Constructive Category Theory and Applications in Algebraic Geometry

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Outline

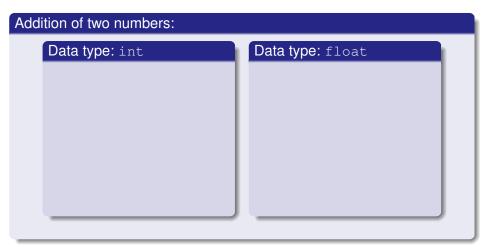
Constructive category theory

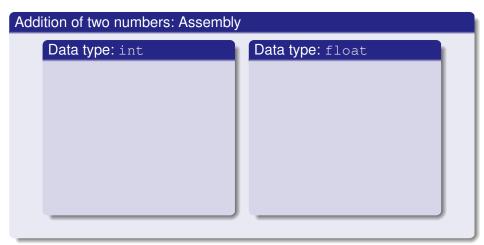
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Constructive category theory

Applications to Algebraic Geometry

Constructive category theory





Addition of two numbers: Assembly

Data type: int

```
addi:
movl %edi, -4(%rsp)
movl %esi, -8(%rsp)
movl -4(%rsp), %esi
addl -8(%rsp), %esi
movl %esi, %eax
ret
```

Data type: float

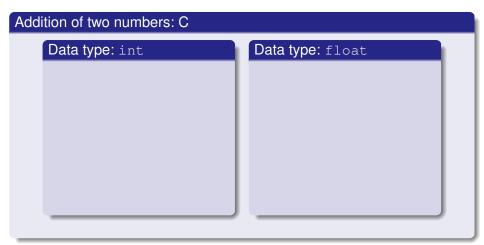
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```
addf:
movss %xmm0, -4(%rsp)
movss %xmm1, -8(%rsp)
movss -4(%rsp), %xmm0
addss -8(%rsp), %xmm0
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```



Addition of two numbers: C

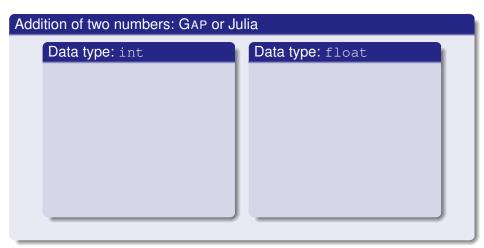
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Addition of two numbers: GAP or Julia

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function( a, b )
    return a + b;
end;
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High language leads to generic code!

Computing the intersection of two subobjects

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Generic algorithm for both cases? Category theory!

Category theory

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- defines a language to formulate theorems and algorithms for different structures at the same time

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CAP implements a categorical programming language

Definition

A category \mathcal{A} contains the following data:

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Δ

В

С

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$$A \longrightarrow B$$

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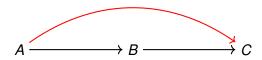
A category A contains the following data:

- \bullet Obj_A
- $Hom_A(A, B)$
- ullet \circ : $\operatorname{\mathsf{Hom}}_{\mathcal{A}}(B,C) \times \operatorname{\mathsf{Hom}}_{\mathcal{A}}(A,B) \to \operatorname{\mathsf{Hom}}_{\mathcal{A}}(A,C)$ (assoz.)

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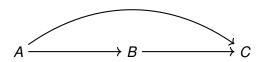
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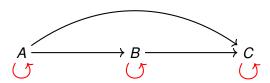
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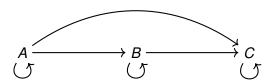
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• data structures for objects and morphisms

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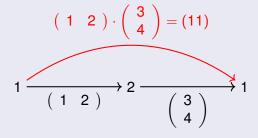
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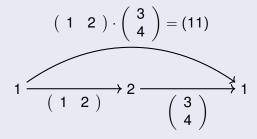
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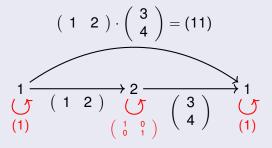
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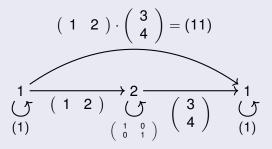
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Some categorical operations in abelian categories

Zero morphisms

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- Addition and subtraction of morphisms

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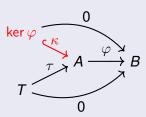
Let $\varphi \in \text{Hom}(A, B)$. To fully describe the kernel of $\varphi \dots$

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$$\ker \varphi \xrightarrow{\kappa} A \xrightarrow{\varphi} B$$

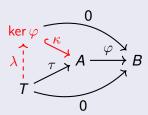
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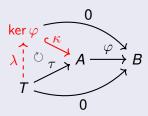
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Implementation of the kernel: Q-vector spaces

Obj :=
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, Hom $(m, n) := \mathbb{Q}^{m \times n}$

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Compute

• $\ker \varphi$ as $\dim(A) - \operatorname{rank}(\varphi)$

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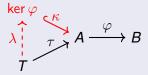
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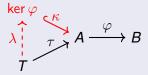
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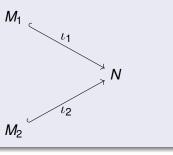
CAP - Categories, Algorithms, and Programming

CAP is a framework to implement computable categories and provides

- specifications of categorical operations,
- generic algorithms based on basic categorical operations,
- a categorical programming language having categorical operations as syntax elements.

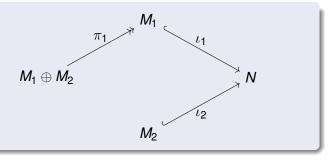
Let $M_1 \subseteq N$ and $M_2 \subseteq N$ subobjects.

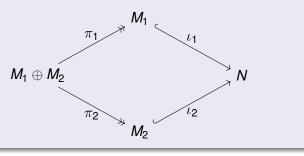
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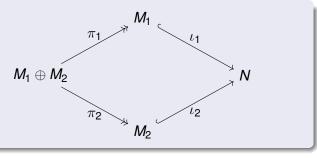
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 $M_1 \oplus M_2$ M_2 N



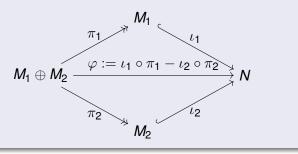


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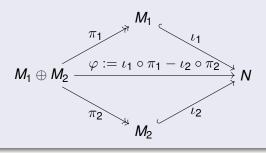


• $\pi_i := \text{ProjectionInFactorOfDirectSum}((M_1, M_2), i), i = 1, 2$

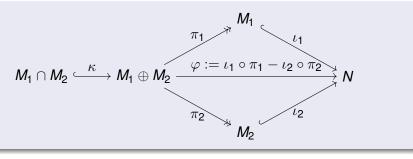
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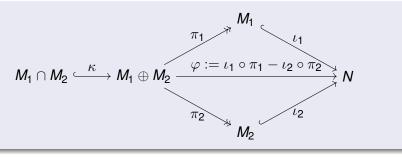
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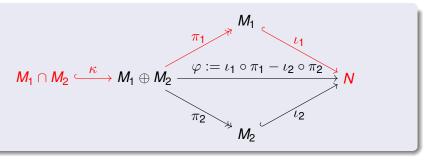
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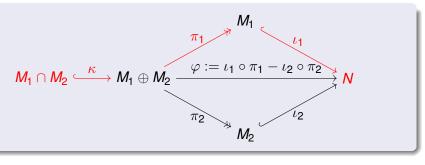
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$$\pi_i := \text{ProjectionInFactorOfDirectSum}((M_1, M_2), i), i = 1, 2$$

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```
\begin{split} \pi_i &:= \operatorname{ProjectionInFactorOfDirectSum}\left(\left(\textit{M}_1, \textit{M}_2\right), i\right), i = 1, 2 \\ & \text{pil} := \operatorname{ProjectionInFactorOfDirectSum}\left(\left[\begin{array}{c} \operatorname{M1}, \ \operatorname{M2} \end{array}\right], \ 1 \right); \\ & \text{pi2} := \operatorname{ProjectionInFactorOfDirectSum}\left(\left[\begin{array}{c} \operatorname{M1}, \ \operatorname{M2} \end{array}\right], \ 2 \right); \\ & \varphi := \iota_1 \circ \pi_1 - \iota_2 \circ \pi_2 \\ \\ & \kappa := \operatorname{KernelEmbedding}\left(\varphi\right) \\ \\ & \gamma := \iota_1 \circ \pi_1 \circ \kappa \end{split}
```

```
\pi_i := \text{ProjectionInFactorOfDirectSum}((M_1, M_2), i), i = 1, 2
  pil := ProjectionInFactorOfDirectSum( [ M1, M2 ], 1 );
  pi2 := ProjectionInFactorOfDirectSum( [ M1, M2 ], 2 );
\varphi := \iota_1 \circ \pi_1 - \iota_2 \circ \pi_2
  lambda := PostCompose( iotal, pil );
   phi := lambda - PostCompose( iota2, pi2 );
\kappa := \text{KernelEmbedding}(\varphi)
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\operatorname{pi2} := \operatorname{ProjectionInFactorOfDirectSum}\left(\left[\begin{array}{c} \operatorname{M1}, \operatorname{M2} \right], 2 \right);

\varphi := \iota_1 \circ \pi_1 - \iota_2 \circ \pi_2

\operatorname{lambda} := \operatorname{PostCompose}\left(\operatorname{iota1}, \operatorname{pi1}\right);

\operatorname{phi} := \operatorname{lambda} - \operatorname{PostCompose}\left(\operatorname{iota2}, \operatorname{pi2}\right);

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  gamma := PostCompose( lambda, kappa );
```

```
pi1 := ProjectionInFactorOfDirectSum( [ M1, M2 ], 1 );
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 pil := ProjectionInFactorOfDirectSum( [ M1, M2 ], 1 );
  pi2 := ProjectionInFactorOfDirectSum( [ M1, M2 ], 2 );
  lambda := PostCompose( iotal, pil );
  phi := lambda - PostCompose( iota2, pi2 );
  kappa := KernelEmbedding( phi );
  gamma := PostCompose( lambda, kappa );
  return gamma;
end:
```

```
Schnitt := function( iotal, iota2 )
  local M1, M2, pi1, pi2, lambda, phi, kappa, gamma;
 M1 := Source(iota1);
 M2 := Source(iota2);
 pil := ProjectionInFactorOfDirectSum( [ M1, M2 ], 1 );
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  lambda := PostCompose( iotal, pil );
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```

Computing the intersection: Q-vector space

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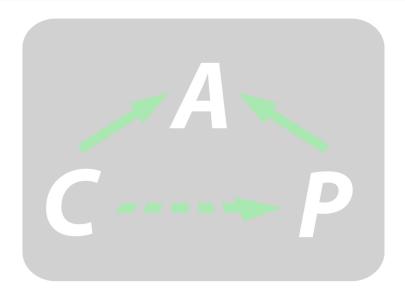
```
gap> gamma := Schnitt( iotal, iota2 );
<A morphism in the category of matrices over Q>
```

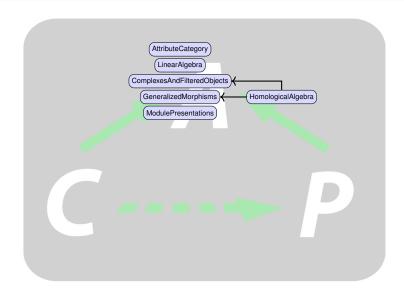
Computing the intersection: Q-vector space

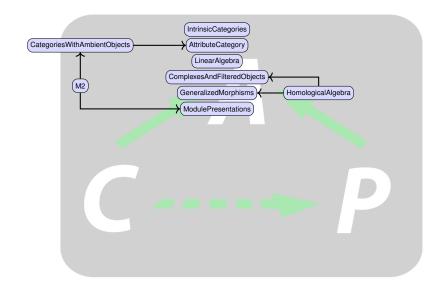
Compute the intersection of

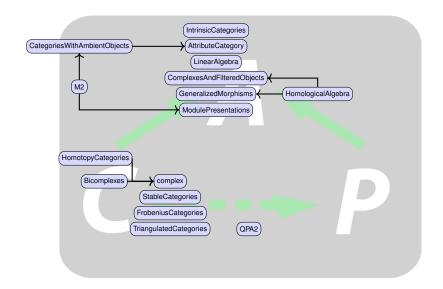
```
gap> gamma := Schnitt( iota1, iota2 );
<A morphism in the category of matrices over Q>
gap> Display( gamma );
[ [ 1,  1,  0  ] ]
```

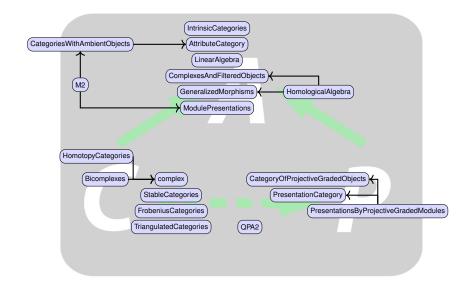
A morphism in the category of matrices over Q

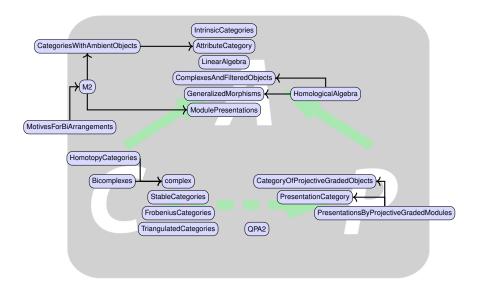


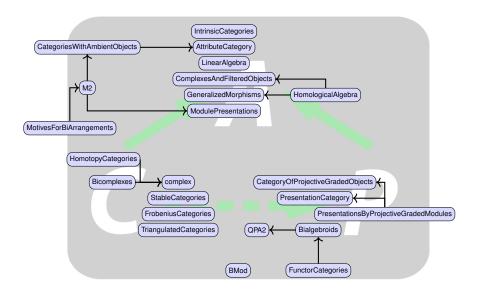


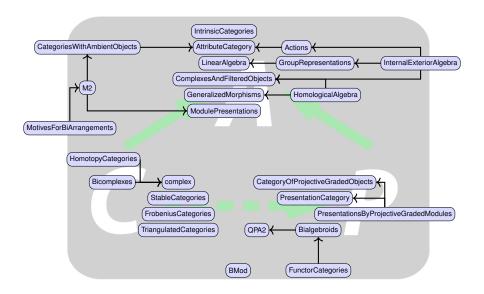


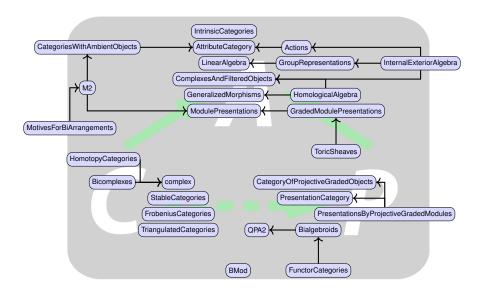


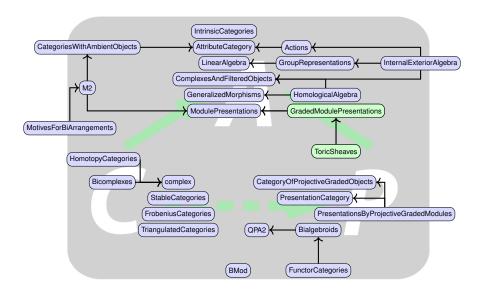












Applications to Algebraic Geometry

Let *K* be an algebraically closed field.

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Affine space

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In the language of category theory:

Equivalence of categories

$$S$$
-mod $\stackrel{\sim}{\longrightarrow} \mathfrak{Coh}(\mathbb{A}^n)$

Projective space

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In the language of category theory: Equivalence of categories

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Computability of S-grmod_G/S-grmod_G⁰?

Serre quotient

Serre quotient

Let A be an abelian category and C a thick subcategory.

Serre quotient

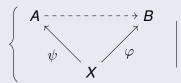
Serre quotient

Let \mathcal{A} be an abelian category and \mathcal{C} a thick subcategory. The **Serre quotient** \mathcal{A}/\mathcal{C} is an abelian category with

• $Obj_{\mathcal{A}/\mathcal{C}} := Obj_{\mathcal{A}}$

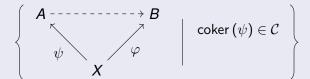
Serre quotient

- $Obj_{\mathcal{A}/\mathcal{C}} := Obj_{\mathcal{A}}$
- $\operatorname{\mathsf{Hom}}_{\mathcal{A}/\mathcal{C}}(A,B) :=$



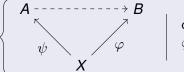
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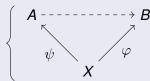
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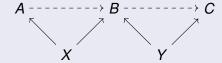
$$\operatorname{\mathsf{coker}} (\psi) \in \mathcal{C} \ arphi \left(\operatorname{\mathsf{ker}} (\psi)
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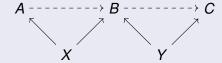
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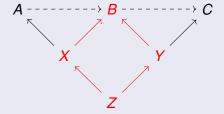


Composition in the Serre quotient \mathcal{A}/\mathcal{C}

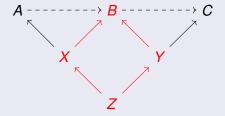




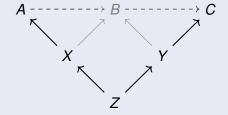




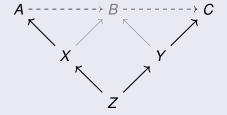
Composition in the Serre quotient A/C



FiberProduct: Algorithm for intersection



Composition in the Serre quotient A/C



Composition only by computations in A!

Theorem (Barakat, Lange-Hegermann)

Is A computable abelian and C decidable,

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Theorem (G.)

Let *X* be a normal toric variety without torus factors.

Theorem (Barakat, Lange-Hegermann)

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Let X be a normal toric variety without torus factors. Then the thick subcategory S-gr mod_G^0 of f. g. G-graded modules over S which sheafify to zero

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So $\mathfrak{Coh}(X)$ is computable abelian!

We can apply algorithms for abelian categories to coherent sheaves over toric varieties:

Intersection

So $\mathfrak{Coh}(X)$ is computable abelian!

- Intersection
- Homology

So $\mathfrak{Coh}(X)$ is computable abelian!

- Intersection
- Homology
- Diagram chases

So $\mathfrak{Coh}(X)$ is computable abelian!

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- ...