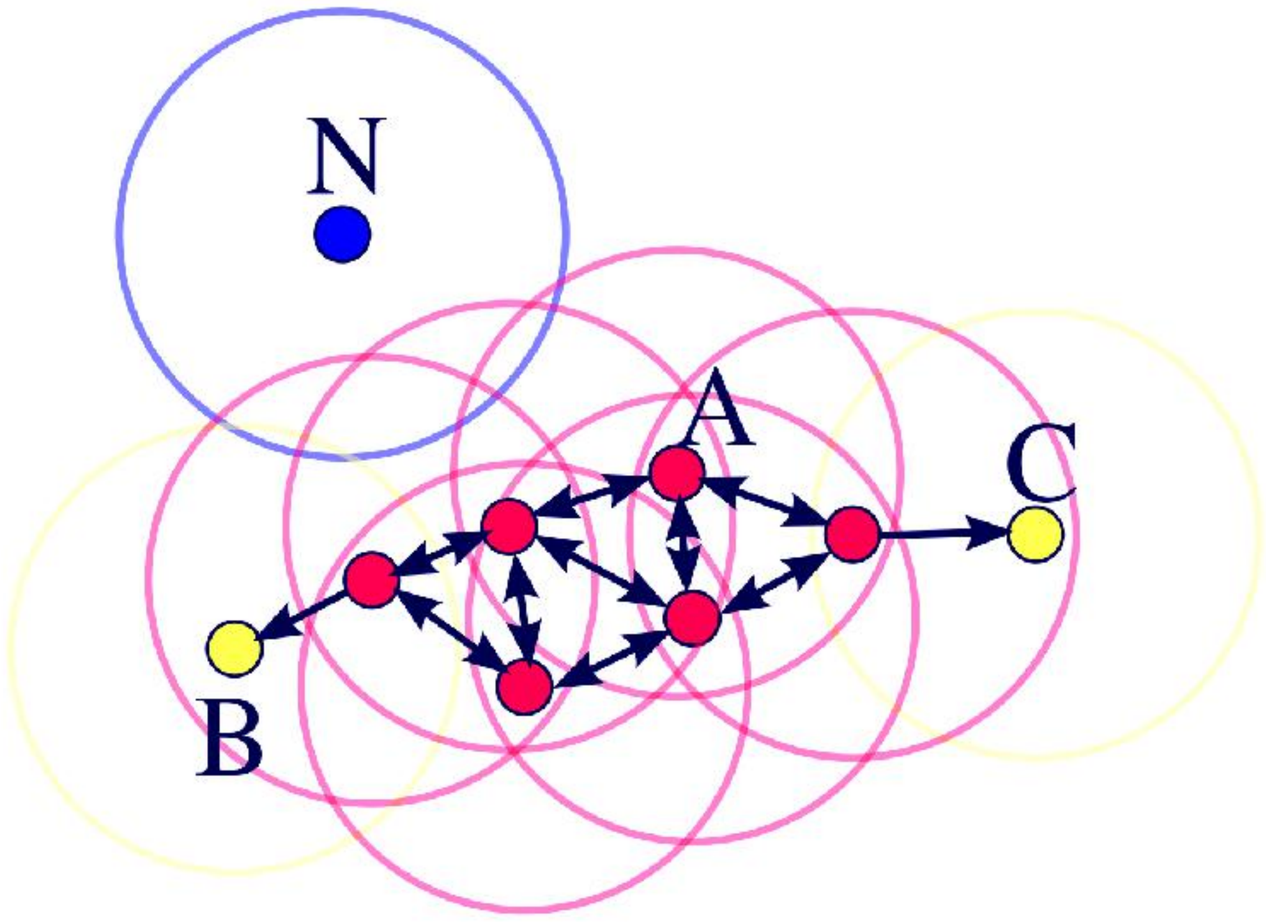
DBSCAN: Definitions and Algorithm Outline

- cluster to which a core point belongs = set of reachable points
- non-core points ≈ edge of the clusters (cannot reach others points)
- reachability is transitive, but not symmetric (except for core points)
- non-core points in the same cluster are not reachable from each other



source: https://en.wikipedia.org/wiki/DBSCAN