

Algorithmics SAT - Friendship Network Part 2

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Abstract

‘How can a tourist best spend their day out?’ I’ve been finding it hard to plan trips with my friends, especially when everybody lives all over the city and we would all like to travel together. This SAT project aims to model the Victorian public transport network and its proximity to friends’ houses, factoring in data about each individual to find the most efficient and effective traversals and pathways for us travelling to locations around Victoria.

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This section of the Algorithmics SAT focuses on a time complexity analysis of the solution in order to establish the efficiency of the algorithm and feasibility in the real world.

Throughout the analysis, note the following variables are used as shorthand: Let F = number of friends Let L = number of landmarks Let R = number of routes

Algorithm Pseudocode

The following is the final pseudocode reiterated from Part 1, namely for convenience while analysing, since multiple modifications were made to the initial pseudocode.

Let A = starting vertex Let B = ending vertex Let $S = \{P, Q, R\}$ or any other vertices to be visited along the way.
Let $C \in S$ (random node in S)

```
1 function main(  
2     friends: dictionary,  
3     landmarks: dictionary,  
4     routes: dictionary,  
5     timetable: dictionary  
6 ):  
7     // global variable declarations  
8     concession: bool = Ask the user "Do you posses a concession card?"  
9     holiday: bool = Ask the user "Is today a weekend or a holiday?"  
10    user_name: string = Ask the user to select a friend from friends dictionary  
11    selected_time = Ask the user what time they are leaving  
12  
13    cached_djk: dictionary = empty dictionary  
14    edge_lookup_matrix: matrix = |V| x |V| matrix that stores a list of edges in each entry  
15  
16    // get distance of all friends from landmarks  
17    friend_distances: dictionary = calculate_nodes(friends, landmarks)
```

```

18 visit_set: set = set of all closest nodes from friend_distances
19 people_at_nodes: dictionary = all friends sorted into keys of which nodes they are closest
    to, from visit_set
20
21 home: string = closest node of user_name
22
23 print all friends, where they live closest to and how far away
24
25 print out friends that would take more than 20 minutes to walk (average human walking
    speed is 5.1 km/h)
26
27 hamiltonian_path = held_karp(home, home, visit_set, selected_time)
28
29 print how much the trip would cost and how long it would take
30
31 print the path of the hamiltonian_path
32 end function

```

```

1 function calculate_nodes (
2     friend_data: dictionary,
3     node_data: dictionary
4 ):
5     for friend in friend_data:
6         home: tuple = friend['home']
7         // initial min vals that will be set to smallest iterated distance
8         min: float = infinity
9         min_node: node = null
10
11         for node in node_data:
12             location: tuple = node['coordinates']
13             // find real life distance (functional abstraction)
14             distance: float = latlong_distance(home, location)
15             if distance < min:
16                 min = distance
17                 min_node = node
18
19         distance_dict[friend]['min_node'] = min_node
20         distance_dict[friend]['distance'] = min
21 end function

```

```

1 function held_karp (
2     start: node,
3     end: node,
4     visit: set<node>,
5     current_time: datetime
6 ):
7     if visit.size = 0:
8         djik = dijkstras(start, end, current_time)
9         return djik['cost']
10    else:
11        min = infinity
12        For node C in set S:
13            sub_path = held_karp(start, C, (set \ C), current_time)
14            djik = dijkstras(C, end, current_time + toMinutes(sub_path['cost']))
15            cost = sub_path['cost'] + djik['cost']
16            if cost < min:
17                min = cost

```

```

18         return min
19 end function

1 function dijkstras (
2     start: node,
3     end: node,
4     current_time: datetime
5 ):
6     // Set all node distance to infinity
7     for node in graph:
8         distance[node] = infinity
9         predecessor[node] = null
10        unexplored_list.add(node)
11
12    // starting distance has to be 0
13    distance[start] = 0
14
15    // while more to still explore
16    while unexplored_list is not empty:
17        min_node = unexplored node with min cost
18        unexplored_list.remove(min_node)
19
20        // go through every neighbour and relax
21        for each neighbour of min_node:
22            current_dist = distance[min_node] + dist(min_node, neighbour, current_time +
23                to_minutes(distance[min_node]))
24            // a shorter path has been found to the neighbour -> relax value
25            if current_dist < distance[neighbour]:
26                distance[neighbour] = current_dist
27                predecessor[neighbour] = min_node
28
29    return distance[end]
30 end function

1 function dist (
2     start: node,
3     end: node,
4     current_time: datetime
5 ):
6     // if the start and end node are the same, it takes no time to get there
7     if start = end:
8         return 0
9     else if edges = null:
10        // if no edge exists between nodes
11        return infinity
12
13    edges = edge_lookup_matrix[start][end]
14    distances = []
15
16    // go over each possible edge between nodes (multiple possible)
17    for edge in edges:
18        line = edge.line
19        // next time bus/train will be at node (functional abstraction)
20        next_time = soonest_time_at_node(timetable, line, start, current_time)
21        wait_time = next_time - current_time
22        distances.add(edge.weight + wait_time)
23

```

```

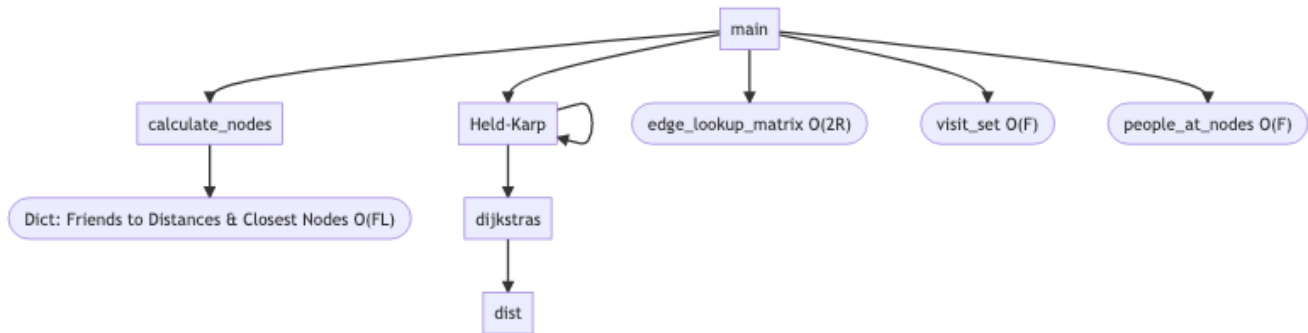
24     return min(distances)
25 end function

```

Expected Time Complexity

As explained in Part 1 of the SAT, the algorithm in essence boils down to an applied version of the Held–Karp algorithm, which has a time complexity of $O(n^2 2^n)$. Hence, it would make sense for our combination of Held–Karp and Dijkstra’s to result in a time complexity slightly larger.

Call Tree



As we can see, the main function calls a few distinct processes ¹:

1. First it creates the edge lookup matrix, which is abstracted in the pseudocode. This Big O time is derived from the Pythonic implementation of the lookup matrix as follows ²:

```

1 edge_lookup_matrix = {frozenset({edge['from'], edge['to']}): [] for edge in edges}
2 for edge in edges:
3     edge_lookup_matrix[frozenset({edge['from'], edge['to']})].append(edge)

```

Evidently, this loops over each edge in **edges** twice, resulting in a linear time complexity of $O(2R)$

2. It then calls **calculate_nodes** with an input of both **friends** and **landmarks**, the output of which is used to create our **visit_set**. This Big O time is derived from the fact that **calculate_nodes** is simply a nested for-loop, iterating over each friend and every landmark, resulting in a worst case time complexity of $O(F \times L)$.
3. It now uses the output of **calculate_nodes** (stored as **friend_distances**) to create a set of nodes we need to visit, which is abstracted in the pseudocode. This Big O time is derived from the Pythonic implementation of the set as follows:

```

1 visit_set = set(val['closest_node'] for key, val in friend_distances.items())

```

Evidently, this loops over each friend once, resulting in a linear time complexity of $O(F)$

4. Similar to the above implementation, the **main** function now creates **people_at_nodes** to create a dictionary of nodes and which people are closest to that node, with a similar $O(F)$ as above.

¹This analysis is done assuming that the time complexity of accessing a dictionary, list or array element is $O(1)$, as these basic pseudocode elements are generally done in constant time.

²Due to the nature of functional abstraction, the implementation of creating the **edge_lookup_matrix** is not specified in the pseudocode. Although it is referred to as a lookup matrix of size $|V| \times |V|$ which would have a quadratic time complexity, the pseudocode has actually been implemented as a dictionary in $O(2R)$ time, which is a bit more efficient. Nonetheless, even if it was changed to $O(L^2)$, it would make minimal difference to the final asymptotic time complexity.

5. Various other print statements are called, all with $O(F)$ time to display information about each friend.

6. Finally, after all this prep is done, `held_karp` is called to find the shortest hamiltonian path of the graph.

As we can see from this process and the call tree above, there are 3 main elements that contribute to the time complexity of our algorithm besides `held_karp`: 1. `calculate_nodes` which contributes $F \times L$ to our time. 2. Calculating the `edge_lookup_matrix`, which contributes $2R$ to our time complexity but simply turns into R when considering the asymptotic complexity. 3. Calculating the `visit_set`, `people_at_nodes` and two other print calls. This contributes $4F$ where 4 accounts for these 4 processes but could be any other arbitrary constant, as this simply turns into F when considering the asymptotic time complexity.

If we let the time complexity of `held_karp` be represented by $HK(n)$ where n denotes the calculated size of the `visit_set`, our current time complexity of the `main` function can be represented as $O(HK(n) + FL + R + F)$.

Held-Karp Time Complexity

Figuring out the time complexity of the other processes in our algorithm was relatively easy; we can simply look at their pseudocode implementation (or what they would be if they are abstracted) and look at the general number of operations. Held-Karp on the other hand is a bit harder as it is a recursive algorithm, making direct analysis a bit more troublesome. To begin, we can try to represent the modified Held-Karp algorithm as a recurrence relation to aid in mathematical analysis.

To recap, Held-Karp³ works by utilising the fact that every subpath of a path of minimum distance is itself of minimum distance. This means that we can reduce the length of S by one each time by finding the minimum distance/path between C and B while running Held-Karp again on the set S without C , but as C as the new value for B .

As stated in part 1, this logic can be represented recursively as the following:

Let $\text{Cost}_{A \rightarrow B, S}$ = The minimum cost of a cycle free path from A to B that visits all the vertices of S.

Let $d_{A, B}$ = The minimum cost of travelling from A to B, as outputted by Dijkstra's.

$\therefore \text{Cost}_{A \rightarrow B, S} = \min(\text{Cost}_{A \rightarrow C, S - \{B\}} + d_{CB})$

We can then turn this into a recurrence relation for Big O, where n is the size of the set S and $d(n)$ is the cost function, which in our case is Dijkstra's:

$$T_n = \begin{cases} n(T_{n-1} + d(n)) & n > 0 \\ d(n) & n = 0 \end{cases}$$

Now that we have a recurrence relation for Held-Karp in terms of the cost of running Dijkstra's, the next logical step is to find the number of operations required to run Dijkstra's every time (which would be in the worst case scenario where none of our previous calculations are reused).

Dijkstra's Time Complexity

We can analyse Dijkstra's step by step by viewing all the elements of the pseudocode and evaluating them separately and then add them up together at the end:

1. We can see that initial loop runs for every node, or L times, as each node represents a landmark.
2. In the main while loop, we iterate over every node in the graph, making the while loop run L times as well.
3. To find the `min_node`, the pseudocode iterates over every single node in the `unexplored_list`. As this list decreases by one each time, the total cost of finding the `min_node` can be represented as $L + (L - 1) + (L - 2) + \dots + 1 = \frac{L(L+1)}{2}$.

³The following variables will be used as shorthand throughout the analysis.

Let A = starting vertex

Let B = ending vertex

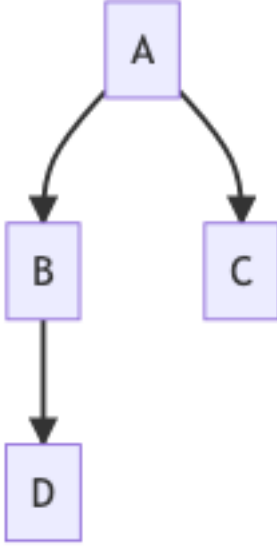
Let $S = \{P, Q, R\}$ or any other vertices to be visited along the way.

Let n = the length of the visit set S .

Let $C \in S$ (random node in S), and to clarify: $C \neq A, B$ as S does not include them

2) + \dots + 1 + 0. This resembles the triangular numbers, and hence we can also represent the total `min_node` cost as $\frac{L(L+1)}{2}$.

4. The nested for loop inside the while loop is a bit trickier as it covers all neighbours of the current `min_node`. As we have established that every single node in the graph will be the `min_node` at some point, we can use the graph below as an example for how many times this loop would occur. Over here, we can see that *A* has 2 neighbours, *B* has 2 neighbours, *C* has 1 neighbour and *D* has 1 neighbour. This makes it evident that the amount of times this inner for loop will run is actually just the sum of the degrees of the graph, and by the handshaking lemma, this is simply equal to twice the number of edges in the graph. Hence, the total amount of times this loop will run is $2R$.



5. Finally, inside this for loop, we call the `dist` function. As is evident from the pseudocode, this function uses the `edge_lookup_matrix` and goes over the edges between two nodes. In most practical cases, this will simply be one or two edges if multiple bus or train lines go across the same nodes. The `soonest_time_at_node` function is also an abstraction the next available bus/train time given any time at a particular node, which can possibly be implemented into a dictionary to be done in constant time. Due to these two factors, when looking at the asymptotic behaviour, this can be simplified to $O(1)$.

Now that we have considered all parts of our implementation of Dijkstra's, we can combine it to get a single cost function: $d(n) = L + L \left(\frac{L(L+1)}{2} + 2R \right) = 2LR + \frac{1}{2}L^3 + \frac{1}{2}L^2 + L$. Considering the behaviour of this function asymptotically, we can see that it would have a time complexity of $O(2LR + L^3)$, which is far from ideal and can be improved significantly (Dijkstra's can supposedly be done in $O(L + R \log L)$ with a min-priority queue).

Modified Held-Karp Time Complexity

Now that we have an established cost function, we can attempt to evaluate T_n in terms of $d(n)$. To reiterate:

$$T_n = \begin{cases} n(T_{n-1} + d(n)) & n > 0 \\ d(n) & n = 0 \end{cases}$$

$$d(n) = 2LR + \frac{1}{2}L^3 + \frac{1}{2}L^2 + L$$

Keeping this in terms of $d(n)$, we can create a table to see how this recurrence relation gets bigger as n increases.

n	0	1	2	3	4	5
T_n	$d(n)$	$2d(n)$	$6d(n)$	$21d(n)$	$88d(n)$	$445d(n)$

The working for this table is shown below, but you can easily keep going to follow the pattern for higher values of n :

$$n = 0: T_n = d(n)$$

$$n = 1: T_n = 1(T_0 + d(n)) = 2d(n)$$

$$n = 2: T_n = 2(T_1 + d(n)) = 6d(n)$$

$$n = 3: T_n = 3(T_2 + d(n)) = 21d(n)$$

$$n = 4: T_n = 4(T_3 + d(n)) = 88d(n)$$

$$n = 5: T_n = 5(T_4 + d(n)) = 445d(n)$$

Now we run into a bit of an issue. Just looking at the coefficients for a second, we have the recurrence relation $T_n = n(T_{n-1} + 1), T_0 = 1$. Looking all over the web for this, the only place I could find any reference to this sequence is [here](#), which provides us with the slightly horrendous formula of $T(n) = (n! + \text{floor}(e \times n!)) \times d(n)$.

A floor function here is definitely a bit wild, but I'm going to presume that as $n \rightarrow \infty$ the floor function would make no difference, and then $T(n) = n!(e + 1) \times d(n)$. Subbing in our known time complexity of $d(n)$, we get a final Big O of $O(n!(e + 1)(2LR + L^3))$ for the original implementation of our modified Held-Karp with no caching of its own Dijkstra's outputs.

We can verify that this is somewhat correct by intuition. If we look back at Part 1, we can get the time taken to run the unoptimised modified Held-Karp on our data with different n values. $(2LR + L^3)$ should be a constant for any particular graph, meaning that if our Big O time complexity is correct then execution time $\propto n!(e + 1)$.

n	$\frac{\text{execution time}}{n!(e+1)}$
5	3×10^{-5}
6	4×10^{-5}
7	3×10^{-5}
8	3×10^{-5}
9	3×10^{-5}

Note that $n < 5$ would be rather unreliable due to the decimal inaccuracy of my recorded execution times (4dp)

As we can see, this proportionality is fairly constant, so it would probably be safe to assume that the worst-case time complexity for the unoptimised modified Held-Karp algorithm would be $O(n!(e + 1)(2LR + L^3))$, or at least something pretty close to it.

Optimised Modified Held-Karp Time Complexity

As was established in part 1, this factorial time complexity is not nearly sufficient enough for real world applications. Not only is it simply worse than brute forcing it, it makes it so calculating the Hamiltonian path with just my own friend group takes a ludicrous amount of time.