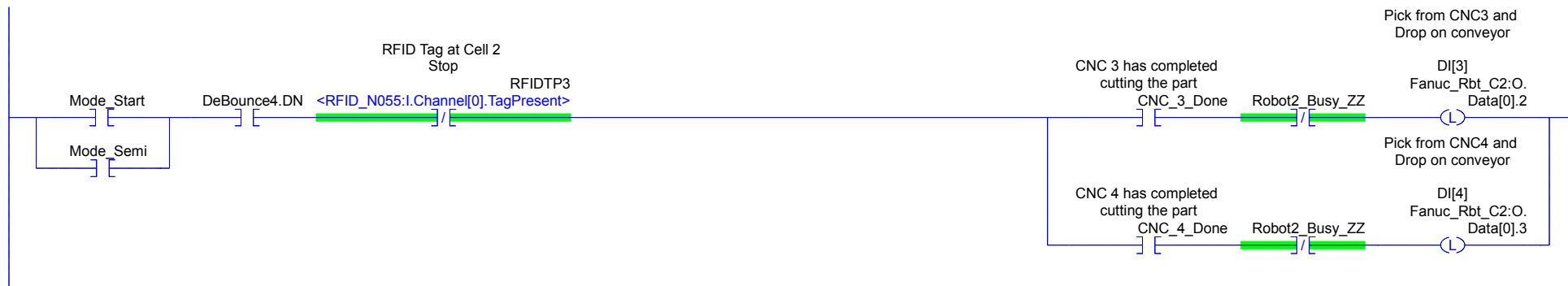
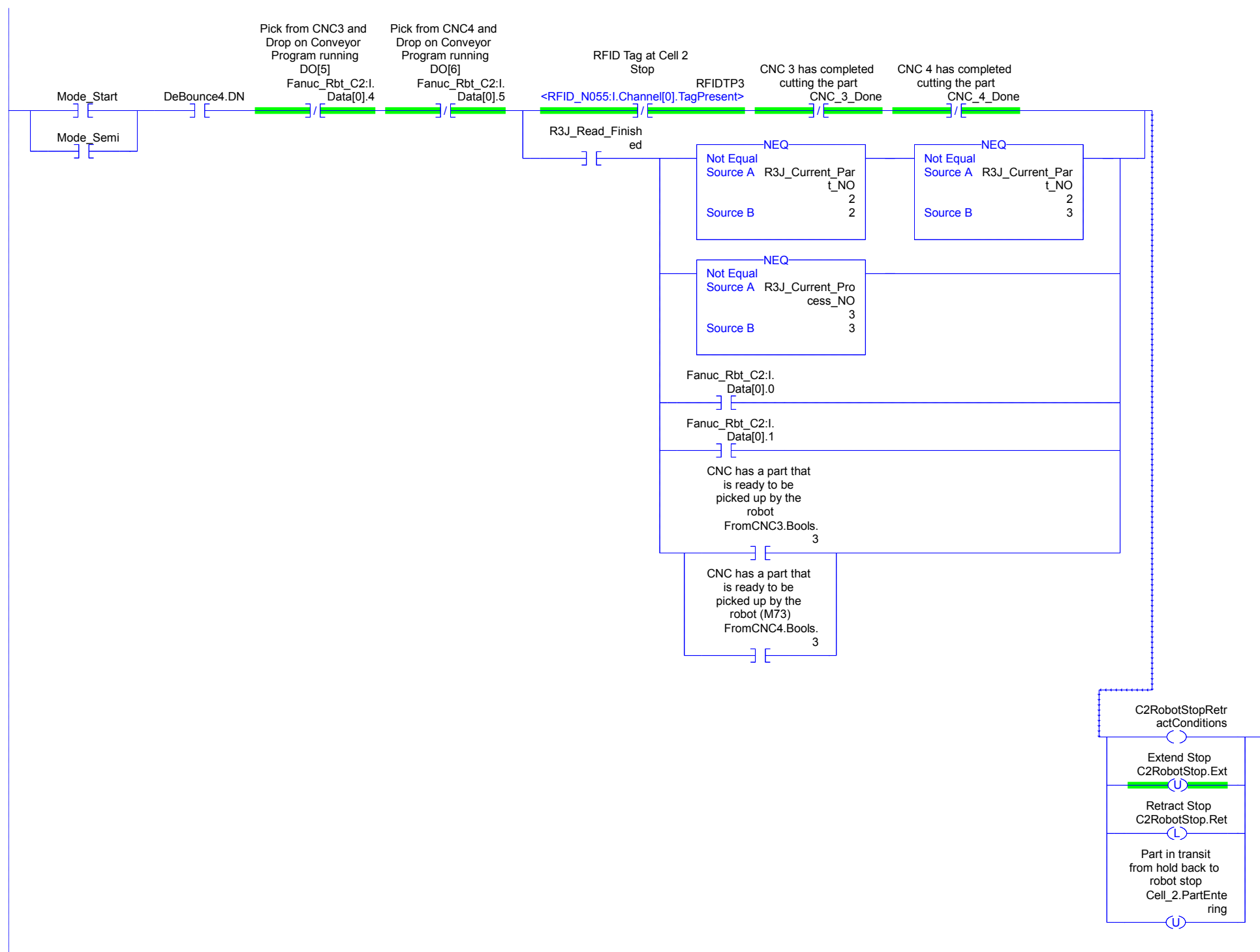
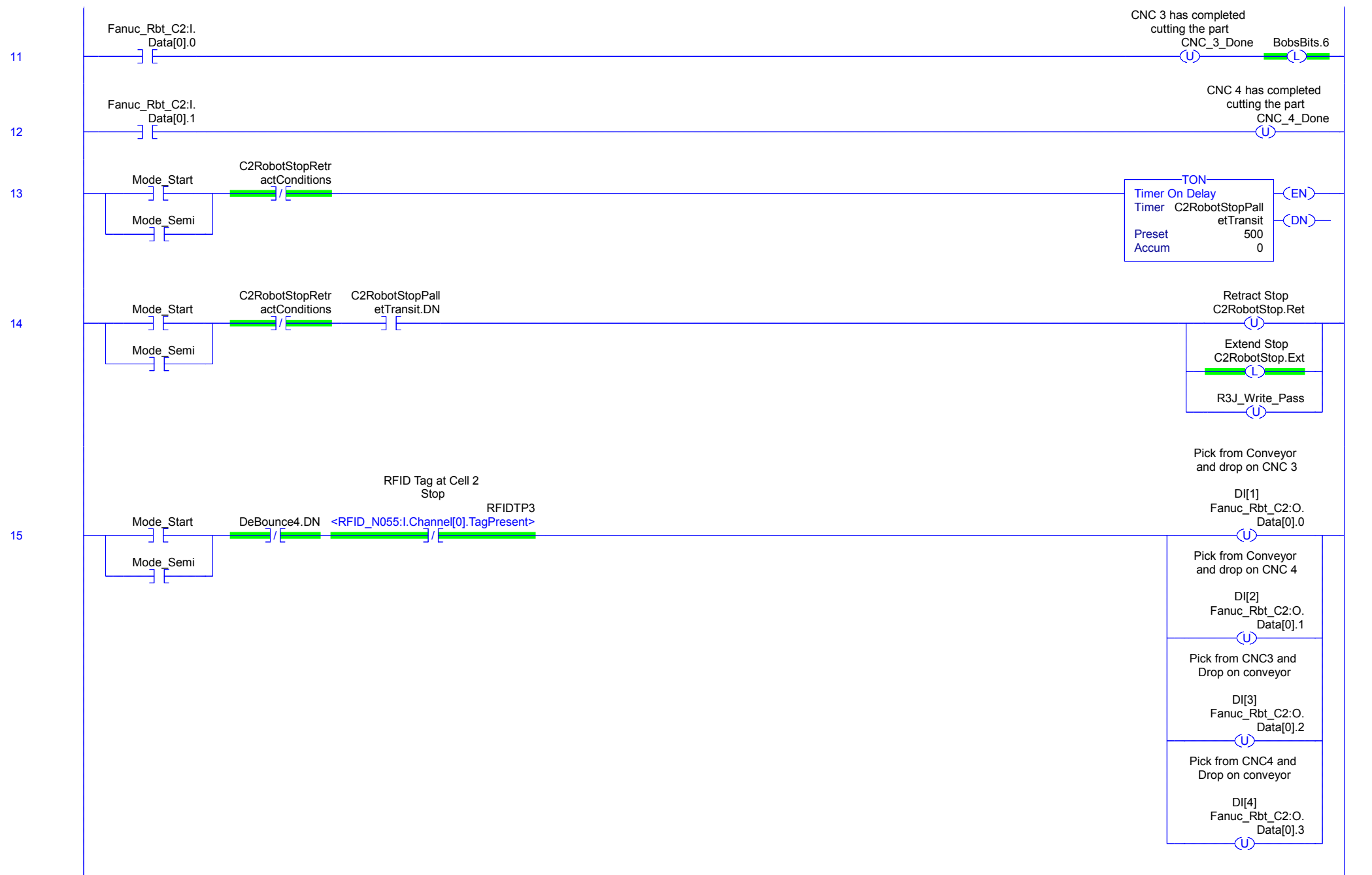


9



10





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Robot2\_Busy\_ZZ

Pick from Conveyor  
and Drop on CNC3  
Program running  
DO[3]  
Fanuc\_Rbt\_C2:I.  
Data[0].2

Pick from Conveyor  
and Drop on CNC4  
Program running  
DO[4]  
Fanuc\_Rbt\_C2:I.  
Data[0].3

Pick from CNC3 and  
Drop on Conveyor  
Program running  
DO[5]  
Fanuc\_Rbt\_C2:I.  
Data[0].4

Pick from CNC4 and  
Drop on Conveyor  
Program running  
DO[6]  
Fanuc\_Rbt\_C2:I.  
Data[0].5

(End)