

## Starling Murmuration

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# Contents

<b>1</b>	<b>Starling Murmurations</b>	<b>1</b>
<b>2</b>	<b>Class Index</b>	<b>3</b>
2.1	Class List . . . . .	3
<b>3</b>	<b>File Index</b>	<b>5</b>
3.1	File List . . . . .	5
<b>4</b>	<b>Class Documentation</b>	<b>7</b>
4.1	boid Class Reference . . . . .	7
4.1.1	Constructor & Destructor Documentation . . . . .	8
4.1.1.1	boid() [1/3] . . . . .	8
4.1.1.2	boid() [2/3] . . . . .	8
4.1.1.3	boid() [3/3] . . . . .	8
4.1.2	Member Function Documentation . . . . .	8
4.1.2.1	boundPosition() . . . . .	8
4.1.2.2	getFlapStatus() . . . . .	8
4.1.2.3	getPosition() . . . . .	9
4.1.2.4	getPrevPosTime() . . . . .	9
4.1.2.5	getPrevVelocity() . . . . .	9
4.1.2.6	getVelocity() . . . . .	9
4.1.2.7	moveBoidToNewPos() . . . . .	9
4.1.2.8	rule1and2() . . . . .	9
4.1.2.9	rule3() . . . . .	9
4.1.2.10	setFlapStatus() . . . . .	9

4.1.2.11	<a href="#">setPosition()</a>	10
4.1.2.12	<a href="#">setPrevPosTime()</a>	10
4.1.2.13	<a href="#">setPrevVelocity()</a>	10
4.1.2.14	<a href="#">setSystem()</a>	10
4.1.2.15	<a href="#">setVelocity()</a>	10
4.1.2.16	<a href="#">strongWind()</a>	10
4.1.2.17	<a href="#">tendAwayFromPlace()</a>	10
4.1.2.18	<a href="#">tendToPlace()</a>	11
4.1.2.19	<a href="#">updateFlapStatus()</a>	11
4.1.3	<a href="#">Member Data Documentation</a>	11
4.1.3.1	<a href="#">flapStatus</a>	11
4.1.3.2	<a href="#">position</a>	11
4.1.3.3	<a href="#">prevPosTime</a>	11
4.1.3.4	<a href="#">prevVelocity</a>	11
4.1.3.5	<a href="#">sys</a>	11
4.1.3.6	<a href="#">velocity</a>	12
4.2	<a href="#">obstacle Class Reference</a>	12
4.2.1	<a href="#">Member Function Documentation</a>	12
4.2.1.1	<a href="#">boid() [1/2]</a>	13
4.2.1.2	<a href="#">boid() [2/2]</a>	13
4.2.1.3	<a href="#">boundPosition()</a>	13
4.2.1.4	<a href="#">getFlapStatus()</a>	13
4.2.1.5	<a href="#">getPosition()</a>	13
4.2.1.6	<a href="#">getPrevPosTime()</a>	13
4.2.1.7	<a href="#">getVelocity()</a>	13
4.2.1.8	<a href="#">limitVelocity()</a>	14
4.2.1.9	<a href="#">moveBoidToNewPos()</a>	14
4.2.1.10	<a href="#">operator()()</a>	14
4.2.1.11	<a href="#">rule1and2()</a>	14
4.2.1.12	<a href="#">rule3()</a>	14

4.2.1.13	setPosition()	14
4.2.1.14	setPrevPosTime()	14
4.2.1.15	setVelocity()	15
4.2.1.16	strongWind()	15
4.2.1.17	tendAwayFromPlace()	15
4.2.1.18	tendToPlace()	15
4.2.1.19	updateFlapStatus()	15
4.2.2	Member Data Documentation	15
4.2.2.1	flapStatus	15
4.2.2.2	position	15
4.2.2.3	prevPosTime	16
4.2.2.4	prevVelocity	16
4.2.2.5	velocity	16
4.3	predator Class Reference	16
4.3.1	Constructor & Destructor Documentation	17
4.3.1.1	predator() [1/3]	17
4.3.1.2	predator() [2/3]	17
4.3.1.3	predator() [3/3]	17
4.3.2	Member Function Documentation	17
4.3.2.1	boundPosition()	17
4.3.2.2	getFlapStatus()	18
4.3.2.3	getPosition()	18
4.3.2.4	getPrevPosTime()	18
4.3.2.5	getPrevVelocity()	18
4.3.2.6	getVelocity()	18
4.3.2.7	movePredatorToNewPos()	18
4.3.2.8	rule1()	18
4.3.2.9	rule3()	18
4.3.2.10	setFlapStatus()	19
4.3.2.11	setPosition()	19

4.3.2.12	setPrevPosTime()	19
4.3.2.13	setPrevVelocity()	19
4.3.2.14	setSystem()	19
4.3.2.15	setVelocity()	19
4.3.2.16	strongWind()	19
4.3.2.17	tendAwayFromPlace()	20
4.3.2.18	tendToPlace()	20
4.3.2.19	updateFlapStatus()	20
4.3.3	Member Data Documentation	20
4.3.3.1	flapStatus	20
4.3.3.2	position	20
4.3.3.3	prevPosTime	20
4.3.3.4	prevVelocity	20
4.3.3.5	sys	21
4.3.3.6	velocity	21
4.4	system Class Reference	21
4.4.1	Constructor & Destructor Documentation	22
4.4.1.1	system()	22
4.4.2	Member Function Documentation	22
4.4.2.1	addBoid() [1/4]	22
4.4.2.2	addBoid() [2/4]	22
4.4.2.3	addBoid() [3/4]	22
4.4.2.4	addBoid() [4/4]	23
4.4.2.5	addObstacle() [1/2]	23
4.4.2.6	addObstacle() [2/2]	23
4.4.2.7	addPredator() [1/4]	23
4.4.2.8	addPredator() [2/4]	23
4.4.2.9	addPredator() [3/4]	23
4.4.2.10	addPredator() [4/4]	23
4.4.2.11	findNearestBoid()	24

4.4.2.12	<a href="#">findNeighbouringBoids()</a> [1/2]	24
4.4.2.13	<a href="#">findNeighbouringBoids()</a> [2/2]	24
4.4.2.14	<a href="#">findObstaclesForPredator()</a>	24
4.4.2.15	<a href="#">findVeryCloseObjects()</a>	24
4.4.2.16	<a href="#">flock()</a>	24
4.4.2.17	<a href="#">getBoids()</a>	24
4.4.2.18	<a href="#">getNumBoids()</a>	25
4.4.2.19	<a href="#">getNumObstacles()</a>	25
4.4.2.20	<a href="#">getNumPredators()</a>	25
4.4.2.21	<a href="#">getObstacles()</a>	25
4.4.2.22	<a href="#">getPredators()</a>	25
4.4.2.23	<a href="#">getWind()</a>	25
4.4.2.24	<a href="#">getWindPresent()</a>	25
4.4.2.25	<a href="#">setNumBoids()</a>	25
4.4.2.26	<a href="#">setNumObstacles()</a>	26
4.4.2.27	<a href="#">setNumPredators()</a>	26
4.4.2.28	<a href="#">setWind()</a>	26
4.4.2.29	<a href="#">setWindPresent()</a>	26
4.4.2.30	<a href="#">startWithBoids()</a>	26
4.4.2.31	<a href="#">updateSystem()</a>	26
4.4.3	<a href="#">Member Data Documentation</a>	26
4.4.3.1	<a href="#">boids</a> [1/2]	27
4.4.3.2	<a href="#">boids</a> [2/2]	27
4.4.3.3	<a href="#">numBoids</a>	27
4.4.3.4	<a href="#">numObstacles</a>	27
4.4.3.5	<a href="#">numPredators</a>	27
4.4.3.6	<a href="#">obstacles</a> [1/2]	27
4.4.3.7	<a href="#">obstacles</a> [2/2]	27
4.4.3.8	<a href="#">predators</a> [1/2]	27
4.4.3.9	<a href="#">predators</a> [2/2]	28
4.4.3.10	<a href="#">wind</a>	28
4.4.3.11	<a href="#">windPresent</a>	28

<b>5</b>	<b>File Documentation</b>	<b>29</b>
5.1	/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/boid.h File Reference	29
5.1.1	Macro Definition Documentation	29
5.1.1.1	maxDistForRule1	29
5.2	/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/controls.h File Reference	29
5.2.1	Function Documentation	30
5.2.1.1	computeMatricesFromInputs()	30
5.2.1.2	getModelMatrix()	30
5.2.1.3	getProjectionMatrix()	30
5.2.1.4	getViewMatrix()	30
5.3	/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/flock.h File Reference	30
5.4	/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/obstacle.h File Reference	30
5.5	/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/params.h File Reference	31
5.5.1	Macro Definition Documentation	31
5.5.1.1	flapStates	31
5.5.1.2	maxSpeed	31
5.5.1.3	minDistance	32
5.5.1.4	minDistanceForObstacles	32
5.5.1.5	minDistanceForPredators	32
5.5.1.6	v1Mul	32
5.5.1.7	v2Mul	32
5.5.1.8	v3Mul	32
5.5.1.9	v4Mul	32
5.5.1.10	velocityDivision	32
5.5.1.11	vMul	33
5.5.1.12	xmax	33
5.5.1.13	xmin	33
5.5.1.14	ymax	33
5.5.1.15	ymin	33
5.5.1.16	zmax	33



5.5.1.17	<a href="#">zmin</a>	33
5.6	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/predator.h File Reference</a>	33
5.7	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/shader.h File Reference</a>	34
5.7.1	Function Documentation	34
5.7.1.1	<a href="#">LoadShaders()</a>	34
5.8	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/system.h File Reference</a>	34
5.9	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/README.md File Reference</a>	34
5.10	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/boid.cpp File Reference</a>	34
5.10.1	Function Documentation	35
5.10.1.1	<a href="#">compareFloats()</a>	35
5.10.1.2	<a href="#">limitVelocity()</a>	35
5.10.1.3	<a href="#">normalizeVelocity()</a>	35
5.10.1.4	<a href="#">printvec()</a>	35
5.11	<a href="#">/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/inout.cpp File Reference</a>	36
5.11.1	Function Documentation	37
5.11.1.1	<a href="#">computeRotationOfFrame()</a>	37
5.11.1.2	<a href="#">createBuffers()</a>	38
5.11.1.3	<a href="#">display()</a>	38
5.11.1.4	<a href="#">display_obstacle()</a>	38
5.11.1.5	<a href="#">endEverything()</a>	38
5.11.1.6	<a href="#">initializeEverything()</a>	38
5.11.1.7	<a href="#">initializeWindow()</a>	38
5.11.1.8	<a href="#">mouseButtonCallback()</a>	38
5.11.1.9	<a href="#">output()</a>	39
5.11.1.10	<a href="#">setObjectID()</a>	39
5.11.1.11	<a href="#">setShaders()</a>	39
5.11.2	Variable Documentation	39
5.11.2.1	<a href="#">allow</a>	39
5.11.2.2	<a href="#">angle_x</a>	39
5.11.2.3	<a href="#">angle_y</a>	39

5.11.2.4	boidColor	39
5.11.2.5	elementbuffer_flap	40
5.11.2.6	elementbuffer_obstacle	40
5.11.2.7	FoV	40
5.11.2.8	indices_flap	40
5.11.2.9	indices_obstacle	40
5.11.2.10	LightID	40
5.11.2.11	lightPos	40
5.11.2.12	MatrixID	40
5.11.2.13	MatrixID_lighting	41
5.11.2.14	ModelMatrixID	41
5.11.2.15	ModelMatrixID_lighting	41
5.11.2.16	normalbuffer_obstacle	41
5.11.2.17	normals_obstacle	41
5.11.2.18	obstacleColor	41
5.11.2.19	position	41
5.11.2.20	predatorColor	42
5.11.2.21	programID	42
5.11.2.22	programID_lighting	42
5.11.2.23	projectionMatrix	42
5.11.2.24	quit	42
5.11.2.25	rotationMatrixFrame	42
5.11.2.26	rotMatrix	42
5.11.2.27	scalingFactorID	42
5.11.2.28	scalingFactorID_lighting	43
5.11.2.29	Speed	43
5.11.2.30	sys	43
5.11.2.31	vertexbuffer_flap1	43
5.11.2.32	vertexbuffer_flap2	43
5.11.2.33	vertexbuffer_obstacle	43

5.11.2.34 vertexColorID . . . . .	43
5.11.2.35 vertexColorID_lighting . . . . .	43
5.11.2.36 vertexNormalID . . . . .	44
5.11.2.37 vertexPosID . . . . .	44
5.11.2.38 vertexPosID_ligthing . . . . .	44
5.11.2.39 vertices_flap1 . . . . .	44
5.11.2.40 vertices_flap2 . . . . .	44
5.11.2.41 vertices_obstacle . . . . .	44
5.11.2.42 viewMatrix . . . . .	45
5.11.2.43 ViewMatrixID . . . . .	45
5.11.2.44 ViewMatrixID_lighting . . . . .	45
5.11.2.45 window . . . . .	45
5.12 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/main.cpp File Reference . .	45
5.12.1 Function Documentation . . . . .	46
5.12.1.1 initializeEverything() . . . . .	46
5.12.1.2 main() . . . . .	46
5.12.1.3 mouseButtonCallback() . . . . .	46
5.12.1.4 output() . . . . .	46
5.12.1.5 print() . . . . .	46
5.12.2 Variable Documentation . . . . .	46
5.12.2.1 quit . . . . .	47
5.12.2.2 sys . . . . .	47
5.12.2.3 window . . . . .	47
5.13 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/predator.cpp File Reference	47
5.13.1 Function Documentation . . . . .	47
5.13.1.1 compareFloats() . . . . .	47
5.13.1.2 limitVelocity() . . . . .	48
5.13.1.3 normalizeVelocity() . . . . .	48
5.13.1.4 printvec() . . . . .	48
5.14 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/shader.cpp File Reference .	48
5.14.1 Function Documentation . . . . .	48
5.14.1.1 LoadShaders() . . . . .	48
5.15 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/system.cpp File Reference .	49
5.15.1 Function Documentation . . . . .	49
5.15.1.1 distance() . . . . .	49



# Chapter 1

## Starling Murmurations

The software structure is designed to simulate the motion of Starlings using C++. OpenGL is used for animation.

### Getting Started

#### Prerequisites

To install glew:

```
cd external/glew-1.13.0
make
sudo -s
make install
make clean
```

To install openGL:

```
cd external/glfw-3.1.2
mkdir build
cd build
cmake ..
make
sudo make install
```

To install glm:

```
cd external/glm-0.9.7.1
mkdir build
cd build
cmake ..
make
sudo make install
```

#### Installing

For Mac type:

```
make clean
make mac
```

For Linux type:

```
make clean
make linux
```

## Usage

To start the program type

```
./app <number of starlings to start with (Default 500)>
```

To add more boids to the screen, point at the desired position on the window and left click while pressing "B" on Keyboard. To add predators to the screen, point at the desired position on the window and left click while pressing "P" on Keyboard. To add still obstacles to the screen, point at the desired position on the window and left click while pressing "O" on Keyboard.

For rotating the frame of view, use the arrow keys.

## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">boid</a>	7
<a href="#">obstacle</a>	12
<a href="#">predator</a>	16
<a href="#">system</a>	21





## Chapter 3

# File Index

### 3.1 File List

Here is a list of all files with brief descriptions:

/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">boid.h</a> . . . . .	29
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">controls.h</a> . . . . .	29
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">flock.h</a> . . . . .	30
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">obstacle.h</a> . . . . .	30
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">params.h</a> . . . . .	31
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">predator.h</a> . . . . .	33
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">shader.h</a> . . . . .	34
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/ <a href="#">system.h</a> . . . . .	34
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">boid.cpp</a> . . . . .	34
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">inout.cpp</a> . . . . .	36
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">main.cpp</a> . . . . .	45
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">predator.cpp</a> . . . . .	47
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">shader.cpp</a> . . . . .	48
/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/ <a href="#">system.cpp</a> . . . . .	49



## Chapter 4

# Class Documentation

### 4.1 boid Class Reference

```
#include <boid.h>
```

#### Public Member Functions

- `boid` (class `system` \*)
- `boid` (vec3, class `system` \*)
- `boid` (vec3, vec3, class `system` \*)
- `pair< vec3, vec3 > rule1and2` ()
- `pair< vec3, vec3 > rule3` ()
- `vec3 strongWind` ()
- `vec3 tendToPlace` (vec3)
- `vec3 tendAwayFromPlace` ()
- `void moveBoidToNewPos` ()
- `vec3 boundPosition` (vec3)
- `vec3 getPosition` ()
- `void setPosition` (vec3)
- `vec3 getVelocity` ()
- `void setVelocity` (vec3)
- `vec3 getPrevVelocity` ()
- `void setPrevVelocity` (vec3)
- `long getPrevPosTime` ()
- `void setPrevPosTime` (long)
- `int getFlapStatus` ()
- `void setFlapStatus` (int)
- `int updateFlapStatus` ()
- `void setSystem` (class `system` \*)

#### Private Attributes

- `vec3 position`
- `vec3 velocity`
- `vec3 prevVelocity`
- `long prevPosTime`
- `int flapStatus`
- `class system * sys`

### 4.1.1 Constructor & Destructor Documentation

#### 4.1.1.1 `boid()` [1/3]

```
boid::boid (  
    class system * s )
```

#### 4.1.1.2 `boid()` [2/3]

```
boid::boid (  
    vec3 pos,  
    class system * s )
```

#### 4.1.1.3 `boid()` [3/3]

```
boid::boid (  
    vec3 pos,  
    vec3 vel,  
    class system * s )
```

### 4.1.2 Member Function Documentation

#### 4.1.2.1 `boundPosition()`

```
vec3 boid::boundPosition (  
    vec3 vel )
```

#### 4.1.2.2 `getFlapStatus()`

```
int boid::getFlapStatus ( )
```

#### 4.1.2.3 getPosition()

```
vec3 boid::getPosition ( )
```

#### 4.1.2.4 getPrevPosTime()

```
long boid::getPrevPosTime ( )
```

#### 4.1.2.5 getPrevVelocity()

```
vec3 boid::getPrevVelocity ( )
```

#### 4.1.2.6 getVelocity()

```
vec3 boid::getVelocity ( )
```

#### 4.1.2.7 moveBoidToNewPos()

```
void boid::moveBoidToNewPos ( )
```

#### 4.1.2.8 rule1and2()

```
pair< vec3, vec3 > boid::rule1and2 ( )
```

#### 4.1.2.9 rule3()

```
pair< vec3, vec3 > boid::rule3 ( )
```

#### 4.1.2.10 setFlapStatus()

```
void boid::setFlapStatus (
    int s )
```

**4.1.2.11 setPosition()**

```
void boid::setPosition (
    vec3 position )
```

**4.1.2.12 setPrevPosTime()**

```
void boid::setPrevPosTime (
    long prevPosTime )
```

**4.1.2.13 setPrevVelocity()**

```
void boid::setPrevVelocity (
    vec3 v )
```

**4.1.2.14 setSystem()**

```
void boid::setSystem (
    class system * s )
```

**4.1.2.15 setVelocity()**

```
void boid::setVelocity (
    vec3 velocity )
```

**4.1.2.16 strongWind()**

```
vec3 boid::strongWind ( )
```

**4.1.2.17 tendAwayFromPlace()**

```
vec3 boid::tendAwayFromPlace ( )
```

#### 4.1.2.18 tendToPlace()

```
vec3 boid::tendToPlace (
    vec3 place )
```

#### 4.1.2.19 updateFlapStatus()

```
int boid::updateFlapStatus ( )
```

### 4.1.3 Member Data Documentation

#### 4.1.3.1 flapStatus

```
int boid::flapStatus [private]
```

#### 4.1.3.2 position

```
vec3 boid::position [private]
```

#### 4.1.3.3 prevPosTime

```
long boid::prevPosTime [private]
```

#### 4.1.3.4 prevVelocity

```
vec3 boid::prevVelocity [private]
```

#### 4.1.3.5 sys

```
class system* boid::sys [private]
```

#### 4.1.3.6 velocity

```
vec3 boid::velocity [private]
```

The documentation for this class was generated from the following files:

- [/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/boid.h](#)
- [/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/boid.cpp](#)

## 4.2 obstacle Class Reference

```
#include <obstacle.h>
```

### Public Member Functions

- [boid](#) (vec3)
- [boid](#) (vec3, vec3)
- [operator\(\)](#) ()
- vec3 [rule1and2](#) ()
- vec3 [rule3](#) ()
- vec3 [strongWind](#) ()
- vec3 [tendToPlace](#) ()
- vec3 [tendAwayFromPlace](#) ()
- void [boundPosition](#) ()
- void [limitVelocity](#) ()
- void [moveBoidToNewPos](#) ()
- vec3 [getPosition](#) ()
- void [setPosition](#) (vec3)
- vec3 [getVelocity](#) ()
- void [setVelocity](#) (vec3)
- long [getPrevPosTime](#) ()
- void [setPrevPosTime](#) (long)
- int [getFlapStatus](#) ()
- int [updateFlapStatus](#) ()

### Private Attributes

- vec3 [position](#)
- vec3 [velocity](#)
- vec3 [prevVelocity](#)
- long [prevPosTime](#)
- int [flapStatus](#)

#### 4.2.1 Member Function Documentation



**4.2.1.1 boid()** [1/2]

```
obstacle::boid (
    vec3 )
```

**4.2.1.2 boid()** [2/2]

```
obstacle::boid (
    vec3 ,
    vec3 )
```

**4.2.1.3 boundPosition()**

```
void obstacle::boundPosition ( )
```

**4.2.1.4 getFlapStatus()**

```
int obstacle::getFlapStatus ( )
```

**4.2.1.5 getPosition()**

```
vec3 obstacle::getPosition ( )
```

**4.2.1.6 getPrevPosTime()**

```
long obstacle::getPrevPosTime ( )
```

**4.2.1.7 getVelocity()**

```
vec3 obstacle::getVelocity ( )
```

**4.2.1.8 limitVelocity()**

```
void obstacle::limitVelocity ( )
```

**4.2.1.9 moveBoidToNewPos()**

```
void obstacle::moveBoidToNewPos ( )
```

**4.2.1.10 operator()()**

```
obstacle::operator() ( )
```

**4.2.1.11 rule1and2()**

```
vec3 obstacle::rule1and2 ( )
```

**4.2.1.12 rule3()**

```
vec3 obstacle::rule3 ( )
```

**4.2.1.13 setPosition()**

```
void obstacle::setPosition (
    vec3 )
```

**4.2.1.14 setPrevPosTime()**

```
void obstacle::setPrevPosTime (
    long )
```

#### 4.2.1.15 setVelocity()

```
void obstacle::setVelocity (
    vec3 )
```

#### 4.2.1.16 strongWind()

```
vec3 obstacle::strongWind ( )
```

#### 4.2.1.17 tendAwayFromPlace()

```
vec3 obstacle::tendAwayFromPlace ( )
```

#### 4.2.1.18 tendToPlace()

```
vec3 obstacle::tendToPlace ( )
```

#### 4.2.1.19 updateFlapStatus()

```
int obstacle::updateFlapStatus ( )
```

### 4.2.2 Member Data Documentation

#### 4.2.2.1 flapStatus

```
int obstacle::flapStatus [private]
```

#### 4.2.2.2 position

```
vec3 obstacle::position [private]
```

#### 4.2.2.3 prevPosTime

```
long obstacle::prevPosTime [private]
```

#### 4.2.2.4 prevVelocity

```
vec3 obstacle::prevVelocity [private]
```

#### 4.2.2.5 velocity

```
vec3 obstacle::velocity [private]
```

The documentation for this class was generated from the following file:

- /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/[obstacle.h](#)

## 4.3 predator Class Reference

```
#include <predator.h>
```

### Public Member Functions

- [predator](#) (class [system](#) \*)
- [predator](#) (vec3, class [system](#) \*)
- [predator](#) (vec3, vec3, class [system](#) \*)
- vec3 [rule1](#) ()
- vec3 [rule3](#) ()
- vec3 [strongWind](#) ()
- vec3 [tendToPlace](#) (vec3)
- vec3 [tendAwayFromPlace](#) ()
- vec3 [boundPosition](#) (vec3)
- void [movePredatorToNewPos](#) ()
- vec3 [getPosition](#) ()
- void [setPosition](#) (vec3)
- vec3 [getVelocity](#) ()
- void [setVelocity](#) (vec3)
- vec3 [getPrevVelocity](#) ()
- void [setPrevVelocity](#) (vec3)
- long [getPrevPosTime](#) ()
- void [setPrevPosTime](#) (long)
- int [getFlapStatus](#) ()
- int [updateFlapStatus](#) ()
- void [setFlapStatus](#) (int)
- void [setSystem](#) (class [system](#) \*)

## Private Attributes

- `vec3` [position](#)
- `vec3` [velocity](#)
- `vec3` [prevVelocity](#)
- `long` [prevPosTime](#)
- `int` [flapStatus](#)
- `class` [system](#) \* `sys`

## 4.3.1 Constructor & Destructor Documentation

### 4.3.1.1 `predator()` [1/3]

```
predator::predator (  
    class system * s )
```

### 4.3.1.2 `predator()` [2/3]

```
predator::predator (  
    vec3 pos,  
    class system * s )
```

### 4.3.1.3 `predator()` [3/3]

```
predator::predator (  
    vec3 pos,  
    vec3 vel,  
    class system * s )
```

## 4.3.2 Member Function Documentation

### 4.3.2.1 `boundPosition()`

```
vec3 predator::boundPosition (  
    vec3 vel )
```

**4.3.2.2 getFlapStatus()**

```
int predator::getFlapStatus ( )
```

**4.3.2.3 getPosition()**

```
vec3 predator::getPosition ( )
```

**4.3.2.4 getPrevPosTime()**

```
long predator::getPrevPosTime ( )
```

**4.3.2.5 getPrevVelocity()**

```
vec3 predator::getPrevVelocity ( )
```

**4.3.2.6 getVelocity()**

```
vec3 predator::getVelocity ( )
```

**4.3.2.7 movePredatorToNewPos()**

```
void predator::movePredatorToNewPos ( )
```

**4.3.2.8 rule1()**

```
vec3 predator::rule1 ( )
```

**4.3.2.9 rule3()**

```
vec3 predator::rule3 ( )
```

#### 4.3.2.10 setFlapStatus()

```
void predator::setFlapStatus (
    int s )
```

#### 4.3.2.11 setPosition()

```
void predator::setPosition (
    vec3 position )
```

#### 4.3.2.12 setPrevPosTime()

```
void predator::setPrevPosTime (
    long prevPosTime )
```

#### 4.3.2.13 setPrevVelocity()

```
void predator::setPrevVelocity (
    vec3 v )
```

#### 4.3.2.14 setSystem()

```
void predator::setSystem (
    class system * s )
```

#### 4.3.2.15 setVelocity()

```
void predator::setVelocity (
    vec3 velocity )
```

#### 4.3.2.16 strongWind()

```
vec3 predator::strongWind ( )
```

#### 4.3.2.17 `tendAwayFromPlace()`

```
vec3 predator::tendAwayFromPlace ( )
```

#### 4.3.2.18 `tendToPlace()`

```
vec3 predator::tendToPlace (
    vec3 place )
```

#### 4.3.2.19 `updateFlapStatus()`

```
int predator::updateFlapStatus ( )
```

### 4.3.3 Member Data Documentation

#### 4.3.3.1 `flapStatus`

```
int predator::flapStatus [private]
```

#### 4.3.3.2 `position`

```
vec3 predator::position [private]
```

#### 4.3.3.3 `prevPosTime`

```
long predator::prevPosTime [private]
```

#### 4.3.3.4 `prevVelocity`

```
vec3 predator::prevVelocity [private]
```



## 4.3.3.5 sys

```
class system* predator::sys [private]
```

## 4.3.3.6 velocity

```
vec3 predator::velocity [private]
```

The documentation for this class was generated from the following files:

- /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/[predator.h](#)
- /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/[predator.cpp](#)

## 4.4 system Class Reference

```
#include <flock.h>
```

## Public Member Functions

- [flock](#) ()
- void [addBoid](#) ([boid](#))
- void [addPredator](#) ([predator](#))
- void [addObstacle](#) ([obstacle](#))
- vector< vector< [vec3](#) > > [findNeighbouringBoids](#) ([vec3](#))
- [system](#) ()
- void [addBoid](#) (class [boid](#))
- void [addBoid](#) ([vec3](#))
- void [addBoid](#) ([vec3](#), [vec3](#))
- void [addPredator](#) (class [predator](#))
- void [addPredator](#) ([vec3](#))
- void [addPredator](#) ([vec3](#), [vec3](#))
- void [addObstacle](#) ([vec3](#))
- vector< pair< [vec3](#), [vec3](#) > > [findNeighbouringBoids](#) ([vec3](#))
- pair< vector< pair< [vec3](#), [vec3](#) > >, vector< pair< [vec3](#), [vec3](#) > > > [findVeryCloseObjects](#) ([vec3](#))
- pair< [vec3](#), [vec3](#) > [findNearestBoid](#) ([vec3](#))
- pair< vector< pair< [vec3](#), [vec3](#) > >, vector< pair< [vec3](#), [vec3](#) > > > [findObstaclesForPredator](#) ([vec3](#))
- void [startWithBoids](#) (int)
- int [getNumBoids](#) ()
- void [setNumBoids](#) (int)
- int [getNumPredators](#) ()
- void [setNumPredators](#) (int)
- int [getNumObstacles](#) ()
- void [setNumObstacles](#) (int)
- void [updateSystem](#) ()
- vector< class [boid](#) > & [getBoids](#) ()
- vector< class [predator](#) > & [getPredators](#) ()
- vector< [vec3](#) > & [getObstacles](#) ()
- [vec3](#) [getWind](#) ()
- void [setWind](#) ([vec3](#))
- bool [getWindPresent](#) ()
- void [setWindPresent](#) (bool)

## Private Attributes

- vector< [boid](#) \* > [boids](#)
- vector< [predator](#) \* > [predators](#)
- vector< [obstacle](#) \* > [obstacles](#)
- vector< class [boid](#) > [boids](#)
- vector< class [predator](#) > [predators](#)
- vector< [vec3](#) > [obstacles](#)
- int [numBoids](#)
- int [numPredators](#)
- int [numObstacles](#)
- bool [windPresent](#)
- [vec3](#) [wind](#)

## 4.4.1 Constructor & Destructor Documentation

### 4.4.1.1 system()

```
system::system ( )
```

## 4.4.2 Member Function Documentation

### 4.4.2.1 addBoid() [1/4]

```
void system::addBoid (
    boid b )
```

### 4.4.2.2 addBoid() [2/4]

```
void system::addBoid (
    class boid )
```

### 4.4.2.3 addBoid() [3/4]

```
void system::addBoid (
    vec3 pos )
```

**4.4.2.4 addBoid()** [4/4]

```
void system::addBoid (
    vec3 pos,
    vec3 vel )
```

**4.4.2.5 addObstacle()** [1/2]

```
void system::addObstacle (
    obstacle )
```

**4.4.2.6 addObstacle()** [2/2]

```
void system::addObstacle (
    vec3 o )
```

**4.4.2.7 addPredator()** [1/4]

```
void system::addPredator (
    predator p )
```

**4.4.2.8 addPredator()** [2/4]

```
void system::addPredator (
    class predator )
```

**4.4.2.9 addPredator()** [3/4]

```
void system::addPredator (
    vec3 pos )
```

**4.4.2.10 addPredator()** [4/4]

```
void system::addPredator (
    vec3 pos,
    vec3 vel )
```

#### 4.4.2.11 findNearestBoid()

```
pair< vec3, vec3 > system::findNearestBoid (
    vec3 p )
```

#### 4.4.2.12 findNeighbouringBoids() [1/2]

```
vector< pair< vec3, vec3 > > system::findNeighbouringBoids (
    vec3 b )
```

#### 4.4.2.13 findNeighbouringBoids() [2/2]

```
vector<pair<vec3,vec3> > system::findNeighbouringBoids (
    vec3 b )
```

#### 4.4.2.14 findObstaclesForPredator()

```
pair< vector< pair< vec3, vec3 > >, vector< pair< vec3, vec3 > > > system::findObstacles↵
ForPredator (
    vec3 b )
```

#### 4.4.2.15 findVeryCloseObjects()

```
pair< vector< pair< vec3, vec3 > >, vector< pair< vec3, vec3 > > > system::findVeryClose↵
Objects (
    vec3 b )
```

#### 4.4.2.16 flock()

```
system::flock ( )
```

#### 4.4.2.17 getBoids()

```
vector< boid > & system::getBoids ( )
```

**4.4.2.18 getNumBoids()**

```
int system::getNumBoids ( )
```

**4.4.2.19 getNumObstacles()**

```
int system::getNumObstacles ( )
```

**4.4.2.20 getNumPredators()**

```
int system::getNumPredators ( )
```

**4.4.2.21 getObstacles()**

```
vector< vec3 > & system::getObstacles ( )
```

**4.4.2.22 getPredators()**

```
vector< class predator > & system::getPredators ( )
```

**4.4.2.23 getWind()**

```
vec3 system::getWind ( )
```

**4.4.2.24 getWindPresent()**

```
bool system::getWindPresent ( )
```

**4.4.2.25 setNumBoids()**

```
void system::setNumBoids (
    int n )
```

#### 4.4.2.26 setNumObstacles()

```
void system::setNumObstacles (
    int n )
```

#### 4.4.2.27 setNumPredators()

```
void system::setNumPredators (
    int n )
```

#### 4.4.2.28 setWind()

```
void system::setWind (
    vec3 w )
```

#### 4.4.2.29 setWindPresent()

```
void system::setWindPresent (
    bool wp )
```

#### 4.4.2.30 startWithBoids()

```
void system::startWithBoids (
    int n )
```

#### 4.4.2.31 updateSystem()

```
void system::updateSystem ( )
```

### 4.4.3 Member Data Documentation

**4.4.3.1 boids** [1/2]

```
vector<boid*> system::boids [private]
```

**4.4.3.2 boids** [2/2]

```
vector<class boid> system::boids [private]
```

**4.4.3.3 numBoids**

```
int system::numBoids [private]
```

**4.4.3.4 numObstacles**

```
int system::numObstacles [private]
```

**4.4.3.5 numPredators**

```
int system::numPredators [private]
```

**4.4.3.6 obstacles** [1/2]

```
vector<obstacle*> system::obstacles [private]
```

**4.4.3.7 obstacles** [2/2]

```
vector<vec3> system::obstacles [private]
```

**4.4.3.8 predators** [1/2]

```
vector<predator*> system::predators [private]
```

#### 4.4.3.9 predators [2/2]

```
vector<class predator> system::predators [private]
```

#### 4.4.3.10 wind

```
vec3 system::wind [private]
```

#### 4.4.3.11 windPresent

```
bool system::windPresent [private]
```

The documentation for this class was generated from the following files:

- [/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/flock.h](#)
- [/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/system.h](#)
- [/Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/system.cpp](#)



## Chapter 5

# File Documentation

### 5.1 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/boid.h File Reference

```
#include "params.h"
```

#### Classes

- class [boid](#)

#### Macros

- #define [maxDistForRule1](#) 0.2

#### 5.1.1 Macro Definition Documentation

##### 5.1.1.1 maxDistForRule1

```
#define maxDistForRule1 0.2
```

### 5.2 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/controls.h File Reference

#### Functions

- void [computeMatricesFromInputs](#) ()
- glm::mat4 [getViewMatrix](#) ()
- glm::mat4 [getProjectionMatrix](#) ()
- glm::mat4 [getModelMatrix](#) ()

## 5.2.1 Function Documentation

### 5.2.1.1 computeMatricesFromInputs()

```
void computeMatricesFromInputs ( )
```

### 5.2.1.2 getModelMatrix()

```
glm::mat4 getModelMatrix ( )
```

### 5.2.1.3 getProjectionMatrix()

```
glm::mat4 getProjectionMatrix ( )
```

### 5.2.1.4 getViewMatrix()

```
glm::mat4 getViewMatrix ( )
```

## 5.3 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/flock.h File Reference

### Classes

- class [system](#)

## 5.4 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/obstacle.h File Reference

### Classes

- class [obstacle](#)

## 5.5 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/params.h File Reference

```
#include <thread>
#include <bits/stdc++.h>
#include <unistd.h>
#include <vector>
#include <iostream>
#include <math.h>
#include <GL/glew.h>
#include <GLFW/glfw3.h>
#include <glm/glm.hpp>
#include <glm/gtc/matrix_transform.hpp>
#include <glm/gtx/vector_angle.hpp>
#include <glm/gtx/transform.hpp>
```

### Macros

- `#define xmin -2.4`
- `#define ymin -1.8`
- `#define zmin -2.4`
- `#define xmax 2.4`
- `#define ymax 1.8`
- `#define zmax 2.4`
- `#define maxSpeed 0.05`
- `#define minDistance 0.0235`
- `#define minDistanceForPredators 0.048`
- `#define minDistanceForObstacles 0.20`
- `#define flapStates 15`
- `#define velocityDivision (maxSpeed*3000000)`
- `#define vMul 5`
- `#define v1Mul 0.9`
- `#define v2Mul 0.9`
- `#define v3Mul 0.8`
- `#define v4Mul 1.7`

### 5.5.1 Macro Definition Documentation

#### 5.5.1.1 flapStates

```
#define flapStates 15
```

#### 5.5.1.2 maxSpeed

```
#define maxSpeed 0.05
```

#### 5.5.1.3 minDistance

```
#define minDistance 0.0235
```

#### 5.5.1.4 minDistanceForObstacles

```
#define minDistanceForObstacles 0.20
```

#### 5.5.1.5 minDistanceForPredators

```
#define minDistanceForPredators 0.048
```

#### 5.5.1.6 v1Mul

```
#define v1Mul 0.9
```

#### 5.5.1.7 v2Mul

```
#define v2Mul 0.9
```

#### 5.5.1.8 v3Mul

```
#define v3Mul 0.8
```

#### 5.5.1.9 v4Mul

```
#define v4Mul 1.7
```

#### 5.5.1.10 velocityDivision

```
#define velocityDivision (maxSpeed*3000000)
```

#### **5.5.1.11 vMul**

```
#define vMul 5
```

#### **5.5.1.12 xmax**

```
#define xmax 2.4
```

#### **5.5.1.13 xmin**

```
#define xmin -2.4
```

#### **5.5.1.14 ymax**

```
#define ymax 1.8
```

#### **5.5.1.15 ymin**

```
#define ymin -1.8
```

#### **5.5.1.16 zmax**

```
#define zmax 2.4
```

#### **5.5.1.17 zmin**

```
#define zmin -2.4
```

## **5.6 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/predator.h File Reference**

```
#include "params.h"
```

## Classes

- class [predator](#)

## 5.7 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/shader.h File Reference

### Functions

- GLuint [LoadShaders](#) (const char \*vertex\_file\_path, const char \*fragment\_file\_path)

#### 5.7.1 Function Documentation

##### 5.7.1.1 LoadShaders()

```
GLuint LoadShaders (
    const char * vertex_file_path,
    const char * fragment_file_path )
```

## 5.8 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/include/system.h File Reference

```
#include "params.h"
```

## Classes

- class [system](#)

## 5.9 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/README.md File Reference

## 5.10 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/boid.cpp File Reference

```
#include "boid.h"
#include "predator.h"
#include "system.h"
#include "params.h"
```

## Functions

- bool [compareFloats](#) (float A, float B)
- void [printvec](#) (vec3 vv)
- vec3 [limitVelocity](#) (vec3 v)
- vec3 [normalizeVelocity](#) (vec3 v)

### 5.10.1 Function Documentation

#### 5.10.1.1 [compareFloats\(\)](#)

```
bool compareFloats (  
    float A,  
    float B )
```

#### 5.10.1.2 [limitVelocity\(\)](#)

```
vec3 limitVelocity (  
    vec3 v )
```

#### 5.10.1.3 [normalizeVelocity\(\)](#)

```
vec3 normalizeVelocity (  
    vec3 v )
```

#### 5.10.1.4 [printvec\(\)](#)

```
void printvec (  
    vec3 vv )
```

## 5.11 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/inout.cpp File Reference

```
#include <GL/glew.h>
#include <GLFW/glfw3.h>
#include <glm/glm.hpp>
#include <glm/gtc/matrix_transform.hpp>
#include <glm/gtx/vector_angle.hpp>
#include <glm/gtx/transform.hpp>
#include "shader.h"
#include <unistd.h>
#include <vector>
#include <iostream>
#include <math.h>
#include "system.h"
#include "boid.h"
#include "params.h"
#include "predator.h"
```

### Functions

- glm::mat4 [computeRotationOffFrame](#) ()
- void [initializeWindow](#) ()
- void [setObjectID](#) ()
- void [createBuffers](#) ()
- void [setShaders](#) ()
- void [initializeEverything](#) ()
- void [endEverything](#) ()
- void [display](#) (GLuint vertex)
- void [display\\_obstacle](#) ()
- void [mouseButtonCallback](#) (GLFWwindow \*[window](#), int button, int action, int mods)
- void [output](#) (std::vector< [boid](#) > &boids, std::vector< [predator](#) > &predators, std::vector< glm::vec3 > &obstacles)

### Variables

- GLFWwindow \* [window](#)
- class [system](#) sys
- bool [quit](#)
- std::vector< glm::vec3 > [vertices\\_flap2](#) {glm::vec3(0,1.5,-0.102471),glm::vec3(-0.5,-0.5,-0.390471),glm::vec3(0.5,-0.5,-0.390471),glm::vec3(0,-0.5,0.475529),glm::vec3(0,-1.5,-0.102471),glm::vec3(1.4,0.5,1.0295),glm::vec3(1.77,0,1.1266),glm::vec3(1.77,0,1.0665),glm::vec3(-1.4,0.5,1.0295),glm::vec3(-1.77,0,1.1266),glm::vec3(-1.77,0,1.0295),glm::vec3(-0.0415631,0.75,0.0425294),glm::vec3(-0.150781,-0.25,0.142529),glm::vec3(-0.266067,-0.25,-0.0574706),glm::vec3(0.0415631,0.75,0.0425294),glm::vec3(0.150781,-0.25,0.142529),glm::vec3(0.266067,-0.25,-0.0574706)}
- std::vector< glm::vec3 > [vertices\\_flap1](#) {glm::vec3(0,1.5,-0.102471),glm::vec3(-0.5,-0.5,-0.390471),glm::vec3(0.5,-0.5,-0.390471),glm::vec3(0,-0.5,0.475529),glm::vec3(0,-1.5,-0.102471),glm::vec3(1.4,0.5,-0.944471),glm::vec3(1.77,0,-0.981471),glm::vec3(1.77,0,-1.18147),glm::vec3(-1.4,0.5,-0.944471),glm::vec3(-1.77,0,-0.981471),glm::vec3(-1.77,0,-1.18147),glm::vec3(-0.0415631,0.75,0.0425294),glm::vec3(-0.150781,-0.25,0.142529),glm::vec3(-0.266067,-0.25,-0.0574706),glm::vec3(0.0415631,0.75,0.0425294),glm::vec3(0.150781,-0.25,0.142529),glm::vec3(0.266067,-0.25,-0.0574706)}
- std::vector< uint16\_t > [indices\\_flap](#) {0,2,1,4,3,1,4,2,3,4,1,2,15,5,14,15,6,5,14,5,16,16,5,7,9,11,8,9,12,11,10,8,11,10,11,13,10,



- `std::vector< glm::vec3 > vertices_obstacle {glm::vec3(-1,-1,1),glm::vec3(1,-1,1),glm::vec3(1,1,1),glm::vec3(-1,1,1),glm::vec3(-1,-1,-1),glm::vec3(1,-1,-1),glm::vec3(1,1,-1),glm::vec3(-1,1,-1)}`
- `std::vector< uint16_t > indices_obstacle {0,1,3,3,1,2,2,1,5,2,5,6,3,2,7,7,2,6,3,7,4,3,4,0,0,4,1,4,5,1,4,7,6,5,4,6}`
- `std::vector< glm::vec3 > normals_obstacle {glm::vec3(-1,-1,1),glm::vec3(1,-1,1),glm::vec3(1,1,1),glm::vec3(-1,1,1),glm::vec3(-1,-1,-1),glm::vec3(1,-1,-1),glm::vec3(1,1,-1),glm::vec3(-1,1,-1)}`
- GLuint `vertexbuffer_flap2`
- GLuint `elementbuffer_flap`
- GLuint `vertexbuffer_flap1`
- GLuint `elementbuffer_obstacle`
- GLuint `vertexbuffer_obstacle`
- GLuint `normalbuffer_obstacle`
- GLuint `programID`
- GLuint `programID_lighting`
- GLuint `ModelMatrixID`
- GLuint `ModelMatrixID_lighting`
- GLuint `ViewMatrixID`
- GLuint `ViewMatrixID_lighting`
- GLuint `MatrixID`
- GLuint `MatrixID_lighting`
- GLuint `LightID`
- GLuint `vertexPosID`
- GLuint `vertexPosID_lighting`
- GLuint `vertexNormalID`
- GLuint `vertexColorID`
- GLuint `vertexColorID_lighting`
- GLuint `scalingFactorID`
- GLuint `scalingFactorID_lighting`
- glm::mat4 `viewMatrix`
- glm::mat4 `projectionMatrix`
- glm::mat4 `rotationMatrixFrame`
- float `FoV` = 45.0f
- glm::vec3 `position` = glm::vec3(0,0,5)
- glm::mat4 `rotMatrix` = glm::mat4(1.0f)
- float `angle_y` = 0.0f
- float `angle_x` = 0.0f
- float `Speed` = 0.01f
- bool `allow` = true
- glm::vec3 `lightPos` = glm::vec3(0,0,25)
- glm::vec3 `predatorColor` = glm::vec3(0.41,0.41,0.41)
- glm::vec3 `boidColor` = glm::vec3(0.078f,0.078f,0.078f)
- glm::vec3 `obstacleColor` = glm::vec3(0.277,0.56,0)

## 5.11.1 Function Documentation

### 5.11.1.1 computeRotationOfFrame()

```
glm::mat4 computeRotationOfFrame ( )
```

#### 5.11.1.2 createBuffers()

```
void createBuffers ( )
```

#### 5.11.1.3 display()

```
void display (
    GLuint vertex )
```

#### 5.11.1.4 display\_obstacle()

```
void display_obstacle ( )
```

#### 5.11.1.5 endEverything()

```
void endEverything ( )
```

#### 5.11.1.6 initializeEverything()

```
void initializeEverything ( )
```

#### 5.11.1.7 initializeWindow()

```
void initializeWindow ( )
```

#### 5.11.1.8 mouseButtonCallback()

```
void mouseButtonCallback (
    GLFWwindow * window,
    int button,
    int action,
    int mods )
```

#### 5.11.1.9 output()

```
void output (
    std::vector< boid > & boids,
    std::vector< predator > & predators,
    std::vector< glm::vec3 > & obstacles )
```

#### 5.11.1.10 setObjectID()

```
void setObjectID ( )
```

#### 5.11.1.11 setShaders()

```
void setShaders ( )
```

### 5.11.2 Variable Documentation

#### 5.11.2.1 allow

```
bool allow = true
```

#### 5.11.2.2 angle\_x

```
float angle_x = 0.0f
```

#### 5.11.2.3 angle\_y

```
float angle_y = 0.0f
```

#### 5.11.2.4 boidColor

```
glm::vec3 boidColor = glm::vec3(0.078f,0.078f,0.078f)
```

#### 5.11.2.5 elementbuffer\_flap

```
GLuint elementbuffer_flap
```

#### 5.11.2.6 elementbuffer\_obstacle

```
GLuint elementbuffer_obstacle
```

#### 5.11.2.7 FoV

```
float FoV = 45.0f
```

#### 5.11.2.8 indices\_flap

```
std::vector<uint16_t> indices_flap {0,2,1,4,3,1,4,2,3,4,1,2,15,5,14,15,6,5,14,5,16,16,5,7,9,11,8,9,12,11,10,8
```

#### 5.11.2.9 indices\_obstacle

```
std::vector<uint16_t> indices_obstacle {0,1,3,3,1,2,2,1,5,2,5,6,3,2,7,7,2,6,3,7,4,3,4,0,0,4,1,4,5,1,4,7,6,5,4
```

#### 5.11.2.10 LightID

```
GLuint LightID
```

#### 5.11.2.11 lightPos

```
glm::vec3 lightPos = glm::vec3(0,0,25)
```

#### 5.11.2.12 MatrixID

```
GLuint MatrixID
```

#### 5.11.2.13 MatrixID\_lighting

```
GLuint MatrixID_lighting
```

#### 5.11.2.14 ModelMatrixID

```
GLuint ModelMatrixID
```

#### 5.11.2.15 ModelMatrixID\_lighting

```
GLuint ModelMatrixID_lighting
```

#### 5.11.2.16 normalbuffer\_obstacle

```
GLuint normalbuffer_obstacle
```

#### 5.11.2.17 normals\_obstacle

```
std::vector<glm::vec3> normals_obstacle {glm::vec3(-1,-1,1),glm::vec3(1,-1,1),glm::vec3(1,1,1),glm↵  
::vec3(-1,1,1),glm::vec3(-1,-1,-1),glm::vec3(1,-1,-1),glm::vec3(1,1,-1),glm::vec3(-1,1,-1)}
```

#### 5.11.2.18 obstacleColor

```
glm::vec3 obstacleColor = glm::vec3(0.277,0.56,0)
```

#### 5.11.2.19 position

```
glm::vec3 position = glm::vec3(0,0,5)
```

**5.11.2.20 predatorColor**

```
glm::vec3 predatorColor = glm::vec3(0.41,0.41,0.41)
```

**5.11.2.21 programID**

```
GLuint programID
```

**5.11.2.22 programID\_lighting**

```
GLuint programID_lighting
```

**5.11.2.23 projectionMatrix**

```
glm::mat4 projectionMatrix
```

**5.11.2.24 quit**

```
bool quit
```

**5.11.2.25 rotationMatrixFrame**

```
glm::mat4 rotationMatrixFrame
```

**5.11.2.26 rotMatrix**

```
glm::mat4 rotMatrix = glm::mat4(1.0f)
```

**5.11.2.27 scalingFactorID**

```
GLuint scalingFactorID
```

**5.11.2.28 scalingFactorID\_lighting**

```
GLuint scalingFactorID_lighting
```

**5.11.2.29 Speed**

```
float Speed = 0.01f
```

**5.11.2.30 sys**

```
class system sys
```

**5.11.2.31 vertexbuffer\_flap1**

```
GLuint vertexbuffer_flap1
```

**5.11.2.32 vertexbuffer\_flap2**

```
GLuint vertexbuffer_flap2
```

**5.11.2.33 vertexbuffer\_obstacle**

```
GLuint vertexbuffer_obstacle
```

**5.11.2.34 vertexColorID**

```
GLuint vertexColorID
```

**5.11.2.35 vertexColorID\_lighting**

```
GLuint vertexColorID_lighting
```

**5.11.2.36 vertexNormalID**

```
GLuint vertexNormalID
```

**5.11.2.37 vertexPosID**

```
GLuint vertexPosID
```

**5.11.2.38 vertexPosID\_ligthing**

```
GLuint vertexPosID_ligthing
```

**5.11.2.39 vertices\_flap1**

```
std::vector<glm::vec3> vertices_flap1 {glm::vec3(0,1.5,-0.102471),glm::vec3(-0.5,-0.5,-0.↵
390471),glm::vec3(0.5,-0.5,-0.390471),glm::vec3(0,-0.5,0.475529),glm::vec3(0,-1.5,-0.102471),glm↵
::vec3(1.4,0.5,-0.944471),glm::vec3(1.77,0,-0.981471),glm::vec3(1.77,0,-1.18147),glm::vec3(-1.↵
4,0.5,-0.944471),glm::vec3(-1.77,0,-0.981471),glm::vec3(-1.77,0,-1.18147),glm::vec3(-0.↵
0415631,0.75,0.0425294),glm::vec3(-0.150781,-0.25,0.142529),glm::vec3(-0.266067,-0.25,-0.↵
0574706),glm::vec3(0.0415631,0.75,0.0425294),glm::vec3(0.150781,-0.25,0.142529),glm::vec3(0.↵
266067,-0.25,-0.0574706)}
```

**5.11.2.40 vertices\_flap2**

```
std::vector<glm::vec3> vertices_flap2 {glm::vec3(0,1.5,-0.102471),glm::vec3(-0.5,-0.5,-0.↵
390471),glm::vec3(0.5,-0.5,-0.390471),glm::vec3(0,-0.5,0.475529),glm::vec3(0,-1.5,-0.102471),glm↵
::vec3(1.4,0.5,1.0295),glm::vec3(1.77,0,1.1266),glm::vec3(1.77,0,1.0665),glm::vec3(-1.4,0.↵
5,1.0295),glm::vec3(-1.77,0,1.1266),glm::vec3(-1.77,0,1.0295),glm::vec3(-0.0415631,0.75,0.↵
0425294),glm::vec3(-0.150781,-0.25,0.142529),glm::vec3(-0.266067,-0.25,-0.0574706),glm::vec3(0.↵
0415631,0.75,0.0425294),glm::vec3(0.150781,-0.25,0.142529),glm::vec3(0.266067,-0.25,-0.↵
0574706)}
```

**5.11.2.41 vertices\_obstacle**

```
std::vector<glm::vec3> vertices_obstacle {glm::vec3(-1,-1,1),glm::vec3(1,-1,1),glm::vec3(1,1,1),glm↵
::vec3(-1,1,1),glm::vec3(-1,-1,-1),glm::vec3(1,-1,-1),glm::vec3(1,1,-1),glm::vec3(-1,1,-1)}
```



#### 5.11.2.42 viewMatrix

```
glm::mat4 viewMatrix
```

#### 5.11.2.43 ViewMatrixID

```
GLuint ViewMatrixID
```

#### 5.11.2.44 ViewMatrixID\_lighting

```
GLuint ViewMatrixID_lighting
```

#### 5.11.2.45 window

```
GLFWwindow* window
```

## 5.12 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/main.cpp File Reference

```
#include <iostream>
#include "system.h"
#include <chrono>
#include "boid.h"
#include "predator.h"
#include <glm/glm.hpp>
#include <stdlib.h>
```

### Functions

- void `output` (std::vector< `boid` > &, std::vector< `predator` > &, std::vector< glm::vec3 > &)
- void `initializeEverything` ()
- void `mouseButtonCallback` (GLFWwindow \*, int, int, int)
- void `print` (string)
- int `main` (int argc, char \*argv[])

### Variables

- GLFWwindow \* `window`
- bool `quit` = false
- class `system` `sys`

## 5.12.1 Function Documentation

### 5.12.1.1 initializeEverything()

```
void initializeEverything ( )
```

### 5.12.1.2 main()

```
int main (
    int argc,
    char * argv[ ] )
```

### 5.12.1.3 mouseButtonCallback()

```
void mouseButtonCallback (
    GLFWwindow * ,
    int ,
    int ,
    int )
```

### 5.12.1.4 output()

```
void output (
    std::vector< boid > & ,
    std::vector< predator > & ,
    std::vector< glm::vec3 > & )
```

### 5.12.1.5 print()

```
void print (
    string )
```

## 5.12.2 Variable Documentation

#### 5.12.2.1 quit

```
bool quit = false
```

#### 5.12.2.2 sys

```
class system sys
```

#### 5.12.2.3 window

```
GLFWwindow* window
```

## 5.13 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/predator.cpp File Reference

```
#include "boid.h"  
#include "predator.h"  
#include "system.h"  
#include "params.h"
```

### Functions

- bool [compareFloats](#) (float, float)
- void [printvec](#) (vec3)
- vec3 [limitVelocity](#) (vec3)
- vec3 [normalizeVelocity](#) (vec3)

### 5.13.1 Function Documentation

#### 5.13.1.1 compareFloats()

```
bool compareFloats (  
    float ,  
    float )
```

#### 5.13.1.2 limitVelocity()

```
vec3 limitVelocity (
    vec3 )
```

#### 5.13.1.3 normalizeVelocity()

```
vec3 normalizeVelocity (
    vec3 )
```

#### 5.13.1.4 printvec()

```
void printvec (
    vec3 )
```

### 5.14 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/shader.cpp File Reference

```
#include <stdio.h>
#include <string>
#include <vector>
#include <iostream>
#include <fstream>
#include <algorithm>
#include <sstream>
#include <stdlib.h>
#include <string.h>
#include <GL/glew.h>
#include "shader.h"
```

#### Functions

- GLuint [LoadShaders](#) (const char \*vertex\_file\_path, const char \*fragment\_file\_path)

#### 5.14.1 Function Documentation

##### 5.14.1.1 LoadShaders()

```
GLuint LoadShaders (
    const char * vertex_file_path,
    const char * fragment_file_path )
```

## 5.15 /Users/madhur/Documents/Sem 6/COP290/Assignment 2/git/Code/src/system.cpp File Reference

```
#include "system.h"
#include "boid.h"
#include "predator.h"
```

### Functions

- float [distance](#) (vec3 a, vec3 b)

#### 5.15.1 Function Documentation

##### 5.15.1.1 distance()

```
float distance (
    vec3 a,
    vec3 b )
```



# Index

/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/README.md, [34](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/boid.h, [29](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/controls.h, [29](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/flock.h, [30](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/obstacle.h, [30](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/params.h, [31](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/predator.h, [33](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/shader.h, [34](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/include/system.h, [34](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/boid.cpp, [34](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/inout.cpp, [36](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/main.cpp, [45](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/predator.cpp, [47](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/shader.cpp, [48](#)  
/Users/madhur/Documents/Sem 6/COP290/Assignment  
2/git/Code/src/system.cpp, [49](#)

addBoid  
    system, [22](#)  
addObstacle  
    system, [23](#)  
addPredator  
    system, [23](#)  
allow  
    inout.cpp, [39](#)  
angle\_x  
    inout.cpp, [39](#)  
angle\_y  
    inout.cpp, [39](#)  
boid, [7](#)  
    boid, [8](#)  
    boundPosition, [8](#)  
    flapStatus, [11](#)  
    getFlapStatus, [8](#)  
    getPosition, [8](#)  
    getPrevPosTime, [9](#)  
    getPrevVelocity, [9](#)  
    getVelocity, [9](#)  
    moveBoidToNewPos, [9](#)  
    obstacle, [12](#), [13](#)  
    position, [11](#)  
    prevPosTime, [11](#)  
    prevVelocity, [11](#)  
    rule1and2, [9](#)  
    rule3, [9](#)  
    setFlapStatus, [9](#)  
    setPosition, [9](#)  
    setPrevPosTime, [10](#)  
    setPrevVelocity, [10](#)  
    setSystem, [10](#)  
    setVelocity, [10](#)  
    strongWind, [10](#)  
    sys, [11](#)  
    tendAwayFromPlace, [10](#)  
    tendToPlace, [10](#)  
    updateFlapStatus, [11](#)  
    velocity, [11](#)  
boid.cpp  
    compareFloats, [35](#)  
    limitVelocity, [35](#)  
    normalizeVelocity, [35](#)  
    printvec, [35](#)  
boid.h  
    maxDistForRule1, [29](#)  
boidColor  
    inout.cpp, [39](#)  
boids  
    system, [26](#), [27](#)  
boundPosition  
    boid, [8](#)  
    obstacle, [13](#)  
    predator, [17](#)  
compareFloats  
    boid.cpp, [35](#)  
    predator.cpp, [47](#)  
computeMatricesFromInputs  
    controls.h, [30](#)  
computeRotationOfFrame  
    inout.cpp, [37](#)  
controls.h  
    computeMatricesFromInputs, [30](#)  
    getModelMatrix, [30](#)  
    getProjectionMatrix, [30](#)  
    getViewMatrix, [30](#)

- createBuffers
  - inout.cpp, 37
- display
  - inout.cpp, 38
- display\_obstacle
  - inout.cpp, 38
- distance
  - system.cpp, 49
- elementbuffer\_flap
  - inout.cpp, 39
- elementbuffer\_obstacle
  - inout.cpp, 40
- endEverything
  - inout.cpp, 38
- findNearestBoid
  - system, 23
- findNeighbouringBoids
  - system, 24
- findObstaclesForPredator
  - system, 24
- findVeryCloseObjects
  - system, 24
- flapStates
  - params.h, 31
- flapStatus
  - boid, 11
  - obstacle, 15
  - predator, 20
- flock
  - system, 24
- FoV
  - inout.cpp, 40
- getBoids
  - system, 24
- getFlapStatus
  - boid, 8
  - obstacle, 13
  - predator, 17
- getModelMatrix
  - controls.h, 30
- getNumBoids
  - system, 24
- getNumObstacles
  - system, 25
- getNumPredators
  - system, 25
- getObstacles
  - system, 25
- getPosition
  - boid, 8
  - obstacle, 13
  - predator, 18
- getPredators
  - system, 25
- getPrevPosTime
  - boid, 9
  - obstacle, 13
  - predator, 18
- getPrevVelocity
  - boid, 9
  - predator, 18
- getProjectionMatrix
  - controls.h, 30
- getVelocity
  - boid, 9
  - obstacle, 13
  - predator, 18
- getViewMatrix
  - controls.h, 30
- getWind
  - system, 25
- getWindPresent
  - system, 25
- indices\_flap
  - inout.cpp, 40
- indices\_obstacle
  - inout.cpp, 40
- initializeEverything
  - inout.cpp, 38
  - main.cpp, 46
- initializeWindow
  - inout.cpp, 38
- inout.cpp
  - allow, 39
  - angle\_x, 39
  - angle\_y, 39
  - boidColor, 39
  - computeRotationOfFrame, 37
  - createBuffers, 37
  - display, 38
  - display\_obstacle, 38
  - elementbuffer\_flap, 39
  - elementbuffer\_obstacle, 40
  - endEverything, 38
  - FoV, 40
  - indices\_flap, 40
  - indices\_obstacle, 40
  - initializeEverything, 38
  - initializeWindow, 38
  - LightID, 40
  - lightPos, 40
  - MatrixID\_lighting, 40
  - MatrixID, 40
  - ModelMatrixID\_lighting, 41
  - ModelMatrixID, 41
  - mouseButtonCallback, 38
  - normalbuffer\_obstacle, 41
  - normals\_obstacle, 41
  - obstacleColor, 41
  - output, 38
  - position, 41
  - predatorColor, 41
  - programID\_lighting, 42



- programID, [42](#)
  - projectionMatrix, [42](#)
  - quit, [42](#)
  - rotMatrix, [42](#)
  - rotationMatrixFrame, [42](#)
  - scalingFactorID\_lighting, [42](#)
  - scalingFactorID, [42](#)
  - setObjectID, [39](#)
  - setShaders, [39](#)
  - Speed, [43](#)
  - sys, [43](#)
  - vertexColorID\_lighting, [43](#)
  - vertexColorID, [43](#)
  - vertexNormalID, [43](#)
  - vertexPosID\_lighting, [44](#)
  - vertexPosID, [44](#)
  - vertexbuffer\_flap1, [43](#)
  - vertexbuffer\_flap2, [43](#)
  - vertexbuffer\_obstacle, [43](#)
  - vertices\_flap1, [44](#)
  - vertices\_flap2, [44](#)
  - vertices\_obstacle, [44](#)
  - viewMatrix, [44](#)
  - ViewMatrixID\_lighting, [45](#)
  - ViewMatrixID, [45](#)
  - window, [45](#)
- LightID
- inout.cpp, [40](#)
- lightPos
- inout.cpp, [40](#)
- limitVelocity
- boid.cpp, [35](#)
  - obstacle, [13](#)
  - predator.cpp, [47](#)
- LoadShaders
- shader.cpp, [48](#)
  - shader.h, [34](#)
- main
- main.cpp, [46](#)
- main.cpp
- initializeEverything, [46](#)
  - main, [46](#)
  - mouseButtonCallback, [46](#)
  - output, [46](#)
  - print, [46](#)
  - quit, [46](#)
  - sys, [47](#)
  - window, [47](#)
- MatrixID\_lighting
- inout.cpp, [40](#)
- MatrixID
- inout.cpp, [40](#)
- maxDistForRule1
- boid.h, [29](#)
- maxSpeed
- params.h, [31](#)
- minDistance
- params.h, [31](#)
- minDistanceForObstacles
- params.h, [32](#)
- minDistanceForPredators
- params.h, [32](#)
- ModelMatrixID\_lighting
- inout.cpp, [41](#)
- ModelMatrixID
- inout.cpp, [41](#)
- mouseButtonCallback
- inout.cpp, [38](#)
  - main.cpp, [46](#)
- moveBoidToNewPos
- boid, [9](#)
  - obstacle, [14](#)
- movePredatorToNewPos
- predator, [18](#)
- normalbuffer\_obstacle
- inout.cpp, [41](#)
- normalizeVelocity
- boid.cpp, [35](#)
  - predator.cpp, [48](#)
- normals\_obstacle
- inout.cpp, [41](#)
- numBoids
- system, [27](#)
- numObstacles
- system, [27](#)
- numPredators
- system, [27](#)
- obstacle, [12](#)
- boid, [12, 13](#)
  - boundPosition, [13](#)
  - flapStatus, [15](#)
  - getFlapStatus, [13](#)
  - getPosition, [13](#)
  - getPrevPosTime, [13](#)
  - getVelocity, [13](#)
  - limitVelocity, [13](#)
  - moveBoidToNewPos, [14](#)
  - operator(), [14](#)
  - position, [15](#)
  - prevPosTime, [15](#)
  - prevVelocity, [16](#)
  - rule1and2, [14](#)
  - rule3, [14](#)
  - setPosition, [14](#)
  - setPrevPosTime, [14](#)
  - setVelocity, [14](#)
  - strongWind, [15](#)
  - tendAwayFromPlace, [15](#)
  - tendToPlace, [15](#)
  - updateFlapStatus, [15](#)
  - velocity, [16](#)
- obstacleColor
- inout.cpp, [41](#)
- obstacles

- system, 27
- operator()
  - obstacle, 14
- output
  - inout.cpp, 38
  - main.cpp, 46
- params.h
  - flapStates, 31
  - maxSpeed, 31
  - minDistance, 31
  - minDistanceForObstacles, 32
  - minDistanceForPredators, 32
  - v1Mul, 32
  - v2Mul, 32
  - v3Mul, 32
  - v4Mul, 32
  - vMul, 32
  - velocityDivision, 32
  - xmax, 33
  - xmin, 33
  - ymax, 33
  - ymin, 33
  - zmax, 33
  - zmin, 33
- position
  - boid, 11
  - inout.cpp, 41
  - obstacle, 15
  - predator, 20
- predator, 16
  - boundPosition, 17
  - flapStatus, 20
  - getFlapStatus, 17
  - getPosition, 18
  - getPrevPosTime, 18
  - getPrevVelocity, 18
  - getVelocity, 18
  - movePredatorToNewPos, 18
  - position, 20
  - predator, 17
  - prevPosTime, 20
  - prevVelocity, 20
  - rule1, 18
  - rule3, 18
  - setFlapStatus, 18
  - setPosition, 19
  - setPrevPosTime, 19
  - setPrevVelocity, 19
  - setSystem, 19
  - setVelocity, 19
  - strongWind, 19
  - sys, 20
  - tendAwayFromPlace, 19
  - tendToPlace, 20
  - updateFlapStatus, 20
  - velocity, 21
- predator.cpp
  - compareFloats, 47
  - limitVelocity, 47
  - normalizeVelocity, 48
  - printvec, 48
- predatorColor
  - inout.cpp, 41
- predators
  - system, 27
- prevPosTime
  - boid, 11
  - obstacle, 15
  - predator, 20
- prevVelocity
  - boid, 11
  - obstacle, 16
  - predator, 20
- print
  - main.cpp, 46
- printvec
  - boid.cpp, 35
  - predator.cpp, 48
- programID\_lighting
  - inout.cpp, 42
- programID
  - inout.cpp, 42
- projectionMatrix
  - inout.cpp, 42
- quit
  - inout.cpp, 42
  - main.cpp, 46
- rotMatrix
  - inout.cpp, 42
- rotationMatrixFrame
  - inout.cpp, 42
- rule1
  - predator, 18
- rule1and2
  - boid, 9
  - obstacle, 14
- rule3
  - boid, 9
  - obstacle, 14
  - predator, 18
- scalingFactorID\_lighting
  - inout.cpp, 42
- scalingFactorID
  - inout.cpp, 42
- setFlapStatus
  - boid, 9
  - predator, 18
- setNumBoids
  - system, 25
- setNumObstacles
  - system, 25
- setNumPredators
  - system, 26
- setObjectID

- inout.cpp, 39
- setPosition
  - boid, 9
  - obstacle, 14
  - predator, 19
- setPrevPosTime
  - boid, 10
  - obstacle, 14
  - predator, 19
- setPrevVelocity
  - boid, 10
  - predator, 19
- setShaders
  - inout.cpp, 39
- setSystem
  - boid, 10
  - predator, 19
- setVelocity
  - boid, 10
  - obstacle, 14
  - predator, 19
- setWind
  - system, 26
- setWindPresent
  - system, 26
- shader.cpp
  - LoadShaders, 48
- shader.h
  - LoadShaders, 34
- Speed
  - inout.cpp, 43
- startWithBoids
  - system, 26
- strongWind
  - boid, 10
  - obstacle, 15
  - predator, 19
- sys
  - boid, 11
  - inout.cpp, 43
  - main.cpp, 47
  - predator, 20
- system, 21
  - addBoid, 22
  - addObstacle, 23
  - addPredator, 23
  - boids, 26, 27
  - findNearestBoid, 23
  - findNeighbouringBoids, 24
  - findObstaclesForPredator, 24
  - findVeryCloseObjects, 24
  - flock, 24
  - getBoids, 24
  - getNumBoids, 24
  - getNumObstacles, 25
  - getNumPredators, 25
  - getObstacles, 25
  - getPredators, 25
  - getWind, 25
  - getWindPresent, 25
  - numBoids, 27
  - numObstacles, 27
  - numPredators, 27
  - obstacles, 27
  - predators, 27
  - setNumBoids, 25
  - setNumObstacles, 25
  - setNumPredators, 26
  - setWind, 26
  - setWindPresent, 26
  - startWithBoids, 26
  - system, 22
  - updateSystem, 26
  - wind, 28
  - windPresent, 28
- system.cpp
  - distance, 49
- tendAwayFromPlace
  - boid, 10
  - obstacle, 15
  - predator, 19
- tendToPlace
  - boid, 10
  - obstacle, 15
  - predator, 20
- updateFlapStatus
  - boid, 11
  - obstacle, 15
  - predator, 20
- updateSystem
  - system, 26
- v1Mul
  - params.h, 32
- v2Mul
  - params.h, 32
- v3Mul
  - params.h, 32
- v4Mul
  - params.h, 32
- vMul
  - params.h, 32
- velocity
  - boid, 11
  - obstacle, 16
  - predator, 21
- velocityDivision
  - params.h, 32
- vertexColorID\_lighting
  - inout.cpp, 43
- vertexColorID
  - inout.cpp, 43
- vertexNormalID
  - inout.cpp, 43
- vertexPosID\_lighting

- inout.cpp, [44](#)
- vertexPosID
  - inout.cpp, [44](#)
- vertexbuffer\_flap1
  - inout.cpp, [43](#)
- vertexbuffer\_flap2
  - inout.cpp, [43](#)
- vertexbuffer\_obstacle
  - inout.cpp, [43](#)
- vertices\_flap1
  - inout.cpp, [44](#)
- vertices\_flap2
  - inout.cpp, [44](#)
- vertices\_obstacle
  - inout.cpp, [44](#)
- viewMatrix
  - inout.cpp, [44](#)
- ViewMatrixID\_lighting
  - inout.cpp, [45](#)
- ViewMatrixID
  - inout.cpp, [45](#)
- wind
  - system, [28](#)
- windPresent
  - system, [28](#)
- window
  - inout.cpp, [45](#)
  - main.cpp, [47](#)
- xmax
  - params.h, [33](#)
- xmin
  - params.h, [33](#)
- ymax
  - params.h, [33](#)
- ymin
  - params.h, [33](#)
- zmax
  - params.h, [33](#)
- zmin
  - params.h, [33](#)