Appendix C.III: Hypothesized Method - Confirmatory Latent Class Analysis (CLCA)

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```
library(tidyverse)
library(MplusAutomation)
library(rhdf5)
library(here)
library(glue)
library(gt)
library(janitor)
library(reshape2)
library(cowplot)
Read data file n_6000_lca_rep1.dat (N=6000; Replication 5)
C3_data <- read.delim2(here("C1-Simulation", "n_6000_lca_rep5.dat"), sep = "", header = FALSE) %>%
    select(-V18) %>%
    setNames(c("primary", "change", "interupt", "initiat", "engage", "approach",
        "response", "expect", "new", "same", "relative", "objects", "sequence", "trans",
        "avoid", "control", "touch")) %>%
    purrr::modify_if(is.character, as.numeric)
write_csv(C3_data, here("data", "C3_simulated_N6000R5.csv"))
Procedure: Hypothesized Model
   • Step 1: Estimate unconstrained model (comparison model)
   • Step 2: Estimate hypothesis-driven model with boundary and inequality constraints
Step 1
Estimate unconstrained LCA Model with Simulated Data (C3_data)
```

```
m_unconstrained <- mplusObject(</pre>
 TITLE = "Unconstrained Model",
 VARIABLE =
  "categorical = primary-touch;
   usevar = primary-touch;
    classes = c(5); ",
  ANALYSIS =
  "estimator = mlr;
   type = mixture;
   starts = 0;
   !starts = 500 200;
   STSEED = 21345; !!! USE SEED TO REPLICATE THESIS RESULTS !!!
 OUTPUT = "svalues;",
 PLOT = "type = plot3;
          series = primary-touch(*);",
 usevariables = colnames(C3_data),
 rdata = C3_data)
m_unconstrained_fit <- mplusModeler(m_unconstrained,</pre>
                 dataout=here("C3-Hypothesized", "Unconstrained.dat"),
                 modelout=here("C3-Hypothesized", "Unconstrained.inp") ,
                 check=TRUE, run = TRUE, hashfilename = FALSE)
```

Step 2

Estimate Revised Hypothesis Model

```
m1 <- mplusObject(

TITLE = "Hypothesis-M1",

VARIABLE =
   "categorical = primary-touch;
   usevar = primary-touch;
   classes = c(5); ",

ANALYSIS =
   "estimator = mlr;
   type = mixture;
   !starts = 500 200;
   !STSEED = 459573; !!! USE SEED TO REPLICATE THESIS RESULTS !!!</pre>
```

```
"!!! NAME & LABEL PARAMETERS !!!
%OVERALL%
%C#1%
            !!!High_Flex!!!
[ primary$1*-.85 ](t1);
 [ change$1*-.85 ](t2);
[interupt$1*-.85](t3);
[ initiat$1*-.85 ](t4);
[ engage$1*-.85 ](t5);
 [approach$1*-.85](t6);
 [response$1*-.85](t7);
[ expect$1*-.85 ](t8);
      new$1*-.85 ](t9);
[ same$1*-.85](t10);
[relative$1*-.85](t11);
 [ objects$1*-.85 ](t12);
 [sequence$1*-.85](t13);
[ trans$1*-.85](t14);
[ avoid$1*-.85 ](t15);
[ control$1*-.85 ](t16);
[ touch$1*-.85](t17);
%C#2%
             !!!ScIn_Flex!!!
[ primary$1*-.85 ](t18);
[ change$1*-.85 ](t19);
[interupt$1*-.85](t20);
[ initiat$1*-.85 ](t21);
 [ engage$1*-.85 ](t22);
 [approach$1*-.85](t23);
 [response$1*-.85 ](t24);
 [ expect$1*-.85 ](t25);
     new$1*.85 ](t26);
   same$1*.85 ](t27);
[relative$1*.85 ](t28);
[ objects$1*.85 ](t29);
[sequence$1*.85 ](t30);
[ trans$1*.85 ](t31);
[ avoid$1*.85 ](t32);
 [ control$1*.85 ](t33);
[ touch$1*.85 ](t34);
%C#3%
             !!!LocSnsLo!!!
[ primary$1*.85 ](t35);
[ change$1*.85 ](t36);
[interupt$1*.85 ](t37);
[ initiat$1*.85 ](t38);
```

```
[ engage$1*.85 ](t39);
[approach$1*.85](t40);
[response$1*.85 ](t41);
[ expect$1*.85 ](t42);
     new$1*-.85](t43);
    same$1*-.85](t44);
[relative$1*-.85](t45);
[ objects$1*-.85](t46);
[sequence$1*-.85](t47);
[ trans$1*-.85](t48);
   avoid$1*-.85](t49);
[ control$1*-.85](t50);
   touch$1*-.85](t51);
%C#4%
           !!!Env_Flex !!!
    [ primary$1 ](t52);
    [ change$1 ](t53);
    [interupt$1 ](t54);
    [ initiat$1 ](t55);
    [ engage$1 ](t56);
    [approach$1](t57);
    [response$1 ](t58);
    [ expect$1 ](t59);
     new$1*.85 ](t60);
    same$1*.85 ](t61);
[relative$1*.85](t62);
[ objects$1*-.85](t63);
[sequence$1*-.85](t64);
[ trans$1*-.85](t65);
[ avoid$1*.85 ](t66);
[ control$1*.85 ](t67);
   touch$1*.85 ](t68);
%C#5%
              !!!Low_Flex!!!
 [ primary$1*.85 ](t69);
 [ change$1*.85 ](t70);
[interupt$1*.85](t71);
 [ initiat$1*.85 ](t72);
 [ engage$1*.85 ](t73);
 [approach$1*.85](t74);
 [response$1*.85](t75);
 [ expect$1*.85 ](t76);
      new$1*.85 ](t77);
     same$1*.85 ](t78);
[relative$1*.85](t79);
 [ objects$1*.85 ](t80);
 [sequence$1*.85](t81);
[ trans$1*.85](t82);
[ avoid$1*.85 ](t83);
[ control$1*.85 ](t84);
[ touch$1*.85](t85);
```

```
MODELCONSTRAINT = "
!!! THRESHOLD BOUNDARIES
                                     111
!!! -.85 (THRESHOLD) ~ .70 (PROBABILTY) !!!
!!! .85 (THRESHOLD) ~ .30 (PROBABILTY) !!!
! LABELS C1-C5 BELOW REFLECT ORDER OF CLASSES IN PLOT (NOT MPLUS C# LABELS ABOVE)
  ! C1 | C2 | C3 | C4 | C5 !
  !High_Flex|ScIn_Flex|Env_Flex |LocSnsLo|Low_Flex!
   !_____|___|___|
   t1 <-.8; t18<-.8; t35> .8; t69> .8; !!!U1 !!!
t2 <-.8; t19<-.8; t36> .8; t70> .8; !!!U2 !!!
                                     t71> .8; !!!U3 !!!
t72> .8; !!!U4 !!!
t73> .8; !!!U5 !!!
t74> .8; !!!U6 !!!
   t3 <-.8; t20<-.8; t37> .8;
   t4 <-.8; t21<-.8; t38> .8;
   t5 <-.8; t22<-.8; t39> .8;
   t6 <-.8; t23<-.8; t40> .8;
   t7 <-.8; t24<-.8; t41> .8;
                                      t75> .8; !!!U7 !!!
   t8 <-.8; t25<-.8; t42> .8;
                                      t76> .8; !!!U8 !!!
   t9 <-.8; t26> .8; t43<-.8; t60> .8; t77> .8; !!!U9 !!!
   t10<-.8; t27> .8; t44<-.8; t61> .8; t78> .8; !!!U10!!!
   t11<-.8; t28> .8; t45<-.8; t62> .8; t79> .8; !!!U11!!!
   t12<-.8; t29> .8; t46<-.8; t63<-.8; t80> .8; !!!U12!!!
   t13<-.8; t30> .8; t47<-.8; t64<-.8; t81> .8; !!!U13!!!
   t14<-.8; t31> .8; t48<-.8; t65<-.8; t82> .8; !!!U14!!!
   t15<-.8; t32> .8; t49<-.8; t66> .8; t83> .8; !!!U15!!!
   t16<-.8; t33> .8; t50<-.8; t67> .8; t84> .8; !!!U16!!!
   t17<-.8; t34> .8; t51<-.8; t68> .8; t85> .8; !!!U17!!!
       EQUALITY (& INEQUALITY) CONSTRAINTS !!!
111
 ! C1vC2 | C3vC4 | C4vC5 !
  !____!
           t35=-t52; !!!U1 !!!
            t36=-t53;
                              !!!U2 !!!
            t37=-t54;
                             !!!U3 !!!
            t38=-t55:
                             !!!U4 !!!
                              !!!U5 !!!
            t39=-t56;
            t40=-t57:
                              !!!U6 !!!
            t41=-t58;
                              !!!U7 !!!
            t42=-t59;
                              !!! 8U!!!
                              !!!U9 !!!
  t9 = -t26;
  t10=-t27;
                               !!!U10!!!
  t11=-t28;
                              !!!U11!!!
                    t63=-t80; !!!U12!!!
  t12=-t29;
  t13=-t30;
                    t64=-t81; !!!U13!!!
                    t65=-t82; !!!U14!!!
  t14=-t31;
  t15=-t32;
                              !!!\U15!!!
  t16=-t33;
                               !!!U16!!!
  t17=-t34;
                               !!!U17!!!
```

Step 3: Compare model fit

Conduct the Sattorra-Bentler adjusted Log Likelihood Ratio (LRT) difference test:

- Baseline model (parent): Unconstrained.out is the 'un-constrained model" with 89 parameters.
- Confirmatory model (nested): Hypothesis.CLCA.out is the "constrained model" with 69 parameters.

```
hypothesized_models <- readModels(here("C3-Hypothesized"), quiet = TRUE)
```

```
\#*0 = null or nested model & *1 = comparison or parent model
# Log Likelihood Values
LO <- hypothesized_models[["Hypothesis.CLCA.out"]][["summaries"]][["LL"]]
L1 <- hypothesized_models[["Unconstrained.out"]][["summaries"]][["LL"]]
# LRT equation
lr \leftarrow -2 * (L0 - L1)
# Parameters
p0 <- hypothesized_models[["Hypothesis.CLCA.out"]][["summaries"]][["Parameters"]]
p1 <- hypothesized_models[["Unconstrained.out"]][["summaries"]][["Parameters"]]
# Scaling Correction Factors
c0 <- hypothesized_models[["Hypothesis.CLCA.out"]][["summaries"]][["LLCorrectionFactor"]]</pre>
c1 <- hypothesized_models[["Unconstrained.out"]][["summaries"]][["LLCorrectionFactor"]]</pre>
# Difference Test Scaling correction (Sattorra-Bentler adjustment)
cd \leftarrow ((p0 * c0) - (p1 * c1))/(p0 - p1)
# Chi-square difference test(TRd)
TRd <- (lr)/(cd)
```

```
# Degrees of freedom
df <- abs(p0 - p1)

# Significance test
(p_diff <- pchisq(TRd, df, lower.tail = FALSE))</pre>
```

[1] 0

RESULT: The Log Likelihood χ^2 difference test comparing the Baseline and Hypothesized LCA models was, $\chi^2(20) = 2929.14, p < .001$. See Reference Here

Compare model fit summary statistics: Unconstrained and Hypothesized

Calculate indices derived from the Log Likelihood (LL)

Format fit table

```
allFit %>%
  gt() %>%
  tab_header(title = md("**Model Fit Comparision Table**"), subtitle = md(" ")) %>%
  cols_label(Title = "Model", Parameters = md("Par"), LL = md("*LL*"), BIC = md("BIC"),
        aBIC = md("aBIC")) %>%
  tab_footnote(footnote = md("*Note.* Par = Parameters; *LL* = model log likelihood;
  BIC = Bayesian information criterion; aBIC = sample size adjusted BIC."),
        locations = cells_title()) %>%
  tab_options(column_labels.font.weight = "bold")
```

Model Fit Comparision Table¹

Model	Par	LL	BIC	aBIC
Unconstrained Model	89	-52601.37	105977.0	105694.2
Hypothesized Model	69	-54038.40	108677.1	108457.8

 $^1Note.$ Par = Parameters; LL= model log likelihood; BIC = Bayesian information criterion; aBIC = sample size adjusted BIC.