Due Date: April 29th 23:59, 2020

<u>Instructions</u>

- Read all instructions and questions carefully before you begin.
- For all questions, show your work!
- The repository for this homework is https://github.com/CW-Huang/IFT6135H20_assignment

Problem 1

Variational Autoencoders (VAEs) are probabilistic generative models to model data distribution $p(\mathbf{x})$. In this question, you will be asked to train a VAE on the *Binarised MNIST* dataset, using the negative ELBO loss as shown in class. Note that each pixel in this image dataset is <u>binary</u>: The pixel is either black or white, which means each datapoint (image) a collection of binary values. You have to model the likelihood $p_{\theta}(\mathbf{x}|\mathbf{z})$, i.e. the decoder, as a product of bernoulli distributions.¹

- 1. (unittest, 4 pts) Implement the function 'log_likelihood_bernoulli' in 'q1_solution.py' to compute the log-likelihood $\log p(x)$ for a given binary sample x and Bernoulli distribution p(x). p(x) will be parameterized by the mean of the distribution p(x = 1), and this will be given as input for the function.
- 2. (unittest, 4 pts) Implement the function 'log_likelihood_normal' in 'q1_solution.py' to compute the log-likelihood $\log p(x)$ for a given float vector x and isotropic Normal distribution $p(z) = \mathcal{N}(\mu, \operatorname{diag}(\sigma^2))$. Note that μ and $\log(\sigma^2)$ will be given for Normal distributions.
- 3. (unittest, 4 pts) Implement the function 'log_mean_exp' in 'q1_solution.py' to compute the following equation² for each y_i in a given $Y = \{y_1, y_2, \dots, y_i, \dots y_M\}$;

$$\log \frac{1}{K} \sum_{k=1}^{K} \exp\left(y_i^{(k)} - a_i\right) + a_i,$$

where $a_i = \max_k y_i^{(k)}$. Note that $\mathbf{y}_i = [y_i^{(1)}, y_i^{(2)}, \dots, y_i^{(k)}, \dots, y_i^{(K)}]$ s.

- 4. (unittest, 4 pts) Implement the function 'kl_gaussian_gaussian_analytic' in 'q1_solution.py' to compute KL divergence $D_{\text{KL}}(q(\boldsymbol{z}|\boldsymbol{x})||p(\boldsymbol{z}))$ via analytic solution for given p and q. Note that p and q are multivariate normal distributions with diagonal covariance.
- 5. (unittest, 4 pts) Implement the function 'kl_gaussian_gaussian_mc' in 'q1_solution.py' to compute KL divergence $D_{\text{KL}}(q(\boldsymbol{z}|\boldsymbol{x})||p(\boldsymbol{z}))$ by using Monte Carlo estimate for given p and q. Note that p and q are multivariate normal distributions with diagonal covariance.

¹The binarized MNIST is <u>not</u> interchangeable with the MNIST dataset available on torchvision. So the data loader as well as dataset will be provided.

²This is a type of log-sum-exp trick to deal with numerical underflow issues: the generation of a number that is too small to be represented in the device meant to store it. For example, probabilities of pixels of image can get really small. For more details of numerical underflow in computing log-probability, see http://blog.smola.org/post/987977550/log-probabilities-semirings-and-floating-point.

- 6. (report, 15 pts) Consider a latent variable model $p_{\theta}(\boldsymbol{x}) = \int p_{\theta}(\boldsymbol{x}|\boldsymbol{z})p(\boldsymbol{z})d\boldsymbol{z}$. The prior is define as $p(\boldsymbol{z}) = \mathcal{N}(\boldsymbol{0}, \boldsymbol{I}_L)$ and $\boldsymbol{z} \in \mathbb{R}^L$. Train a VAE with a latent variable of 100-dimensions (L = 100). Use the provided network architecture and hyperparameters described in 'vae.ipynb'³. Use ADAM with a learning rate of 3×10^{-4} , and train for 20 epochs. Evaluate the model on the validation set using the **ELBO**. Marks will neither be deducted nor awarded if you do not use the given architecture. Note that for this question you have to:
 - (a) Train a model to achieve an average per-instance ELBO of ≥ -102 on the validation set, and report the ELBO of your model. The ELBO on validation is written as:

$$\frac{1}{|\mathcal{D}_{\mathrm{valid}}|} \sum_{\boldsymbol{x}_i \in \mathcal{D}_{\mathrm{valid}}} \mathcal{L}_{\mathrm{ELBO}}(\boldsymbol{x}_i) \geq -102$$

Feel free to modify the above hyperparameters (except the latent variable size) to ensure it works.

Solution

In Fig.1 we can see the value of the ELBO evaluated on the validation set as function of the epochs, the best result achieved in the epoch 20 was ELBO = -101.54 using the same hyperparameters and architecture given in the original template.

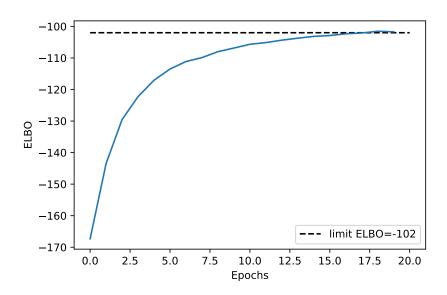


Figure 1: ELBO evaluated on the validation set as function of the epochs

7. (report, 15 pts) Evaluate log-likelihood of the trained VAE models by using importance sampling, which was covered during the lecture. Use the codes described in 'vae.ipynb'. The formula is reproduced here with additional details:

$$\log p(\boldsymbol{x} = \boldsymbol{x}_i) \approx \log \frac{1}{K} \sum_{k=1}^{K} \frac{p_{\theta}(\boldsymbol{x} = \boldsymbol{x}_i | \boldsymbol{z}_i^{(k)}) \ p(\boldsymbol{z} = \boldsymbol{z}_i^{(k)})}{q_{\phi}(\boldsymbol{z} = \boldsymbol{z}_i^{(k)} | \boldsymbol{x}_i)}; \quad \text{for all } k: \ \boldsymbol{z}_i^{(k)} \sim q_{\phi}(\boldsymbol{z} | \boldsymbol{x}_i)$$

and $x_i \in \mathcal{D}$.

³This file is executable in Google Colab. You can also convert vae.ipynb to vae.py using the Colab.

(a) Report your evaluations of the trained model on the test set using the log-likelihood estimate $(\frac{1}{N}\sum_{i=1}^{N}\log p(\boldsymbol{x}_i))$, where N is the size of the test dataset. Use K=200 as the number of importance samples, D as the dimension of the input (D=784 in the case of MNIST), and L=100 as the dimension of the latent variable.

Solution

After training the ELBO we evaluated the algorithm on the test set, the log likelihood estimate on the test set was -95.6. In Fig.2 we can see an example of the original MNIST data set and the corresponding reconstruction using VAE and the ELBO algorithm, we can see that the algorithm obtained a good representation of the probability distribution function of the data set.

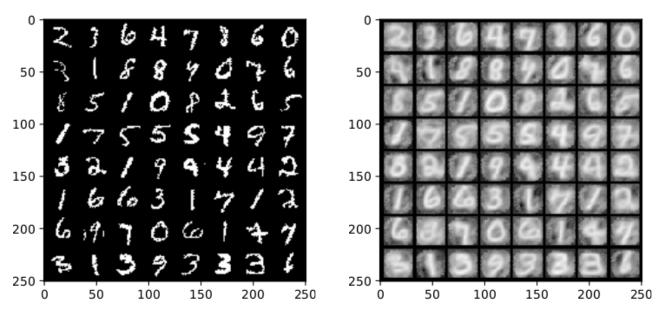


Figure 2: Left: Original batch of images of the MNIST data set. Right: Reconstruction of the image using VAE and the ELBO algorithm

Problem 2

Generative Adversarial Network (GAN) enables the estimation of distributional measure between arbitrary empirical distributions. In this question, you will first implement a function to estimate the Squared Hellinger as well as one to estimate the Earth mover distance. This will allow you to look at and contrast some properties of the f-divergence 4 and the Earth-Mover distance 5 .

We provide samplers ⁶ to generate the different distributions that you will need for this question. In the same repository, we also provide the architecture of a neural network function Critic: $\mathcal{X} \to \mathbb{R}$ s.t. $\mathcal{X} \subset \mathbb{R}^2$ in model.py. For training, you may use SGD with a learning rate of 1e-3 and a mini batch size of 512.

 $^{^4}$ Relevant reference on f-divergence: https://arxiv.org/abs/1606.00709

⁵Relevant reference on Wasserstein GAN: https://arxiv.org/abs/1701.07875

⁶See the assignment repository https://github.com/CW-Huang/IFT6135H20_assignment

1. (report, 4 pts) Provide the objective function of the Squared Hellinger in your report (See Nowozin et al. – Footnote 4).

Solution

The objective function is given by

$$F(\theta, w) = \mathbb{E}_{x \sim P}[g_f(V_w(x))] + \mathbb{E}_{x \sim Q}[-f^*(g_f(V_w(x)))] \tag{1}$$

which for Hellinger takes the form

$$F(\theta, w) = \mathbb{E}_{x \sim P} \left[1 - \exp(-V_w(x)) \right] - \mathbb{E}_{y \sim Q} \left[\frac{(1 - \exp(-V_w(y)))}{\exp(-V_w(y))} \right]$$
 (2)

with V_w the critic model.

- 2. (unittest, 4 pts) Implement the function 'vf_squared_hellinger' in 'q2_solution.py' to compute the objective function for estimating the Squared Hellinger distance. Please, consider the definition given in Nowozin. We give more instruction in the code template.
- 3. (report, 4 pts) In your report, provide the objective function of the Wasserstein distance and the objective function of the "Lipschitz Penalty" ⁷

Solution

The objective function for the Wasserstein distance is

$$F(\theta, w) = \mathbb{E}_{x \sim P}[V_w(x)] - \mathbb{E}_{y \sim Q}[V_w(y)]$$
(3)

And the objective function of Lipschitz Penalty is given by

$$F(\theta, w) = \mathbb{E}_{y \sim Q}[V_w(y)] - \mathbb{E}_{x \sim P}[V_w(x)] + \lambda \mathbb{E}_{\hat{x} \sim \tau}[(\max\{0, ||\nabla V_w(\hat{x})|| - 1\})^2]$$
(4)

with V_w the critic model, and $\tau = tx + (1-t)y$ for $t \sim U[0,1]$

- 4. (unittest, 4 pts) Implement the functions 'vf_wasserstein_distance' and 'lp_reg' in 'q2_solution.py' to compute the objective function of the Wasserstein distance and compute the "Lipschitz Penalty". Consider that the norm used in the regularizer is the L2-norm.
- 5. (report, 10 pts) Let $u \sim U[0,1]$ be the uniform random variable with support in the interval [0,1]. We define p the distribution of $(0,u) \in \mathbb{R}^2$ and q the distribution of $(\theta,u) \in \mathbb{R}^2$ (We provide a function generating the p and q in the file q2_samplers.py). Plot the estimated Squared Hellinger distance between p and q and the estimated Earth-Mover distance between p and q for $\theta \in [0,2]$ with interval of 0.1 (i.e. 21 points). The x-axis should be the value of θ and the y-axis should be your estimate. In your report, provide two plots: a plot of the estimate of the Squared Hellinger with respect to θ and a plot of the estimate of the Wasserstein distance with respect to θ . Also, provide a one or two lines explanation of the behaviour you observe.

Solution

Fig.3 shows a comparison between the Wasserstein and Hellinger distance with θ varied from

⁷See Section 5 of https://arxiv.org/pdf/1709.08894.pdf

0 to 2. We can see that Hellinger distance shows the most difference between two probability densities that only vary a small amount, however it presents an asymptotic behavior for distant distributions. On the other hand the Wasserstein or Earth Mover's Distance between two distributions is proportional to the minimum amount of work required to change one distribution into the other. In this case a unit of work is interpreted as the amount of work necessary to move one unit of weight by one unit of distance, in this particular case we can imagine that the distributions have the same "weight" (they are all uniform distributions between [0,1]) so the distance between the distributions is proportional to θ so Wasserstein exhibits a linear behaviour.

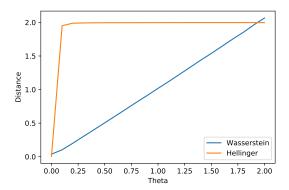


Figure 3: Estimated squared Hellinger distance and Weisserstein distance as function of θ

Problem 3

Recent years have shown an explosion of research into using deep learning and computer vision algorithms to generate images.

In this final question, you will use the GAN framework train a generator to generate a distribution of high dimensional images $\mathcal{X} \subset \mathbb{R}^{32 \times 32 \times 3}$, namely the **Street View House Numbers** dataset (SVHN) ⁸. We will consider the prior distribution $p(z) = \mathcal{N}(\mathbf{0}, I)$ the isotropic gaussian distribution. We provide a function for sampling from the SVHN datasets in 'q3_samplers.py'.

Hyperparameters & Training Pointers We provide code for the GANs network as well as the hyperparameters you should be using. We ask you to code the training procedure to train the GANs as well as the qualitative exploration that you will include in your report. You can re-use the WGAN-lp objective you wrote in the the previous question.

Qualitative Evaluation In your report,

⁸The SVHN dataset can be downloaded at http://ufldl.stanford.edu/housenumbers/

1. (report, 8 pts) Provide visual samples. Comment the quality of the samples from each model (e.g. blurriness, diversity).

Solution





Figure 4: Left: Original batch of images of the MNIST data set. Right: Fake images given by the generator of the GAN algorithm

In Fig.4(left) we see a real batch of training images, we note that some images in the data set are not very clear, consequently some numbers have less quality than others. In Fig.4(right) we see the fake images created by the generator, although the images are a little blurry it is clear that the generator clearly learned the true representation of the numbers.

2. (report, 8 pts) We want to see if the model has learned a disentangled representation in the latent space. Sample a random z from your prior distribution. Make small perturbations to your sample z for each dimension (e.g. for a dimension $i, z'_i = z_i + \epsilon$). ϵ has to be large enough to see some visual difference. For each dimension, observe if the changes result in visual variations (that means variations in g(z)). You do not have to show all dimensions, just a couple that result in interesting changes.

Solution

In Fig.5 we can see two different perturbations of a sample z taken from the prior distribution. Originally the generator applied to a random tensor z produces a fake image as shown in Fig.4 (right). Now one perturbed the tensor z (with dimension $z_{dim} = 100$) in the arbitrary position 15 with an arbitrary value of 45, i.e z'[15] = z[15] + 45 and applied again the generator g(z'), the result is shown in Fig.5 (left). In Fig.5(left) can see that the whole batch of fake images shows the number 8, which implies that the model learned the representation of that number in the latent space. Using the same idea one perturbed the arbitrary position z'[60] = z[60] + 45 observing that the whole set of fake images exhibits the number 5 as can be seen in Fig.5(right)

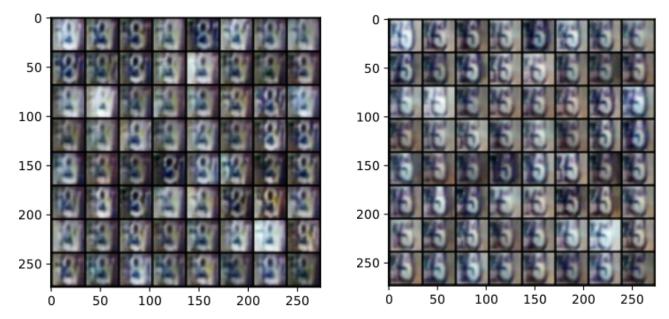


Figure 5: Perturbation of a random z from the prior distribution. Left: z'[15] = z[15] + 45. Right: z'[60] = z[60] + 45

- 3. (report, 8 pts) Compare between interpolating in the data space and in the latent space. Pick two random points z_0 and z_1 in the latent space sampled from the prior.
 - (a) For $\alpha=0,\,0.1,\,0.2\dots 1$ compute $z'_{\alpha}=\alpha z_0+(1-\alpha)z_1$ and plot the resulting samples $x'_{\alpha}=g(z'_{\alpha}).$

Solution

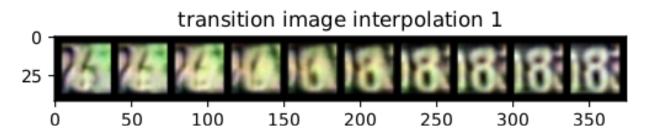


Figure 6: Transition image using the interpolation $z'_{\alpha} = \alpha z_0 + (1 - \alpha)z_1$, the fake images for each α are obtained using $x'_{\alpha} = g(z'_{\alpha})$

(b) Using the data samples $x_0 = g(z_0)$ and $x_1 = g(z_1)$ and for $\alpha = 0, 0.1, 0.2...1$ plot the samples $\hat{x}_{\alpha} = \alpha x_0 + (1 - \alpha)x_1$.

Solution

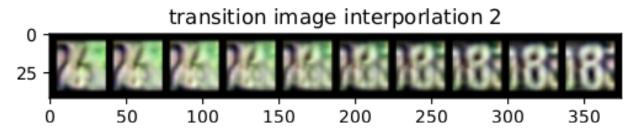


Figure 7: Transition image using the interpolation $\hat{x}_{\alpha} = \alpha x_0 + (1 - \alpha)x_1$, where $x_0 = g(z_0)$ and $x_1 = g(z_1)$

Interpolation 1 represents a transition in the latent space and interpolation 2 represents a transition in data space. Accordingly with the Fig.7 and Fig.6 the transition in the latent space is faster, however the transition in the data space is softer. Clearly both schemes converges to the same final image.