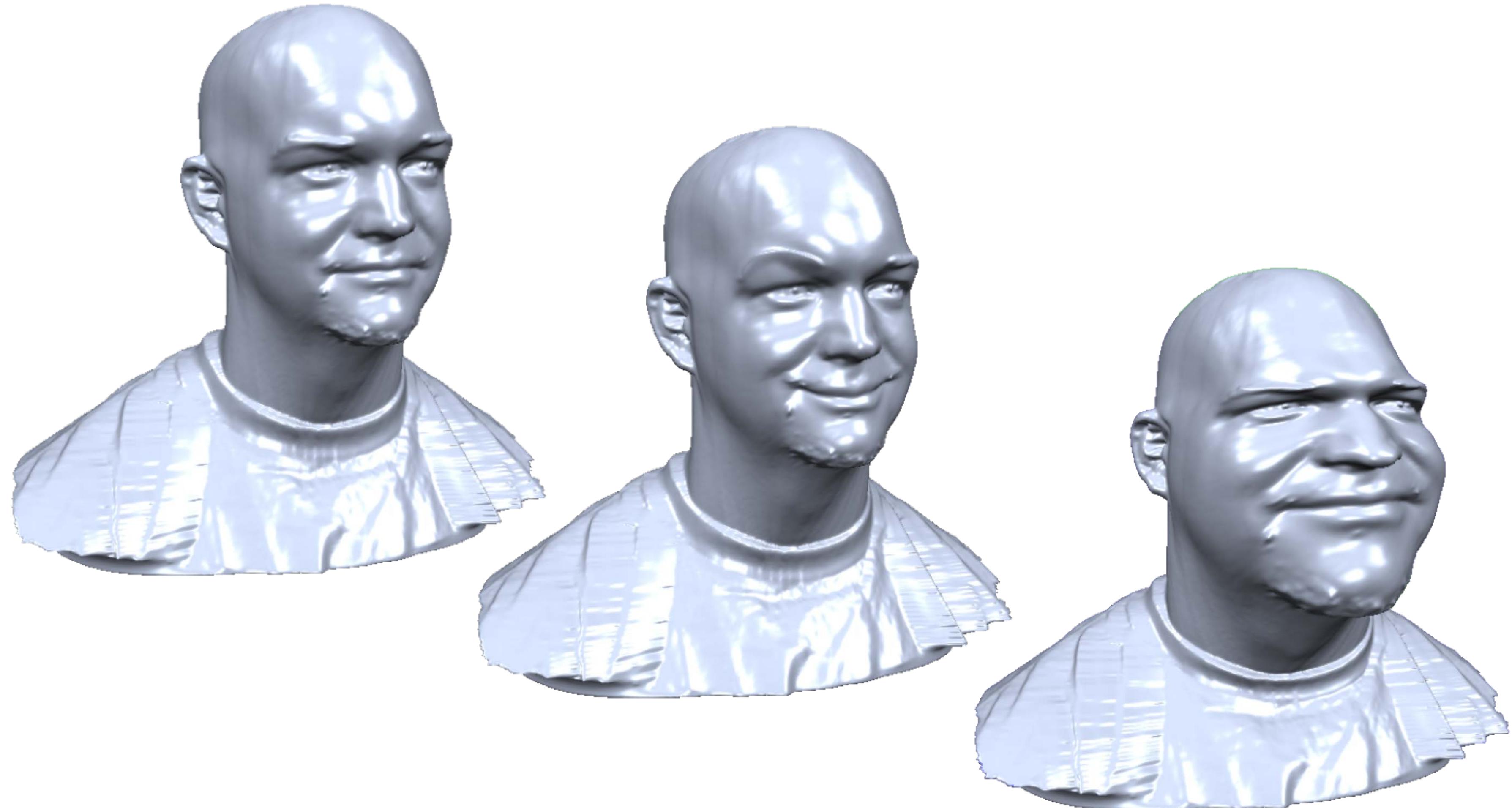
Solid Texture Synthesis [Kopf07]



Lazy Solid Texture Synthesis [Dong08]

# Local & Global Deformations

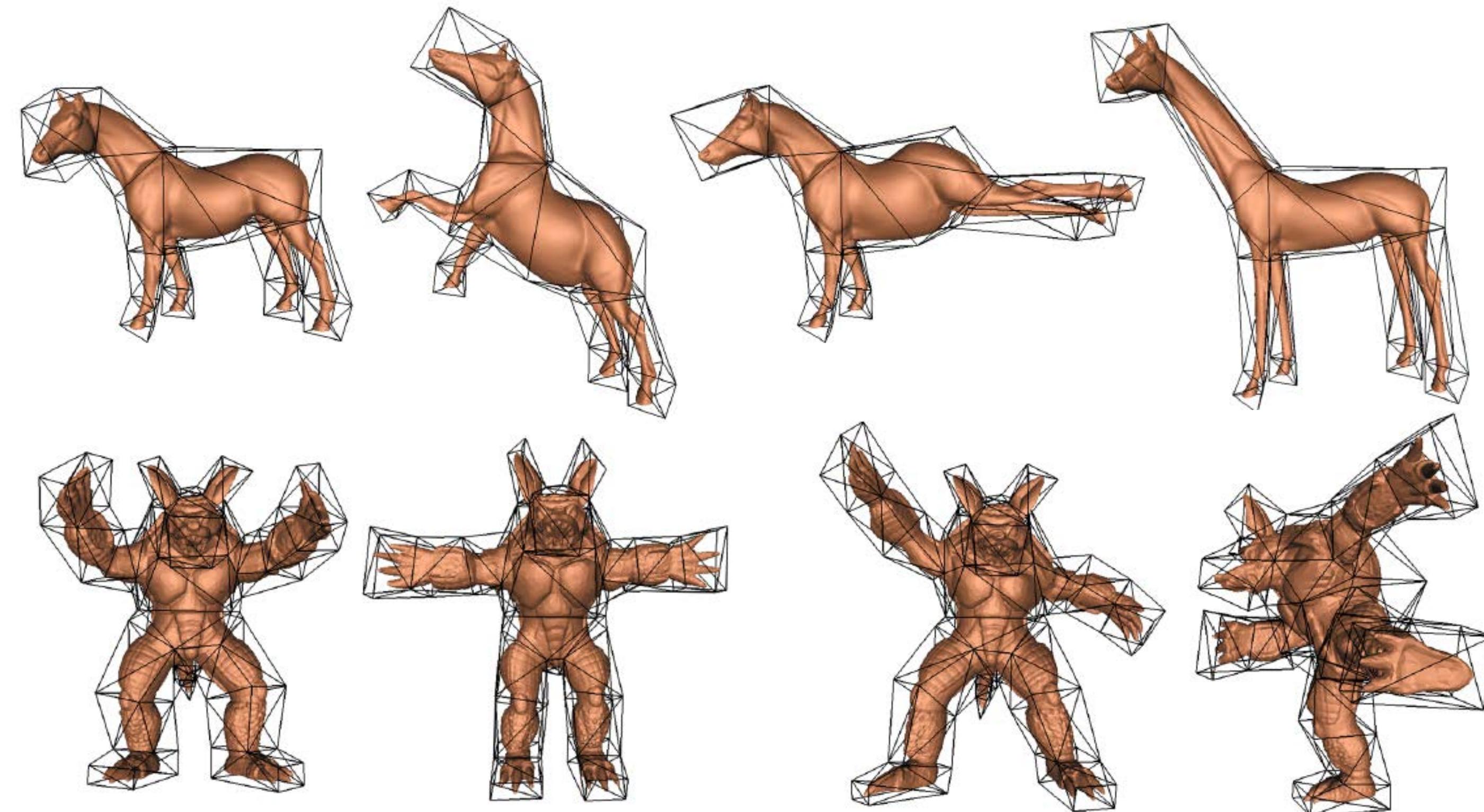
[Real-Time Shape Editing using Radial Basis Functions, Botsch and Kobbelt, EUROGRAPHICS 2005]



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# Cage-based Deformations

[Ju et al. 2005]

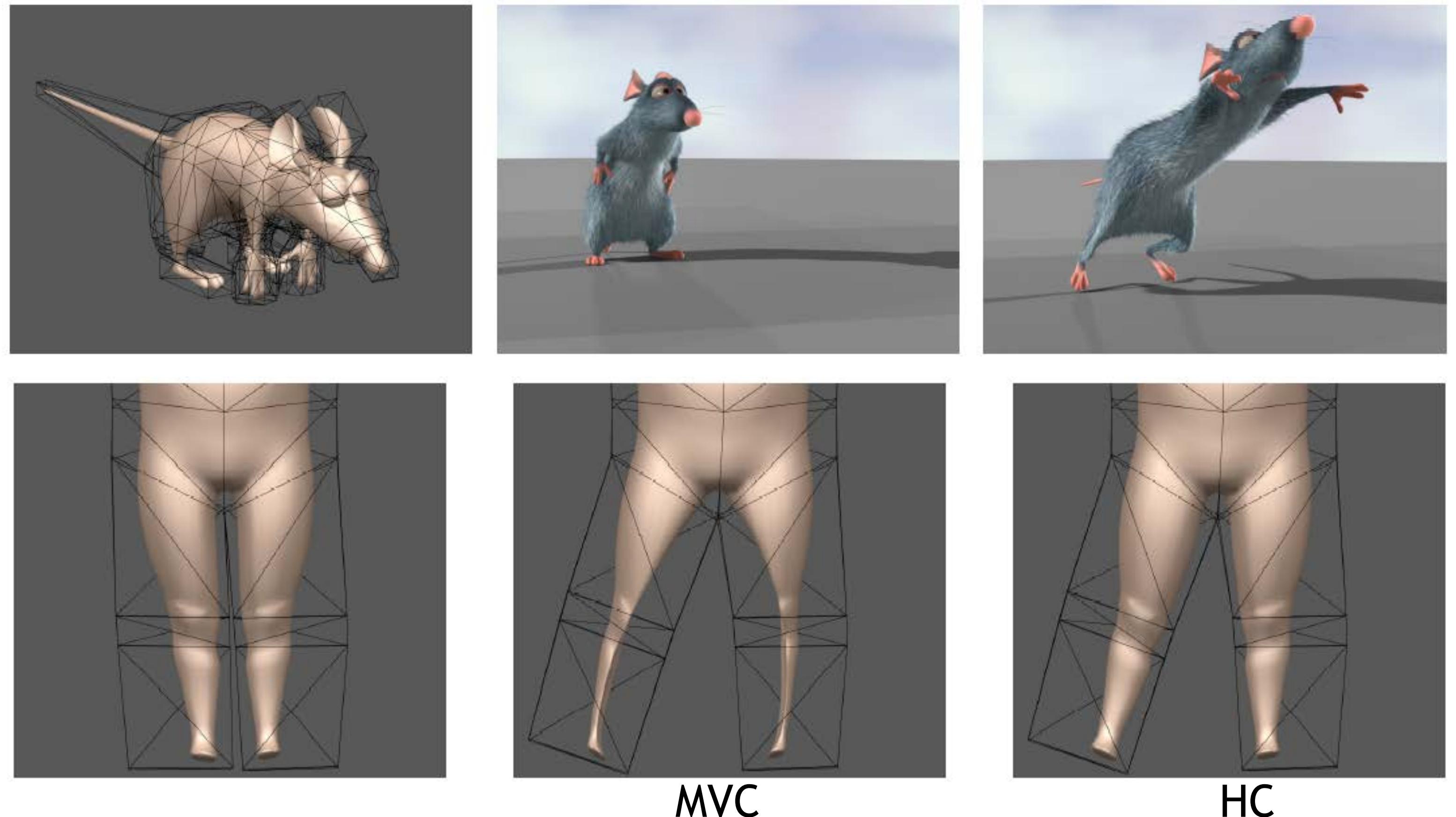


<http://www.cs.wustl.edu/~taoju/research/meanvalue.pdf>

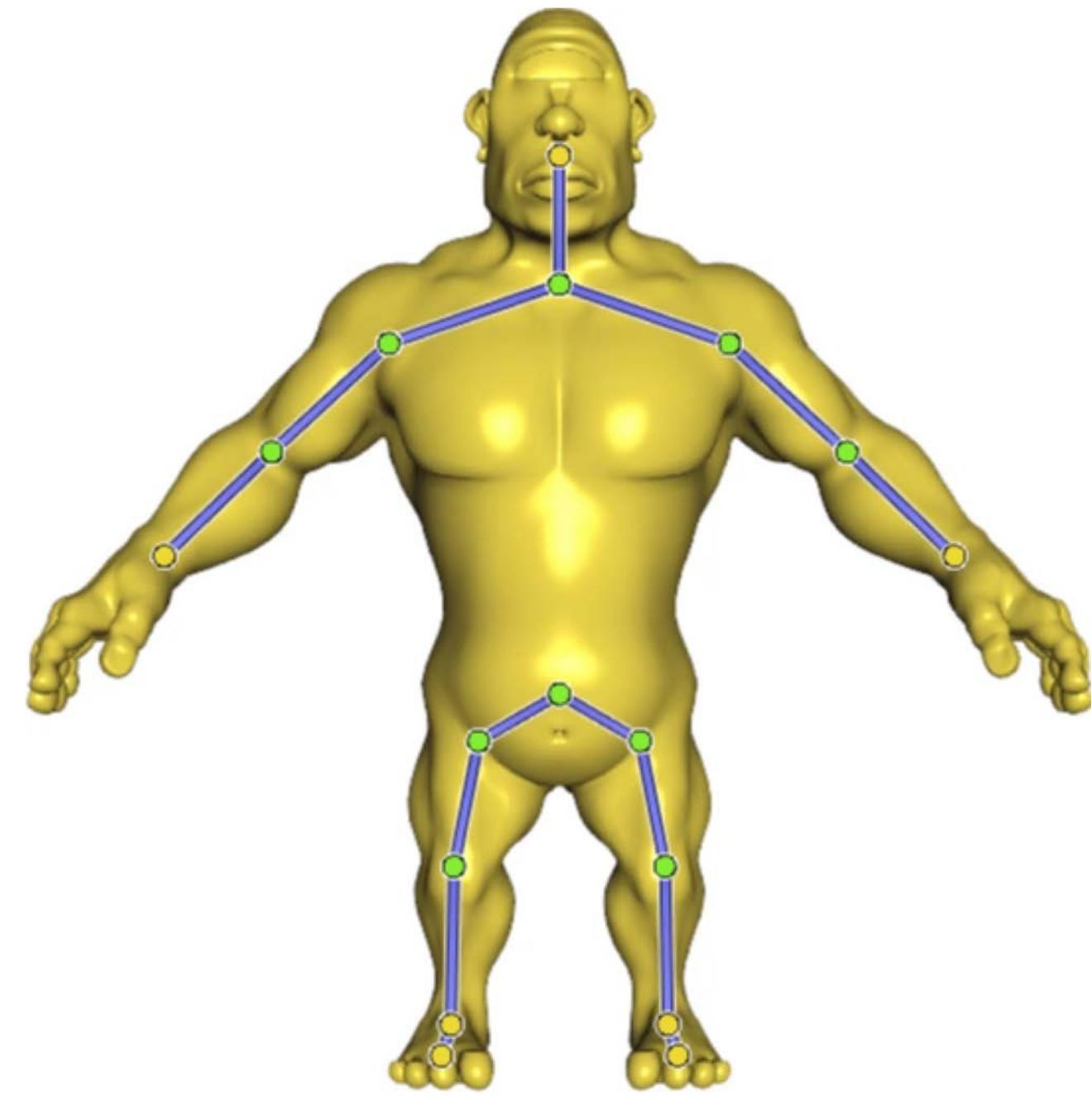


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# Harmonic coordinates ([Joshi et al. 2007](#))



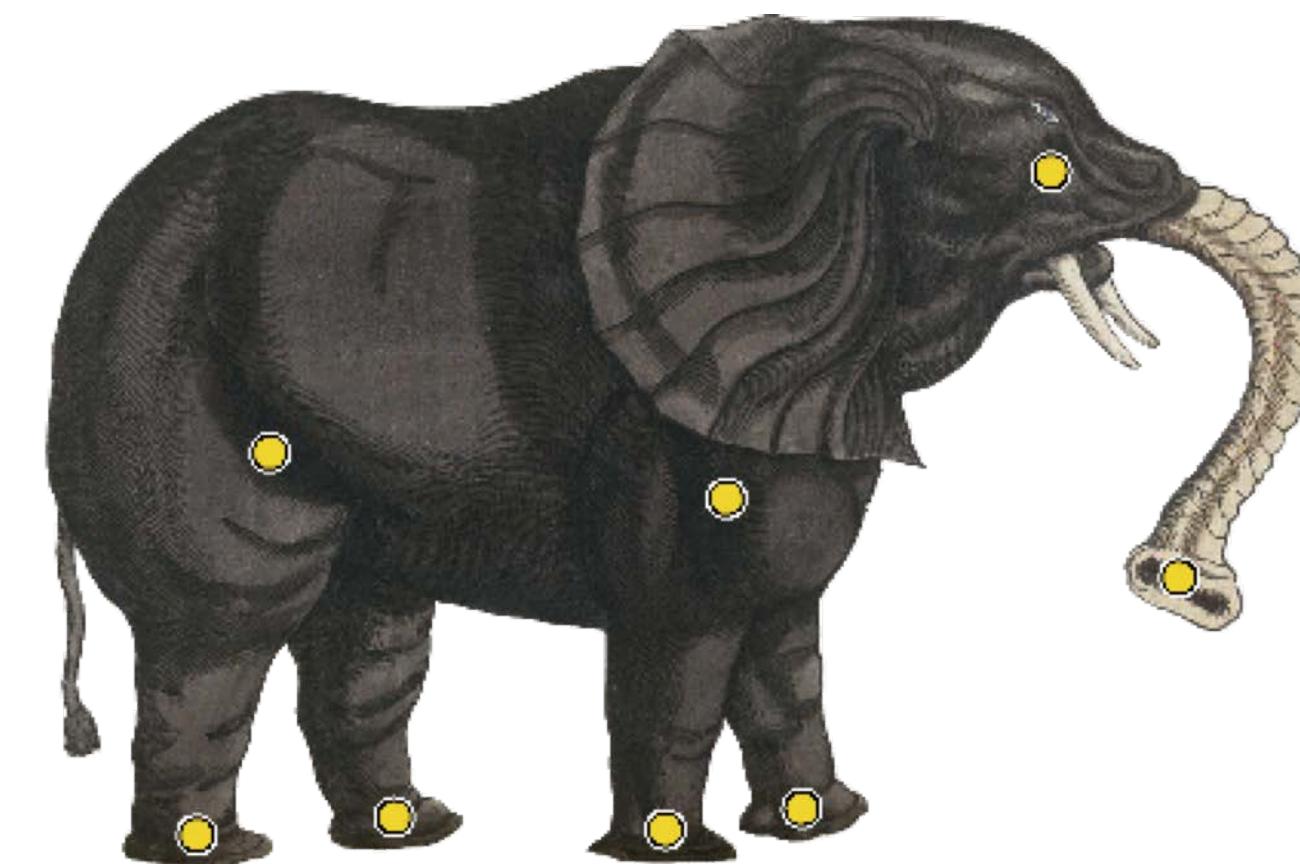
# LBS generalizes to different handle types



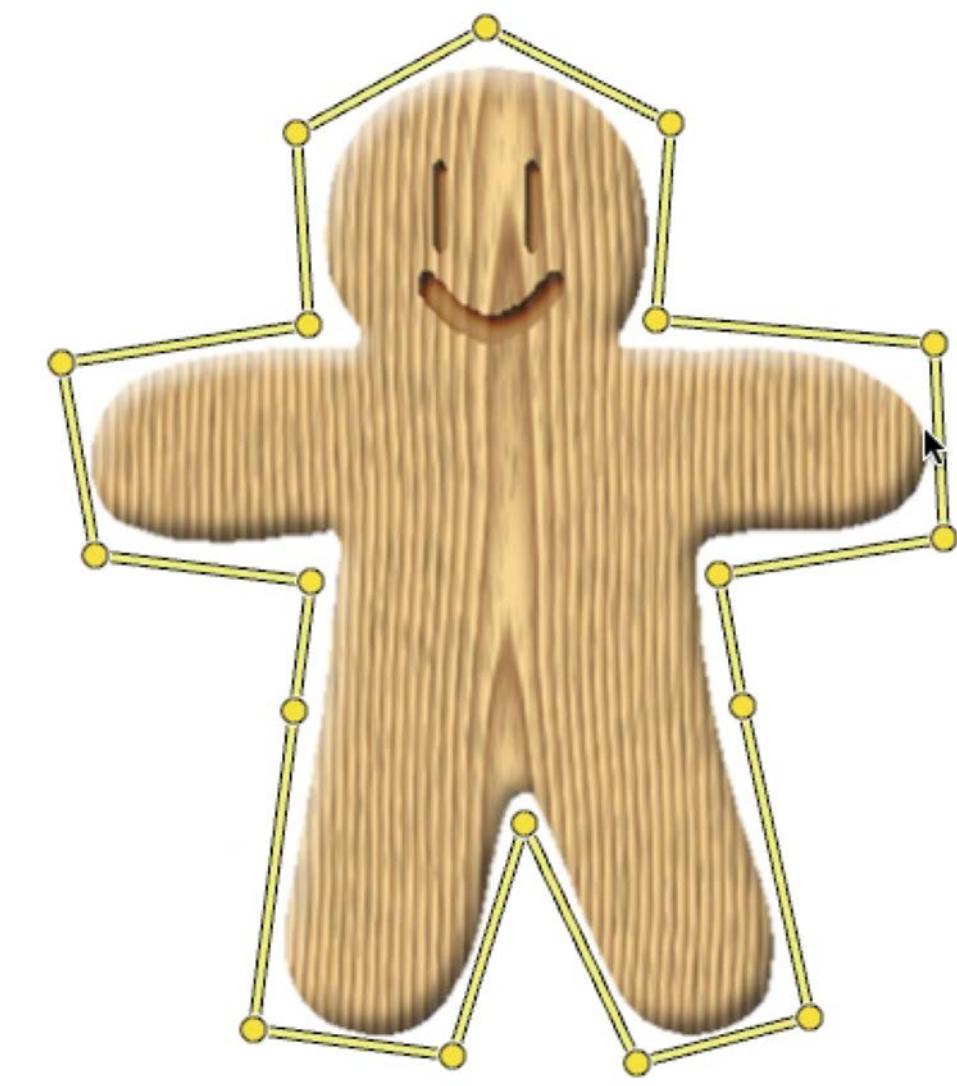
skeletons



regions

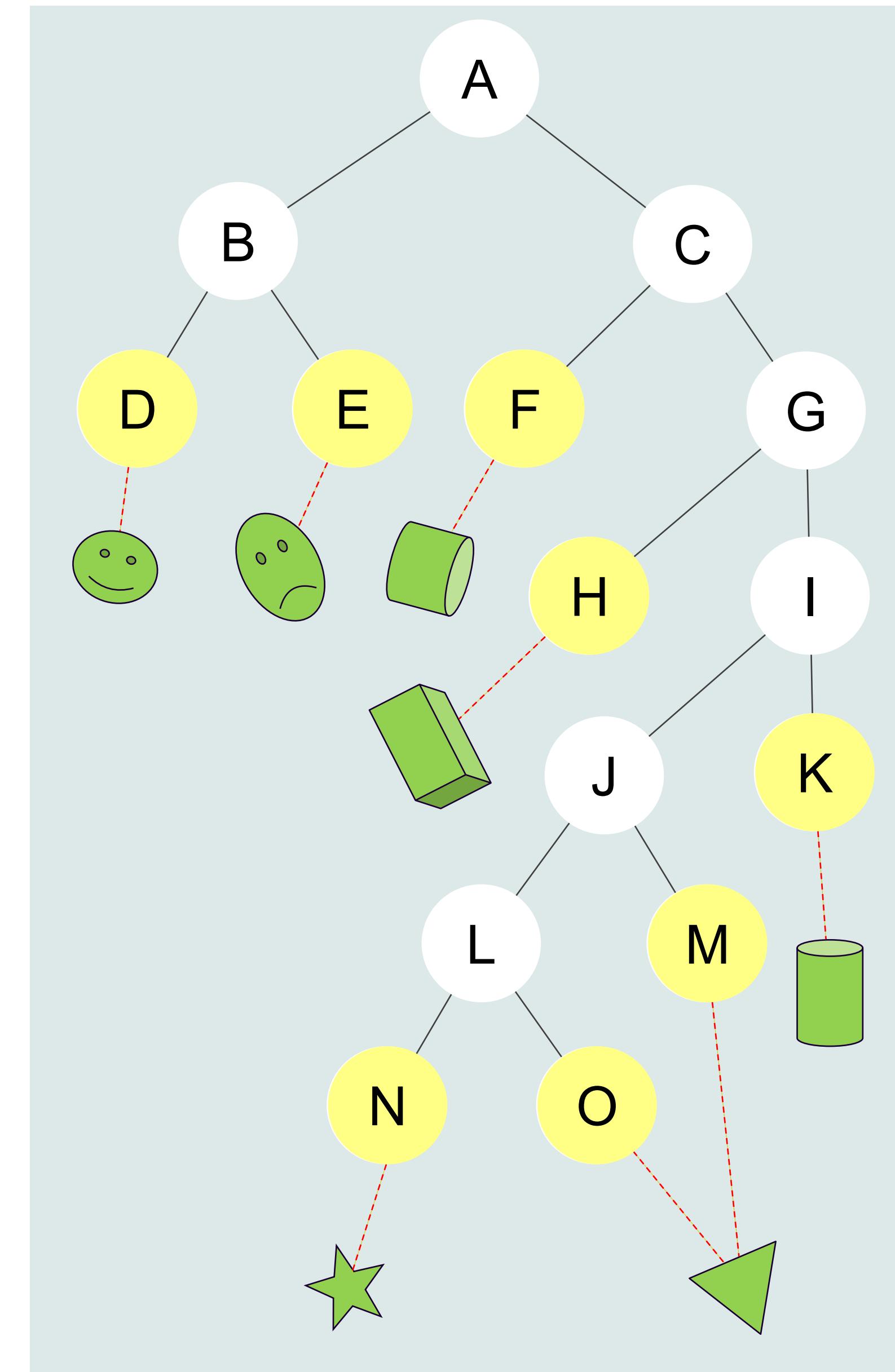
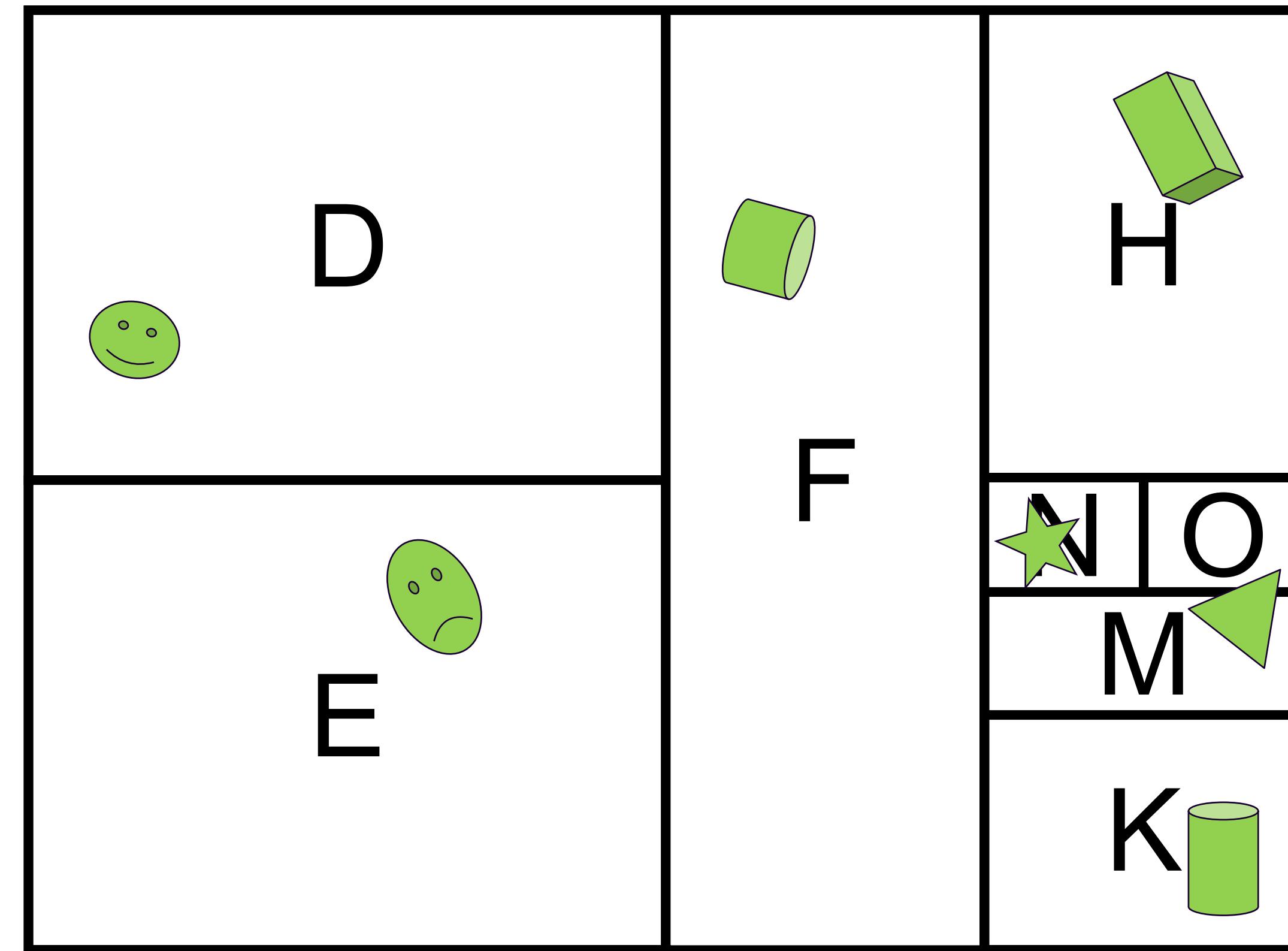


points



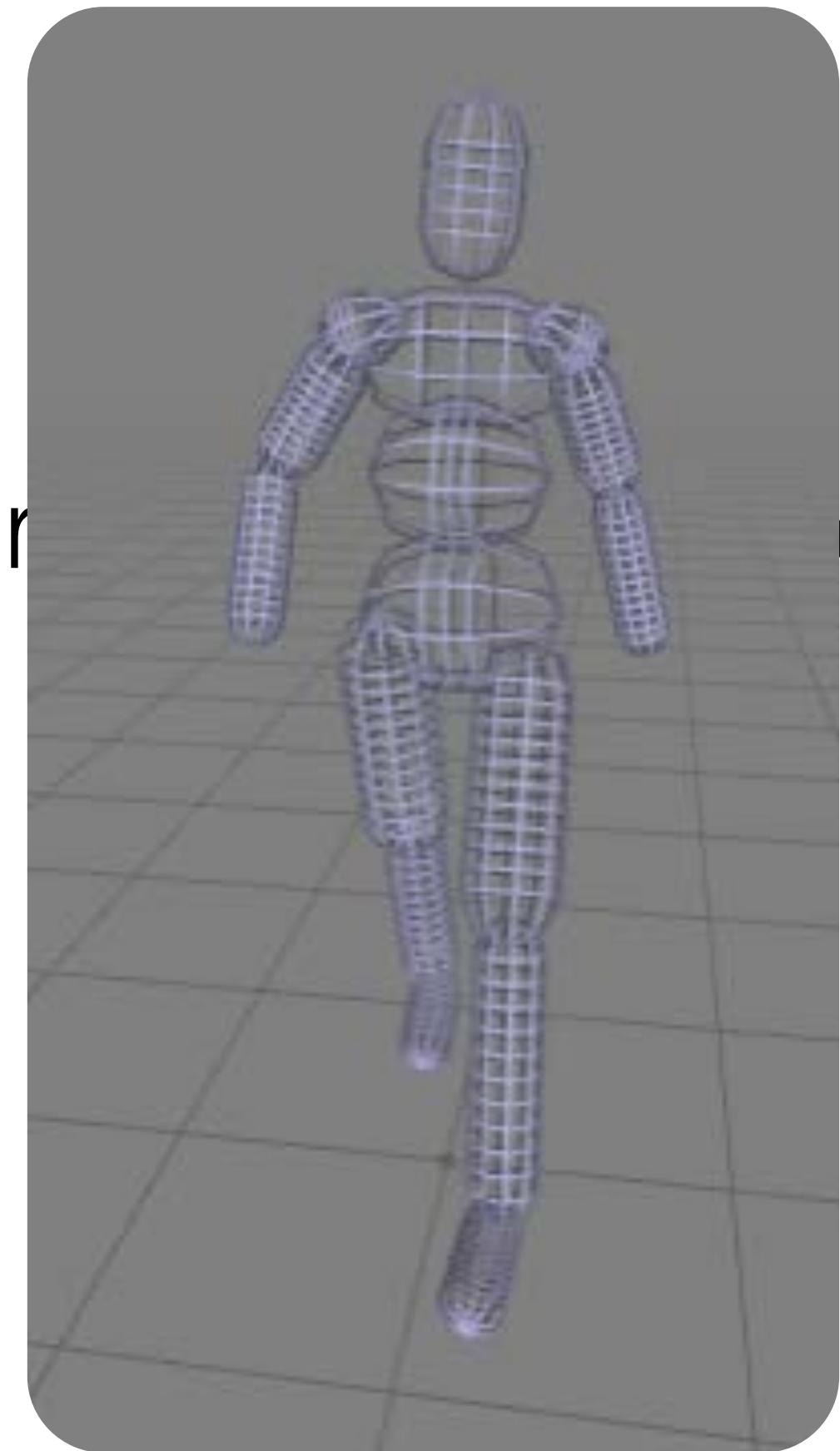
cages

# kD-tree



# Geometric Proxies

- Idea: use a geometric proxy to approximate objects in the scene



# Final Project

- Time and location option
- Tuesday, Dec 11, LOV 103, 10:00 am – 12:00 pm
- Thursday, Dec 13, LOV 151, 2:00 pm – 4:00 pm
- Friday, Dec 14, LOV 151, 8:00 am – 9:30 am
- Submit the entire package, source code and readme, through CANVAS
- 8 mins for each presenter, in the alphabetical order of the last name



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