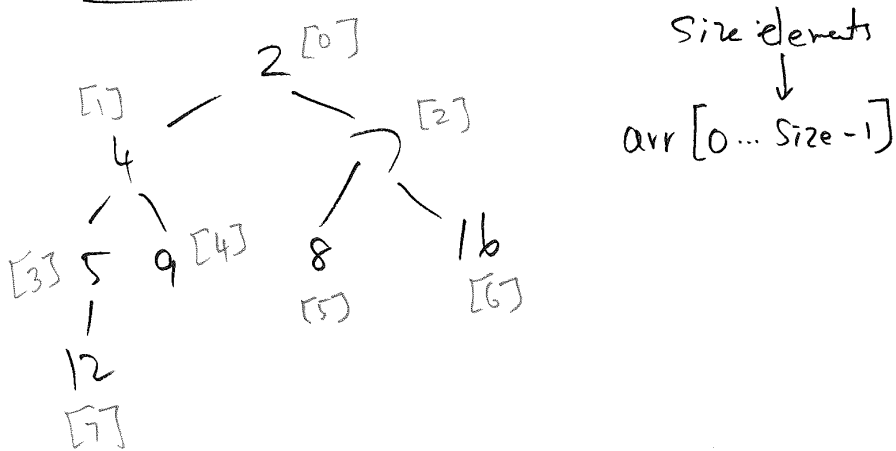


## Priority Queues ADT

- (i) insert / add - add new elements
- (ii) DeleteMin / ExtractMin / remove
  - remove element with max priority

Binary heap - implementation of PQ.

Complete binary tree - structure property  
value of node  $\leq$  value of children - order property  
parent has higher priority



remove():

```
min ← pq[0]
pq[0] ← pq[size--] ← move()
percolateDown(0)
return min
```

percolateDown(i): // Heap order may be violated at i, but only with its children

```
x ← pq[i]
c ← 2 * i + 1
while c ≤ size - 1 do
    if c < size - 1 and pq[c] > pq[c+1] then
        c++
    // c is smaller child of i
    if x ≤ pq[c] then break
    pq[i] ← pq[c] // move()
    i ← c
    c ← 2 * i + 1
```

```
pq[i] ← x // move(...)
```

peek(): return pq[0]

## Implementation of operations:

Heap occupies  $pq[0 \dots n-1]$

Height of tree =  $\log_2 n$  RT of each op =  $O(\log n)$ .

helper funcn:  $\text{parent}(i) = \text{return } (i-1)/2$

add(x):

if  $\text{size} \neq pq.\text{length}$  then  
(a) resize to bigger array  $\leftarrow$  Java  
or (b) throw exception  $\leftarrow$  We do this.

$pq[\text{size}] \leftarrow x$

percolateUp(size)

size++

percolateUp(i): // Heap order may be violated  
at  $pq[i]$  with respect to  
parent of i.

while  $i > 0$  and  $x < pq[\text{parent}(i)]$  do

$pq[i] \leftarrow pq[\text{parent}(i)]$

$i \leftarrow \text{parent}(i) \leftarrow \text{move}(pq, i, pq[\text{parent}(i)])$

$pq[i] \leftarrow x$

$\leftarrow \text{move}(pq, i, x)$

## Minimum spanning Trees (MST): Prim's algorithm.

Indexed priority queues:

PQ + index of each element is stored  
in the element.

PQ

$\text{move}(pq, i, x):$

$pq[i] \leftarrow x$

Indexed PQ

$\text{move}(pq, i, x):$

$pq[i] \leftarrow x$

$x.\text{putIndex}(i)$

$\text{percolateUp}(\text{index of } v \text{ in } q):$

$\text{percolateUp}(v.\text{getIndex}())$

**Priority Queues:** Each element has a priority. Elements are removed in the order of their priorities. Traditionally, smaller the value of priority, higher its priority. Duplicates are allowed, but not null values.

Operation	Traditional name	Java method
Insert a new element	Insert ( x )	add ( x ), offer ( x )
Remove element with maximum priority	DeleteMin ( ), ExtractMin ( )	remove ( ), poll ( )
Element with maximum priority	Min ( )	peek ( )

Java's PriorityQueue is iterable, but the iteration order is not in order of priority. There is a contains( ) operation, but it is inefficient. There is no operation to remove arbitrary elements.

**Implementation of priority queues:** Binary heaps (usually stored in arrays).

```
graph TD; 2 --> 4; 2 --> 7; 4 --> 5; 4 --> 9; 5 --> 12; 7 --> 8; 7 --> 16;
```

Array implementation:

2	4	7	5	9	8	16	12
0	1	2	3	4	5	6	7

Root is stored at index 0.

For a node at index  $i$ :

Parent's index:  $(i - 1) / 2$ .

Index of Children:  $\{2i + 1, 2i + 2\}$ .

Heaps are binary trees in which each node stores one element, satisfying the following properties:

1. Order property: priority of node  $\leq$  priority of its children, i.e., it has higher priority than its children,
2. Structure property: complete binary trees (all but last levels are full; last level is packed from left).

Operations will restore structure property first, and then ensure order property, using percolate Up/Down.

<p>Heap occupies <math>pq[0 \cdots size - 1]</math>.  Height of tree is <math>\log(size)</math>.  Running time of each operation: <math>O(\log(size))</math>.</p> <p>parent ( i ): return ( i - 1 ) / 2</p> <p>add ( x ):  if size = pq.length then // can resize pq here  throw Exception "Priority queue is full"  pq [ size ] <math>\leftarrow</math> x      把新加的放在最后然后向上调整  percolateUp ( size )  size ++</p> <p><b>percolateUp ( i ):</b>  x <math>\leftarrow</math> pq [ i ]  while i &gt; 0 and x &lt; pq [ parent(i) ] do  pq [ i ] <math>\leftarrow</math> pq [ parent(i) ]      把parent放下来  i <math>\leftarrow</math> parent(i)      更新 i  pq [ i ] <math>\leftarrow</math> x</p>	<p>remove ( ):  min <math>\leftarrow</math> pq [ 0 ]  pq [ 0 ] <math>\leftarrow</math> pq [ -- size ]      存好最顶上的值，然后把最后个值放在最顶上，然后向下调整  percolateDown ( 0 )  return min</p> <p><b>percolateDown ( i ):</b>  x <math>\leftarrow</math> pq [ i ]  c = 2 * i + 1      左孩子  while c <math>\leq</math> size - 1 do  if c &lt; size - 1 and pq [ c ] &gt; pq [ c + 1 ] then  c ++      c得到左右孩子中较小的那个  if x <math>\leq</math> pq [ c ] then break      比左右孩子都小就调整完成  pq [ i ] <math>\leftarrow</math> pq [ c ]      把孩子中较小的放到parent位置  i <math>\leftarrow</math> c      更新 i 位置 ( 当前调整的位置 )  c <math>\leftarrow</math> 2 * i + 1      更新 c 位置 ( 调整位置的孩子位置 )  pq [ i ] <math>\leftarrow</math> x</p> <p>peek ( ) : return pq [ 0 ]</p>
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## Minimum spanning trees (MST)

**Input:** **Undirected**, connected graph  $G = (V, E)$ , weights on edges  $w : E \rightarrow \mathbb{Z}$ .

**Output:** Spanning tree  $T \subseteq E$ , such that  $w(T) = \sum_{e \in T} w(e)$  is a minimum among all spanning trees of  $G$ .

**Prim's algorithm** for finding MST:

Grow a tree starting at some node  $\text{src}$  as source.

$S$  = Set of nodes connected by the tree. Initially,  $S = \{\text{src}\}$ .

while  $S \neq V$  do

Find a edge,  $e = (u, v)$  of **minimum weight**, connecting some  $u \in S$  with some  $v \in V - S$ .

Extend tree by adding edge  $e$  to tree.  **$S \leftarrow S \cup \{v\}$** .

从指定的顶点开始寻找最小权值的邻接点。图 $G=\langle V, E \rangle$ ，初始时 $S=\{V_0\}$ ，把与 $V_0$ 相邻接，且边的权值最小的顶点加入到 $S$ 。不断地把 $S$ 中的顶点与 $V-S$ 中顶点的最小权值边加入，直到所有顶点都已加入到 $S$ 中。

**Prim1**(  $G, \text{src}$  ): // Implementation #1 using a priority queue of edges

for  $u \in V$  do {  $u.\text{seen} \leftarrow \text{false}$ ;  $u.\text{parent} \leftarrow \text{null}$  }

$\text{src}.\text{seen} \leftarrow \text{true}$ ;  $\text{wmst} \leftarrow 0$ ; Create a priority queue  $q$  of edges

for( Edge  $e$ :  $\text{src}$  ) {  $q.\text{add}(e)$  }

while  $q$  is not empty do

$e \leftarrow q.\text{remove}()$ . Let  $e = (u, v)$ , with  $u.\text{seen} = \text{true}$ . 找到weight最小的那条

if  $v.\text{seen}$  then continue // skip this edge 访问过了就跳过

$v.\text{seen} \leftarrow \text{true}$ ;  $v.\text{parent} \leftarrow u$ ;  $\text{wmst} \leftarrow \text{wmst} + w(e)$  没访问过就访问( $u, v$ )

for( Edge  $e2$ :  $v$  ):

if !  $e2.\text{otherEnd}(v).\text{seen}$  then  $q.\text{add}(e2)$  把新加入的顶点连着的没有访问过的顶点的边加入队列

return // MST is implicitly stored by parent pointers

**Prim2**(  $G, \text{src}$  ): // Implementation #2 using indexed priority queue of vertices

// Node  $v \in V - S$  stores in  $v.d$ , the weight of a smallest edge that connects  $v$  to some  $u \in S$

for  $u \in V$  do {  $u.\text{seen} \leftarrow \text{false}$ ;  $u.\text{parent} \leftarrow \text{null}$ ;  $u.d \leftarrow \infty$  }

$\text{src}.d \leftarrow 0$ ;  $\text{wmst} \leftarrow 0$

$q \leftarrow$  new priority queue of vertices with  $u.d$  as priority of  $u$

while  $q$  is not empty do

$u \leftarrow q.\text{remove}()$ ;  $u.\text{seen} \leftarrow \text{true}$ ;  $\text{wmst} \leftarrow \text{wmst} + u.d$

for( Edge  $e$ :  $u$  ) do

$v \leftarrow e.\text{otherEnd}(u)$

if !  $v.\text{seen}$  and  $e.\text{weight} < v.d$  then

$v.d \leftarrow e.\text{weight}$ ;  $v.\text{parent} \leftarrow u$ ;

$\text{percolateUp}(\text{index of } v \text{ in } q)$  // How do we find the index of  $v$  in  $q$ ?

return

class PrimVertex implements Comparator<PrimVertex>, Index {

int d, index;

public int compare( PrimVertex  $u$ , PrimVertex  $v$  ) {

if (  $u.d < v.d$  ) return -1; else if (  $u.d == v.d$  ) return 0; else return 1; }

public void putIndex( int  $i$  ) { index =  $i$ ; }

public int getIndex( ) { return index; }

}