

Angular Kinetics

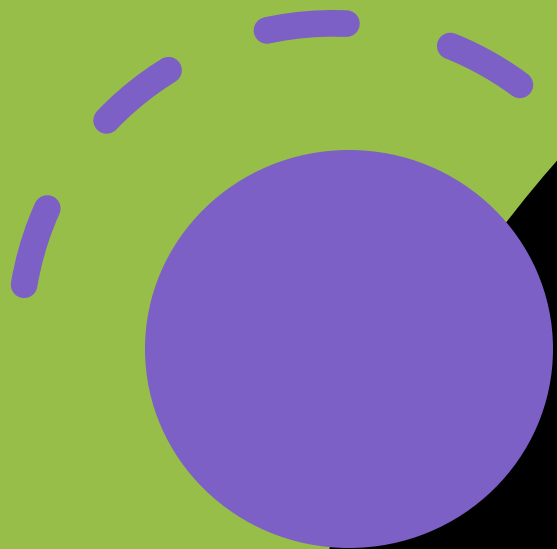
Moment of Inertia

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Stanford University

Biomechanical Analysis of Human Movement

Queen's University (KNPE 254)



Warmup

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What is the angular equivalent of displacement?

Position

Angular displacement

Angle

None of the above

Total Results: 0

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What is the angular equivalent of displacement?

Position

Angular displacement

Angle

None of the above

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What is the angular equivalent of displacement?

Position

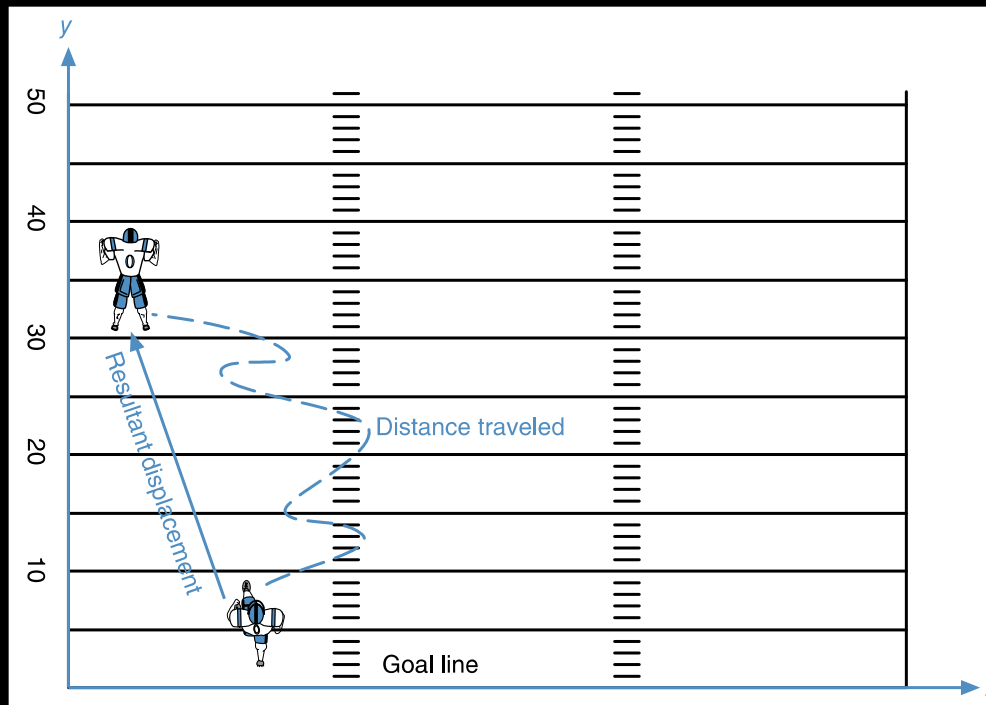
Angular displacement

Angle

None of the above

(Angular) Displacement

Linear Displacement



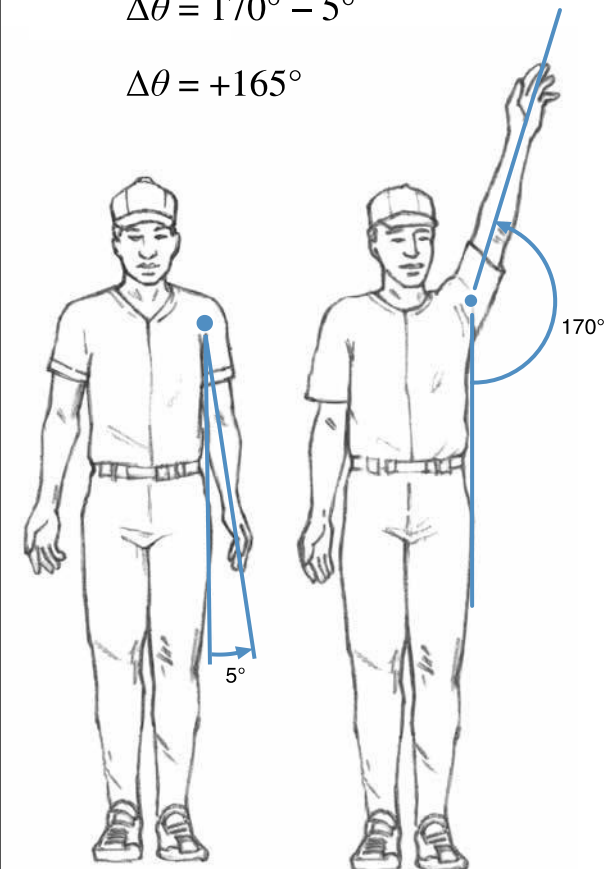
Angular Displacement

$$\Delta\theta = \theta_f - \theta_i$$

$$\Delta\theta = 170^\circ - 5^\circ$$

$$\Delta\theta = +165^\circ$$

(6.2)



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What is the angular equivalent of acceleration?

RPM

Omega

Angular
Acceleration

Circumfrential
Acceleration

None of the
above

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(Angular) Acceleration

Average
Acceleration

$$\bar{a} = \frac{\Delta v}{\Delta t} = \frac{v_f - v_i}{\Delta t}$$

Average
Angular Acceleration

$$\bar{\alpha} = \frac{\Delta \omega}{\Delta t} = \frac{\omega_f - \omega_i}{\Delta t}$$



♥ MOVIE TIME ♥



I'M SO EXCITED!!



CAN'T WAIT!!!

What did you notice in the video?
What did you wonder about?

Top

What did you notice/wonder about in the video?

- There's a solid and a hollow cylinder
- Are they the same weight?
- They are on a ramp
 - Why are they on a ramp!?
- It's a race!
 - Who's going to win?

Linear Inertia (mass)

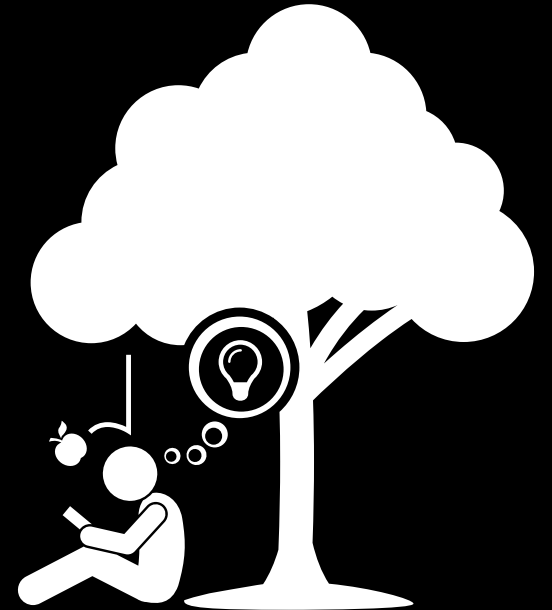
A body's tendency/ability to resist change in motion

$$F = ma$$

$F = \text{Force}$

$m = \text{mass}$

$a = \text{acceleration}$



Linear Inertia (mass)

A body's tendency/ability to resist change in motion

$$F = ma$$

$$a \propto F \quad \text{constant } m$$

$$\frac{F}{m} = a$$

$$a \propto \frac{1}{m} \quad \text{constant } F$$

$$a = \frac{F}{m}$$

Angular Inertia (Moment of Inertia)

A body's tendency/ability to resist change in angular motion

$$\tau = I\alpha$$

$\tau = \text{Torque}$

$I = \text{moment of inertia}$

$\alpha = \text{angular acceleration}$



Angular Inertia (Moment of Inertia)

A body's tendency/ability to resist change in angular motion

$$\tau = I\alpha$$

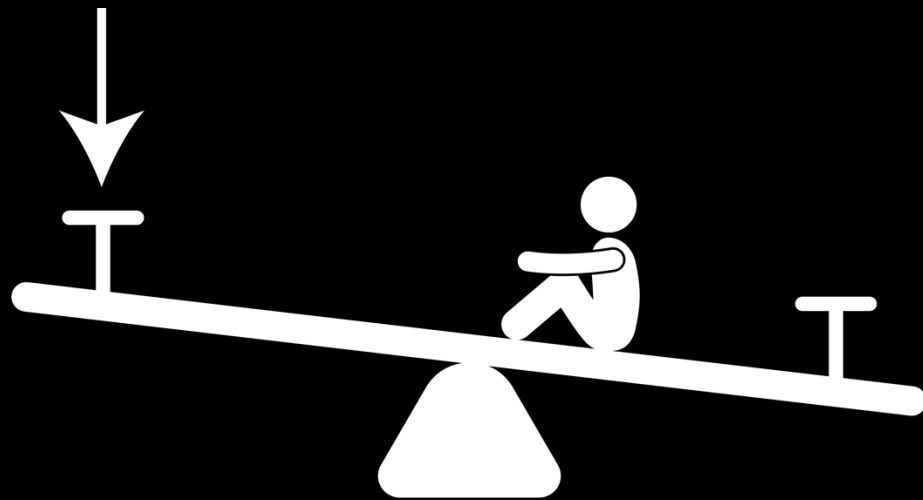
$$\alpha \propto \tau \quad \text{constant } I$$

$$\frac{\tau}{I} = \alpha$$

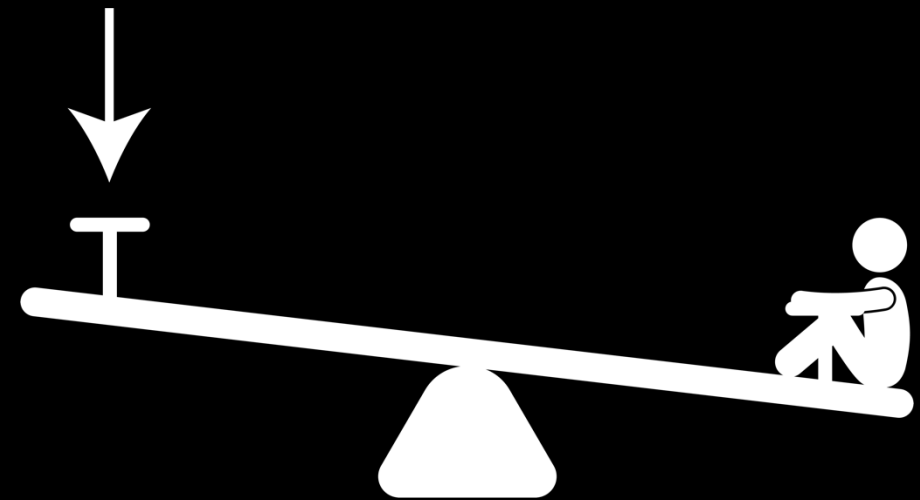
$$\alpha \propto \frac{1}{I} \quad \text{constant } \tau$$

$$\alpha = \frac{\tau}{I}$$

Moment of Inertia (I) in the real world



Close to axis of rotation

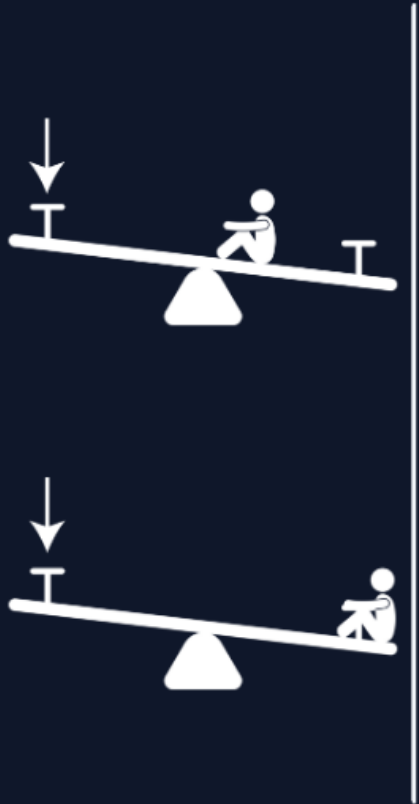


Far from axis of rotation

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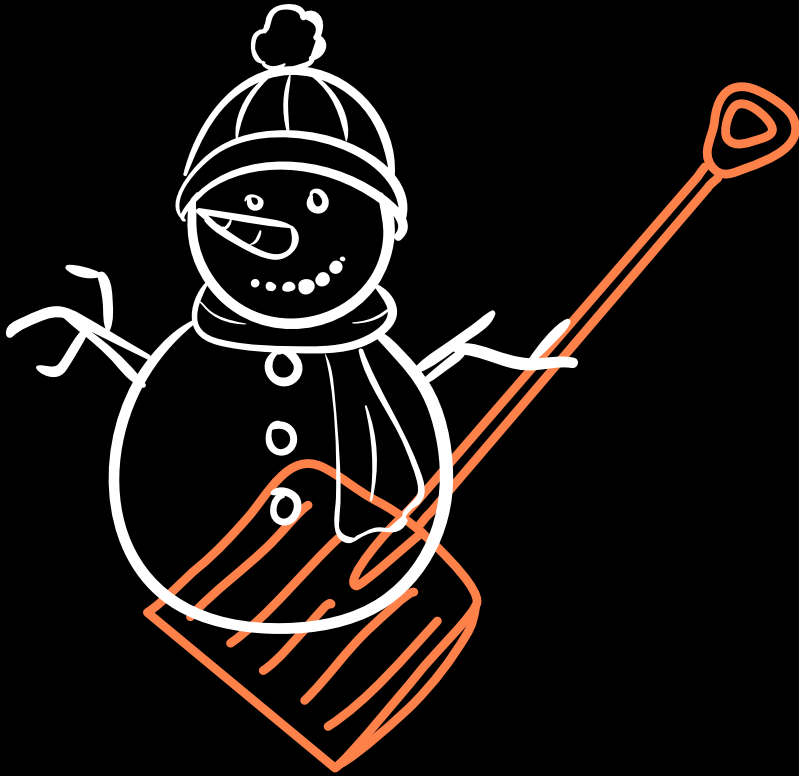
Which will resist rotating most?



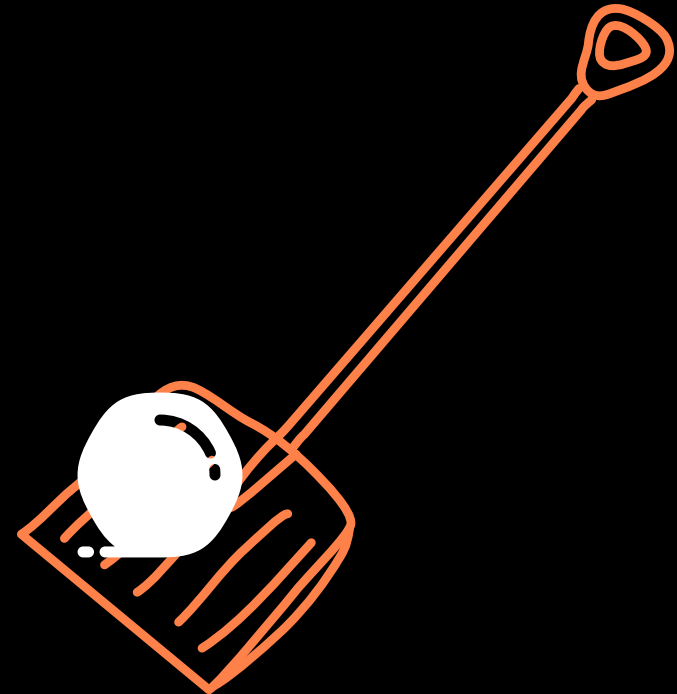
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Moment of Inertia (I) in the real world



Large mass



Small mass

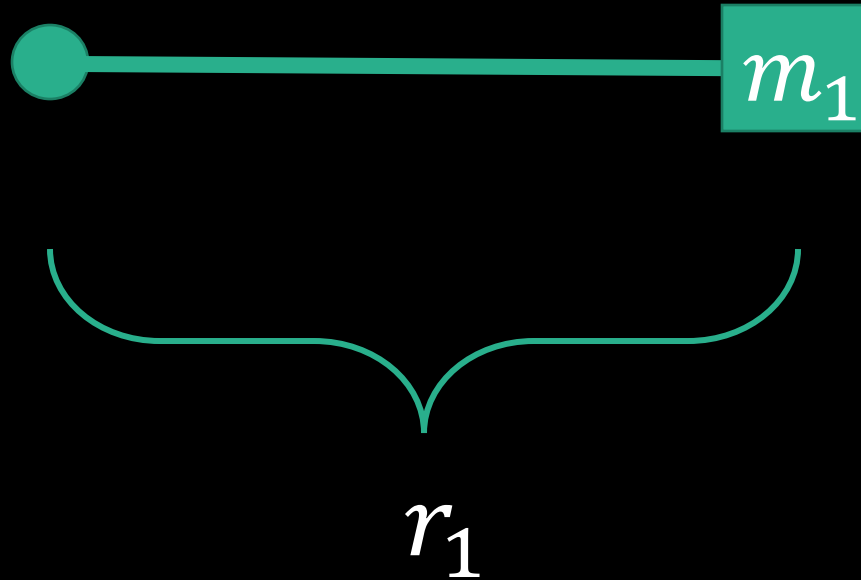
Calculating Moment of Inertia

$$I = mr^2$$

I = moment of inertia

m = mass

r = radius



Calculating Moment of Inertia

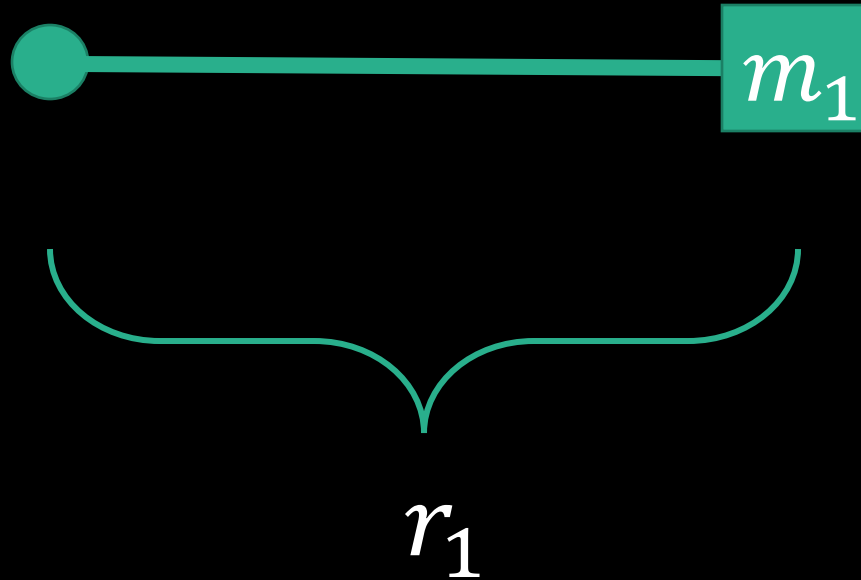
$$I = mr^2$$

$$I = 10 \times 1^2$$

$$I = 10 \text{ kg}\cdot\text{m}^2$$

$$m_1 = 10 \text{ kg}$$

$$r_1 = 1 \text{ m}$$



Calculating Moment of Inertia

$$I = mr^2$$

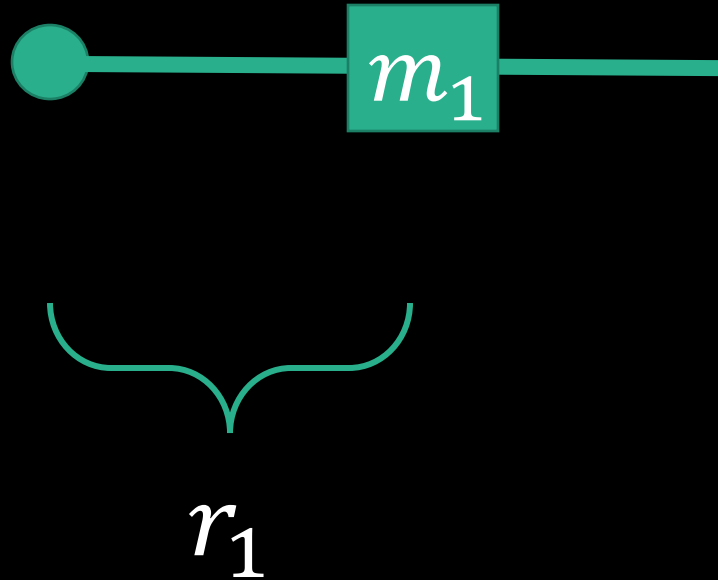
$$I = 10 \times 0.5^2$$

$$I = 10 \times$$

$$0.25$$

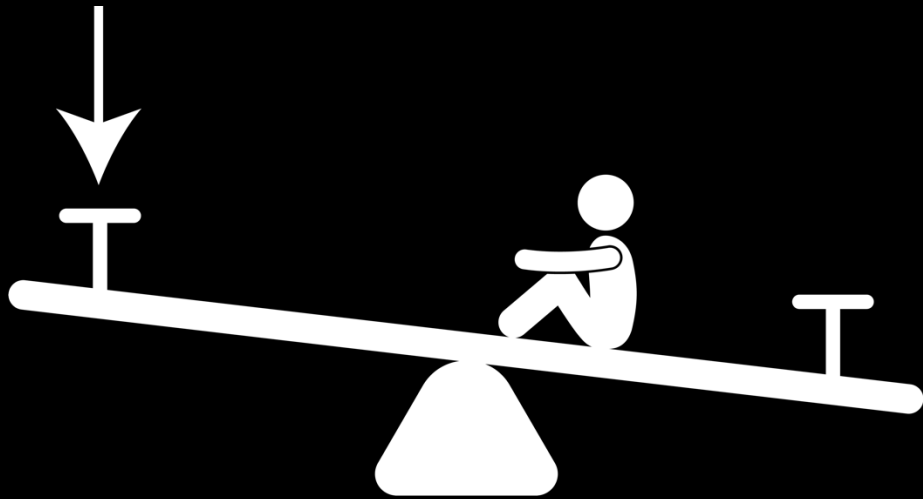
$$I_1 = 12.5 \text{ kg}\cdot\text{m}^2$$

$$r_1 = 0.5\text{m}$$

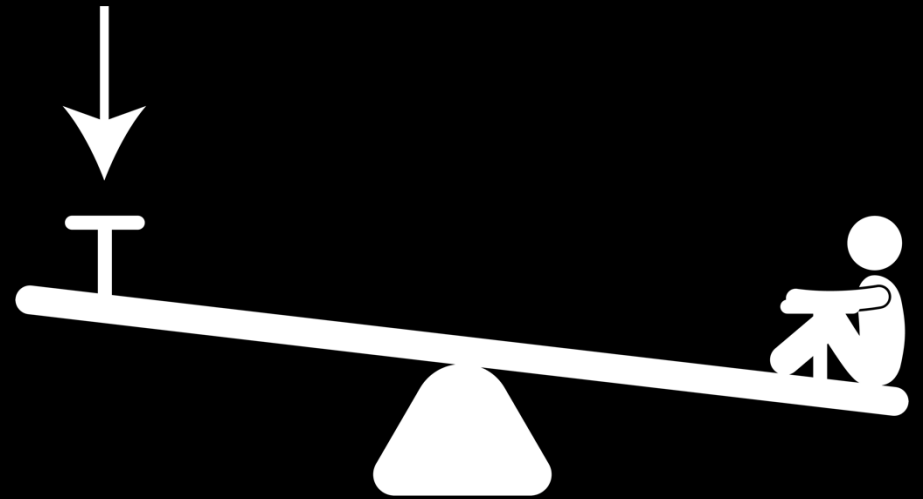


Calculating Moment of Inertia

$$I = mr^2$$



Small Moment of Inertia



Big Moment of Inertia

Calculating Moment of Inertia

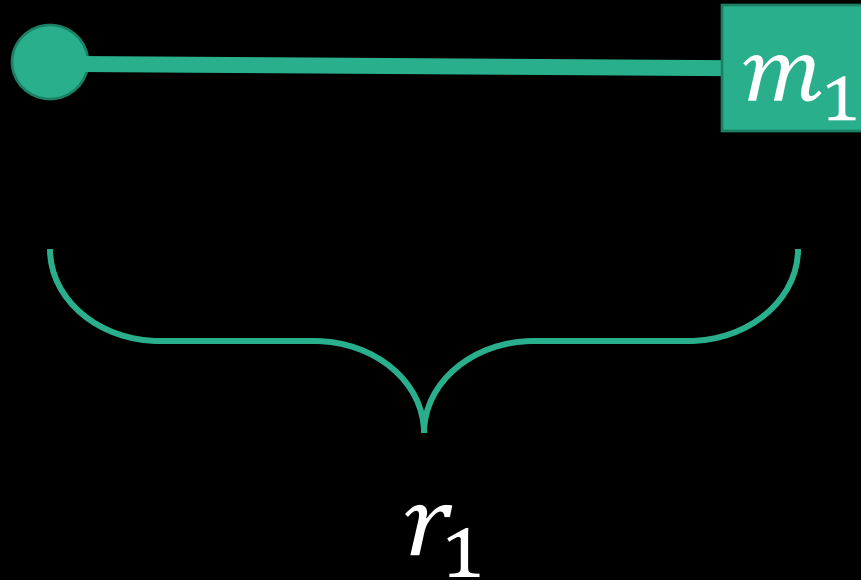
$$I = mr^2$$

$$I = 10 \times 1^2$$

$$I = 10 \text{ kg}\cdot\text{m}^2$$

$$m_1 = 10 \text{ kg}$$

$$r_1 = 1 \text{ m}$$



Calculating Moment of Inertia

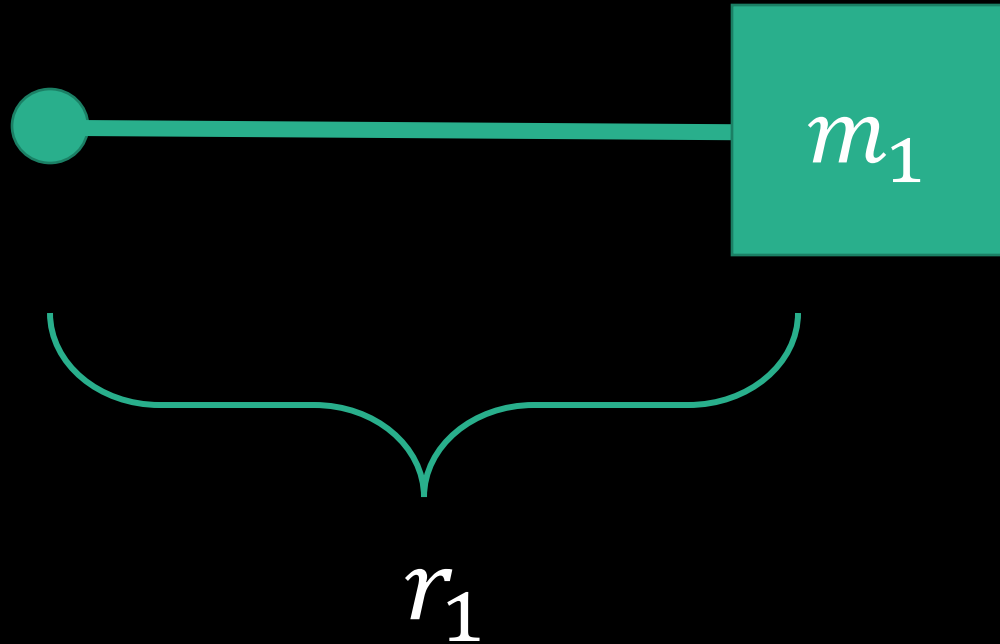
$$I = mr^2$$

$$I = 20 \times 1^2$$

$$I = 20 \text{ kg}\cdot\text{m}^2$$

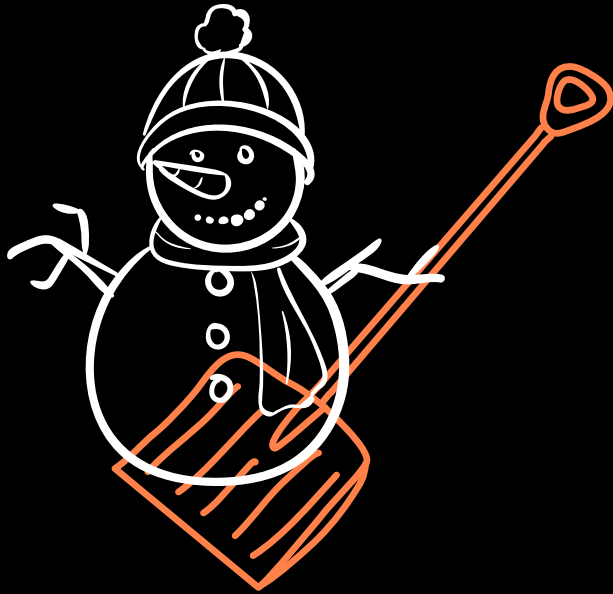
$$m_1 = 20 \text{ kg}$$

$$r_1 = 1 \text{ m}$$

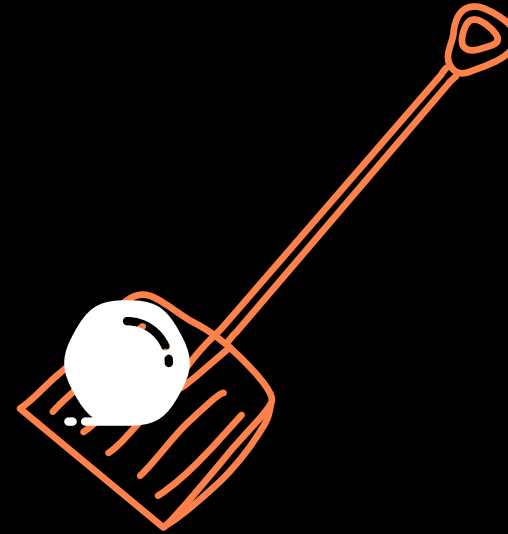


Calculating Moment of Inertia

$$I = mr^2$$



Big Moment of Inertia



Small Moment of Inertia

Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$

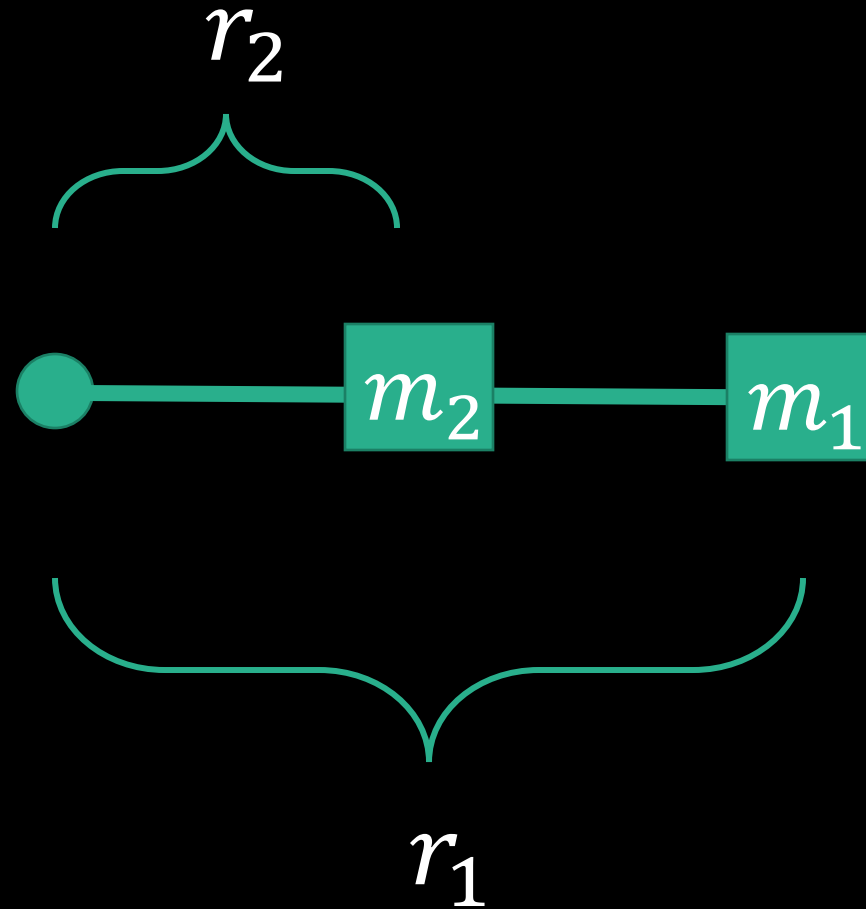
I = moment of inertia

m = mass

r = radius

Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$



$I =$ moment of inertia

$m =$ mass

$r =$ radius

Calculating Moment of Inertia

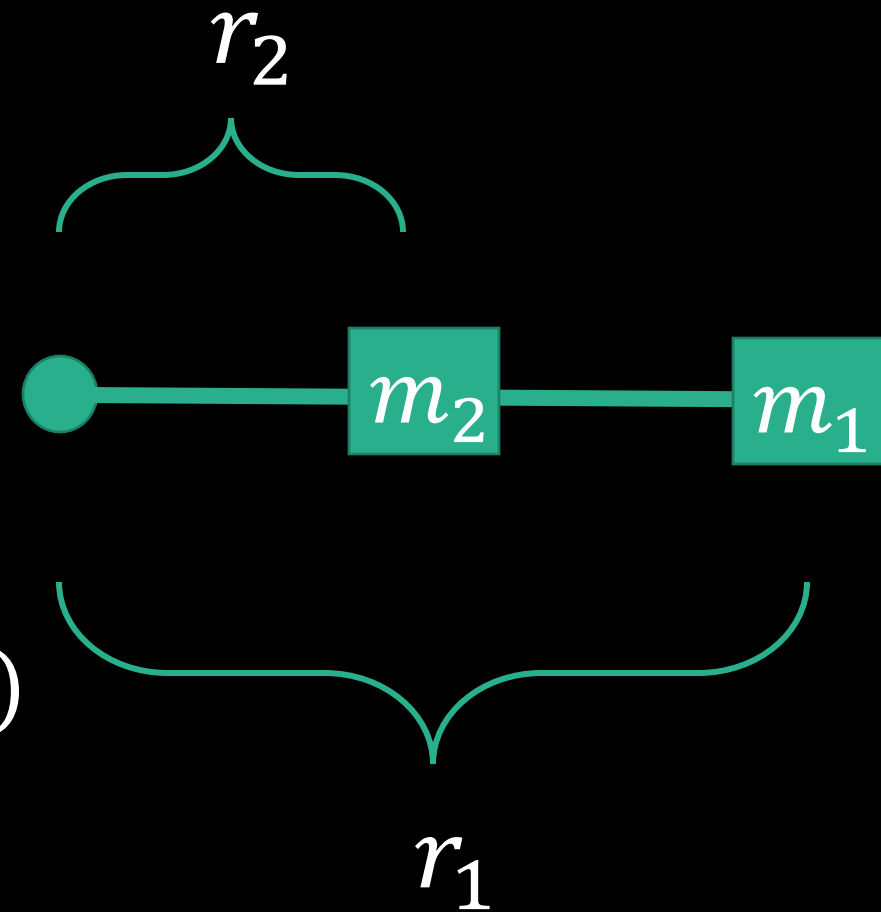
$$I = \sum m_i r_i^2$$

$$I = m_1 r_1^2 + m_2 r_2^2$$

$$I = 10 (1^2) + 10(0.5^2)$$

$$I = 10 + 2.5$$

$$I = 12.5 \text{ kg}\cdot\text{m}^2$$

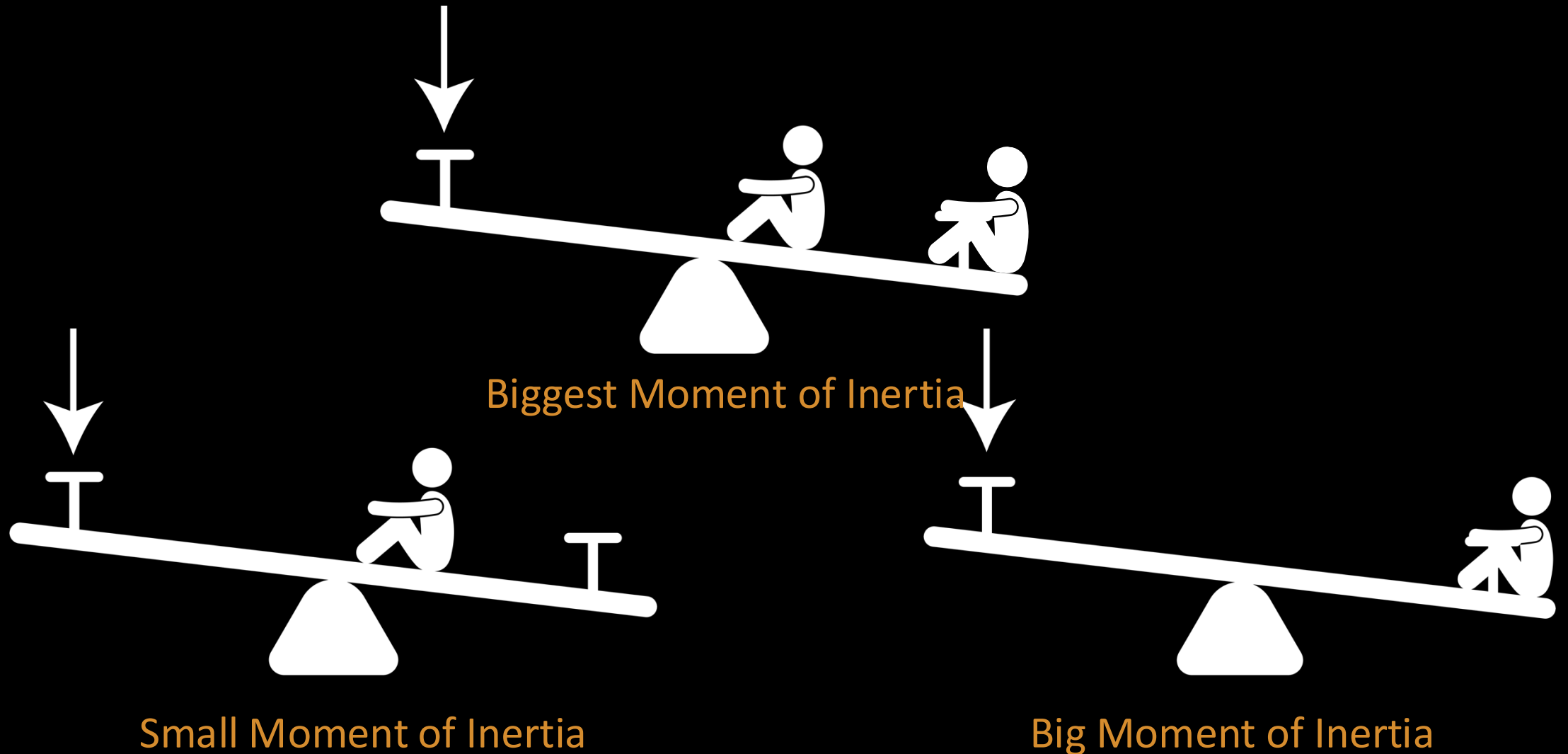


$$m_1 = m_2 = 10 \text{ kg}$$

$$r_1 = 1 \text{ m}$$

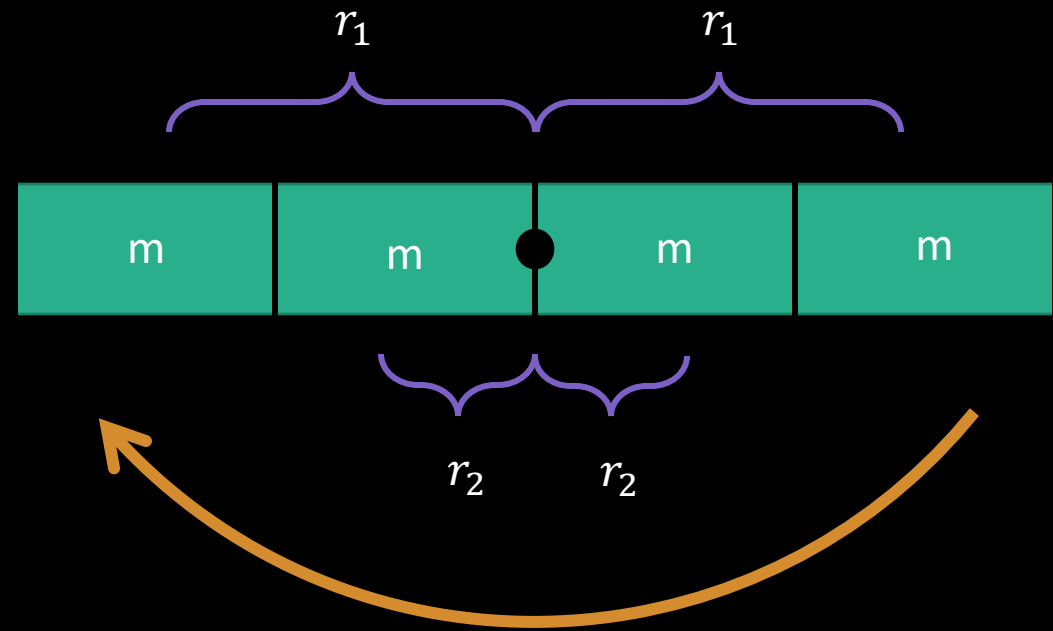
$$r_2 = 0.5 \text{ m}$$

Calculating Moment of Inertia



Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$



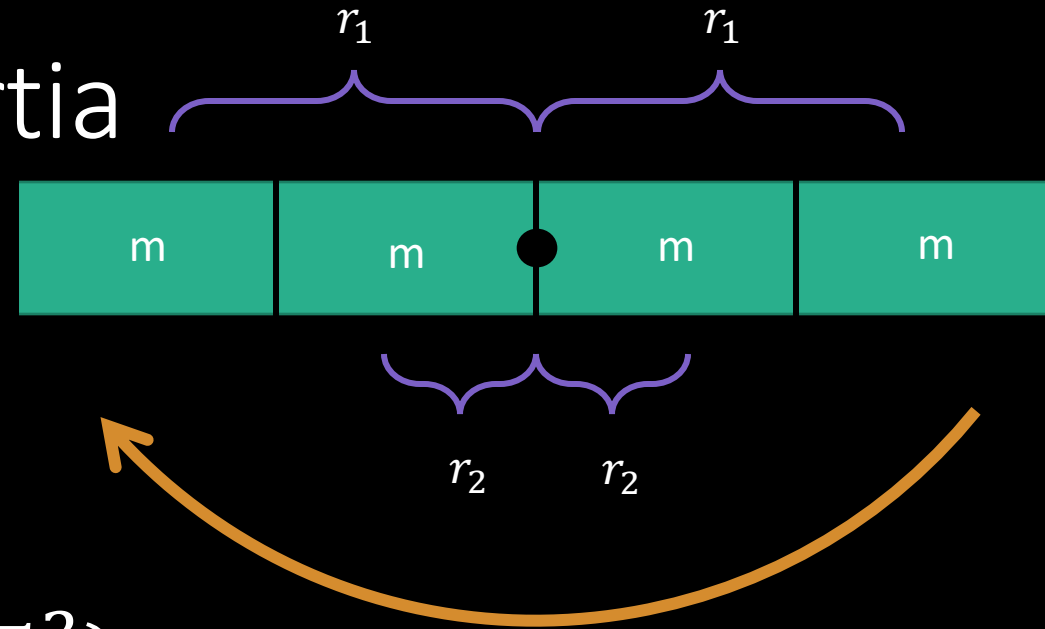
I = moment of inertia

m = mass

r = radius

Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$



$$\frac{I}{2} = mr_1^2 + mr_2^2$$

$$\frac{I}{2} = 10(1^2) + 10(0.5^2)$$

$$\frac{I}{2} = 10 + 2.5$$

$$\frac{I}{2} = 12.5 \quad I \text{ for one half of the rod}$$

$$I = 25 \text{ kg}\cdot\text{m}^2$$

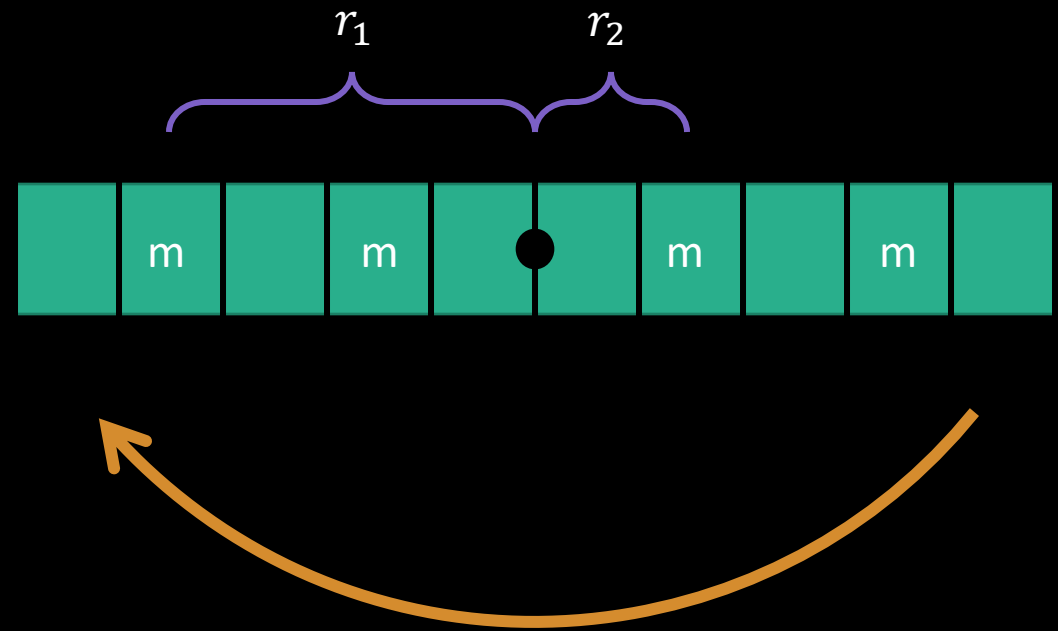
$$m = 10 \text{ kg}$$

$$r_1 = 1 \text{ m}$$

$$r_2 = 0.5 \text{ m}$$

Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$



I = moment of inertia

m = mass

r = radius

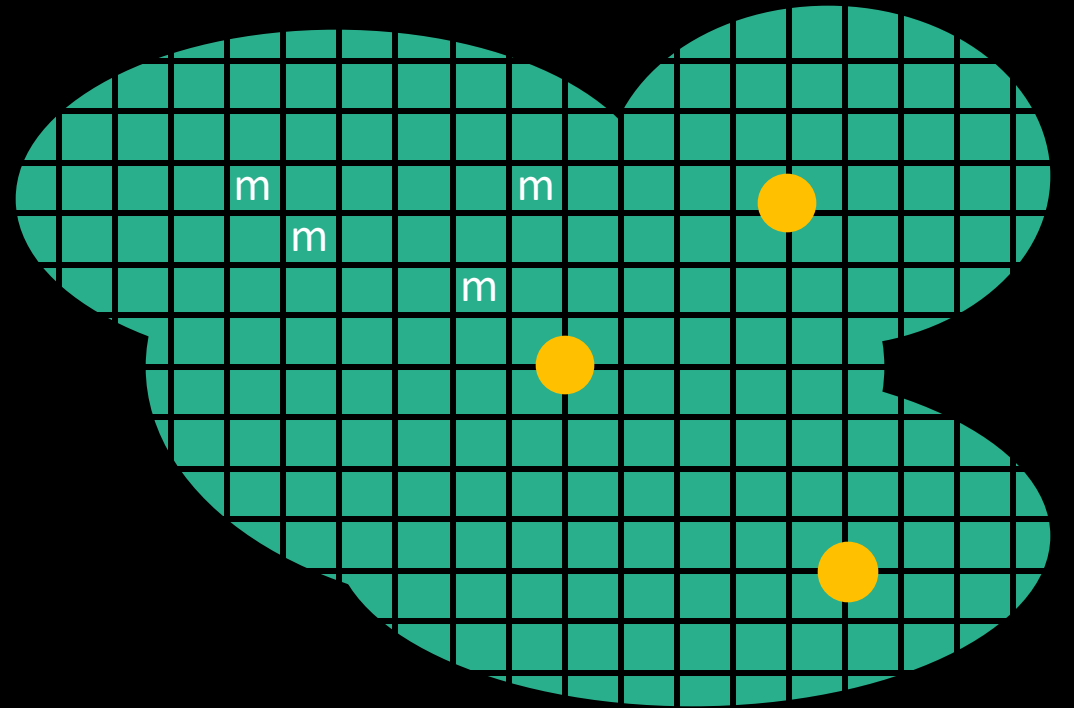
Calculating Moment of Inertia

$$I = \sum m_i r_i^2$$


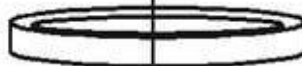

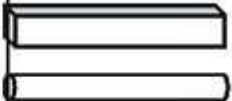


I = moment of inertia

m = mass

r = radius



Calculating Moment of Inertia

<i>Object</i>	<i>Drawing</i>	<i>Moment of Inertia</i>
Disk (rotated about center)		$\frac{1}{2}MR^2$
Ring (rotated about center)		MR^2
Rod or plank (rotated about center)		$\frac{1}{12}ML^2$
Rod or plank (rotated about end)		$\frac{1}{3}ML^2$
Sphere		$\frac{2}{5}MR^2$
Satellite		MR^2

Moving I - Parallel Axis Theorem

$$I_{new\ axis} = I_{Center\ of\ gravity} + mr^2$$

Rod or plank (rotated about center)		$\frac{1}{12}ML^2$
Rod or plank (rotated about end)		$\frac{1}{3}ML^2$

Moment of Inertia (I) in Sports

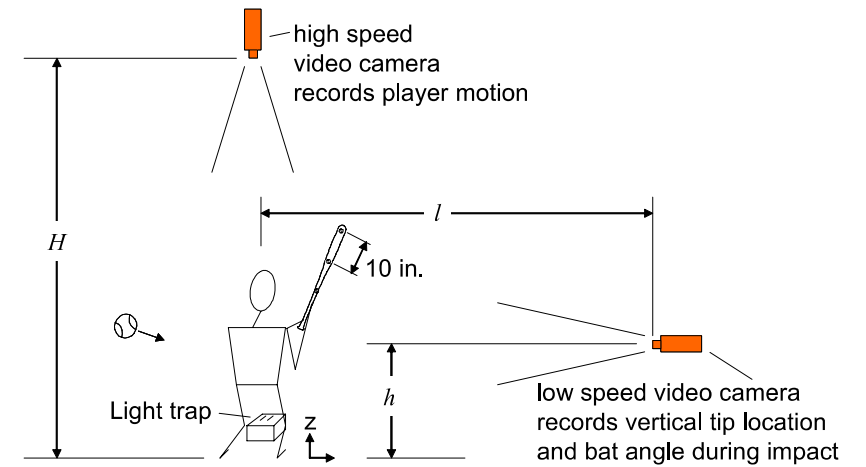


Figure 2. Schematic of video system used to determine the bat speed.

Moment of Inertia (I) in Sports

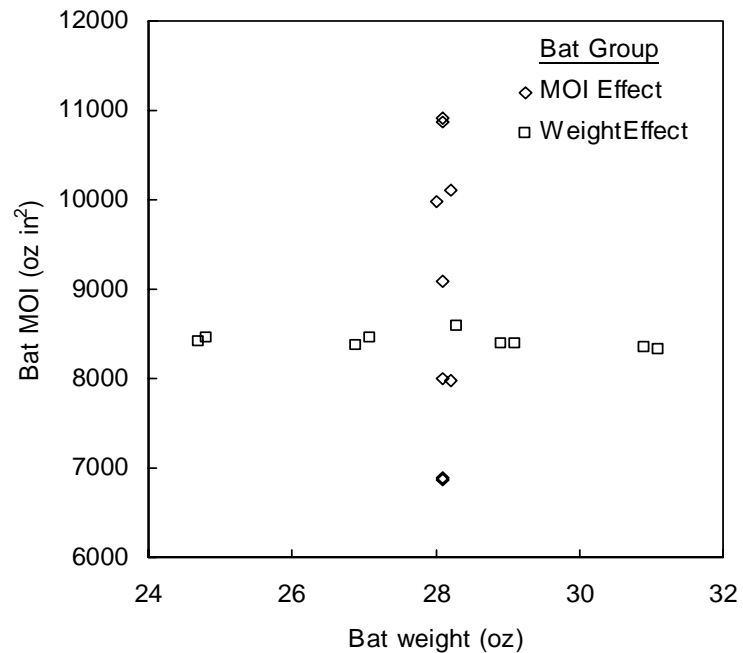


Figure 1. Weight and MOI of the 20 bats

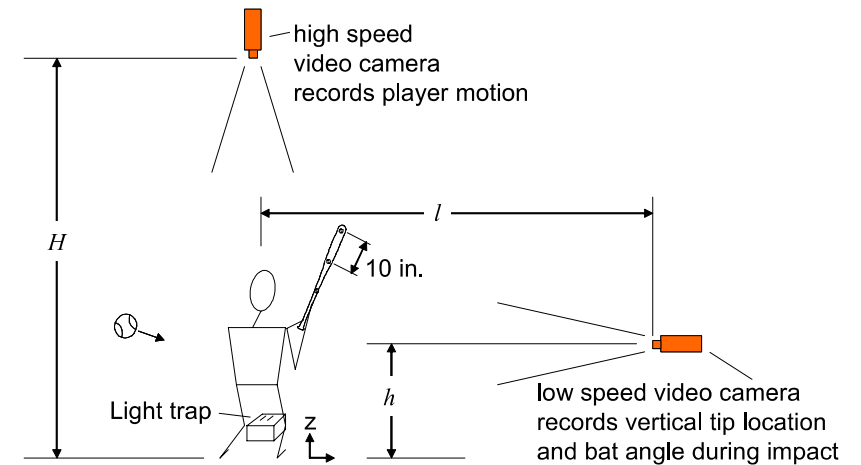


Figure 2. Schematic of video system used to determine the bat speed.

Moment of Inertia (I) in Sports

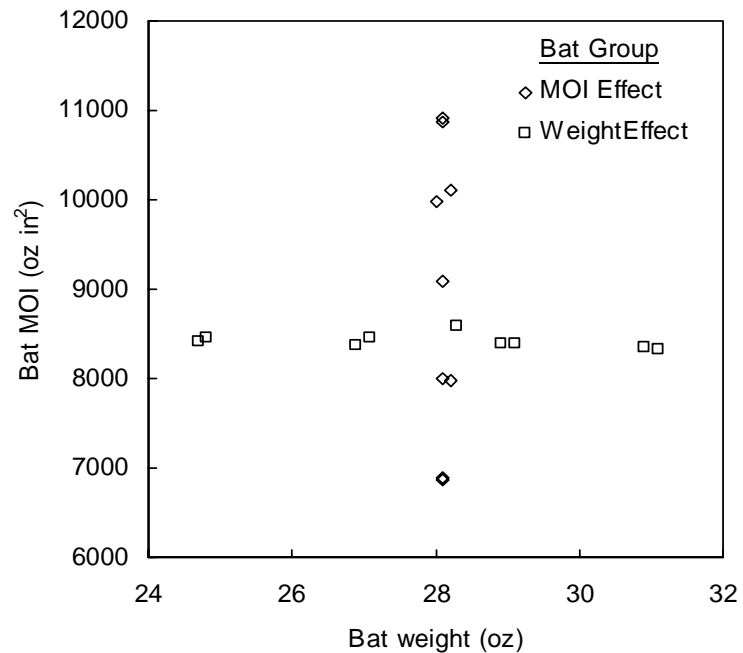


Figure 1. Weight and MOI of the 20 bats

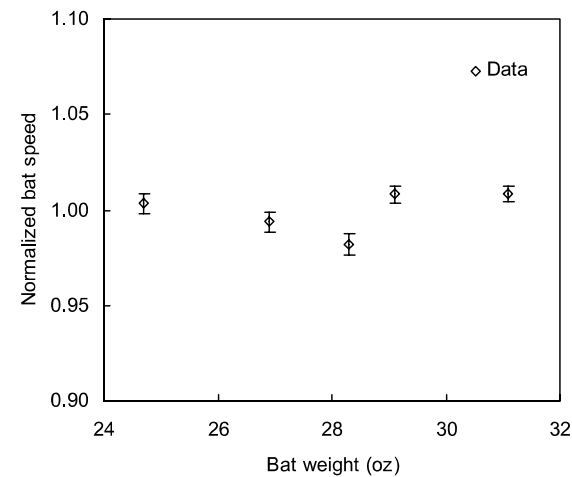


Figure 3. Normalized bat swing speed (6 inches from the tip) as a function of bat mass for bats with constant MOI.

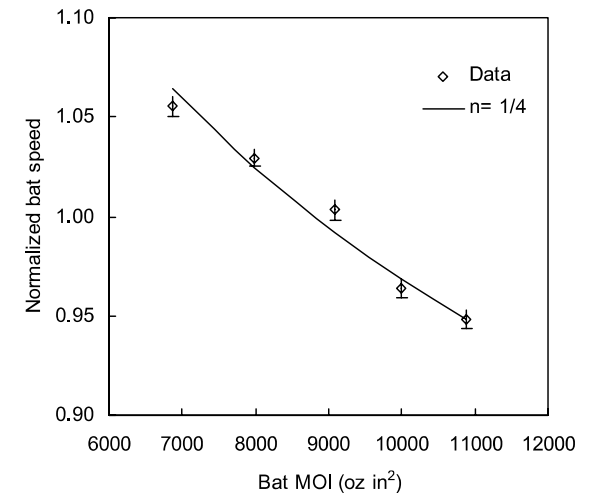


Figure 4. Normalized swing speed as a (6 inches from the tip) function of bat MOI for bats with constant mass.





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Which one will win?

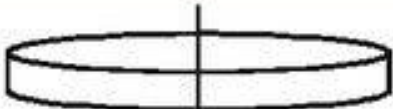
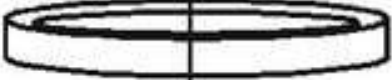
Tie

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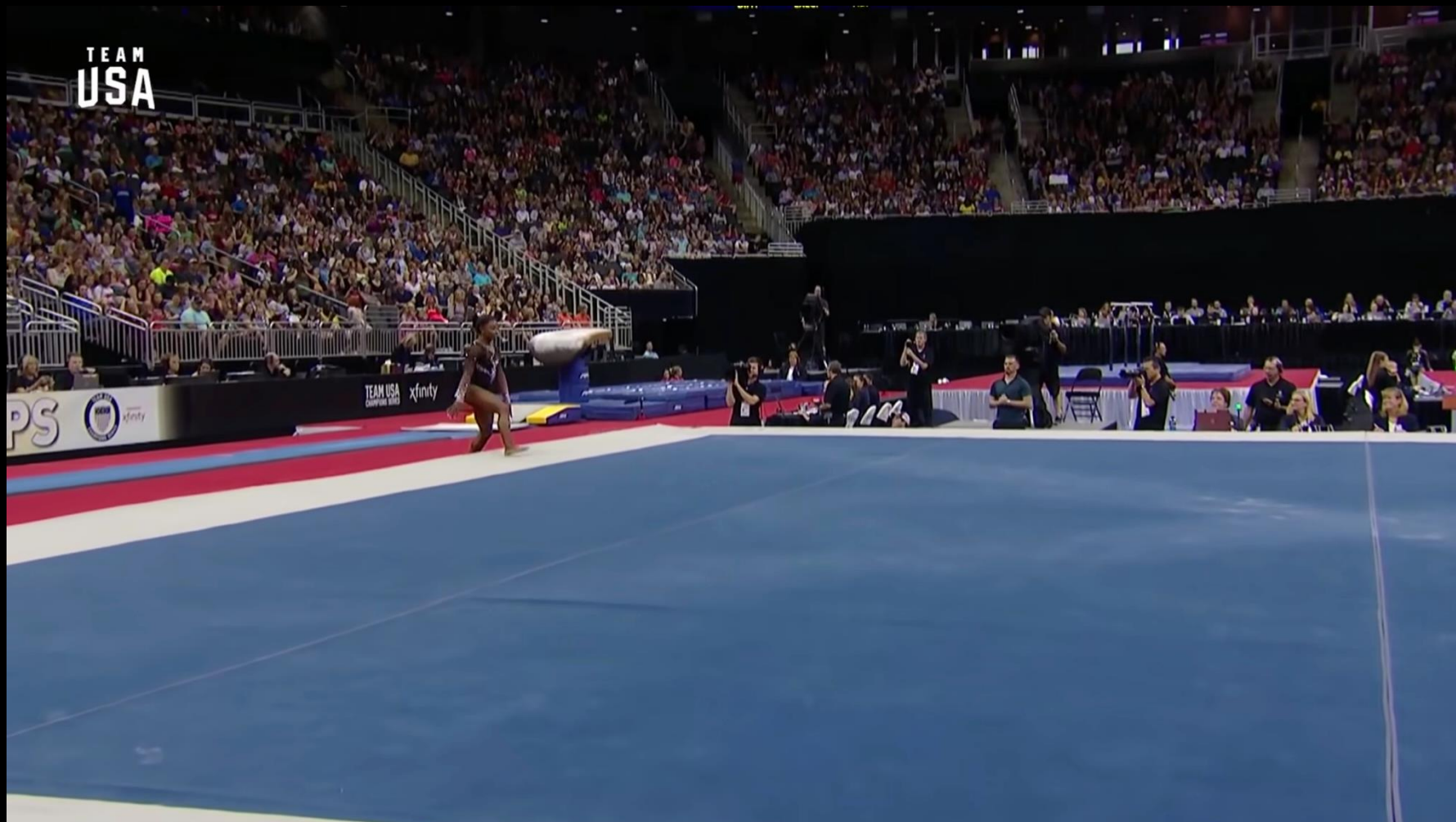


Why did the ring win!?

<i>Object</i>	<i>Drawing</i>	<i>Moment of Inertia</i>
Disk (rotated about center)		$\frac{1}{2}MR^2$
Ring (rotated about center)		MR^2

- Solid disk has a smaller I
- Therefore, it has a smaller resistance to change in angular motion.

Simone Biles



Simone Biles



