DSA4266 Group 3

Fish Larvae

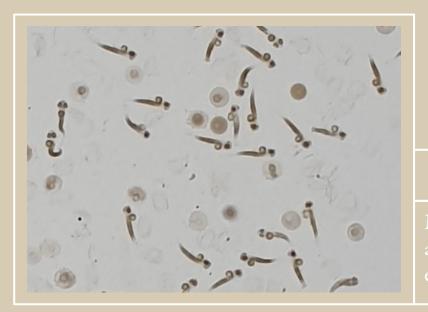




Counting

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Introduction



Fish Larvae Counting

Monitor the stocking density of the fish larva and counts of fertilized and unfertilized fish eggs at regular intervals

Objective



Our goal is to train a <u>predictive model</u> that is able to <u>accurately classify</u> images of petri-dish containing three main classes: *Fertilised Eggs*, *Unfertilized Eggs* and *Fish Larvae*, and an *Unidentifiable* class to handle foreign objects as well.



Once trained, we are to implement an intuitive user interface with focus on <u>accuracy</u> and <u>scalability</u>.



Definition

Phase 1: Mid-Term Assessment

Phase 2: Final Assessment



Our Workflow

01

Data Pre-Processing



02

Modelling & Tuning

03

Testing

04

Implementation of Solution



01

Data Pre-Processing

Data preparation



Labelling of Data





Fertilized Egg

Objects with partially formed head and curled up



Fish Larva

Obvious object that has a head and a long tail (can be curved)



Unfertilized Egg

Sphere like structure of at least a certain size



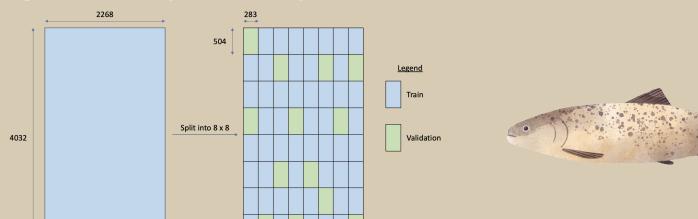
Unidentifiable

Objects that do not resemble any of the 3 classes, or foreign objects



Recap: Phase 1 Data Preparation

- Labelled images with references to slide provided (non-SFA images)
- Sliced each image 8x8 into 64 equal parts of size (504, 283) when view vertically
- Resulting in 640 slices (i.e. 640 = 64 * 10 images)
- Train-Validation Split (8:2) resulting in <u>507</u> training data and <u>133</u> validation data



Phase 2: Total Counts

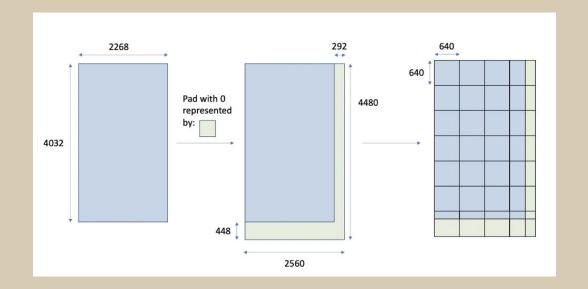
Label Type	Total Number of Labels
Fertilised Egg	376
Unfertilised Egg	244
Fish Larvae	956
Unidentifiable	129

 $Labelled\ using\ LabelImg: \underline{https://github.com/tzutalin/labelImg}$

Image Number	Fertilised Eggs	Unfertilised Eggs	Fish Larvae	Unidentifiable	Remark(s)
20210729_131410.jpg (1)	56	3	60	7	Low Unfert Eggs
20210729_132515.jpg (2)	1	64	41	10	Low Fert Eggs
20210729_132649.jpg (3)	5	137	174	11	Low Fert Eggs High Unfert Eggs High Larvae
20210729_134857.jpg (4)	21	3	66	6	Low Unfert Eggs
20210729_134912.jpg (5)	23	5	64	7	Low Unfert Eggs
20210903_095054.jpg (6)	42	10	117	34	High Fert Eggs High Unidentif
20210903_100603.jpg (7)	90	3	68	13	High Fert Eggs
20210903_100651.jpg (8)	43	15	124	13	High Larvae
20210903_100734.jpg (9)	76	3	81	18	High Fert Eggs Low Unfert Eggs High Larvae
20210903_100758.jpg (10)	19	1	161	10	High Larvae

Phase 2: Slicing

- Right and bottom part of the image is padded with 0
- Slicing the incoming images results in squares of dimension (640, 640) regardless of input size
- In line with pre-trained weights which were trained on 640

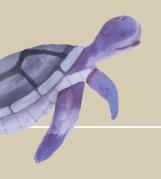






Phase 2: Breakdown of Sliced Labels

Label Type	New Number of Sliced Labels	New Percentage of Total
Fertilised Egg	28	<u>7%</u>
Unfertilised Egg	17	<u>7%</u>
Fish Larvae	77	<u>8%</u>
Unidentifiable	8	<u>6%</u>



Label Type	Old Number of Sliced Labels (from Old Slices)	Old Percentage of Total (from Old Slices)	
Fertilised Egg	93	13%	
Unfertilised Egg	27	10%	
Fish Larvae	106	16%	
Unidentifiable	18	10%	

Phase 2: Total Counts Post-Slicing

Label Type	New Overall Number of Labels
Fertilised Egg	348
Unfertilised Egg	227
Fish Larvae	879
Unidentifiable	121



Phase 2: Data Augmentation on Training Set

- Validation set is untouched
- Mainly increase the counts of Fertilised Eggs [Unfertilised Eggs have distinct features]
- New training set has 296 slices (original had 224 slices)
- Ratio of major three classes is approximately 3:1:3

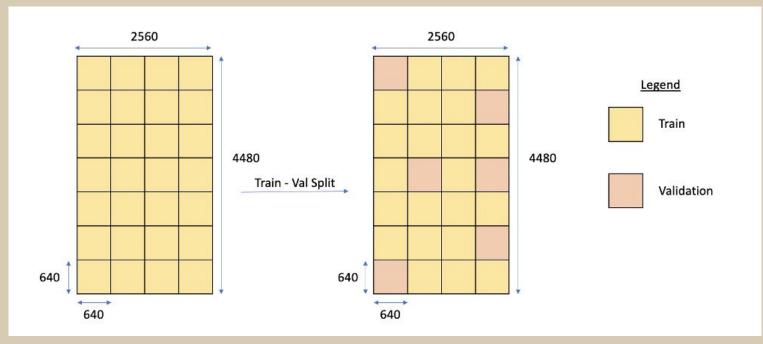
Label Type	Final Overall Number of Labels
Fertilised Egg	952
Unfertilised Egg	360
Fish Larvae	953
Unidentifiable	137





Phase 2: Training-Validation Split (8:2)





Phase 2: Training-Validation Split Counts

Total: 10 images \times 28 Slices each = <u>280 Slices</u>



Training Set: 224 Slices

Label Type	Number of Labels
Fertilised Egg	286
Unfertilised Egg	186
Fish Larvae	695
Unidentifiable	95



Validation Set: <u>56 Slices</u>

Label Type	Number of Labels
Fertilised Egg	62
Unfertilised Egg	41
Fish Larvae	184
Unidentifiable	26



02

Modelling & Tuning

Experimenting to obtain optimal parameters

Recap: Phase 1 Modelling & Tuning

- Made use of YOLOv3 model
- Baseline model: Batch size 8, epochs 50 and SGD
- Run evolution of 100 iterations
- Tune parsable parameters of the best model from evolution
- Attempted ensemble (but no improvements)
- Final model: mAP@0.5 of 0.872 for 3 main classes

110.Class	Images	Labels	Р	R	mAP@.5	mAP@.5:.95
all	133	341	0.665	0.76	0.729	0.341
Fertilised Egg	133	115	0.69	0.922	0.821	0.332
Unfertilised Egg	133	60	0.775	0.917	0.871	0.464
Fish Larvae	133	136	0.813	0.934	0.924	0.431
Unidentifiable	133	30	0.38	0.267	0.301	0.139



Phase 2: Baseline Model

- Made use of YOLOv5s weights
- Using batch size of 8 and 50 epochs
- Default hyp.scratch file
- Auto-Anchor enabled
- Default SGD

Epoch	gpu_mem	box	obj	cls	total	labels	img_size			
49/49	7.67G	0.04068	0.008723	0.01044	0.05985	7	704:	100% 64/64	[02:17<00:00, 2.15s/it]	
	Class	Images	Labe	ls	P	R	mAP@.5	mAP@.5:.95:	100% 9/9 [00:07<00:00,	1.19it/s]
	all	133	34	41	0.516	0.782	0.68	0.262		
Fertil	lised Egg	133	1	15	0.515	0.896	0.782	0.285		
Unferti	lised Egg	133		50	0.61	0.917	0.875	0.348		
Fis	sh Larvae	133	1	36	0.626	0.949	0.847	0.358		
Unider	ntifiable	133		30	0.314	0.367	0.215	0.0574		
50 epochs co	ompleted in	2.067 hou	rs.							



Phase 2: Evolution



Weights	Image Size	Batch Size	Epochs	Optimizer	mAP
YOLOv5s	640	30	150	SGD	0.71606
YOLOv5m	640	30	150	SGD	0.71772
YOLOv5l	640	30	150	SGD	0.74272
YOLOv5x	640	30	150	SGD	0.7116
YOLOv5s	640	30	150	Adam	0.7406
YOLOv5m	640	30	150	Adam	0.7410
YOLOv5l	640	30	150	Adam	0.7424
YOLOv5x	640	30	150	Adam	0.7347

Phase 2: Leading Model from Evolution

Class	Images	Labels	P	R	mAP@.5	mAP@.5:.95
all	56	313	0.727	0.727	0.743	0.395
Fertilised Egg	56	62	0.723	0.774	0.839	0.432
Unfertilised Egg	56	41	0.948	0.893	0.962	0.57
Fish Larvae	56	184	0.849	0.973	0.908	0.474
Unidentifiable	56	26	0.389	0.269	0.264	0.103



The best model from our evolution had a overall mAP of 0.743

3-class mAP of 0.903



Phase 2: Ensemble

- Similar to our Phase I experiment, we used BAGGING approach to ensemble our models
- Trained 10 separate YOLOv5l models with different bootstrap samples and hyperparameters
- Experimented with different aggregation techniques, namely
 - Max aggregation
 - Mean aggregation
 - NMS aggregation



Phase 2: Ensemble

Class	Images	Labels	Р	R	mAP@.5 mA	P@.5:.95:
all	56	313	0.732	0.728	0.754	0.366
Fertilised Egg	56	62	0.672	0.79	0.871	0.425
Unfertilised Egg	56	41	0.901	0.878	0.923	0.45
Fish Larvae	56	184	0.821	0.935	0.933	0.451
Unidentifiable	56	26	0.533	0.308	0.29	0.137

- Out of the 3 aggregation techniques, our ensemble model performed the best with mean aggregation
- Achieved the best overall mAP of 0.754 and 3-class mAP of 0.909



Phase 2: Final Model

While our ensemble model performed the best

- Time and hardware constraint was an issue
- Decided to stick to single-model solutions for this assignment
- Nonetheless, we have shown that ensembling is an effective method to increase model performance.

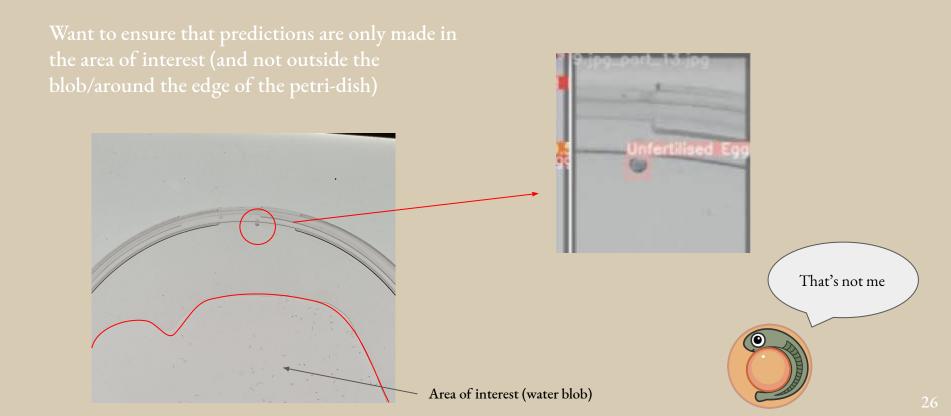


- To allow for greatly flexibility, we deployed two YOLOv5 models a user can choose to run inference on:
- Accurate: YOLOv5 (large) with a 3-class mAP of 0.903 and inference time of 37 seconds
- Speed: YOLOv5 (small) with a 3-class mAP of 0.839 and inference time of 10 seconds
- This flexibility allows user to choose between having
 - Better accuracy, or
 - Faster predictior





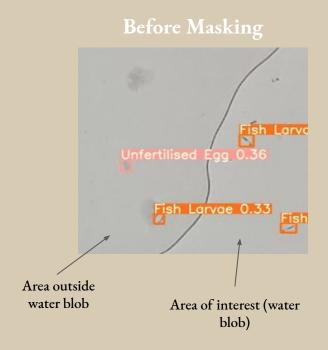
Masking of Test Images



Recap: Phase 1 Masking



• Edges of masking are uneven and do not lie along the lie of the area of interest nicely



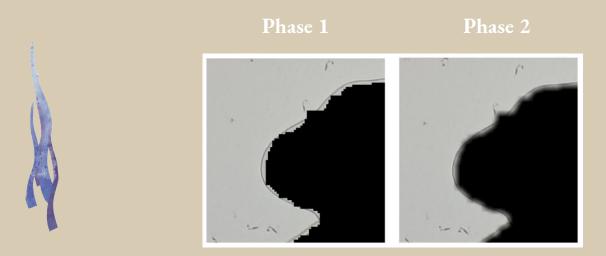




Phase 2: Masking

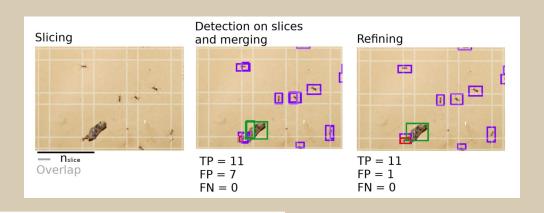


- Added some degree of blurring to the mask
- Obtained mask which is smoother and better aligned with the area of interest



Recap: Phase 1 Testing

- Using image from post-masking, we slice the masked image into 64 parts
- Slice with overlap to account for objects that are lost during slicing
- Run inference on individual slices: get normalized BB coordinates
- Rescale BB coordinates and redraw onto original size image



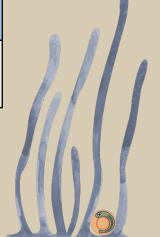


Phase 2: Testing

- Testing directly on full image (no longer slicing test images)
- Higher emphasis on Non-Max Suppression Parameters
- Tuned Confidence Threshold to 0.45, IOU Threshold to 0.15

Percentile	Minimum	25 th Percentile	Mean	75 th Percentile	Maximum
Confidence Scores at conf_t = 0.45	0.455	0.789	0.814	0.860	0.952

Saves up on predicting time and computational space: no rescaling needed



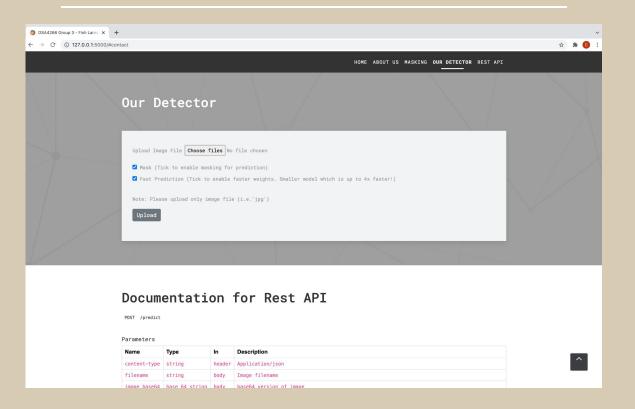


04

Implementation of Solution

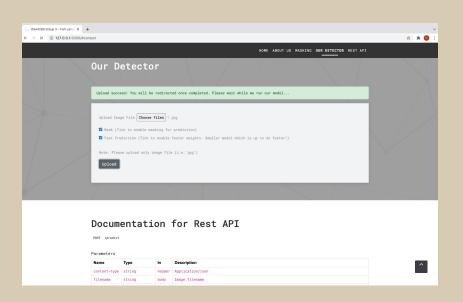
Productionizing our solution

UI: Intuitive & Easy to Use

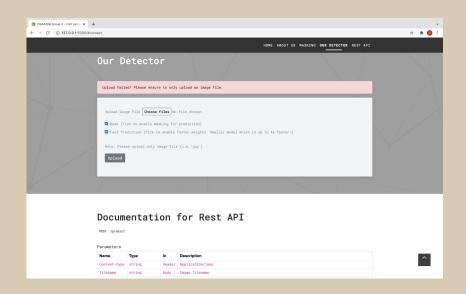


UI: Handles Right & Wrong Inputs

Right Input

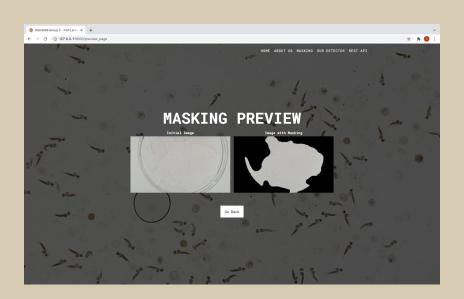


Wrong Input

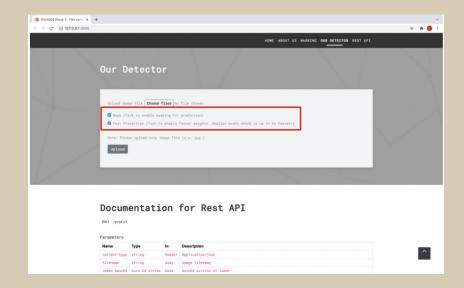


UI: Additional Features

Masking Preview



Option to Mask/Use Faster Weights



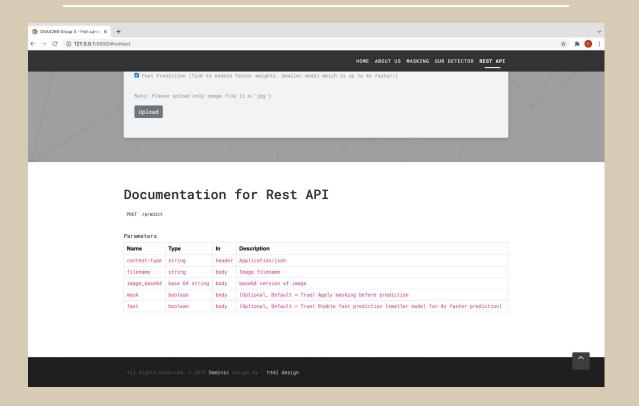
UI: Additional Outputs

- JSON file(s) (required)
- Annotated Image(s)
- Counts of classes in each image



Name	^ Date Modified	Size	Kind
2.jpg	Today at 9:39 PM	1.2 MB	JPEG image
2.json	Today at 9:39 PM	1.6 MB	Plain Text
3.jpg	Today at 9:39 PM	1.4 MB	JPEG image
3.json	Today at 9:39 PM	1.7 MB	Plain Text
counts.csv	Today at 9:39 PM	102 bytes	CSV Document

UI: Rest API



Future Work: Scalability

- Auto-balance of new dataset to remove class imbalance
 - Fish data expected to be highly skewed
 - Our data augmentation solution can be automated to balance new incoming fish data based on different seasons



	Label Type	Original Overall Number of Labels
	Fertilised Egg	348
	Unfertilised Egg	227
	Fish Larvae	879
	Unidentifiable	121



Label Type	New Overall Number of Labels
Fertilised Egg	952
Unfertilised Egg	360
Fish Larvae	953
Unidentifiable	137

Future Work: Scalability

Speed accuracy tradeoff

- Whilst our ensemble model performed the best with a 3-class mAP of 0.909, time and hardware constraint was a limiting factor
- With access to better hardware (eg. GPUs) in the future, ensemble models is viable for future offline predictions
- Transfer learning for efficient future training
 - Upstream feature extraction layers are frozen while downstream layers are allowed to learn the variation in new datasets
 - No need to train full model; reducing training times

