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Robot2_Busy_ZZ

Pick from Conveyor
and Drop on CNC3
Program running
DO[3]
Fanuc_Rbt_C2:I.
Data[0].2

Pick from Conveyor
and Drop on CNC4
Program running
DO[4]
Fanuc_Rbt_C2:I.
Data[0].3

Pick from CNC3 and
Drop on Conveyor
Program running
DO[5]
Fanuc_Rbt_C2:I.
Data[0].4

Pick from CNC4 and
Drop on Conveyor
Program running
DO[6]
Fanuc_Rbt_C2:I.
Data[0].5

(End)