THE B+ TREE INDEX

CS 564- Fall 2021

WHAT IS THIS LECTURE ABOUT?

The **B+ tree** index

- Basic principles
- Search/Insertion/Deletion
- Design choices
- I/O Cost

INDEX RECAP

We have the following SQL query:

```
SELECT *
FROM Sales
WHERE price > 100;
```

Indexes help us organize the file to answer the above query efficiently!

INDEXES

Hash index:

- good for equality search
- in expectation constant I/O cost for search and insert

B+ tree index:

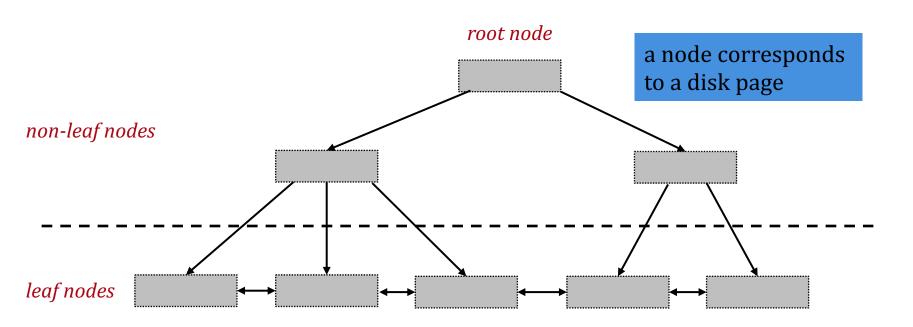
- good for range search
- good for equality search

B+ TREE BASICS

THE B+ TREE INDEX

- a dynamic tree-structured index
 - adjusted to be always height-balanced
 - 1 node = 1 physical page
- supports efficient equality and range search
- widely used in many DBMSs
 - SQLite uses it as the default index
 - SQL Server, DB2, ...

B+ TREE INDEX: BASIC STRUCTURE



index entries:

- exist *only* in the leaf nodes
- are sorted according to the search key

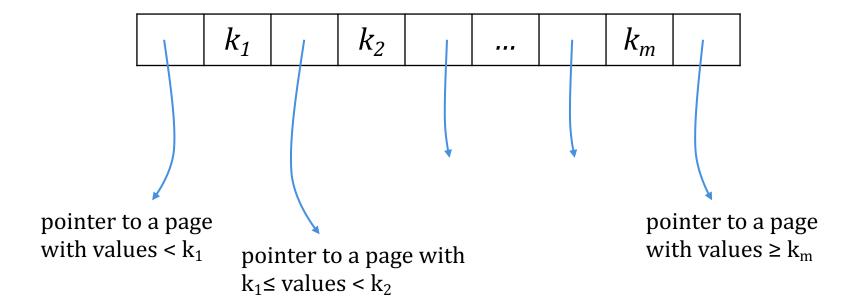
B+ TREE: NODE

- the parameter *d* is the *order* of the tree
- each node contains $d \le m \le 2d$ entries
 - minimum 50% occupancy always
- with the exception of the root node, which can have $1 \le m \le 2d$ entries

$oxed{k_1} oxed{k_2} oxed{\ldots} oxed{k_m}$
--

NON-LEAF NODES

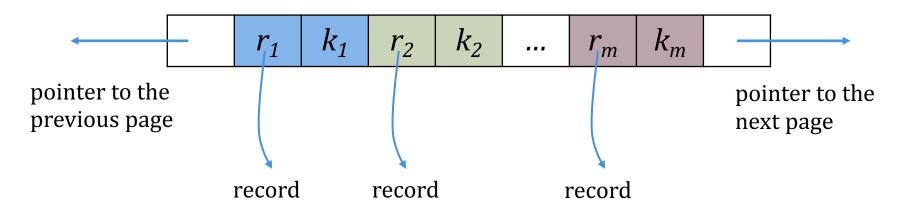
A non-leaf (or internal) node with m entries has m+1 pointers to lower-level nodes

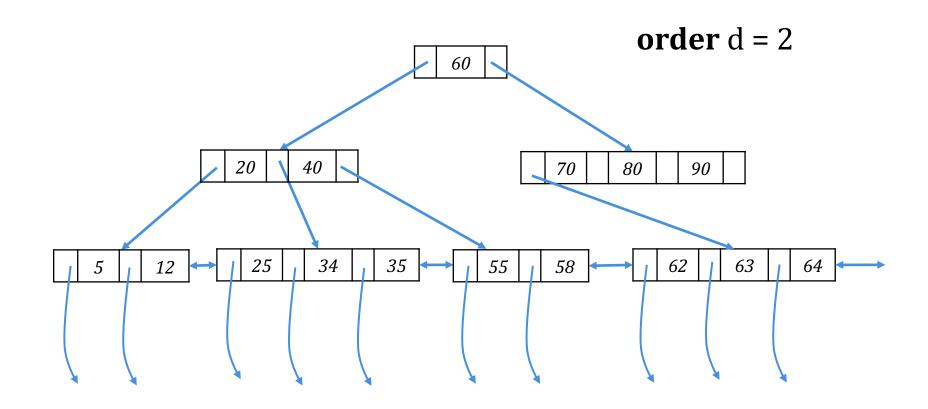


LEAF NODES

A leaf node with *m* entries has

- m pointers to the data records (rids)
- pointers to the next and previous leaves





B+ TREE OPERATIONS

B+ TREE OPERATIONS

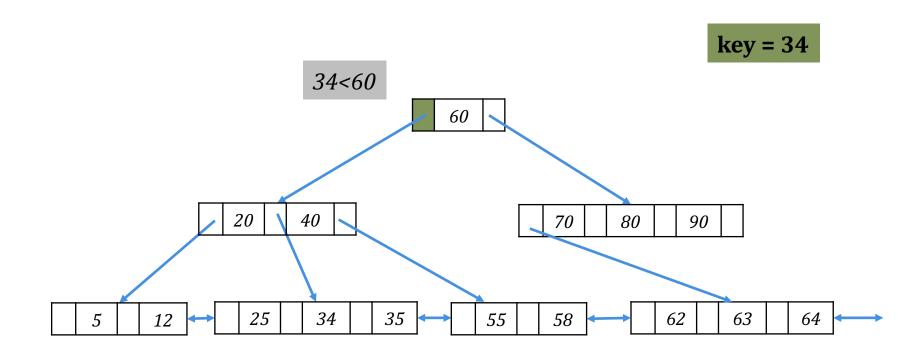
A B+ tree supports the following operations:

- equality search
- range search
- insert
- delete
- bulk loading (not covered in this lecture)

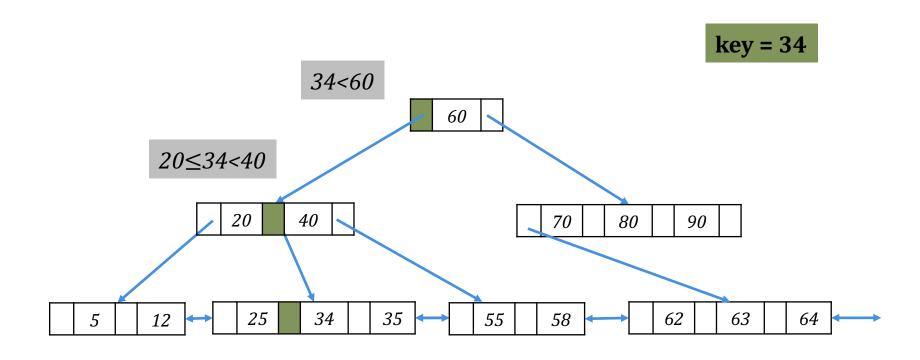
SEARCH

- start from the root node
- examine the index entries in non-leaf nodes to find the correct child
- traverse down the tree until a leaf node is reached
 - for equality search, we are done
 - for range search, traverse the leaves sequentially using the previous/next pointers

EQUALITY SEARCH: EXAMPLE

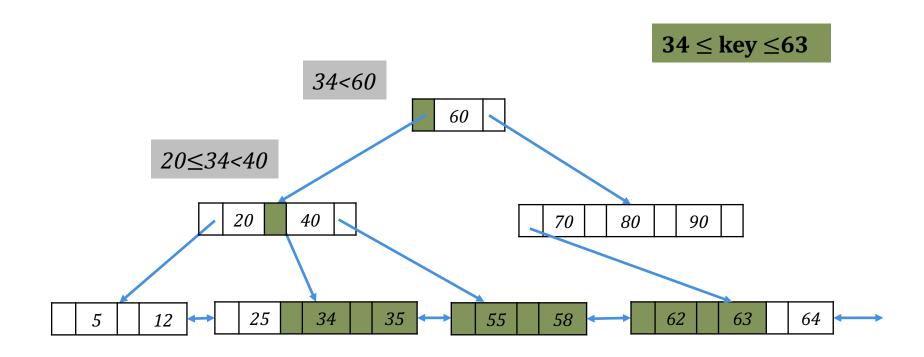


EQUALITY SEARCH: EXAMPLE



To locate the correct data entry in the leaf node, we can do either linear or binary search

RANGE SEARCH: EXAMPLE



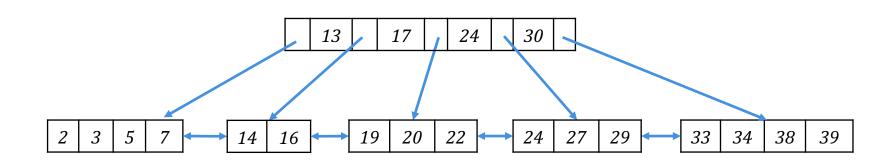
After we find the leftmost point of the range, we traverse sequentially!

INSERT

- find the leaf node L where the entry belongs
- insert data entry in L
 - If L has enough space, DONE!
 - Otherwise, we must split L (into L and a new node L')
 - redistribute entries evenly, **copy up** the middle key
 - insert index entry pointing to L' into parent of L
- This can propagate recursively to other nodes!
 - to split a non-leaf node, redistribute entries evenly, but
 push up the middle key

order $\mathbf{d} = 2$

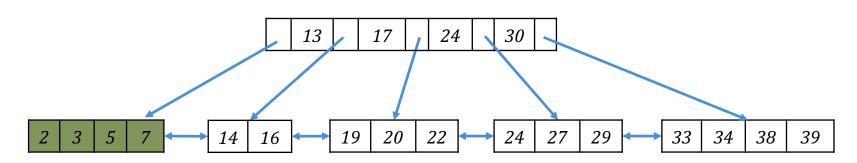
insert 8

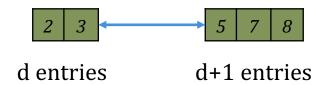


order $\mathbf{d} = 2$

insert 8

the leaf node is full so we must split it!

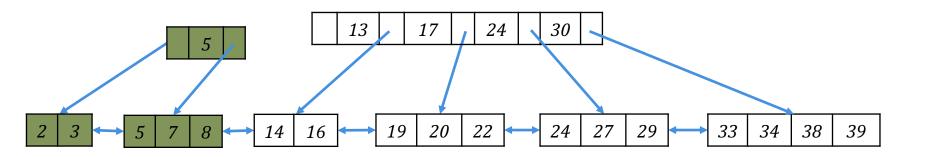




order $\mathbf{d} = 2$

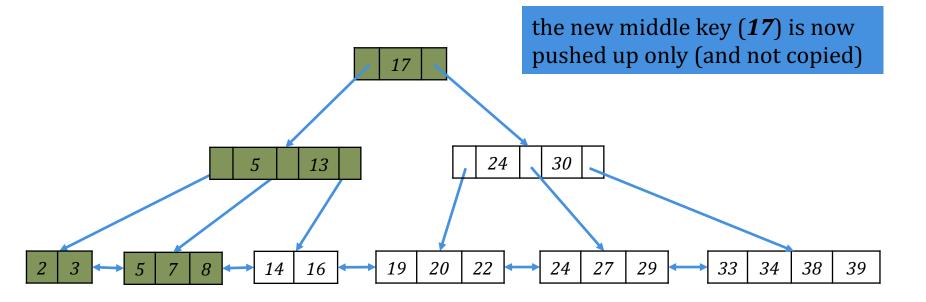
insert 8

the middle key (5) must be copied up, but the root node is full as well!



order $\mathbf{d} = 2$

insert 8



INSERT PROPERTIES

The B+ tree insertion algorithm has several attractive qualities:

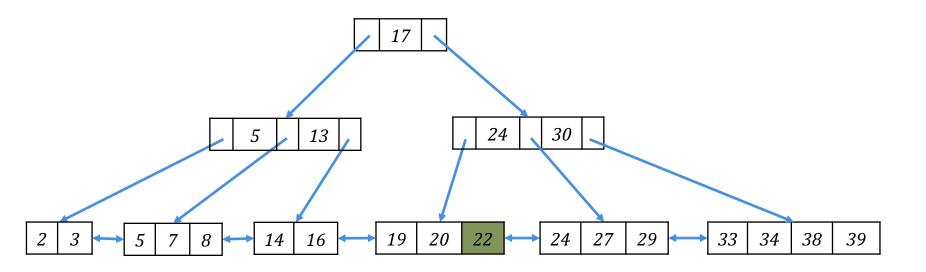
- about the same cost as exact search
- it is *self-balancing:* the tree remains balanced (with respect to height) even after multiple insertions

DELETE

- find the leaf node L where entry belongs
- remove the entry
 - If L is at least half-full, DONE!
 - If L has only d-1 entries,
 - Try to redistribute borrowing entries from a neighboring sibling
 - If redistribution fails, merge L and sibling
- If a merge occurred, we must delete an entry from the parent of L

order $\mathbf{d} = 2$

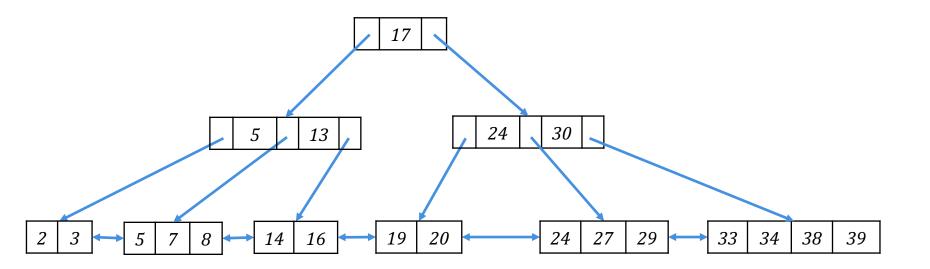
delete 22



since by deleting 22 the node remains half-full, we simply remove it

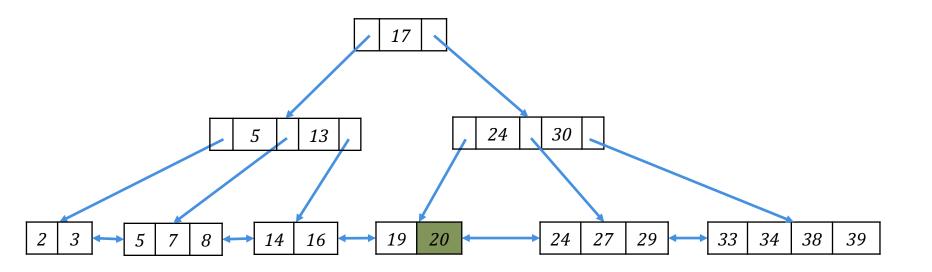
order $\mathbf{d} = 2$

delete 22



order $\mathbf{d} = 2$

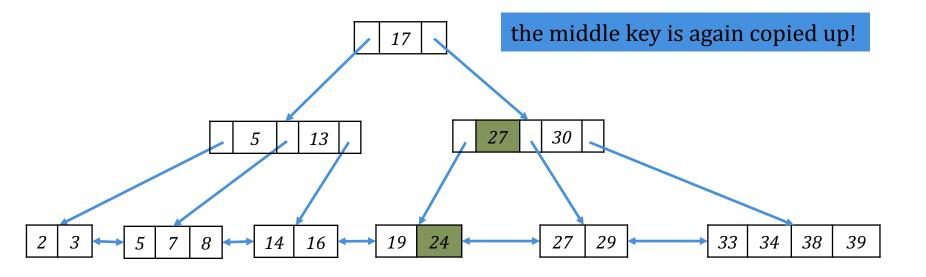
delete 20



by removing 20 the node is not half-full anymore, so we attempt to redistribute!

order $\mathbf{d} = 2$

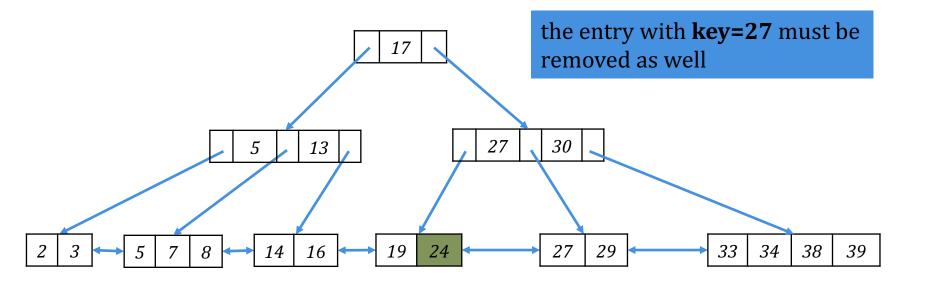
delete 20



by removing 20 the node is not half-full anymore, so we attempt to redistribute!

order $\mathbf{d} = 2$

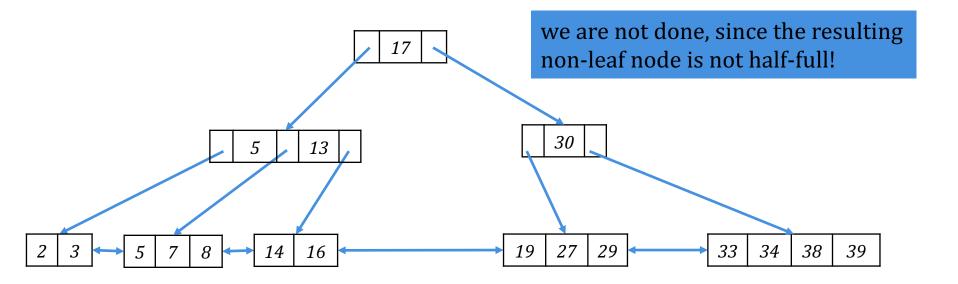
delete 24



in this case, we have to merge nodes!

order $\mathbf{d} = 2$

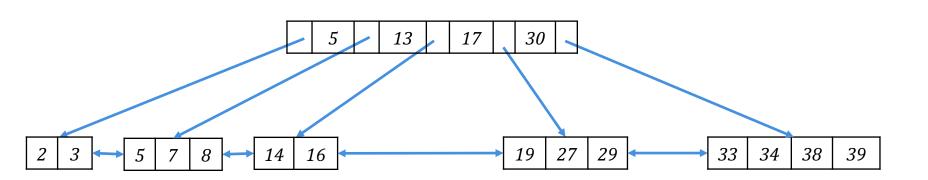
delete 24



order $\mathbf{d} = 2$

delete 24

we are not done, since the resulting non-leaf node is not half-full!



MORE ON DELETE

- Redistribution of entries is also possible for the non-leaf nodes
- We can also try to redistribute using all siblings, and not only the neighboring one

DUPLICATES

<u>Duplicate keys</u>: many index entries with the same key value

- Solution #1
 - All entries with a given key value reside on a single page
 - Use overflow pages
- Solution #2
 - Allow duplicate key values in data entries
 - Modify search operation

B+ TREE DESIGN & COST

B+ TREE: FAN-OUT

fan-out f: the number of pointers to child nodes coming out of a non-leaf node

- compared to binary trees (fan-out =2), B+ trees have a high fan-out $(d+1 \le f \le 2d+1)$
- The fan-out of B+ trees is dynamic, but we will typically assume it is constant for our cost model

B+ TREE: FILL-FACTOR

fill-factor *F*: the percent of available slots in the B+ tree that are filled

- it is usually < 1 to leave slack for (quicker) insertions!
- typical fill factor F = 2/3

B+ TREE: HEIGHT

height *h*: the number of levels of the non-leaf nodes

- the height is at least 1 (root node)
- high fan-out -> smaller height-> less I/O per search
- typical heights of B+ trees: 3 or 4

- page size P = 4000 bytes
- search key size = 30 bytes
- address size = 10 bytes
- fill-factor $\mathbf{F} = 2/3$
- number of records = 2,000,000
- We assume that the index entries store only the search key and the address of tuple
- We assume no duplicate entries

What is the order **d** and fan-out **f**?

- each non-leaf node stores up to 2d values of the key + (2d+1) addresses for the children pages
- to fit this into a single page, we must have:

$$2d \cdot 30 + (2d+1) \cdot 10 \le 4000$$

 $d \le 50$

• since a maximum capacity node has $(2\mathbf{d}+1) = 101$ children, and the fill-factor is 2/3, the fan-out is $\mathbf{f} = 101 * \frac{2}{3} = 67$

How many leaf pages are in the B+ tree?

- we assume for simplicity that each leaf page stores only pairs of (key, address)
- each pair needs 30+10 = 40 bytes
- to store 2,000,000 such pairs with fill-factor $\mathbf{F} = 2/3$, we need:

$$\#leaves = (2,000,000 * 40)/(4,000 * F) = 30,000$$

What is the height **h** of the B+ tree?

- we calculated that we need to index N = 30,000 pages
- $\mathbf{h} = 1$ -> indexes \mathbf{f} pages
- $\mathbf{h} = 2$ -> indexes \mathbf{f}^2 pages

height must be $\mathbf{h} = \lceil log_f N \rceil$

- ...
- $\mathbf{h} = \mathbf{k}$ -> indexes $\mathbf{f}^{\mathbf{k}}$ pages

for our example, $h = [log_{67}30,000] = 3$

What is the total size of the tree?

- #pages = $1 + 67 + 67^2 + 30,000 = 34,557$
- the top levels of the B+ tree do not take much space and can be kept in the buffer pool
 - level 0 = 1 page ~ 4 KB
 - level 1 = 67 pages \sim 268 KB
 - $level 2 = 4,489 pages \sim 18 MB$

COST MODEL FOR SEARCH

To do equality search:

- we read one page per level of the tree
- levels that we can fit in buffer are free!
- finally we read in the actual record

$$I/O \cos t = h - L_B + 1 + I$$

I = 0 if the record is stored at the leaf node, otherwise *I* = 1

If we have $\mathbf{\textit{B}}$ available buffer pages, we can store $\mathbf{\textit{L}}_{B}$ levels of the B+ Tree in memory:

• *L*_B is the number of levels such that the sum of all the levels' nodes fit in the buffer:

$$B \ge 1 + f + \dots + f^{L_B - 1}$$

COST MODEL FOR SEARCH

To do range search:

- we read one page per level of the tree
- levels that we can fit in buffer are free!
- we read sequentially the pages in the range

$$I/O \cos t = h - L_B + OUT$$

Here, *OUT* is the I/O cost of loading the additional leaf nodes we need to access + the I/O cost of loading each *page* of the results