



# ARTIFICIAL INTELLIGENT SYSTEMS

(BMA-EL-IZB-LJ-RE 1. YEAR 2024/2025)

## GENETIC ALGORITHMS & EVOLUTIONARY MACHINE LEARNING

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# LECTURE TOPICS

- Introduction
- Genetic algorithms
- Chromosome representation
- Examples of the use of genetic algorithm
- Applications of genetic algorithms

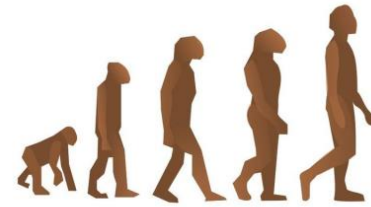


# INTRODUCTION



- In Artificial Intelligence, searching for solutions means **searching** through the **space of possible solutions**.
- Solutions or partial solutions are viewed as points in the search space.
- The problems to be solved are normally first formulated as **mathematical models** expressed in terms of functions.
- Finding solutions then means **discovering the parameters** that **optimize the model** or the function components that provide optimal system performance.
- An optimization problem is defined as **finding values** of the variables that **minimize or maximize** the objective function while satisfying the **constraints**.

# INTRODUCTION



- A genetic algorithm is an **AI search heuristic** that mimics the process of **natural selection**.
- Genetic algorithms (GAs) are the main paradigm of **evolutionary computing**.
- GAs are inspired by **Darwin's theory** about evolution – the "*survival of the fittest*".
- In nature, competition among individuals for scanty resources results in the fittest individuals dominating over the weaker ones.
- The basic principles of GAs are **selection, reproduction, inheritance, recombination/crossover, and mutation**.

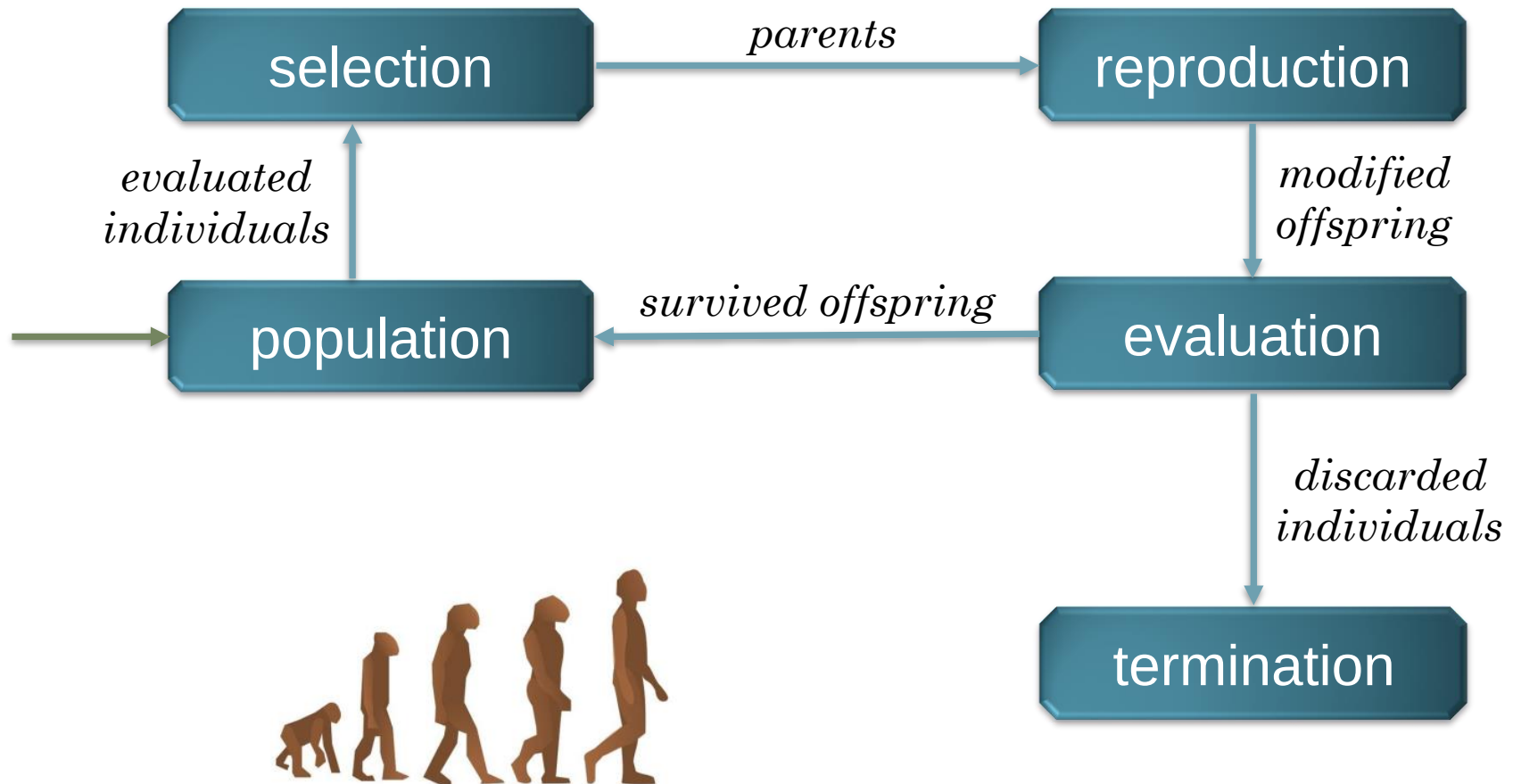
# INTRODUCTION

- In a genetic algorithm, a population of candidate solutions (called individuals or **phenotypes**) to an optimization problem **is evolved** toward better solutions.
- Each candidate solution has **a set of properties** (its chromosome or **genotype**) which can be mutated and altered.
- The evolution usually starts from a population of randomly generated individuals.
- An **iterative process** then changes the population in each iteration from generation to generation.

# INTRODUCTION

- In each generation, the **fitness** of every individual in the population is evaluated.
- The fitness is usually the value of the **objective function** in the optimization problem being solved.
- The more fit individuals are randomly selected from the current population, and each individual's genome is **recombined** with other individuals genomes and **randomly mutated** to form a new generation.
- The algorithm terminates when either a **maximum number** of generations has been produced, or a **satisfactory fitness** level has been reached for the population.

# THE EVOLUTIONARY CYCLE



# THE EVOLUTIONARY CYCLE PSEUDO CODE

BEGIN

INITIALISE population with random candidate solution.

EVALUATE each candidate;

REPEAT UNTIL termination condition is satisfied DO

1. SELECT parents;
2. RECOMBINE pairs of parents;
3. MUTATE the resulting offspring;
4. EVALUATE each candidate;
5. SELECT individuals for the next generation;

END.



# GENETIC ALGORITHMS



- A typical genetic algorithm requires:
  - a **genetic representation** of the solution domain,
  - a **fitness function** to evaluate the solution domain.
- A standard representation of each candidate solution is as **an array of bits** of fixed size.
- Such genetic representations are convenient, as their parts are easily aligned due to their fixed size.
- A fitness function is defined by an “environment” in which possible solutions “live” and reproduce.

# OUTLINE OF THE BASIC GENETIC ALGORITHM

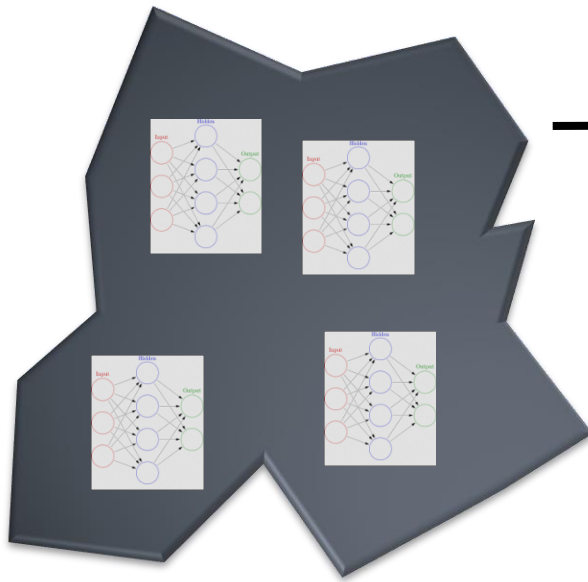
1. **[Start]** Generate a random population of  $n$  chromosomes
2. **[Fitness]** Evaluate the fitness  $f(\mathbf{x})$  of each chromosome  $\mathbf{x}$  in the population.
3. **[New population]** Create a new population by repeating following steps until the new population is complete.
  - (a) **[Selection]** Select two parent chromosomes from a population according to their fitness (better the fitness, higher the probability to be chosen)
  - (b) **[Crossover]** With a crossover probability, cross over the parents to form new offspring (children). If no crossover was performed, offspring is the exact copy of parents.
  - (c) **[Mutation]** With a mutation probability, mutate new offspring at each locus (position in chromosome).
  - (d) **[Selection]** Place new offspring in the new population
4. **[Replace]** Use new generated population for a further run of the algorithm
5. **[Test]** If the end condition is satisfied, stop, and return the best solution in current population
6. **[Loop]** Go to step 2

# SEARCHING FOR OPTIMAL MATHEMATICAL MODELS AND FUNCTIONS

- Individuals in a population are mathematical models or functions represented by the **values of their parameters** to be optimized (e.g. neural networks, decision trees, etc).
- The **genetic representations** of the individuals are derived from the parametric variables of the models or functions to be optimized.
- The **fitness function** are derived from the objective function that is defined for the original optimization problem
- The evolutionary cycle then **iteratively reproduces** the population of the individuals (models) that achieve the highest values of the fitness (objective) function.

# CHROMOSOME REPRESENTATION

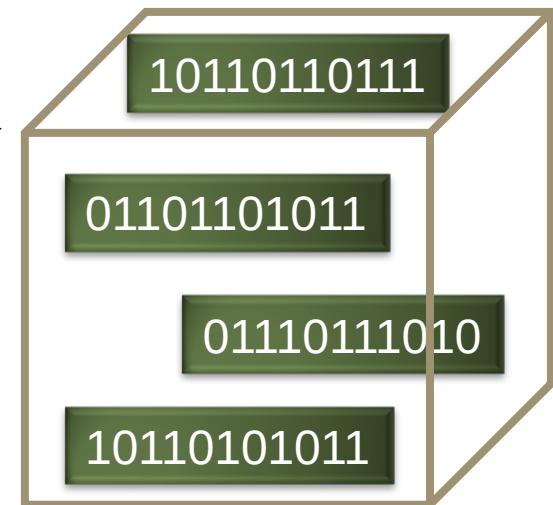
Phenotype space of  
individuals  
(mathematical models)



Encoding  
(representation)



Genotype space of  
chromosomes



Decoding  
(inverse representation)

# CHROMOSOME REPRESENTATION

- Many different genetic representations (genotypes) of individual's properties (phenotypes) have been proposed and used.
- Due to its relative simplicity, **binary encoding** is the most common representation of individual's information that is often used.
- However, binary encoding is **not natural** for many problems and sometimes corrections must be made after crossover and/or mutation, or **more complicated** crossover and mutation rules need to be used
- There are many other ways of encoding, e.g., encoding values as **integer** or **real numbers** or some **other data structures** etc.
- The use of a particular encoding method depends on the problem to be solved.

# CHROMOSOME REPRESENTATION

- Binary strings can represent strings of characters, integers or quantized real values.

```
[00101010|10010101|11101101|00101001|10011110]
```

- Nowadays it is generally accepted that it is better to encode numerical variables directly as integers

```
[42535126|09767283|86192876|76243546|67718231]
```

- Or even directly as floating point values.

```
[1.311; 3.988; 9.123|4.877; 6.712; 0.981|0.123; 9.712; 7.100]
```

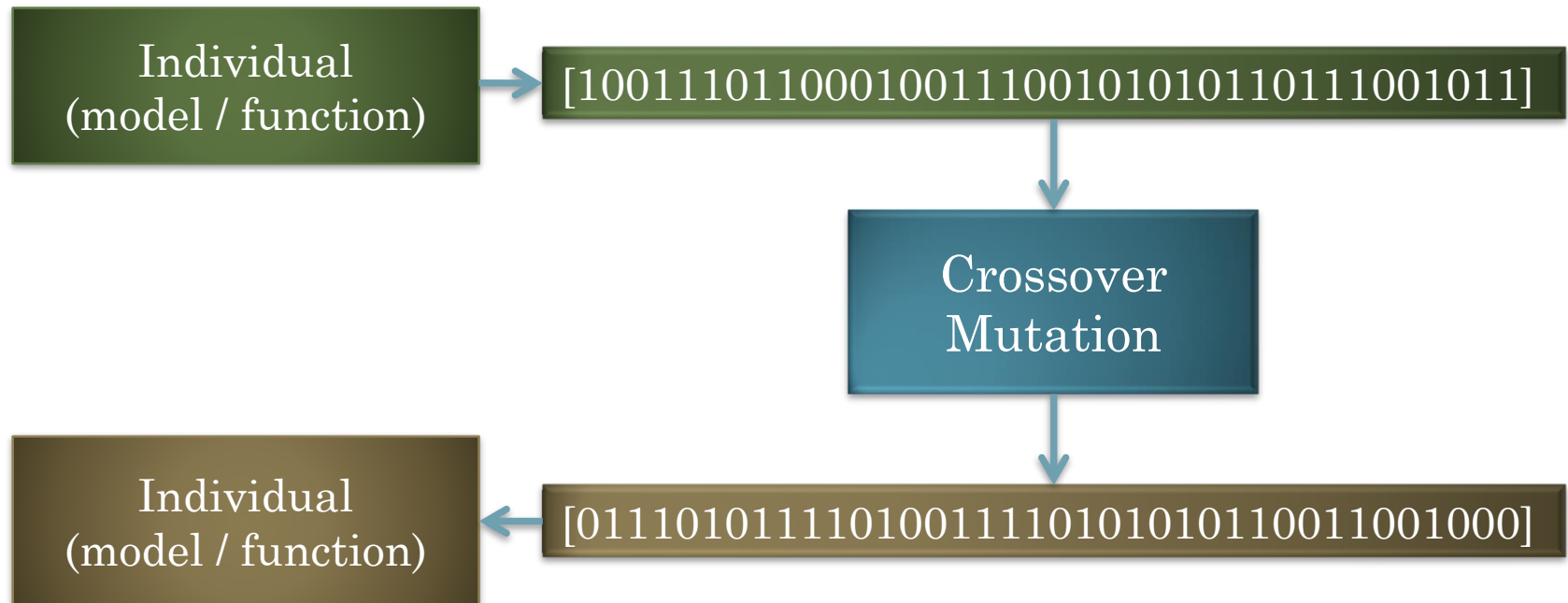
# CHROMOSOME REPRESENTATION

- A critical step for the success of a genetic algorithm is the use of an **appropriate encoding** of the parameters of the individuals into their genetic representations (chromosomes).
- Any modification of a chromosome should represent **valid** set of parameter values that are **within their range**.
- The above should be considered when the crossover and mutation operations are defined as well.
- **Gray coding** is an example of an encoding that is often used, as it ensures that small changes in the genotype cause small changes in the phenotype and vice-verse (unlike binary coding).

Dec.	Bin.	Gray
0	000	000
1	001	001
2	010	011
3	011	010
4	100	110
5	101	111
6	110	101
7	111	100

# REPRODUCTION

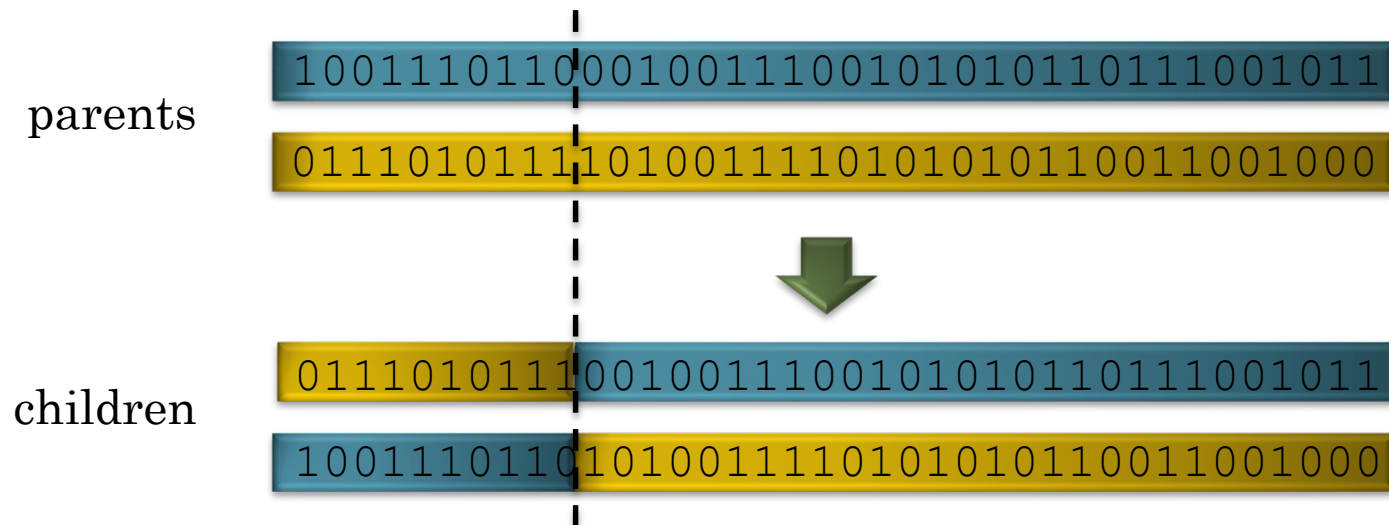
- The crossover and mutation operations are used to modify individuals from generation to generation.
- As mentioned, any modification of a chromosome should represent a **valid** set of parameter values that are **within their range**.





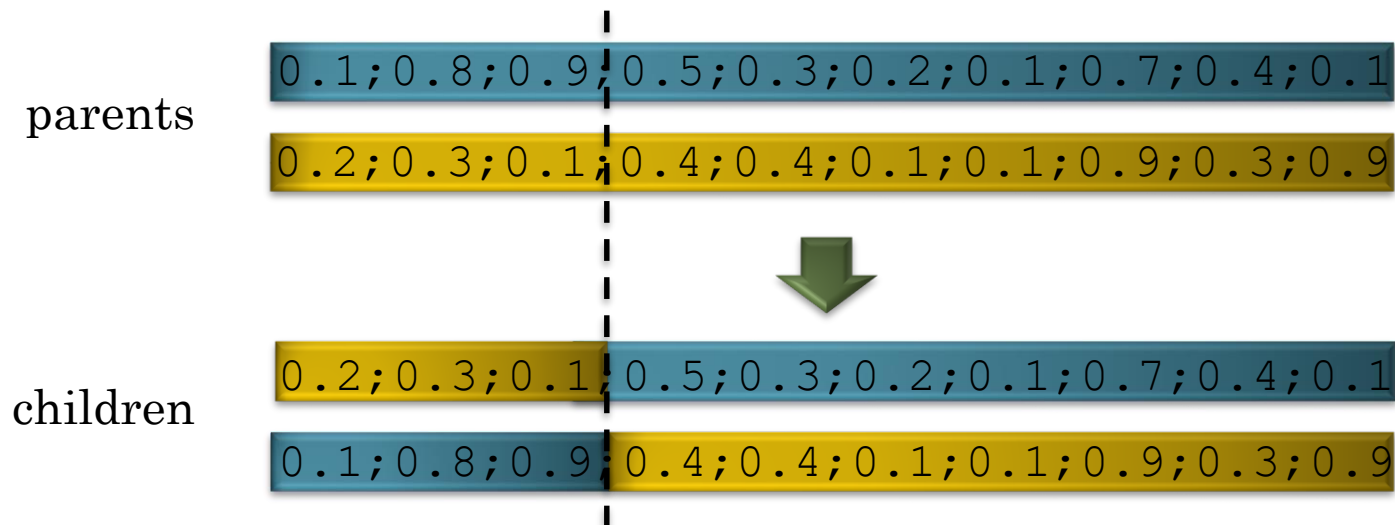
# CROSSOVER OPERATION

- Crossover is a **genetic operator** used to vary chromosomes from one generation to the next.
- Crossover is a process of taking more than one parent solutions and producing a child solution from them.
- The chromosomes of two randomly chosen individuals (parents) are crossover to create one or more children, where **1-point** or ***n*-point** crossover methods are used.



# CROSSOVER OPERATION

- For integer or real values encoded chromosomes different arithmetic crossover operations are used, such as single and simple arithmetic crossover



# MUTATION OPERATION

- With a low probability, a few genes are randomly altered in a chromosome.
- Binary, integer or real value mutations are used depending how chromosomes are encoded

10011101100010011100101010110111001011



110111011000110111001010101101110001011

0.1;0.8;0.9;0.5;0.3;0.2;0.1;0.7;0.4;0.1



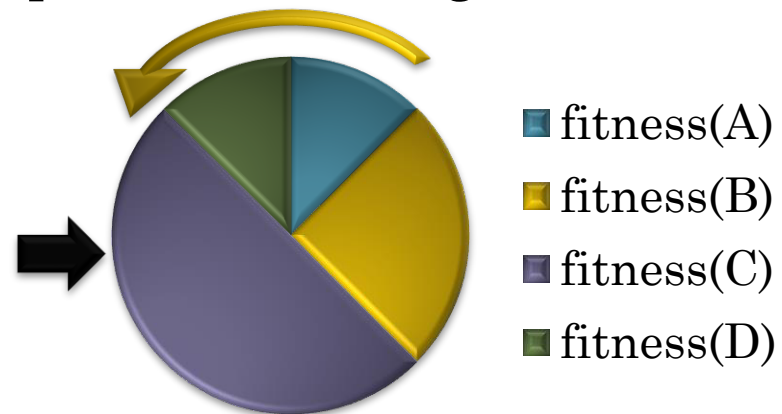
0.1;0.7;0.9;0.5;0.3;0.2;0.2;0.7;0.4;0.1

# FITNESS FUNCTION

- In general, a **fitness function** is a particular type of objective function that is used to summarise how close a given solution is to achieving the optimisation aims.
- The **fitness** used in GAs is usually the value of the objective function in the original optimization problem being solved.
- Even though the computer should come up with the final solution/design, it is the **human designer** who has to design the fitness function.
- If the fitness function is designed badly, the algorithm will either converge on an inappropriate solution, or will have **difficulty converging** at all.

# FITNESS FUNCTION AND SELECTION

- The values of function is **normalized to the sum** of its values throughout the population.
- The normalized values are then considered as the **probabilities of reproduction** of each individual represented by their chromosomes.
- A higher value of the normalised fitness functions means a **higher probability** of reproduction of the individual.
- A **random selection** is then implemented using the roulette wheel technique.
- Assign to each individual a part of the roulette wheel and spin the wheel  $n$  times to select  $n$  individuals.



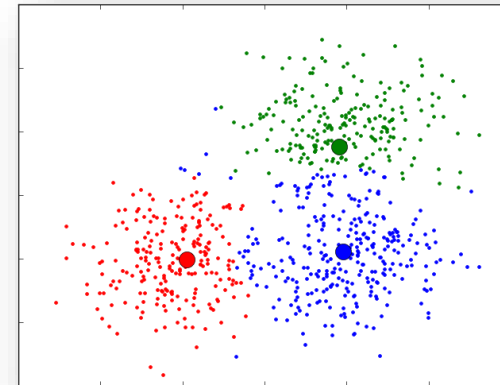
# EXAMPLES

- **k-means clustering** is a classical datamining algorithm that aims at partitioning  $n$  observations into  $k$  clusters in which each observation belongs to the cluster with the nearest mean observation, serving as a prototype of the cluster.

$$[\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m] = [w_{11}; w_{12}; \dots; w_{1l} | w_{21}; w_{22}; \dots; w_{2l} | \dots | w_{m1}; w_{m2}; \dots; w_{ml}]$$

$$J([\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m]) = \sum_{i=1}^n \sum_{j=1}^m \mu_{ij} d(\mathbf{x}_i, \mathbf{w}_j)$$

$$\mu_{ij} = \begin{cases} 1 & , \quad d(\mathbf{x}_i, \mathbf{w}_j) = \min_{k=1, \dots, m} d(\mathbf{x}_i, \mathbf{w}_k) \\ 0 & , \quad \text{otherwise} \end{cases}$$



- Chromosomes are encoded as sequences of prototype vectors values.
- Crossover is allowed only on contacts between the vectors in the chromosomes.
- Mutations are small random changes of the vector values.

# SEARCHING FOR A MAXIMUM OF A MULTIVARIATE FUNCTION

- Searching for a maximum of a function  $f_1(x, y)$  that is constrained with a function  $f_2(x, y)$ .

- The domain of the both function is the same

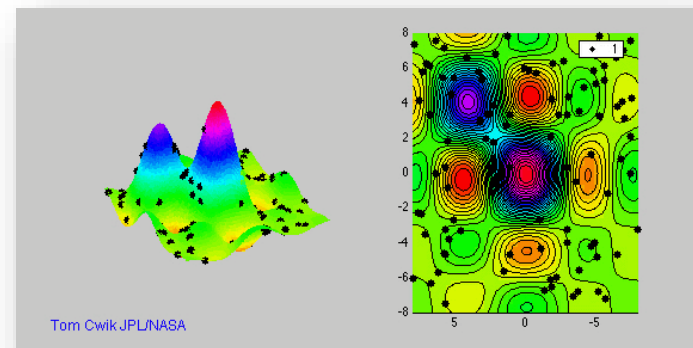
$$(x, y) \in [0, 10) \times [0, 10)$$

- Chromosomes are coded as an eight-digit decimal code

$$(x = 7,623, y = 3,098) \rightarrow [76233098]$$

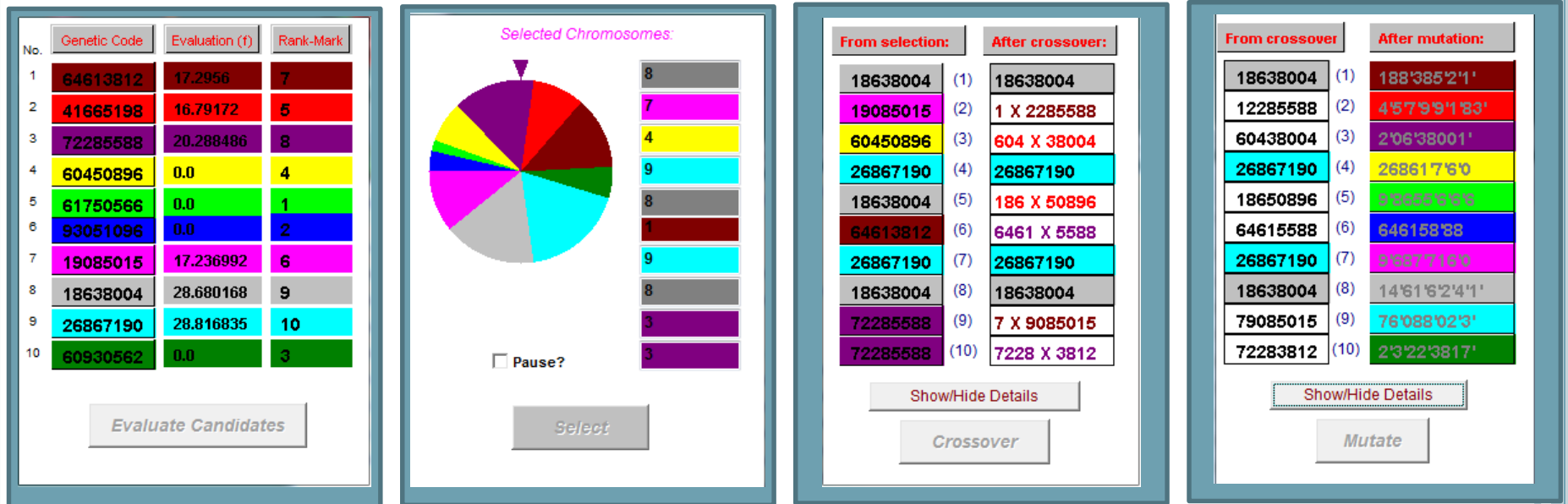
- Crossover is carried out with a cut at one random point

[76233098]  
[53094145]       $\rightarrow$       [76233145]  
[53094098]



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# SEARCHING FOR A MAXIMUM OF A MULTIVARIATE FUNCTION



(c) Yun Li & Sylvain Marquios, University of Glasgow



# ADVANTAGES OF GENETIC ALGORITHMS

- Genetic algorithms are usually simple and are easy to be implemented.
- They can be **parallelized** with a little effort.
- Objective functions that are **not smooth**, are **noisy** and their derivatives does not exists can still be used as the fitness function for a genetic algorithm.
- Genetic algorithms can also handle with the **stochastic** nature of objective functions.
- They are flexible to hybridize with other techniques.

# LIMITATIONS OF GENETIC ALGORITHMS

- Repeated **fitness function evaluation** for **complex problems** is often the most prohibitive and limiting segment of genetic algorithms.
- Where the number of elements which are exposed to mutation is large there is often an exponential increase in search space size.
- The "better" solution is only in comparison to other solutions, and **the stop criterion is not clear** in every problem.
- In many problems, GAs may have a tendency to converge towards local optima or even arbitrary points rather than the global optimum of the problem.
- GAs cannot effectively solve problems in which the only fitness measure is a **single right/wrong** measure.
- For specific optimization problems, other optimization algorithms **may be more efficient** in terms of speed of convergence.

# APPLICATIONS OF GENETIC ALGORITHMS

- Automated design
- Bioinformatics - RNA structure prediction.
- Code-breaking
- Control engineering
- Learning robot behavior
- Multimodal Optimization
- Timetabling problems,
- Training artificial neural networks
- Traveling salesman problem and its applications.
- ...

# RELATED ALGORITHMS

- Swarm intelligence  
(candidate solutions moves in the search space)
- Ant colony optimization
- Particle swarm optimization
- Intelligent Water Drops  
(modifying the amount of soil on the river's bed)
- Simulated annealing
- Tabu search
- Harmony search
- Memetic algorithm  
(the idea comes from memes, which unlike genes, can adapt themselves.)
- Cultural algorithm
- ...

# QUESTIONS

- What is the aim of genetic algorithms?
- What are the main operators of generic algorithms?
- How potential solutions of a problem are encoded into chromosomes?
- What are the advantages and limitations of genetic algorithms?
- Give an example of optimization with a genetic algorithm.