

# CLE Type System

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## 1 Introduction

## 2 CLE Types Grammar

The following is a small grammar for CLE types  $\tau$ .  $l$  and  $r$  represent enclaves and can be thought of as arbitrary identifiers.  $\alpha, \beta, \theta, \sigma$  are sets of remote enclaves, while  $\delta$  is a set of  $\mu$ .

$$\begin{aligned}\tau, \pi, \gamma &::= l \ \sigma \mid l \ \delta \\ \mu &::= r \ (\alpha_1, \dots, \alpha_n) \rightarrow_{\phi} \theta\end{aligned}$$

$l \ \sigma$  describes a variable in enclave  $l$  which can be shared with enclaves inside  $\sigma$ . The inhabitants of  $l \ \delta$  are functions in the enclave  $l$ . For every  $r \ (\alpha_1, \dots, \alpha_n) \rightarrow_{\phi} \theta \in \delta$  every function whose type is  $l \ \delta$  can be called from an enclave  $r$  with arguments whose shareability is  $\alpha_1, \dots, \alpha_n$ , whose function body can share with  $\phi$  and whose return is able to be shared with  $\theta$ .

The terms of the inhabitants of these types are an idealized subset of llvm, where the only control flow instructions are breaks and function calls.

## 3 Type rules

Here we assume all functions and global variables have cle types associated with them. We will focus on how to infer such types in the next section. There are several types of judgements, each of which is enumerated below:

### 3.1 Judgements

1.  $\Gamma \vdash e : \tau$ . Top-level entity or instruction  $e$  has type  $\tau$ .
2.  $\Gamma \vdash b :_{\pi} \gamma$ . Basic block or set of basic blocks  $b$  has type  $\pi$  for all variables bound in instructions, type  $\gamma$  for the terminator.
3.  $\Gamma \vdash t :_{\pi} \gamma$ . Terminator  $t$  has type  $\gamma$  and all referenced basic blocks,  $b$  are given type  $\pi\gamma$ .

### 3.2 Rules for top-level entities

$$\frac{\tau = l \sigma}{\Gamma \vdash @x : \tau} \text{ global-decl} \quad \frac{\tau = l \sigma}{\Gamma \vdash @x = c : \tau} \text{ global-def}$$

$$\frac{\forall (r (\alpha_1, \dots, \alpha_n) \rightarrow_\phi \theta) \in \delta. \Gamma[@f \mapsto \tau, \%1 \mapsto l \alpha_1, \dots, \%n \mapsto l \alpha_n] \vdash body :_{(l \phi)} l \theta}{\Gamma \vdash @f(\%1, \dots, \%n) \{body\} : l \delta} \text{ fn-def}$$

$$\frac{\Gamma(@f) = \tau = l \delta}{\Gamma \vdash @f(\%1, \dots, \%n) \{body\} : \tau} \text{ fn-def-known}$$

### 3.3 Rules for basic blocks and instruction lists

$$\frac{\Gamma \vdash b :_\pi \gamma \quad \Gamma, \%b :_\pi \gamma \vdash bbs :_\pi \gamma}{\Gamma \vdash b \ bbs :_\pi \gamma} \text{ fn-body}$$

$$\frac{\Gamma \vdash instrs : \pi \quad \Gamma \vdash term :_\pi \gamma}{\Gamma \vdash \%b : instrs \ term :_\pi \gamma} \text{ bb-unknown}$$

$$\frac{\Gamma(\%b) =_\pi \gamma}{\Gamma \vdash \%b : instrs \ term :_\pi \gamma} \text{ bb-known}$$

$$\frac{\Gamma \vdash instr : \pi \quad \Gamma[\%a \mapsto \pi] \vdash instrs : \pi}{\Gamma \vdash \%a = instr; instrs : \pi} \text{ instrs}$$

### 3.4 Rules for special instructions and terminators

$$\frac{\Gamma(\%1) = l \alpha_1, \dots, \Gamma(\%n) = l \alpha_n \quad l (\alpha_1, \dots, \alpha_n) \rightarrow_\phi \theta \in \delta \quad \Gamma \vdash @f : r \delta}{\Gamma \vdash \text{call } @f(\%1, \dots, \%n) : l \theta} \text{ call}$$

$$\frac{\Gamma(\%a) = \gamma \quad \Gamma \vdash \%b_1 :_\pi \gamma \quad \Gamma \vdash \%b_2 :_\pi \gamma}{\Gamma \vdash \text{br } \%a, \%b_1, \%b_2 :_\pi \gamma} \text{ break}$$

$$\frac{\Gamma(\%a) = \gamma}{\Gamma \vdash \text{ret } \%a :_\pi \gamma} \text{ ret}$$

### 3.5 General rule for instructions

The rules for all other instructions can be derived from general instruction form which takes in a number of arguments:

$$\text{instr } \%a_1, \dots, \%a_n$$

Thus,

$$\frac{\Gamma(\%a_1) = \dots = \Gamma(\%a_n) = \pi}{\Gamma \vdash \text{instr } \%a_1, \dots, \%a_n : \pi} \text{ ret}$$

## 4 Conversion from CLE label and enclave assignments

### 4.1 Enclaves vs. Levels

The CLE JSON annotations deal in terms of levels, while the type system operates on enclaves. Since every enclave resides at a level, we can understand a level as a set of enclaves.

### 4.2 Annotated function assignments

We start with unannotated function  $f$  is assigned a label  $q$  and enclave  $l$ . Immediately, we know  $f$  must have a type  $l \delta$ . To find  $\delta$  we do the following:

1. Lookup  $q$ 's corresponding cle json in the cle map.
2. For every cdf inside  $q$ 's definition
3. For each remote level in the cdfs for  $q$ , we lookup the argtaints, codtaints and rettaints labels and expand their corresponding levels into sets of remote enclaves. For argtaints, we obtain a set of enclaves for each argument  $\alpha_1, \dots, \alpha_n$ . For codtaints and rettaints, we obtain two sets  $\phi$  and  $\theta$  for codtaints and rettaints respectively.
4. For each remote level, we obtain a set of remote enclaves  $E$ . For each enclave  $r$  in  $E$ , we construct a  $\mu = r (\alpha_1, \dots, \alpha_n) \rightarrow_{\phi} \theta$ .

### 4.3 Unannotated function assignments

Unannotated functions can only be called within an enclave. Thus, every unannotated function  $f$  in enclave  $l$  has type  $l \delta$  where  $\delta = \{l (\alpha_1, \dots, \alpha_n) \rightarrow_{\phi} \theta\}$ , assuming there is some way to obtain  $\alpha_1, \dots, \alpha_n, \phi, \theta$ .

### 4.4 Global variables

A global variable  $g$  in enclave  $l$  will have type  $l \sigma$ . To determine  $\sigma$ , we lookup the remote levels in the cdfs for  $g$  and expand to get a set of enclaves for each remote level. Then  $\sigma$  is the union of these sets.