COMP6771 Week 9.1

Runtime Polymorphism

Key concepts

- Inheritance: ability to create new classes based on existing ones
 - Supported by class derivation
- **Polymorphism:** allows objects of a subclass to be used as if they were objects of a base class
 - Supported via virtual functions
- **Dynamic binding:** run-time resolution of the appropriate function to invoke based on the type of the object
 - Closely related to polymorphism
 - Supported via virtual functions

Thinking about programming

- Represent concepts with classes
- Represent relations with inheritance or composition
 - Inheritance: A is also a B, and can do everything B does
 - "is a" relationship
 - A dog is an animal
 - Composition (data member): A contains a B, but isn't a B itself
 - "has a" relationship
 - A person **has a** name
 - Choose the right one!

Protected members

- Protected is a keyword we can use instead of public / private
- Protected members are accessible only to the class, or any subclass of it

Inheritance in C++

- To inherit off classes in C++, we use "class DerivedClass: public BaseClass"
- Visibility can be one of:
 - public (generally use this unless you have good reason not to)
 - o If you don't want public, you should (usually) use composition
 - protected
 - private
- Visibility is the maximum visibility allowed
 - If you specify ": private BaseClass", then the maximum visibility is private
 - Any BaseClass members that were public or protected are now private

Tenets of C++

- Don't pay for what you don't use
 - C++ Supports OOP
 - No runtime performance penalty
 - C++ supports generic programming with the STL and templates
 - No runtime performance penalty
 - Polymorphism is extremely powerful, and we need it in C++
 - Do we need polymorphism at all when using inheritance?
 - Answer: sometimes
 - But how do we do so, considering that we don't want to make anyone who doesn't use it pay a performance penalty

Inheritance and memory layout

This is very important, as it guides the design of everything we discuss this week

BaseClass object

int_member_
string_member_

BaseClass subobject

SubClass subobject

SubClass object

```
int_member_
string_member_
```

vector_member_ ptr_member_

```
1 class BaseClass {
2  public:
3   int GetIntMember() {    return int_member_; }
4   std::string GetClassName() {
5     return "BaseClass"
6   };
7
8  private:
9   int int_member_;
10  std::string string_member_;
11 }
```

```
1 class SubClass: public BaseClass {
2  public:
3   std::string GetClassName() {
4    return "SubClass";
5  }
6
7  private:
8   std::vector<int> vector_member_;
9   int* ptr_member_;
10 }
```

Inheritance and constructors

- Every subclass constructor must call a base class constructor
 - If none is manually called, the default constructor is used
 - A subclass cannot initialise fields defined in the base class
 - Abstract classes must have constructors

```
class BaseClass {
    public:
     BaseClass(int member): int member {member} {}
    private:
    int int member ;
     std::string string member ;
   class SubClass: public BaseClass {
    public:
     SubClass(int member, int* ptr): BaseClass{member}, ptr member {ptr} {}
     // Won't compile.
     SubClass(int member, int* ptr): int member {member}, ptr member {ptr} {}
15
16 private:
     std::vector<int> vector member ;
     int* ptr member ;
19 }
```

Polymorphism and values

- How many bytes is a BaseClass instance?
- How many bytes is a SubClass instance?
- One of the guiding principles of C++ is "You don't pay for what you don't use"
 - Let's discuss the following code, but pay great consideration to the memory layout

```
1 class BaseClass {
   public:
    int GetMember() { return member ;
     std::string GetClassName() {
      return "BaseClass"
    };
    private:
     int member ;
10
```

```
void PrintClassName(BaseClass base class) {
     std::cout << base class.GetClassName()</pre>
                << '\n';
 6 int main() {
     BaseClass base class;
     SubClass subclass;
     PrintClassName(base class);
     PrintClassName(subclass);
11 }
```

```
1 class SubClass: public BaseClass {
   public:
    std::string GetClassName() {
      return "SubClass";
   private:
    int subclass data ;
```

The object slicing problem

- If you declare a BaseClass variable, how big is it?
- How can the compiler allocate space for it on the stack, when it doesn't know how big it could be?
- The solution: since we care about performance, a BaseClass can only store a BaseClass, not a SubClass
 - If we try to fill that value with a SubClass, then it just fills it with the BaseClass subobject, and drops the SubClass subobject

```
1 class BaseClass {
   public:
    int GetMember() { return member ;
     std::string GetClassName() {
       return "BaseClass"
    };
    private:
     int member ;
10
```

```
void PrintClassName(BaseClass base class) {
     std::cout << base class.GetClassName()</pre>
                << '\n';
4 }
 6 int main() {
     BaseClass base class;
     SubClass subclass;
     PrintClassName(base class);
     PrintClassName(subclass);
11 }
```

```
1 class SubClass: public BaseClass {
   public:
    std::string GetClassName() {
      return "SubClass";
   private:
    int subclass data ;
```

Polymorphism and References

- How big is a reference/pointer to a BaseClass
- How big is a reference/pointer to a SubClass
- Object slicing problem solved (but still another problem)
- One of the guiding principles of C++ is "You don't pay for what you don't use"
 - How does the compiler decide which version of GetClassName to call?
 - When does the compiler decide this? Compile or runtime?
 - How can it ensure that calling GetMember doesn't have similar overhead

```
1 class BaseClass {
    public:
    int GetMember() { return member ;
    std::string GetClassName() {
       return "BaseClass"
    private:
     int member ;
10 }
```

```
1 void PrintClassName(
       const BaseClass& base class) {
  std::cout << base class.GetClassName()</pre>
         << ' ' << base class.GetMember()
         << '\n';
 8 int main() {
     BaseClass base class;
     SubClass subclass;
11
     PrintClassName(base class);
     PrintClassName(subclass);
12
13 }
```

```
1 class SubClass: public BaseClass {
   public:
    std::string GetClassName() {
      return "SubClass";
   private:
    int subclass data ;
```

Virtual functions

- How does the compiler decide which version of GetClassName to call?
- How can it ensure that calling GetMember doesn't have similar overhead
 - Explicitly tell the compiler that GetClassName is a function designed to be modified by subclasses
 - Use the keyword "virtual" in the base class
 - Use the keyword "override" in the subclass

```
1 class SubClass: public BaseClass {
1 class BaseClass {
                                         1 void PrintClassName(
  public:
                                               const BaseClass& base class) {
                                                                                         2 public:
   int GetMember() { return member ; } 3
                                           std::cout << base class.GetClassName()</pre>
                                                                                              std::string GetClassName() override
   virtual std::string GetClassName() 4
                                                 << ' ' << base class.GetMember()
                                                                                               return "SubClass";
     return "BaseClass"
                                                 << '\n';
   };
                                                                                             private:
                                                                                              int subclass data ;
  private:
                                        8 int main() {
   int member ;
                                             BaseClass base class;
                                            SubClass subclass;
                                           PrintClassName(base class);
                                            PrintClassName(subclass);
                                        13 }
```

Override

- While override isn't required by the compiler, you should always use it
- Override fails to compile if the function doesn't exist in the base class. This helps with:
 - Typos
 - Refactoring
 - Const / non-const methods
 - Slightly different signatures

```
1 class BaseClass {
2  public:
3   int GetMember() { return member_; }
4   virtual std::string GetClassName() {
5    return "BaseClass"
6  };
7
8  private:
9  int member_;
10 }
```

```
1 class SubClass: public BaseClass {
2  public:
3    // This compiles. But this is a
4    // different function to the
5    // BaseClass GetClassName.
6    std::string GetClassName() const {
7      return "SubClass";
8    }
9
10    private:
11    int subclass_data_;
12 }
```

Virtual functions

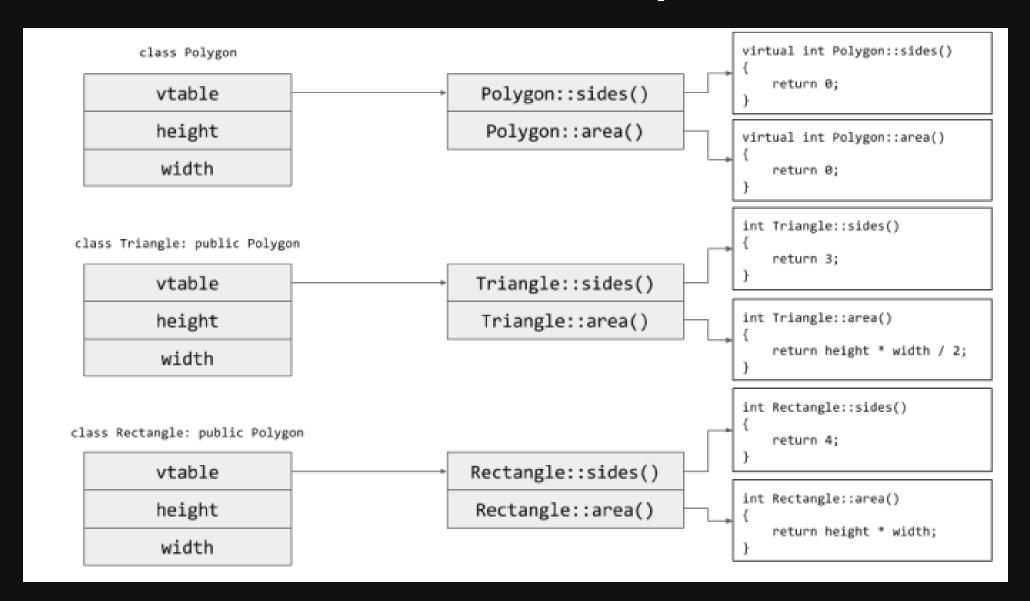
```
1 class BaseClass {
    public:
     virtual std::string GetClassName() {
       return "BaseClass"
     };
    ~BaseClass() {
      std::cout << "Destructing base class\n";</pre>
10
   class SubClass: public BaseClass {
    public:
14
     std::string GetClassName() override {
15
      return "SubClass";
16
17
    ~SubClass() {
18
19
      std::cout << "Destructing subclass\n";</pre>
20
21
```

- What do we expect to see?
- What do we actually see?

VTables

- Each class has a VTable stored in the data segment
 - A vtable is an array of function pointers that says which definition each virtual function points to for that class
- If the VTable for a class is non-empty, then every member of that class has an additional data member that is a pointer to the vtable
- When a virtual function is called **on a reference or pointer type**, then the program actually does the following
 - 1. Follow the vtable pointer to get to the vtable
 - 2. Increment by an offset, which is a constant for each function
 - 3. Follow the function pointer at vtable[offset] and call the function

VTable example



Final

- Specifies to the compiler "this is not virtual for any subclasses"
- If the compiler has a variable of type SubClass&, it now no longer needs to look it up in the vtable
- This means static binding if you have a SubClass&, but dynamic binding for BaseClass&

```
1 class BaseClass {
2  public:
3   int GetMember() { return member_; }
4   virtual std::string GetClassName() {
5    return "BaseClass"
6  };
7
8  private:
9  int member_;
10 }
```

```
class SubClass: public BaseClass {
public:
std::string GetClassName() override final {
   return "SubClass";
}

private:
int subclass_data_;
}
```

Abstract Base Classes (ABCs)

- Might want to deal with a base class, but the base class by itself is nonsense
 - What is the default way to draw a shape? How many sides by default?
 - A function takes in a "Clickable"
- Might want some default behaviour and data, but need others
 - All files have a name, but are reads done over the network or from a disk
- If a class has at least one "abstract" (pure virtual in C++) method, the class is abstract and cannot be constructed
 - It can, however, have constructors and destructors
 - These provide semantics for constructing and destructing the ABC subobject of any derived classes

Pure virtual functions

- Virtual functions are good for when you have a default implementation that subclasses may want to overwrite
- Sometimes there is no default available
- A pure virtual function specifies a function that a class must override in order to not be abstract

```
1 class Shape {
2    // Your derived class "Circle" may forget to write this.
3    virtual void draw(Canvas&) {}
4    
5    // Fails at link time because there's no definition.
6    virtual void draw(Canvas&);
7    
8    // Pure virtual function.
9    virtual void draw(Canvas&) = 0;
10 };
```

Creating polymorphic objects

- In a language like Java, everything is a pointer
 - This allows for code like on the left
 - Not possible in C++ due to objects being stored inline
- If you want to store a polymorphic object, use a pointer

```
1 // Java-style C++ here
2 // Don't do this.
3
4 std::vector<BaseClass> base;
5 base.push_back(BaseClass{});
6 base.push_back(SubClass1{});
7 base.push_back(SubClass2{});
```

```
1 // Good C++ code
2 // But there's a potential problem here.
3 // (*very* hard to spot)
4
5 std::vector<std::unique_ptr<BaseClass>> base;
6 base.push_back(std::make_unique<BaseClass>());
7 base.push_back(std::make_unique<Subclass1>());
8 base.push_back(std::make_unique<Subclass2>());
```

Destructing polymorphic objects

- Which constructor is called?
- Which destructor is called?
- What could the problem be?
 - What would the consequences be?
- How might we fix it, using the techniques we've already learnt?

```
1 // Simplification of previous slides code.
2
3 std::unique_ptr<BaseClass> base = std::make_unique<BaseClass>();
4 std::unique_ptr<BaseClass> base = std::make_unique<Subclass>();
```

Destructing polymorphic objects

- Whenever you write a class intended to be inherited from, always make your destructor virtual
- Remember: When you declare a destructor, the move constructor and assignment are not synthesized

```
1 class BaseClass {
2   BaseClass(BaseClass&&) = default;
3   BaseClass& operator=(BaseClass&&) = default;
4   virtual ~BaseClass() = default;
5 }
```

Forgetting this can be a hard bug to spot

Static and dynamic types

- Static type is the type it is declared as
- Dynamic type is the type of the object itself
- Static means compile-time, and dynamic means runtime
 - Due to object slicing, an object that is neither reference or pointer
 always has the same static and dynamic type

Quiz - What's the static and dynamic types of each of these?

```
1 int main() {
2    BaseClass base_class;
3    SubClass subclass;
4    BaseClass sub_copy{subclass};
5    // The following could all be replaced with pointers
6    // and have the same effect.
7    const BaseClass& base_to_base{base_class};
8    const BaseClass& base_to_sub{subclass};
9    // Fails to compile
10    const SubClass& sub_to_base{base_class};
11    const SubClass& sub_to_sub{subclass};
12    // Fails to compile (even though it refers to at a sub);
13    const SubClass& sub_to_base_to_sub{base_to_sub};
14 }
```

Static and dynamic binding

- Static binding: Decide which function to call at compile time (based on static type)
- Dynamic binding: Decide which function to call at runtime (based on dynamic type)
- (++
 - Statically typed (types are calculated at compile time)
 - Static binding for non-virtual functions
 - Dynamic binding for virtual functions
- Java
 - Statically typed
 - Dynamic binding

Up-casting

- Casting from a derived class to a base class is called up-casting
- This cast is always safe
 - All dogs are animals

```
Dog dog;

// Up-cast with references.
Animal& animal{dog};
// Up-cast with pointers.
Animal* animal{&dog};

// What's this (hint: not an up-cast)?
Animal animal{dog};
```

Down-casting

- Casting from a base class to a derived class is called down-casting
- This cast is not safe
 - Not all animals are dogs

```
1 Dog dog;
2 Cat cat;
3 Animal& animal_dog{dog};
4 Animal& animal_cat{cat};
5
6 // Attempt to down-cast with references.
7 // Neither of these compile.
8 // Why not?
9 Dog& dog_ref{animal_dog};
10 Dog& dog_ref{animal_cat};
```

How to down cast

- The compiler doesn't know if an Animal happens to be a Dog
 - If you know it is, you can use static_cast
 - Otherwise, you can use dynamic_cast
 - Returns null pointer for pointer types if it doesn't match
 - Throws exceptions for reference types if it doesn't match

```
Dog dog;
Cat cat;
Animal& animal_dog{dog};
Animal& animal_cat{cat};

// Attempt to down-cast with references.
Dog& dog_ref{static_cast<Dog&>(animal_dog)};
Dog& dog_ref{dynamic_cast<Dog&>(animal_dog)};
// Undefined behaviour (incorrect static cast).
Dog& dog_ref{static_cast<Dog&>(animal_cat)};
// Throws exception
Dog& dog_ref{dynamic_cast<Dog&>(animal_cat)};
```

```
1 Dog dog;
2 Cat cat;
3 Animal& animal_dog{dog};
4 Animal& animal_cat{cat};
5
6 // Attempt to down-cast with pointers.
7 Dog* dog_ref{static_cast<Dog*>(animal_dog)};
8 Dog* dog_ref{dynamic_cast<Dog*>(animal_dog)};
9 // Undefined behaviour (incorrect static cast).
10 Dog* dog_ref{static_cast<Dog*>(animal_cat)};
11 // returns null pointer
12 Dog* dog_ref{dynamic_cast<Dog*>(animal_cat)};
```

Types of functions

Syntax	Name	Meaning
virtual void fn() = 0;	pure virtual	Inherit interface only
virtual void fn() {}		Inherit interface with optional implementation
void fn() {}		Inherit interface and mandatory implementation

Note: nonvirtuals can be hidden by writing a function with the same name in a subclass

DO NOT DO THIS

Covariants

- If a function overrides a base, which type can it return?
 - If a base specifies that it returns a LandAnimal, a derived also needs to return a LandAnimal
- Every possible return type for the derived must be a valid return type for the base

```
class Base {
  virtual LandAnimal& GetFavoriteAnimal();
};

class Derived: public Base {
  // Fails to compile: Not all animals are land animals.
  Animal& GetFavoriteAnimal() override;
  // Compiles: All land animals are land animals.
  LandAnimal& GetFavoriteAnimal() override;
  // Compiles: All dogs are land animals.
  Dog& GetFavoriteAnimal() override;
};
```

Contravariants

- If a function overrides a base, which types can it take in?
 - If a base specifies that it takes in a LandAnimal, a LandAnimal must always be valid input in the derived
- Every possible parameter to the base must be a possible parameter for the derived

```
class Base {
  virtual void UseAnimal(LandAnimal&);
};

class Derived: public Base {
  // Compiles: All land animals are valid input (animals).
  void UseAnimal(Animal&) override;
  // Compiles: All land animals are valid input (land animals).
  void UseAnimal(LandAnimal&) override;
  // Fails to compile: Not All land animals are valid input (dogs).
  void UseAnimal(Dog&) override;
};
```

Default arguments and virtuals

- Default arguments are determined at compile time for efficiency's sake
- Hence, default arguments need to use the **static** type of the function
- Avoid default arguments when overriding virtual functions

```
1 class Base {
   virtual void PrintNum(int i = 1) {
       std::cout << "Base " << i << '\n';
 5 };
  class Derived: public Base {
     void PrintNum(int i = 2) override {
       std::cout << "Derived " << i << '\n';
10
11 };
12
13 int main() {
   Derived derived;
15 Base& base;
16 derived.PrintNum(); // Prints "Derived 2"
17
   base->PrintNum(); // Prints "Derived 1"
18 }
```

Construction of derived classes

- Base classes are always constructed before the derived class is constructed
 - The base class is never dependent on the derived class
 - The derived may be dependent on the base

```
class Animal {...}
class LandAnimal: public Animal {...}
class Dog: public LandAnimals {...}

Dog d;

// Dog() calls LandAnimal()
// LandAnimal() calls Animal()
// Animal members constructed using initialiser list
// Animal constructor body runs
// LandAnimal members constructed using initialiser list
// LandAnimal constructor body runs
// Dog members constructed using initialiser list
// Dog constructor body runs
```

Virtuals in constructors

If a class is not fully constructed, cannot perform dynamic binding

```
1 class Animal {...};
 2 class LandAnimal: public Animal {
     LandAnimal() {
       Run();
 7 virtual void Run() {
       std::cout << "Land animal running\n";</pre>
10 };
11 class Dog: public LandAnimals {
   void Run() override {
       std::cout << "Dog running\n";</pre>
13
14
15 };
16
17 // When the LandAnimal constructor is being called,
18 // the Dog part of the object has not been created yet.
19 // C++ chooses to not allow dynamic binding in constructors
20 // because Dog::Run() might depend upon Dog's members.
21 Dog d;
```

Destruction of derived classes

• Easy to remember order: Always opposite to construction order

```
class Animal {...}
class LandAnimal: public Animal {...}
class Dog: public LandAnimals {...}

Dog d;

// ~Dog() destructor body runs
// Dog members destructed in reverse order of declaration
// ~LandAnimal() destructor body runs
// LandAnimal members destructed in reverse order of declaration
// ~Animal() destructor body runs
// Animal members destructed in reverse order of declaration
// Animal members destructed in reverse order of declaration.
```

Virtuals in destructors

- If a class is partially destructed, cannot perform dynamic binding
- Unrelated to the destructor itself being virtual

```
1 class Animal {...};
 2 class LandAnimal: public Animal {
     virtual ~LandAnimal() {
       Run();
    virtual void Run() {
       std::cout << "Land animal running\n";</pre>
10 };
11 class Dog: public LandAnimals {
     void Run() override {
12
       std::cout << "Dog running\n";</pre>
13
14
15 };
16
17 // When the LandAnimal constructor is being called,
18 // the Dog part of the object has already been destroyed.
19 // C++ chooses to not allow dynamic binding in destructors
20 // because Dog::Run() might depend upon Dog's members.
21 Dog d;
```