

# **Smart Parking Availability System**

## **IoT-Based Project Plan Presentation (PPP)**

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**Goal:** Real car detection + live availability dashboard

# Problem Statement

- Students waste time driving through parking garages searching for open spots
- No clear visibility into availability before entering
- Results in:
  - Time loss
  - Traffic congestion
  - Frustration

# Project Goal

Build a **real, working** smart parking system that:

- Detects whether spots are occupied
- Sends occupancy data wirelessly to a server
- Displays availability in a web dashboard in near real-time

## What “Detection” Means in This Project

Parking availability will be determined using **real vehicle detection**.

- **Primary detection sensor:** Ultrasonic distance sensor (per spot)
- A spot is **Occupied** when the measured distance is below a threshold
- A spot is **Available** otherwise

# Hardware

From the provided kit/skeleton, the project can use:

- **ESP32-C6 (WiFi / BLE)**
- **Arduino Nano (controller)**
- **TMP102 (I2C temperature sensor) (optional add-on)**

For real parking detection, **ultrasonic sensors are required.**

# **Selected Approach**

## **Approach A: ESP32-C6 Direct (Simpler)**

Ultrasonic Sensor(s) → **ESP32-C6** → WiFi → Backend → Web UI

**Why:** fewer parts, simpler wiring, easier to scale.

## **Alternative Approach (If Needed)**

### **Approach B: Arduino + ESP32-C6**

Ultrasonic Sensor(s) → **Arduino Nano** → Serial (UART) → **ESP32-C6** → WiFi → Backend

**Why:** separates sensing/logic (Arduino) from networking (ESP32).

# How Ultrasonic Detection Works

1. Sensor measures distance from sensor to ground/vehicle
2. Arduino/ESP32 reads distance repeatedly
3. Apply rule:
  - If distance < threshold → **Occupied**
  - Else → **Available**

Threshold is calibrated during testing for the garage setup.

## Data Flow (End-to-End)

Ultrasonic Sensor → Microcontroller (ESP32/Arduno) → WiFi → API → Database → Dashboard

# Backend Overview (Node.js + Express)

- Receives sensor updates via REST API (HTTP)
- Validates incoming data
- Stores spot states + history
- Computes:
  - total spots
  - occupied count
  - available count

# Database Overview (MongoDB)

Collections (example):

- **spots**: spotId, currentStatus, lastSeen
- **readings**: spotId, distanceCm, occupied, timestamp

Why MongoDB:

- Flexible JSON structure
- Works well with time-series style data

## Frontend Overview (React)

Dashboard shows:

- Total available spots
- Occupied vs available
- Live updates (polling or WebSocket later)
- Simple, readable UI for quick decision-making

## Learning With AI (Project-Relevant Skills)

AI will be used as a learning + debugging assistant for:

- **C/C++ (Embedded Programming)**: sensor reading, timing, state logic
- **ESP32 Networking**: WiFi setup, HTTP requests, reliability retries
- **Node.js + Express**: building REST APIs, input validation, error handling
- **MongoDB**: schema design, queries, storing time-series data
- **React**: state management, rendering live spot status

## **Key Features**

1. Real vehicle detection using ultrasonic sensors
2. Occupancy classification (Occupied/Available)
3. Wireless transmission to server
4. API + database storage
5. Web dashboard for availability

# Milestones & Sprints

## Sprint 1 – Hardware + Local Detection

- Wire ultrasonic sensor(s)
- Read distance reliably
- Convert distance to occupied/available
- Calibrate thresholds

## **Sprint 2 – Connectivity + Backend**

- ESP32 sends data to server
- Build Express API endpoints
- Store data in MongoDB
- Verify end-to-end ingestion

## Sprint 3 – Dashboard + Integration

- Build React dashboard
- Display live status counts
- Integration testing (hardware → UI)
- Improve reliability + documentation

## Progress Tracking & Metrics

- GitHub commits (weekly)
- Hardware milestone completion
- Accuracy of occupancy classification
- Successful transmission rate
- End-to-end latency (sensor → dashboard)

# Risks & Mitigation

## Risks

- Sensor noise / false triggers
- WiFi drops / missed updates
- Scaling to multiple spots

## Mitigation

- Smoothing (moving average) + hysteresis thresholds
- Retry + heartbeat updates
- Start with 1–2 spots (MVP), then expand

## **PPP Readiness Statement**

- Real detection method selected (ultrasonic)
- Clear architecture + data flow defined
- Implementation plan with milestones prepared

# **Thank You**

Questions & Feedback Welcome