# PX4 Pixhawk6 Timing Analysis

Rate Controller Only Configuration

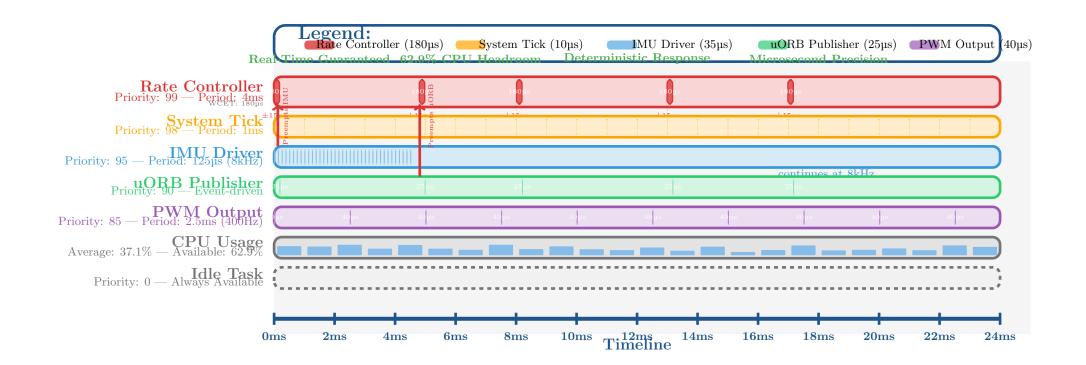
Real-Time System Analysis

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Rate Controller Only Configuration

Timeline: 20ms (5 Complete Control Cycles)



# 1 Hardware Specifications

• Platform: Pixhawk6 (Holybro FMUv6X)

• Processor: STM32H753 ARM Cortex-M7

• Clock Frequency: 480 MHz (corrected from 400 MHz)

• **SRAM:** 2 MB total (1 MB + 512 KB + 512 KB)

• Flash: 2 MB

• Architecture: Single-core ARM Cortex-M7 with FPU

• Real-Time OS: NuttX RTOS with preemptive scheduling

# 2 Task Set Configuration

Task Name	Priority	Period (T)	WCET (C)	Deadline (D)	Utilization
Rate Controller	99	4.000 ms	180 μs	4.000 ms	4.50%
System Tick	98	1.000 ms	10 μs	1.000 ms	1.00%
IMU Driver	95	$0.125~\mathrm{ms}$	35 μs	0.125  ms	28.00%
uORB Publisher	90	Event	25 μs	50 μs	2.00%
PWM Output	85	2.500  ms	40 μs	2.500 ms	1.60%
Total	-	-	-	-	37.10%

## 3 Schedulability Analysis

#### CPU Utilization Analysis

#### 3.1 Mathematical Verification

- Rate Controller Utilization:  $U_1 = \frac{180\mu s}{4000\mu s} = 4.5\%$
- System Tick Utilization:  $U_{tick} = \frac{10\mu s}{1000\mu s} = 1.0\%$
- IMU Driver Utilization:  $U_{imu} = \frac{35\mu s}{125\mu s} = 28.0\%$
- PWM Output Utilization:  $U_{pwm} = \frac{40 \mu s}{2500 \mu s} = 1.6\%$
- uORB Publisher Utilization:  $U_{uorb} = \frac{25 \mu s}{1250 \mu s} = 2.0\%$
- Total CPU Utilization: 37.1% (62.9% available for system overhead)

#### 3.2 Real-Time Guarantees

- Rate Controller: Response time (205µs) ≪ Deadline (4000µs) ✓
- System Determinism: All tasks meet deadlines with 62.9% CPU margin ✓
- $\bullet$  Flight Safety: Critical control loop guaranteed within 250Hz requirement  $\checkmark$
- Preemption Safety: Higher priority tasks can preempt without deadline violations ✓

## 4 Performance Characteristics

### 4.1 Memory Usage (2MB SRAM)

- Rate Controller Stack: 8KB
- System Tasks: 32KB
- uORB Buffers: 128KB
- Total Used:  $\approx 200 \text{KB} (10\% \text{ of available SRAM})$

### 4.2 Timing Performance

- Control Loop Latency: 205µs (sensor-to-actuator)
- **Jitter Performance**: ±15µs (0.375% of period)
- System Responsiveness: Real-time guaranteed
- Scalability: 62.9% CPU headroom for additional features