B TREES (DBns)

- Self Balancing Trees
- In search trees like binary search tree, AVL Tree, Red-Black tree, etc., every node contains only one value (key) and a maximum of two children.
- But there is a special type of search tree called B-Tree in which a node contains more than one value (key) and more than two children.
- B-Tree was developed in the year 1972 by Bayer and McCreight with the name Height Balanced mway Search Tree. Later it was named as B-Tree.

B-Tree is a self-balanced search tree in which every node contains multiple keys and has more than two children.

Here, the number of keys in a node and number of children for a node depends on the order of B-Tree. Every B-Tree has an order.

B-Tree of Order m has the following properties...

Property #1 - All leaf nodes must be at same level.

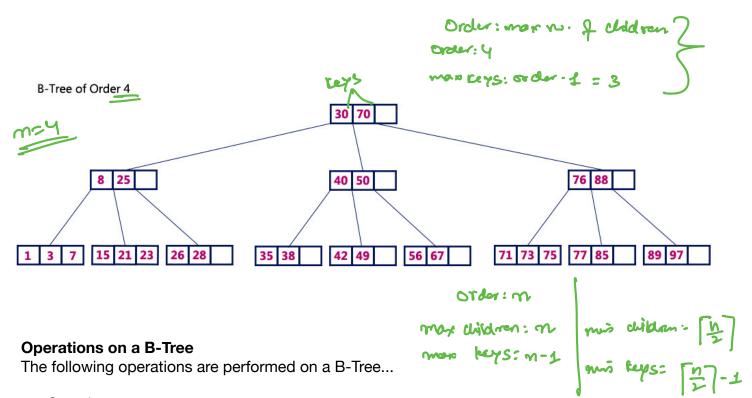
Property #2 - All nodes except root must have at least [m/2]-1 keys and maximum of m-1 keys.

Property #3 - All non leaf nodes except root (i.e. all internal nodes) must have at least m/2 children.

Property #4 - If the root node is a non leaf node, then it must have atleast 2 children.

Property #5 - A non leaf node with n-1 keys must have n number of children.

Property #6 - All the key values in a node must be in Ascending Order.



- 1. Search
- 2. Insertion
- 3. Deletion

Search Operation in B-Tree

The search operation in B-Tree is similar to the search operation in Binary Search Tree.

In a Binary search tree, the search process starts from the root node and we make a 2-way decision every time (we go to either left subtree or right subtree).

In B-Tree also search process starts from the root node but here we make an n-way decision every time, where 'n' is the total number of children the node has.

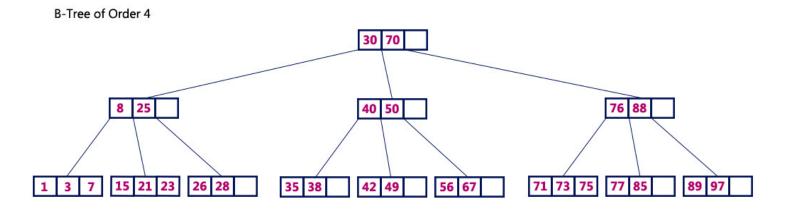
In a B-Tree, the search operation is performed with O(log n) time complexity.

The search operation is performed as follows...

- Step 1 Read the search element from the user.
- Step 2 Compare the search element with first key value of root node in the tree.
- Step 3 If both are matched, then display "Given node is found!!!" and terminate the function
- Step 4 If both are not matched, then check whether search element is smaller or larger than that key value.
- Step 5 If search element is smaller, then continue the search process in left subtree.
- Step 6 If search element is larger, then compare the search element with next key value in the same node and repeat steps 3, 4, 5 and 6 until we find the exact match or until the search element is compared with last key value in the leaf node.
- Step 7 If the last key value in the leaf node is also not matched then display "Element is not found" and terminate the function.

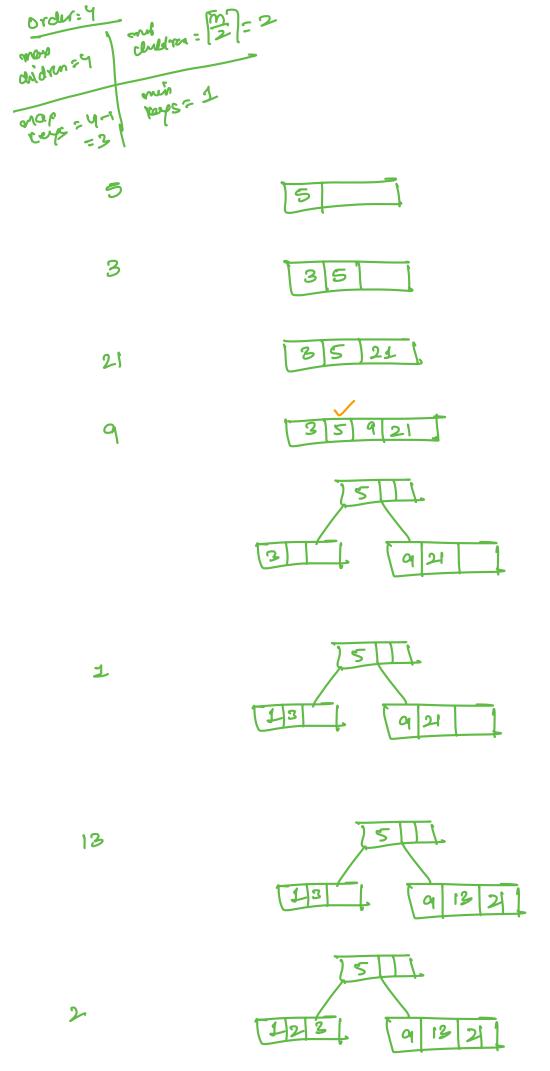
Insertion Operation in B-Tree

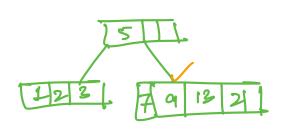
In a B-Tree, a new element must be added only at the leaf node. That means, the new keyValue is always

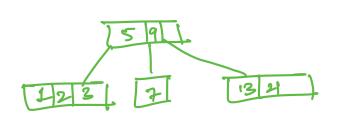


attached to the leaf node only. The insertion operation is performed as follows...

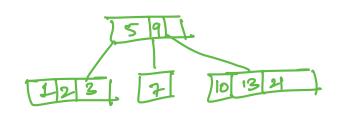
- Step 1 Check whether tree is Empty.
- Step 2 If tree is Empty, then create a new node with new key value and insert it into the tree as a root node.
- Step 3 If tree is Not Empty, then find the suitable leaf node to which the new key value is added using Binary Search Tree logic.
- Step 4 If that leaf node has empty position, add the new key value to that leaf node in ascending order of key value within the node.
- Step 5 If that leaf node is already full, split that leaf node by sending middle value to its parent node. Repeat the same until the sending value is fixed into a node.
- Step 6 If the splitting is performed at root node then the middle value becomes new root node for the tree and the height of the tree is increased by one.

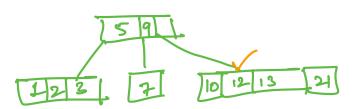


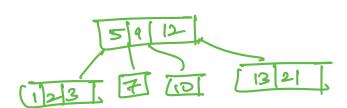


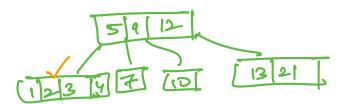


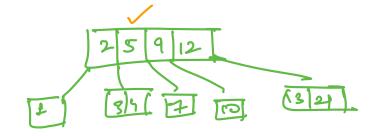
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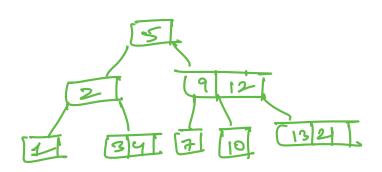




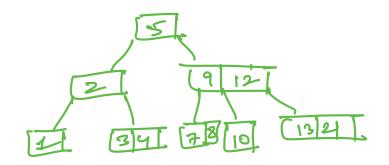






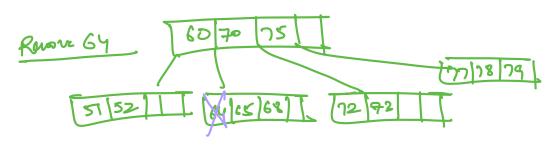


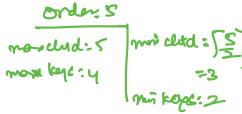
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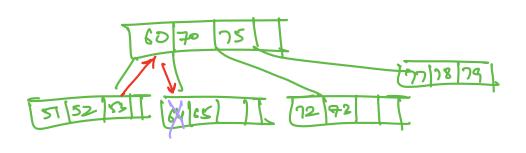
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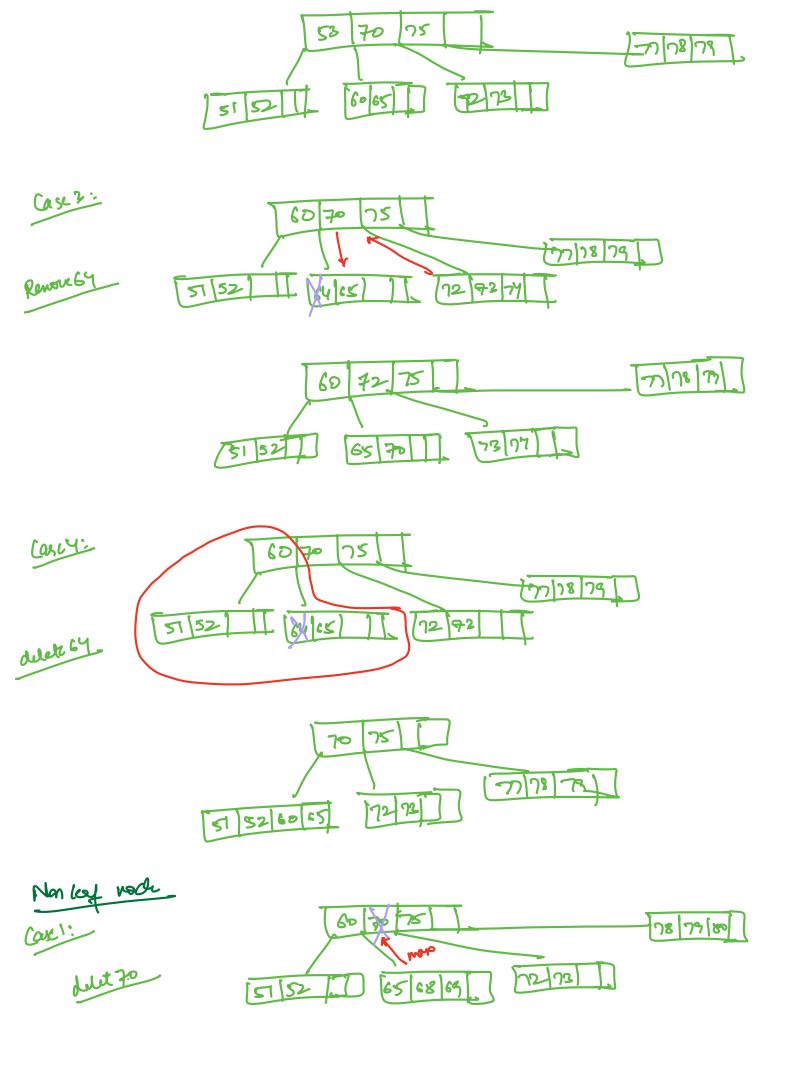


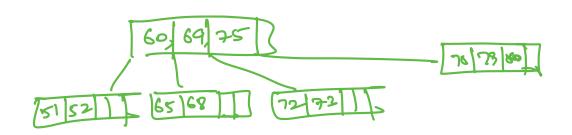


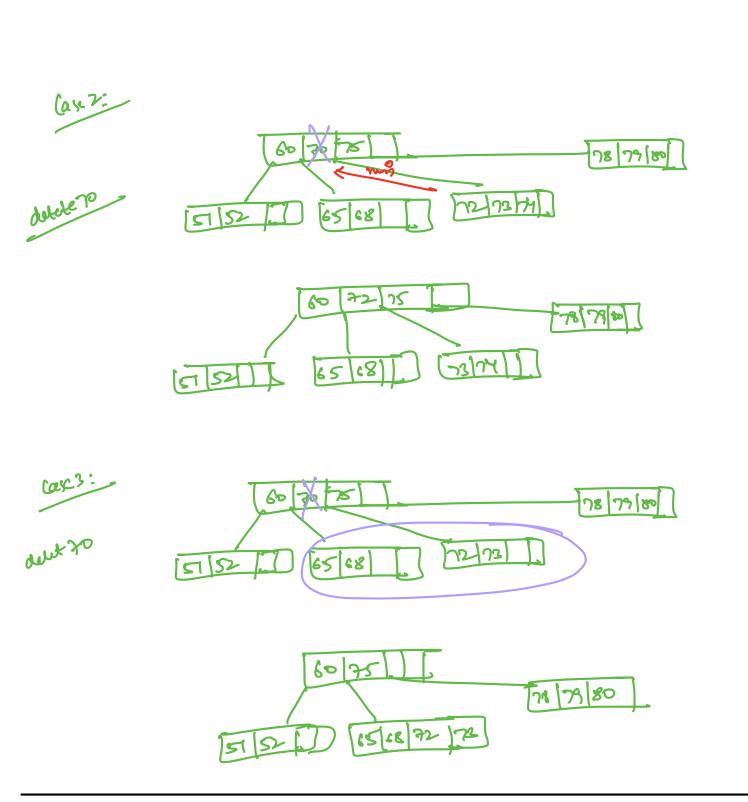
Case 7:



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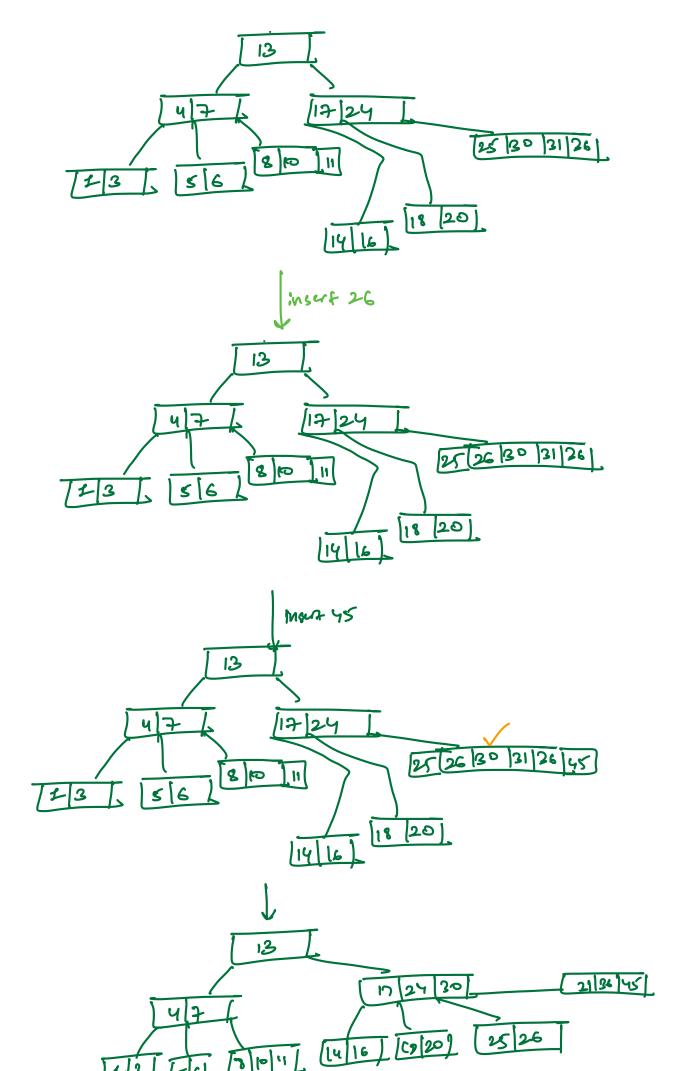




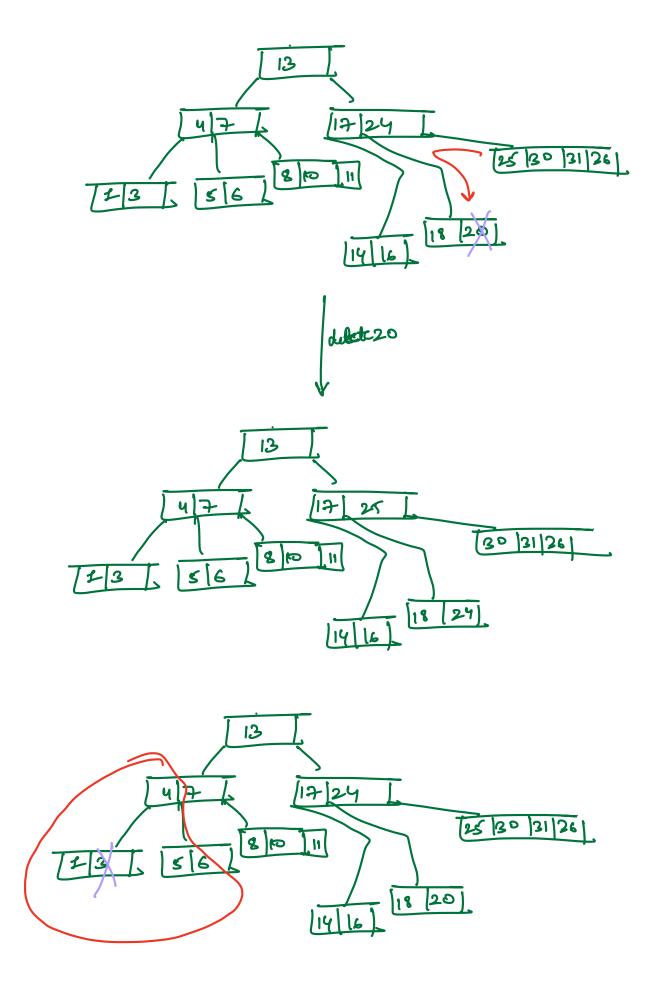
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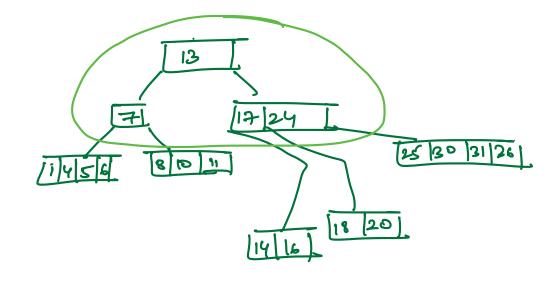
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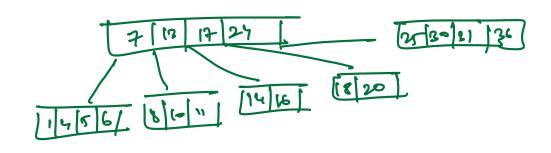
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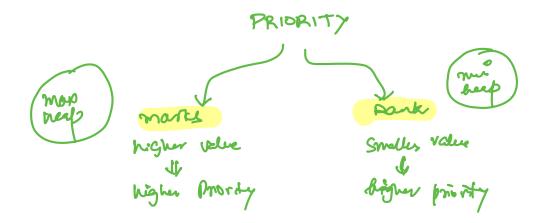
Heep ? Graper (Hashvig)

HEAP PRIDRITY QUEUE

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(Dese)	0(m)	0(1)	9(1)	
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Heap?

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Paret Value > Child Value Paret Volu CChild Value

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Best + le olisid

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2 wild

Before starting a new level, previous levels should

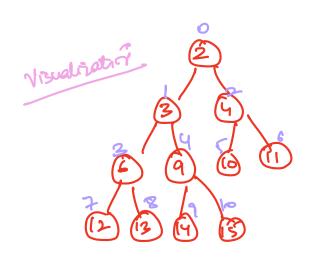
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20 30 X 10 X 10 X 20 30 X

nicuds. n-i levels completely filled Priority 100

Implementation

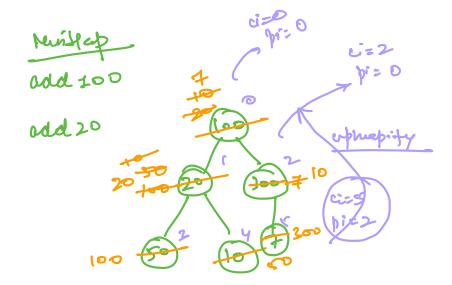
Exact Grape

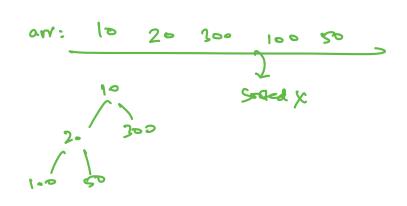


0 1	2	3	4	5	6	7	8	9	10	
23	4	6	9	9	15	12	13	14-	18	

$$\begin{vmatrix} p_1^n = 2 \\ l = 5 \\ r = 6 \end{vmatrix}$$

$$\begin{vmatrix} p_1^n \\ p_2^n \\ 2p_1 + 1 \\ p_2^n \\ p_1^n + 1 \end{vmatrix}$$









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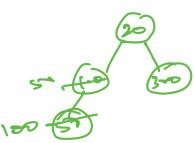
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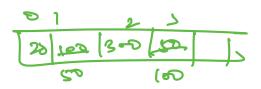
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20 poo 20 .

oad 50





odd P



