

Rasterization

Acknowledgements: Daniele Panozzo

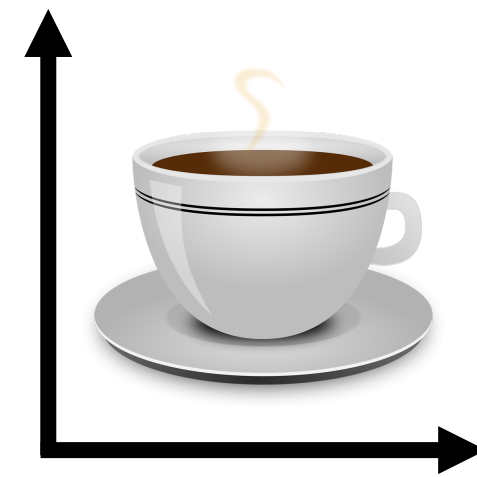
CAP 5726 - Computer Graphics - Fall 18 – Xifeng Gao



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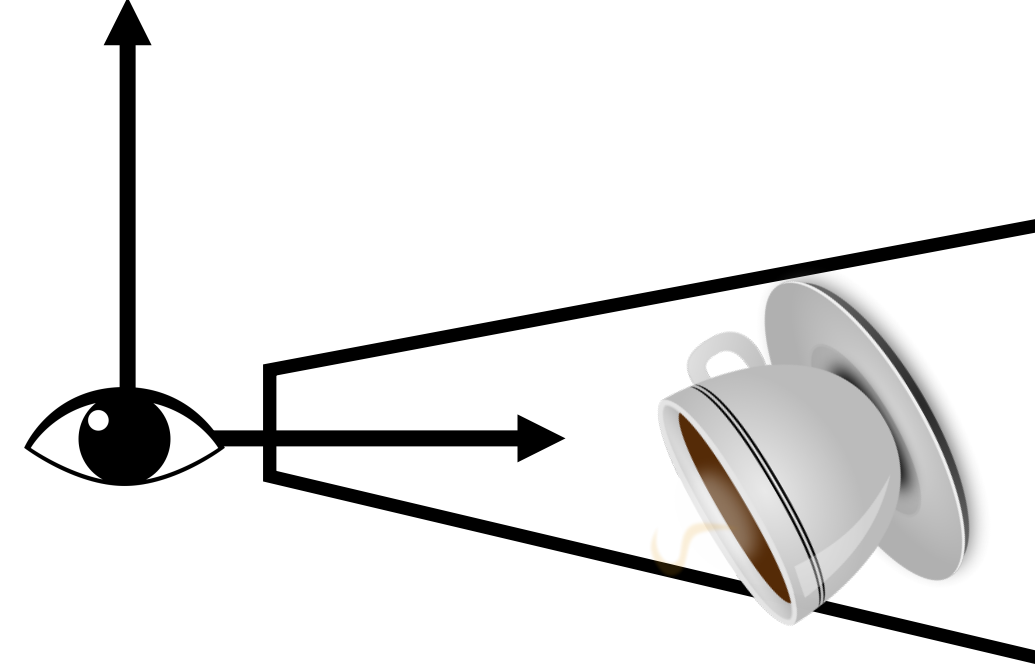
Recap: Viewing Transformation

object space



model

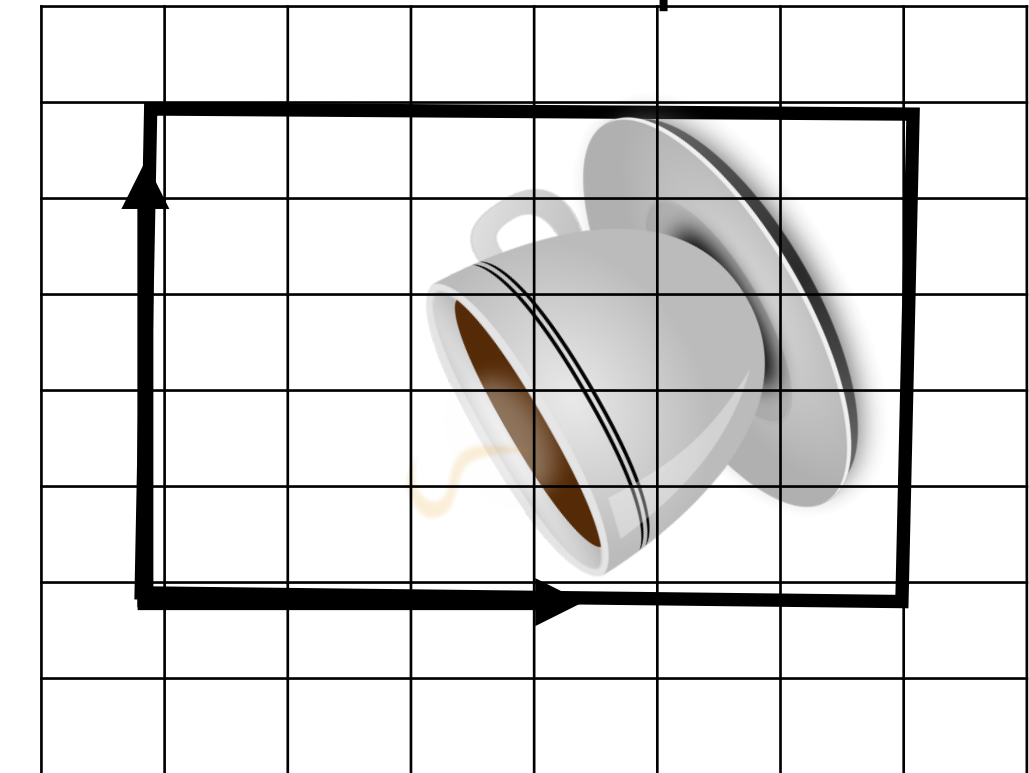
camera space



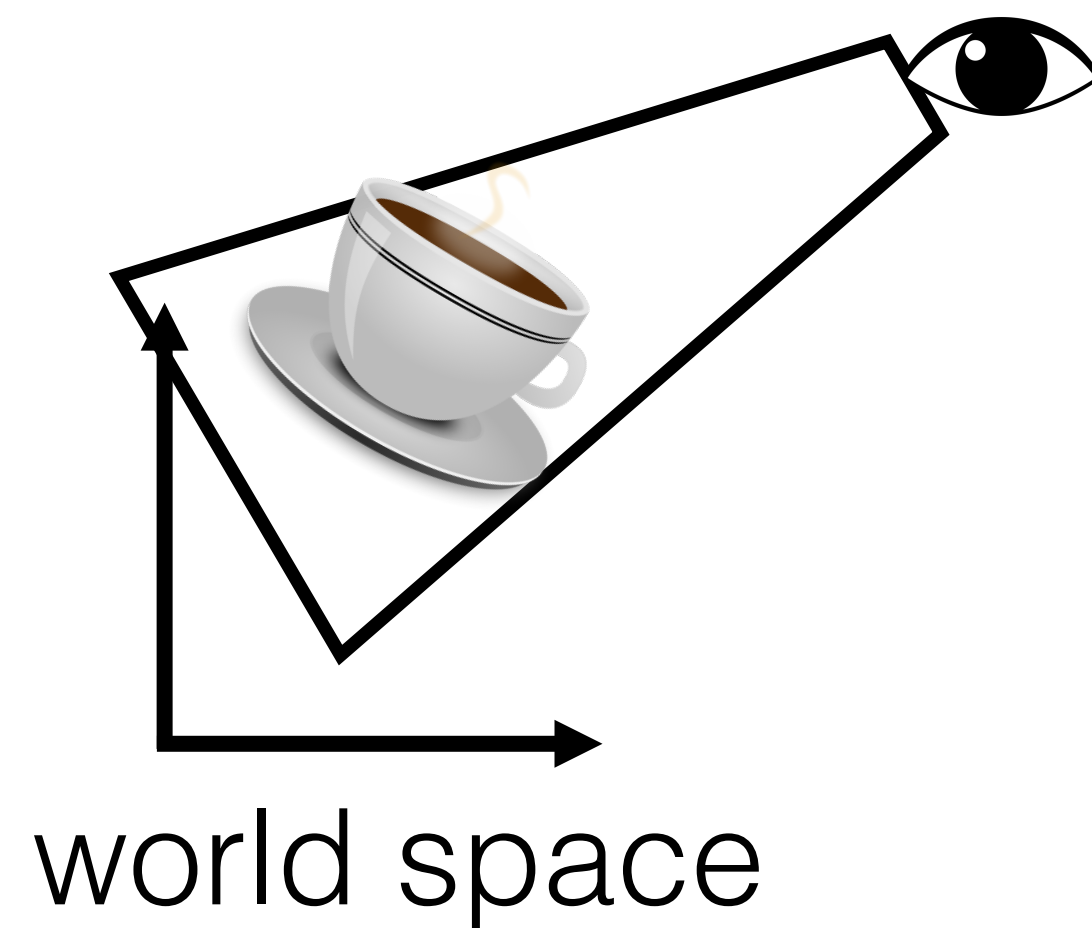
camera

projection

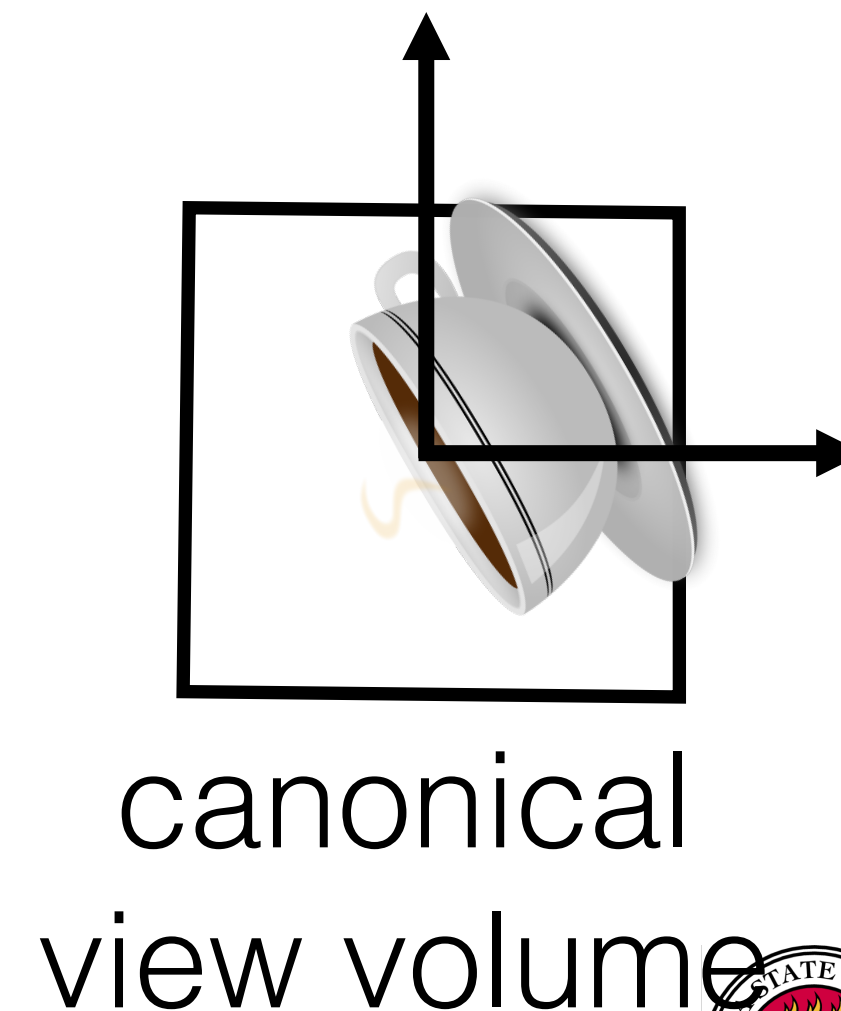
screen space



viewport



world space



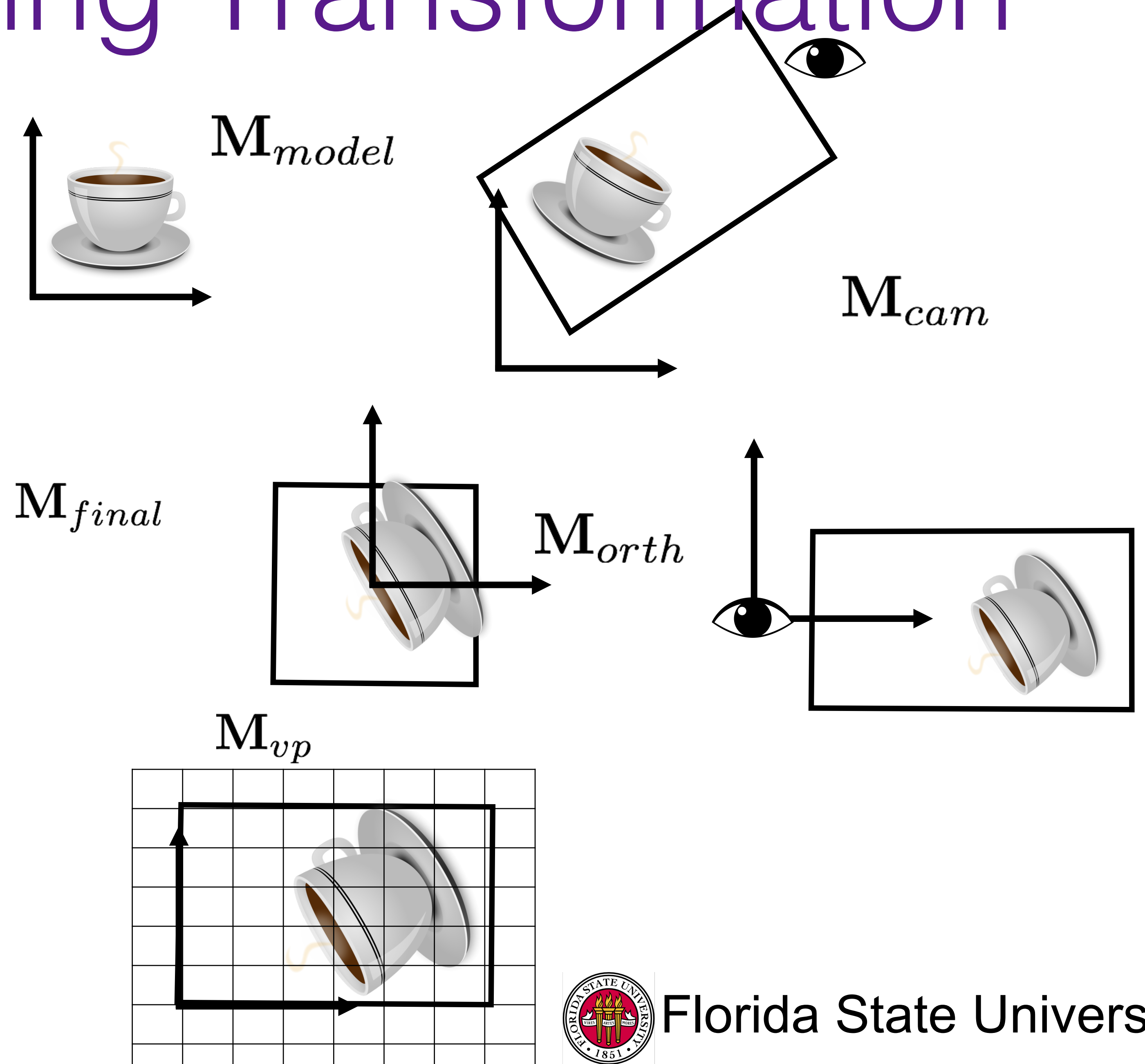
canonical
view volume

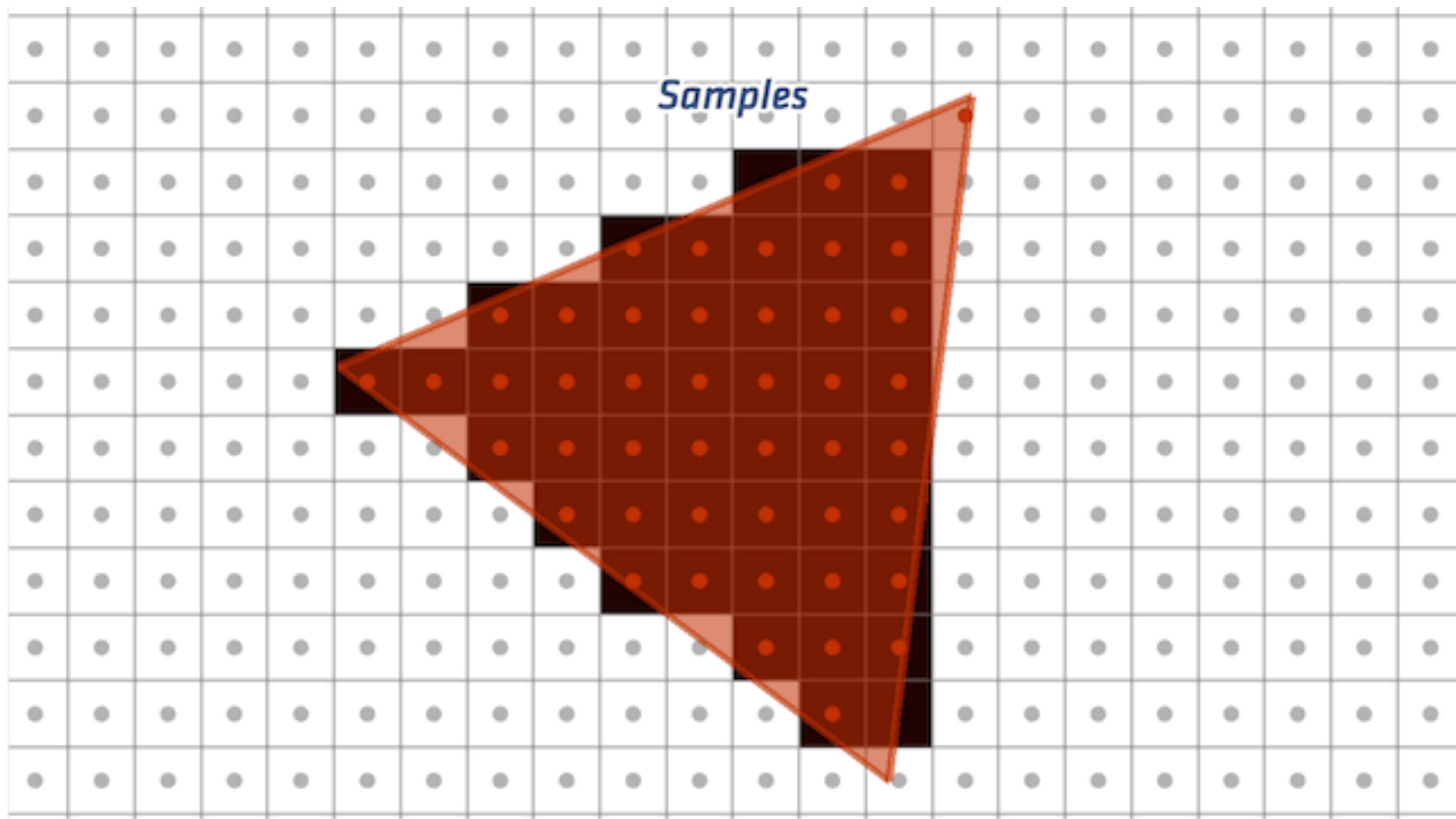


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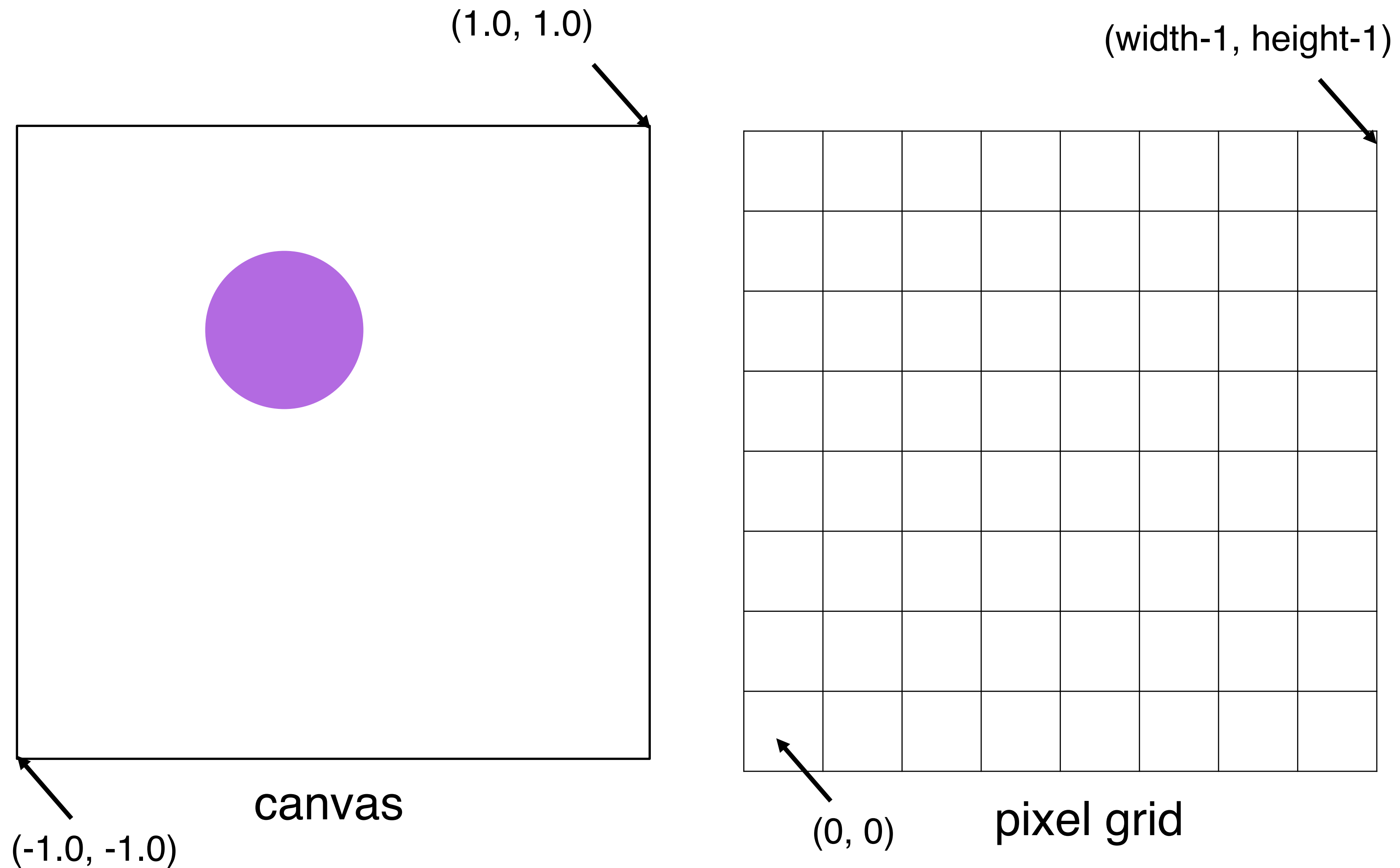
Recap: Viewing Transformation

- Construct Viewport Matrix \mathbf{M}_{vp}
- Construct Projection Matrix \mathbf{M}_{orth}
- Construct Camera Matrix \mathbf{M}_{cam}
- $\mathbf{M} = \mathbf{M}_{vp}\mathbf{M}_{orth}\mathbf{M}_{cam}$
- For each model
 - Construct Model Matrix \mathbf{M}_{model}
 - $\mathbf{M}_{final} = \mathbf{M}\mathbf{M}_{model}$
 - For every point \mathbf{p} in each primitive of the model
 - $\mathbf{p}_{final} = \mathbf{M}_{final}\mathbf{p}$
 - Rasterize the model

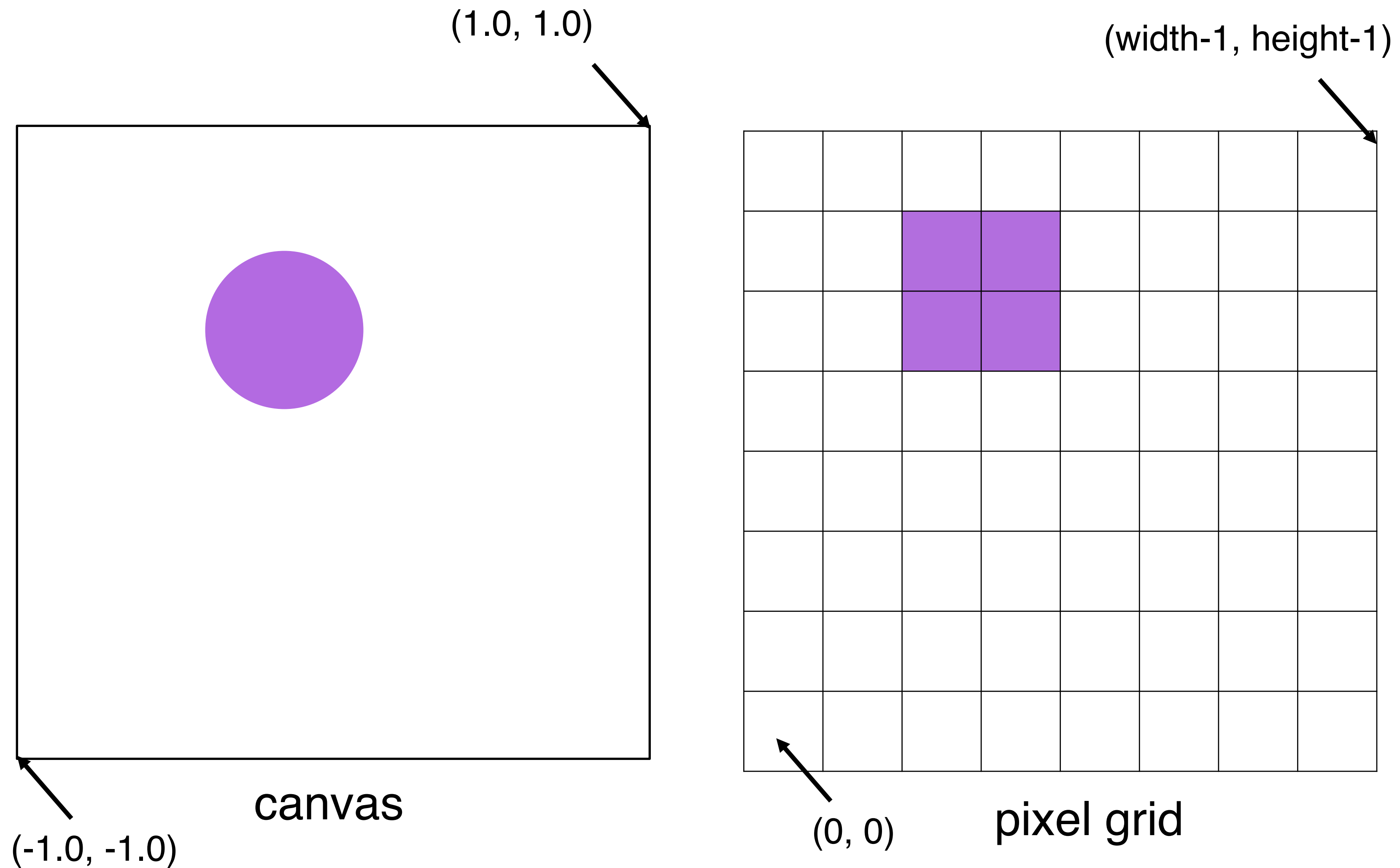




2D Canvas



2D Canvas



Implicit Geometry Representation

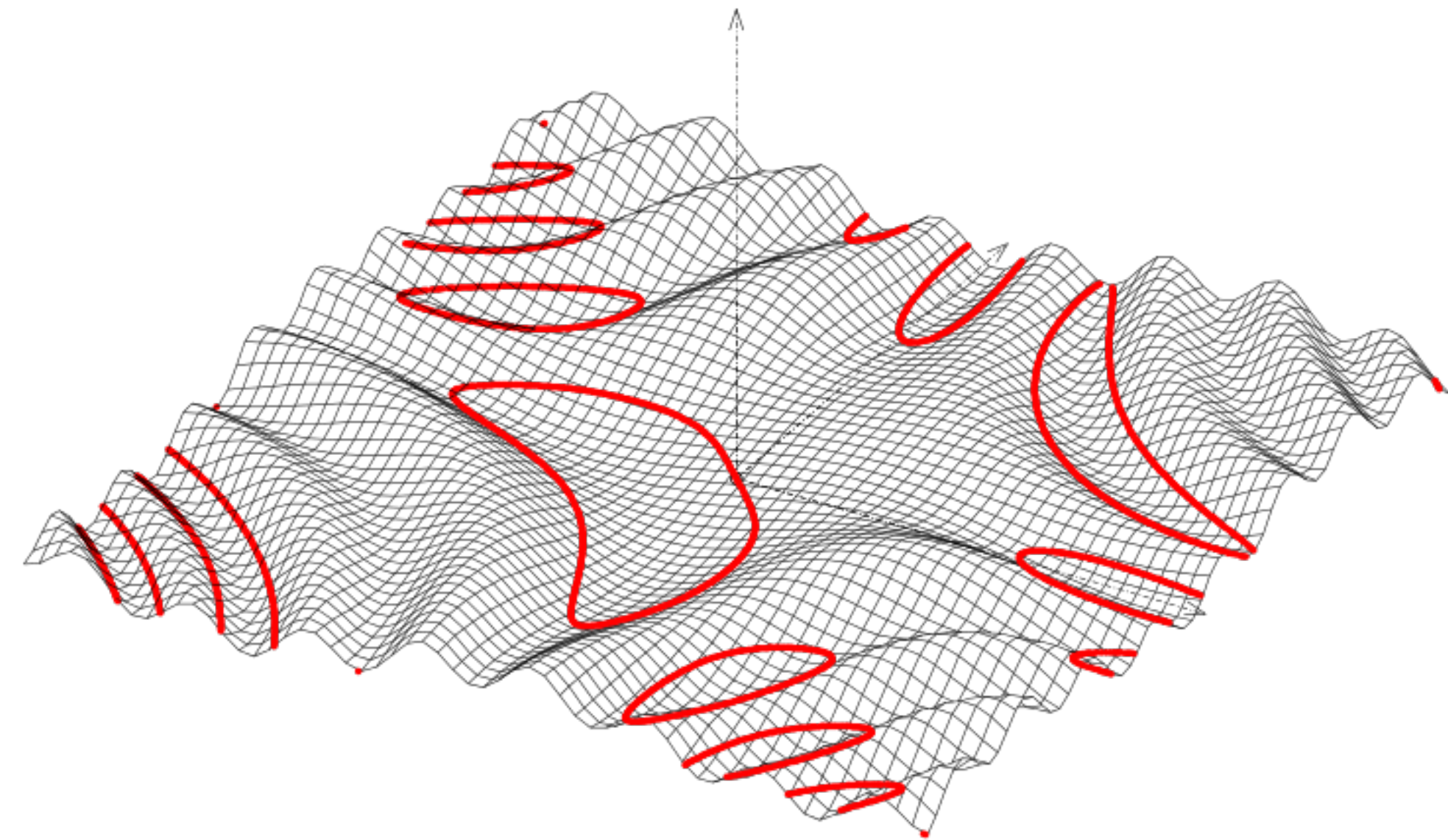
- Define a curve as zero set of 2D implicit function
 - $F(x,y) = 0 \rightarrow$ on curve
 - $F(x,y) < 0 \rightarrow$ inside curve
 - $F(x,y) > 0 \rightarrow$ outside curve
- Example: Circle with center (c_x, c_y) and radius r

$$F(x, y) = (x - c_x)^2 + (y - c_y)^2 - r^2$$



Implicit Geometry Representation

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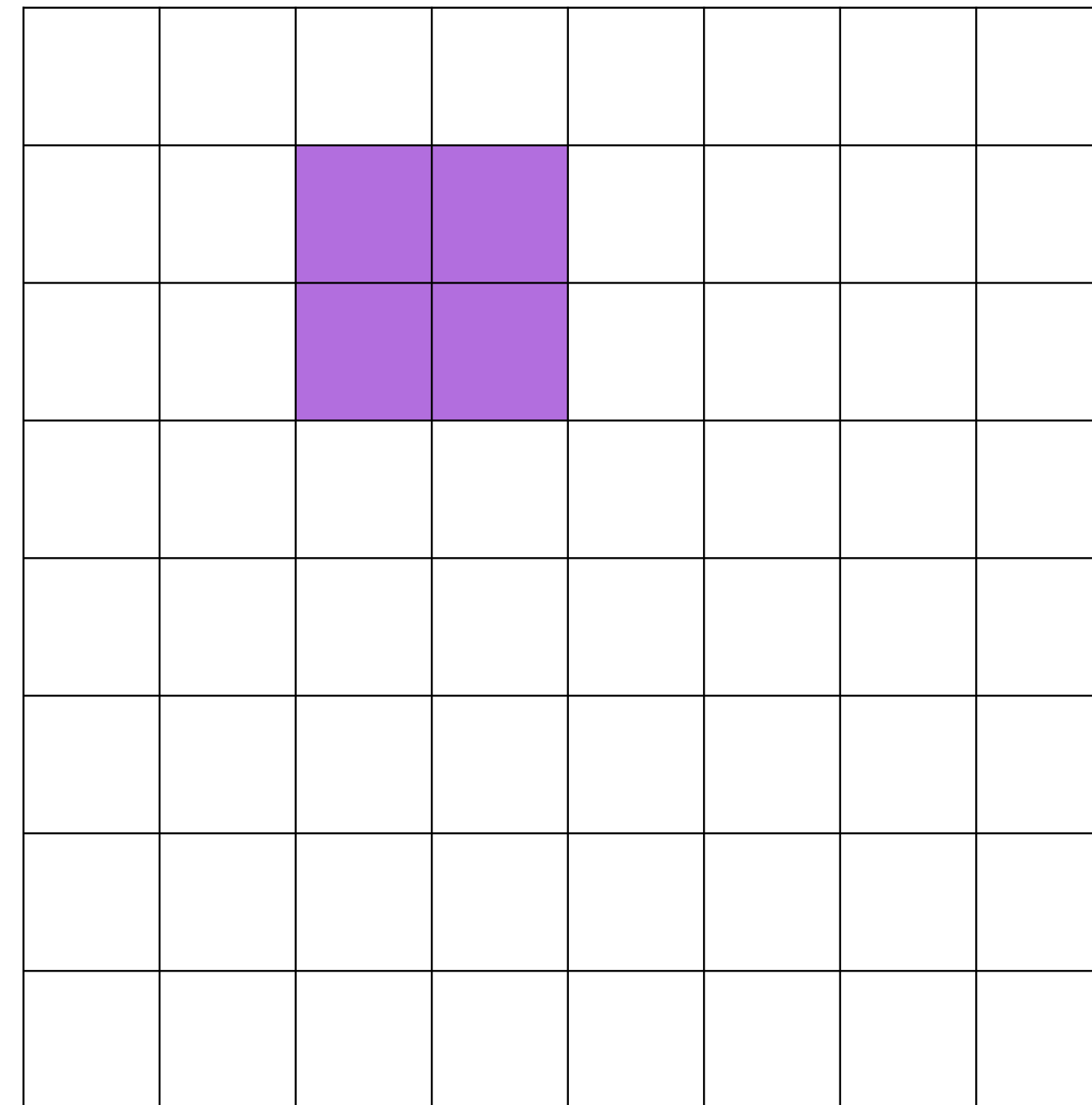


By Ag2gaeh - Own work, CC BY-SA 4.0, <https://commons.wikimedia.org/w/index.php?curid=45004240>



Implicit Rasterization

```
for all pixels (i,j)
    (x,y) = map_to_canvas (i,j)
    if  $F(x,y) < 0$ 
        set_pixel (i,j, color)
```



Implicit Geometry Representation

- Example: Triangle

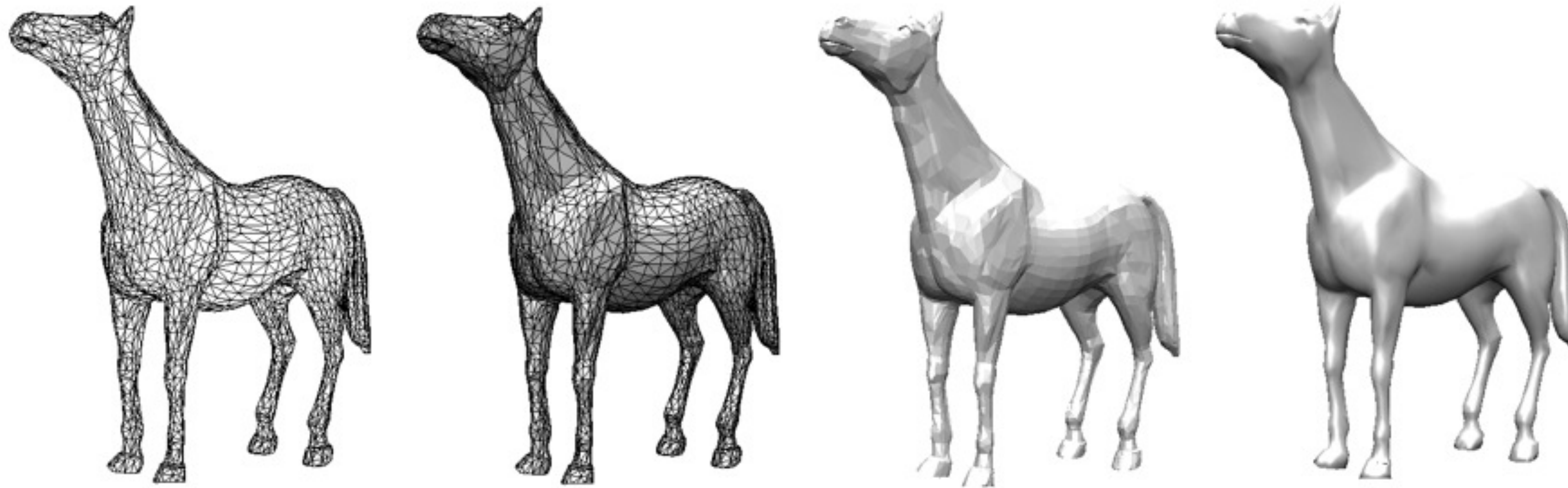


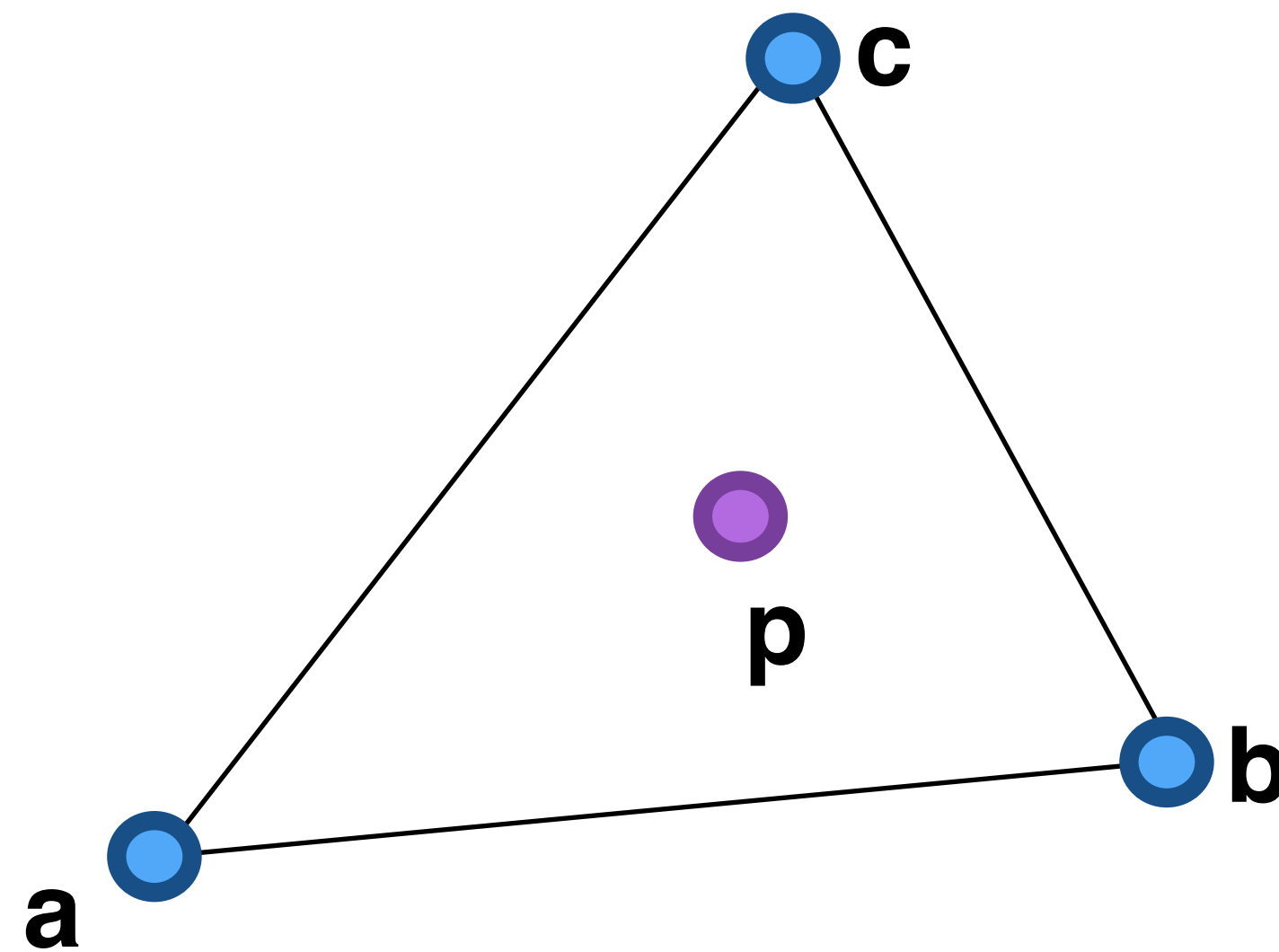
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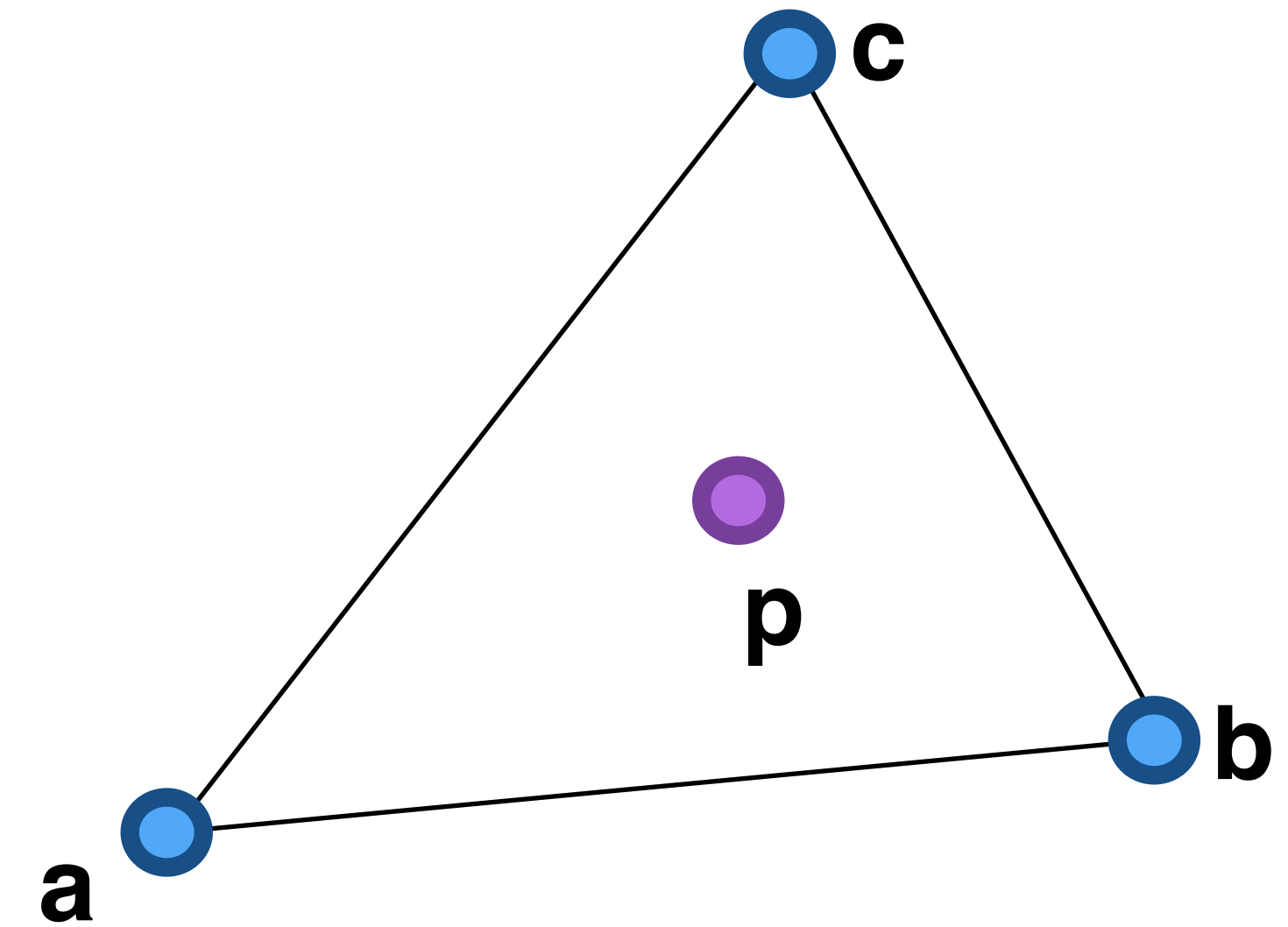
Barycentric Interpolation

- Barycentric coordinates:
 - $\mathbf{p} = \alpha\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c}$ with $\alpha + \beta + \gamma = 1$



Barycentric Interpolation

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 - $\mathbf{p} = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$ with $\alpha + \beta + \gamma = 1$
 - Unique for non-collinear $\mathbf{a}, \mathbf{b}, \mathbf{c}$



$$\begin{bmatrix} \mathbf{a}_x & \mathbf{b}_x & \mathbf{c}_x \\ \mathbf{a}_y & \mathbf{b}_y & \mathbf{c}_y \\ 1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} \mathbf{p}_x \\ \mathbf{p}_y \\ 1 \end{bmatrix}$$



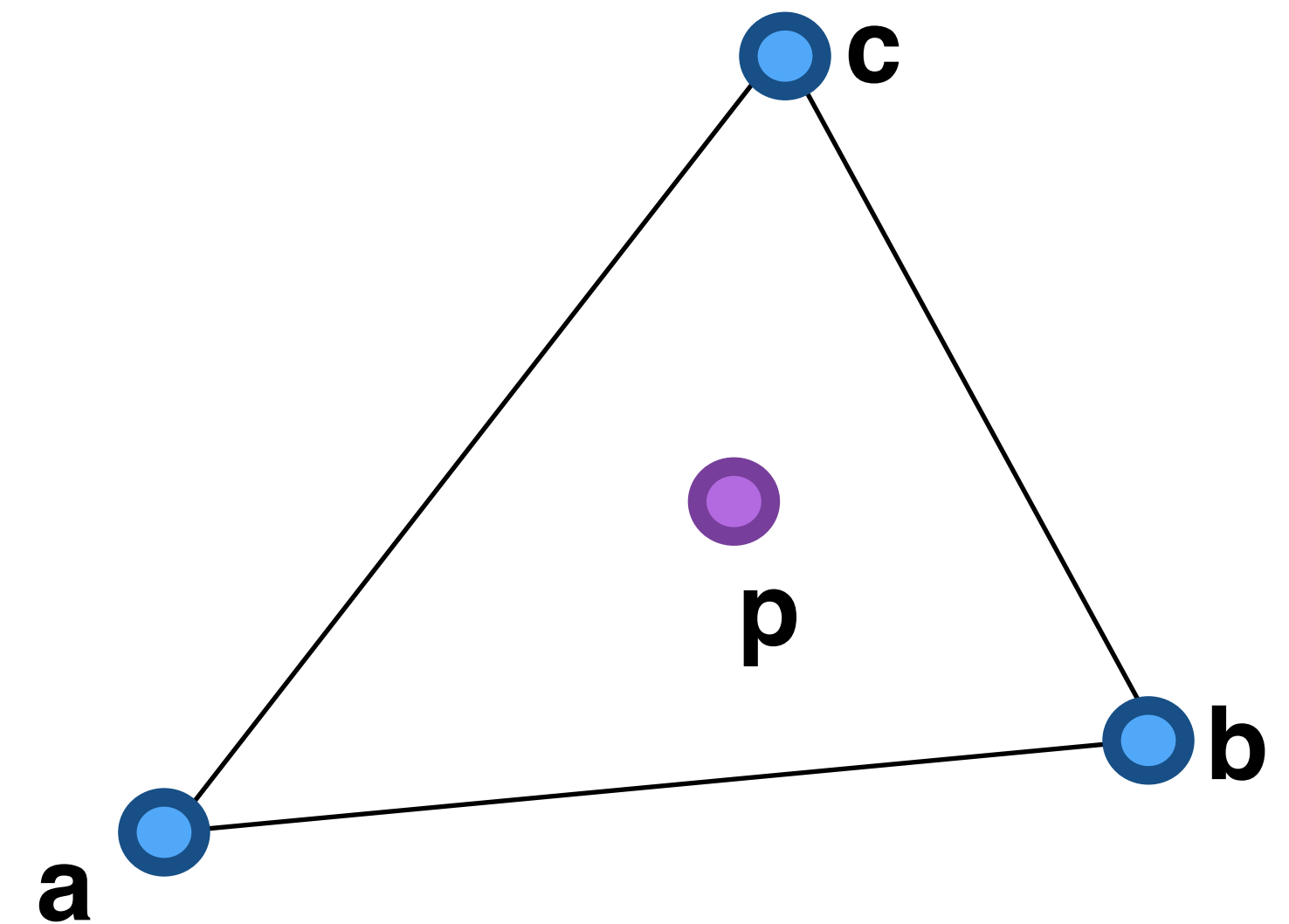
Barycentric Interpolation

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 - Unique for non-collinear $\mathbf{a}, \mathbf{b}, \mathbf{c}$
 - Ratio of triangle areas

$$\alpha(\mathbf{p}) = \frac{\text{area}(\mathbf{p}, \mathbf{b}, \mathbf{c})}{\text{area}(\mathbf{a}, \mathbf{b}, \mathbf{c})}$$

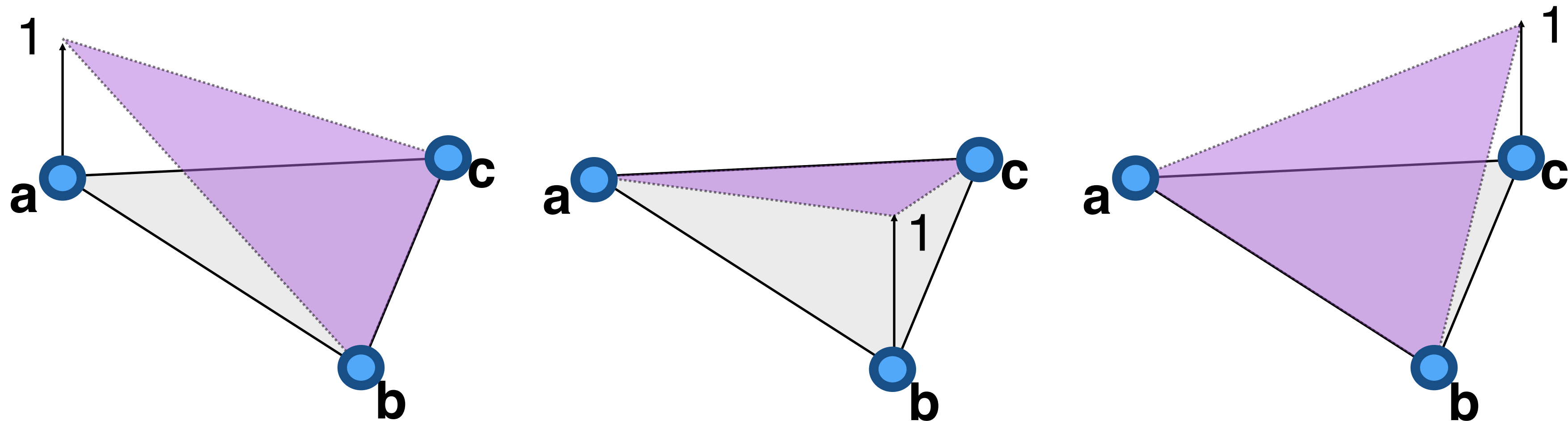
$$\beta(\mathbf{p}) = \frac{\text{area}(\mathbf{p}, \mathbf{c}, \mathbf{a})}{\text{area}(\mathbf{a}, \mathbf{b}, \mathbf{c})}$$

$$\gamma(\mathbf{p}) = \frac{\text{area}(\mathbf{p}, \mathbf{a}, \mathbf{b})}{\text{area}(\mathbf{a}, \mathbf{b}, \mathbf{c})}$$



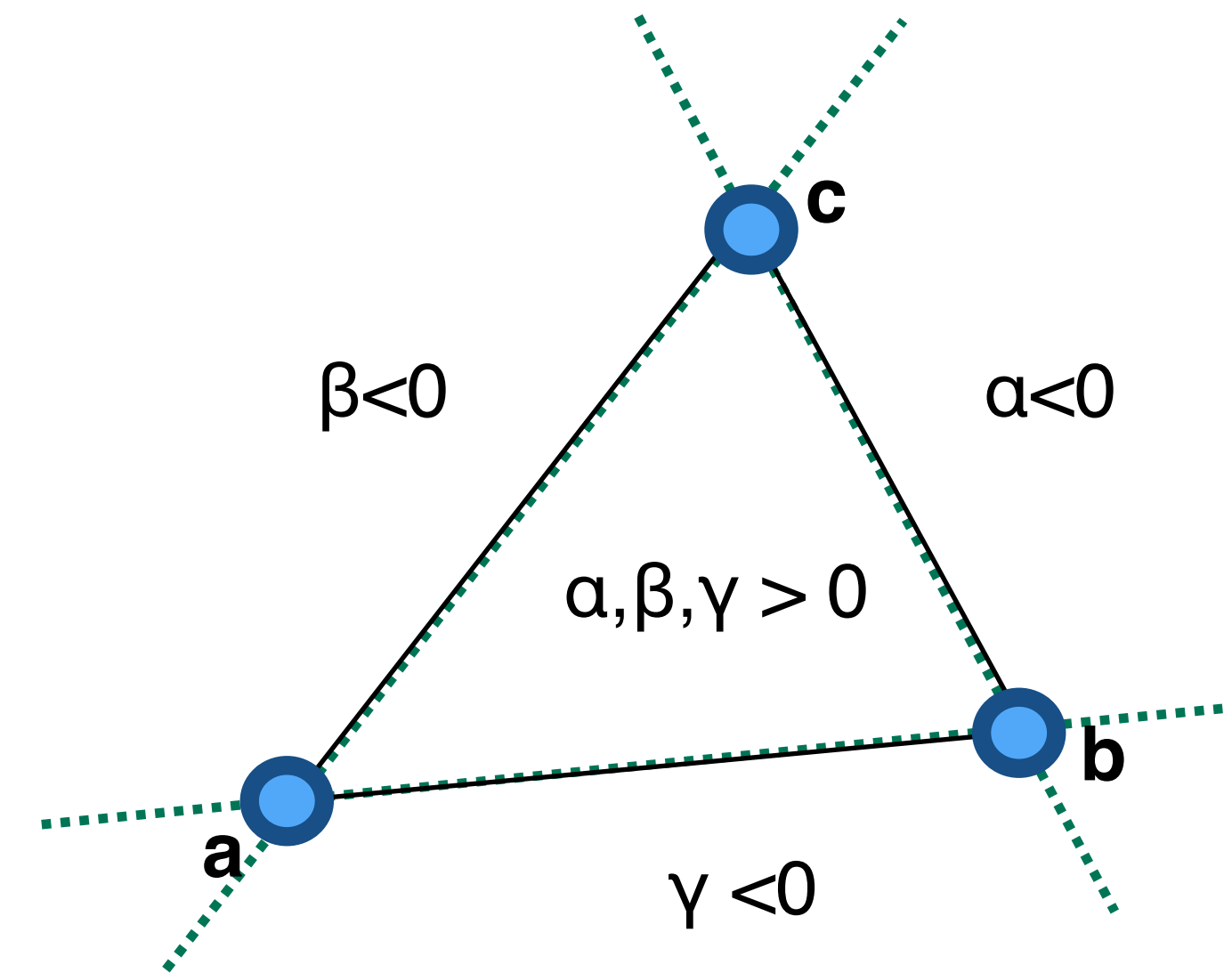
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 - $\alpha(\mathbf{p})$, $\beta(\mathbf{p})$, $\gamma(\mathbf{p})$ are linear functions



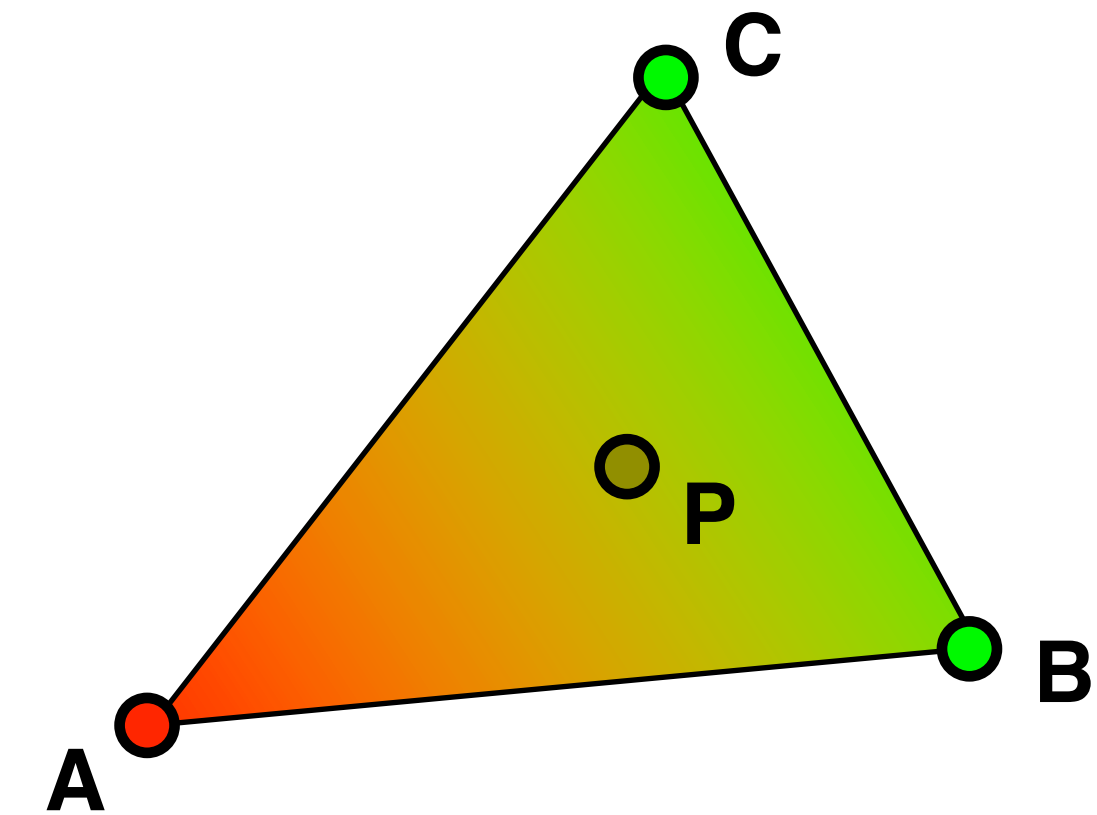
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 - Gives inside/outside information



Barycentric Interpolation

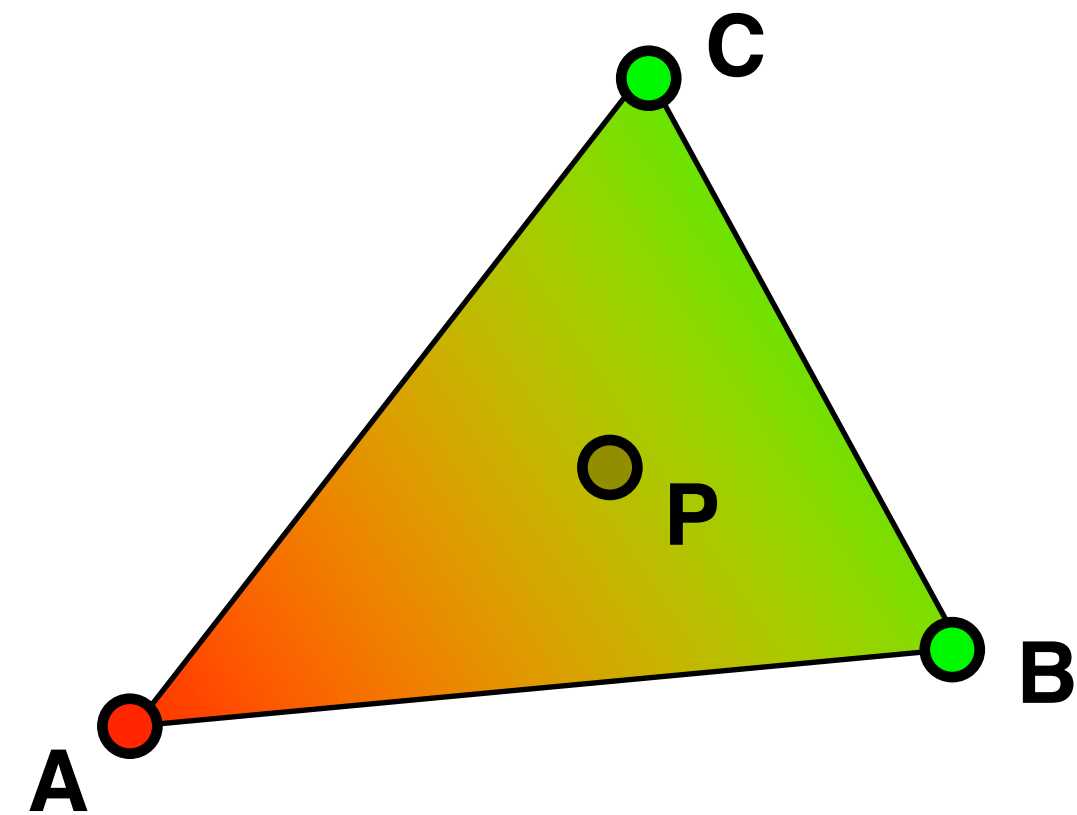
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 - Ratio of triangle areas
 - $\alpha(\mathbf{p})$, $\beta(\mathbf{p})$, $\gamma(\mathbf{p})$ are linear functions
 - Gives inside/outside information
 - Use barycentric coordinates to interpolate vertex normals (or other data, e.g. colors)



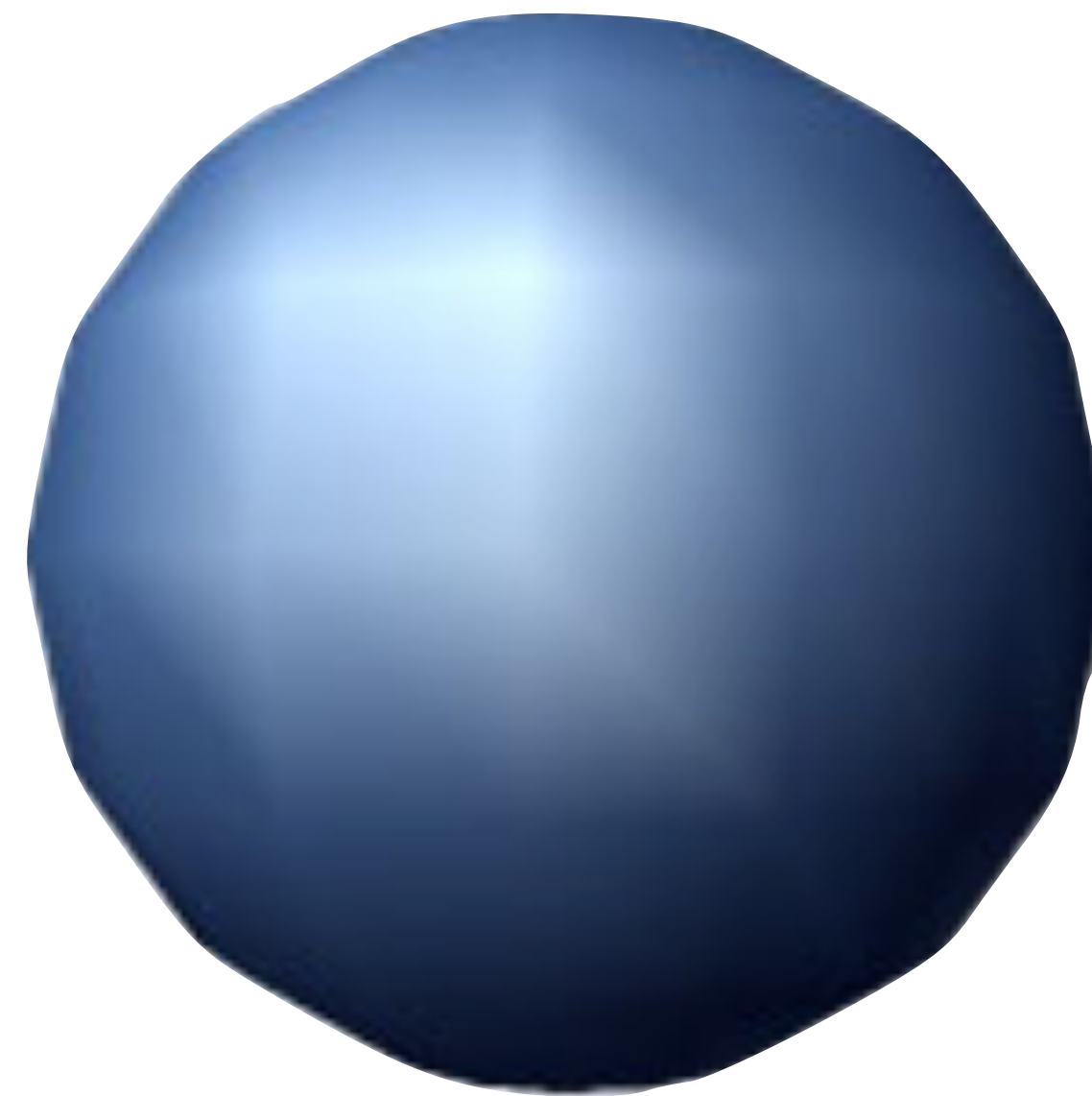
$$\mathbf{n}(\mathbf{P}) = \alpha \cdot \mathbf{n}(\mathbf{A}) + \beta \cdot \mathbf{n}(\mathbf{B}) + \gamma \cdot \mathbf{n}(\mathbf{C})$$



Color Interpolation

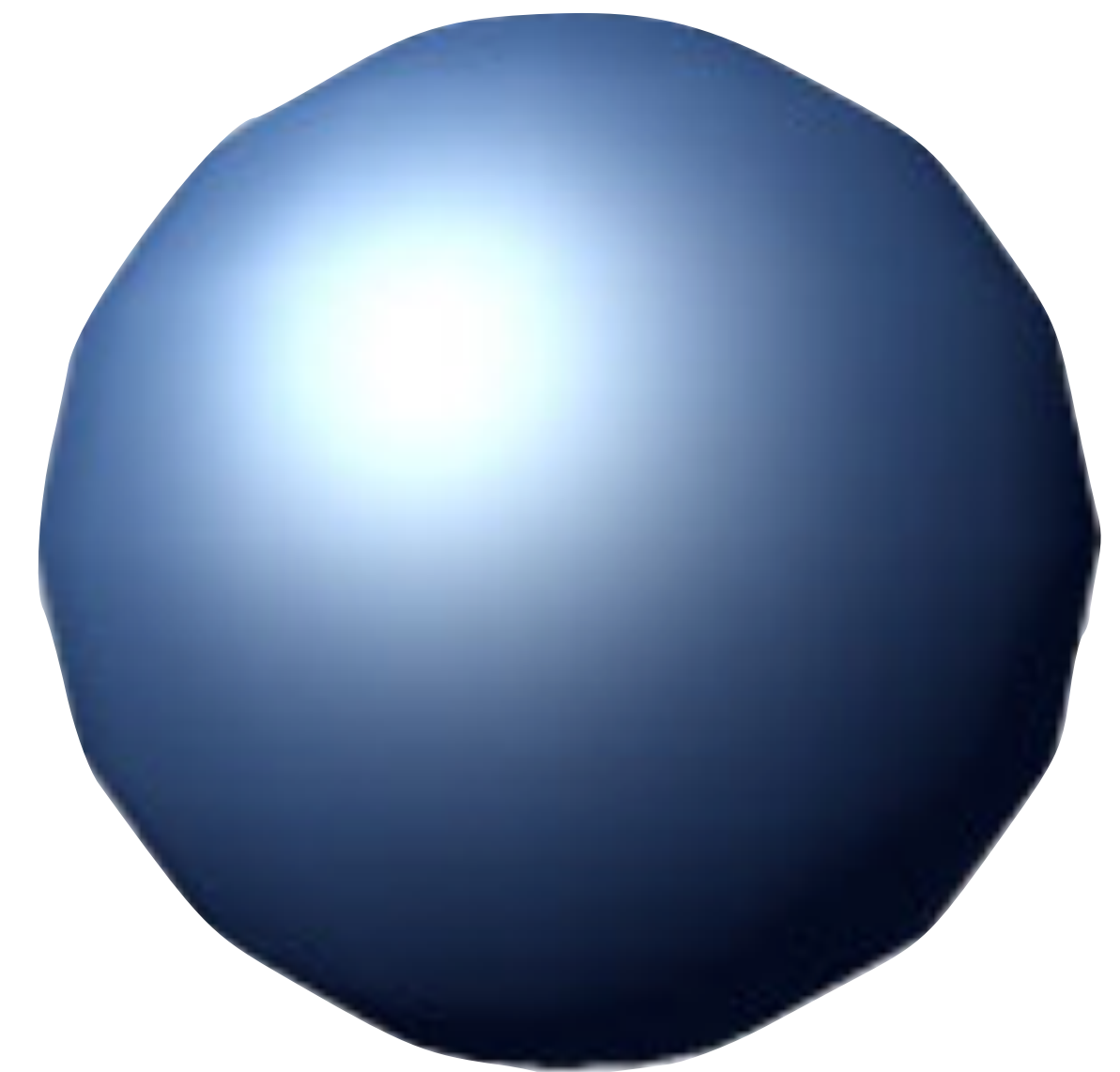


Per-vertex



Evaluate color on vertices,
then interpolates it

Per-pixel



Interpolates positions and normals,
then evaluate color on each pixel

<http://www.cgchannel.com/2010/11/cg-science-for-artists-part-2-the-real-time-rendering-pipeline/>

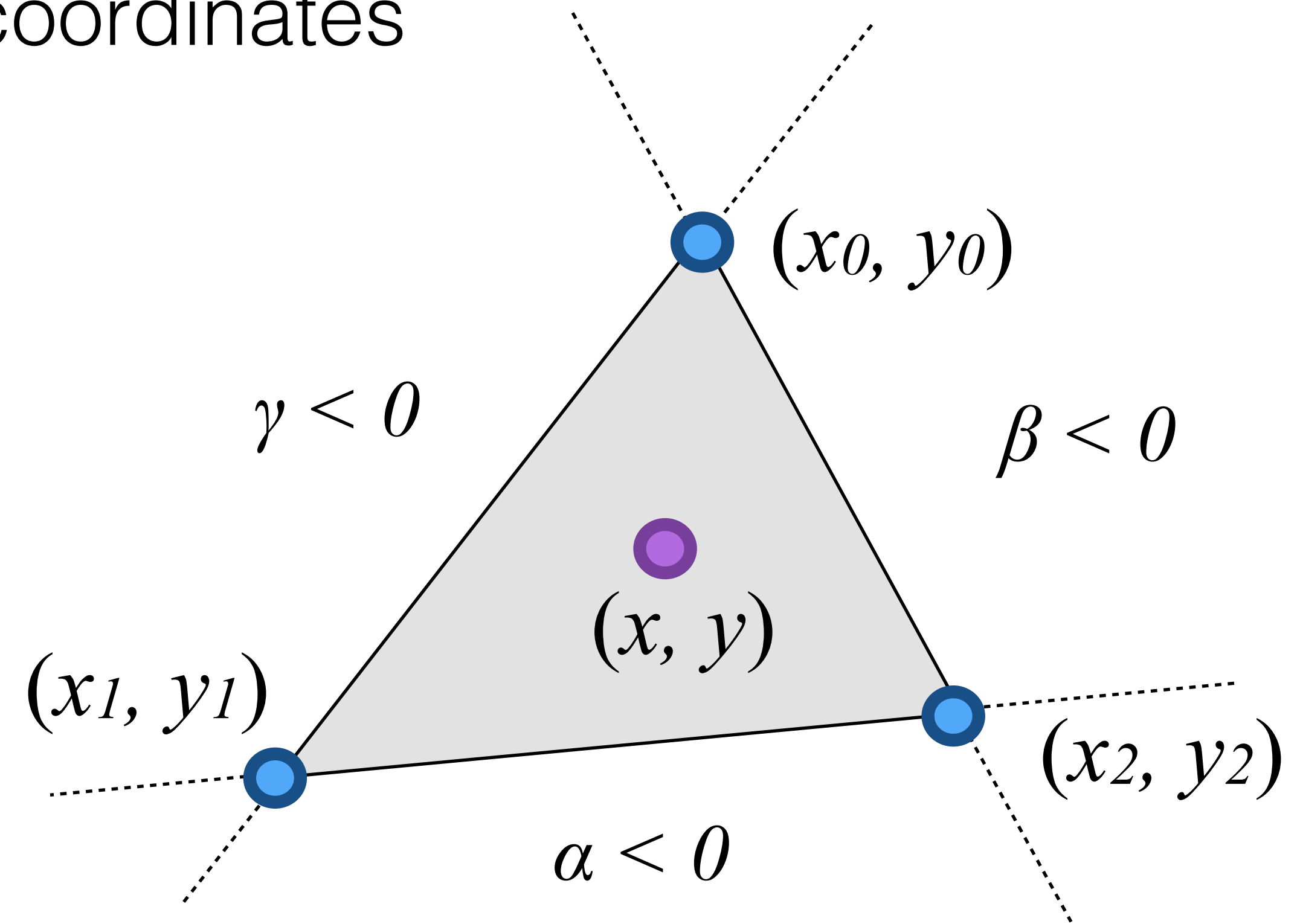
Triangle Rasterization

- Each triangle is represented as three 2D points (x_0, y_0) , (x_1, y_1) , (x_2, y_2)
- Rasterization using barycentric coordinates

$$x = \alpha \cdot x_0 + \beta \cdot x_1 + \gamma \cdot x_2$$

$$y = \alpha \cdot y_0 + \beta \cdot y_1 + \gamma \cdot y_2$$

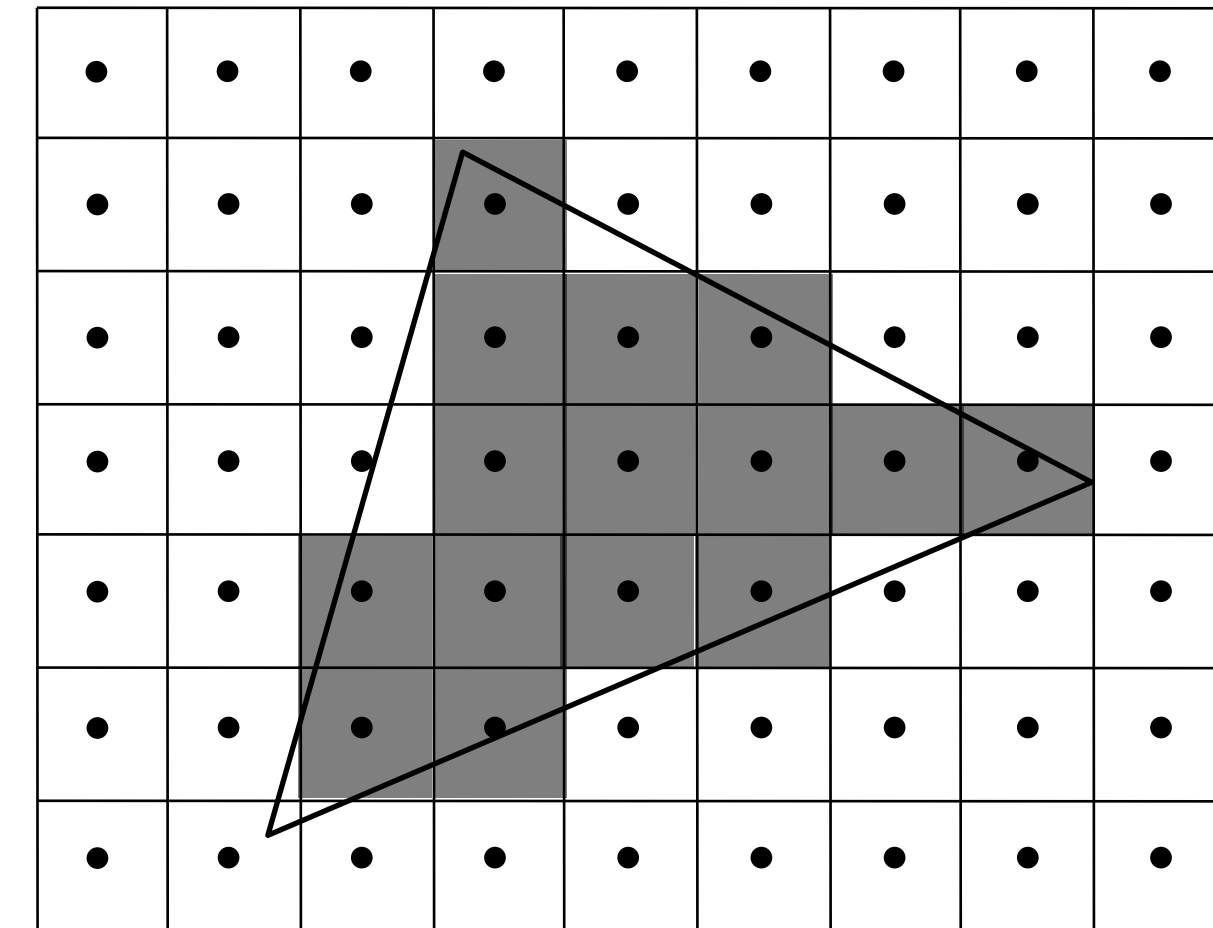
$$\alpha + \beta + \gamma = 1$$



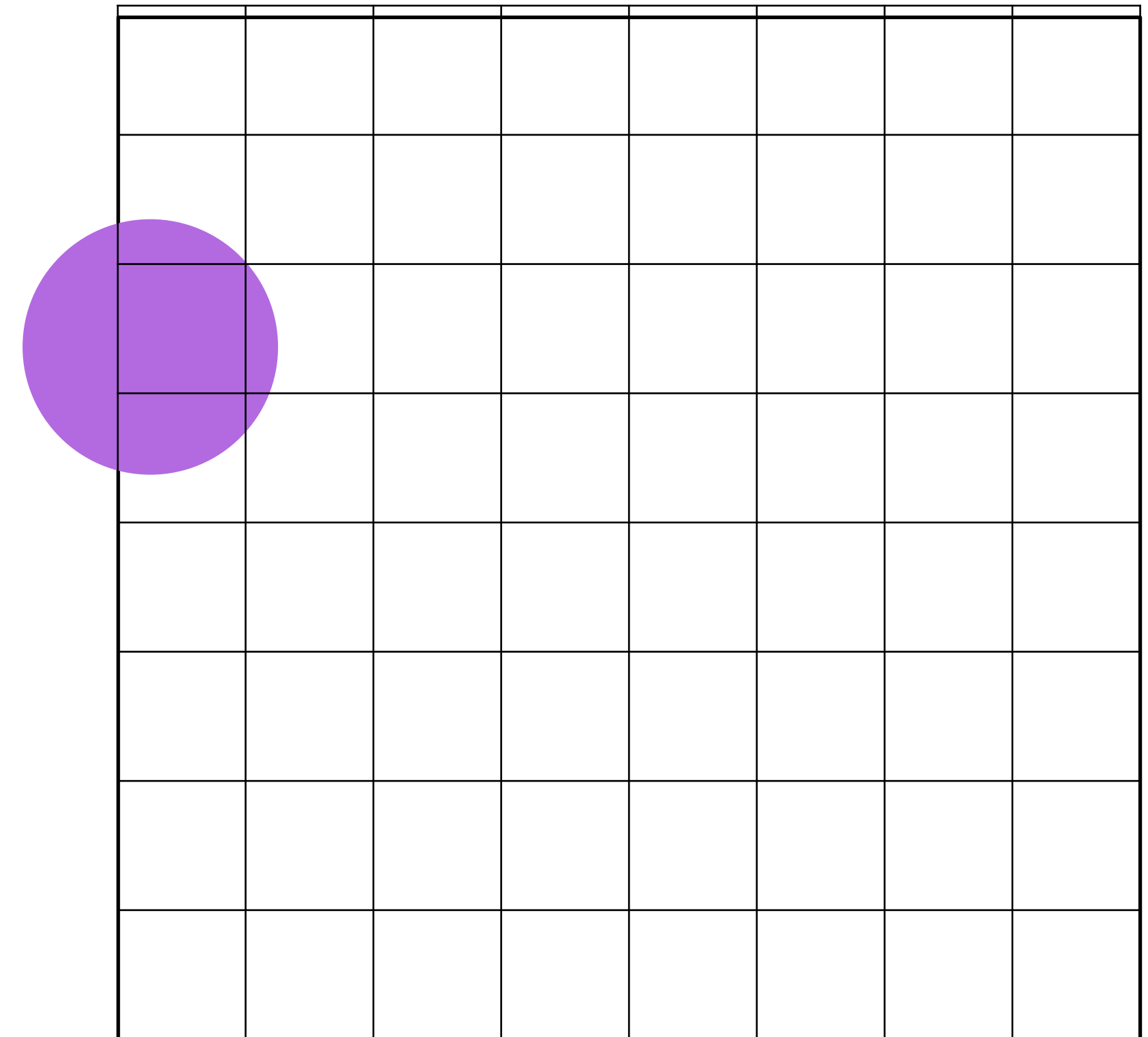
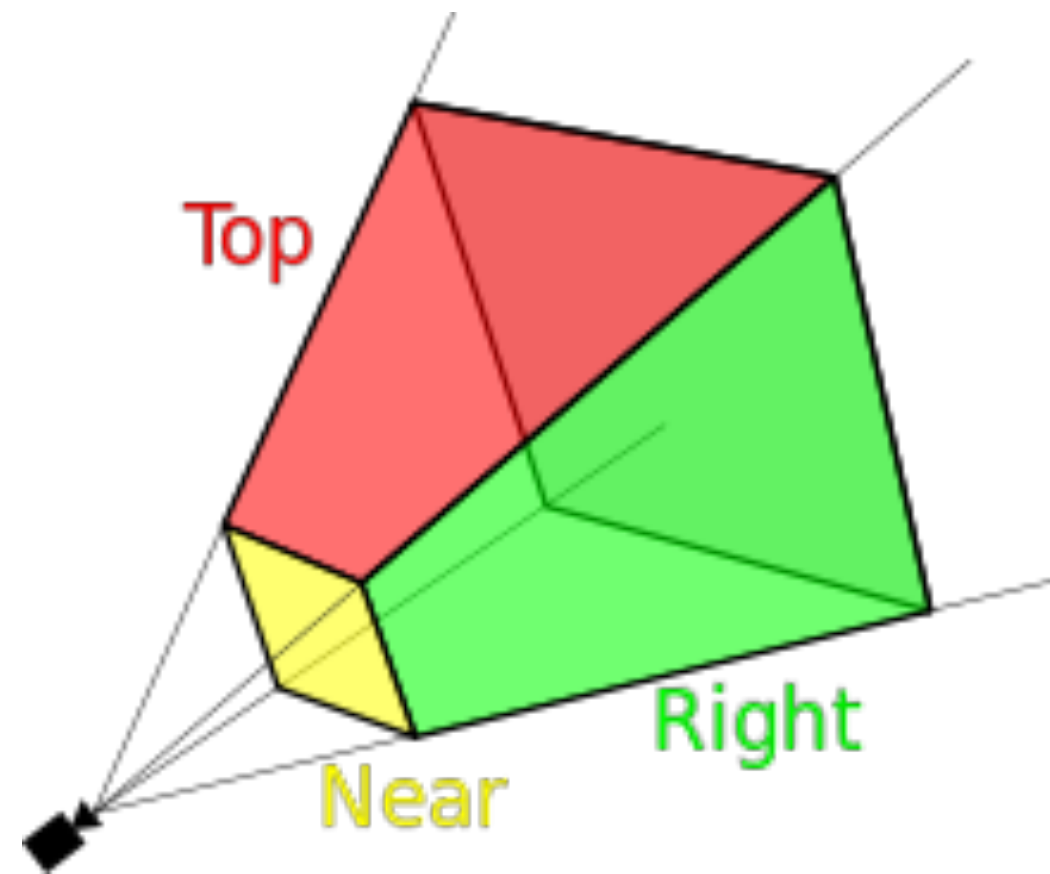
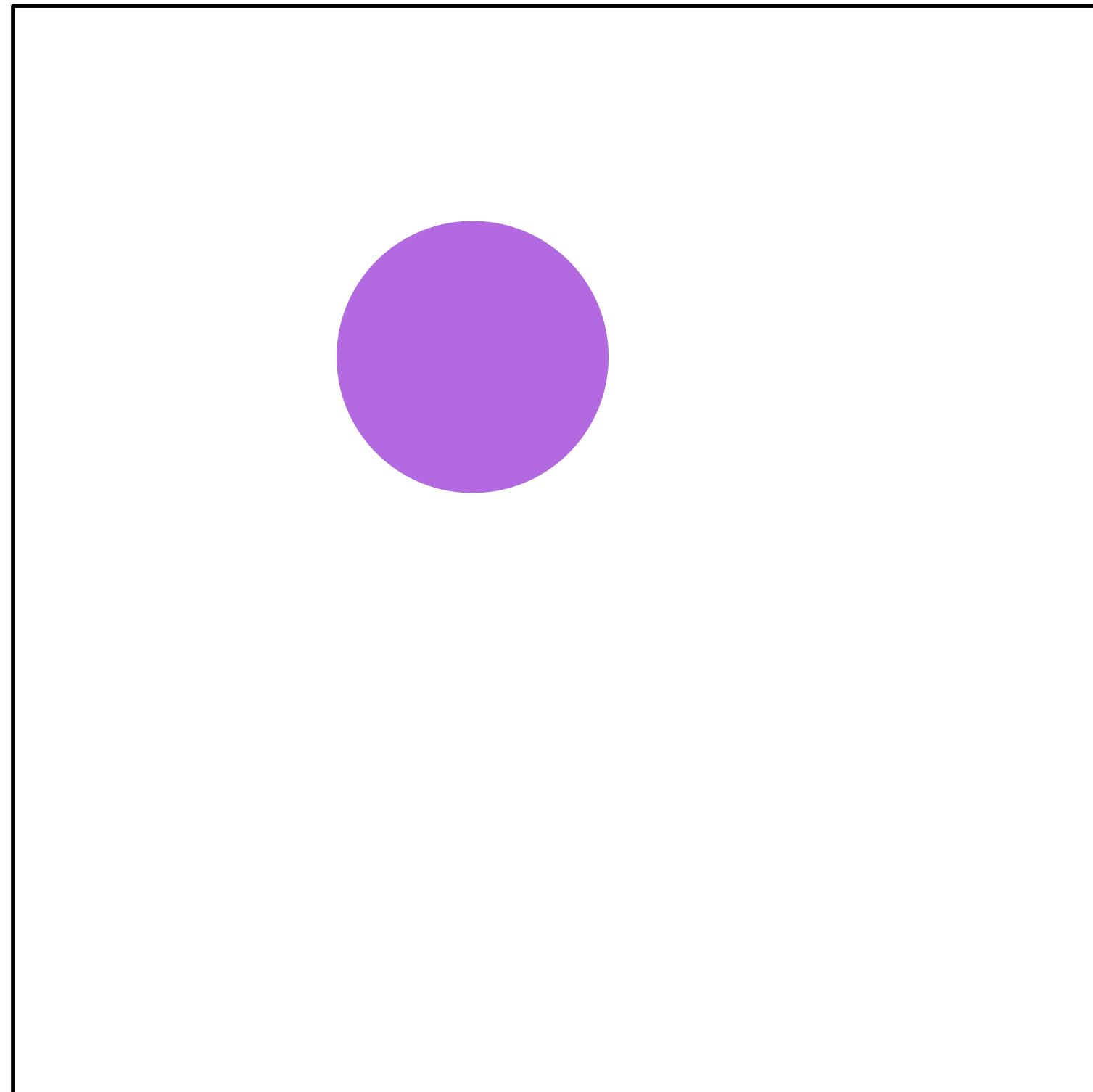
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```
for all  $y$  do  
  for all  $x$  do  
    compute  $(\alpha, \beta, \gamma)$  for  $(x, y)$   
    if  $(\alpha \in [0, 1] \text{ and } \beta \in [0, 1] \text{ and } \gamma \in [0, 1])$   
      set_pixel  $(x, y)$ 
```



Clipping

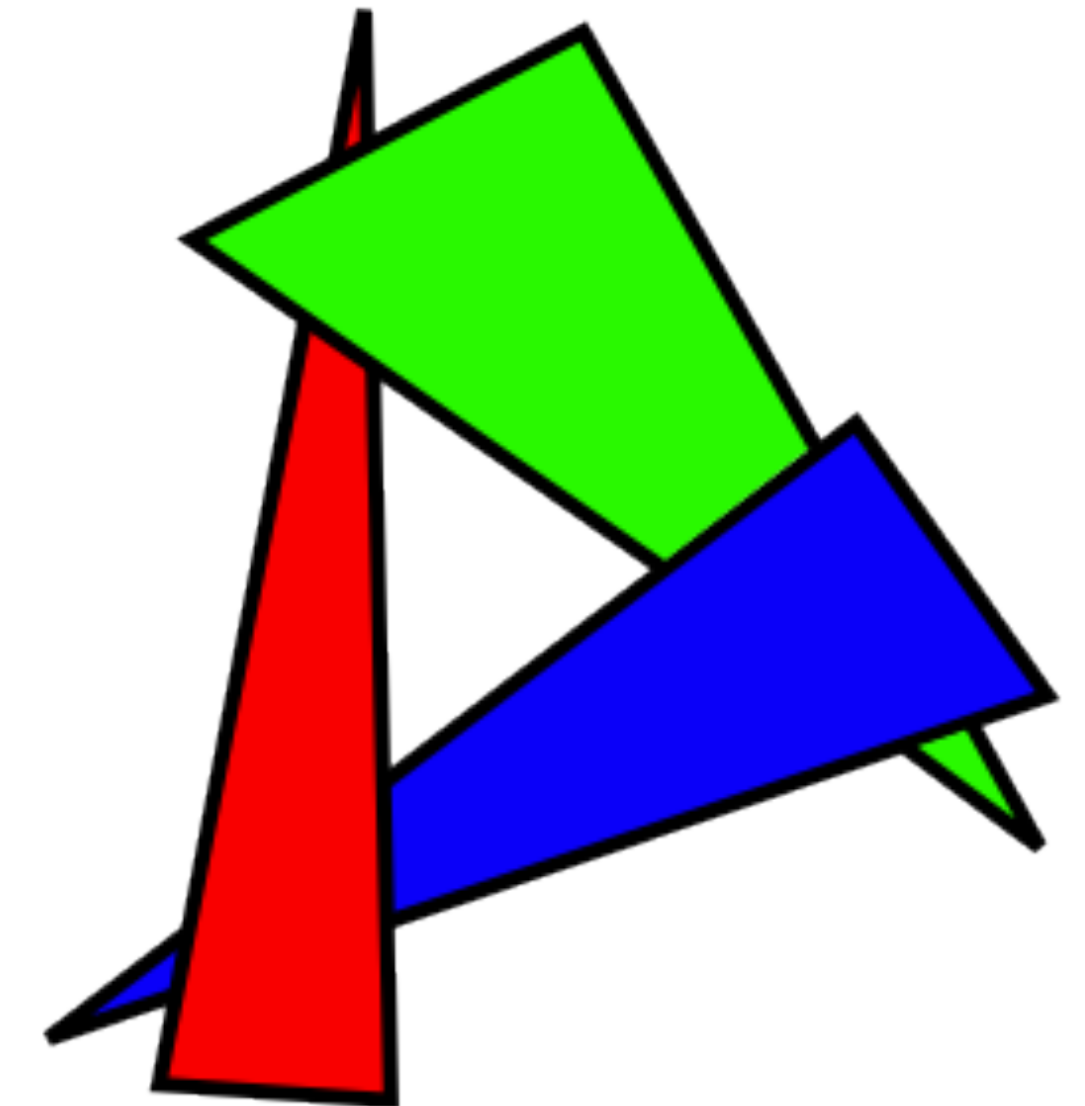
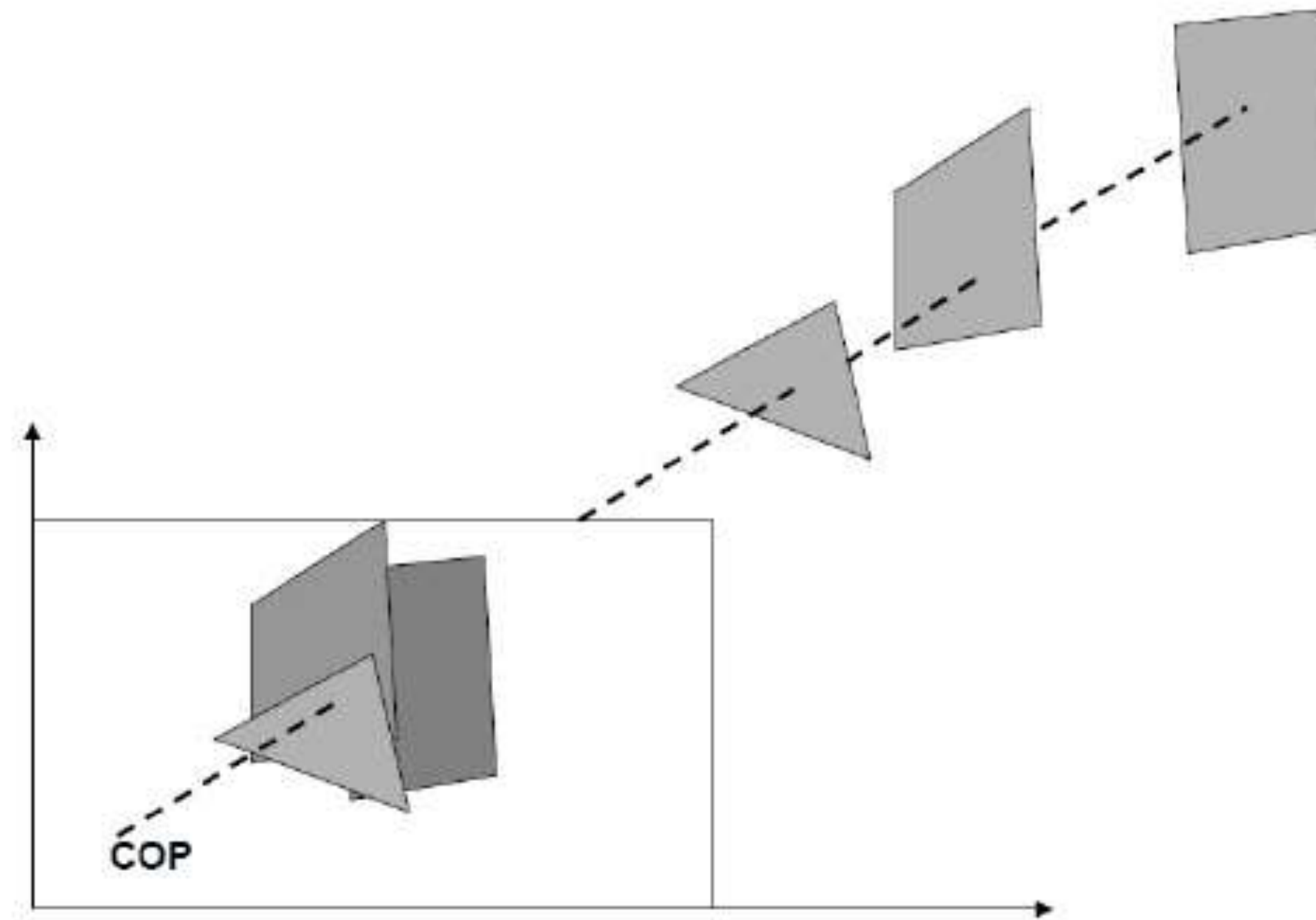


- Ok if you do it brute force
- Care is required if you are explicitly tracing the boundaries

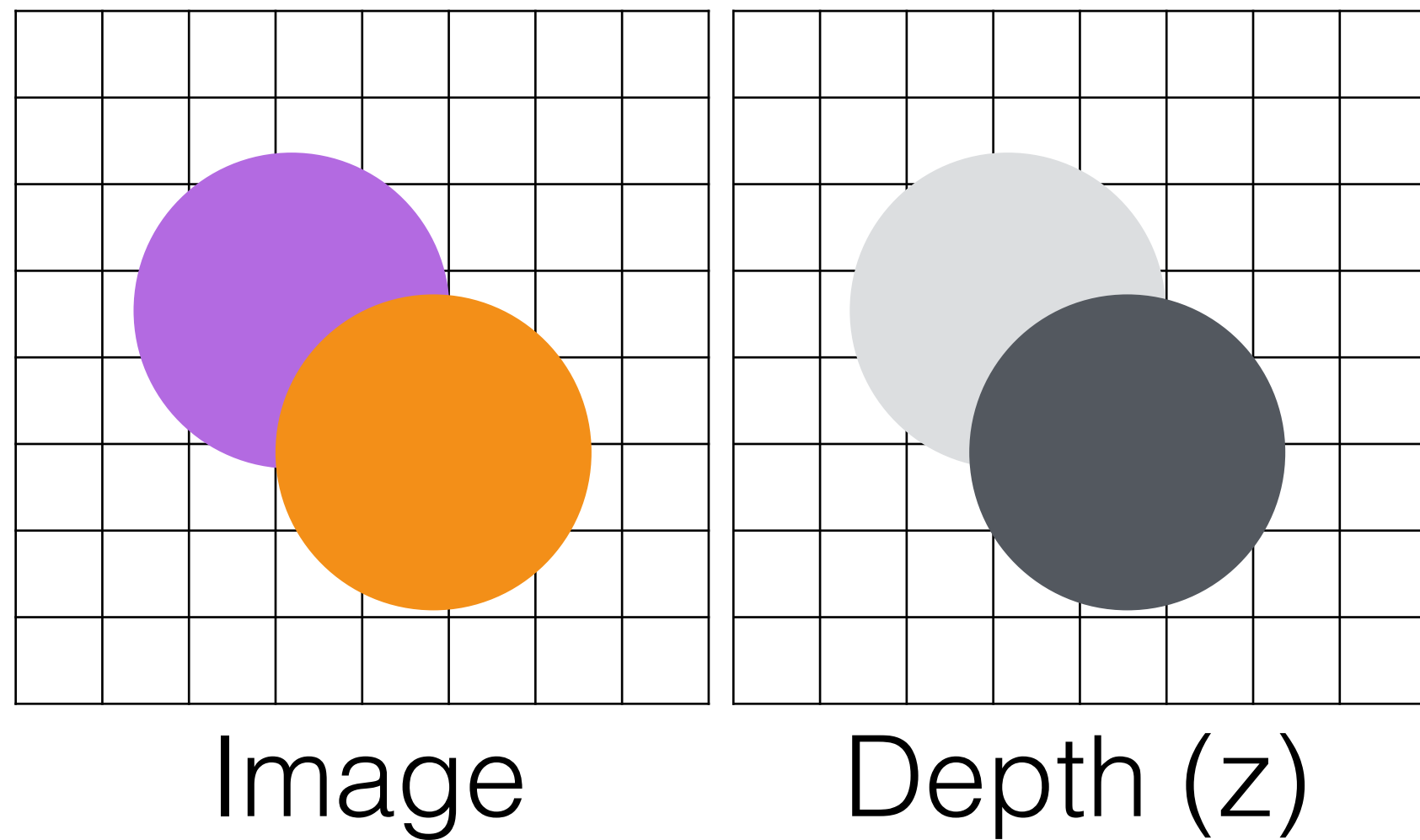


Objects Depth Sorting

- To handle occlusion, you can sort all the objects in a scene by depth
- This is not always possible!



z-buffering

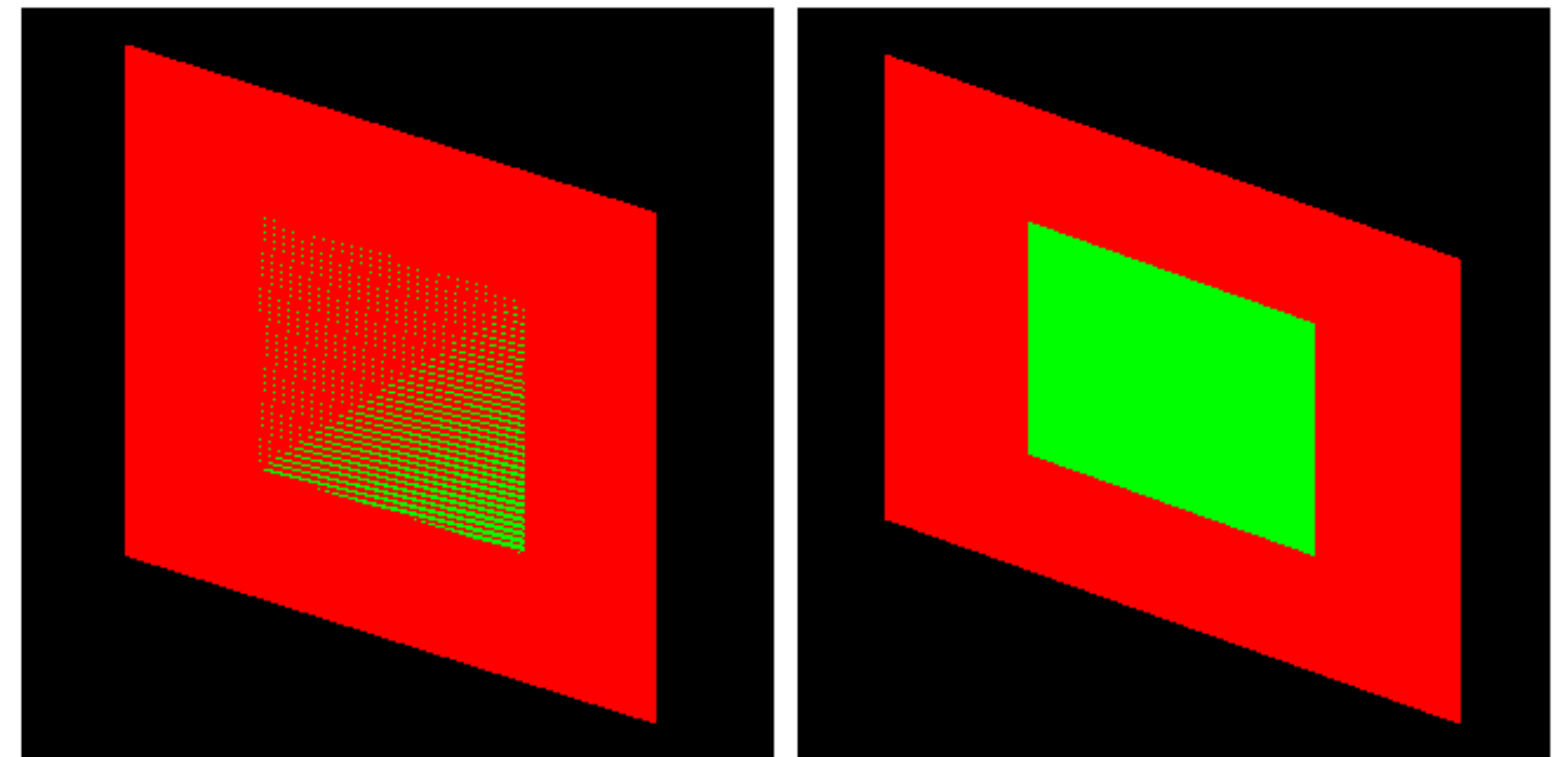
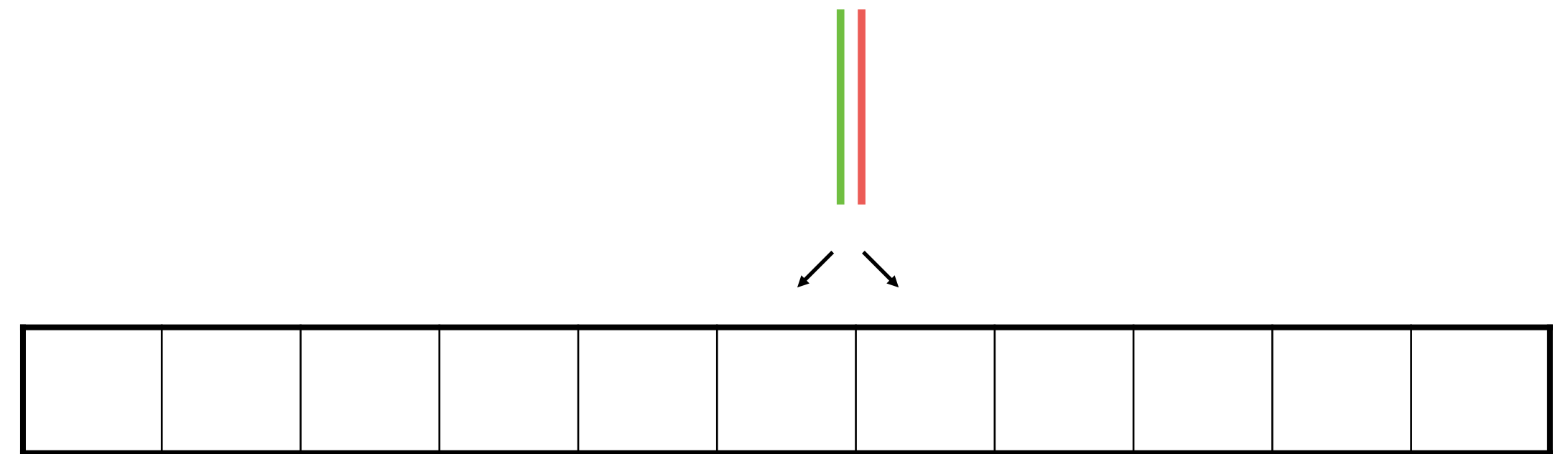


- You render the image both in the Image and in the depth buffer, where you store only the depth
- When a new fragment comes in, you draw it in the image only if it is closer
- This always work and it is cheap to evaluate! It is the default in all graphics hardware
- You still have to sort for transparency...



z-buffer quantization and “z-fighting”

- The z-buffer is quantized (the number of bits is heavily dependent on the hardware platform)
- Two close object might be quantized differently, leading to strange artifacts, usually called “z-fighting”



Super Sampling Anti-Aliasing



Non-antialiased type



Antialiased type



Enlarged portion of type

- Render $n \times n$ pixels instead of one
- Assign the average to the pixel

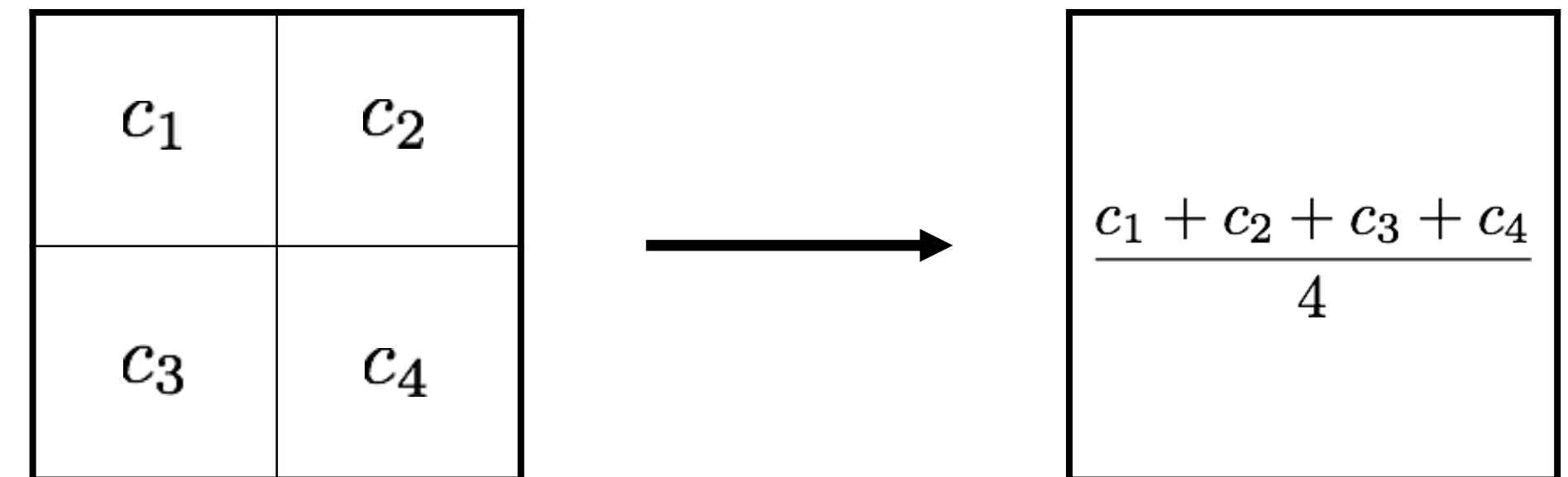
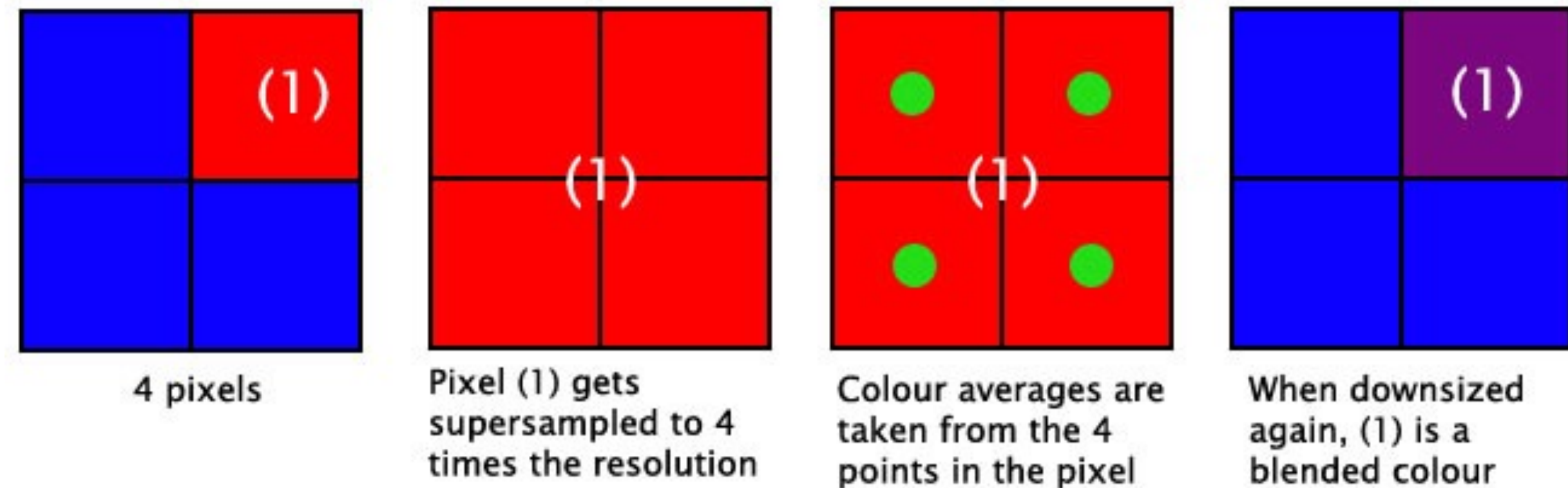


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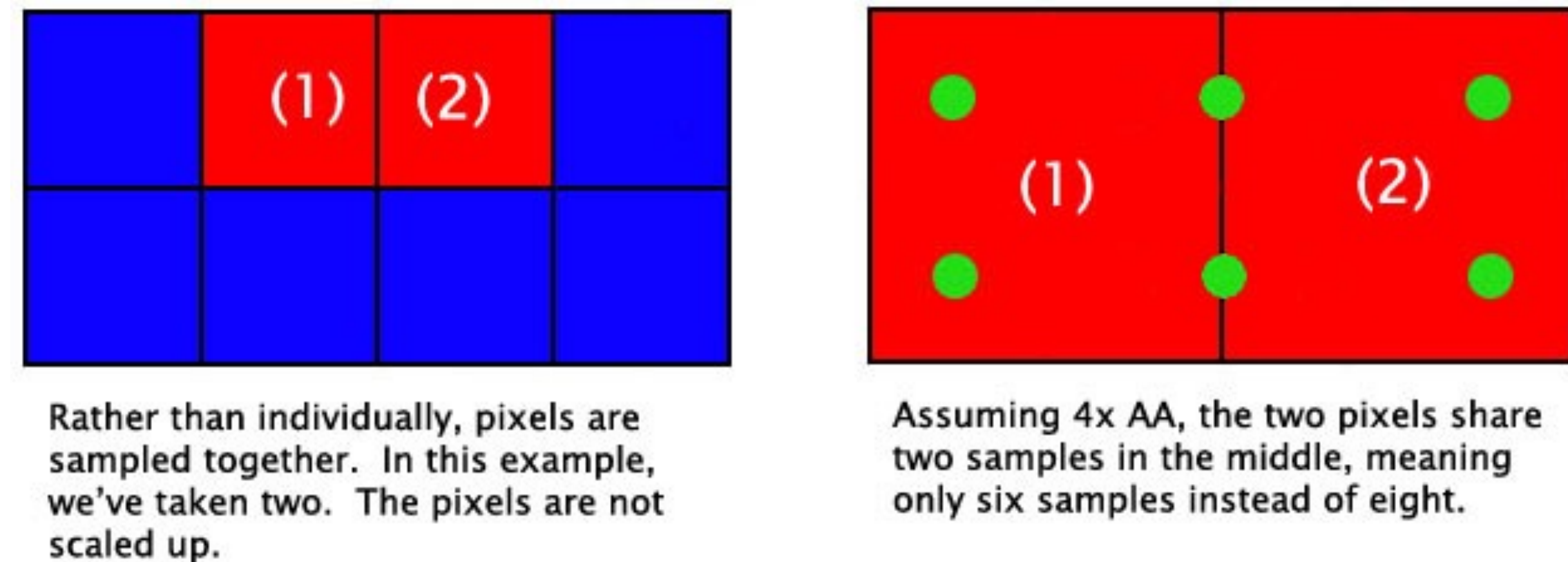


Many different names and variants

- SSAA (FSAA)
- MSAA
- CSAA
- EQAA
- FXAA
- TX AA



MSAA



Copyright: [tested.com](http://www.tested.com/tech/pcs/1194-how-to-choose-the-right-anti-aliasing-mode-for-your-gpu/#) (<http://www.tested.com/tech/pcs/1194-how-to-choose-the-right-anti-aliasing-mode-for-your-gpu/#>)



References

Fundamentals of Computer Graphics, Fourth Edition
4th Edition by [Steve Marschner](#), [Peter Shirley](#)

Chapter 8



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